Adaptive Unitarity and Magnus Exponential for Scattering Amplitudes

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based on the collaborations with:

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Motivation

Amplitudes & Phenomenology

Developing an algorithm for multi-loop many-leg processes

Extending the NLO automation at high high orders

From the beauty of simple formulas (in special kinematics) to the beauty of the structures (in arbitrary kinematics)

Path

Multi-loop Integrand Reduction: exploiting dimensional regularization
Revisiting the 1-loop decomposition

Novel decomposition @ any loop: the 2-loop case to begin with

Magnus Series for Master Integrals

Two-loop Master Integrals for the QCD-EW corrections to Drell-Yan scattering

Amplitudes Decomposition: *the algebraic way*



 $\mathbf{a} = \mathbf{a} \mathbf{x} \mathbf{i} + \mathbf{a} \mathbf{y} \mathbf{j} + \mathbf{a} \mathbf{z} \mathbf{k}$

Basis: {**i j k**}

Scalar product/Projection: to extract the components

> $a_x = a.i$ $a_y = a.j$

 $a_z = a.k$

Amplitudes Decomposition: *the algebraic way*



Amplitudes Decomposition: *the algebraic way*



Integrand-Reduction

unitarity at integrand level

Ossola Papadopoulos Pittau (2006) Ellis Giele Kunszt Melnikov (2007) Ossola & *P.M.* (2011) Badger, Frellesvig, Zhang (2011) Zhang (2012) Mirabella, Ossola, Peraro, & *P.M.* (2012)

>> Ossola

One-Loop Integrand Decomposition

$$\begin{aligned} \mathcal{A}_{n}^{\text{case-loop}} &= \int d^{-2\epsilon} \mu \int d^{4}q \; A_{n}(q,\mu^{2}) \;, \quad A_{n}(q,\mu^{2}) \equiv \frac{\mathcal{N}_{n}(q,\mu^{2})}{D_{0}D_{1}\cdots D_{n-1}} \qquad \bar{D}_{i} = (\bar{q}+p_{i})^{2} - m_{i}^{2} = (q+p_{i})^{2} - m_{i}^{2} - \mu^{2} \\ \text{We use a bar to denote objects living in } d = 4 - 2\epsilon \text{ dimensions} \qquad \notin \neq \notin + \mu \;, \quad \text{with} \qquad q^{2} = q^{2} - \mu^{2} \;. \\ \mathcal{A}_{n}^{\text{one-loop}} &= c_{5,0} \quad \swarrow \quad + c_{4,0} \quad \square \quad + c_{4,4} \quad \downarrow_{\mathbf{f} \cdot \mathbf{f}} \quad + c_{3,0} \quad \square \quad + c_{3,7} \quad \downarrow_{\mathbf{f} \cdot \mathbf{f}} \quad + c_{2,0} - (- + c_{2,9} - q_{1,2}) - + c_{1,0} \\ \mathcal{O} \text{ ssola, Papadopoulos, Pittau} \\ \mathcal{A}_{n}(q,\mu^{2}) &\neq \quad \frac{c_{5,0}}{D_{0}D_{1}D_{2}D_{3}D_{4}} \quad + \frac{c_{4,0} + c_{4,4}\mu^{4}}{D_{0}D_{1}D_{2}D_{3}} \quad + \frac{c_{3,0} + c_{3,7}\mu^{2}}{D_{0}D_{1}D_{2}} \quad + \frac{c_{2,0} + c_{2,9}\mu^{2}}{D_{0}D_{1}} \quad + \frac{c_{1,0} + f_{0}(q,\mu^{2})}{D_{0}D_{1}D_{2}} \\ &= \frac{c_{5,0} + f_{01234}(q,\mu^{2})}{D_{0}D_{1}D_{2}D_{3}D_{4}} \quad + \frac{c_{4,0} + c_{4,4}\mu^{4} + f_{0123}(q,\mu^{2})}{D_{0}D_{1}D_{2}D_{3}} \quad + \frac{c_{3,0} + c_{3,7}\mu^{2} + f_{012}(q,\mu^{2})}{D_{0}D_{1}D_{2}} \quad + \frac{c_{2,0} + c_{2,9}\mu^{2} + f_{01}(q,\mu^{2})}{D_{0}D_{1}} \quad + \frac{c_{1,0} + f_{0}(q,\mu^{2})}{D_{0}D_{1}} \\ &= \frac{c_{5,0} + f_{01234}(q,\mu^{2})}{D_{0}D_{1}D_{2}D_{3}D_{4}} \quad + \frac{c_{4,0} + c_{4,4}\mu^{4} + f_{0123}(q,\mu^{2})}{D_{0}D_{1}D_{2}D_{3}} \quad + \frac{c_{3,0} + c_{3,7}\mu^{2} + f_{012}(q,\mu^{2})}{D_{0}D_{1}D_{2}} \quad + \frac{c_{2,0} + c_{2,9}\mu^{2} + f_{01}(q,\mu^{2})}{D_{0}D_{1}} \quad + \frac{c_{1,0} + f_{0}(q,\mu^{2})}{D_{0}D_{1}} \quad + \frac{c_{1,0} + f_{0}(q,\mu^{2})}{D_{0}} \quad + \frac{c_{1,0} + f_{0}(q,\mu^{2})}{D_{0}D_{1}} \quad + \frac{c_{1,0} + f_{0}(q,\mu^{2})}{D_{0}} \quad +$$

f's are "spurious" ==> integrate to 0 !!!



""" "" "find the right variables encoding the cut-structure"

variables

- ISP's = Irreducible Scalar Products:
 - q-components which can variate under cut-conditions
 - spurious: vanishing upon integration
 - non-spurious: non-vanishing upon integration \Rightarrow MI's

Quantum Field Theory

Unitarity-Cuts, Vanishing denominators

Cut-residue

Amplitudes factorization in tree-amplitudes

Amplitude decomposition

Zhang (2012); Badger Frellesvig Zhang (2012) Mirabella, Ossola, Peraro, & **P.M.** (2012)

Algebraic Geometry

Polynomial equations, ideals

Remainder of polynomial division

Polynomials in quotient rings



Multivariate Polynomial division

Multi-Loop Integrand Recurrence

Mirabella, Ossola, Peraro, & P.M. (2012)

l-Loop Recurrence Relation





The Maximum-Cut Theorem

At any loop ℓ , loops we define *maximum cut* as the set of vanishing denominators

$$D_0 = D_1 = \ldots = 0$$

which constrains completely the components of the loop momenta. O-dimensional We assume that, in non-exceptional phase-space points, a maximum-cut has a finite number n_s of solutions, each with multiplicity one. Then,

Theorem 4.1 (Maximum cut). The residue at the maximum-cut is a polynomial paramatrised by n_s coefficients, which admits a univariate representation of degree $(n_s - 1)$.

One-Loop Integrand Decomposition $d = 4 - 2\epsilon$

Choice of 4-dimensional basis for an *m*-point residue

$$e_1^2 = e_2^2 = 0$$
, $e_1 \cdot e_2 = 1$, $e_3^2 = e_4^2 = \delta_{m4}$, $e_3 \cdot e_4 = -(1 - \delta_{m4})$

• Coordinates: $\mathbf{z} = (z_1, z_2, z_3, z_4, z_5) \equiv (x_1, x_2, x_3, x_4, \mu^2)$

$$q_{4-\text{dim}}^{\mu} = -p_{i_1}^{\mu} + x_1 \ e_1^{\mu} + x_2 \ e_2^{\mu} + x_3 \ e_3^{\mu} + x_4 \ e_4^{\mu}, \qquad q^2 = q_{4-\text{dim}}^2 - \mu^2$$

Generic numerator

$$\mathcal{N}_{i_1\cdots i_m} = \sum_{j_1,\dots,j_5} \alpha_{\vec{j}} \, z_1^{j_1} \, z_2^{j_2} \, z_3^{j_3} \, z_4^{j_4} \, z_5^{j_5}, \qquad (j_1\dots j_5) \quad \text{such that} \quad \operatorname{rank}(\mathcal{N}_{i_1\cdots i_m}) \le m$$

Residues

$$\begin{split} \Delta_{i_{1}i_{2}i_{3}i_{4}i_{5}} &= c_{0} & \text{reproducing:} \\ \Delta_{i_{1}i_{2}i_{3}i_{4}} &= c_{0} + c_{1}x_{4} + \mu^{2}(c_{2} + c_{3}x_{4} + \mu^{2}c_{4}) & \text{Ellis Giele Kunszt Melnikov} \\ \Delta_{i_{1}i_{2}i_{3}} &= c_{0} + c_{1}x_{3} + c_{2}x_{3}^{2} + c_{3}x_{3}^{3} + c_{4}x_{4} + c_{5}x_{4}^{2} + c_{6}x_{4}^{3} + \mu^{2}(c_{7} + c_{8}x_{3} + c_{9}x_{4}) \\ \Delta_{i_{1}i_{2}} &= c_{0} + c_{1}x_{2} + c_{2}x_{3} + c_{3}x_{4} + c_{4}x_{2}^{2} + c_{5}x_{3}^{2} + c_{6}x_{4}^{2} + c_{7}x_{2}x_{3} + c_{9}x_{2}x_{4} + c_{9}\mu^{2} \\ \Delta_{i_{1}} &= c_{0} + c_{1}x_{1} + c_{2}x_{2} + c_{3}x_{3} + c_{4}x_{4} \end{split}$$

Longitudinal and Transverse Space

Peraro Primo **P.M.** (to appear)

Dimensional Regularization

$$d = 4 - 2\epsilon$$



 \blacksquare Denominators do not depend on "the angular variables" of the Transverse Space Ω_{\perp}

Numerators depend on "all" loop variables

idea n.1

$$d = d_{//} + d_{\perp}$$

Integrating over Transverse Space

One-Loop Integrals
$$d = 4 - 2\epsilon$$

$$I_n^d[\mathcal{N}] = \int \frac{d^d q}{\pi^{d/2}} \frac{\mathcal{N}(q)}{\prod_{i=0}^{n-1} \mathcal{D}_i}, \qquad \mathcal{D}_i = \left(q + \sum_{j=0}^i p_j\right)^2 + m_i^2, \qquad p_0 = 0,$$

$$\begin{array}{ll} \text{loop momentum} \\ \text{parametrization} \end{array} \qquad q^{\alpha} = q^{\alpha}_{[4]} + \mu^{\alpha}, \qquad q^{\alpha}_{[4]} = \sum_{i=1}^{4} x_i e^{\alpha}_i, \qquad q^2 = q^2_{[4]} + \mu^2. \end{array}$$

$$\begin{aligned} & \overleftarrow{\mathcal{K}} \text{ Integration} \\ & \text{variables} \end{aligned} \quad I_n^d[\mathcal{N}] = \frac{\mathcal{K}}{\pi^2 \Gamma\left(\frac{d-4}{2}\right)} \int_{-\infty}^{\infty} \prod_{i=1}^4 dx_i \int_0^{\infty} d\mu^2 (\mu^2)^{\frac{d-6}{2}} \frac{\mathcal{N}(x_i, \mu^2)}{\prod_{i=0}^{n-1} \mathcal{D}_i}, \end{aligned}$$

$$\mathcal{D}_{i} = \left(q_{[4]} + \sum_{j=0}^{i} p_{j}\right)^{2} + \mu^{2} + m_{i}^{2},$$

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$$\mathcal{K} = \sqrt{\det\left(\frac{\partial q_{[4]}^{\mu}}{\partial x_i}\frac{\partial q_{[4]\,\mu}}{\partial x_j}\right)}.$$

One-Loop Integrals $d = d_{//} + d_{\perp}$

 $\begin{array}{l} \overleftarrow{\varphi} \text{ loop momentum} \\ \text{parametrization} \end{array} \qquad q^{\alpha} = q^{\alpha}_{[k]} + \lambda^{\alpha}, \qquad q^{\alpha}_{[k]} = \sum_{j=1}^{k} x_{j} e^{\alpha}_{j}, \qquad q^{2} = q^{2}_{[k]} + \lambda^{2}, \end{array}$

k-dimensional the space spanned by the external momenta

 $\lambda^{\alpha} = \sum_{j=k+1}^{4} x_j e_j^{\alpha} + \mu^{\alpha}, \qquad \lambda^2 = \sum_{j=k+1}^{4} x_j^2 + \mu^2, \qquad (d-k) \text{-dimensional orthogonal subspace.}$ Larsen Zhang;

$$I_n^d[\mathcal{N}] = \frac{1}{\pi^2 \Gamma\left(\frac{d-4}{2}\right)} \int d^k q_{[k]} \int_0^\infty d\lambda^2 (\lambda^2)^{\frac{d-k-2}{2}} \prod_{i=1}^{4-k} \int_{-1}^1 d\cos\theta_i (\sin\theta_i)^{d-k-i-2} \frac{\mathcal{N}(q)}{\prod_{i=0}^{n-1} \mathcal{D}_i}.$$

$$\mathcal{N}(q) \equiv \mathcal{N}(q_{[k]}^{\alpha}, \lambda^2, \{x_{k+1}, ..., x_4\}). \qquad \mathcal{D}_i = \left(q_{[k]} + \sum_{j=0}^i p_j\right)^2 + \lambda^2 + m_i^2.$$

 \blacksquare Denominators do not depend on "the angular variables" of the Transverse Space Ω_{\perp}

 \mathbf{M} Integration over Ω_{\perp} :?

Integrating over Transverse Angles

Peraro Primo **P.M.** (to appear)

Gegenbauer polynomials

orthogonal polynomials over the interval [-1, 1]weight function $\omega_{\alpha}(x) = (1 - x^2)^{\alpha - \frac{1}{2}}$

generating function $\frac{1}{(1-2xt+t^2)^{\alpha}} = \sum_{n=1}^{\infty} C_n^{(\alpha)}(x)t^n.$

$$C_0^{(\alpha)}(x) = 1,$$

$$C_1^{(\alpha)}(x) = 2\alpha x,$$

$$C_2^{(\alpha)}(x) = -\alpha + 2\alpha(1+\alpha)x^2$$

$$\begin{aligned} x &= \frac{1}{2\alpha} C_0^{(\alpha)}(x) C_1^{(\alpha)}(x), \\ x^2 &= \frac{1}{4\alpha^2} [C_1^{(\alpha)}(x)]^2, \\ x^3 &= \frac{1}{4\alpha^2(1+\alpha)} C_1^{(\alpha)}(x) [\alpha C_0^{(\alpha)}(x) + C_2^{(\alpha)}(x)], \\ x^4 &= \frac{1}{4\alpha^2(1+\alpha)^2} [\alpha C_0^{(\alpha)}(x) + C_2^{(\alpha)}(x)]^2, \end{aligned}$$

Orthogonality condition

$$\int_{-1}^{1} d\cos\theta(\sin\theta)^{2\alpha-1} C_n^{(\alpha)}(\cos\theta) C_m^{(\alpha)}(\cos\theta) = \delta_{mn} \frac{2^{1-2\alpha}\pi\Gamma(n+2\alpha)}{n!(n+\alpha)\Gamma^2(\alpha)}$$

. . .

Integration over Transverse Angles: trivialized @ all-loop!

Alternative to PV-tensor reduction in the transverse-space

One-Loop Integrals $d = d_{//} + d_{\perp}$

k-dimensional the space spanned by the external momenta

 $\lambda^{\alpha} = \sum_{j=k+1}^{4} x_j e_j^{\alpha} + \mu^{\alpha}, \qquad \lambda^2 = \sum_{j=k+1}^{4} x_j^2 + \mu^2, \qquad (d-k) \text{-dimensional orthogonal subspace.}$

$$I_n^d[\mathcal{N}] = \frac{1}{\pi^2 \Gamma\left(\frac{d-4}{2}\right)} \int d^k q_{[k]} \int_0^\infty d\lambda^2 (\lambda^2)^{\frac{d-k-2}{2}} \prod_{i=1}^{4-k} \int_{-1}^1 d\cos\theta_i (\sin\theta_i)^{d-k-i-2} \frac{\mathcal{N}(q)}{\prod_{i=0}^{n-1} \mathcal{D}_i}.$$

$$\mathcal{N}(q) \equiv \mathcal{N}(q_{[k]}^{\alpha}, \lambda^2, \{x_{k+1}, ..., x_4\}). \qquad \mathcal{D}_i = \left(q_{[k]} + \sum_{j=0}^i p_j\right)^2 + \lambda^2 + m_i^2.$$

🗹 Denominators do not depend on "the angular variables" of the Transverse Space Ω_\perp

Spurious integrals vanish automatically Integrality condition

Four-point integrals

$$I_4^d[\mathcal{N}] = \int \frac{d^3 q_{[3]}}{\pi^{d/2}} \int d^{d-3} \lambda \frac{\mathcal{N}(q_{[3]}, \lambda^2, x_4)}{\mathcal{D}_0 \mathcal{D}_1 \mathcal{D}_2 \mathcal{D}_3}$$

$$x_4 = \lambda \cos \theta_1$$

$$I_4^d[\mathcal{N}] = \frac{1}{\pi^2 \Gamma(\frac{d-4}{2})} \int d^3 q_{[3]} \int_0^\infty d\lambda^2 (\lambda^2)^{\frac{d-5}{2}} \int_{-1}^1 d\cos\theta_1 (\sin\theta_1)^{d-6} \frac{\mathcal{N}(q_{[3]}, \lambda^2, \cos\theta_1)}{\mathcal{D}_0 \mathcal{D}_1 \mathcal{D}_2 \mathcal{D}_3}$$

Sexamples

$$\cos^{2} \theta_{1} = \frac{1}{(d-5)^{2}} \left[C_{1}^{\left(\frac{d-5}{2}\right)}(\cos \theta_{1}) \right]^{2},$$

$$\cos^{4} \theta_{1} = \frac{1}{(d-3)^{2}} \left[C_{0}^{\left(\frac{d-5}{2}\right)}(\cos \theta_{1}) + \frac{4}{(d-5)^{2}} C_{2}^{\frac{d-5}{2}}(\cos \theta_{1}) \right]^{2}$$

$$\begin{split} I_4^d[x_4^2] = & \frac{1}{d-3} I_4^d[\lambda^2] = \frac{1}{2} I_4^{d+2}[1], \\ I_4^d[x_4^4] = & \frac{3}{(d-3)(d-1)} I_4^d[\lambda^4] = \frac{3}{4} I_4^{d+4}[1] \end{split}$$

 \checkmark Gegenbauer integration produces powers of $\lambda_{ij} = \lambda_i \cdot \lambda_j$



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$$x_3 = \lambda \cos \theta_1$$
$$x_4 = \lambda \sin \theta_1 \cos \theta_2$$

$$I_{3}^{d}[\mathcal{N}] = \frac{1}{\pi^{2}\Gamma\left(\frac{d-4}{2}\right)} \int d^{2}q_{[2]} \int_{0}^{\infty} d\lambda^{2} (\lambda^{2})^{\frac{d-4}{2}} \int_{-1}^{1} d\cos\theta_{1} (\sin\theta_{1})^{d-5} \times \int_{-1}^{1} d\cos\theta_{2} (\sin\theta_{2})^{d-6} \frac{\mathcal{N}(q_{[2]}, \lambda^{2}, \{\cos\theta_{1}, \sin\theta_{1}, \cos\theta_{2}\})}{\mathcal{D}_{0}\mathcal{D}_{1}\mathcal{D}_{2}}$$

Two-point integrals

$$\begin{aligned} x_2 &= \lambda \cos \theta_1 \\ x_3 &= \lambda \sin \theta_1 \cos \theta_2, \\ x_4 &= \lambda \sin \theta_1 \sin \theta_2 \cos \theta_3 \end{aligned}$$

$$I_{2}^{d}[\mathcal{N}] = \frac{1}{\pi^{2}\Gamma(\frac{d-4}{2})} \int dq_{[1]} \int_{0}^{\infty} d\lambda^{2} (\lambda^{2})^{\frac{d-3}{2}} \int_{-1}^{1} d\cos\theta_{1}(\sin\theta_{1})^{d-4} \times \int_{-1}^{1} d\cos\theta_{2}(\sin\theta_{2})^{d-5} \int_{-1}^{1} d\cos\theta_{3}(\sin\theta_{3})^{d-6} \times \frac{\mathcal{N}(q_{[1]},\lambda^{2},\cos\theta_{1},\sin\theta_{1},\cos\theta_{2},\sin\theta_{2},\cos\theta_{3})}{\mathcal{D}_{0}\mathcal{D}_{1}},$$

$$I_{2}^{d}[\mathcal{N}]|_{p^{2}=0} = \frac{1}{\pi^{2}\Gamma\left(\frac{d-4}{2}\right)} \int d^{2}q_{[2]} \int_{0}^{\infty} d\lambda^{2} (\lambda^{2})^{\frac{d-4}{2}} \int_{-1}^{1} d\cos\theta_{1} (\sin\theta_{1})^{d-5} \times \int_{-1}^{1} d\cos\theta_{2} (\sin\theta_{2})^{d-6} \frac{\mathcal{N}(q_{[2]}, \lambda^{2}, \cos\theta_{1}, \sin\theta_{1}, \cos\theta_{2})}{\mathcal{D}_{0}\mathcal{D}_{1}}, \qquad \begin{cases} x_{3} = \lambda \cos\theta_{1} \\ x_{4} = \lambda \sin\theta_{1} \cos\theta_{2} \\ x_{4} = \lambda \sin\theta_{1} \cos\theta_{2} \end{cases}$$

$$\begin{array}{l} \checkmark \quad \textbf{One-point integrals} \\ \left\{ \begin{array}{l} x_1 = \lambda \cos \theta_1, \\ x_2 = \lambda \sin \theta_1 \cos \theta_2, \\ x_3 = \lambda \sin \theta_1 \sin \theta_2 \cos \theta_3 \\ x_4 = \lambda \sin \theta_1 \sin \theta_2 \sin \theta_3 \cos \theta_4 \end{array} \right. \\ \left. I_1^d [\mathcal{N}] = \frac{1}{\pi^2 \Gamma \left(\frac{d-4}{2}\right)} \int_0^\infty d\lambda^2 (\lambda^2)^{\frac{d-2}{2}} \int_{-1}^1 d\cos \theta_1 (\sin \theta_1)^{d-3} \int_{-1}^1 d\cos \theta_1 (\sin \theta_1)^{d-4} \times \int_{-1}^1 d\cos \theta_2 (\sin \theta_2)^{d-5} \times \int_{-1}^1 d\cos \theta_3 (\sin \theta_3)^{d-6} \times \\ \frac{\mathcal{N}(q_{[1]}, \lambda^2, \cos \theta_1, \sin \theta_1, \cos \theta_2, \sin \theta_2, \cos \theta_3, \sin \theta_3, \cos \theta_4)}{\mathcal{D}_0} \end{array}$$

idea n.2

$$d = d_{//} + d_{\perp}$$

Cutting in the Longitudinal Space

Adaptive Unitarity @ 1-loop

$$d = d_{//} + d_{\perp}$$
e Integrand red'n

$$q^{\alpha} = q_{[k]}^{\alpha} + \lambda^{\alpha}, \qquad D_{i} = \left(q_{[k]} + \sum_{i=0}^{i} p_{i}\right)^{2} + \lambda^{2} + m_{i}^{2}.$$

$$q_{[k]}^{\alpha} = \sum_{j=1}^{k} x_{j} \varepsilon_{1}^{\alpha}, \qquad \lambda^{2}$$
Cutting in different dimensions
according to the # of legs

$$\int 1 - \log r : \text{always MAXIMUM CUTS}$$
New residue parametrization

$$\int \Delta_{i_{0} \cdots i_{4}} = q_{0}.$$

$$\int \Delta_{i_{0} \cdots i_{3}} = c_{0} + c_{1}x_{1} + c_{2}x_{1}^{2} + c_{3}x_{1}^{3} + c_{4}x_{1}^{4},$$

$$\Delta_{i_{0}1i_{12}} = c_{0} + c_{1}x_{3} + c_{2}x_{4}^{2} + c_{3}x_{3}^{2} + c_{6}x_{3}^{3} + c_{7}x_{3}^{2}x_{4} + c_{8}x_{3}x_{4}^{2} + c_{9}x_{3}^{2},$$

$$\Delta_{i_{0}i_{1}} = c_{0} + c_{1}x_{2} + c_{2}x_{3} + c_{3}x_{4} + c_{4}x_{2}x_{3} + c_{5}x_{2}x_{4} + c_{6}x_{3}x_{4} + c_{7}x_{1}^{2} + c_{8}x_{3}^{2} + c_{9}x_{4}^{2},$$

$$\Delta_{i_{0}i_{1}} = c_{0} + c_{1}x_{1} + c_{2}x_{3} + c_{3}x_{4} + c_{4}x_{2}x_{3} + c_{6}x_{3}x_{4} + c_{7}x_{1}^{2} + c_{8}x_{3}^{2} + c_{9}x_{4}^{2},$$

$$\Delta_{i_{0}i_{1}} = c_{0} + c_{1}x_{1} + c_{2}x_{3} + c_{4}x_{1}x_{3} + c_{5}x_{1}x_{4} + c_{6}x_{3}x_{4} + c_{7}x_{1}^{2} + c_{8}x_{3}^{2} + c_{9}x_{4}^{2},$$

$$\Delta_{i_{0}i_{1}} = c_{0} + c_{1}x_{1} + c_{2}x_{3} + c_{4}x_{1}x_{3} + c_{5}x_{1}x_{4} + c_{6}x_{3}x_{4} + c_{7}x_{1}^{2} + c_{8}x_{3}^{2} + c_{9}x_{4}^{2},$$

$$\Delta_{i_{0}i_{1}} = c_{0} + c_{1}x_{1} + c_{2}x_{3} + c_{4}x_{1}x_{3} + c_{5}x_{1}x_{4} + c_{6}x_{3}x_{4} + c_{7}x_{1}^{2} + c_{8}x_{3}^{2} + c_{9}x_{4}^{2},$$

$$\Delta_{i_{0}i_{1}} = c_{0} + c_{1}x_{1} + c_{2}x_{3} + c_{4}x_{1}x_{3} + c_{5}x_{1}x_{4} + c_{6}x_{3}x_{4} + c_{7}x_{1}^{2} + c_{8}x_{3}^{2} + c_{9}x_{4}^{2},$$

$$\Delta_{i_{0}i_{1}} = c_{0} + c_{1}x_{1} + c_{2}x_{3} + c_{4}x_{1}x_{3} + c_{5}x_{1}x_{4} + c_{6}x_{3}x_{4} + c_{7}x_{1}^{2} + c_{8}x_{3}^{2} + c_{9}x_{4}^{2},$$

$$\Delta_{i_{0}i_{1}} = c_{0} + c_{1}x_{1} + c_{2}x_{3} + c_{4}x_{1}x_{3} + c_{5}x_{1}x_{4} + c_{6}x_{3}x_{4} + c_{7}x_{1}^{2} + c_{8}x_{3}^{2} + c_{9}x_{4}^{2},$$

$$\Delta_{i_{0}i_{1}} = c_{0} + c_{1}x_{1} + c_{2}x_{3} + c_{1}x_{1}x_{3} + c_{1}x_{3} + c_{1}x_{3} + c_{1}x_{3} + c_{1}x_{3} + c_{1}x_{3} + c_{1}x_{3} + c_{1}x_$$

Adaptive Unitarity @ 1-loop

 $d = d_{//} + d_{\perp}$

Integrand red'n

Solution of the Residues over Transverse Angles

$$\int \frac{d^{d}q}{\pi^{d/2}} \frac{\Delta_{i_{0}i_{1}i_{2}i_{3}}}{D_{i_{0}}D_{i_{1}}D_{i_{2}}D_{i_{3}}} = c_{0}I_{4}^{d}[1] + \frac{1}{(d-3)}c_{2}I_{4}^{d}[\lambda^{2}] + \frac{3}{(d-3)(d-1)}c_{4}I_{4}^{d}[\lambda^{4}] = c_{0}I_{4}^{d}[1] + \frac{1}{2}c_{2}I_{4}^{d+2}[1] + \frac{3}{4}c_{4}I_{4}^{d+4}[1].$$

$$\int \frac{d^{d}q}{\pi^{d/2}} \frac{\Delta_{i_{0}i_{1}i_{2}}}{D_{i_{0}}D_{i_{1}}D_{i_{2}}} = c_{0}I_{3}^{d}[1] + \frac{1}{(d-3)}(c_{3}+c_{3})I_{3}^{d}[\lambda^{2}] = c_{0}I_{3}^{d}[1] + \frac{1}{2}(c_{3}+c_{5})I_{3}^{d+2}[1].$$

$$- \int \frac{d^{d}q}{\pi^{d/2}} \frac{\Delta_{i_{0}i_{1}}}{D_{i_{0}}D_{i_{1}}} = c_{0}I_{2}^{d}[1] + \frac{1}{(d-3)}(c_{7}+c_{8}+c_{9})I_{2}^{d}[\lambda^{2}] = c_{0}I_{2}^{d}[1] + \frac{1}{2}(c_{7}+c_{8}+c_{9})I_{2}^{d+2}[1].$$

$$- \int \frac{d^{d}q}{\pi^{d/2}} \frac{\Delta_{i_{0}i_{1}}}{D_{i_{0}}D_{i_{1}}} = c_{0}I_{2}^{d}[1] + c_{1}I_{2}^{d}[x_{1}] + c_{7}I_{2}^{d}[x_{1}^{2}] + \frac{1}{(d-3)}(c_{8}+c_{9})I_{3}^{d}[\lambda^{2}] = c_{0}I_{2}^{d}[1] + c_{1}I_{2}^{d}[x_{1}] + c_{7}I_{2}^{d}[x_{1}^{2}] + \frac{1}{2}(c_{8}+c_{9})I_{2}^{d+2}[1].$$

$$- \int \frac{d^{d}q}{\pi^{d/2}} \frac{\Delta_{i_{0}i_{1}}}{D_{i_{0}}D_{i_{1}}} \Big|_{p^{2}=0} = c_{0}I_{2}^{d}[1] + c_{1}I_{2}^{d}[x_{1}] + c_{7}I_{2}^{d}[x_{1}^{2}] + \frac{1}{(d-3)}(c_{8}+c_{9})I_{3}^{d}[\lambda^{2}] = c_{0}I_{2}^{d}[1] + c_{1}I_{2}^{d}[x_{1}] + c_{7}I_{2}^{d}[x_{1}^{2}] + \frac{1}{2}(c_{8}+c_{9})I_{2}^{d+2}[1].$$

$$- \int \frac{d^{d}q}{\pi^{d/2}} \frac{\Delta_{i_{0}i_{1}}}{D_{i_{0}}} = c_{0}I_{1}^{d}[1].$$

$$- \frac{\lambda^{2}}{\pi^{d/2}} \frac{d^{d}q}{D_{i_{0}}} \frac{\Delta_{i_{0}}}{D_{i_{0}}}} = c_{0}I_{1}^{d}[1].$$



Divide et Impera

Philip II of Macedon



i) Divide...ii) et Integra...iii) et Divide

Divide-et-Integra-et-Divide

Additional Polynomial Division



divide		divide
$\Delta_{i_0 \cdots i_n}$	$\Delta_{i_0 \cdots i_n}^{\mathrm{int}}$	$\Delta'_{i_0 \cdots i_n}$
1	_	_
{1} 5	3	- 1
$\{1, x_4, x_4^2, x_4^3, x_4^4\}$	$\{1, \lambda^2, \lambda^4\}$	{1}
$ \begin{array}{c} 10\\ \{1, x_3, x_4, x_3^2, x_3 x_4, x_4^2, x_3^3, x_3^2 x_4, x_3 x_4^2, x_4^3\} \end{array} $	$2 \ \{1,\lambda^2\}$	1 {1}
	2	1
	$\frac{\{1,\lambda^2\}}{4}$	$\{1\}$
$\{1, x_1, x_3, x_4, x_1^2, x_1x_3, x_1x_4, x_3^2, x_3x_4, x_4^2\}$	$\{1, x_1, x_1^2, \lambda^2\}$	$\{1, x_1, x_1^2\}$
5 {1 r_1 r_2 r_3 r_4 }	1 {1}	_
	$\begin{tabular}{ c c c c c } \hline & & & & & & & & \\ \hline & & & & & & & & \\ \hline & & & &$	$\begin{tabular}{ c c c c c } \hline \texttt{Untegrd} \\ \hline & & & & & & & & & & & & & & & & & &$

minimal number of irreducible non-spurious monomials (irr. scal. prod.s)!

Second polynomial division <==> Dimensional Recurrence @ integrand level

$$d = d_{//} + d_{\perp}$$
idea n.1 Integrating over Transverse Space
idea n.2 Cutting in the Longitudinal Space

☑ both ideas can be applied @ all-loops

Two-Loop Integrals
$$d = 4 - 2\epsilon$$

$$I_n^d[\mathcal{N}] = \int \frac{d^d q_1 d^d q_2}{\pi^d} \frac{\mathcal{N}(q_1, q_2)}{\prod_i \mathcal{D}_i}, \qquad q_1^{\alpha} = q_{1[4]}^{\alpha} + \mu_1^{\alpha}, \quad q_2^{\alpha} = q_{2[4]}^{\alpha} + \mu_2^{\alpha}, \qquad \mu_i \cdot \mu_j = \mu_{ij}, \quad q_i \cdot q_j = q_{i[4]} \cdot q_{j[4]} + \mu_{ij}, \quad q_i \cdot \mu_j = \mu_{ij}, \quad q_i \cdot q_j = q_{i[4]} \cdot q_{j[4]} + \mu_{ij}, \quad q_i \cdot \mu_j = \mu_{ij}, \quad \mu_i \cdot \mu_j = \mu$$

 $\begin{array}{l} \widehat{\varphi} \text{ loop momentum} \\ \text{parametrization} \end{array} \qquad q_{1[4]}^{\alpha} = \sum_{i=1}^{4} x_i e_i^{\alpha}, \qquad q_{2[4]}^{\alpha} = \sum_{i=1}^{4} y_i f_i^{\alpha}, \end{array}$

$$I_n^d[\mathcal{N}] = \frac{2^{d-6}\mathcal{K}_1\mathcal{K}_2}{\pi^5\Gamma(d-5)} \int \prod_{i=1}^4 dx_i dy_i \int_0^\infty d\mu_{11} \int_0^\infty d\mu_{22} \int_{-\sqrt{\mu_{11}\mu_{22}}}^{\sqrt{\mu_{11}\mu_{22}}} d\mu_{12}(\mu_{11}\mu_{22}-\mu_{12}^2)^{\frac{d-6}{2}} \times \frac{\mathcal{N}(x_j, y_i, \mu_{ij})}{\prod_i \mathcal{D}_i},$$

Two-Loop Integrals

$$d = d_{//} + d_{\perp}$$

 $q_{1}^{\alpha} = q_{1[k]}^{\alpha} + \lambda_{1}^{\alpha}, \qquad q_{2}^{\alpha} = q_{2[k]}^{\alpha} + \lambda_{2}^{\alpha}, \qquad k \leq 3,$ $q_{1[k]}^{\alpha} = \sum_{j=1}^{k} x_{j} e_{j}^{\alpha}, \qquad q_{2[k]}^{\alpha} = \sum_{j=1}^{k} y_{j} e_{j}^{\alpha}, \qquad k - \text{dimensional space spanned by the external kinematics}$ $\lambda_{1}^{\alpha} = \sum_{j=k+1}^{4} x_{j} e_{j}^{\alpha} + \mu_{1}^{\alpha}, \qquad \lambda_{2}^{\alpha} = \sum_{j=k+1}^{4} y_{j} e_{j}^{\alpha} + \mu_{2}^{\alpha} \qquad (d-k) - \text{dimensional orthogonal subspaces},$ $\cos \theta_{12} = \frac{\lambda_{12}}{\sqrt{\lambda_{11}\lambda_{22}}},$ $I_{1}^{d}[M] = \sum_{j=k+1}^{2^{d-6}} \int d^{k} a - d^{k} a - \int_{0}^{\infty} d\lambda_{1} + (\lambda_{1}) \frac{d-k-2}{2} \int_{0}^{\infty} d\lambda_{2} + (\lambda_{2}) \frac{d-k-2}{2} \times \frac{1}{2^{d-6}} \int d^{k} a - d^{k} a - \int_{0}^{\infty} d\lambda_{2} + (\lambda_{2}) \frac{d-k-2}{2} \int_{0}^{\infty} d\lambda_{2} + (\lambda_{2}) \frac{d-k-2}{2} \times \frac{1}{2^{d-6}} \int d^{k} a - d^{k} a - \int_{0}^{\infty} d\lambda_{2} + (\lambda_{2}) \frac{d-k-2}{2} \int_{0}^{\infty} d\lambda_{2} + (\lambda_{2}) \frac{d-k-2}{2} \times \frac{1}{2^{d-6}} \int d^{k} a - d^{k} a - \int_{0}^{\infty} d\lambda_{2} + (\lambda_{2}) \frac{d-k-2}{2} \int_{0}^{\infty} d\lambda_{2} + (\lambda_{2}) \frac{d-k-2}{2} \times \frac{1}{2^{d-6}} \int d^{k} a - d^{k} a - \int_{0}^{\infty} d\lambda_{2} + (\lambda_{2}) \frac{d-k-2}{2} \int_{0}^{\infty} d\lambda_{2} + (\lambda_{2}) \frac{d-k-2}{2} \times \frac{1}{2^{d-6}} \int d^{k} a - d^{k} a - \int_{0}^{\infty} d\lambda_{2} + (\lambda_{2}) \frac{d-k-2}{2} \int_{0}^{\infty} d\lambda_{2} + (\lambda_{2}) \frac{d-k-2}{2} \times \frac{1}{2^{d-6}} \int d^{k} a - d^{k} a - \int_{0}^{\infty} d\lambda_{2} + (\lambda_{2}) \frac{d-k-2}{2} \int_{0}^{\infty} d\lambda_{2} + (\lambda_{2}) \frac{d-k-2}{2} \times \frac{1}{2^{d-6}} \int d^{k} a - d^{k} a - \int_{0}^{\infty} d\lambda_{2} + (\lambda_{2}) \frac{d-k-2}{2} + \frac{1}{2^{d-6}} + \frac{1}{2^{d-6}} \int_{0}^{\infty} d\lambda_{2} + \frac{1}{2^{d-6}} + \frac{1}{2^{d-6}} \int_{0}^{\infty} d\lambda_{2} + \frac{1}{2^{d-6}} + \frac{1}{2^{d-6$

$$I_{n}^{d}[\mathcal{N}] = \frac{1}{\pi^{5}\Gamma(n-k-1)} \int d^{\kappa}q_{1[k]}d^{\kappa}q_{2[k]}\int_{0}^{\infty} d\lambda_{11}(\lambda_{11})^{\frac{1}{2}} \int_{0}^{\infty} d\lambda_{22}(\lambda_{22})^{\frac{1}{2}} \times \int_{-1}^{1} d\cos\theta_{12}(\sin\theta_{12})^{d-k-3} \int_{-1}^{1} \prod_{i=1}^{4-k} d\cos\theta_{i1}d\cos\theta_{i+12}(\sin\theta_{i1})^{d-k-i-2}(\sin\theta_{i+12})^{d-k-i-3} \times \frac{\mathcal{N}(q_{1},q_{2})}{\prod_{i}\mathcal{D}_{i}}.$$

In the Denominators do not depend on "the angular variables" of the Transverse Space Ω_{\perp} In the Numerators depend on "all" loop variables

Integration over Ω_{\perp} : **Gegenbauer orthogonality condition** Spurious integrals vanish automatically @ all-loop!

Adaptive Unitarity @ 2-loop

Novel Integrand red'n



Marbitrary (external and internal) kinematics!

8 and 7 legs

$\mathcal{I}_{i_1 \cdots i_n}$	$\Delta_{i_1 \cdots i_n}$	$\mathcal{I}_{i_1 \cdots i_n}$	$\Delta_{i_1 \cdots i_n}$
\mathcal{T}^{P}	1	τ^{P}	6
2123456789101	{1}	2124567891011	$\{1, x_{41}\}$
Inpl Inpl Inpl Inpl Inpl Inpl Inpl Inpl	1	$\mathcal{I}_{124567901011}^{\text{NP1}}$	10
	{1}	124507851011 Y Y	$\{1, x_{42}\}$
<i>I</i> ^{NP2} /1234567891011	1	$\mathcal{I}_{123456891011}^{\text{NP1}}$	6
	{1}		$\{1, x_{42}\}$
$\mathcal{I}^{\rm P}_{234567891011}$	6	$\mathcal{I}_{124567891011}^{\text{NP2}}$	10
	$\{1, x_{41}\}$		$\{1, x_{42}\}$
$\mathcal{I}_{234567891011}^{\rm NP1}$	10	$\mathcal{I}_{24567891011}^{\text{NP1}}$	15
 	$\{1, x_{42}\}$		$\{1, x_{31}, x_{41}\}$
$\mathcal{I}^{\rm NP2}_{123457891011}$	6	$\mathcal{I}_{23456791011}^{\rm NP2}$	33
1	$\{1, x_{42}\}$		$\{1, x_{41}, x_{42}\}$
$\mathcal{I}^{\mathrm{NP2}}_{123467891011}$	10	$\mathcal{I}_{12456891011}^{\text{NP1}}$	39
1	$\{1, x_{42}\}$	\ 	$\{1, x_{41}, x_{42}\}$
$\mathcal{I}^{\rm P}_{23467891011}$		$\mathcal{I}_{12345681011}^{\text{NP1}}$	
	$\{1, x_{31}, x_{41}\}$		$\{1, x_{32}, x_{42}\}$
$\mathcal{I}^{\rm P}_{23457891011}$	33 [1 m m]	$\mathcal{I}_{12467891011}^{NP2}$	40
	$\{1, x_{41}, x_{42}\}$		$\{1, x_{41}, x_{42}\}$
$\mathcal{I}_{23457891011}^{\rm NP1}$	39 [1 mu mu]	$\mathcal{I}_{247891011}^{\text{NP1}}$	$\begin{bmatrix} 20 \\ 1 & m \\ m$
	$\{1, x_{41}, x_{42}\}$		$\{1, x_{21}, x_{31}, x_{41}\}$
$\mathcal{I}_{12345691011}^{\text{NP1}}$	$\begin{bmatrix} 10\\ 1 & r_{10} & r_{10} \end{bmatrix}$	$\mathcal{I}_{2347891011}^{\text{NP1}}$	$\begin{bmatrix} & 10 \\ 1 & r_{01} & r_{12} & r_{13} \end{bmatrix}$
	15. <u>11, 232, 242</u>		116
I ^{NP2} 23467891011	$\begin{cases} 1 \\ x_{41} \\ x_{40} \end{cases}$	$\mathcal{I}_{2457891011}^{\text{NP1}}$	$\begin{cases} 110 \\ \begin{cases} 1 & r_{41} & r_{22} & r_{42} \end{cases} \end{cases}$
1	[1, <i>w</i> 41, <i>w</i> 42]		$\frac{1}{80}$
		$\mathcal{I}_{1245781011}^{\text{NP1}}$	$\begin{cases} 1 & r_{21} & r_{41} & r_{40} \end{cases}$
$\mathcal{I}_{23457891011}^{\text{NP1}}$ $\mathcal{I}_{12345691011}^{\text{NP1}}$ $\mathcal{I}_{23467891011}^{\text{NP2}}$	$ \begin{array}{c} 59\\ \{1, x_{41}, x_{42}\}\\ 15\\ \{1, x_{32}, x_{42}\}\\ 45\\ \{1, x_{41}, x_{42}\} \end{array} $	$\begin{array}{c c} \mathcal{I}_{247891011}^{\text{NP1}} & \checkmark & \checkmark \\ \hline \\ \mathcal{I}_{2347891011}^{\text{NP1}} & \checkmark & \checkmark \\ \hline \\ \mathcal{I}_{2457891011}^{\text{NP1}} & \checkmark & \checkmark \\ \hline \\ \mathcal{I}_{1245781011}^{\text{NP1}} & \checkmark & \checkmark \\ \end{array}$	$ \begin{array}{c} 20\\ \{1, x_{21}, x_{31}, x_{41}\}\\ 76\\ \{1, x_{31}, x_{41}, x_{42}\}\\ 116\\ \{1, x_{41}, x_{32}, x_{42}\}\\ 80\\ \{1, x_{31}, x_{41}, x_{42}\} \end{array} $

6 and 5 legs

$\mathcal{I}_{i_1 \cdots i_n}$	$\Delta_{i_1 \cdots i_n}$	$\mathcal{I}_{i_1 \cdots i_n}$	$\Delta_{i_1 \cdots i_n}$
τP	15	τ^{P}	20
L13567891011	$\{1, x_{31}, x_{41}\}$	L1567891011	$\{1, x_{21}, x_{31}, x_{41}\}$
$\mathcal{I}^{\mathrm{P}}_{12456701011}$	62	$\mathcal{I}_{1256701011}^{\mathrm{P}}$	76
	$\{1, x_{41}, x_{42}\}$		$\{1, x_{31}, x_{41}, x_{42}\}\$
International In	39	$\mathcal{I}_{1567801011}^{\text{NP1}}$	80
2330891011 / 7	$\{1, x_{41}, x_{42}\}$	1307891011	$\{1, x_{31}, x_{41}, x_{42}\}$
$\mathcal{I}_{12345601011}^{\text{NP1}}$	15	$\mathcal{I}_{167801011}^{P}$	15
12040091011	$\{1, x_{32}, x_{42}\}$		$\{1, x_{11}, x_{21}, x_{31}, x_{41}\}$
$\mathcal{I}_{13567801011}^{NP2}$	45	$\mathcal{I}_{1356801011}^{\text{NP1}}$	116
13507891011	$\{1, x_{41}, x_{42}\}$	1550691011	$\{1, x_{31}, x_{32}, x_{42}\}$
$\mathcal{I}_{2567801011}^{P}$	20	$\mathcal{I}_{146701011}^{\mathrm{P}}$	94
2307891011	$\{1, x_{21}, x_{31}, x_{41}\}$		$\{1, x_{21}, x_{31}, x_{41}, x_{42}\}$
$\mathcal{I}_{2256801011}^{\mathrm{P}}$	76	$\mathcal{I}_{1679011}^{\mathrm{P}}$	66
2330891011 / 17	$\{1, x_{31}, x_{41}, x_{42}\}$	10/0911	$\{1, x_{11}, x_{21}, x_{31}, x_{41}, x_{42}\}\$
$\mathcal{I}_{2567801011}^{\text{NP1}}$	80	$\mathcal{I}_{125601011}^{\mathrm{P}}$	160
2307891011	$\{1, x_{31}, x_{41}, x_{42}\}$		$\{1, x_{31}, x_{41}, y_{32}, x_{42}\}$
International In	116	$\mathcal{I}_{125701011}^{\text{NP1}}$	185
2450891011	$\{1, x_{41}, x_{32}, x_{42}\}$	155791011	$\{1, x_{31}, x_{41}, x_{32}, x_{42}\}$
$\mathcal{I}_{2c7801011}^{P}$	15	$\mathcal{I}_{1956011}^{\mathrm{P}}$	180
-307891011	$\{1, x_{11}, x_{21}, x_{31}, x_{41}\}\$	-1250911	$\{1, x_{11}, x_{31}, x_{41}, x_{32}, x_{42}\}\$
$\mathcal{T}^{\mathrm{P}}_{\mathrm{or}\mathrm{7001011}}$	94	TNP1	246
-257891011	$\{1, x_{21}, x_{31}, x_{41}, x_{42}\}\$	-24691011	$\{1, x_{31}, x_{41}, x_{22}, x_{32}, x_{42}\}\$
$\mathcal{I}_{225701011}^{\mathrm{P}}$	160		
-230/91011	$\{1, x_{31}, x_{41}, x_{32}, x_{42}\}$		
$\mathcal{T}^{\text{NP1}}_{\text{outpoint}}$	185		
	$\{1, x_{31}, x_{41}, x_{32}, x_{42}\}$		

• 4 legs: divide-integra-divide



$\mathcal{I}_{i_1 \cdots i_n}$	$\Delta_{i_1 \cdots i_n}$	$\Delta_{i_1\cdots i_n}^{\mathrm{int}}$	$\Delta'_{i_1\cdots i_n}$
τP \prec	94	53	10
	$\{1, x_{21}, x_{31}, x_{41}, x_{42}\}$	$\{1, x_{21}, x_{31}, \lambda_{11}, \lambda_{22}, \lambda_{12}\}$	$\{1, x_{21}, x_{31}\}$
$ au^{\mathrm{P}}$	160	93	22
	$\{1, x_{31}, x_{41}, x_{32}, x_{42}\}$	$\{1, x_{31}, x_{32}, \lambda_{11}, \lambda_{22}, \lambda_{12}\}$	$\{1, x_{31}, x_{32}\}$
τ^{NP1}	184	105	25
	$\{1, x_{31}, x_{42}, x_{32}, x_{42}\}$	$\{1, x_{31}, x_{32}, \lambda_{11}, \lambda_{22}, \lambda_{12}\}$	$\{1, x_{31}, x_{32}\}$
τ^{P}	180	101	39
L ₁₃₅₆₈₁₁	$\{1, x_{31}, x_{41}, x_{22}, x_{32}, x_{42}\}$	$\{1, x_{31}, x_{22}, x_{32}, \lambda_{11}, \lambda_{22}, \lambda_{12}\}$	$\{1, x_{31}, x_{22}, y_{32}\}$
τ^{P}	66	35	10
L16891011	$\{1, x_{11}, x_{21}, x_{31}, x_{41}, x_{42}\}\$	$\{1, x_{11}, x_{21}, x_{31}, \lambda_{11}, \lambda_{22}, \lambda_{12}\}$	$\{1, x_{11}, x_{21}, x_{31}\}$
$ au^{\text{NP1}}$	245	137	55
	$\{1, x_{31}, x_{41}, x_{21}, x_{32}, x_{42}\}$	$\{1, x_{31}, x_{22}, x_{32}, \lambda_{11}, \lambda_{22}, \lambda_{12}\}$	$\{1, x_{31}, x_{22}, y_{32}\}$
$ au^{\mathrm{P}}$	115	66	35
	$\{1, x_{31}, x_{41}, x_{12}, x_{22}, x_{32}, x_{42}\}\$	$\{1, x_{31}, x_{12}, x_{22}, x_{32}, \lambda_{11}, \lambda_{22}, \lambda_{12}\}$	$\{1, x_{31}, x_{12}, x_{22}, x_{32}\}$
$ au^{\mathrm{P}}$	180	103	60
-136811	$\{1, x_{11}, x_{31}, x_{41}, x_{22}, x_{32}, x_{42}\}$	$\{1, x_{11}, x_{31}, x_{22}, x_{32}, \lambda_{11}, \lambda_{22}, \lambda_{12}\}$	$\{1, x_{11}, x_{31}, x_{22}, x_{32}\}$

• 3, 2, 1 legs: divide-integra-divide



$\mathcal{I}_{i_1 \cdots i_n}$	$\Delta_{i_1 \cdots i_n}$	$\Delta^{\mathrm{int}}_{i_1\cdots i_k}$	$\Delta'_{i_1 \cdots i_k}$
τ^{P}	180	22	4
L ₁₃₅₆₉₁₁	$\{1, x_{31}, x_{41}, x_{22}, x_{32}, x_{42}\}$	$\{1, x_{22}, \lambda_{11}, \lambda_{22}, \lambda_{12}\}$	$\{1, x_{22}\}$
τ^{NP1} \rightarrow	240	30	6
L ₁₅₆₉₁₀₁₁	$\{1, x_{31}, x_{41}, x_{22}, x_{32}, x_{42}\}\$	$\{1, x_{22}, \lambda_{11}, \lambda_{22}, \lambda_{12}\}$	$\{1, x_{22}\}$
τ^{P}	180	33	13
L1571011	$\{1, x_{21}, x_{31}, x_{41}, x_{12}, x_{32}, x_{42}\}$	$\{1, x_{21}, x_{12}, \lambda_{11}, \lambda_{22}, \lambda_{12}\}$	$\{1, x_{21}, x_{12}\}$
τ^{P}	115	20	6
21691011	$\{1, x_{31}, x_{41}, x_{12}, x_{22}, x_{32}, x_{42}\}$	$\{1, x_{11}, x_{22}\lambda_{11}, \lambda_{22}, \lambda_{12}\}$	$\{1, x_{12}, x_{22}\}$
$\tau^{\rm P}$	100	26	16
	$\{1, x_{11}, x_{21}, x_{31}, x_{41}, x_{22}, x_{32}, x_{42}\}$	$\{1, x_{11}, x_{21}, x_{22}, \lambda_{11}, \lambda_{22}, \lambda_{12}\}$	$\{x_{11}, x_{21}, x_{22}\}$

$\mathcal{I}_{i_1 \cdots i_n}$	$\Delta_{i_1 \cdots i_n}$	$\Delta_{i_1\cdots i_n}^{\operatorname{int}}$	$\Delta'_{i_1 \cdots i_n}$
τP	180	8	1
	$\{1, x_{21}, x_{31}, x_{41}, x_{22}, x_{32}, x_{42}\}$	$\{1,\lambda_{11},\lambda_{22},\lambda_{12}\}$	{1}
$\tau^{\rm P}$ $-$	100	8	3
L ₁₆₁₀₁₁	$\{1, x_{11}, x_{21}, x_{31}, x_4, x_{22}, y_3, x_{42}\}$	$\{1, x_{11}, \lambda_{11}, \lambda_{22}, \lambda_{12}\}$	$\{1, x_{11}\}$
$\mathcal{I}^{\mathrm{P}}_{131011}$ ~~	100	26	16
	$\{1, x_{11}, x_{21}, x_{31}, x_{41}, x_{12}, x_{32}, x_{42}\}$	$\{1, x_{11}, x_{21}, x_{12}, \lambda_{11}, \lambda_{22}, \lambda_{12}\}$	$\{1, x_{11}, x_{21}, x_{12}\}$
$\mathcal{I}^{\mathrm{P}}_{21011}$ —	45	9	6
	$\{1, x_{11}, x_{21}, x_{31}, x_{41}, x_{12}, x_{22}, x_{32}, x_{42}\}\$	$\{1, x_{11}, x_{12}, \lambda_{11}, \lambda_{22}, \lambda_{12}\}$	$\{1, x_{11}, x_{12}\}$
$\tau P \qquad \cdots \qquad \cdots \qquad \cdots$	45	18	15
	$\{1, x_{11}, x_{21}, x_{31}, x_{41}, x_{12}, x_{22}, x_{32}, x_{42}\}\$	$\{1, x_{11}, x_{21}, x_{12}, x_{22}, \lambda_{11}, \lambda_{22}, \lambda_{12}\}\$	$\{1, x_{11}, x_{22}, x_{21}, x_{22}\}$

$\mathcal{I}_{i_1 \cdots i_n}$ $\Delta_{i_1 \cdots i_n}$		$\Delta_{i_1\cdots i_n}^{\mathrm{int}}$	$\Delta'_{i_1\cdots i_n}$	
$ au^{ ext{P}}$	\bigcirc	45	4	1
	$\{1, x_{11}, x_{21}, x_{31}, x_{41}, x_{12}, x_{22}, x_{32}, x_{42}\}$	$\{1, \lambda_{11}, \lambda_{22}, \lambda_{12}\}$	{1}	

Integrand generation + Integration over Transverse Angles

GoSam >> Jones

Simplifying the integrands to be reduced (nleg < 5) Removing the transverse direction ==> less coefficients to be determined

Integrand generation + Integration over Transverse Angles GoSam

Simplifying the integrands to be reduced (nleg < 5) Removing the transverse direction ==> less coefficients to be determined

Integrals whose denominators depend on a reduced set of variables (@ higher-loops)



Integrand generation + Integration over Transverse Angles GoSam

- Simplifying the integrands to be reduced (nleg < 5) Removing the transverse direction ==> less coefficients to be determined
- Integrals whose denominators depend on a reduced set of variables (@ higher-loops)
- Mote :: Generalizing and extending to all-loop the R2-integration

Integrand generation + Integration over Transverse Angles GoSam

Simplifying the integrands to be reduced (nleg < 5) Removing the transverse direction ==> less coefficients to be determined

Integrals whose denominators depend on a reduced set of variables (@ higher-loops)

Mote :: Generalizing and extending to all-loop the R2-integration

Adaptive Integrand Reduction + IBP-id's

Fire; Reduze; LiteRed ...

Algebraic Geometry Methods (exploiting sygyzy's)

Kosower Gluza Kaida; Ita; Larsen Zhang;

• Adaptive Integrand Reduction + Numerical MIs

Improved Sector Decomposition

SecDec >> Jones, Kerner

The Geometry of Cut-Residues

l-Loop Recurrence Relation



Harmonic expansion of the residue: Rotation Invariance manifest



Differential Equations for Master Integrals





space-time

dimensions

kinematic variable (s,t,u, masses)



Kotikov; Remiddi; Gehrmann Remiddi Argeri Bonciani Ferroglia Remiddi **P.M**. Aglietti Bonciani DeGrassi Vicini Weinzierl

... Henn; Henn Smirnov & Smirnov Henn Melnikov, Smirnov Caron-Huot Henn Gehrmann vonManteuffel Tancredi Lee Argeri diVita Mirabella Schlenk Schubert Tancredi **P.M**. diVita Schubert Yundin **P.M**. Papadopoulos Papadopoulos Tommasini Wever Ablinger Bluemlein DeFreitas Schneider

Quantum Mechanics

Schroedinger Eq'n (ε-linear Hamiltonian)

 $i\hbar \partial_t |\Psi(t)\rangle = H(\epsilon, t) |\Psi(t)\rangle$, $H(\epsilon, t) = H_0(t) + \epsilon H_1(t)$

Interaction Picture

 $H_{i,I}(t) = B^{\dagger}(t) \ H_i(t) \ B(t)$

Search Matrix Transform

$$i\hbar \partial_t B(t) = H_0(t)B(t)$$
 B

$$B(t) = e^{-\frac{i}{\hbar} \int_{t_0}^t d\tau H_0(\tau)}$$

Schroedinger Eq'n (canonical form)

 $i\hbar \partial_t |\Psi_I(t)\rangle = \epsilon H_{1,I}(t) |\Psi_I(t)\rangle,$

Magnus Expansion

System of 1st ODE

 $\partial_x Y(x) = A(x)Y(x)$, $Y(x_0) = Y_0$. A(x) non-commutative

Solution: Matrix Exponential

$$Y(x) = e^{\Omega(x,x_0)} Y(x_0) \equiv e^{\Omega(x)} Y_0,$$

$$\Omega(x) = \sum_{n=1}^{\infty} \Omega_n(x) .$$

 \sim

BCH-formula

$$\Omega_{1}(x) = \int_{x_{0}}^{x} d\tau_{1} A(\tau_{1}) ,$$

$$\Omega_{2}(x) = \frac{1}{2} \int_{x_{0}}^{x} d\tau_{1} \int_{x_{0}}^{\tau_{1}} d\tau_{2} \left[A(\tau_{1}), A(\tau_{2}) \right] ,$$

$$\Omega_{3}(x) = \frac{1}{6} \int_{x_{0}}^{t} d\tau_{1} \int_{x_{0}}^{\tau_{1}} d\tau_{2} \int_{x_{0}}^{\tau_{2}} d\tau_{3} \left[A(\tau_{1}), \left[A(\tau_{2}), A(\tau_{3}) \right] \right] + \left[A(\tau_{3}), \left[A(\tau_{2}), A(\tau_{1}) \right] \right] .$$

Argeri, Di Vita, Mirabella,

Schlenk, Schubert, Tancredi, P.M. (2014)

Filterated Integrals

$$C_{i_{k},...,i_{1}}^{[\gamma]} \equiv \int_{\gamma} d\log \eta_{i_{1}} \dots d\log \eta_{i_{k}} \equiv \int_{0 \le t_{1} \le \dots \le t_{k} \le 1} g_{i_{k}}^{\gamma}(t_{k}) \dots g_{i_{1}}^{\gamma}(t_{1}) dt_{1} \dots dt_{k} \qquad g_{i}^{\gamma}(t) = \frac{d}{dt} \log \eta_{i}(\gamma(t))$$
Chen Goncharov
Remiddi Vermaseren Gehrmann Remiddi
Bonciani Remiddi **P.M.**
Vollinga Weinzierl
Brown

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Duhr Gangl Rhodes

Argeri, Di Vita, Mirabella, Schlenk, Schubert, Tancredi, **P.M**. (2014)

Quantum Mechanics

- Time-evolution in Perturbation Theory
- ^β perturbation parameter: ε
- Section Section 4 ματαγραφία ματαγρατιμα ματαγραφία ματαγρα ματαγραφία ματαγραφία ματαγ
- Unitary transform
- Schroedinger Equation in the interaction picture (ε-factorization)
- Solution: Dyson series

• Feynman Integrals

- Kinematic-evolution in Dimensional Regularization
 space-time dimensional parameter: ε = (4-d)/2
 Linear system in ε
 non-Unitary Magnus transform
- System of Differential Equations in canonical form (ε-factorization) Henn (2013)
- Solution: Dyson/Magnus series

boundary term (simpler integral)

Feynman integrals can be determined from differential equations that looks like gauge transformations

 $= \mathrm{e}^{\Omega(d,x)}$

Drell-Yan @ 2loop EW-QCD

Bonciani, Di Vita, Schubert, P.M. (to appear)



Systems of 1st ODE for 41 Master Integrals using Reduze 2

$$d\mathcal{I} = \epsilon \, d\hat{A} \, \mathcal{I} \quad \text{with} \quad d\hat{A} = \hat{A}_x \, dx + \hat{A}_y \, dy$$

$$dA = \sum_{i=1}^{n} M_i \ d\log \eta_i$$

• 1-Mass



₽31 MIs

alphabet: 6 rational letters

solution: GPL's

umerical checks using **GiNac** vs **SecDec constants:** GPL's @ 1 • $\{-1, 0, \frac{1}{2}, 1\}$ 2-Mass



₩36 MIs

alphabet: 12 rational + 5 irrational letters

solution: Iterated integrals ::

O mixed Chen-Goncharov representation

numerical checks using **GiNac** vs **SecDec**

O 1-fold representation over GPLs-kernel by using ibp for Chen-integrals **constants:** GPL's @ 1 • $\{-1, 0, -i, i, 1, (-1)^{\frac{1}{3}}, -(-1)^{\frac{2}{3}}\}, \cdot \{-1, 0, -i, i, 1, -(-1)^{\frac{1}{6}}, -(-1)^{\frac{5}{6}}\},$

Summary and Outlook

☑ IntegrANDS

Se Multi-Loop Integrand Reduction

- Complete Development :: for generic kinematics
- Exploiting DimReg :: Adaptive Unitarity and Transverse space integration
 - any loop :: we are at the same point as OPP for 1-loop.

Applying symmetries to the coefficients w/in the integrand decomposition

FDF: simple implementation of FDH scheme for generalized unitarity cuts Fazio, Mirabella, Torres, PM (2014)

BCJ relations @ tree-level in DimReg w/in FDF Primo, Schubert, Torres, PM (2015)

BCJ relations @ 1-Loop Chester (2016)

Primo, Torres (2016)

☑ IntegrALS

Multi-Loop Master Integrals evaluation

Differential Equations (analytic as well as numerical) :: Magnus Exponential

exploiting Path invariance

MI's in different dimensions ==> Adaptive Differential Equations?

Numerical methods: the big short