Computing correlation functions

LAP08, DESY Zeuthen

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The idea of these lectures

Assume you were given a set of gauge configurations

- you want to compute basic observables like
 - pion mass
 - pion decay constant
 - pion electromagnetic form factor
 - ...
- what has to be done to compute these observables?
- these lectures should provide and explain some tools that are necessary to complete this task
- by no means comprehensive!

Content

1st lecture

- orrelation functions
- quark propagators
 - types of quark sources
 - inversion algorithm
 - sequential sources
 - smearing
 - boundary conditions
- ratios of correlation functions
- the Dublin approach
- deflation

2nd lecture

- implementation of these ideas in chroma
- o do it yourself



Assume generic interpolating operator $O_{\Gamma}^{12}(x) = \bar{\psi}_a(x)\Gamma\psi_b(x)$:

$$C_{2}(\vec{p}, x_{0}) = \sum_{\vec{x}} e^{-i\vec{p}\vec{x}} \left\langle O_{\Gamma'}^{12}(\vec{x}, x_{0}) \left(O_{\Gamma}^{12}(\vec{0}, 0) \right)^{\dagger} \right\rangle_{\text{QCD}}$$



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$$\begin{array}{lll} C_{2}(\vec{\rho},x_{0}) & = & \sum\limits_{\vec{x}} e^{-i\vec{\rho}\vec{x}} \left\langle O_{\Gamma'}^{12}(\vec{x},x_{0}) \left(O_{\Gamma}^{12}(\vec{0},0) \right)^{\dagger} \right\rangle_{\rm QCD} \\ & = & \sum\limits_{\vec{x}} e^{-i\vec{\rho}\vec{x}} \left\langle {\rm Tr} \left\{ S_{1}^{\dagger}(\vec{x},x_{0};\vec{0},0)\gamma_{5}\Gamma' S_{2}(\vec{x},x_{0};\vec{0},0)\gamma_{0}\Gamma^{\dagger}\gamma_{0}\gamma_{5} \right\} \right\rangle_{\rm QCD} \end{array}$$



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2pt-function

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more complicated if disconnected contribution





$$\begin{split} C_{3}(\dots) &= \sum_{\vec{x},\vec{y}} e^{i\vec{p}_{f}\cdot(\vec{x}-\vec{y})} e^{i\vec{p}_{i}\cdot\vec{x}} \langle O_{\Gamma'}(\vec{x},x_{0}) j_{\Gamma_{j}}(\vec{y},y_{0}) O_{\Gamma}^{\dagger}(\vec{0},0) \rangle_{\text{QCD}} \\ &= \sum_{\vec{x},\vec{y}} e^{i\vec{p}_{f}(\vec{x}-\vec{y})} e^{i\vec{p}_{i}\vec{y}} \langle \operatorname{Tr} \left\{ S_{1}(\vec{0},0;\vec{x},x_{0})\Gamma' S_{3}(\vec{x},x_{0};\vec{y},y_{0})\Gamma_{j}S_{2}(\vec{y},y_{0};\vec{0},0)\gamma_{0}\Gamma^{\dagger}\gamma_{0} \right\} \rangle_{\text{QCD}} \\ &= \frac{Z_{j}Z_{f}}{4E_{f}E_{f}} \langle \Gamma'(\vec{p}_{f}) | j_{\Gamma_{j}}(0) | \Gamma_{\Gamma}(\vec{p}_{i}) \rangle_{\text{QCD}} \\ &\times \left\{ \theta(x_{0}-y_{0}) e^{-E_{i}y_{0}-E_{f}(x_{0}-y_{0})} - \theta(y_{0}-x_{0}) e^{-E_{i}(T-y_{0})-E_{f}(y_{0}-x_{0})} \right\} \end{split}$$



Gamma matrices and symmetries

State	$I^G(J^{PC})$	Operator		
$\operatorname{Scalar}(\sigma)$	$1^{-}(0^{++})$	$\overline{u}(x)d(x)$		
	$1^{-}(0^{++})$	$\overline{u}(x)\gamma_4 d(x)$		
Pseudoscalar	$1^{-}(0^{-+})$	$\overline{u}(x)\gamma_5 d(x)$		
	$1^{-}(0^{-+})$	$\overline{u}(x)\gamma_4\gamma_5 d(x)$		
Vector	$1^+(1^{})$	$\overline{u}(x)\gamma_i d(x)$		
	$1^+(1^{})$	$\overline{u}(x)\gamma_i\gamma_4 d(x)$		
Axial (a_1)	$1^{-}(1^{++})$	$\overline{u}(x)\gamma_i\gamma_5 d(x)$		
$\operatorname{Tensor}(b_1)$	$1^+(1^{+-})$	$\overline{u}(x)\gamma_i\gamma_j d(x)$		

Gupta, hep-lat/9807028

Also very helpful: symmetry transformation of lattice propagators

Bernard, Lectures given at TASI '89

- $P: \qquad Q(x,y,[U]) = \gamma^0 Q(x^p,y^p,[U]^p) \gamma^0$
- $T: \qquad Q(x,y,[U]) = \gamma^0 \gamma^5 Q(x^\tau,y^\tau,[U]^\tau) \gamma^5 \gamma^0$
- $C: \qquad Q(x,y,[U]) = \mathcal{C}\widetilde{Q}(y,x,[U]^c)\mathcal{C}^{-1}$
- $H: \qquad Q(x,y,[U]) = \gamma_5 Q^{\dagger}(y,x,[U]) \gamma_5$
- $CH: \qquad Q(x,y,[U]) = \mathcal{C}\gamma_5 Q^*(x,y,[U]^c)\gamma_5 \mathcal{C}^{-1} ,$

where
$$C = \gamma_0 \gamma_2$$
 and $C \gamma_\mu C = -\gamma_\mu^T$

Definition of the propagator $S(\vec{y}, y_0; \vec{x}, x_0)$ - the inverse of the Dirac operator:

$$\underbrace{\mathsf{D}^{ab}_{\alpha\beta}(z,y)}_{(V.43\cdot\mathbb{C})^2} \mathcal{S}^{bc}_{\beta\gamma}(y,x) = \delta(z-x)\delta^{ac}\delta_{\alpha\gamma}$$

e.g. $24^3 \times 64 \times 4 \times 3 = 10616832$ \rightarrow huge!!!! "naive" numerical inversion is impossible

• exact solution: solve N linear problems

$$Dz_1 = e_1, \ldots, Dz_N = e_N$$

where e_i is *i*th column of id_N result: $N \times N$ -matrix $S = [z_1, ..., z_N]$ example: I think nobody has ever done it for LQCD

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result: $N \times n$ -matrix SV with $V = [v_1, \ldots, v_n]$

example: point source propagator (similarly for smeared source props):

 $N \times 12$ -matrix with e.g. $V = [e_1, \dots, e_{12}]$ this corresponds to a propagator from one space-time point to all others (point-to-all propagator)

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• but: $X = VW \approx 1$ through a Monte Carlo method for choosing V and W

before studying different choices for the quark source let's look at how to compute the propagator given a source b

the generic problem: solve

$$Ax = b$$

for the vector *x* this is a minimisation problem: consider

$$f(x) = \frac{1}{2}x^{T}Ax - b^{T}x + c$$

the minimum of this function is

$$f'(x) = 0 = \frac{1}{2}(Ax + x^T A) - b$$

so for positive definite and symmetric A the minimum of f(x) is what we are looking for Ax = b



entertaining reading: An Introduction to the Conjugate Gradient Method Without the Agonizing Pain Edition $1\frac{1}{4}$ by Jonathan Richard Shewchuk

• the problem of finding x is equivalent to find the extremum of a quadratic form

- correlation functions in terms of propagators \checkmark
- $\bullet\,$ algorithm for computation of correlators $\checkmark\,$
- choosing a clever quark source

- $\bullet\,$ correlation functions in terms of propagators $\checkmark\,$
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- choosing a clever quark source
 - point source (nothing to say here)
 - noise source
 - smeared source
 - sequential sources

Noise source

Comp. Phys. Comm. 78 (1994) 256-264

- remember: look for W such that (SV)W = S; i.e. $VW \approx 1$
- the approximation $X = VW \approx 1$ is reached through e.g. a set of individually, identically distributed random numbers $\{\mu_{nl}\}$ where n = 1, ..., N, l = 1, ..., L and which satisfy

$$\mathsf{E}[\mu_{mk}(\mu_{nl})^*] = \delta_{mn}\delta_{kl}$$

(note: $E[\cdot]$ is expectation value over a series of experiments)

- we construct V as $V = \frac{1}{\sqrt{L}} [\mu_{nl}]$
- and $W \equiv (V^*)^T$ to construct

$$X \equiv VW$$

with elements
$$x_{mn} = \frac{1}{L} \sum_{l=1}^{L} \mu_{ml} \mu_{nl}^*$$

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• The noise-average has the following properties

$$\begin{aligned} \mathsf{E}[\mathbf{x}_{mn}] &= \delta_{mn} \\ \mathsf{E}[(\mathbf{x}_{mn} - \delta_{mn})(\mathbf{x}_{pq}^* - \delta_{pq})] &= 0 & \text{if } (mn) \neq (pq) \text{ or } (mn) \neq (qp) \\ \mathsf{E}[|\mathbf{x}_{mn} - \delta_{mn}|^2] &= \frac{1}{L} & \text{if } m \neq n \end{aligned}$$

 let's look at the trace of the propagator (we always look at traces of objects constructed from propagators...)

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$$var[\operatorname{Tr}(SX)] = \sum_{\substack{m,n=1\\m\neq n}} \left\{ \frac{|s_{mn}|^2}{L} + s_{mn}s_{nm}^*E[x_{nm}^2] \right\} + \sum_{n=1}^N |s_{nn}|^2 E[|x_{nn}-1|^2]$$

• choices for the noise source which minimise the variance:

• Z(2)-noise:
$$\mathcal{P}[\eta_{nl} = 1] = \frac{1}{2}$$
 and $\mathcal{P}[\eta_{nl} = -1] = \frac{1}{2}$
since $var[Tr(SX^{Z(2)})] = \sum_{\substack{m \neq n}} \frac{|s_{mn}|^2 + s_{mn}s_{nm^*}}{L}$

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1/2

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since $var[Tr(SX^{Z(2)})] = \sum_{m \neq n} \frac{|s_{mn}|^2 + s_{mn}s_{nm^*}}{L}$

•
$$Z(J)$$
-noise $\mathcal{P}[\mu_{nl}^J = e^{2\pi l j/J}] = \frac{1}{J}$
since $var[\mathcal{T}r(SX^{Z(J)})] = \sum_{m \neq n} \frac{|smp|^2}{L}$

• difficult to say which one is better - depends on term $\sum_{m \neq n} s_{mn} s_{nm}^*$

Constructing meson correlation functions from noise source props

• 2pt function from point source:

$$C_{2}(\vec{0},t) = \sum_{\vec{x}} \left\langle \operatorname{Tr} \left\{ S_{1}^{+}(\vec{x},x_{0};\vec{0},0)\gamma_{5}\Gamma' S_{2}(\vec{x},x_{0};\vec{0},0)\gamma_{0}\Gamma^{+}\gamma_{0}\gamma_{5} \right\} \right\rangle_{\mathrm{QCD}}$$

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• 2pt-function from noise source (one-end trick Phys. Rev. D59 074503 (1999)):

$$\begin{split} C_2(\vec{0},t) &= \sum_{\vec{x},\vec{y}} \left\langle \mathrm{Tr} \left\{ S_1(\vec{y},y_0;\vec{x},x_0) \Gamma' S_2(\vec{x},x_0;\vec{y},y_0) \gamma_0 \Gamma^{\dagger} \gamma_0 \right\} \right\rangle_{\mathrm{QCD}} \\ &\approx \sum_{\vec{y}} \frac{1}{L} \sum_{I} \left\langle \mathrm{Tr} \left\{ \Psi_{1,I}(\vec{y},y_0;x_0) \left(\Psi_{2,I}^{\gamma_5 \Gamma'}(\vec{y},y_0;x_0) \right)^{\dagger} \gamma_5 \gamma_0 \Gamma^{\dagger} \gamma_0 \right\} \right\rangle_{\mathrm{QCD}} \end{split}$$

where

$$\begin{split} \Psi_{1,l}(\vec{y}, y_0; x_0) &= \sum_{\vec{x}} [S_1(\vec{y}, y_0; \vec{x}, x_0)]_{a\alpha b\beta} \underbrace{[\eta_l(\vec{x}, x_0)]_{b,f}}_{\text{noise source}} \\ \Psi_{2,l}^{\gamma_5 \Gamma}(\vec{y}, y_0; x_0) &= \sum_{\vec{x}} S_2(\vec{y}, y_0; \vec{x}, x_0) \underbrace{\gamma_5 \Gamma \eta(\vec{x}, x_0)}_{\text{noise source}} \end{split}$$

$$\begin{array}{lll} i) & \Psi_{l}(\vec{y}, y_{0}; x_{0}) & = & \sum_{\vec{x}} S(\vec{y}, y_{0}; \vec{x}, x_{0}) \eta_{l}(\vec{x}, x_{0}) \\ ii) & \Psi_{l}^{\gamma_{5}\Gamma}(\vec{y}, y_{0}; x_{0}) & = & \sum_{\vec{x}} S(\vec{y}, y_{0}; \vec{x}, x_{0}) \gamma_{5} \Gamma \eta_{l}(\vec{x}, x_{0}) \\ \end{array}$$

• case
$$\Gamma = \gamma_5 \rightarrow \Psi_1^{\gamma_5 \gamma_5} = \Psi_1$$
:
need $\delta_{\kappa\lambda} \delta_{c,d} \delta(\vec{x} - \vec{z}) = \frac{1}{L} \sum_l \eta_l(\vec{x})_{\kappa,c} \eta_l^{\dagger}(\vec{z})_{\lambda,d}$

• general case: $\delta_{c,d}\delta(\vec{x}-\vec{z}) = \frac{1}{L}\sum_{l}\eta_{l}(\vec{x})_{c}\eta_{l}^{\dagger}(\vec{z})_{d}$

in this case we need four noise vectors (spin explicit) in order to properly represent the gamma-structure

- remark for implementation: use your old inverter for noise source most codes expect 3 × 4 inversions. Here only 1 or 4 inversions, respectively, are necessary. Use standard inverter but skip inversion if norm of the source for a given *spin – color*-index vanishes
- I have secretly assumed that the noise source is limited to one time slice. This is called "dilution". The noise can be diluted more (spin-explicit, color-explicit) or e.g. onto the odd and even site on the lattice.

Dilution in time is known to increase the signal/noise in correlation functions

source type	# of inversions	
point source	12	-
single noise vector:	1	times the number of hits
spin explicit noise vector:	4	times the number of hits



study on a unit gauge configuration JHEP 0808:086,2008

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some experience:

 hit-average and gauge-average are often commutative in practice it may suffice to generate only few noise vectors per configuration (since the gauge noise is larger than the noise from the stochastic source)

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- when 'hitting' various times on a gauge configuration move the source along the 0-direction; this reduces correlation effects originating in the gauge configuration
- how well the noise source works compared to the point source seems to be a function of the volume, the quark masses and the observable under investigation.
 example (JHEP 0807:112,2008):

$16^3 \times 32 \times 16$ DWF, $a^{-1} \approx 1.7$ GeV,	$24^3 \times 64 \times 16$ DWF, $a^{-1} \approx 1.7$ GeV,
$m_{\pi} pprox$ 700MeV	$m_{\pi} pprox 330 { m MeV}$
noise source achieves same stat. er-	noise source achieves same stat. er-
ror on m_{π} at half of the price	ror on m_{π} at 1/12th of the price

Yet another source type: Gaussian smearing

Güsken et al.; NPB (Proc. Suppl.) 17 (1990) 361-364

- motivation: phenomenologically immitate what may or may not be the hadron wave function
- thus increase overlap with desired hadronic state
- similar to point source, but smearing out the delta function
- this corresponds to smear out the fermion fields

$$\tilde{\psi}(\vec{x},t) = \sum_{x'} F(\vec{x},\vec{x}')\psi(\vec{x}',t)$$

Gaussian smearing:

$$F(\mathbf{x},\mathbf{x}') = \delta_{\mathbf{x},\mathbf{x}'} + \alpha H(\mathbf{x},\mathbf{x}')$$

with the hopping matrix

$$H(\boldsymbol{x},\boldsymbol{x}') = \sum_{\mu=1}^{3} \left\{ U_{\mu}(\boldsymbol{x}) \delta_{\boldsymbol{x}',\vec{\boldsymbol{x}}+\hat{\mu}} + U_{\mu}^{\dagger}(\boldsymbol{x}-\hat{\mu}) \delta_{\boldsymbol{x}',\boldsymbol{x}-\hat{\mu}} \right\}$$

with coupling α between nearest neighbours

- iterate this starting from a point source
- in the free case approximately gaussian shape and rotationally invariant

Still not enough sources: sequential source propagators

how to construct 3pt-functions?



- problem here: naively one would need an all-to-all propagator
- way out: sequential source propagator Nucl. Phys. B316 (1989) 355

$$\tilde{S}_{13}(\vec{y}, y_0; \vec{p}, x_0; \vec{0}, 0) = \sum_{\vec{x}} S_3(\vec{y}, y_0; \vec{x}, x_0) \underbrace{\gamma_5 \Gamma' \gamma_5 S_1(\vec{x}, x_0, \vec{0}, 0) e^{i\vec{p}\vec{x}}}_{\text{source}}$$

Still not enough sources: sequential source propagators

$$\tilde{S}_{13}(\vec{y}, y_0; \vec{p}_f, x_0; \vec{0}, 0) = \sum_{\vec{x}} S_3(\vec{y}, y_0; \vec{x}, x_0) \underbrace{\gamma_5 \Gamma' \gamma_5 S_1(\vec{x}, x_0, \vec{0}, 0) e^{i\vec{p}_f \vec{x}}}_{\text{source}}$$

can be solved by

$$\sum_{z} D(\vec{z}, z_{0}; \vec{z}', z'_{0}) \tilde{S}(\vec{z}', z'_{0}, \vec{0}, 0) = \sum_{\vec{y}, y_{0}} e^{i \vec{p}_{f} \vec{y}} \delta_{z, y} \gamma_{5} \Gamma^{\dagger} \gamma_{5} S(y, 0)$$

with the source term

$$\sum_{\vec{y}, y_0} e^{i\vec{p}_t \vec{y}} \delta_{z, y} \gamma_5 \Gamma^{\dagger} \gamma_5 S(y, 0) = \begin{cases} 0 & z_4 \neq \text{sink time slice} \\ \gamma_5 \Gamma^{\dagger} \gamma_5 G(\vec{z}, z_0, \vec{0}, 0) e^{i\vec{p}\vec{z}} & z_4 = \text{sink time slice} \end{cases}$$

- new inversions for each Γ and Fourier mode e^{iβx}
- straight forward to implement with noise source
- once Š has been constructed the three point function can be contracted like a two-point function

Comments on 3pt functions

$$\begin{aligned} \bullet \ C_{3} &= \sum_{\vec{x}_{f},\vec{x}} e^{i\vec{p}_{f}\cdot(\vec{x}_{f}-\vec{x})} e^{i\vec{p}_{j}\cdot\vec{x}} \langle \ O_{f}(t_{f},\vec{x}_{f}) j_{\Gamma_{j}}(t,\vec{x}) \ O_{i}^{\dagger}(t_{i},\vec{0}) \rangle \\ &= \sum_{\vec{x},\vec{y}} e^{i\vec{p}_{f}(\vec{x}-\vec{y})} e^{i\vec{p}_{i}\vec{y}} \langle \operatorname{Tr} \left\{ S_{1}(\vec{0},0;\vec{x},x_{0})\Gamma' S_{3}(\vec{x},x_{0};\vec{y},y_{0})\Gamma_{j}S_{2}(\vec{y},y_{0};\vec{0},0)\gamma_{0}\Gamma^{\dagger}\gamma_{0}) \right\} \rangle \\ &= \sum_{\vec{x},\vec{y}} e^{-i\vec{\ell}\rho_{f}-\rho_{i})\vec{y}} \langle \operatorname{Tr} \left\{ \left(\tilde{S}_{31}(\vec{y},y_{0};\vec{\rho}_{i},x_{0};\vec{0},0) \right)^{\dagger} \gamma_{5}\Gamma_{j}S_{2}(\vec{y},y_{0};\vec{0},0)\gamma_{0}\Gamma^{\dagger}\gamma_{0}\gamma_{5}) \right\} \rangle \end{aligned}$$

chroma does not use the γ_0 - so there might be sign issues

Comments on 3pt functions

$$\begin{aligned} \bullet \ C_{3} &= \sum_{\vec{x}_{f},\vec{x}} e^{i\vec{p}_{f}(\vec{x}_{f}-\vec{x})} e^{i\vec{p}_{i}\cdot\vec{x}} \langle \ O_{f}(t_{f},\vec{x}_{f}) j_{\Gamma_{j}}(t,\vec{x}) \ O_{i}^{\dagger}(t_{i},\vec{0}) \rangle \\ &= \sum_{\vec{x},\vec{y}} e^{i\vec{p}_{f}(\vec{x}-\vec{y})} e^{i\vec{p}_{i}\vec{y}} \langle \operatorname{Tr} \left\{ S_{1}(\vec{0},0;\vec{x},x_{0})\Gamma' S_{3}(\vec{x},x_{0};\vec{y},y_{0})\Gamma_{j}S_{2}(\vec{y},y_{0};\vec{0},0)\gamma_{0}\Gamma^{\dagger}\gamma_{0}) \right\} \rangle \\ &= \sum_{\vec{x},\vec{y}} e^{-i(\vec{\rho}_{f}-\rho_{i})\vec{y}} \langle \operatorname{Tr} \left\{ \left(\tilde{S}_{31}(\vec{y},y_{0};\vec{\rho}_{i},x_{0};\vec{0},0) \right)^{\dagger} \gamma_{5}\Gamma_{j}S_{2}(\vec{y},y_{0};\vec{0},0)\gamma_{0}\Gamma^{\dagger}\gamma_{0}\gamma_{5}) \right\} \rangle \end{aligned}$$

chroma does not use the γ_0 - so there might be sign issues • we extract ME of type $\langle P_f(\vec{p}_f) | V_4(0) | P_i(\vec{p}_i) \rangle$

It turns out to be advantageous to extract them from ratios like e.g.

$$R_{1,P_{i}P_{f}}(\vec{p}_{i},\vec{p}_{f}) = 4\sqrt{E_{i}E_{f}}\sqrt{\frac{C_{P_{i}P_{f}}(t,\vec{p}_{i},\vec{p}_{f}) C_{P_{f}P_{i}}(t,\vec{p}_{i},\vec{p}_{i})}{C_{P_{i}}(T/2,\vec{p}_{i}) C_{P_{f}}(T/2,\vec{p}_{i})}},$$

$$R_{2,P_{i}P_{f}}(\vec{p}_{i},\vec{p}_{f}) = 2\sqrt{E_{i}E_{f}}\sqrt{\frac{C_{P_{i}P_{f}}(t,\vec{p}_{i},\vec{p}_{i}) C_{P_{f}P_{i}}(t,\vec{p}_{i},\vec{p}_{i})}{C_{P_{i}P_{i}}(t,\vec{p}_{i},\vec{p}_{i}) C_{P_{f}P_{f}}(t,\vec{p}_{i},\vec{p}_{i})}},$$
(1)

$$R_{3,P_iP_f}(\vec{p}_i,\vec{p}_f) = 4\sqrt{E_iE_f} \frac{C_{P_iP_f}(t,\vec{p}_i,\vec{p}_f)}{C_{P_f}(T/2,\vec{p}_f)} \sqrt{\frac{C_{P_i}(T/2-t,\vec{p}_i)C_{P_f}(t,\vec{p}_i)C_{P_f}(T/2,\vec{p}_f)}{C_{P_f}(T/2-t,\vec{p}_f)C_{P_i}(t,\vec{p}_i)C_{P_i}(T/2,\vec{p}_f)}}.$$

- sometimes cancellation of renormalisation factor
- plateaus look different optimise!
- cancellation of correlations → better signal
- time-dependence cancels these ratios should be constant for large euclidean separations

Twisted boundary conditions

periodic bc's

$$\psi(\mathbf{x}_i + \mathbf{L}) = \psi(\mathbf{x}_i)$$
$$\vec{p}_{quark} = \vec{n} \frac{2\pi}{L}$$
$$\mathbf{E}_{\pi} = \sqrt{m_{\pi}^2 + (\vec{n} \frac{2\pi}{L})^2}$$



PLB 595 (2004) 408, PLB 593 (2004) 82, PLB 609 (2005) 73, PLB 632 (2006) 313

Twisted boundary conditions



PLB 609 (2005) 73, PLB 632 (2006) 313

Twisted boundary conditions - applications

• pion form factor $\langle \pi(p') | V_{\mu}^{\text{elmag}} | \pi(p) \rangle$



Twisted boundary conditions - applications

• pion form factor $\langle \pi(p') | V_{\mu}^{\text{elmag}} | \pi(p) \rangle$



Implementation of partially twisted BC

• twisted bc's
$$\psi(x) = e^{i \frac{\vec{\theta} \cdot \vec{x}}{L}} \tilde{\psi}(x)$$

• Wilson's hopping term:

$$\overline{\tilde{\psi}}(x) \left[e^{i\frac{a\theta_i}{L}} U_i(x)(1-\gamma_i)\tilde{\psi}(x+\hat{i}) + e^{-i\frac{a\theta_i}{L}} U_i^{\dagger}(x-\hat{i})(1+\gamma_i)\tilde{\psi}(x-\hat{i}) \right]$$

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equivalent: replace the link variables

$$\{U_i(x)\} \to \{e^{i\frac{a\theta_i}{L}}U_i(x)\}$$

inverting on phase-shifted gauge field encodes the momentum shift for the valence quarks

Applicable to other discretizations (e.g. DWF)

Kinematics with twisted bc's

2pt-function

$$E_{\pi} = \sqrt{m_{\pi}^2 + (\vec{n}_{L}^{2\pi} + \frac{\vec{\theta}_{u} - \vec{\theta}_{d}}{L})^2}$$

$$q^{2} = (p_{i} - p_{f})^{2} = \left\{ [E_{i}(\vec{p}_{i}) - E_{f}(\vec{p}_{f})]^{2} - \left[(\vec{p}_{\text{FT},i} + \vec{\theta}_{i}/L) - (\vec{p}_{\text{FT},f} + \vec{\theta}_{f}/L) \right]^{2} \right\}$$

- watch out for relative signs of twist angles when you construct the 3pt function
- changing directions of twists can decrease correlation effects
- keep track of direction of twist correlators involving currents in spacial directions depend on the momentum

Some newer developments for computing propagators

- light quark physics is dominated by the low lying eigen modes of the Dirac operator
- noise from noise source propagators often still too large
- idea: separate treatment of low modes and high modes let $Q = \gamma_5 D$ be the herm. dirac operator

$$Q = Q_1 + Q_2 = \sum_{i=1}^{N_{ev}} \lambda_i v^{(i)} v^{(i)\dagger} + \sum_{i=N_{ev}+1}^{N} \lambda_i v^{(i)} v^{(i)\dagger}$$

exact or other inexact treatment treat as a correction by noisey estimator

- exact treatment of the lowmodes: Comp. Phys Comm. 172 (2005) 145162
- inexact treatment of the lowmodes: JHEP07 (2007) 081
- the orthogonal complement can be corrected for by noise source techniques

The Dublin approach

Comp. Phys Comm. 172 (2005) 145162

• also two pieces for the quark propagator $Q^{-1} = \tilde{Q}_0 + \tilde{Q}_1$: \tilde{Q}_0 is low mode part and $\tilde{Q}_1 = Q^{-1} \mathcal{P}_1$

$$\mathcal{P}_1 = 1 - \mathcal{P}_0 = 1 - \sum_{j=1}^{N_{ev}} v^{(j)} v^{j+1}$$

- correct for Q
 ₁ via N_d × L diluted noise vectors {(η₁⁽¹⁾,...,η_L⁽¹⁾),...,(η₁^(N_d),...,η_L^(N_d))} (due to diluation the noise vectors are mutually orthogonal before taking the noise average)
- the hybrid estimate for the all-to-all prop (for a single noise vector then is $\sum_{i=1}^{N_{ev+N_d}} u^{(i)}(\vec{x}, x_0) w^{(i)}(\vec{y}, y_0)^{\dagger} \gamma_5$ where

$$\begin{split} \mathbf{w}^{(i)} &= \left\{ \frac{\mathbf{v}^{(1)}}{\lambda_1}, \dots, \frac{\mathbf{v}^{(N_{ev})}}{i\lambda_{N_{ev}}}, \eta^{(1)}, \dots, \eta^{(N_d)} \right\} \text{ and } \\ \mathbf{u}^{(i)} &= \left\{ \mathbf{v}^{(1)}, \dots, \mathbf{v}^{(N_{ev})}, \psi^{(1)}, \dots, \psi^{(N_d)} \right\} \end{split}$$

- construct observables from these vectors
- we don't know the optimal number of low modes (they are expensive to construct)
- again volume, quark mass and the observable under consideration do play a role

Approximate quark modes by constant modes

JHEP07 (2007) 081

- Lüscher splits the lattice of spatial extent *L* into *b* sub lattices (domain decomposition)
- on each sub-lattice there are 12 constant modes
- approximation of a global plane wave is already well described by this with small "deficit"
- works if fields are smooth on scale of block size b



Application to QCD

- free field far away from QCD
- helpful observation local coherence:

"... a set of quark fields is referred to as locally coherent if the fields are locally well approximated by a relatively small numer of fields ..."

- this is in fact the case in lattice QCD numerical test compute eigenmodes of DD^t and a domain decomposed subset of these low modes
- test on 64 × 32³-lattice devided into 4⁴-blocks and 12 out of 48 computed eigenmodes selected to construct the domain decomposed sub spaces
- result: the remaining 36 low modes are indeed "coherent" with very small deficits

• open questions:

economic/optimised way to construct deflation modes Lüscher uses relaxation by repeatedly applying the propagator to a random field can one do better?

• can the low modes be applied effectively to the construction of correlation functions like in the Dublin approach?

i	<i>n</i> ₄ <i>n</i> ₃ <i>n</i> ₂ <i>n</i> ₁	Γ _i	equivalent	sink insertion 3pt
0	0000	1	1	a0-a0
1	0001	γ_1	<i>γ</i> 1	a0-rho x 1
2	0010	Y2	Y2	a0-rho y 1
3	0011	$\gamma_1\gamma_2$	$\gamma_1\gamma_2$	a0-b1 z 1
4	0100	γз	γз	a0-rho z
5	0101	$\gamma_1\gamma_3$	Y1Y3	a0-b1 y 1
6	0110	Y2Y3	Y2Y3	a0-b1 x 1
7	0111	$\gamma_1\gamma_2\gamma_3$	$\gamma_5\gamma_4$	a0-pion 2
8	1000	γ4	γ4	a0-a0 2
9	1001	$\gamma_1\gamma_4$	$\gamma_1\gamma_4$	a0-rho x 2
10	1010	Y2Y4	Y2Y4	a0-rho y 2
11	1011	$\gamma_1\gamma_2\gamma_4$	Y3Y5	a0-a1 z 1
12	1100	$\gamma_3\gamma_4$	Y3Y4	a0-rho z 2
13	1101	$\gamma_1\gamma_3\gamma_4$	Y5Y2	a0-a1 y 1
14	1110	Y2Y3Y4	$\gamma_1\gamma_5$	a0-a1 x 1
15	1111	γ_5	γ_5	a0-pion