

# FLASH2 and XFEL

## Machine Protection System – MPS

μTCA-based

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Concept – Experience

3<sup>rd</sup> MicroTCA Workshop – 11th-Dec-2014

# Outline

1. Purpose of MPS
2. Overall requirements
3. Chosen HW
4. Requirements fulfilled by this HW
5. Installation experience
6. MPS-internal communication topology
7. MPS-external interfaces – in-/outputs
8. Cooperation concept



# Purpose



## ➤ MPS **protects** the accelerator from damage

- esp. caused by heavy impacts of electron bunches
- e.g. if beam is misaligned
- e.g. if subsystem trade fails
- e.g. during diagnostic routines or beam commissioning if inappropriate beam mode has been chosen
  - ✓ e.g. during wire scanning, OTR-screen movement, TDS-activity, collimator repositioning
  - ✓ e.g. in gun mode or analysis mode

## ❖ MPS **detects** that indirectly through a whole lot of alarm, error, interlock and status signals from a multitude of (diagnostic) systems

## ❖ MPS **reacts** appropriately by stopping or limiting the electron beam

*How, when and by means of **will be shown later***

# Overall Requirements

## ❖ MPS must be **bullet-proved**

- XFEL benefits from FLASH2 as the new  $\mu$ TCA-based MPS is used there first
- where it is running smoothly with only minor issues for several months

## ❖ MPS shall be as **invisible** as possible

## ❖ MPS' alarm-responses shall be **well-balanced**

- protection shall be as sensitive as necessary, but also as tolerant as reasonable possible to still enable a properly operable system

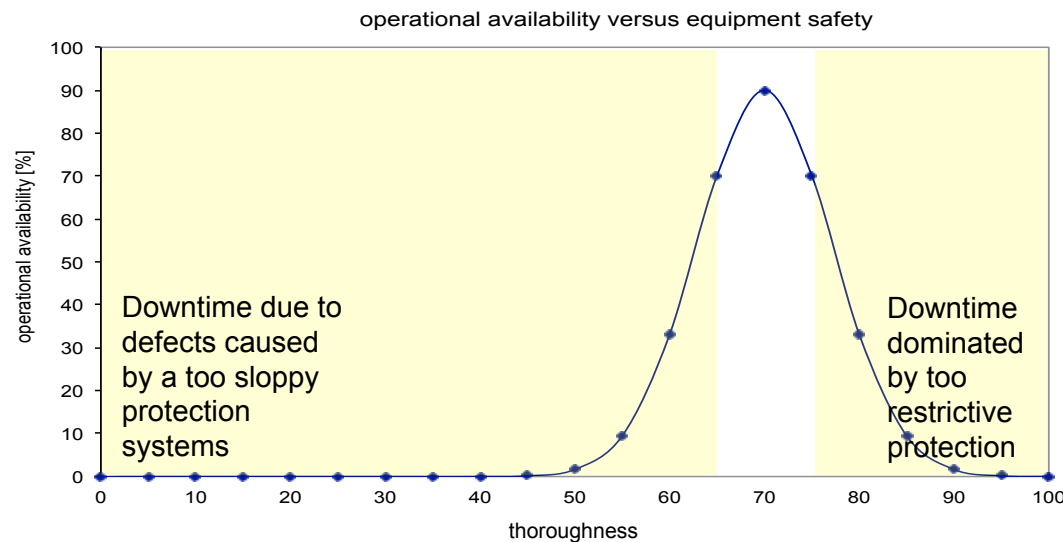
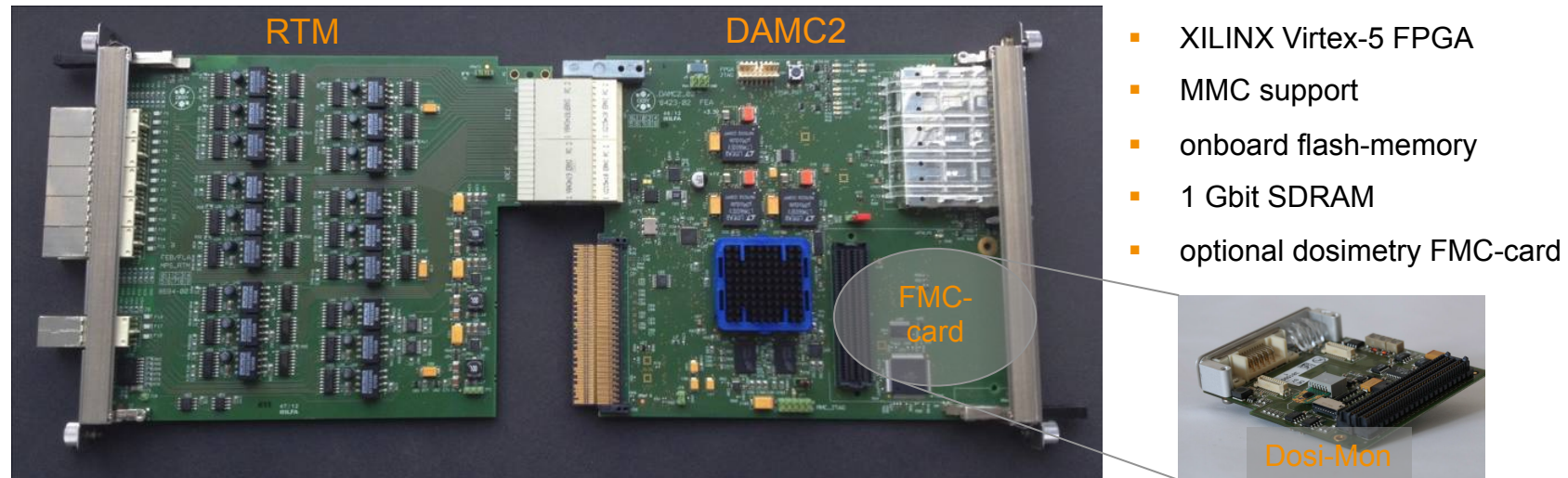


Figure by courtesy of CERN

# Chosen Hardware – DAMC2-board – MTCA.4



## ❖ DAMC2 has been developed at FE

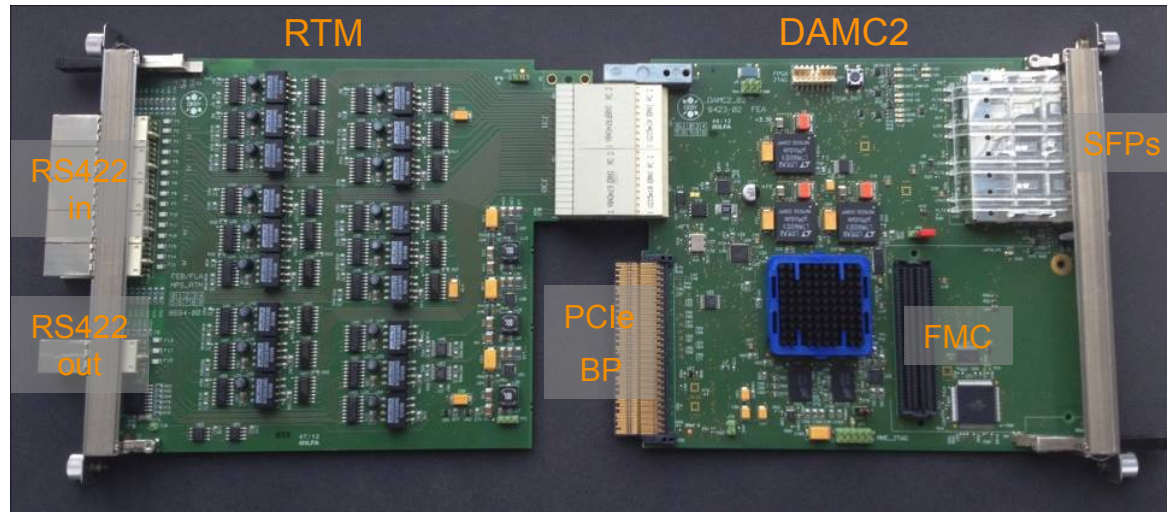
- Besides MPS, other groups have developed firmware for their projects, e.g. BLM-controller
- 25 MPS-boards in use, 100 ordered for the beginning of 2015, further will follow

## ❖ Interface RTM has been developed at FLA and FEB

- Besides MPS, it also used by other systems, e.g. laser controller
- 18 MPS-RTMs in use, 100 delivered and under final assembly, further will follow

## ❖ Radiation dosimetry monitoring FMC-card is currently under development at MDI

# Requirements Fulfilled by the Chosen Hardware



- 4 double-fibred bi-directional optical links (SFPs)
- 45 digital inputs (RS422)
- 7 digital outputs (RS422)
- 3 input lines from backplane
- 2 output lines to backplane
- 3 digital inputs from FMC-card
- I<sup>2</sup>C-bus to FMC-card
- PCIe-bus to all FPGA-registers
- IPMI for firmware updates

## ✓ Safety & availability & timeliness

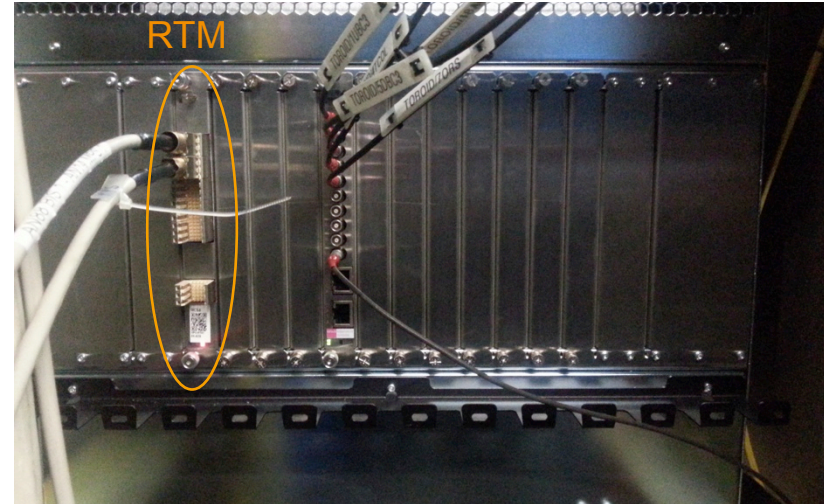
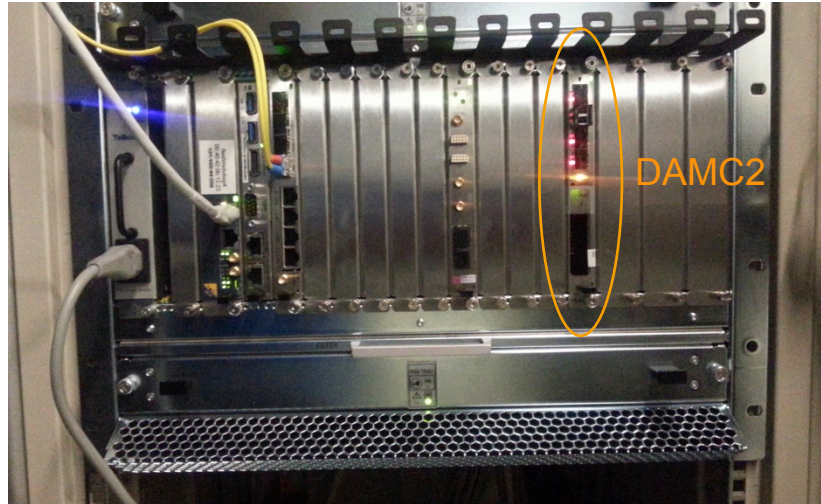
- all **machine safety-relevant** functions are realized within FPGA logic (~42 ns latency)
- to be **independent** from the availability of network, operating system, DOOCS-servers, PCIe-device drivers ...

## ✓ Maintainability & scalability

- MPS architecture can be extended by utilizing the cascaded communication topology
- same firmware on every board, same DOOCS-server on every crate
- all alarm-responses can be configured through DOOCS/JDDD even during machine run
- boards and RTMs are hot-swappable



# Installation Experience



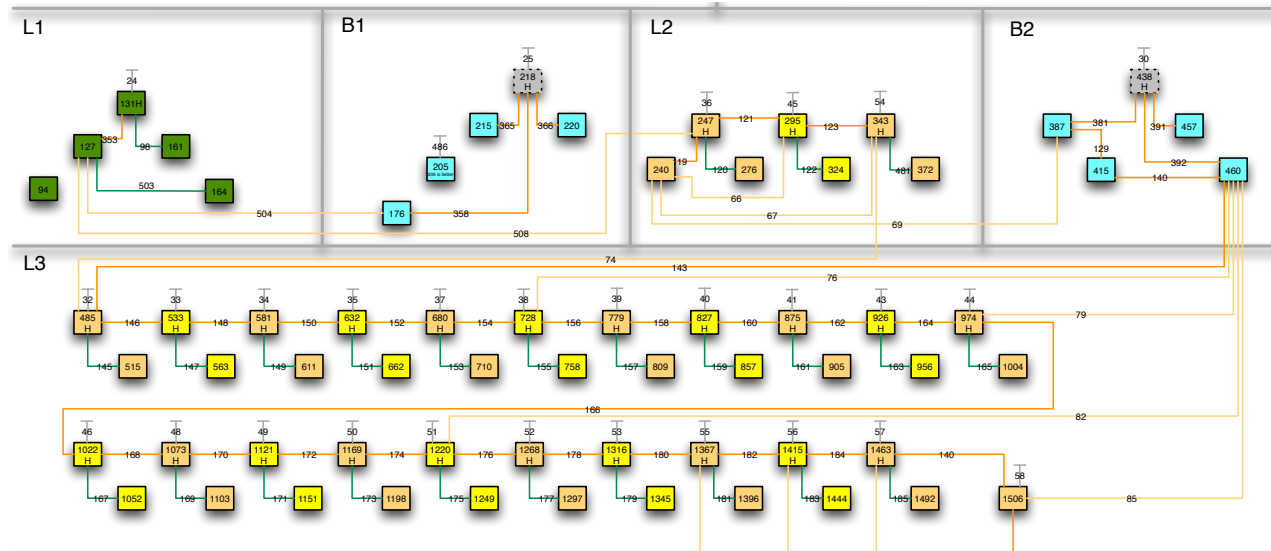
## ✓ Already installed boards (to be grown quickly)

- 6 boards for **operational FLASH2**: injector hutch, cryo annex, extraction area & supply system aisle
- 3 boards for **XFEL gun test**: 7th basement of the XFEL tunnel
- 3 boards for **LLRF tests** at 3 test-stands in the AMTF-hall
- 13 boards for development at several DESY laboratories

## > Reasons of the few anomalies at FLASH2

- mostly: cable contact problems
- once after firmware update: misconfigured operation mode setting

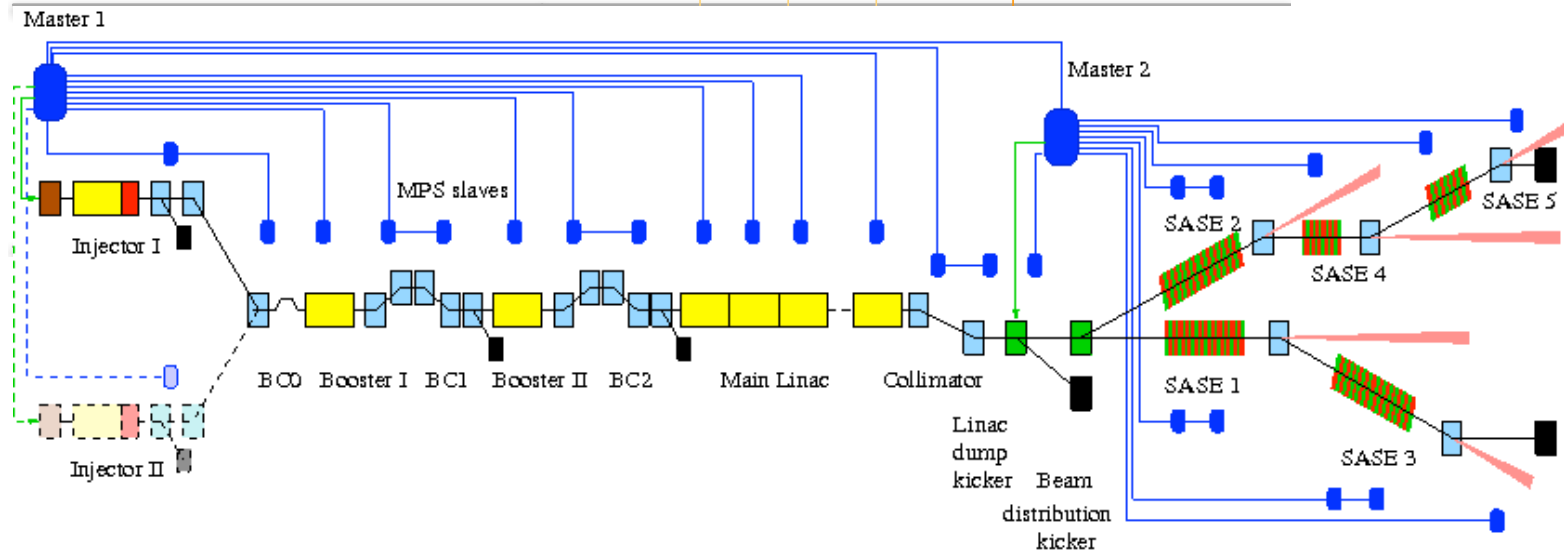
# MPS-internal Communication Topology



➤ In XFEL 150 MPS-boards will be installed

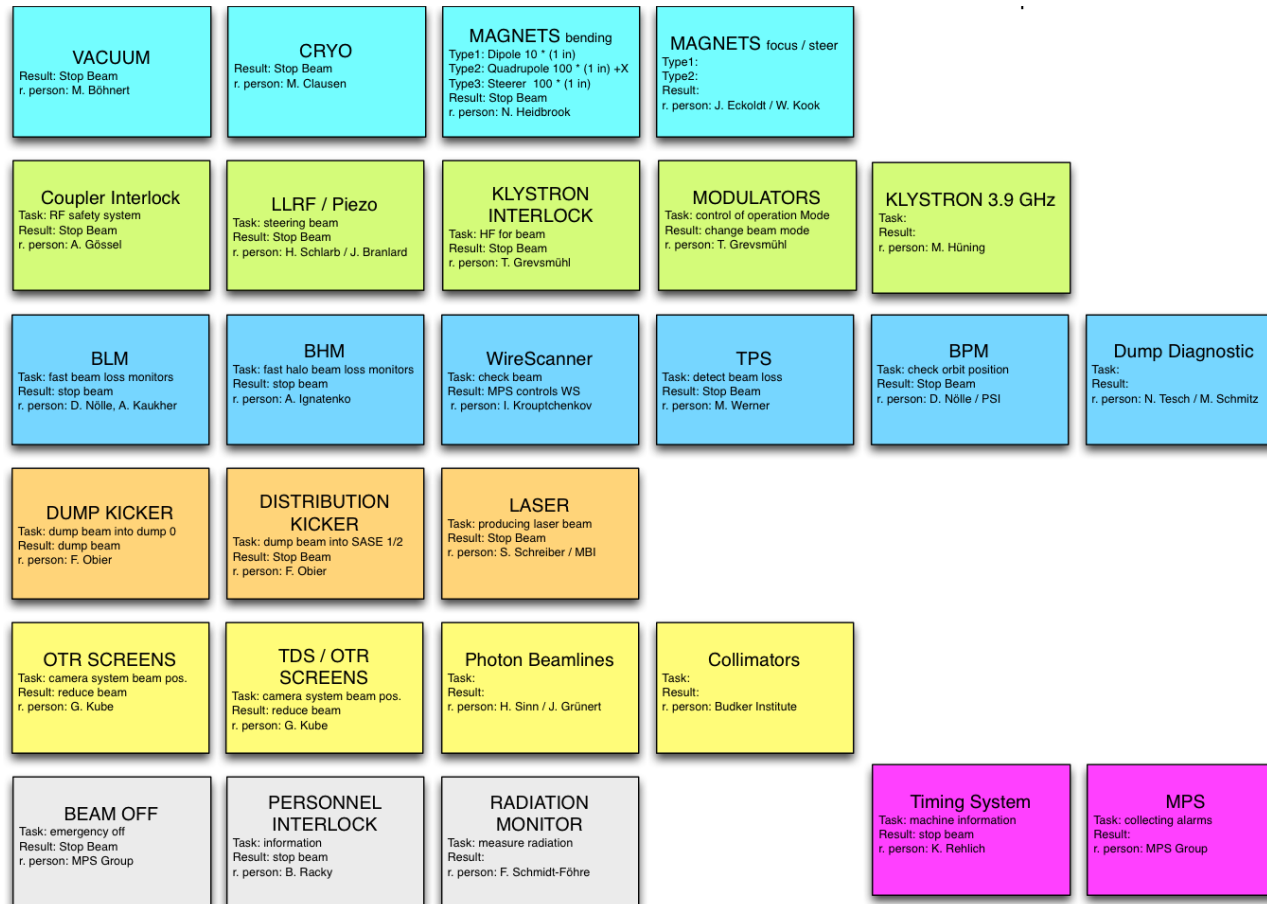
➤ MPS-boards inter-communicate via **fiber optics**

- i.e. telegrams with laser inhibits, beam limits, section availabilities and operation modes



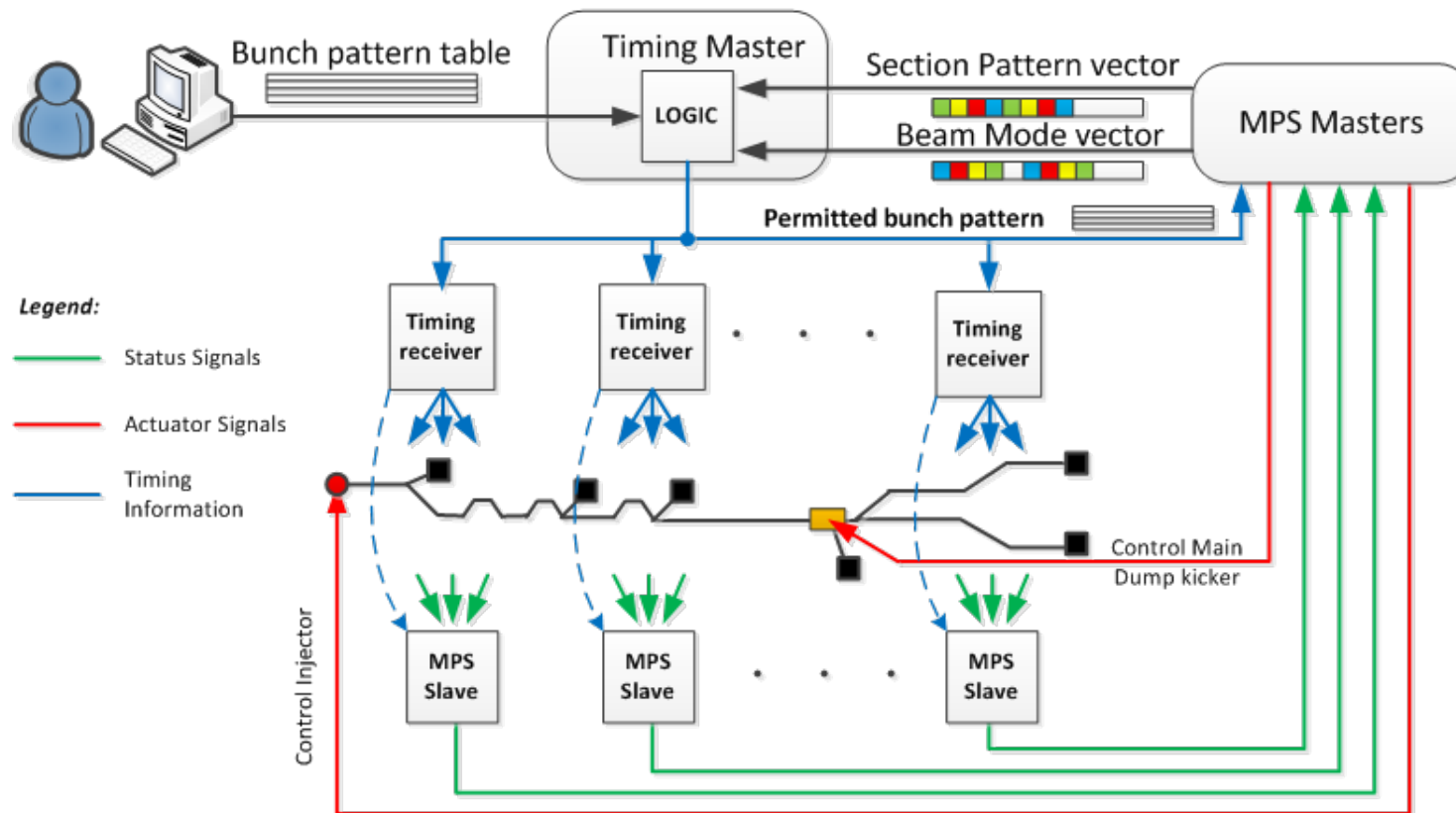


# MPS Inputs – Systems Providing Alarms to MPS



- > In XFEL MPS will receive ~2000 interlock, alarm, error and status signals from ~27 types of systems
- > Alarm signals were provided via **RS422**-conforming twisted-pair copper wires
- > Alarm providing (diagnostic) systems strongly varies in their complexity

# Cooperation Concept with Timing System



- > The operator tells the timing system his/her demanded beam parameters (top left)
- > MPS collects all alarms signals from providing (diagnostic) systems (green lines)
- > MPS evaluates the alarms against current operation modes and sends the appropriate beam limits to the timing system
- > Timing system combines wishes and limits and sends it as bunch pattern tables and triggers, e.g. to laser controller (blue)
- > MPS is also able to bypass the timing system temporarily and control laser and kicker directly (red)

Thank you for your attention!  
Questions and comments are welcome

