Smallest Interval

$$\mathcal{O}_{1-lpha}^{
m S}=\{r^*\}$$
 $P(\mathcal{O}_{1-lpha}^{
m S}|N,p)\overset{?}{\geq}1-lpha$ $P(r^*+1|N,p)\overset{?}{>}P(r^*-1|N,p)$

$$\mathcal{O}_{1-\alpha}^{S} = \{r^*, r^* + 1\}$$
 $\mathcal{O}_{1-\alpha}^{S} = \{r^*, r^* - 1\}$

$$P(\mathcal{O}_{1-\alpha}^{S}|N,p)\stackrel{?}{\geq} 1-\alpha$$
 collect elements according to probability rank with $21-\alpha$

Data Analysis and Monte Carlo Methods

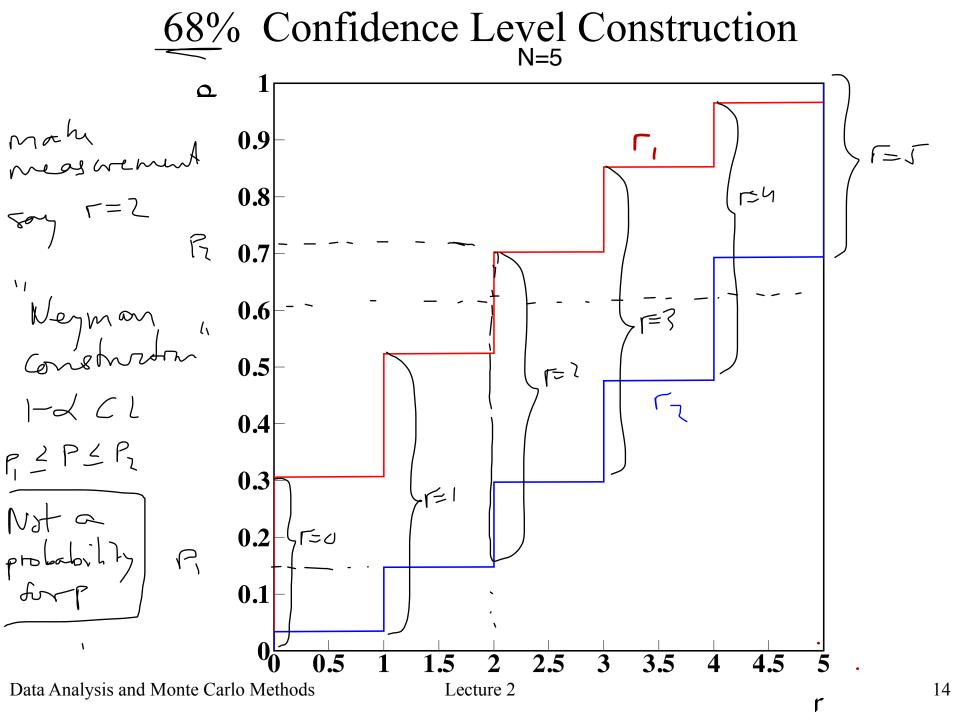
Lecture 2

Binomial Distribution – example

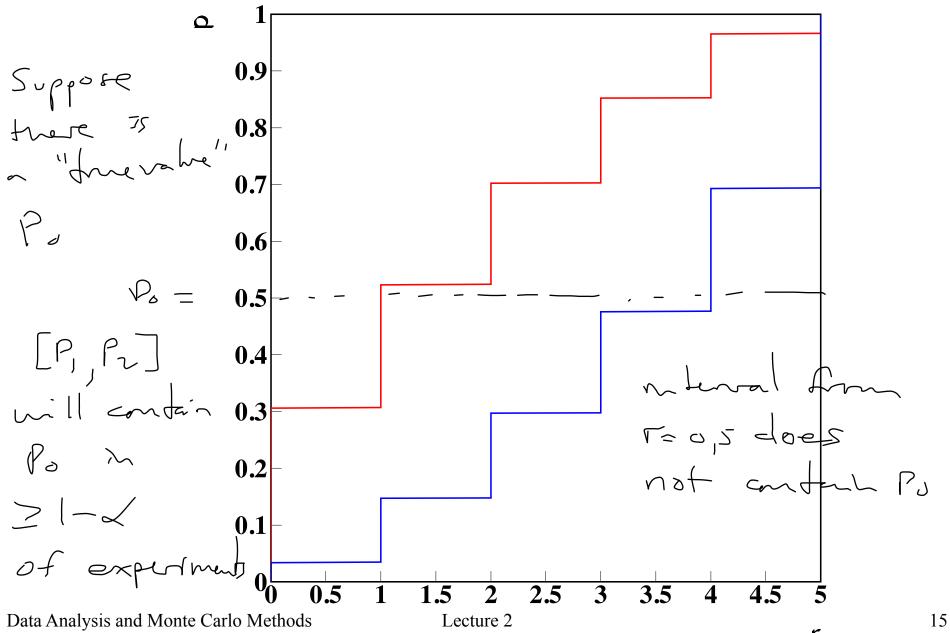
r	P(r N=5,p=0.6)	F(r N=5,p=06)	Rank	F(r N=5,p=06) According to rank
0	0.01024	0.01024	6	1
1	0.0768	0.08704 ひょうど	5	0.98976
2	0.2304	0.31744 U. 9 0	3	0.8352
3	0.3456	0.66304 0,67	1	0.3456
4	0.2592	0.92224 0.33	2	0.6048
5	0.07776	1 0.078	4	0.91296

$$1-2=0.9$$
 $2=0.05$
 $5=0.05$
 $5=0.05$
 $5=0.9$
 $5=0.9$

$$0.9 = \{7,3,9,5\}$$

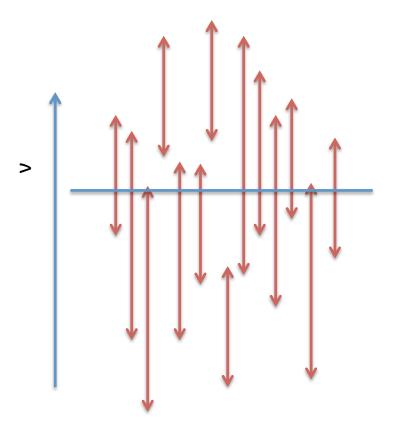


68% Confidence Level Construction N=5



Use of Frequentist CL Intervals

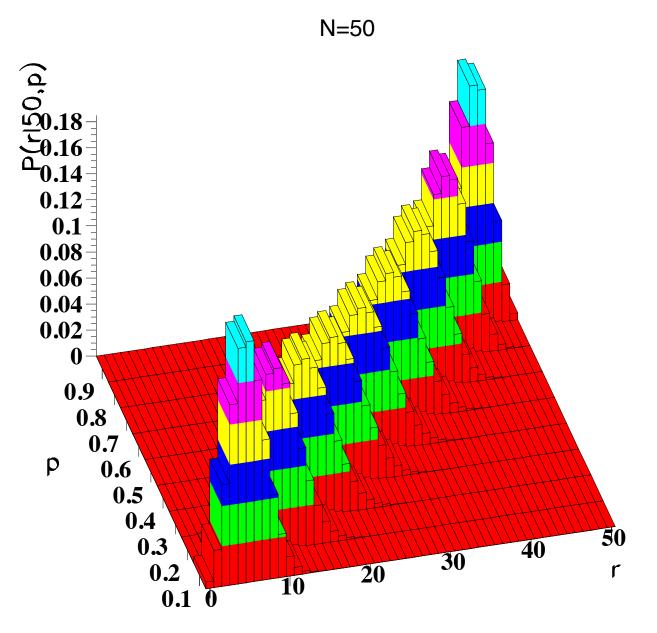
Not intended to be used individually. Rather, collect a lot of intervals and use these to 'find' the true value (not specified how).



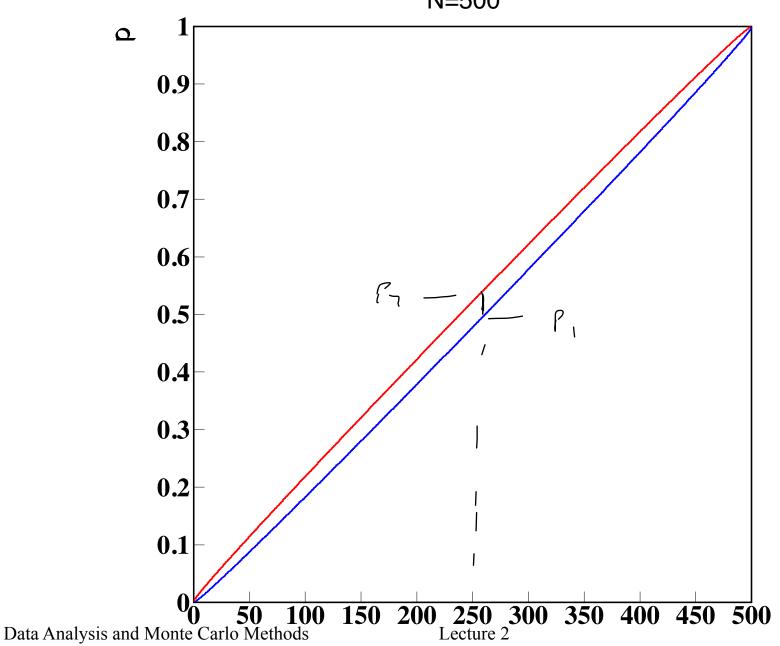
True value should be the one that is in the set of intervals the right fraction of the time (e.g., 68% of the time for the 68% CL intervals).

GERDA Collaboration Meeting 15

Binomial Distribution – in more detail



68% Confidence Levels N=500



Binomial Models – Bayesian Analysis

$$P(\vec{\lambda}, M | \vec{D}) = \frac{P(\vec{D} | \vec{\lambda}, M) P(\vec{\lambda}, M)}{P(\vec{D})}$$

Bayes Equation

$$P(M|\vec{D}) = \underbrace{\int P(\vec{\lambda}, M|\vec{D}) d\vec{\lambda}}_{\text{reconstraints}} = \underbrace{\frac{\left[\int P(\vec{D}|\vec{\lambda}, M) P_0(\vec{\lambda}|M) d\vec{\lambda}\right] P_0(M)}{P(\vec{D})}}_{P(\vec{D})}$$

evidence

$$Z = \int P(\vec{D}|\vec{\lambda}, M) P_0(\vec{\lambda}|M) d\vec{\lambda}$$

"morginal I.helihood

Posterior Odds

$$\frac{P(M_1|D)}{P(M_2|\vec{D})} = Z_1 P_0$$

Prior Odds

Bayes Factor

Binomial Distribution

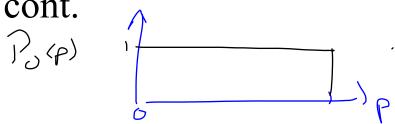
Suppose we perform N trials and have r successes. What is the probability distribution for p?

E.g., you want to say something about the efficiency of your detector.

From Bayes' Theorem:

From Bayes' Theorem:
$$P(p \mid r, N) = \frac{P(r \mid p, N)P_0(p)}{\int_0^1 P(r \mid p, N)P_0(p)dp} = \frac{\frac{N!}{(N-r)!r!}p^r(1-p)^{N-r}P_0(p)}{\int_0^1 \frac{N!}{(N-r)!r!}p^r(1-p)^{N-r}P_0(p)dp}$$

Binomial – cont.



If we assume that $P_0(p)$ is a constant

$$P(p \mid r, N) = \frac{P(r \mid p, N)P_0(p)}{\int_0^1 P(r \mid p, N)P_0(p)dp} = \frac{p^r(1-p)^{N-r}}{\int_0^1 p^r(1-p)^{N-r}dp}$$

The integral is technically a ' β function', and for x,n integers we have

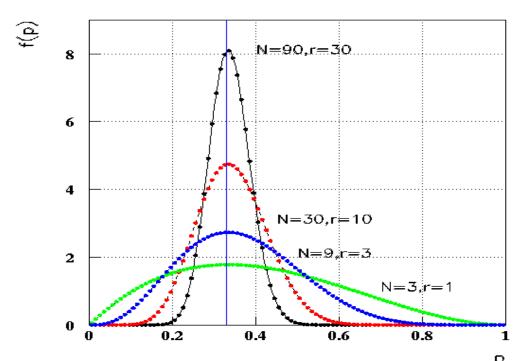
$$\int_{0}^{1} p^{x} (1-p)^{n-x} dp = \frac{x!(n-x)!}{(n+1)!}$$

SO

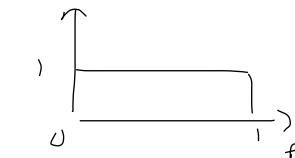
$$P(p \mid r, N) = \frac{(N+1)!}{r!(N-r)!} p^{r} (1-p)^{N-r}$$

Master formula

Binomial - cont.



Note mode at p=r/N



The expectation value and variance are:

$$\langle p \rangle = \int_{0}^{1} \frac{(N+1)!}{r!(N-r)!} p^{r+1} (1-p)^{N-r} dp = \frac{(N+1)!}{r!(N-r)!} \frac{(r+1)!(N-r)!}{(N+2)!} = \frac{r+1}{N+2}$$

$$\sigma^{2} = \frac{(r+1)(N-r+1)}{(N+3)(N+2)^{2}} = \langle p \rangle (1-\langle p \rangle) \frac{1}{N+3}$$

Detailed Example

Imagine we will perform a test of some equipment to determine how well it works (success rate). Two sets of data are taken:

N=100 trials, r=100 Successes

N=100 trials, r=95 Successes

Questions:

- what can we say about the efficiency in the first case?
- what about in the second case
- assuming the tests should be modeled with the same underlying model, what is our combined answer?
- how does it compare to N=200, r=195? (you do this in the exercises)
- are the results compatible?

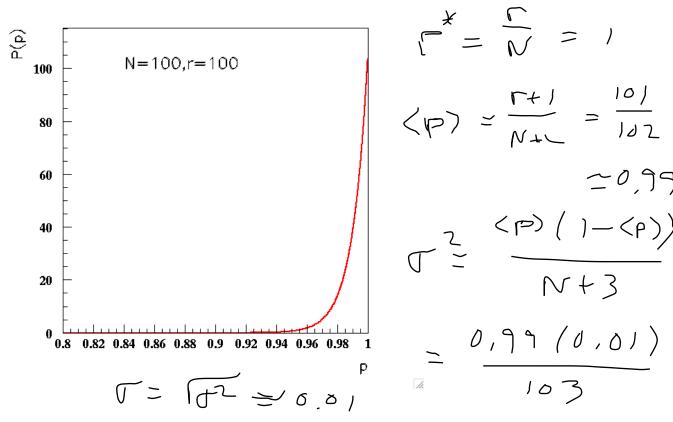
Example

Lecture 2

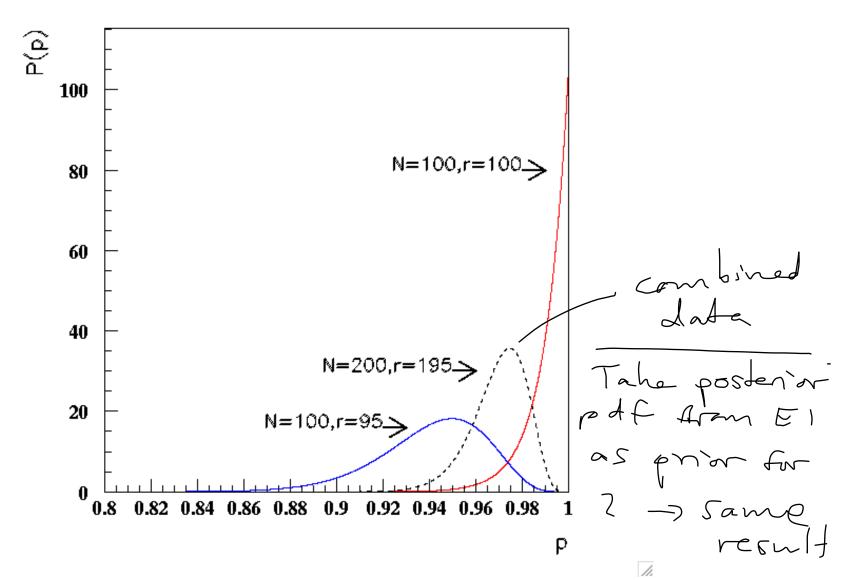
Data set 1: N=100, r=100

$$P(p \mid r, N) = \frac{(N+1)!}{r!(N-r)!} p^{r} (1-p)^{N-r}$$

$$P(p|100, 100) = 101p^{100}$$



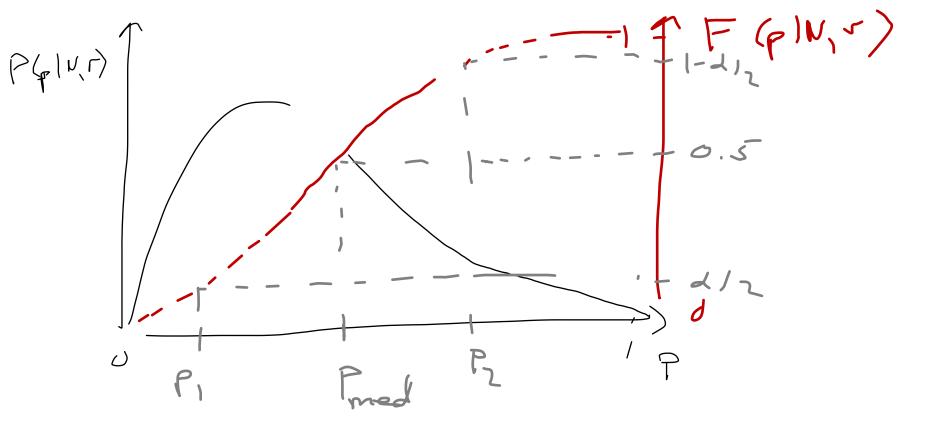
Example-continued



Summarizing a Distribution

Median

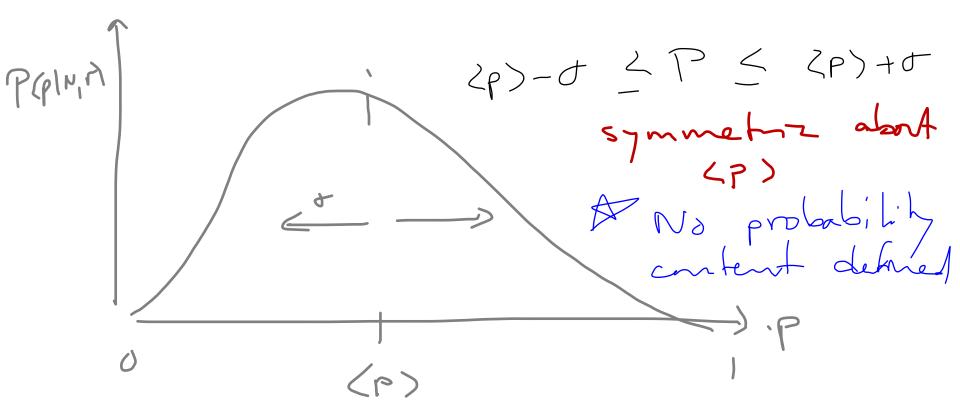
$$F(p_{\text{median}}) = 0.5$$
 $F(p_{\text{lower}}) = \frac{\alpha}{2}$ $F(p_{\text{upper}}) = 1 - \frac{\alpha}{2}$



Summarizing a Distribution

Mean

$$E[p] = \int_0^1 pP(p|N,r)dp \quad \sigma = \sqrt{E[p^2] - E[p]^2}$$



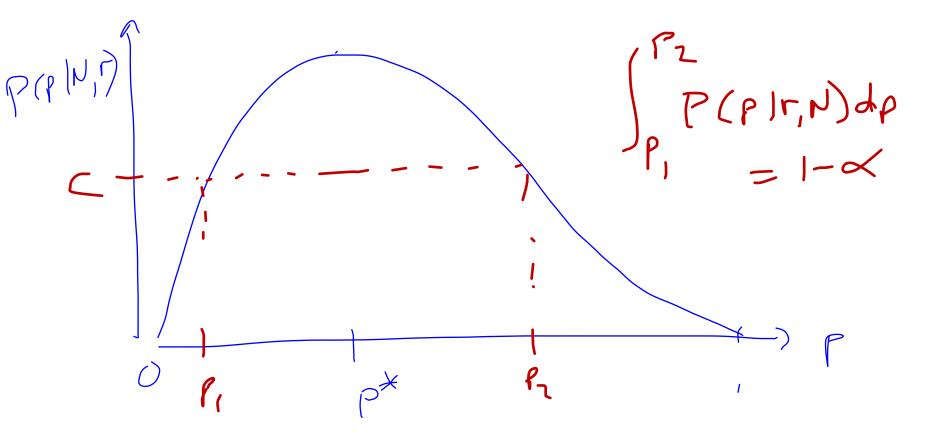
Summarizing a Distribution

Most-probable value (mode)

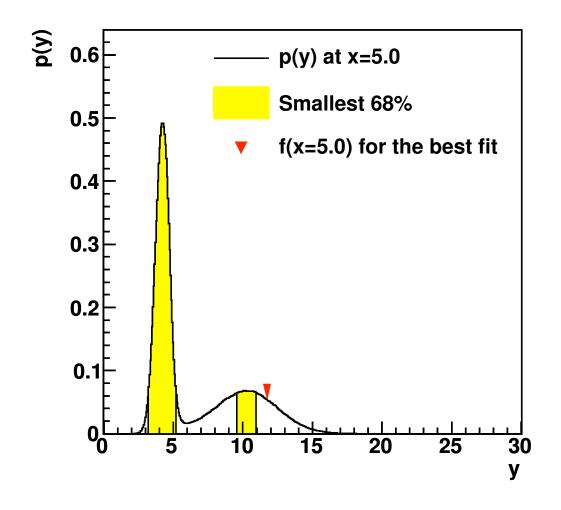
$$p_{\text{mode}} = \max_{p} \left[P(p|r, N) \right]$$

• Shortest interval(s)

$$p_{\text{mode}} = \max_{p} \left[P(p|r, N) \right] \qquad 1 - \alpha = \int_{P(p|r, N) > C} P(p|r, N) dp$$



Example – multimodal distribution



Poisson Distribution

A Poisson distribution applies when we do not know the number of trials (it is a large number), but we know that there is a fixed probability of 'success' per trial, and the trials occur independently of each other.

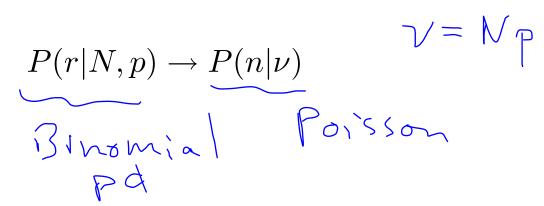
Alternatively – a continuous time process with a constant rate will produce a Poisson distributed number of events in a fixed time interval.

High energy physics example: beams collide at a high frequency (10 MHz, say), and the chance of a 'good event' is very small. The resulting number of events in a fixed time will follow a Poisson distribution. A single trial is one crossing of the beams.

Nuclear physics example: a large sample of radioactive atoms will produce a Poisson distributed number of events in a fixed time interval (assuming a $\tau >> T$)

Poisson Distribution

The Poisson distribution can be derived from the Binomial distribution in the limit when $N \rightarrow \infty$ and $p \rightarrow 0$, but Np fixed and finite. Then



The expected number of events is calculated from a rate, or from a luminosity and cross section or some other way

$$\nu = R \cdot T \text{ or } \nu = \mathcal{L} \cdot \sigma \text{ or...}$$

$$\uparrow \text{ cross section}$$

Poisson Distribution - derivation

$$P(n|N,p) = \frac{N!}{n!(N-n)!} p^n (1-p)^{N-n}$$

$$P(n|N,\frac{\nu}{N}) = \frac{N!}{n!(N-n)!} \frac{\nu^n}{N^n} \left(1 - \frac{\nu}{N}\right)^{N-n}$$

$$\frac{N!}{(N-n)!} = N \cdot (N-1) \cdot \dots \cdot (N-n+1) \approx N^n \quad + \mathcal{O}(N^{n-1})$$

$$\left(1 - \frac{\nu}{N}\right)^{N-n} \to \left(1 - \frac{\nu}{N}\right)^N \to e^{-\nu}$$

$$P(n|\nu) = \frac{e^{-\nu}\nu^n}{n!}$$
 Poisson Distribution

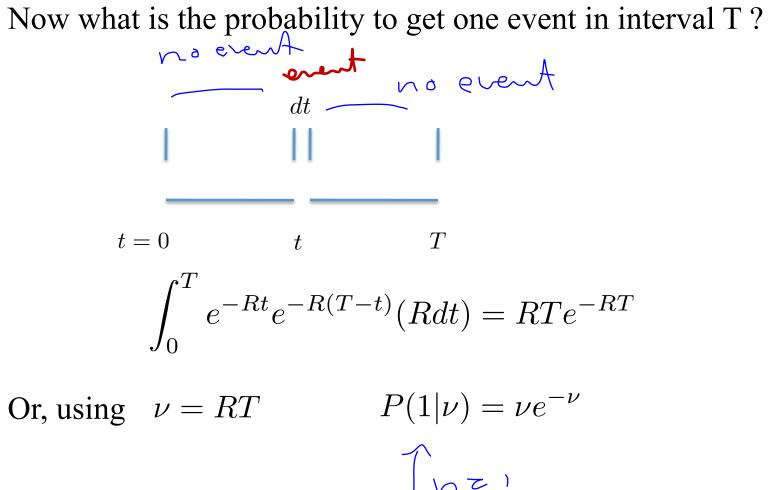
n = 0, 1, 2,

Poisson Distribution-alternate derivation

Process with a constant rate, R. What is the probability that no event has occurred up to time t?

Divide t into many very small intervals
$$\Delta t$$
, $t=n\Delta t$. Then $t=n$ then $t=$

Poisson Distribution-alternate derivation



Poisson Distribution-alternate derivation

Now what is the probability to get two events in interval T?

$$t=0 \qquad t_1 \qquad t_2 \qquad T$$

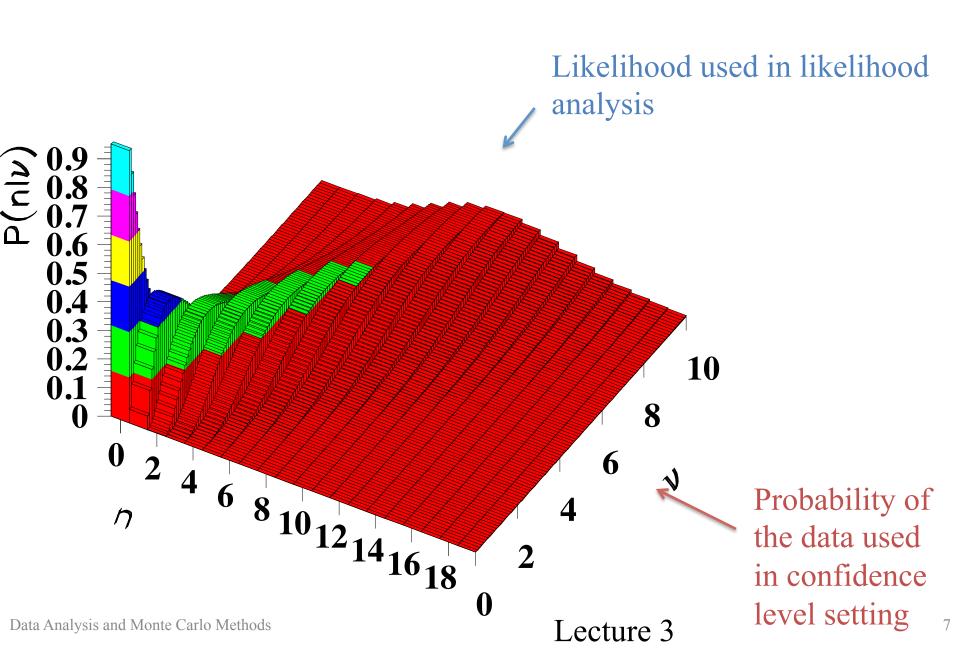
$$P(2|R,T)=e^{-RT}\int_0^T Rdt_1\int_{t_1}^T Rdt_2$$

$$P(2|R,T)=R^2e^{-RT}\int_0^T (T-t_1)dt_1=\frac{R^2T^2e^{-RT}}{2}$$
 or
$$P(2|\nu)=\frac{\nu^2e^{-\nu}}{2} \qquad \text{and} \qquad P(n|\nu)=\frac{\nu^ne^{-\nu}}{n!}$$

Data Analysis and Monte Carlo Methods

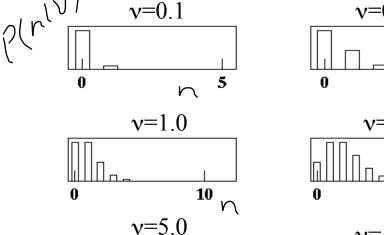
Lecture 3

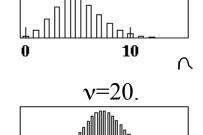
Poisson Example

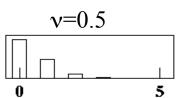


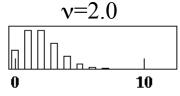
Poisson Distribution-cont.

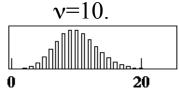
$$P(n \mid v) = \frac{v^n e^{-v}}{n!}$$











$$v=50$$
.

$$n^* = \lfloor \nu \rfloor$$
 $n^* = \lceil \nu \rceil - 1$
 $E[n] = \nu$
 $V[n] = \nu$

Notes:

- As v increases, the distribution becomes more symmetric
- Approximately Gaussian for large ν
- Poisson formula is much easier to use that the Binomial formula.

Poisson Distribution-cont.

Proof of Normalization, mean, variance:

Normalization:
$$\sum_{n=0}^{\infty} \frac{v^n e^{-v}}{n!} = e^{-v} \sum_{n=0}^{\infty} \frac{v^n}{n!} = e^{-v} e^v = 1$$

$$E[n] = \sum_{n=0}^{\infty} n \left(\frac{v^n e^{-v}}{n!} \right) = e^{-v} \sum_{n=1}^{\infty} v \frac{v^{n-1}}{(n-1)!} = v e^{-v} e^v = v$$

$$V[n] = E[n^2] - E[n]^2$$

$$E[n^2] = \sum_{n=0}^{\infty} n^2 \frac{v^n e^{-v}}{n!} = e^{-v} \sum_{n=1}^{\infty} v n \frac{v^{n-1}}{(n-1)!} \quad \text{write } n = (n-1+1)$$

$$= v e^{-v} \left(\sum_{n=1}^{\infty} (n-1) \frac{v^{n-1}}{(n-1)!} + \sum_{n=1}^{\infty} \frac{v^{n-1}}{(n-1)!} \right) = v^2 + v$$

$$V[n] = v^2 + v - v^2 = v \qquad ()$$

Example

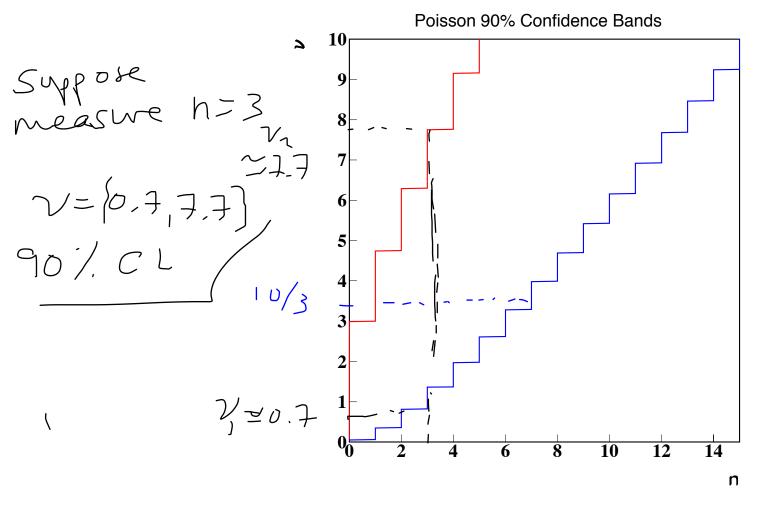
Example for $\underline{v=10/3} = 3.3$

	/		-	\sim
1	/		7.1	\neg
1	$-\alpha$	_	U_{-}	١.
١.	\ \			1

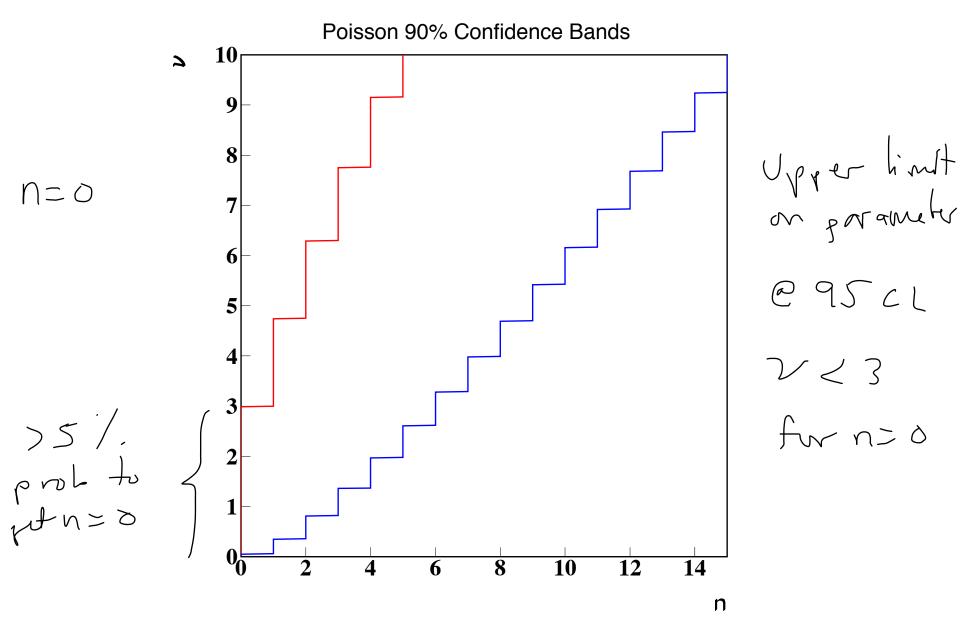
	$\underline{}$	$P(n \nu)$	$F(n \nu)$	R	$F_R(n \nu)$	
	0	0.0357	0.0357	7	0.9468	69
	1	0.1189	0.1546	5	0.8431	
. * 1771	2	0.1982	0.3528	2	0.4184	\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\
n*= LVJ = 3	3	0.2202	0.5730	1	0.2202	
-)	4	0.1835	0.7565	3	0.6019	
	5	0.1223	0.8788	4	0.7242	
	6	0.0680	0.9468	6	0.9111	(O) -
	7	0.0324	0.9792	8	0.9792	d C
1 ,	8	0.0135	0.9927	9	0.9927	ð .S
12/2	9	0.0050	0.9976	10	0.9976	$\left(\begin{array}{cc} \cdot & \cdot \end{array} \right)$
	10	0.0017	0.9993	11	0.9993	5 1,, 6
	11	0.0005	0.9998	12	0.9998	′)))
Q V S	12	0.0001	1.0000	13	1.0000	

Confidence Level Calculation

We observe n events, and ask which values of ν are accepted with confidence level 1- α . For 1- α =0.9, central intervals:



Confidence Level Calculation



Bayesian Data Analysis-Poisson Distribution

Typical examples – counting experiments such as source activity, failure rates, cross sections,...

$$P(\nu|n) = \frac{P(n|\nu)P_0(\nu)}{\int_0^\infty P(n|\nu)P_0(\nu)d\nu} = \frac{\frac{\nu^n e^{-\nu}}{n!}P_0(\nu)}{\int_0^\infty \frac{\nu^n e^{-\nu}}{n!}P_0(\nu)d\nu}$$

This is our master formula. Result in general will depend on choice of prior.

If we assume a flat prior starting at 0 and extending up to some maximum of v much larger than n.

$$P(\nu|n) = \frac{\frac{\nu^n e^{-\nu}}{n!} P_0(\nu)}{\int_0^\infty \frac{\nu^n e^{-\nu}}{n!} P_0(\nu) d\nu} = \frac{\frac{\nu^n e^{-\nu}}{n!}}{\int_0^{\nu_{max}} \frac{\nu^n e^{-\nu}}{n!} d\nu}$$

$$\int_0^{\nu_{max}} \frac{\nu^n e^{-\nu}}{n!} d\nu \approx \frac{1}{n!} \int_0^\infty \nu^n e^{-\nu} d\nu = \frac{1}{n!} n! = 1$$

$$P(\nu|n) = \frac{e^{-\nu}\nu^n}{n!} \qquad \nu^* = n$$
 Now probability density for ν

red a

Very for a

"proper" prior

Lecture 3

The expectation value:

$$<\nu> = \int_0^\infty P(\nu|n)\nu d\nu = \int_0^\infty \frac{\nu^n e^{-\nu}}{n!} \nu d\nu = \frac{(n+1)!}{n!} = n+1$$

The variance:

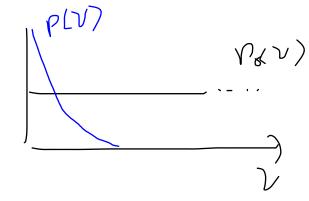
$$\sigma^{2} = \int_{0}^{\infty} P(\nu|n)(\nu - \langle \nu \rangle)^{2} d\nu \qquad 1$$

$$= \int_{0}^{\infty} \frac{\nu^{n} e^{-\nu}}{n!} \nu^{2} d\nu - \langle \nu \rangle^{2} \int_{0}^{\infty} \frac{\nu^{n} e^{-\nu}}{n!} d\nu$$

$$= \frac{(n+2)!}{n!} - (n+1)^{2} = n+1$$

Note:
$$n=0 < v > =1$$
 ???

From prior, expect
$$\langle \nu \rangle = \int_0^{\nu_{max}} P_0(\nu) \nu d\nu = \int_0^{\nu_{max}} \frac{\nu}{\nu_{max}} d\nu$$



$$= \left[\frac{\nu^2}{2(\nu_{max})}\right]_0^{\nu_{max}}$$

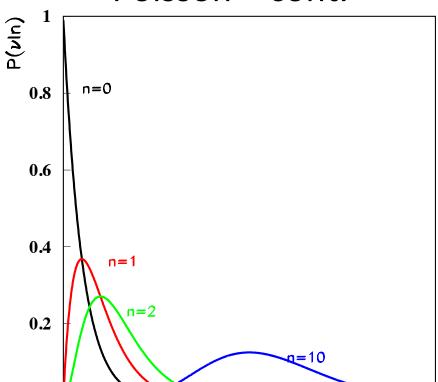
$$= \frac{\nu_{max}}{2}$$

What happened?

$$P(\nu|0) = e^{-\nu}$$

n=0 is a measurement!





Comments:

Some examples

If you decide to quote the mode as your nominal result, you would use $v^*=n$. For large enough n, the 68% probability region is then approximately

10

$$n - \sqrt{n} \to n + \sqrt{n}$$

0

15

20

The cumulative distribution function:

$$F(\nu|n) = \int_0^{\nu} \frac{\nu'^n e^{-\nu'}}{n!} d\nu'$$

$$= \frac{1}{n!} \left[-\nu'^n e^{-\nu'} |_0^{\nu} + n \int_0^{\nu} \nu'^{n-1} e^{-\nu' d\nu'} \right]$$

$$= 1 - e^{-\nu} \sum_{i=0}^n \frac{\nu^i}{i!}$$

Poisson – Examples

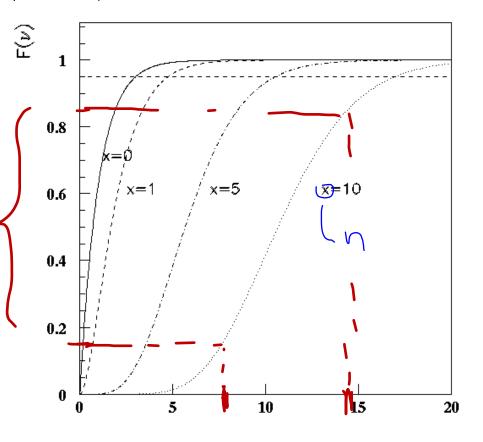
Assume measure zero counts.

With flat prior assumption

$$P(\nu|n=0) = e^{-\nu}$$

$$F(\nu|n=0) = 1 - e^{-\nu}$$

For a 95% credibility upper limit $0.95 = 1 - e^{-\nu}$ $\nu \approx 3$ same and 4 = 0.14 4 = 0.14 68%

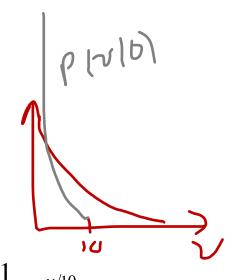


Poisson – cont.

What if we cannot (or do not want to) take a flat prior

Po(v)

Suppose we can model the prior belief as $P_0(v) = \frac{1}{10}e^{-v/10}$



Now Bayes tells us
$$P(v \mid \mathbf{r} = 0) = \frac{P(0 \mid v)P_0(v)}{\int_0^\infty P(0 \mid v)P_0(v)dv} = \frac{e^{-v} \frac{1}{10}e^{-v/10}}{\int_0^\infty \frac{1}{10}e^{-11v/10}dv} = \frac{11}{10}e^{-11v/10}$$

$$<\nu> = \int_{0}^{\infty} \frac{11}{10} e^{-11\nu/10} v d\nu = 0.91$$

 $P(v \le 2.7) = 95\%$, i.e., $v \le 2.7$ with 95% probability

Poisson Distribution-cont.

We often have to deal with a superposition of two Poisson processes – the signal and the background, which are indistinguishable in the experiment. Usually we know the background expectations and want to know the likelihood of a signal in addition.

Example, the signal for large extra dimensions may be the observation of events where momentum balance is (apparently) strongly violated. However this can be mimicked by neutrinos, energy leakage from the detector, etc.

Use the subscripts B for background, s for signal, and assume n events are observed

$$P(n) = \sum_{n_s=0}^{n} P(n_s | v_s) P(n - n_s | v_B)$$

$$= e^{-(v_B + v_s)} \sum_{n_s=0}^{n} \frac{v_s^{n_s} v_B^{n-n_s}}{n_s! (n - n_s)!}$$
Binomial formula with $p = \left(\frac{v_s}{v_s + v_B}\right)$

$$= e^{-(v_B + v_s)} \frac{\left(v_s + v_B\right)^n}{n!} \sum_{n_s=0}^{n} \frac{n!}{n_s! (n - n_s)!} \left(\frac{v_s}{v_s + v_B}\right)^{n_s} \left(\frac{v_B}{v_s + v_B}\right)^{n-n}$$

$$= e^{-(v_B + v_s)} \frac{\left(v_s + v_B\right)^n}{n!}$$

$$= 1 \text{ by normalization}$$

Example

Example for $\underline{v=10/3} = 3.3$

	/		\sim
1 /		7 1	5
1 -a	_	U_{-}	١.
1 1			- 1

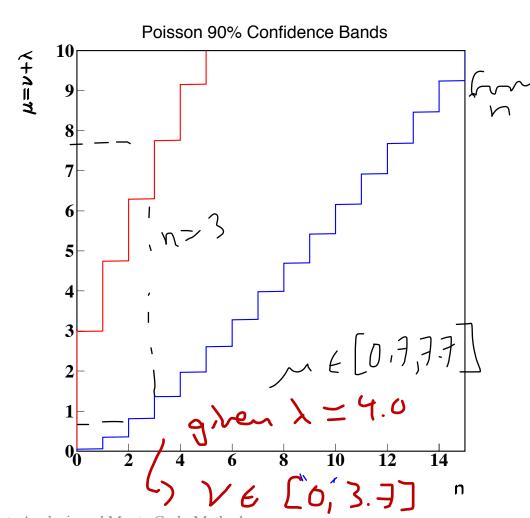
10

	$\underline{}$	$P(n \nu)$	$F(n \nu)$	R	$F_R(n \nu)$	
	0	0.0357	0.0357	7	0.9468	K G
	1	0.1189	0.1546	5	0.8431	
¥ 17/1	2	0.1982	0.3528	2	0.4184	\ \ \ \ \ - \ \ \ \
n*= LV] = 3	3	0.2202	0.5730	1	0.2202	
-)	4	0.1835	0.7565	3	0.6019	
	5	0.1223	0.8788	$\mid 4 \mid$	0.7242	
	6	0.0680	0.9468	6	0.9111	() -
	7	0.0324	0.9792	8	0.9792	09
1,	$\sqrt{8}$	0.0135	0.9927	9	0.9927	0,7
12/2	9	0.0050	0.9976	10	0.9976	$\left(\begin{array}{cc} \cdot & \cdot \end{array} \right)$
	10	0.0017	0.9993	11	0.9993	5 1, , 6
	11	0.0005	0.9998	12	0.9998	')))
\mathcal{O}^{\vee}	12	0.0001	1.0000	13	1.0000	

Frequentist Statistics



Poisson distribution in the presence of background, with mean λ . Then we have the same curves as for signal only, but replace ν with $(\nu+\lambda)$.



- Traditional approach:

 find limit on μ, then
 subtract λ to get limit on
 ν
- limit for ν improves for a fixed n when we add background.
- can get negative limits! For example, $n=0, \lambda>3$ gives $\nu<0$.

Feldman-Cousins Confidence Levels

Imagine we have a Poisson process with known background expectation and unknown signal. If $\lambda \geq 3$ and n=0 then the confidence interval for ν is empty (or includes unphysical values).

This has led to new definitions for the Confidence Intervals. The most popular (at least in particle physics) is the Feldman-Cousins construction, where a rank is assigned to possible outcomes based on

$$r = \frac{P(n|\mu = \lambda + \nu)}{P(n|\hat{\mu})}$$

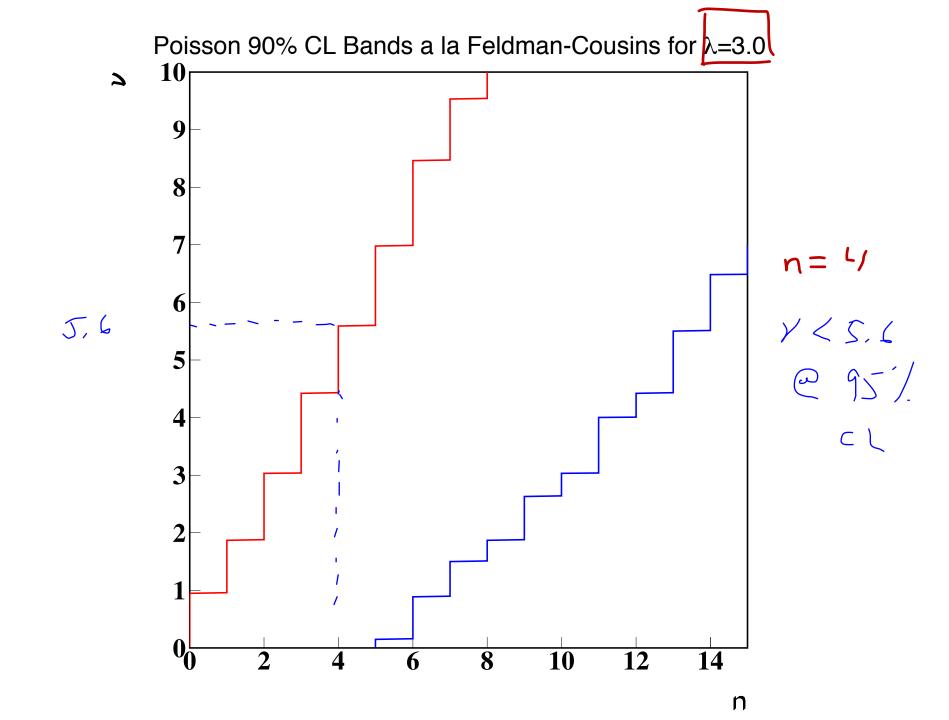
Where $\hat{\mu}$ is the value of μ that maximizes $P(n|\mu)$ given the constraints.

Concrete example: $\lambda = 3.0 \quad \nu = 0.\overline{3}$

	10/3=	7 5
/ / /	13	9 , 3

	\mathcal{M}					<u> ۸</u>
$\underline{}$	$P(n \mathbf{v})$	$\hat{\mu}$	$P(n \hat{\mu})$	r	Rank	$F_R(n u)$
0	0.0357	3.0	0.050	0.717	5	0.7565
1	0.1189	3.0	0.149	0.796	4	0.7208
2	0.1982	3.0	0.224	0.885	3	0.6091
3	0.2202	3.0	0.224	0.983	1	0.2202
4	0.1835	4.0	0.195	0.941	2	0.4037
5	0.1223	5.0	0.175	0.699	6	0.8788
6	0.0680	6.0	0.161	0.422	7	0.9468
7	0.0324	7.0	0.149	0.217	8	0.9792
8	0.0135	8.0	0.140	0.096	9	0.9927
9	0.0050	9.0	0.132	0.038	10	0.9976
10	0.0017	10.0	0.125	0.014	11	0.9993
11	0.0005	11.0	0.119	0.004	12	0.9998

m = max(n, x)Procedure depends an x



The Bayesian Way

$$\mu = \lambda + \nu$$
 $P(n|\mu) = \frac{e^{-\mu}\mu^n}{n!}$

Assuming (as before) that the background is perfectly known:

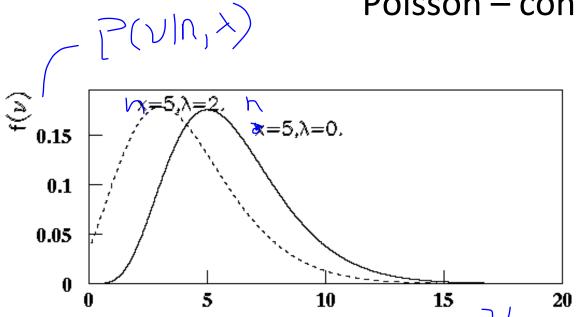
$$P(\nu|n,\lambda) = \frac{P(n|\nu,\lambda)P_0(\nu)}{\int P(n|\nu,\lambda)P_0(\nu)d\nu}$$

assuming a flat $P_0(v)$ and integrating by parts.

$$P(\nu|n,\lambda) = \frac{e^{-\nu}(\lambda+\nu)^n}{n!\sum_{i=0}^n \frac{\lambda^i}{i!}}$$

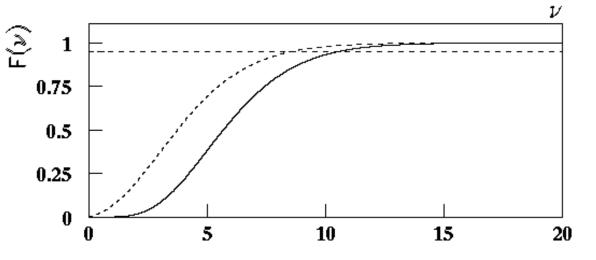
The cumulative pdf is
$$F(\nu|n,\lambda) = 1 - \frac{e^{-\nu} \sum_{i=0}^{n} \frac{(\lambda+\nu)^{i}}{i!}}{\sum_{i=0}^{n} \frac{\lambda^{i}}{i!}}$$

Poisson – cont.



Comment:

For n=0, $P(v|n, \lambda)=e^{-v}$. It does not matter how much background you have, you get the same probability distribution for the signal.



Comparing Feldman-Cousins with Bayesian Analysis with same background $\lambda = 3.0$ and a flat prior.

Recall:
$$P(\nu|n,\lambda) = \frac{e^{-\nu}(\lambda+\nu)^n}{n!\sum_{i=0}^n \frac{\lambda^i}{i!}}$$

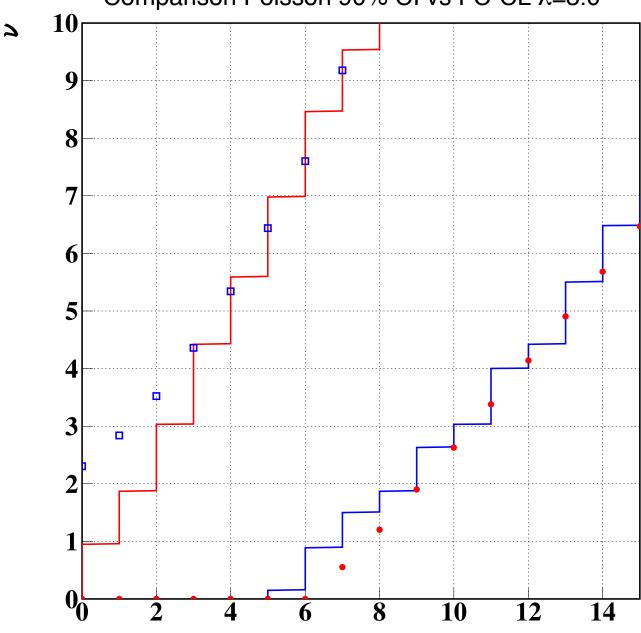
$$F(\nu|n,\lambda) = 1 - \frac{e^{-\nu} \sum_{i=0}^{n} \frac{(\lambda+\nu)^{i}}{i!}}{\sum_{i=0}^{n} \frac{\lambda^{i}}{i!}}$$

We will take the smallest interval with 90% credibility. I.e.,

$$\int_{P>C} P(\nu|n,\lambda)d\nu = 0.90$$

We find $\nu_{\rm down}$ $\nu_{\rm up}$ fulfilling this condition. Numerical integration.

Comparison Poisson 90% CI vs FC-CL λ =3.0



Example

Probabilistic model:

$$P(n_B|\lambda) = \frac{e^{-\lambda}\lambda^{n_B}}{n_B!}$$

$$P(n_S|\nu) = \frac{e^{-\nu}\nu^{n_S}}{n_S!}$$
Signal

$$P(n|\lambda,\nu) = \frac{e^{-\mu}\mu^n}{n!}$$

$$\mu = \lambda + \nu$$

combined is also Poisson processor

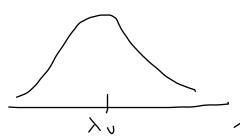
Example

Compare two situations:

- 1) no knowledge on the background
- 2) Separate data help us constrain the background

Suppose we measure n=7 events, what can we say ?

With Background knowledge



$$P(\lambda) = \frac{1}{\sqrt{2\pi}\sigma_{\lambda}} e^{-\frac{1}{2}\frac{(\lambda - \lambda_{0})^{2}}{\sigma_{\lambda}^{2}}}$$

With Background knowledge
$$P(\lambda) = \frac{1}{\sqrt{2\pi}\sigma_{\lambda}}e^{-\frac{1}{2}\frac{(\lambda-\lambda_{0})^{2}}{\sigma_{\lambda}^{2}}} \qquad \text{expts}, \\ \text{we east we mention for the support of the property of the support of the property o$$

Can build this into the likelihood (e.g., frequentist analysis) or call it prior knowledge (either way for Bayes)

$$\mathcal{L}(\nu,\lambda) = P(n|\nu,\lambda)P(\lambda)$$
 [i helihor damaly of the correction of

With Background knowledge - Bayes
$$P(\nu, \lambda) = P(\lambda) P(\nu)$$

$$P(\nu, \lambda | n) = \frac{P(n | \nu, \lambda) P(\lambda) P(\nu)}{\int P(n | \nu, \lambda) P(\lambda) P(\nu) d\lambda d\nu}$$

$$\underline{P(n|\lambda,\nu)} = \frac{e^{-(\lambda+\nu)}(\lambda+\nu)^n}{n!} \qquad P(\lambda) = \frac{1}{\sqrt{2\pi}\sigma_{\lambda}} e^{-\frac{1}{2}\frac{(\lambda-\lambda_0)^2}{\sigma_{\lambda}^2}}$$

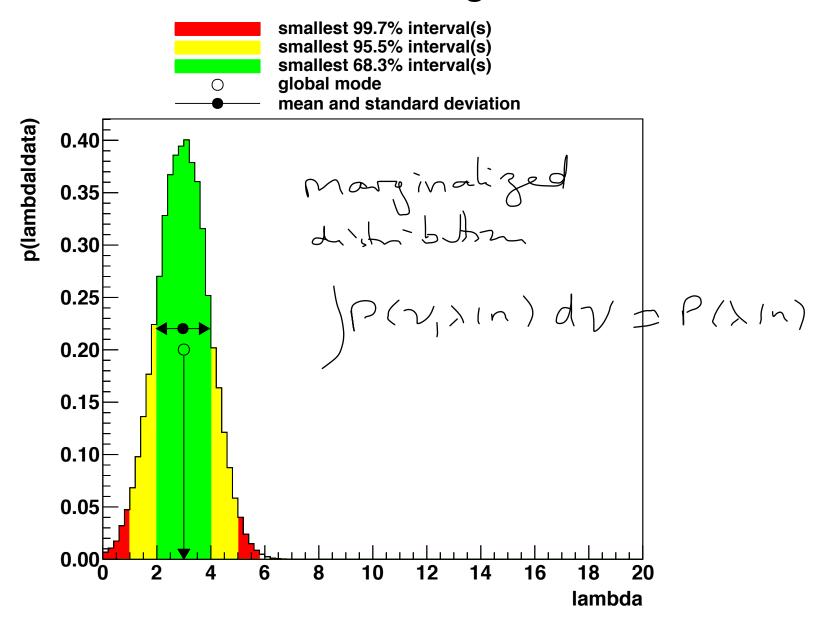
 $P_0(\nu) = {\rm constant}$ We solve this numerically (here with the BAT package) $\frac{1}{\rm https://www.mppmu.mpg.de/bat/}$

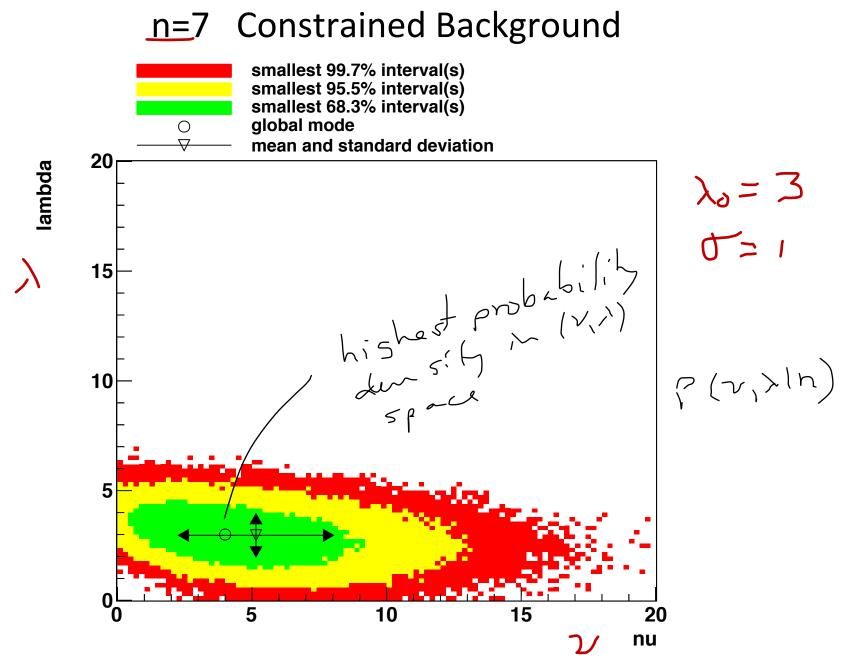
To get a probability distribution for the physics parameter, we marginalize

$$P(\nu|n) = \int P(\nu, \lambda|n) d\lambda$$

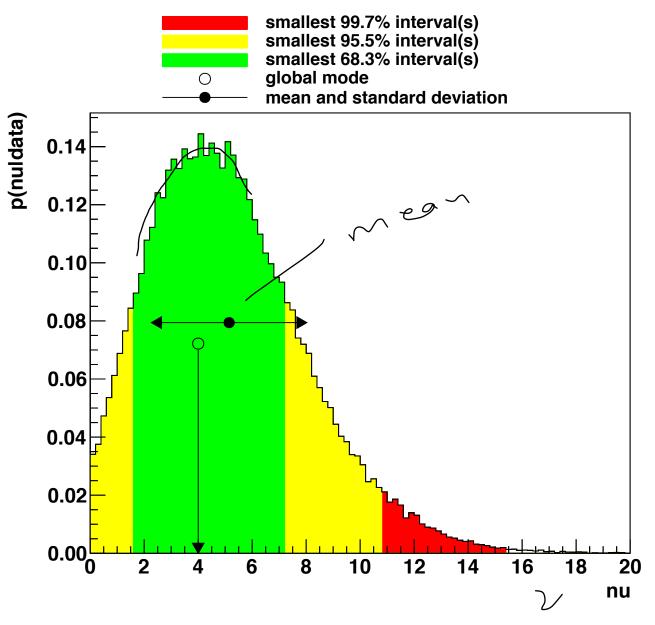
 $P(\nu|n) = \int P(\nu,\lambda|n) d\lambda \qquad \text{humeral program}$

n=7 Constrained Background





n=7 Constrained Background



On/Off Example

As an example, we will consider measuring the decay rate for a radioactive isotope, in the presence of background. Prototype for off source/on source problem.

We take two measurements, one with the source absent, to measure the background rate, and once with the source present.

Data Set	Source in/out	Run Time	Events
1	Out	100	100
2	In	100	110

What can we say about the decay rate for our isotope?

$$N = N_0 e^{-t/\tau} \quad \frac{dN}{dt} = -\frac{N}{\tau}$$

Get an estimate of the background rate from the first data set. Assume we don't know very much. How do we represent this initial lack of knowledge? Pick a simple form:

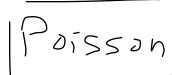
$$P_0(R_B) = \text{constant}$$

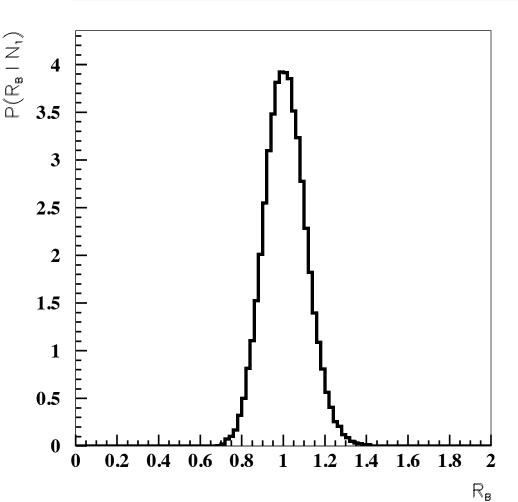
In this type of experiment, the number of counts in a time window follows a **Poisson Distribution**. For a flat prior, we found:

$$P(\lambda|N_1) = \frac{e^{-\lambda}\lambda^{N_1}}{N_1!} \qquad \lambda = R_B T$$

$$P(R_B)dR_B = P(\lambda)d\lambda = \frac{e^{-R_BT}(R_BT)^{N_1}}{N_1!}TdR_B$$

Data Set	Source in/out	Run Time	Events
1	Out	100	100





Now want to extract information on signal rate. We choose

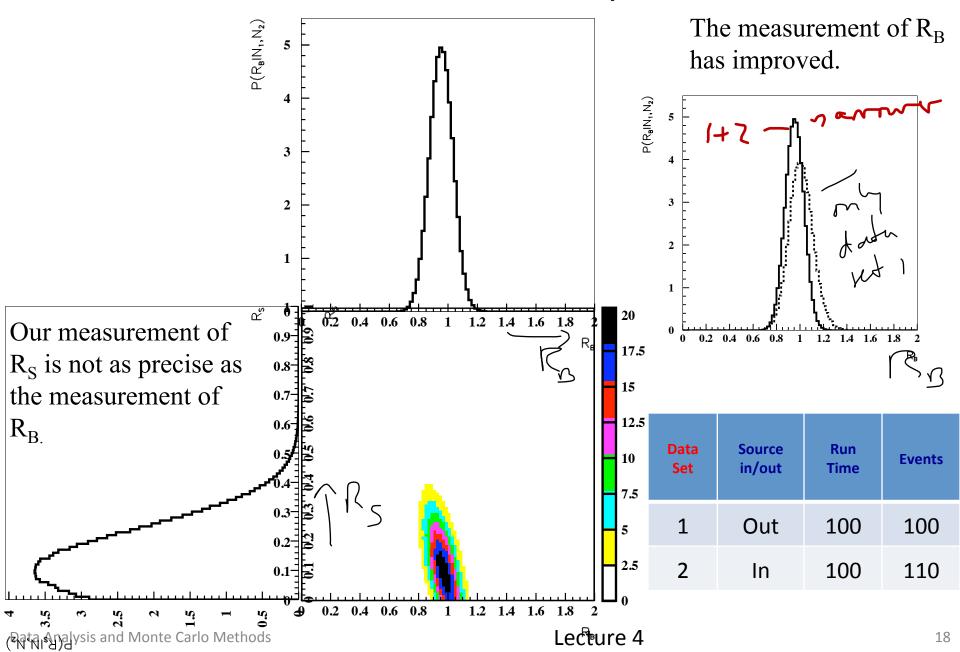
$$P_0(R_B, R_S) = P_0(R_B)P_0(R_S) = \text{constant}, R_S > 0, R_B > 0$$

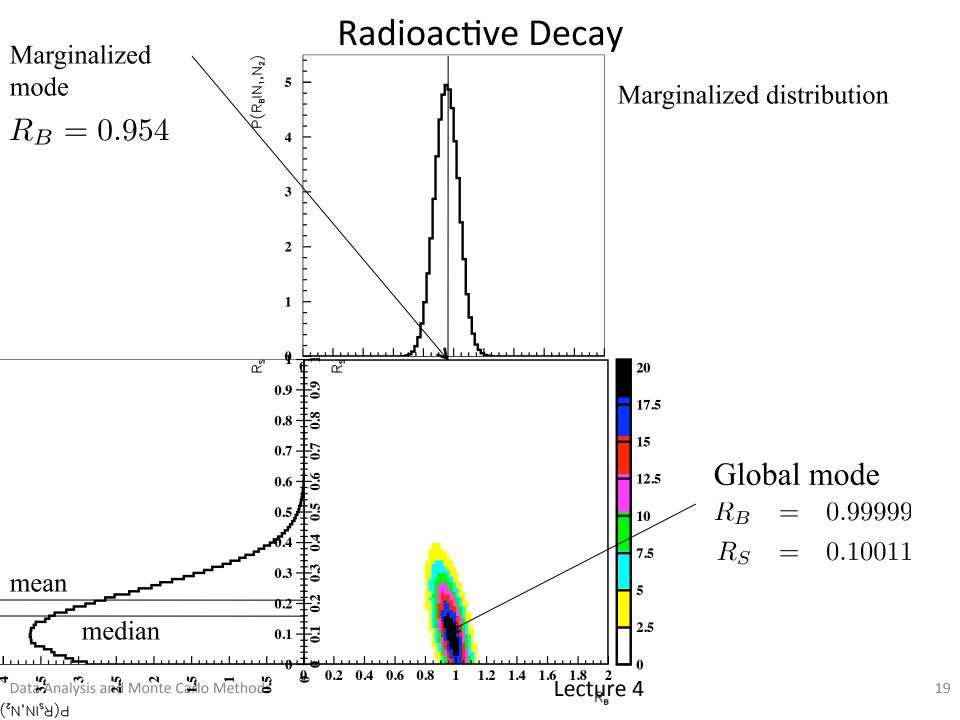
Analyze both data sets simultaneously

$$P(R_{B},R_{S}|N_{1},N_{2}) \propto P(N_{1},N_{2}|R_{B},R_{S})$$

$$P(N_{1},N_{2}|R_{B},R_{S}) = P(N_{1}|R_{B})P(N_{2}|R_{B},R_{S})$$

$$P(N_{1},N_{2}|R_{B},R_{S}) = \frac{(R_{B}T_{1})^{N_{1}}e^{-R_{B}T_{1}}}{N_{1}!} \frac{((R_{B}+R_{S})T_{2})^{N_{2}}e^{-(R_{B}+R_{S})T_{2}}}{N_{2}!}$$





Supernova 1987a

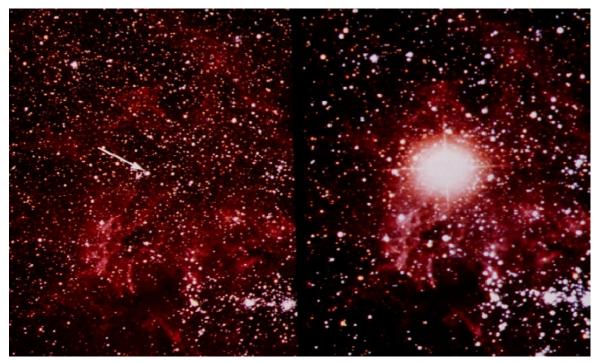
On the night of February 23, 1987 astronomers saw something they hadn't seen for 400 years... a **supernova explosion** close enough to be seen with the naked eye. A massive "blue giant" star, 50 times as large as our sun, had exploded in the Large Magellenic Cloud (a small suburb of our galaxy). The explosion actually occurred 170,000 years before... it took that long for the light to get here.

When a large star has burned up all of the nuclear fuel in it's center it becomes, in a few seconds, an almost empty shell and suddenly collapses.

The rebounding matter and energy becomes a very dense, and very bright, source of light. Suddenly the object becomes hundreds of time brighter than its progenitor star.

The "before" and "after" pictures for SN1987a are shown below.

http://wwwpersonal.umich.edu/~jcv/imb/ imbp4.html



The number of neutrinos emitted is extremely large... about **10^57** escape in a few seconds. After 170,000 years this pulse of neutrinos is spread out over the surface of a sphere 170,000 light-years in radius.... big enough to encompass our **whole galaxy**. Spreading out the 10^57 neutrinos over the surface of this huge sphere gives 10^13 neutrinos per square meter. All of the neutrinos are contained in a thin shell on the surface. The shell is only a few light-seconds thick (about the distance from here to the moon).

Of the 10^16 neutrinos that went through the IMB tank only 8 interacted with enough energy to be detected.... all near the lower limit of our energy threshold.

The normal rate of events from atmospheric neutrinos at these low energies was only about one per week, so seeing 8 in a few seconds meant something truly unique had happened.



Compare:

Did not see the light flash, no other detector recorded a signal. How significant is the results?

Light observed (see pictures) – now what is the significance?

IMB Observations

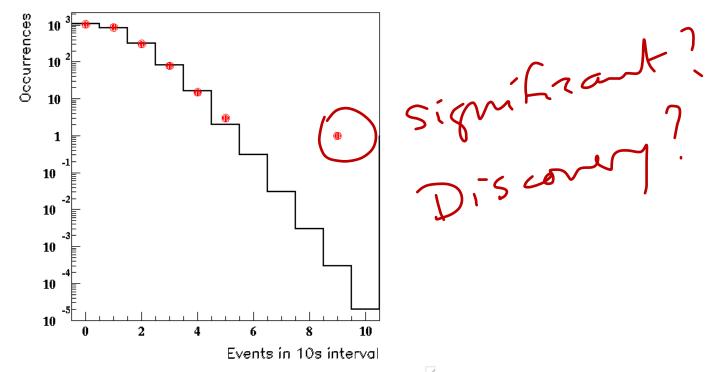
Example: Observation of Supernovae – IMB experiment

Number of events in 10 sec interval: 0 1 2 3 4 5 6 7 8 9

Frequency

Poisson with mean 0.77

1042 860 307 78 15 3 0 0 0 1 1064 823 318 82 16 2 0.3 0.03 0.003 0.0003



Data Analysis and Monte Carlo Methods

Lecture 4

23

IMB Observations

$$P(n \ge 9|0.77) = \sum_{n=0}^{\infty} \frac{e^{-0.77}0.77^n}{n!} = 1.3 \cdot 10^{-7}$$

2306 10s intervals analyzed.

$$P(r \ge 9|0.77, 2306 \text{ trials}) = 1 - P(r < 9|0.77, 2306)$$

$$= 1 - P(r < 9|0.77)^{2306}$$

$$= 1 - (1 - 1.3 \cdot 10^{-7})^{2306}$$

$$\approx 2306 \cdot 1.3 \cdot 10^{-7}$$

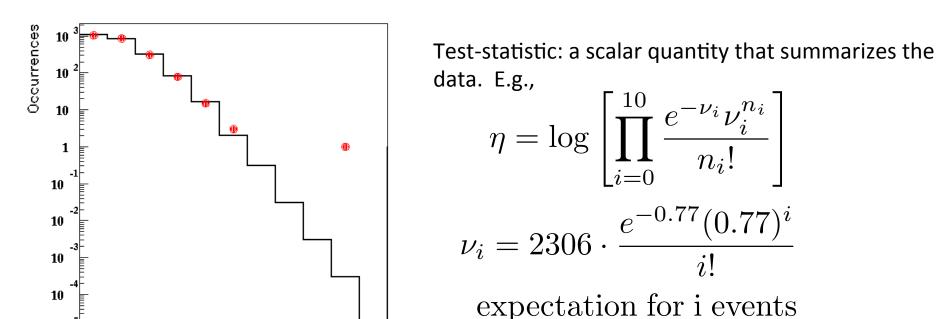
$$= 3 \cdot 10^{-4}$$

Test Statistic and p-value

Example: Observation of Supernovae – IMB experiment

Number of events in 10 sec interval: 0 1 2 3 4 5 6 7 8

 n_i 1042 860 307 78 15 3 0 0 0 1 1 1064 823 318 82 16 2 0.3 0.03 0.003 0.0003



Events in 10s interval

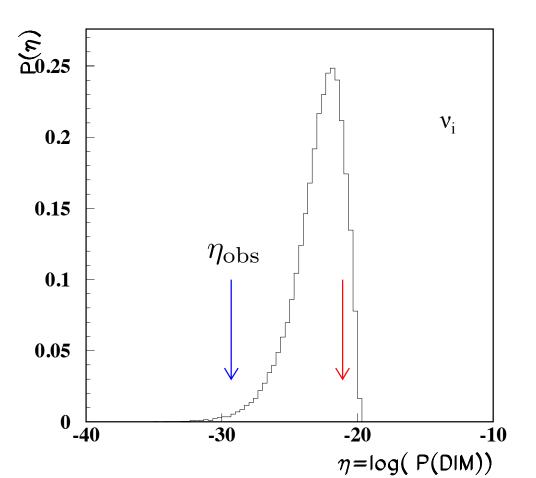
 n_i observations for i events

Distribution of test statistic

Null Hypothesis:

 ${
m H}_{
m 0}$ The bin contents are distributed according to Poisson processes with means ${
m v}_{
m i}$

Assuming H_0 , we can make the distribution of what we expect for η . Here it is:



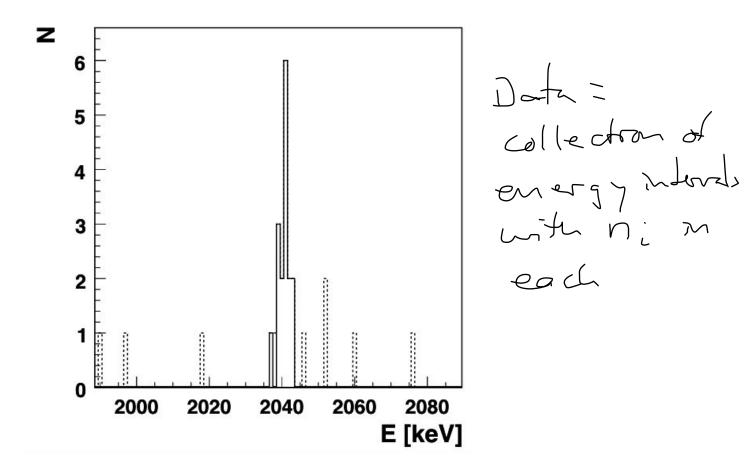
The histogram is from a large number of simulations of the experiment.

The blue arrow shows the observed value of $\boldsymbol{\eta}$

The red arrow shows the value of η if we leave out the observation of the 9 events.

$$p = \int_{\eta_{\min}}^{\eta_{\text{obs}}} P(\eta|H_0) d\eta$$
$$p = 0.007$$

Discovery or not?



Analyze energy spectrum and decide if there is evidence for a signal. Counting experiment – Poisson statistics.

Double Beta Decay Example

Prior:

The existing limits are $T_{1/2}>4\ 10^{25}$ yr; a positive claim for a signal exists at the level $T_{1/2}=1.2\ 10^{25}$ yr; my favorite theorist believes strongly that neutrinos are Majorana particles, but he wont tell me the neutrino mass; the theorist at a neighboring university says that he believes strongly in Leptogenesis, and in that context the neutrino is a Majorana particle but it must be very light, such that neutrinoless double beta decay is unobservable,...

Two models:

H Data comes from background processes only.Background rate uncertain

 \bar{H} Data comes from signal + background processes Background and signal rate uncertain

DBD example
$$P(Data \mid H) = \int P(Data \mid B)P_0(B)dB$$

$$P(Data \mid \overline{H}) = \int P(Data \mid S, B)P_0(S)P_0(B)dBdS$$
ed number of events in bin i

$$n_i$$
 = observed number of events in bin i

$$\lambda_i$$
 = expected number of events in bin i

$$\lambda_{i} = S \int f_{S}(E) dE + B \int f_{B}(E) dE$$

$$\Delta E_{i}$$

$$\Delta E_{i}$$

$$\Delta E_{i}$$

$$\Delta E_{i}$$

Where f_S and f_B are the normalized signal and background probability densities as functions of energy.

then

$$P(Data \mid B) = \prod_{i=1}^{N} \frac{\lambda_{i}(0,B)^{n_{i}}}{n_{i}!} e^{-\lambda_{i}(0,B)}$$

$$P(Data \mid S,B) = \prod_{i=1}^{N} \frac{\lambda_{i}(S,B)^{n_{i}}}{n_{i}!} e^{-\lambda_{i}(S,B)}$$

To determine parameter values or set limits, we need

$$P(S,B \mid Data) = \frac{P(Data \mid S,B)P_0(S)P_0(B)}{\int P(Data \mid S,B)P_0(S)P_0(B)dSdB}$$

and then marginalize

$$P(S \mid Data) = \int P(S,B \mid Data)dB$$

e.g., 90% probability upper limit, S_{90} from solving

$$\int_{0}^{S_{90}} P(S \mid Data) dS = 0.90$$

GERDA example

Assumptions for GERDA:

$$P_0(H) = P_0(\overline{H}) = 1/2$$

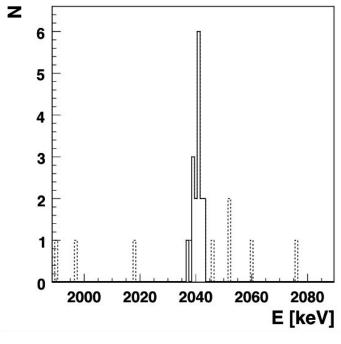
$$P_0(S) = \frac{1}{S_{\text{max}}} \quad 0 \le S \le S_{\text{max}} \quad P_0(S) = 0 \text{ otherwise}$$

$$P_0(B) = \frac{e^{-\frac{(B-\mu_B)^2}{2\sigma_B^2}}}{\int_0^\infty e^{-\frac{(B-\mu_B)^2}{2\sigma_B^2}} dB} \quad B \ge 0; \quad P_0(B) = 0 \quad B < 0 \quad \text{flat shape}$$

$$\rm S_{max}$$
 was calculated assuming $\rm T_{1/2}{=}0.5~10^{25}~yr$ $\rm \mu_B{=}B_0,~~\sigma_B{=}B_0{/}2$

100 keV window analyzed. B₀ total background in this window.

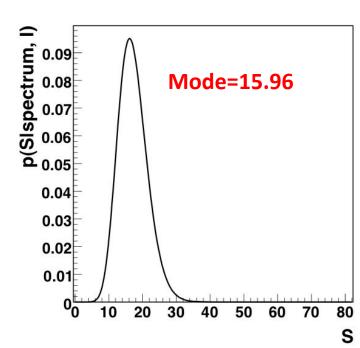


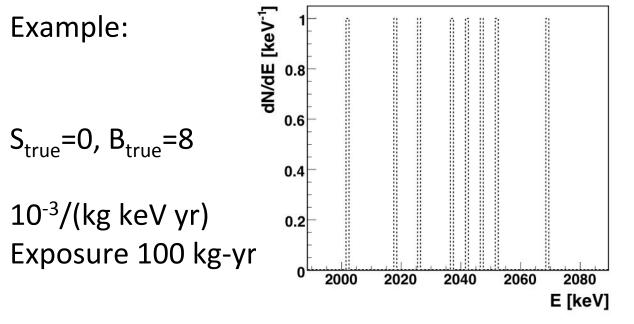


$$P(H \mid Data) = 2.2 \cdot 10^{-12}$$

R bachground mh

Discovery!





$$P(H \mid Data) = 0.93$$

$$P(H \mid D = 0.07)$$

Upper limit on number of signal events:

$$S_{90} = 3.99$$

No discovery – belief in background only enhanced

(started 50/50)

