

Implementing LQCD applications using SciDAC and Chroma

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27. November 2006, LAP06, Zeuthen



Agenda

Introduction

Communication

QLA

QDP++

QIO

Chroma

Conclusions and References

Agenda

Introduction

Communication

QLA

QDP++

QIO

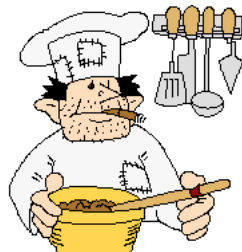
Chroma

Conclusions and References

Disclaimer and Credits

Disclaimer: **Not the speciality of the cook!**

Credits: Talk about work done by others
Here: USQCD collaboration
<http://www.usqcd.org>



Introduction

Challenges for efficient implementations

- ▶ Complex algorithms (see last talks)
- ▶ Complex computer architectures (see next talks)

Nice to face challenges, but: **Time-to-solution may become large!**

Could community efforts help?

- ▶ Interfaces to hide algorithmic details
- ▶ Interfaces to hide machine details (maschine abstraction)

USQCD started to go down this road. **What did they achieve?**

Overview on SciDAC Software

SciDAC software modules (level 1)

- ▶ QCD Message Passing (QMP)
- ▶ QCD Linear Algebra (QLA)

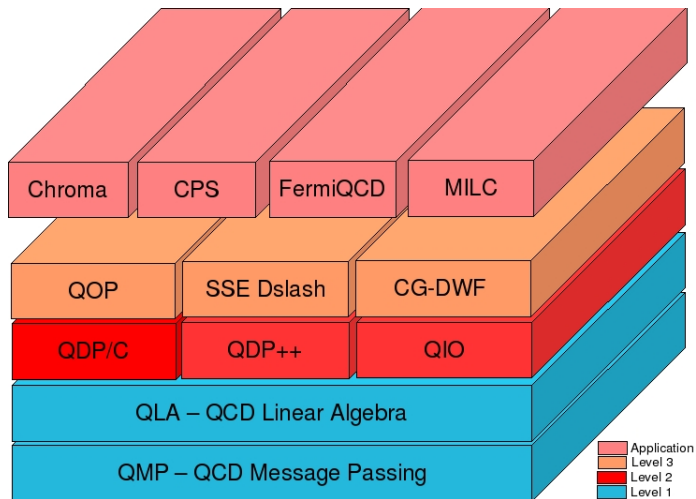
SciDAC software modules (level 2)

- ▶ QCD Data Parallel (QDP)
- ▶ QCD Input Output (QIO)

Applications

- ▶ e.g. Chroma

Overview on SciDAC Software (2)



Agenda

Introduction

Communication

QLA

QDP++

QIO

Chroma

Conclusions and References

MPI: Advantages and Drawbacks

► Advantages:

- Mature and well understood
- Widely supported formal standard (since 1992)
- User interface: simple and efficient
- Available on (almost) all platforms

► Disadvantages:

- Many features are not required for LQCD applications
- These features may nevertheless affect on performance
- Possibly difficult to use all hardware features
 - Architectures may be suitable (BG/L) or less suitable (apeNEXT, QCDOC) for MPI

Design Goals

- ▶ Provide **lean, standard** communication layer **optimized for LQCD**
 - ▶ Simple communication patterns in LQCD
 - ▶ **Homogenous** communication patterns
 - ▶ **Nearest neighbour** communication
 - ▶ **Torus** topology
 - ▶ Collective operations: globus sum, broadcast
 - ▶ Any-to-any communication not required
- ▶ Suitable for very **efficient implementation** on a **variety of interconnects**
- ▶ **Performance requirements:**
 - ▶ Overlap of communication and computation
 - ▶ Multiple outstanding communication requests
 - ▶ Request for send in several directions in one call (QCDOC optimisation)

QMP Functionality

- ▶ Initialisation and finalisation, e.g.
 - ▶ `QMP_init_msg_passing`, `QMP_finalize_msg_passing`
- ▶ Discover machine topology, e.g.
 - ▶ `QMP_get_node_number`
 - ▶ `QMP_get_allocated_number_of_dimensions`
 - ▶ `QMP_get_allocated_dimensions`
- ▶ Logical machine
 - ▶ View of the allocated machine
 - ▶ `QMP_declare_logical_topology(const int *d, int n)`
 - ▶ `QMP_layout_grid` (dynamic layout)
- ▶ Communication
 - ▶ `QMP_declare_send_to`, ...
 - ▶ `QMP_declare_send_relative`, ...
 - ▶ `QMP_declare_multiple`
 - ▶ `QMP_start`, `QMP_is_complete`, `QMP_wait`
- ▶ Collective operations

Example (1)

```
1 int main(int argc , char* argv[])
  {
3     ...
    QMP_status_t status;
5     QMP_thread_level_t req , prv;

7     /* Initialise */
    req = QMP_THREAD_SINGLE;
9     status = QMP_init_msg_passing(&argc , &argv , req , &prv);

11    ...

13    /* Cleanup */
    QMP_finalize_msg_passing();

15    return 0;
17 }
```

Example (2)

```
1 #define NDIM 4

3 int main(int argc, char* argv[])
{
5     int l[NDIM] = {4, 4, 4, 8};
    QMP_status_t status;

7     ...

9     status = QMP_layout_grid(l, NDIM);

11    print_topology();

13    ...
}
```

Example (3)

```
1 int main(int argc, char* argv[])
2 {
3     int l[NDIM] = {4, 4, 4, 8};
4     int g[NDIM] = {2, 1, 1, 1};
5     QMP_status_t status;
6
7     ...
8
9     status = QMP_declare_logical_topology(g, NDIM);
10    status = QMP_layout_grid(l, NDIM);
11
12    print_topology();
13
14    ...
15 }
```

Example (4)

```
1 #define NDIM 4

3 void print_topology(void) {
    int nnodes, idim;

5     if (QMP_get_node_number() != 0) return;

7     nnodes = QMP_get_number_of_nodes();
    printf("#nodes  = %d\n", nnodes);
    {
11         const int *s = QMP_get_subgrid_dimensions();
        printf("subgrid =");
13         for (idim = 0; idim < NDIM; idim++)
            printf(" %d", s[idim]);
15         printf("\n");
    }
17 }
```

QMP

Review

- ▶ Restriction to suitable subset of MPI
- ▶ Performance issues due to requirements wrt machine architecture

Agenda

Introduction

Communication

QLA

QDP++

QIO

Chroma

Conclusions and References

Introduction

- ▶ Linear algebra operations on single node

- ▶ C binding

- ▶ Data objects:

- ▶ Primitives:

QLA_Real	R	real
QLA_Complex	C	complex
QLA_ColorMatrix	M	$N_c \times N_c$ complex matrix
QLA_DiracFermion	D	four-spin, N_c complex matrix

...

- ▶ Array of primitives

Example: Left multiplication by colour matrix

$$\phi_{\mu,i}^a = U_{\nu,i}^{a,b} \psi_{\mu,i}^b$$

```

1 #define N 1000
#define xmalloc(t, n) (t *) malloc(sizeof(t) * n)
3
int main() {
5     QLA_ColorMatrix    *u;
    QLA_DiracFermion    *psi, *phi;
7
    u    = xmalloc(QLA_ColorMatrix, N);
9     psi = xmalloc(QLA_DiracFermion, N);
    phi = xmalloc(QLA_DiracFermion, N);
11
    QLA_D_veq_M_times_D(phi, u, psi, N);
13 }

```

Example: Left multiplication by colour matrix (2)

► Variations: `QLA_T_eqop_M_times_T()`

T =	V	(1-spin, N_c colour spinor)
	H	(2-spin, N_c colour spinor)
	D	(4-spin, N_c colour spinor)
	M	($N_c \times N_c$ complex matrix)
	P	($4N_c \times 4N_c$ complex matrix)
eqop =	[v]eq	(=)
	[v]peq	(+=)
	[v]meq	(-=)
	[v]eqm	(=-)

► Adjoint colour matrix: `QLA_T_eqop_Ma_times_T()`

Example: Reductions

$$r = \sum |\phi|^2$$

```

1 #define N 1000
#define xmalloc(t, n) (t *) malloc(sizeof(t) * n)
3
int main() {
5     QLA_Real          r;
    QLA_DiracFermion    *psi;
7
    psi = xmalloc(QLA_DiracFermion, N);
9
    QLA_r_veq_norm2_D(&r, psi, N);
11 }

```

Other Functions

- ▶ Functions with complex arguments (e.g. $\sqrt{z}$)
- ▶ Random numbers (uniform and Gaussian distribution)
- ▶ Spin/colour traces
- ▶ Multiplication with gamma matrices
- ▶ Ternary operations, e.g.
 - ▶ Addition with scalar multiplication $a \cdot b + c$
- ▶ ...

Review

- ▶ Quite exhaustive set of operations
- ▶ Various routines optimised for SSE, SSE2, PPC 440, PPC 440d

Agenda

Introduction

Communication

QLA

QDP++

QIO

Chroma

Conclusions and References

Introduction

- ▶ Data-parallel programming environment
- ▶ Uses QMP for communication
- ▶ C++ binding (alternative: QDP/C)

Data Objects

► Concept: Object types catagories

- Basic machine types (e.g. int, float, double)
- Real world types (e.g. complex)
- “Primitive types” (e.g. scalar, vector, matrix)
- Grid type

Construct object types using C++ templates

```
typedef OLattice<
    PScalar<PColorMatrix< RComplex<float>, Nc>>>
    LatticeColorMatrix
```

- Grid type: OLattice
- Primitive types: PScalar, PColorMatrix
- Real world types: Rcomplex
- Basic machine types: float
- (Constants: Nc)

Data Objects (2)

► Examples for available objects:

`ColorMatrix`

$N_c \times N_c$ complex matrix

`LatticeColorMatrix`

array of colour matrices

`LatticeFermion`

N_s spin N_c colour spinor

Data Layout

► Information relevant for controlling data layout:

- Number of dimensions
- Lattice size
- Number of threads

► Functions to control this:

- `Layout::setLattSize(const multild<int>& size)`
- `Layout::setSMPFlag({true|false})`
- `Layout::setNumProc(n)`

► Get layout dependent information:

- `Layout::sitesOnNode()`
- `Layout::nodeNumber(x)`

Operations (1)

- ▶ Typical operation in QCD applications:

$$\psi_{\alpha i} = U_{ij}(\gamma_0)_{\alpha\beta} \phi_{\beta j}$$

- ▶ Implementation in QDP++:

```

1 LatticeFermion      psi
  LatticeFermion      phi
3 LatticeColorMatrix  u

5 psi = u * Gamma(1) * phi

```

- ▶ Operation may involve Hermitian conjugate, e.g. $U_{ij}^\dagger$:

```

1 psi = adj(u) * Gamma(1) * phi

```

Operations (2)

- ▶ Shift operation: move data to neighbouring lattice site
 - ▶ May include communication
- ▶ Example: calculation of staples:

$$U_\nu(x + \mu) * U_\mu(x + n\nu)^\dagger * U_\nu(x)^\dagger$$

- ▶ Implementation in QDP++:

```

1 #define NDIM 4

3 int                                mu, nu;
  multi1d<LatticeColorMatrix>      u(NDIM);
5 LatticeColorMatrix                s;

7 s = shift(u[nu], FORWARD, mu) *
    adj(shift(u[mu], FORWARD, nu)) *
9    adj(u[nu]);

```

Example

```
1 int main(int argc, char *argv[]) {  
    QDP_initialize(&argc, &argv);  
3  
    const int xl[] = {4,4,4,4};  
5    QDP::multi1d<int> l(QDP::Nd);  
    l = xl;  
7    QDP::Layout::setLattSize(l);  
    QDP::Layout::create();  
9  
    QDP::multi1d<LatticeColorMatrix> u(Nd);  
11  
    ...  
13  
    QDP::QDP_finalize();  
15  
    return 0;  
17 }
```

Agenda

Introduction

Communication

QLA

QDP++

QIO

Chroma

Conclusions and References

Introduction

- ▶ Input/Output Applications Programmer Interface
- ▶ Different file formats supported:
 - ▶ “Single file format”
 - ▶ I/O through single master node
 - ▶ “Partition file format”
 - ▶ I/O through a set of I/O nodes
 - ▶ Serve all nodes of corresponding partition
 - ▶ “Multi file format”
 - ▶ Write of temporary files to local disks
- ▶ QMP is used for data transport
- ▶ Support for structured file format: **LIME**

LIME

- ▶ LIME = **Lattice QCD Interchange Message Encapsulation**
- ▶ LIME file consists of one or more **messages**
- ▶ Each message consists of one or more **records**
- ▶ A record contains ASCII or binary data
- ▶ 144-byte header:
 - ▶ control word (8 byte)
 - ▶ record length (8 byte)
 - ▶ type string (128 byte)

Example

```
1 #include <stdio.h>
  #include "lime.h"
3
  main(int argc , char* argv[])
5 {
    FILE          *fp;
    LimeReader     *r;
    unsigned char *buf;
7
    fp = fopen(argv[1], "r");
11    r = limeCreateReader(fp);
13
    limeReaderNextRecord(r);
    printf("First header = %s\n", limeReaderType(r));
15 }
```

LIME Interface Functionality

- ▶ Read operations (selection)
 - ▶ Create reader: `limeCreateReader`, `limeDestroyReader`
 - ▶ Header accessors: `limeReaderType`, `limeReaderBytes`
 - ▶ Pay-load read: `limeReaderReadData`
 - ▶ Skip to next record: `limeReaderNextRecord`
 - ▶ Seek within record: `limeReaderSeek`
- ▶ Write operations (selection)
 - ▶ Create writer: `limeCreateWriter`, `limeDestroyWriter`
 - ▶ Write operation: `limeWriteRecordHeader`,
`limeWriteRecordData`, `limeWriterCloseRecord`
- ▶ Header creation

Review

- ▶ Efficient read operations possible
- ▶ Support for >2 GBytes file size
- ▶ Standard adopted by ILDG

Agenda

Introduction

Communication

QLA

QDP++

QIO

Chroma

Conclusions and References

Introduction

- ▶ Application level software package
- ▶ Written in C++
- ▶ Dependencies: QDP++, QMP, libXML
- ▶ Optimised for various platforms (PC-Clusters, QCDOC, BGL)
- ▶ Applications
 - ▶ Pure gauge heatbath
 - ▶ HMC
 - ▶ Measurement

Chroma Modules

- ▶ **I/O module:**
 - ▶ Support for different gauge configuration formats (incl. ILDG)
- ▶ **Measurements module:**
 - ▶ Generation of colour sources
 - ▶ Propagator smearing
 - ▶ Calculation of correlation functions
- ▶ **Inverters:** CG, BiCGStab, SUMR, MINRES, ...
- ▶ **Eigensystems**
- ▶ **Various fermion and gauge actions**

Step 1: Generate SU(3) Configuration

- ▶ Create driver/parameter XML file, say `su3-in.xml`
- ▶ Execute application:
`purgaug -i su3-in.xml -o su3-out.xml`

XML Driver File (1)

Start with cold configuration:

```
1 <?xml version=" 1.0 " ?>
  <purgaug>
3   <Cfg>
      <cfg_type>UNIT</ cfg_type>
5      <cfg_file></ cfg_file>
    </ Cfg>
7    ...
  </purgaug>
```


XML Driver File (2)

Define update parameters:

```
<MCControl>
2  <RNG> ... </RNG>

4  <StartUpdateNum>0</ StartUpdateNum>
    <NWarmUpUpdates>2</ NWarmUpUpdates>
6  <NProductionUpdates>1000</ NProductionUpdates>
    <NUpdatesThisRun>10</ NUpdatesThisRun>
8  <SaveInterval>10</ SaveInterval>
    <SavePrefix>result</ SavePrefix>
10 ...
</MCControl>
```

XML Driver File (3)

Define physical parameters

```
1 <HBltr>
  <GaugeAction>
3    <Name>WILSON_GAUGEACT</Name>
    <beta>6.0</beta>
5    <GaugeState>
      <Name>SIMPLE_GAUGE_STATE</Name>
7      <GaugeBC>
        <Name>PERIODIC_GAUGEBC</Name>
9      </GaugeBC>
    </GaugeState>
11  </GaugeAction>
    ...
13  <nrow>4 4 4 8</nrow>
</HBltr>
```

XML Driver File (4)

Define measurements

```
<InlineMeasurements>
2  <elem>
    <Name>POLYAKOV_LOOP</Name>
    <Frequency>1</Frequency>
    <Param>
6      <version>2</version>
    </Param>
8    <NamedObject>
        <gauge_id>default_gauge_field</gauge_id>
10    </NamedObject>
    </elem>
12</InlineMeasurements>
```

Step 2: Measurement of Hadron Observables

- ▶ Typical measurement application tasks:
 - ▶ Read a gauge configuration
 - ▶ Generate a colour source
 - ▶ Compute quark propagator (“invert” fermion matrix)
 - ▶ Calculate correlation functions
- ▶ Similar procedure as before
 - ▶ Create driver/parameter file, say `hadron-in.xml`
 - ▶ Execute application:

```
chroma -i hadron-in.xml -o hadron-out.xml
```

XML Driver File (1)

Read configuration:

```
<?xml version=" 1.0 " ?>
2 <chroma>
    <Cfg>
4       <cfg_type>SCIDAC</ cfg_type>
       <cfg_file>su3.lime1</ cfg_file>
6    </ Cfg>
    ...
8 </ chroma>
```

XML Driver File (2)

Define tasks:

```
<Param>
  <InlineMeasurements>
    <elem>
      <Name> ... </Name>
      <Frequency> ... </Frequency>
      <Param>
        ...
      </Param>
      <NamedObject>
        <gauge_id>default_gauge_field</gauge_id>
        <source_id>src</source_id>
      </NamedObject>
      ...
    </elem>
  </InlineMeasurements>
</Param>
```

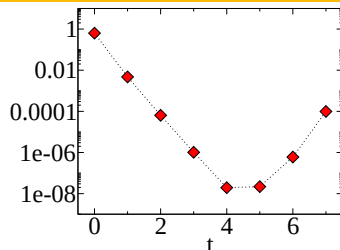
XML Driver File (3)

Calculate propagator:

```
1      <elem>
2          <Name>PROPAGATOR</Name> ...
3          <Param> ...
4              <FermionAction>
5                  <FermAct>WILSON</FermAct>
6                  <Kappa>0.11</Kappa> ...
7              </FermionAction>
8              <InvertParam>...</InvertParam>
9          </Param>
10         <NamedObject>
11             <gauge_id>default_gauge_field</gauge_id>
12             <source_id>src</source_id>
13             <prop_id>prop</prop_id>
14         </NamedObject>
15     </elem>
```

Results

Nucleon correlator:



Review

- ▶ Some very nice concepts
- ▶ Toolbox for quick experiments
- ▶ Complex software, difficult to adapt to own needs
- ▶ Compiler dependencies
- ▶ Lack of documentation
- ▶ Tutorial: <http://www.ph.ed.ac.uk/~bj/HackLatt06>

Agenda

Introduction

Communication

QLA

QDP++

QIO

Chroma

Conclusions and References

Conclusions

► **Advantages of community codes:**

- Avoid re-implementation of standard tasks
- Share porting and optimisation efforts
 - Highly optimised assembly code
- Common lower level routines and data formats
 - Simpler to share code and data

► **Disadvantages of community codes:**

- A lot of effort required to setup such an infrastructure
- Some efforts may be needed to obtain good performance
 - Human resources vs. machine resources

► **SciDAC example:**

- Very useful software infrastructure → Basis for applications software of most US-collaborations
- Successful efforts to keep software
 - portable
 - (relatively) easy to install
- Application level software more difficult to re-use

References

- ▶ Software installed in
`/afs/afh.de/group/ape/lap06/scidac`
- ▶ Copy of sources in
`/afs/afh.de/group/ape/lap06/scidac/src`
- ▶ For documentation see
 - ▶ <http://www.usqcd.org/usqcd-software>

Hints for Building Software

- ▶ Check file `INSTALL`
- ▶ Execute script `configure`
- ▶ When lucky (typically true): execute `make`
- ▶ Most software modules include examples