

# Improving the assembly and metrology of the PS Modules for the CMS Phase-2 Tracker

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Hamburg, 2<sup>nd</sup> of September 2019

# Outline

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- The PS Module

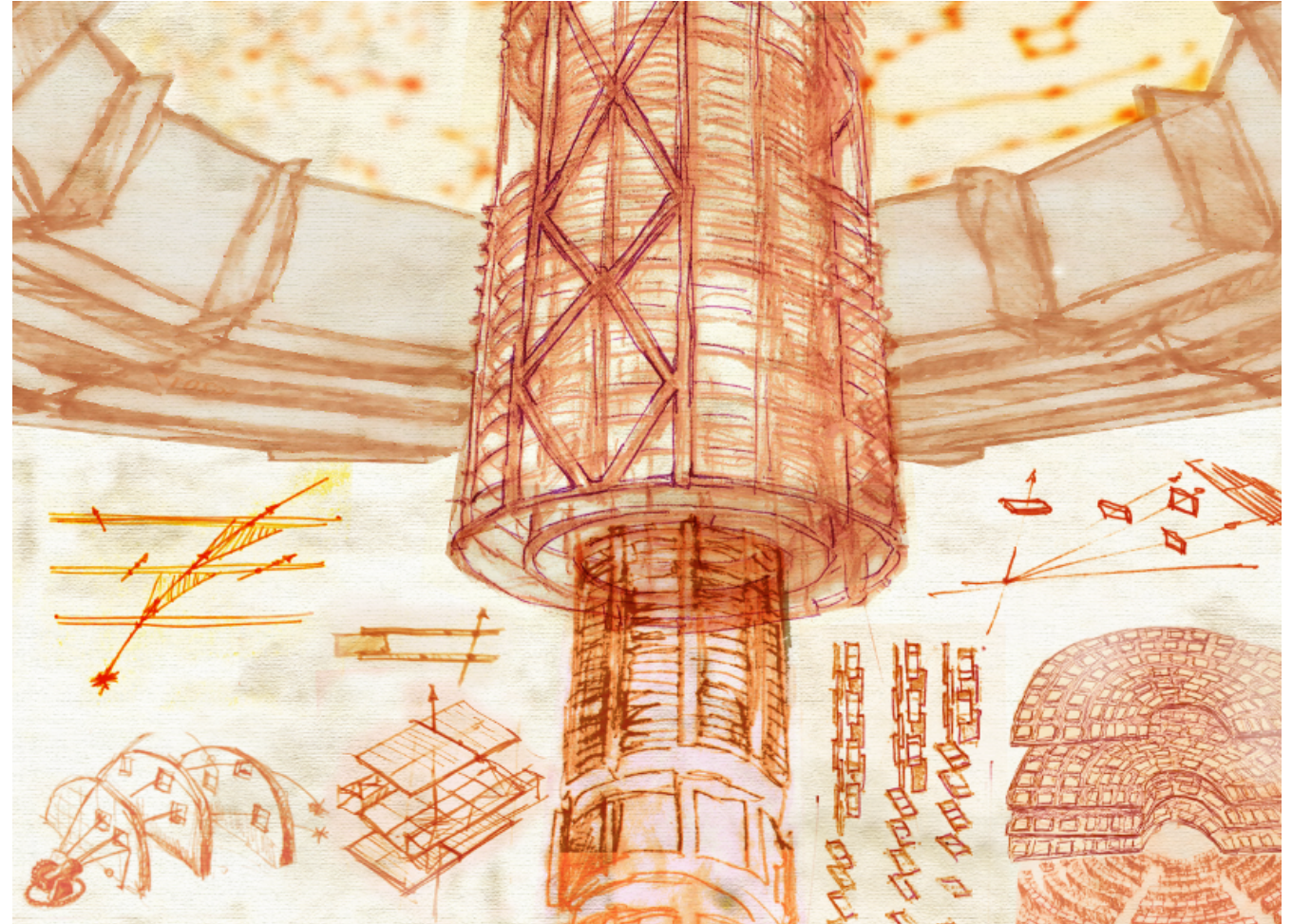
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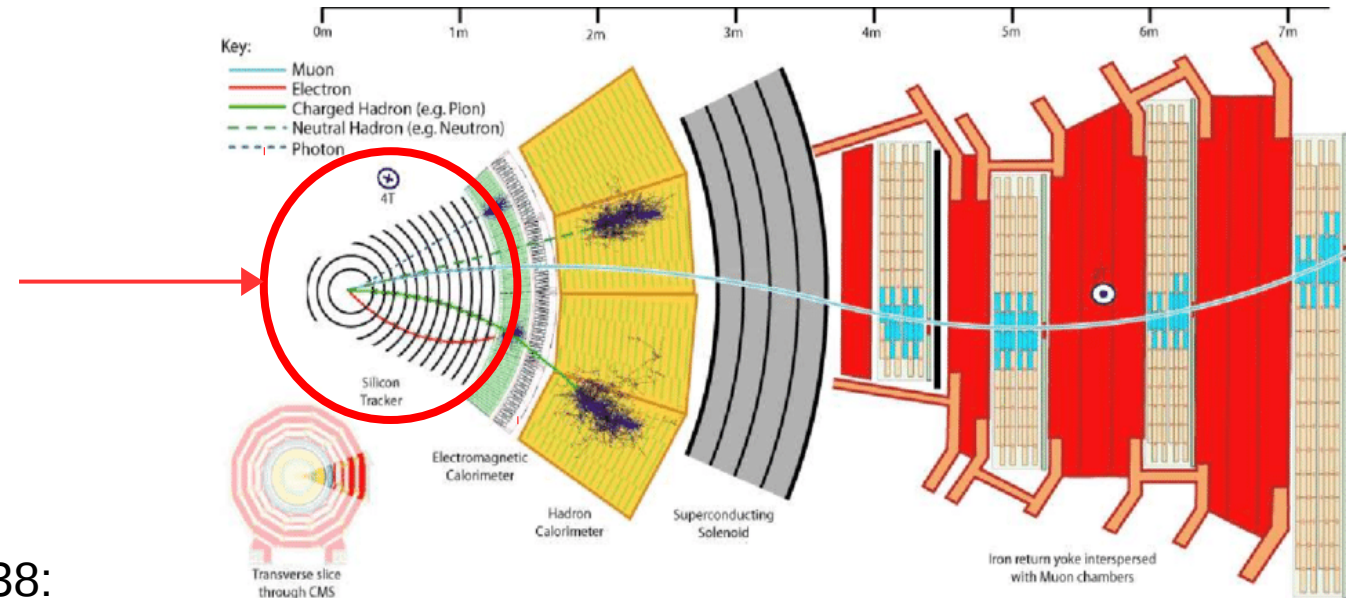


# Introduction

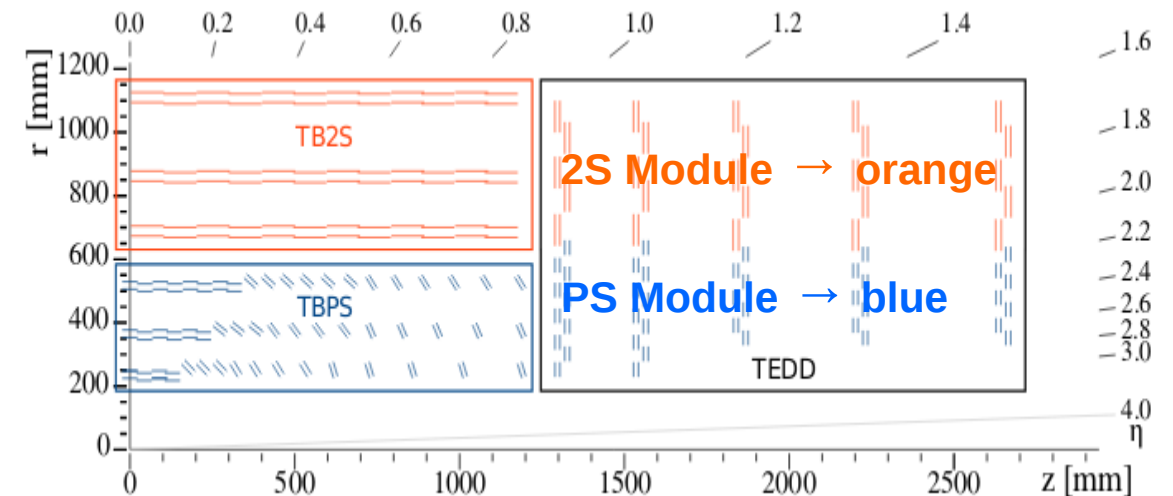
# Introduction

## The CMS Tracker and the HL-LHC

- **The CMS Tracker:**
  - innermost sub-detector of CMS;
  - thousands of silicon sensors used to reconstruct the trajectories of charged particles from LHC collisions.
- The future: **High-Luminosity LHC, 2026-2038:**
  - higher instantaneous luminosity (up to  $5.0 \times 10^{34} \text{ cm}^{-2} \text{ s}^{-1}$ );
  - unprecedented levels of integrated luminosity (up to  $4000 \text{ fb}^{-1}$ ).
- For the HL-LHC, CMS will install a completely new tracking detector - **the CMS Phase-2 Tracker:**
  - increased radiation tolerance, granularity and  $\eta$ -coverage; input to the Level-1 trigger;
  - the DESY Tracker Upgrade group contributes to construct **the new Outer Tracker**.



Pic. 1. A transverse slice through one segment of the CMS detector.

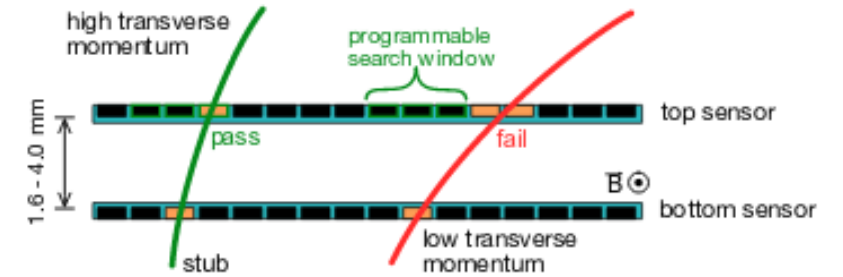


Pic. 2. A sketch of one quarter of the CMS Phase-2 Outer Tracker.

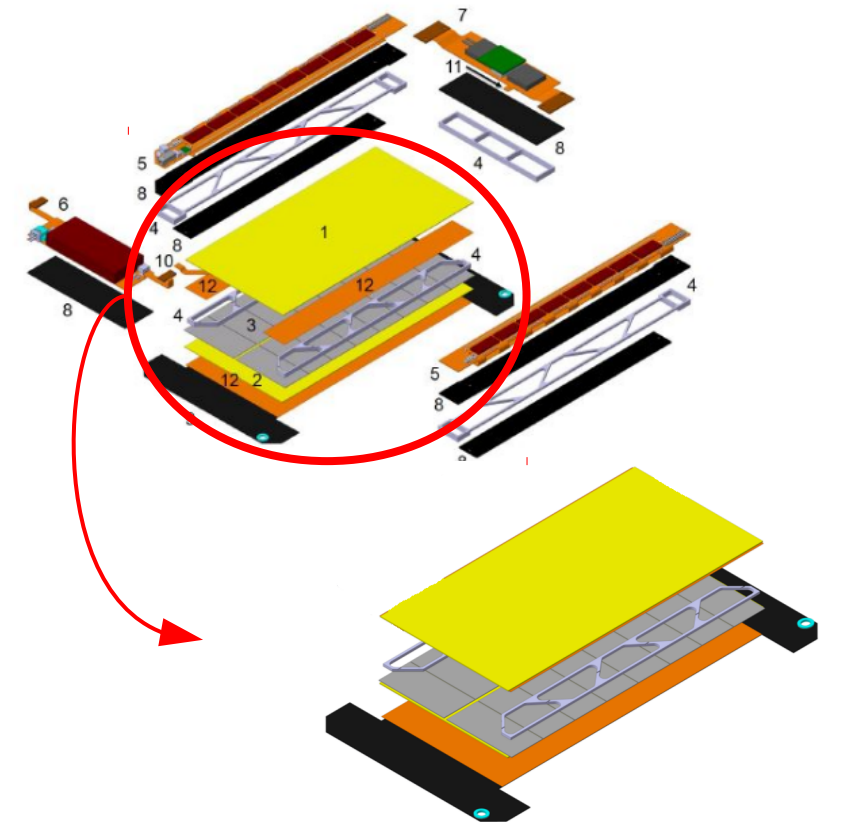
# Introduction

## The PS Module

- **The CMS Phase-2 Outer Tracker:** two types of modules:
  - Pixel-Strip (PS) Modules and Strip-Strip (2S) Modules.
- **The PS Module** most important components are **2 silicon sensors** (dim.: 10 x 5 cm<sup>2</sup>, thick.: 200 um) in a sandwich configuration.
- Stacked-sensors design will allow to have **local reconstruction of high-p<sub>T</sub> tracks** and use this information in the Level-1 trigger:
  - Correlation of hits requires very precise assembly of the sensors:  
PSP-PSs max-allowed rot. misalignment < **800 urad** (0.045 deg).
- **The PS Module assembly** is one of the activities of the **DESY Tracker Upgrade group**:
  - DESY will produce more than **1000 PS Modules**.
  - Currently developing assembly procedure using following parts:  
baseplate, kapton, 2 glasses (instead of silicon sensors), spacers.



Pic. 1. Momentum measurement concept.



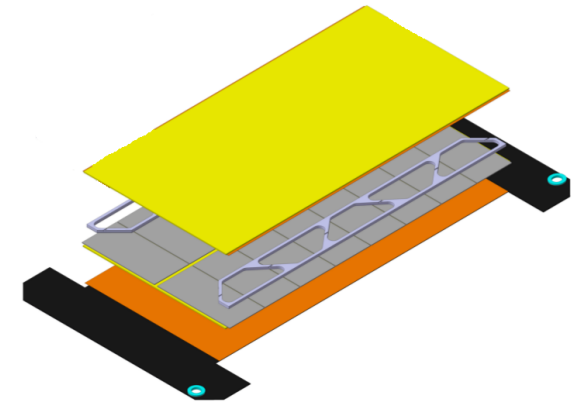
Pic. 2. The PS Module design.

# PS Module assembly

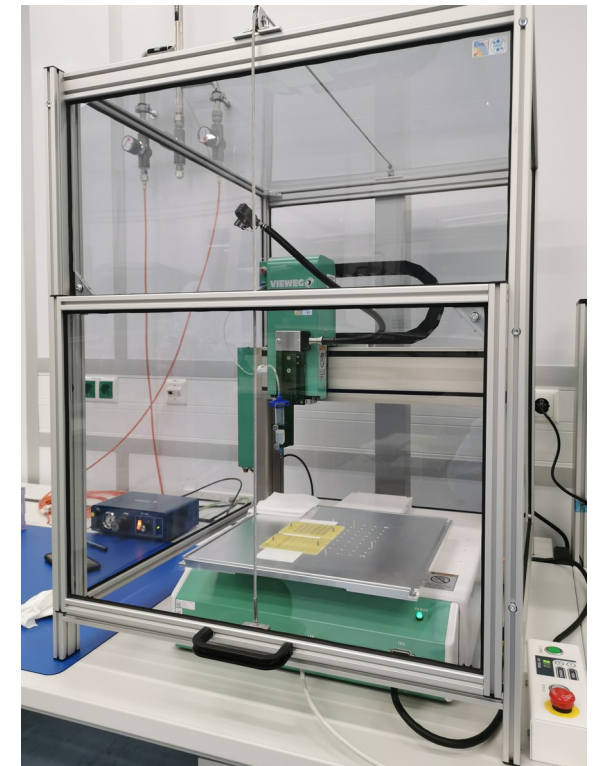
# Baseplate+kapton gluing

## Motivation, goal and method

- **Motivation:**
  - The PS Module will be attached to a **baseplate** made of carbon fiber reinforced polymer in order to support the structure.
  - **A kapton foil** (thick.: 25um) on the baseplate is necessary to electrically isolate the baseplate from the PS-p sensor.
- **Goal:**
  - Development of a procedure to glue kapton foil to baseplate (and perform this step in the reproducible way).
- **Method:** Program **the automatic dispenser** to dispense glue on baseplate.
  - Development of a program to operate the automatic dispenser.
  - Tested different patterns to dispense the glue (Polytec EP 601 LV).
  - Best configuration: one 7,5 cm line in the middle, 30-40 mg of glue.



Pic. 1. The PS Module design.

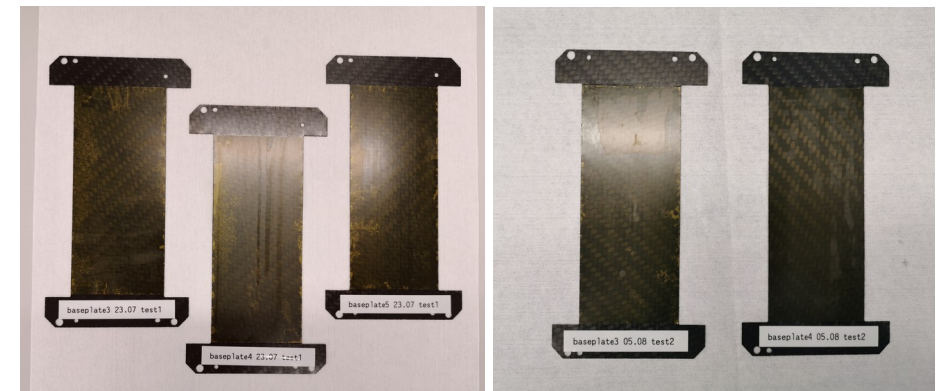
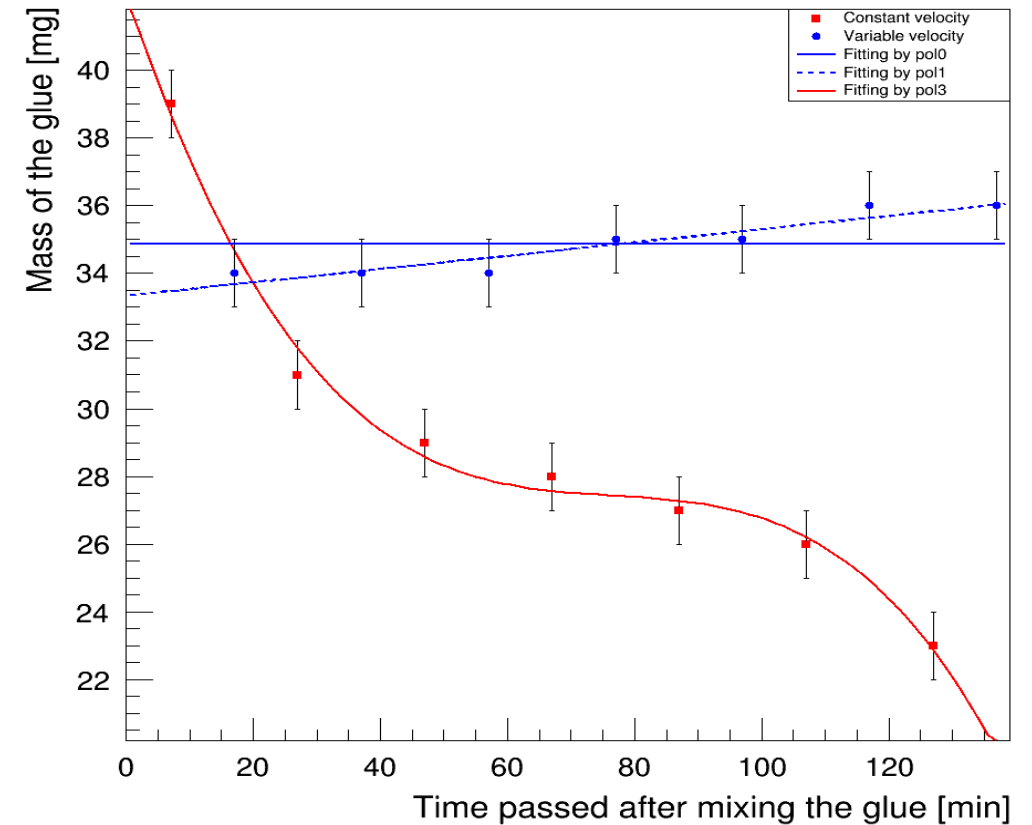


Pic. 2. The automatic dispenser.

# Baseplate+kapton gluing

## Results

- Two important factors to account:
  1. Modification of the routine parameters - **dispensing velocity** - wrt time passed after mixing the glue:
    - Goal: constant amount of the glue.
    - **Red**: constant velocity;
    - **Blue**: adjusted velocity.
    - Found rule to adjust dispensing velocity wrt time.
  2. Method of manually **squeegeeing** (after dispensing).
    - Improper squeegeeing can lead to air bubbles.
- **Results:**
  - Development of the procedure to dispense the glue.
  - Glued 7 prototypes using different methods (last 3 without air bubbles).
- **Next step:** Improve the positioning of kapton on baseplate (currently done manually).



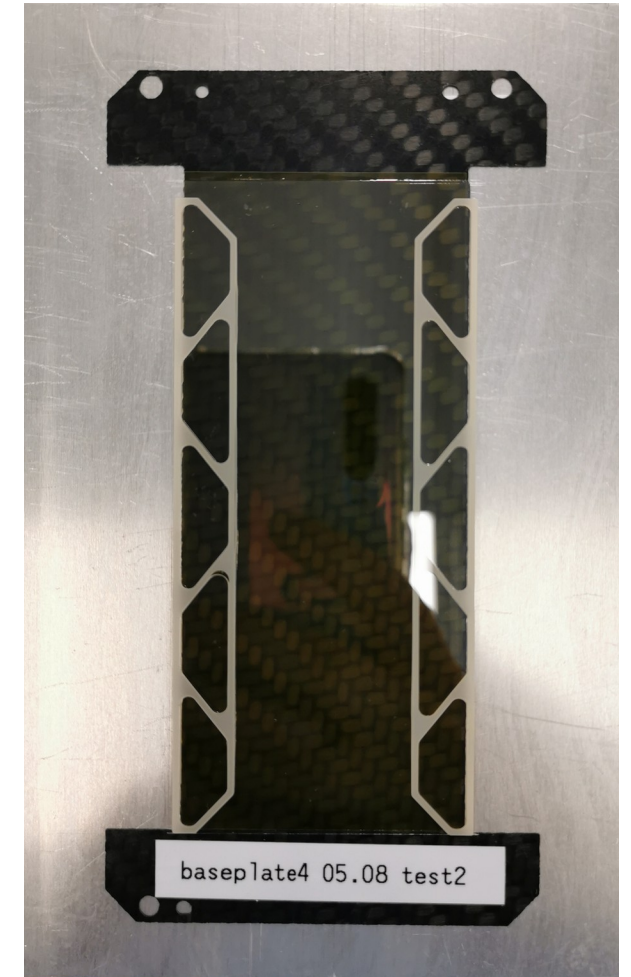
Pic. 1. Glued baseplates (5 of 7) with kapton foil on top.



# Baseplate+sensors gluing

## Gluing baseplate to glass+glass sandwich

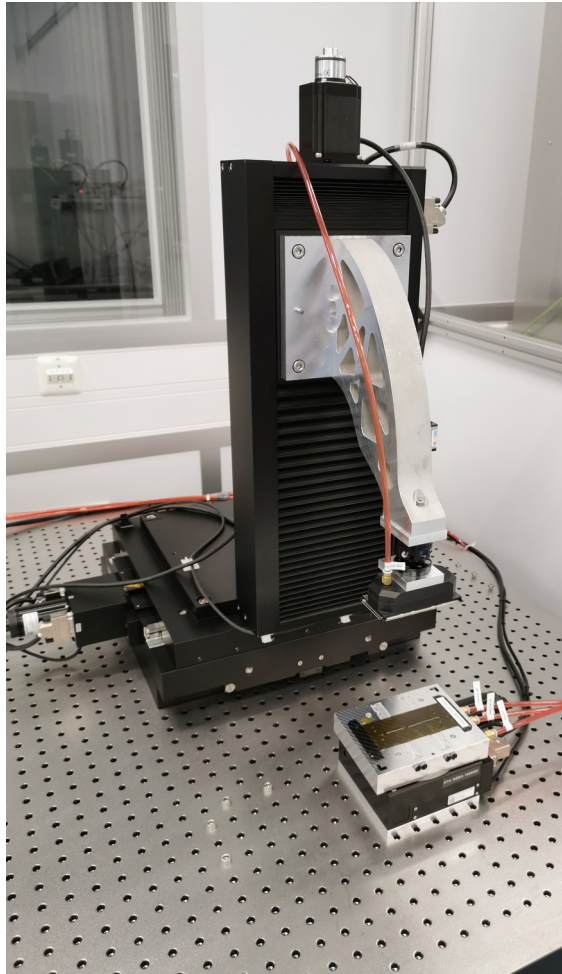
- **Motivation:**
  - Development of a procedure to glue baseplate to sensors-sandwich obtaining thin glue layer with full coverage.
- **Method:** development of a routine with the automatic dispenser:
  - Goal: thickness of glue layer: **~25  $\mu\text{m}$**  → amount of glue: **~100 mg**.
  - Best configuration: one 8,5 cm line in the middle + 4 dots in the corners.
- **Results:**
  - Successfully applied the procedure in assembly of last 2 prototypes (1 with **200  $\mu\text{m}$  thickness** glasses, 1 with **700  $\mu\text{m}$  thickness** glasses).
  - Good coverage of the glue layer (only few small air bubbles between baseplate and glass).
- **Next step:** More testing, measurement of the thickness of the glue layer.



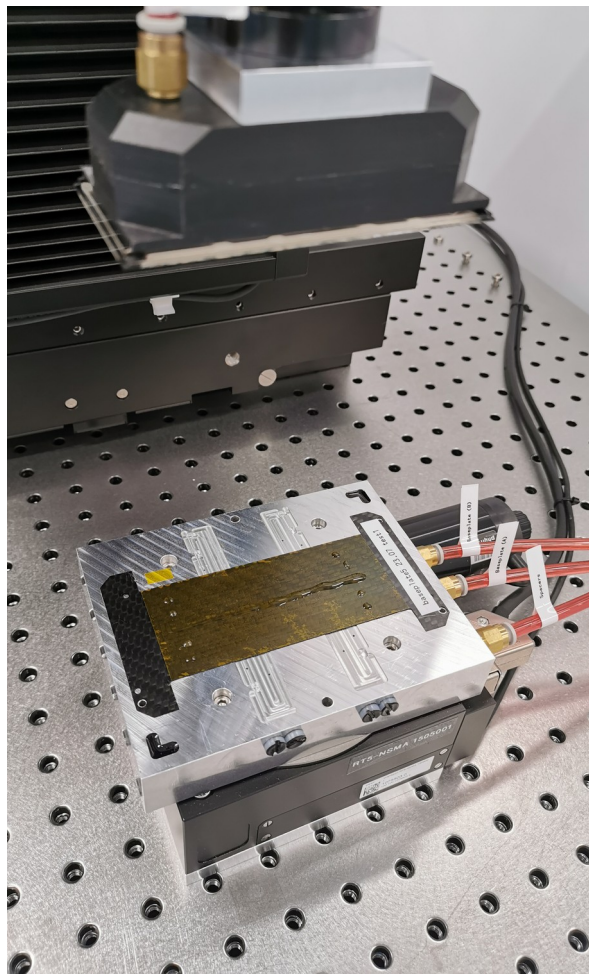
Pic. 1. Assembled PS Module.

# Baseplate+sensors gluing

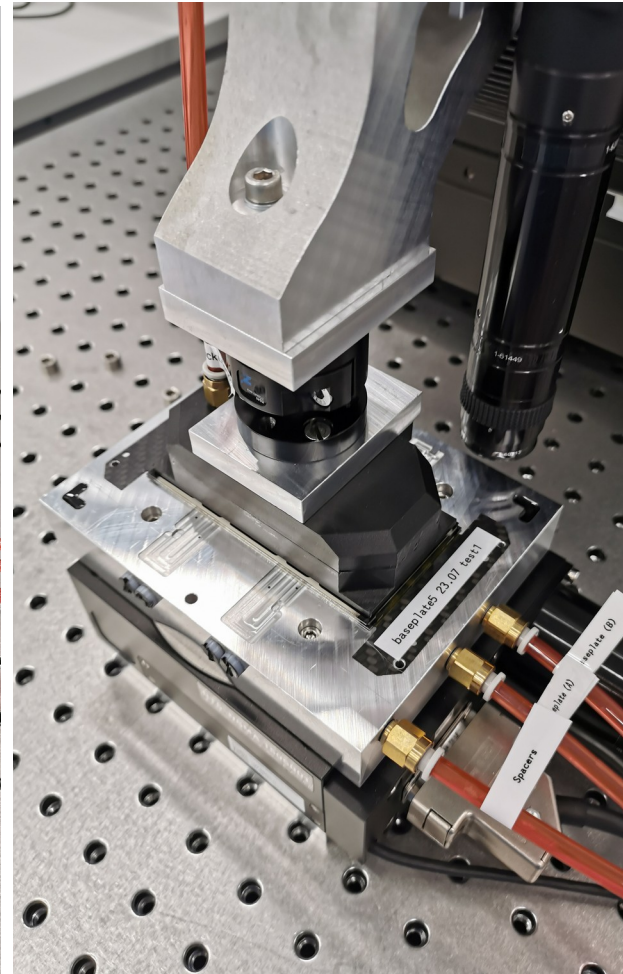
Gluing baseplate to glass+glass sandwich



*Pic. 1. The assembly robot.*



*Pic. 2. Kapton+baseplate.*



*Pic. 3. Gluing the parts together.*



*Pic. 4. Assembled PS Module.*

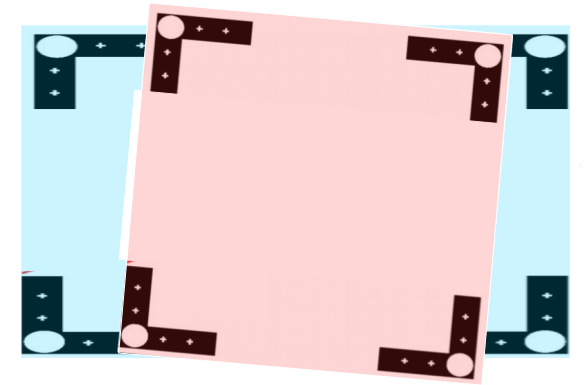
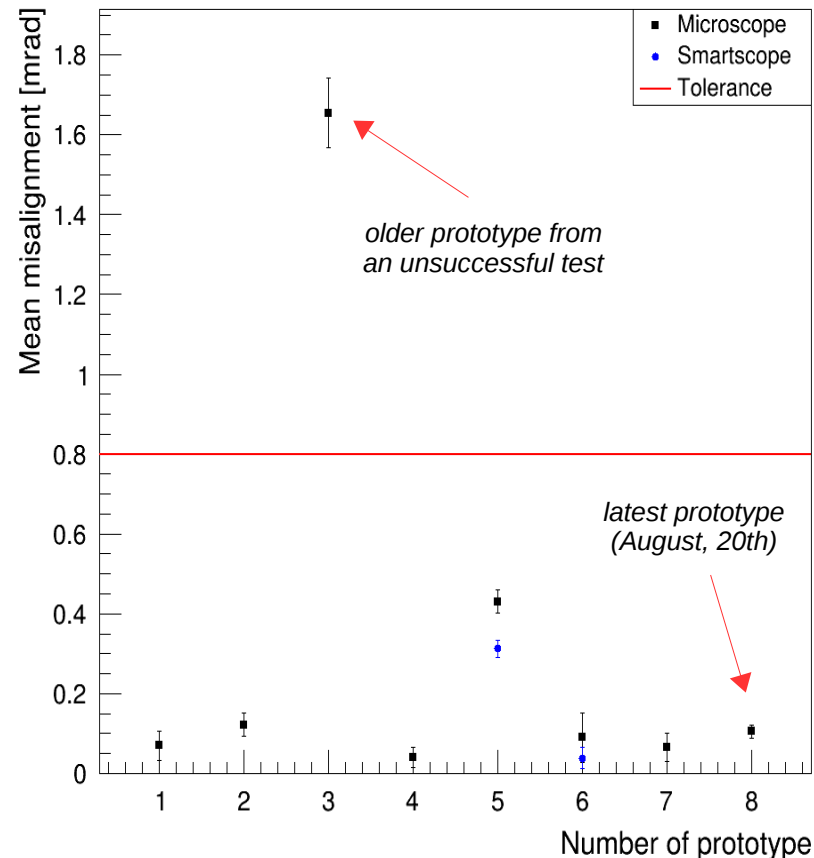
**PS Module**

**metrology measurements**

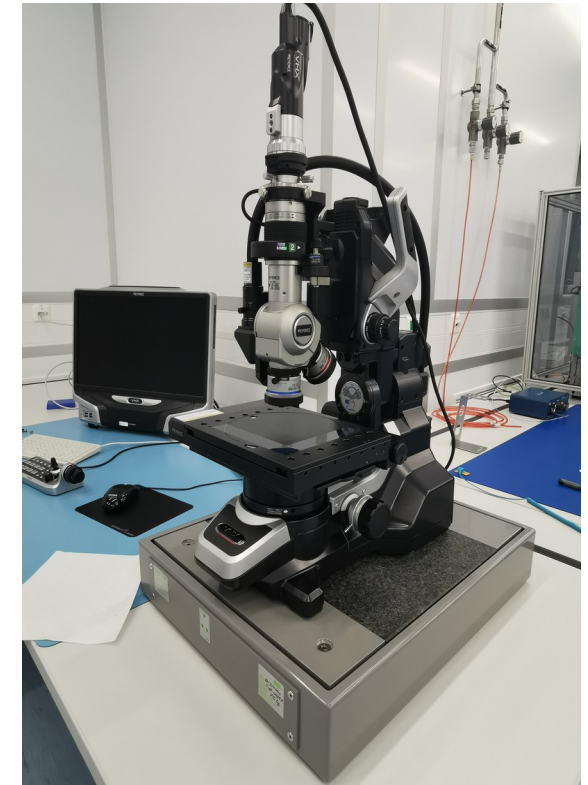
# PS Module metrology measurements

## Measurements of rotational misalignment of PS sensors

- **Motivation:**
  - Verify if components of the PS Module prototypes are assembled well.
- **Measurements of the markers:**
  - of all 8 existing modules using a microscope;
  - of 2 modules using SmartScope (to compare to microscope data).
- Development of a program to analyze microscope data (python, ROOT).
- **Results:**
  - **7 out of 8** prototypes have rot. misalignment within specifications (**< 800 urad**).
- The procedure and tools can be applied to new PS Modules in the future.



Pic. 1. Misalignment concept.



Pic. 2. The microscope in 25c.

# Summary

# Summary

## PS module assembly

- Developed the procedures to perform 2 steps of PS Modules assembly: baseplate+kapton and baseplate+sensors gluing.
- Successfully applied the procedures in assembly of last 2 prototypes (1 with **200 um thickness** glasses, 1 with **700 um thickness** glasses).
- Good coverage of the glue layer (only few small air bubbles between baseplate and glass).

## Metrology measurements

- Developed the procedure to analyze microscope data.
- **7 out of 8** prototypes have rot. misalignment within specifications (**< 800 urad**).

## Next steps

- Improve the positioning of kapton on baseplate (currently done manually).
- Measurement of the thickness of the glue layer between baseplate and sensors-sandwich.
- Improve the metrology tools by adding additional features.

# Thank you

## Contact

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# Back-up

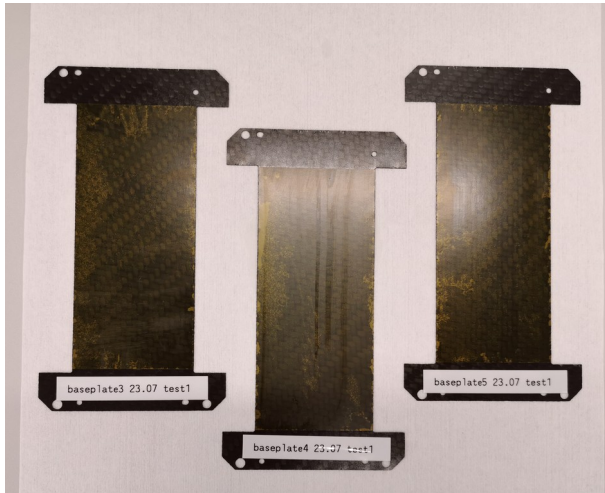


# Gluing kapton to a baseplate

## Results

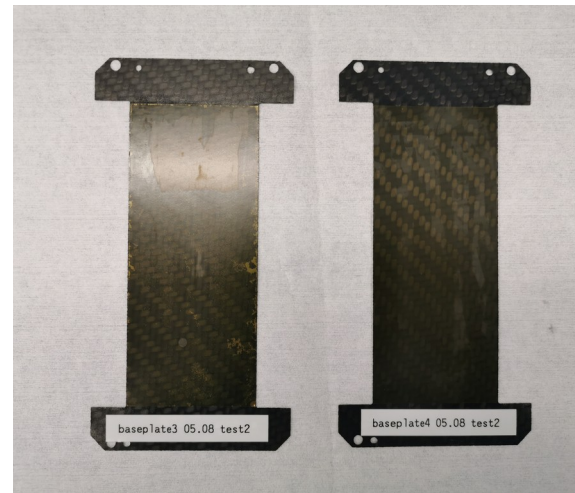
### Test #1

- All: 6 cm line in the center.
- Bp3: 5 min; 1.3 mm/s; 43 mg.
- Bp4: 45 min; 1.1 mm/s; 43 mg.
- Bp5: 80 min; 0.9 mm/s; 46 mg.
- All: different methods of squeezing; by the use of force.
- **All: clearly visible air bubbles.**



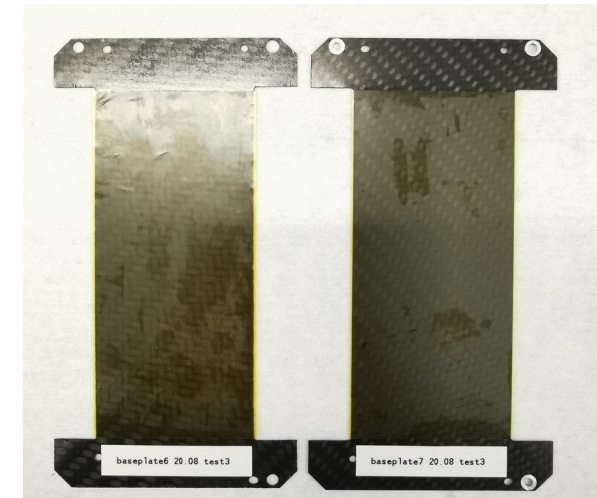
### Test #2

- Both: 7.5 cm line in the center.
- Bp3: 27 min; 1.3 mm/s; 43 mg; squeezing by the use of force.
- Bp4: 72 min; 1.3 mm/s; 39 mg; squeezing without using force.
- **Bp3: clearly visible air bubbles.**
- **Bp4: no bubbles, looks properly.**



### Test #3

- Both: 7.5 cm line in the center
- Bp6: 15 min; 1.3 mm/s; 62 mg; squeezing without using force.
- Bp7: 120 min; 0.9 mm/s; 72 mg; squeezing without using force.
- **Both: no bubbles, look the best in comparison to the previous tests.**

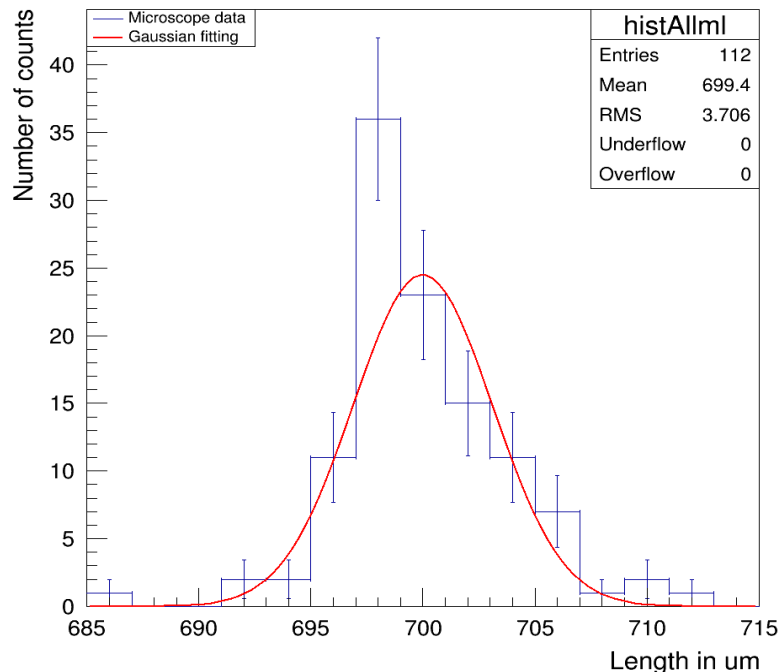


# Metrology measurements

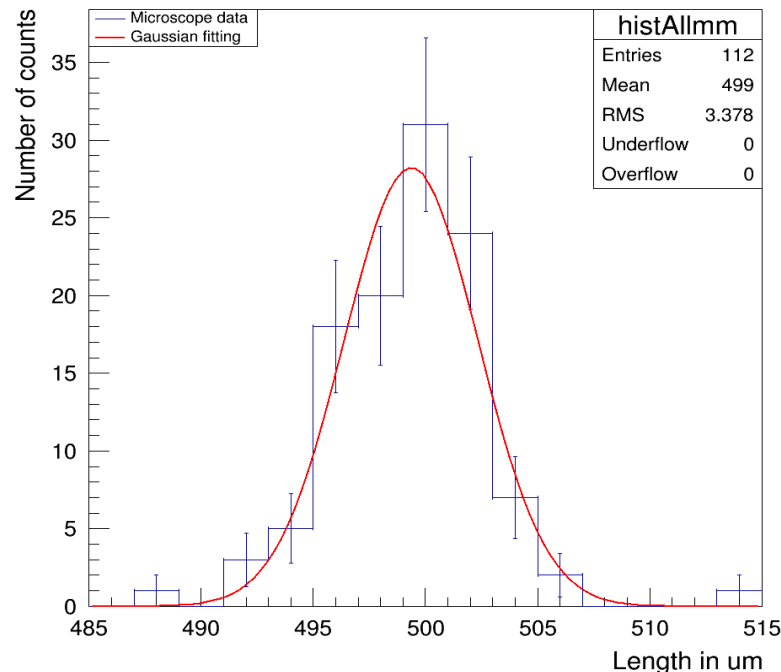
## Both glasses' marker's long/middle/short length

- **Goal:** Additional measurements to calculate the dimensions of the markers and distances between them.
- Measurement of the markers' dimensions of the 7 existing prototypes.
- Markers' design lengths: long  $\rightarrow$  700  $\mu\text{m}$ ; medium  $\rightarrow$  500  $\mu\text{m}$ ; short  $\rightarrow$  200  $\mu\text{m}$ .

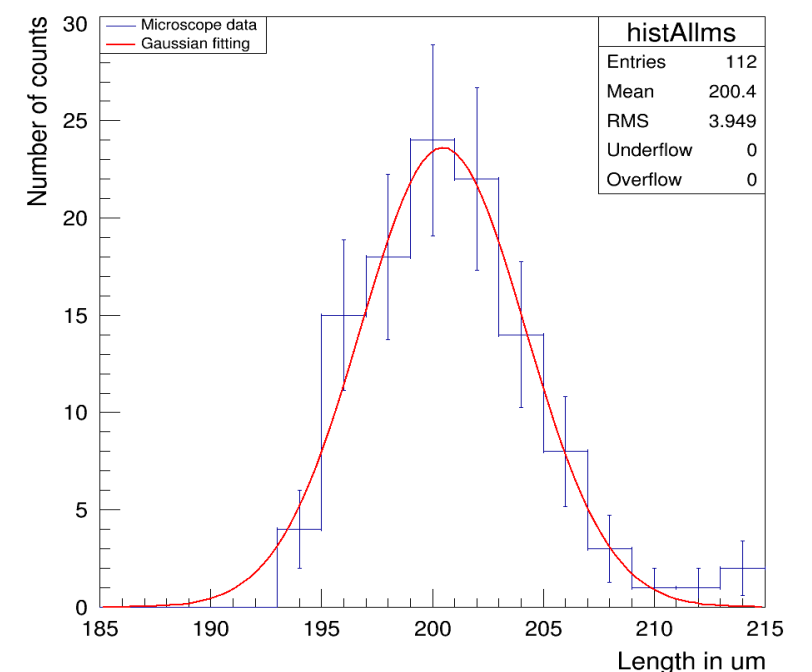
Histogram of marker's long length



Histogram of marker's medium length



Histogram of marker's short length



**Conclusion:** All markers' dimensions are similar for each measured prototype and they are in good agreement with markers' designs.

# Metrology measurements

## Rectangularity – quality of the markers

Final results for the microscope:

Number of the prototype	Mean angle [degrees]	Std deviation [degrees]
1.	90.000	0.008
2.	90.000	0.012
3.	90.001	0.010
4.	89.999	0.010
5.	90.000	0.008
6.	89.999	0.008
7.	90.000	0.009

Final results for the smartscope:

Number of the prototype	Mean angle [degrees]	Std deviation [degrees]
5.	90.000	0.003
6.	90.000	0.005

**Conclusion:** all the markers are positioned well.

## Histogram of rectangularity

