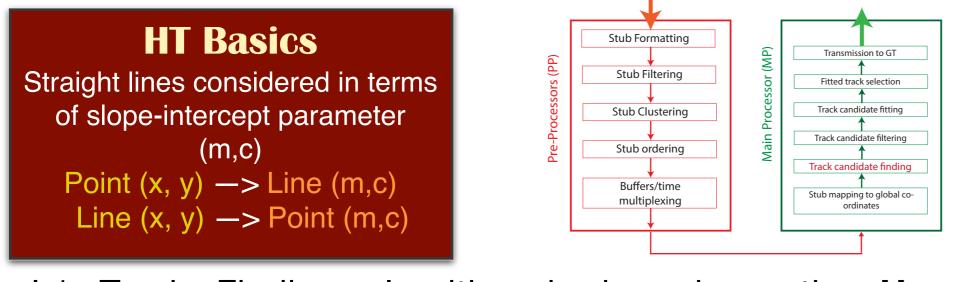
# **Demonstrator Plans for FPGA-based** L1 Track-finding with Hough Transform Davide Cieri - davide.cieri@stfc.ac.uk

## Track Trigger Concept

One of the major upgrades of the **Phase II CMS experiment** at CERN will be the Track Trigger. The UK groups proposed for it a Time Multiplexed Trigger architecture, based on FPGA electronics. In a TMT all data from one event are analysed by a single processor. To achieve this two processing layers are required (Pre-processors & Main-Processors). The PPs take data directly from the Front-end modules and buffer them into the MPs, where the Track Finding algorithm is implemented.



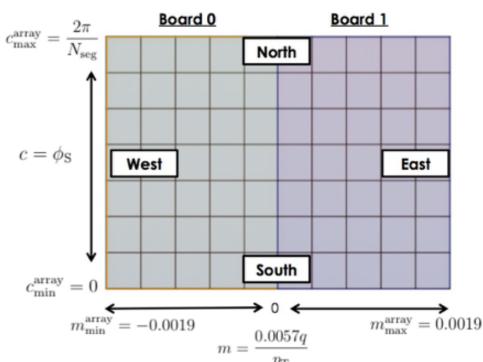
The L1 Track Finding algorithm is based on the Hough **Transform** method, which is applied to the  $r,\phi$  coordinates, projecting them in the *m*,*c* plane.  $2\pi/N_{s}$ 

### The First Demonstrator

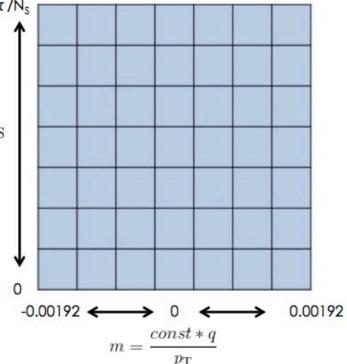
The first demonstrator would simulate the behaviour of a Main Processor board. It will be formed by two **µTCA MP7 boards**, in which a  $r-\phi$  Hough Transform array will be implemented. Future demonstrators will make use also of the *z*-coordinate information and include a track-fitting stage. The array will be **split** in the two boards **simmetrically** at m=0. Board 0 will reconstruct negative particles, whereas board 1 will operate with positives.



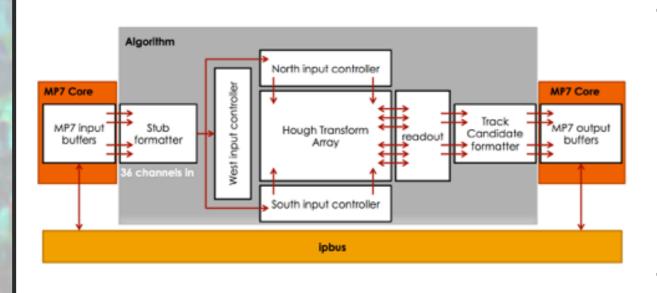




Here  $c = \phi_S$  is the the predicted  $\phi$ coordinate of the track at a chosen radial offset, with respect to the lower  $c = \phi_{\rm S}$ bound of the  $\phi$  segment that the stub is allocated to; and *m* is proportional to the inverse of  $p_{\tau}$ . When a cell contains 5 or more stubs at unique radii, a track candidate is found (**r-filter**).

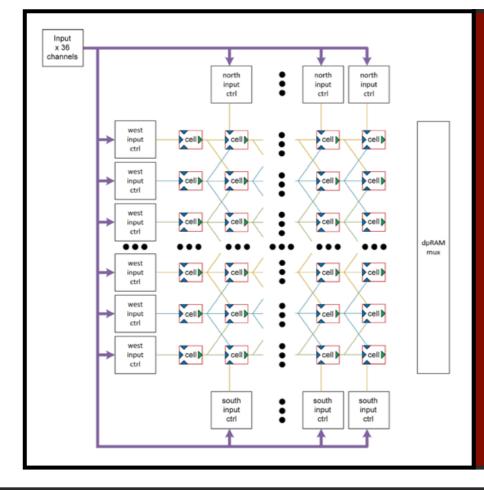


## The Main-Processor



The MP firmware will be constituted by two main blocks, the MP7 Core and the Algorithm. The MP7 core provides the infrastructure for clocking, TTC signals and the

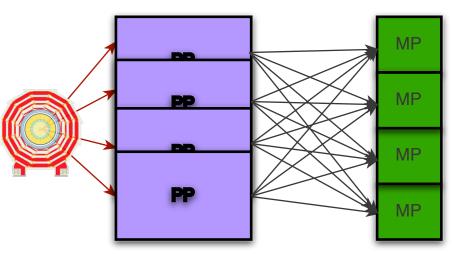
handling of input/output data. The input to the board is over 72 optical links, each carrying a 32 bits word. Stub data will require 64 bits, thus each stub will be split across two input frames on the same link. The 72 input channels carry 36 stubs per tick, therefore the algorithm firmware will have 36 inputs. The algorithm represents the Hough Transform array.



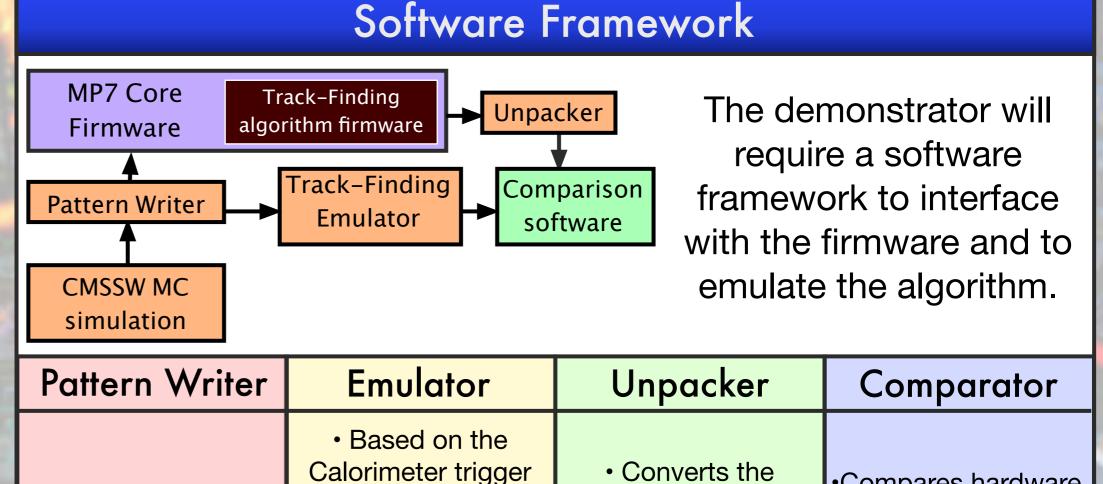
#### **Array Dataflow**

#### The Pre-Processor

The Pre-Processor tasks will be reproduced by the **software**, which will send its output into MP7 input buffers via IPbus. The three main responsibilities of the PP are:



- Assignment of stubs to the correspondent  $\phi$  segment
- Calculation of the bend resolution parameter  $\rho$
- Place cut on stub  $p_{\perp}$  and  $\eta$  parameters Additional tasks can also be implemented, like stub clustering and duplicate removal.



• Stubs can enter in the array from West, North and South

• Input controllers determine if the stub should enter the array at the adjacent cell Inside the array dataflow allowed only along east, south-east and north-east directions

- Stubs stored in cell if they satisfy cell *m*-*c* conditions
- Cell marked for readout when it fulfils r-filter criteria
  - BX end signaled using a fake stub

## Acknowledgment

The research leading to these results has received funding from the People Programme (Marie Curie Actions) of the European Union's Seventh Framework Programme FP7/2007-2013/ under REA agreeement n. [317446] INFIERI "Intelligent Fast Interconnected and Efficient Devices for Frontier Exploitation in Research and Industry"

upgrade emulator output data of the Matches precisely MP7 firmware in EDM files for the the firmware Used for data compator. quality and dataflow • Forms a single framework with the studies, analysis and comparison emulator with MC simulation

•Compares hardware and emulator results

• Creates plots for debugging and analysis

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\*Supported by the EU FP7-PEOPLE-2012-ITN project nr. 317446, INFIERI, "Intelligent Fast Interconnected and Efficient Devices for Frontier Exploitation in Reasearch and Industry"







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