

Loops and legs master integrals for splitting functions from differential equations in QCD

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Splitting functions in perturbative QCD

- process independent quantities
- govern collinear evolution of hard scattering processes with hadrons
 - parton distribution functions in the initial state
(a space-like hard scale $Q^2 = -q^2 > 0$)

$$\frac{d}{d \ln q^2} f_a^h(x, q^2) = \int_x^1 \frac{dz}{z} P_{ab}^S(z, \alpha_s(q^2)) f_b^h\left(\frac{x}{z}, q^2\right)$$

- fragmentation functions in the final state
(a time-like hard scale $Q^2 = q^2 > 0$)

$$\frac{d}{d \ln q^2} D_a^h(x, q^2) = \int_x^1 \frac{dz}{z} P_{ba}^T(z, \alpha_s(q^2)) D_b^h\left(\frac{x}{z}, q^2\right)$$

- expanded in perturbation theory, e.g.,

$$P_{ab}^T(x, \alpha_s) = \frac{\alpha_s}{4\pi} P_{ab}^{T(0)}(x) + \left(\frac{\alpha_s}{4\pi}\right)^2 P_{ab}^{T(1)}(x) + \left(\frac{\alpha_s}{4\pi}\right)^3 P_{ab}^{T(2)}(x) + \dots$$

Analytical expression for $P_{qg}^{T(2)}$ is known with a **small uncertainty**.

Splitting functions at NLO

Space-like

- Axial gauge
 - Principal Value
Curci Furmanski Petronzio '80
Ellis Vogelsang '98
 - Mandelstam-Leibbrandt
Bassetto Heinrich Kunstz Vogelsang '98
 - New Principal Value
OG Jadach Skrzypek Kusina '14
- Feynman gauge
 - x space
Floratos Kounnas Lacaze '81
 - Mellin space Moch Vermaseren '99

Time-like

- Axial gauge
 - Principal Value
Furmanski Petronzio '80
- Feynman gauge
 - x space
Floratos Kounnas Lacaze '81
Rijken, van Neerven '96
 - Mellin space Mitov Moch '06
- analytic cont. $-q^2 \rightarrow +q^2$
Stratmann Vogelsang '96
Blumlein, Ravindran, van Neerven '00
Moch Vogt '07
 - Drell-Yan-Levy relation
Drell Levy Yan '70
 - Gribov-Lipatov relation
Gribov Lipatov '72

Splitting functions at NNLO

Space-like

- Axial gauge*
 - Feynman gauge
 - Mellin space
- Moch Vermaseren Vogt '04

Time-like

- Axial gauge*
- analytic continuation
$$P_{ab}^{S(2)} \rightarrow P_{ba}^{T(2)}$$
 - NNLO non-singlet
Mitov Moch Vogt '06
 - NNLO singlet $P_{qq}^{T(2)}$ and $P_{gg}^{T(2)}$
Moch Vogt '07
 - NNLO singlet $P_{gq}^{T(2)}$ and $P_{qg}^{T(2)}$
Almasy Moch Vogt '11

* Spurious poles of axial gauge are too complex at NNLO.

- How can we find a missing contribution to $P_{qg}^{T(2)}$ splitting function?
- Well, let us try to calculate it explicitly!

In this talk

- I will briefly discuss how to extract $P_{qg}^{T(NNLO)}$ from $e^+e^- \rightarrow 3$ jets at NNLO.
- We will see that to solve this (and many other problems in QFT) we need tools for automatic calculation of master integrals.
- I will introduce **Fuchsia** — program for reducing differential equations for master integrals to canonical form based on the Lee algorithm.
- We will consider $P_{gq}^{T(NLO)}$ as a demonstration example.
- At the very end I will discuss current status of the **Fuchsia** project.

e⁺e⁻ → γ* → 3 jets

$$\frac{d^2\sigma}{dx d\cos\theta} = \frac{3}{8}(1 + \cos^2\theta) \mathcal{F}_T(x, \epsilon) + \frac{3}{4}\sin^2\theta \mathcal{F}_L(x, \epsilon) + \frac{3}{4}\cos\theta \mathcal{F}_A(x, \epsilon)$$

- Transverse fragmentation functions

$$\mathcal{F}_T(x, \epsilon) \simeq (x^2 g^{\mu\nu} + 4k_0^\mu k_0^\nu) W_{\mu\nu}(x, \epsilon), \quad x = 2q \cdot k_0$$

- Hadronic tensor

$$W_{\mu\nu}(x, \epsilon) \simeq \int d^m \text{PS}^{(n)} M_\mu^{(n)} M_\nu^{(n)*}$$

where $d^m \text{PS}^{(n)}$ is n -particle phase-space in $m = 4 - 2\epsilon$ dimensions and $M_\mu^{(n)}$ is amplitude of the process

Example: LO contribution

$$\mathcal{F}_T^{(1)}(x, \epsilon) \equiv \text{diagram} \simeq (x^2 g^{\mu\nu} + 4k_0^\mu k_0^\nu) \int d^m \text{PS}^{(3)} \left(\text{diagram}_1 + \text{diagram}_2 \right)^2$$

$$d^m \text{PS}^{(3)} = \underbrace{d^m k_0 \delta^+(k_0^2)}_{\text{gluon}} \underbrace{d^m k_1 \delta^+(k_1^2)}_{\text{quark}} \underbrace{d^m k_2 \delta^+(k_2^2)}_{\text{anti-quark}} \delta(x - 2q \cdot k_0) \delta^m(q - k_0 - k_1 - k_2)$$

Mass factorization for $\mathcal{F}_T(x, \epsilon)$

Vermaseren, Vogt, Moch '05

We can extract splitting functions on the rhs ($P_{gq}^{(0)}, P_{gq}^{(1)}, P_{gq}^{(2)}$) when we know the lhs of the following expressions

- $$\mathcal{F}_T^{(1)}(x, \epsilon) = \frac{1}{\epsilon} P_{gq}^{(0)}(x) + c_{T,g}^{(1)}(x) + \epsilon a_{T,g}^{(1)}(x) + \epsilon^2 b_{T,g}^{(1)}(x)$$
- $$\begin{aligned} \mathcal{F}_T^{(2)}(x, \epsilon) &= \frac{1}{\epsilon^2} \left\{ \frac{1}{2} P_{gi}^{(0)} P_{iq}^{(0)} + \frac{1}{2} \beta_0 P_{gq}^{(0)} \right\} - \frac{1}{\epsilon} \left\{ \frac{1}{2} P_{gq}^{(1)} + P_{gi}^{(0)} c_i^{(1)} \right\} \\ &+ \left\{ c_g^{(2)} - P_{gi}^{(0)} a_i^{(1)} \right\} + \epsilon \left\{ a_g^{(2)} - P_{gi}^{(0)} b_i^{(1)} \right\} \end{aligned}$$
- $$\begin{aligned} \mathcal{F}_T^{(3)}(x, \epsilon) &= \frac{1}{\epsilon^3} \left\{ \frac{1}{6} P_{gi}^{(0)} P_{ij}^{(0)} P_{jq}^{(0)} + \frac{1}{2} \beta_0 P_{gi}^{(0)} P_{iq}^{(0)} + \frac{1}{3} \beta_0^2 P_{gq}^{(0)} \right\} \\ &+ \frac{1}{\epsilon^2} \left\{ \frac{1}{6} P_{gi}^{(0)} P_{iq}^{(1)} + \frac{1}{3} P_{gi}^{(1)} P_{iq}^{(0)} + \frac{1}{3} \beta_1 P_{gq}^{(0)} + \frac{1}{2} P_{gi}^{(0)} P_{ij}^{(0)} c_j^{(1)} + \beta_0 \left(\frac{1}{3} P_{gq}^{(1)} + \frac{1}{2} P_{gi}^{(0)} c_i^{(1)} \right) \right\} \\ &- \frac{1}{\epsilon} \left\{ \frac{1}{3} P_{gq}^{(2)} + \frac{1}{2} P_{gi}^{(1)} c_i^{(1)} + P_{gi}^{(0)} c_i^{(2)} - \frac{1}{2} P_{gi}^{(0)} P_{ij}^{(0)} a_j^{(1)} - \frac{1}{2} \beta_0 P_{gi}^{(0)} a_i^{(1)} \right\} \\ &+ \left\{ c_g^{(3)} - P_{gi}^{(0)} a_i^{(2)} - \frac{1}{2} P_{gi}^{(1)} a_i^{(1)} + \frac{1}{2} P_{gi}^{(0)} P_{ij}^{(0)} b_j^{(1)} + \frac{1}{2} \beta_0 P_{gi}^{(0)} b_i^{(1)} \right\} \end{aligned}$$

Feynman integrals for $\mathcal{F}_T(x, \epsilon)$

$$\mathcal{F}_T^{(NNLO)}(x, \epsilon) = \underbrace{\text{diagram 1} + \text{diagram 2}}_{RR} + \underbrace{\text{diagram 3}}_{RV} + \underbrace{\text{diagram 4} + \text{diagram 5}}_{VV}$$

$$d^m \text{PS}^{VV} = \underbrace{d^m l_1}_{\text{loop \#1}} \underbrace{d^m l_2}_{\text{loop \#2}} \underbrace{d^m k_0 \delta(k_0^2)}_{\text{leg \#1}} \underbrace{d^m k_1 \delta(k_1^2)}_{\text{leg \#2}} \underbrace{d^m k_2 \delta(k_2^2)}_{\text{leg \#3}} \\ \times \delta^m(q - k_0 - k_1 - k_2) \delta(x - 2q \cdot k_0)$$

Perfectly suits for **IBP reduction**:

- Loops and Legs integrals are reduced simultaneously
- $\delta(x - 2q \cdot k_0)$ and $\delta(k_i^2)$ are replaced by cut propagators, i.e., according to Cutkosky's rules
- LiteRed and Reduze2 have support for cut propagators
- define system of differential equations in x -space

Fuchsia project

Gituliar, Magerya '16 (in preparation)

Fuchsia is a program for reducing differential equations for master integrals to the **canonical form** Henn '13:

- based on the **Lee algorithm** Lee '14
- open-source and free (no proprietary software dependencies)
- implemented in SageMath (Python, Maxima, GiNaC)

The idea is to find a **rational transformation** in three reduction steps:

1. **Fuchsification** decrease Poincaré rank to 0 at all singular points (i.e. get rid of irregular singularities)
2. **Normalization**: balance eigenvalues to $n\epsilon$ form
3. **Factorization**: reduce to canonical form

Notation and definitions

Let us consider a system of ODEs

$$\frac{d\bar{f}}{dx} = \mathbb{A}(x, \epsilon) \bar{f},$$

where $\bar{f}(x, \epsilon)$ is a vector of n unknown functions (e.g., master integrals).

$$\mathbb{A}(x, \epsilon) = \sum_k \frac{1}{(x - x_k)^{1+p_k}} \sum_{i=0}^{\infty} A_{ik}(\epsilon)(x - x_k)^i$$

For any system we can define an integer number

$$m_{x=x_k}(\mathbb{A}) = p_k \geq 0$$

as a **Poincaré rank** of \mathbb{A} at $x = x_k$.

For $\mathbb{B} = \begin{pmatrix} \frac{\epsilon}{x} & 0 \\ -\frac{\epsilon}{x^2} & \frac{\epsilon}{1+x} \end{pmatrix}$ we have $m_{x=0} = 1$ and $m_{x=-1} = 0$.

Step I: Fuchsification

We say that such matrix has **Fuchsian form**¹ if its Poincaré rank is 0 at every singular point (including ∞).

For example, we can transform

$$\mathbb{B} = \begin{pmatrix} \frac{\epsilon}{x} & 0 \\ -\frac{\epsilon}{x^2} & \frac{\epsilon}{1+x} \end{pmatrix} \text{ to } \begin{pmatrix} \frac{\epsilon}{x} & 0 \\ -\frac{1}{x} & \frac{\epsilon}{1+x} + \frac{1}{x} \end{pmatrix} \text{ with } m(\mathbb{B}) = 0 \text{ at any point.}$$

Not every system can be transformed to the Fuchsian form, however

- due to the analyticity of S-matrix; and
- structure of the Feynman integrals

every system for master integrals should, in principle, be reducible to Fuchsian form.

Fuchsia finds Fuchsian form and transformation matrix of rational functions by analyzing Jordan form of the input matrix.

¹after German mathematician Lazarus Fuchs (1833–1902)

Example: differential equations for $P_{gq}^T(1)$ at NLO

Input

$$\left(\begin{array}{cccccccc} \frac{(2\epsilon-1)(2x-1)}{x(1-x)} & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \frac{3\epsilon-2}{x(1-x)} & \frac{1-3\epsilon}{x} & 0 & 0 & 0 & 0 & 0 & 0 \\ \frac{x(1-x)}{(2\epsilon-1)} & 0 & \frac{1-6\epsilon}{x+1} & \frac{2}{x+1} & 0 & 0 & 0 & 0 \\ \epsilon^2 x(1-x)(x+1) & -\frac{(2\epsilon-1)(3\epsilon-1)}{x^2} & \frac{2(6\epsilon-1)}{x(x+1)} & \frac{2\epsilon(x^2+3x-2)}{(1-x)x(x+1)} & 0 & 0 & 0 & 0 \\ \frac{\epsilon x^2(x+1)}{2(x^2+4x+1)} & \frac{2(2\epsilon-1)(x-1)}{\epsilon x^3(x+1)^2} & \frac{2(6\epsilon-1)(x-1)}{x^2(x+1)^3} & \frac{4(x^2+1)}{x^2(x+1)^3} & -\frac{(2\epsilon+1)(2x+1)}{x(x+1)} & 0 & 0 & 0 \\ 0 & -\frac{(2\epsilon-1)}{\epsilon(1-x)x} & 0 & 0 & 0 & \frac{2\epsilon}{1-x} & 0 & 0 \\ -\frac{4}{\epsilon^2(1-x)^3 x^3(x+1)} & -\frac{2(2\epsilon-1)(x-2)}{\epsilon(1-x)^2 x^3} & -\frac{2(6\epsilon-1)}{x^2(1-x)(x+1)} & \frac{4(x^2+1)}{(1-x)^2 x^2(x+1)} & 0 & -\frac{4\epsilon}{(1-x)^2 x} & \frac{(2\epsilon+1)(2x-1)}{(1-x)x} & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & \frac{(2\epsilon+1)(2x-1)}{(1-x)x} \end{array} \right)$$

Output

$$\left(\begin{array}{cccccccc} \frac{(2\epsilon-1)(2x-1)}{x(1-x)} & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \frac{1}{x(1-x)} & \frac{1-3\epsilon}{x} & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & \frac{1}{1-x} & \frac{1+(2\epsilon-1)x}{x(1-x)} & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{(1+2\epsilon)(2x-1)}{x(1-x)} & 0 & 0 & 0 & 0 \\ \frac{\epsilon}{x(1+x)} & \frac{\epsilon^2}{x} & 0 & 0 & \frac{(2\epsilon-1)x^2+6\epsilon x-4\epsilon+1}{x(1-x)(x+1)} & \frac{\epsilon}{x(1+x)} & 0 & 0 \\ \frac{2(6\epsilon-1)}{(1-x)(1+x)} & 0 & 0 & 0 & \frac{4(6\epsilon-1)}{1+x} & \frac{1-2(3\epsilon-1)x}{x(1+x)} & 0 & 0 \\ \frac{(14\epsilon-3)x+22\epsilon-3}{2\epsilon(1-x)x(1+x)} & \frac{\epsilon x-5\epsilon+2}{x(1-x)} & \frac{4\epsilon^2}{x} & 0 & \frac{(2\epsilon-3)x^2-18\epsilon+8x+11}{\epsilon x(1-x)(1+x)} & \frac{(4\epsilon-3)x^2-2(2\epsilon-3)x+9}{4\epsilon x(1-x)(1+x)} & \frac{(4\epsilon-1)x-2\epsilon}{x(1-x)} & \frac{4\epsilon+x-3}{2x(1-x)} \\ \frac{4}{x(1-x)(1+x)} & \frac{4\epsilon}{x} & 0 & 0 & \frac{8(x^2+2x-1)}{x(1-x)(1+x)} & \frac{x+3}{x(1+x)} & 0 & \frac{(2\epsilon+1)(2x+1)}{x(1+x)} \end{array} \right)$$

Step II: Normalization

We say that matrix $\mathbb{A}(\mathbf{x}, \epsilon)$ is **normalized** if eigenvalues of all its residues have form $m\epsilon$, where m is some number.

We assume that initial eigenvalues have form $n + m\epsilon$, where n is integer

A key idea for Lee's normalization algorithm is a **balance transformation** between two points x_1 and x_2

$$\mathbb{T}(x) = \mathcal{B}(\mathbb{P}, x_1, x_2; x) = 1 - \mathbb{P}(\epsilon) + \frac{x - x_2}{x - x_1} \mathbb{P}(\epsilon)$$

where $\mathbb{P}(\epsilon)$ is some projector matrix, i.e. $\mathbb{P}^2 = \mathbb{P}$.

We choose

- points x_1 and x_2 by analyzing eigenvalues
- projector $\mathbb{P}(\epsilon)$ by analyzing eigenvectors

Example: eigenvalues for x_1 and x_2 :

$x_1 = 0$:

$$[1-4\epsilon, 1-3\epsilon, -1-2\epsilon, -2\epsilon, 1-2\epsilon, 1-2\epsilon, 1, 1]$$

$x_2 = 1$:

$$[-1-2\epsilon, -2\epsilon, -2\epsilon, 1-2\epsilon, 1-2\epsilon, 0, 0, 0]$$

Input

$$\left(\begin{array}{cccccccc} \frac{(2\epsilon-1)(2x-1)}{x(1-x)} & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \frac{1}{x(1-x)} & \frac{1-3\epsilon}{x} & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & \frac{1}{1-x} & \frac{1+(2\epsilon-1)x}{x(1-x)} & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{(1+2\epsilon)(2x-1)}{x(1-x)} & 0 & 0 & 0 & 0 \\ \frac{\epsilon}{x(1+x)} & \frac{\epsilon^2}{x} & 0 & 0 & \frac{(2\epsilon-1)x^2+6\epsilon x-4\epsilon+1}{x(1-x)(x+1)} & \frac{\epsilon}{x(1+x)} & 0 & 0 \\ \frac{2(6\epsilon-1)}{(1-x)(1+x)} & 0 & 0 & 0 & \frac{4(6\epsilon-1)}{1+x} & \frac{1-2(3\epsilon-1)x}{x(1+x)} & 0 & 0 \\ \frac{(14\epsilon-3)x+22\epsilon-3}{2\epsilon(1-x)x(1+x)} & \frac{\epsilon x-5\epsilon+2}{x(1-x)} & \frac{4\epsilon^2}{x} & 0 & \frac{(2\epsilon-3)x^2-18\epsilon+8x+11}{\epsilon x(1-x)(1+x)} & \frac{(4\epsilon-3)x^2-2(2\epsilon-3)x+9}{4\epsilon x(1-x)(1+x)} & \frac{(4\epsilon-1)x-2\epsilon}{x(1-x)} & \frac{4\epsilon+x-3}{2x(1-x)} \\ \frac{4}{x(1-x)(1+x)} & \frac{4\epsilon}{x} & 0 & 0 & \frac{8(x^2+2x-1)}{x(1-x)(1+x)} & \frac{x+3}{x(1+x)} & 0 & \frac{(2\epsilon+1)(2x+1)}{x(1+x)} \end{array} \right)$$

Output

$$\left(\begin{array}{cccccccc} \frac{2\epsilon}{1-x} - \frac{2\epsilon}{x} & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \frac{1}{x} & -\frac{3\epsilon}{x} & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & \frac{1}{1-x} & \frac{2\epsilon}{1-x} & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{2\epsilon}{1-x} - \frac{2\epsilon}{x} & 0 & 0 & 0 & 0 \\ \frac{3}{x} & \frac{\epsilon}{x} & 0 & 0 & \frac{2\epsilon}{1-x} + \frac{4\epsilon}{x} & -\frac{1}{x} & 0 & 0 \\ \frac{6\epsilon}{1+x} + \frac{6\epsilon}{1-x} + \frac{16\epsilon}{x} & \frac{8\epsilon^2}{x} - \frac{4\epsilon^2}{1+x} & 0 & 0 & \frac{12\epsilon^2}{1+x} + \frac{12\epsilon^2}{1-x} + \frac{32\epsilon^2}{x} & -\frac{2\epsilon}{1+x} - \frac{8\epsilon}{x} & 0 & 0 \\ \frac{4}{x} - \frac{2}{1-x} & \frac{4\epsilon}{1-x} + \frac{8\epsilon}{x} & \frac{4\epsilon^2}{1-x} - \frac{4\epsilon^2}{x} & 0 & \frac{16\epsilon}{x} - \frac{4\epsilon}{1-x} & -\frac{3}{x} & \frac{2\epsilon}{1-x} - \frac{2\epsilon}{x} & 0 \\ \frac{6}{1+x} - \frac{8}{x} & \frac{4\epsilon}{1+x} - \frac{4\epsilon}{x} & 0 & 0 & \frac{8\epsilon}{1+x} - \frac{4\epsilon}{1-x} - \frac{16\epsilon}{x} & \frac{3}{x} + \frac{2}{1+x} & 0 & -\frac{2\epsilon}{1+x} - \frac{2\epsilon}{x} \end{array} \right)$$

Output

$$\begin{pmatrix} \frac{2\epsilon}{1-x} - \frac{2\epsilon}{x} & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \frac{1}{x} & -\frac{3\epsilon}{x} & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & \frac{1}{1-x} & \frac{2\epsilon}{1-x} & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{2\epsilon}{1-x} - \frac{2\epsilon}{x} & 0 & 0 & 0 & 0 & 0 \\ \frac{3}{x} & \frac{\epsilon}{x} & 0 & 0 & \frac{2\epsilon}{1-x} + \frac{4\epsilon}{x} & -\frac{1}{x} & 0 & 0 & 0 \\ \frac{6\epsilon}{1+x} + \frac{6\epsilon}{1-x} + \frac{16\epsilon}{x} & \frac{8\epsilon^2}{x} - \frac{4\epsilon^2}{1+x} & 0 & 0 & \frac{12\epsilon^2}{1+x} + \frac{12\epsilon^2}{1-x} + \frac{32\epsilon^2}{x} & -\frac{2\epsilon}{1+x} - \frac{8\epsilon}{x} & 0 & 0 & 0 \\ \frac{4}{x} - \frac{2}{1-x} & \frac{4\epsilon}{1-x} + \frac{8\epsilon}{x} & \frac{4\epsilon^2}{1-x} - \frac{4\epsilon^2}{x} & 0 & \frac{16\epsilon}{x} - \frac{4\epsilon}{1-x} & -\frac{3}{x} & \frac{2\epsilon}{1-x} - \frac{2\epsilon}{x} & 0 & 0 \\ \frac{6}{1+x} - \frac{8}{x} & \frac{4\epsilon}{1+x} - \frac{4\epsilon}{x} & 0 & 0 & \frac{8\epsilon}{1+x} - \frac{4\epsilon}{1-x} - \frac{16\epsilon}{x} & \frac{3}{x} + \frac{2}{1+x} & 0 & -\frac{2\epsilon}{1+x} - \frac{2\epsilon}{x} & 0 \end{pmatrix}$$

Eigenvalues before and after normalization:

$x=0$:

$$[1-4\epsilon, 1-3\epsilon, -1-2\epsilon, -2\epsilon, 1-2\epsilon, 1-2\epsilon, 1, 1] \rightarrow [-4\epsilon, -3\epsilon, -2\epsilon, -2\epsilon, -2\epsilon, -2\epsilon, 0, 0]$$

$x=1$:

$$[-1-2\epsilon, -2\epsilon, -2\epsilon, 1-2\epsilon, 1-2\epsilon, 0, 0, 0] \rightarrow [-2\epsilon, -2\epsilon, -2\epsilon, -2\epsilon, -2\epsilon, 0, 0, 0]$$

$x=-1$:

$$[1-2\epsilon, 1-2\epsilon, 0, 0, 0, 0, 0, 0] \rightarrow [-2\epsilon, -2\epsilon, 0, 0, 0, 0, 0, 0]$$

$x=\infty$:

$$[-1+2\epsilon, -1+2\epsilon, -1+3\epsilon, -2+4\epsilon, -2+4\epsilon, -1+4\epsilon, 1+4\epsilon, -2+6\epsilon] \rightarrow [2\epsilon, 2\epsilon, 3\epsilon, 4\epsilon, 4\epsilon, 4\epsilon, 4\epsilon, 6\epsilon]$$

Step III: Factorization

Now we can find an x -independent transformation $\mathbb{T}(\epsilon)$ for any point $x = x_k$ such that

$$\mathbb{T}^{-1}(\epsilon)\mathbb{A}_k(\epsilon)\mathbb{T}(\epsilon) = \epsilon\mathbb{C}_k$$

Since matrix \mathbb{C}_k is constant, for every residue of \mathbb{A} we write

$$\frac{\mathbb{T}^{-1}(\epsilon)\mathbb{A}_k(\epsilon)\mathbb{T}(\epsilon)}{\epsilon} = \mathbb{C}_k = \frac{\mathbb{T}^{-1}(\mu)\mathbb{A}_k(\mu)\mathbb{T}(\mu)}{\mu}, \quad \mu = \text{any number}$$

We treat components of \mathbb{T} as unknown variables and solve linear system of equations for them. That gives unknown transformation $\mathbb{T}(\epsilon)$.

Input

$$\begin{pmatrix} \frac{2\epsilon}{1-x} - \frac{2\epsilon}{x} & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \frac{1}{x} & -\frac{3\epsilon}{x} & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & \frac{1}{1-x} & \frac{2\epsilon}{1-x} & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{2\epsilon}{1-x} - \frac{2\epsilon}{x} & 0 & 0 & 0 & 0 & 0 \\ \frac{3}{x} & \frac{\epsilon}{x} & 0 & 0 & \frac{2\epsilon}{1-x} + \frac{4\epsilon}{x} & -\frac{1}{x} & 0 & 0 & 0 \\ \frac{6\epsilon}{1+x} + \frac{6\epsilon}{1-x} + \frac{16\epsilon}{x} & \frac{8\epsilon^2}{x} - \frac{4\epsilon^2}{1+x} & 0 & 0 & \frac{12\epsilon^2}{1+x} + \frac{12\epsilon^2}{1-x} + \frac{32\epsilon^2}{x} & -\frac{2\epsilon}{1+x} - \frac{8\epsilon}{x} & 0 & 0 & 0 \\ \frac{4}{x} - \frac{2}{1-x} & \frac{4\epsilon}{1-x} + \frac{8\epsilon}{x} & \frac{4\epsilon^2}{1-x} - \frac{4\epsilon^2}{x} & 0 & \frac{16\epsilon}{x} - \frac{4\epsilon}{1-x} & -\frac{3}{x} & \frac{2\epsilon}{1-x} - \frac{2\epsilon}{x} & 0 & 0 \\ \frac{6}{1+x} - \frac{8}{x} & \frac{4\epsilon}{1+x} - \frac{4\epsilon}{x} & 0 & 0 & \frac{8\epsilon}{1+x} - \frac{4\epsilon}{1-x} - \frac{16\epsilon}{x} & \frac{3}{x} + \frac{2}{1+x} & 0 & -\frac{2\epsilon}{1+x} - \frac{2\epsilon}{x} & 0 \end{pmatrix}$$

Output

$$\begin{pmatrix} \frac{2}{1-x} - \frac{2}{x} & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ -\frac{1}{19x} & -\frac{3}{x} & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & -\frac{1}{19(1-x)} & \frac{2}{1-x} & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{2}{1-x} - \frac{2}{x} & 0 & 0 & 0 & 0 & 0 \\ \frac{3}{x} & -\frac{19}{x} & 0 & 0 & \frac{2}{1-x} + \frac{4}{x} & -\frac{1}{x} & 0 & 0 & 0 \\ \frac{6}{1+x} + \frac{6}{1-x} + \frac{16}{x} & \frac{76}{1+x} - \frac{152}{x} & 0 & 0 & \frac{12}{1+x} + \frac{12}{1-x} + \frac{32}{x} & -\frac{2}{1+x} - \frac{8}{x} & 0 & 0 & 0 \\ \frac{19(1-x)}{8} - \frac{4}{19x} & \frac{4}{(1-x)} + \frac{8}{x} & \frac{76}{x} - \frac{76}{1-x} & \frac{4}{19(1-x)} - \frac{16}{19x} & 0 & \frac{3}{19x} & \frac{2}{1-x} - \frac{2}{x} & 0 & 0 \\ \frac{8}{19x} - \frac{6}{19(1+x)} & \frac{4}{1+x} - \frac{4}{x} & 0 & 0 & \frac{4}{19(1-x)} + \frac{16}{19x} - \frac{8}{19(1+x)} & \frac{2}{19(1+x)} - \frac{3}{19x} & 0 & -\frac{2}{1+x} - \frac{2}{x} & 0 \end{pmatrix}$$

Summary

Fuchsia — a tool for reducing differential equations for master integrals to canonical form

- all main algorithms from [Lee '14](#)
- open-source and free (SageMath: Python, Maxima, GiNaC)

A little bit of optimization and we are ready for release!

Please, send us some examples of your systems.

Stay tuned we will release soon

Thank you!