

Implementation of a GUI for the MPS

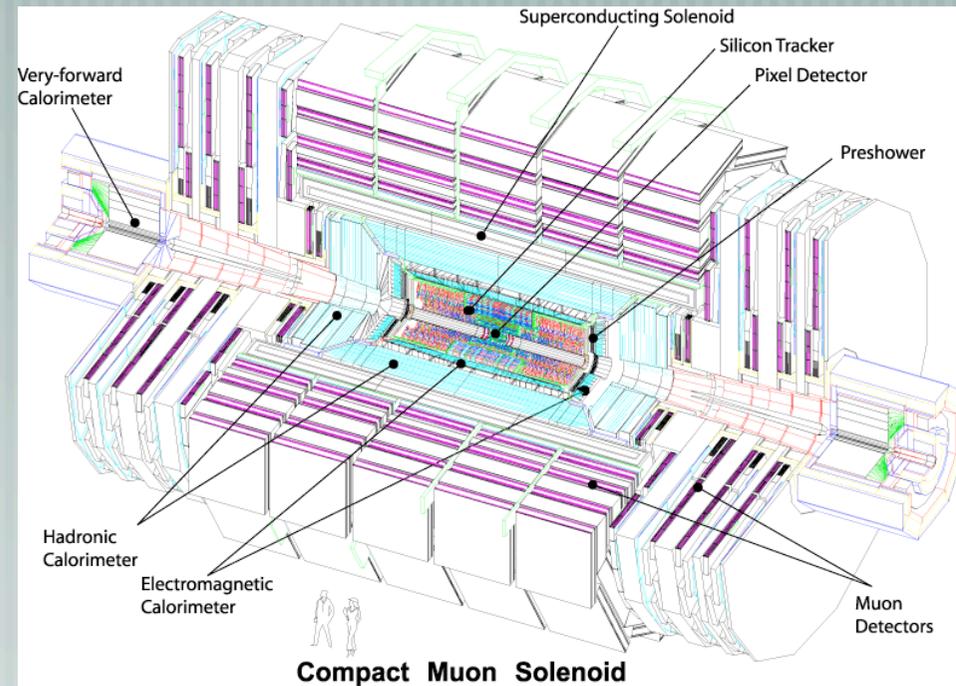
Luis Alberto Sánchez Moreno, DESY Summer 2008

CMS tracker

The tracker is the device responsible for reconstructing the trajectories merging from the pp collisions.

CMS tracker is the largest silicon detector ever built.

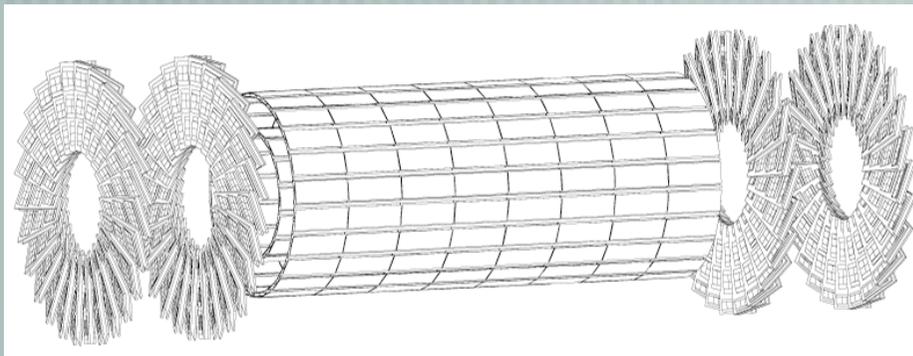
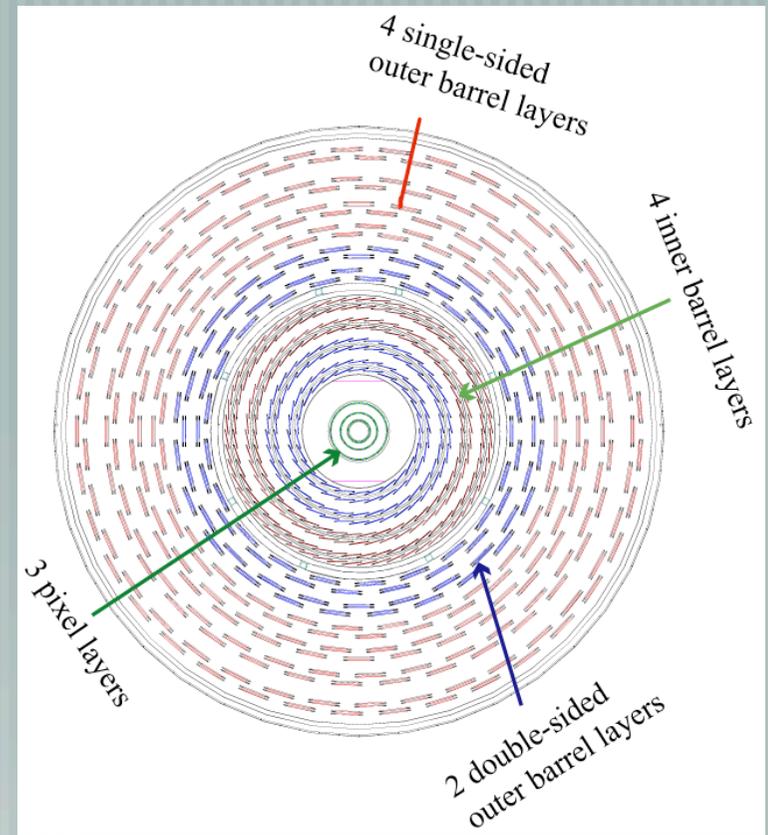
A major requirement has been to achieve at least a 10% accuracy in the determination of the transversal momentum.



Tracker layout

- [The tracker system consists of a series of concentric cylindrical detectors located inside a solenoid magnet that create an axial magnetic field.
- [The detectors form a cylinder by assembling a set of rectangular sub-assemblies with the right orientation.
- [The layout comprise 25,000 silicon sensors having a composite surface of 210 m^2 . The diameter is 2.4 m and the length is 5.4 m.

Layout for the silicon strip detector which is composed by several sub-detectors, namely the tracker inner barrel, tracker outer barrel, tracker inner disks and tracker endcaps.



The pixel detector is composed by two barrel layers, it is located surrounding the immediate vicinity of the interaction region.

Why a silicon detector?

- [Gas detectors are intrinsically limited in position reconstruction due to diffusion.
- [Heavy flavor hadrons will be produced in QCD processes in LHC. High resolution required.
- [This can be achieved by a silicon detector.

Tracker must be aligned!

— [We need to know with high precision the position of every single element of the tracker.

— [This is impossible to achieve at this level of precision by mechanical (or optical) means.

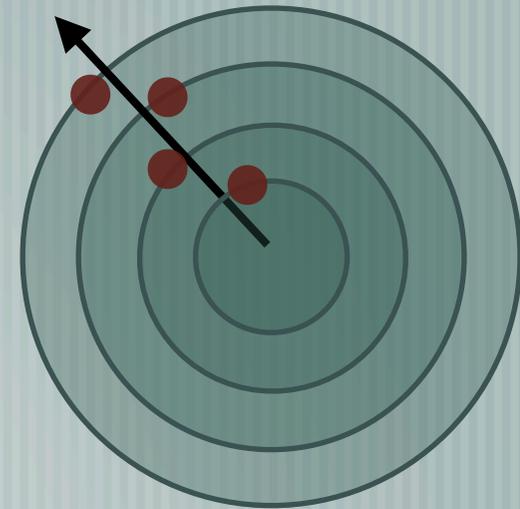
— [Track based alignment has been used successfully in the past.

Track based alignment

Track based alignment is based on the chi squared minimization principle of residuals.

For CMS this is a complicated issue as it implies around $O(100,000)$ parameters.

In the CMS tracker one usual track consists of 20 measurements, a helix track can be determined from only five parameters .



Algorithms

- [The first one is the Hits and Impact method which minimizes a chi squared function constructed from the track hit-residuals on the sensor, it is an iterative and computationally light method.
- [The Kalman filter algorithm is another iterative method that avoids large matrix inversion and can use prior information, in this method the speed of convergence depends on the layer.

The Millepede algorithm

— [Millepede is a linear least-squares algorithm.

— [Designed for certain problems where parameters can be separated into global and local.

Data sample sources

— [High p_T muons from W,Z decays.

— [Cosmic muons.

— [Beam halo muons.

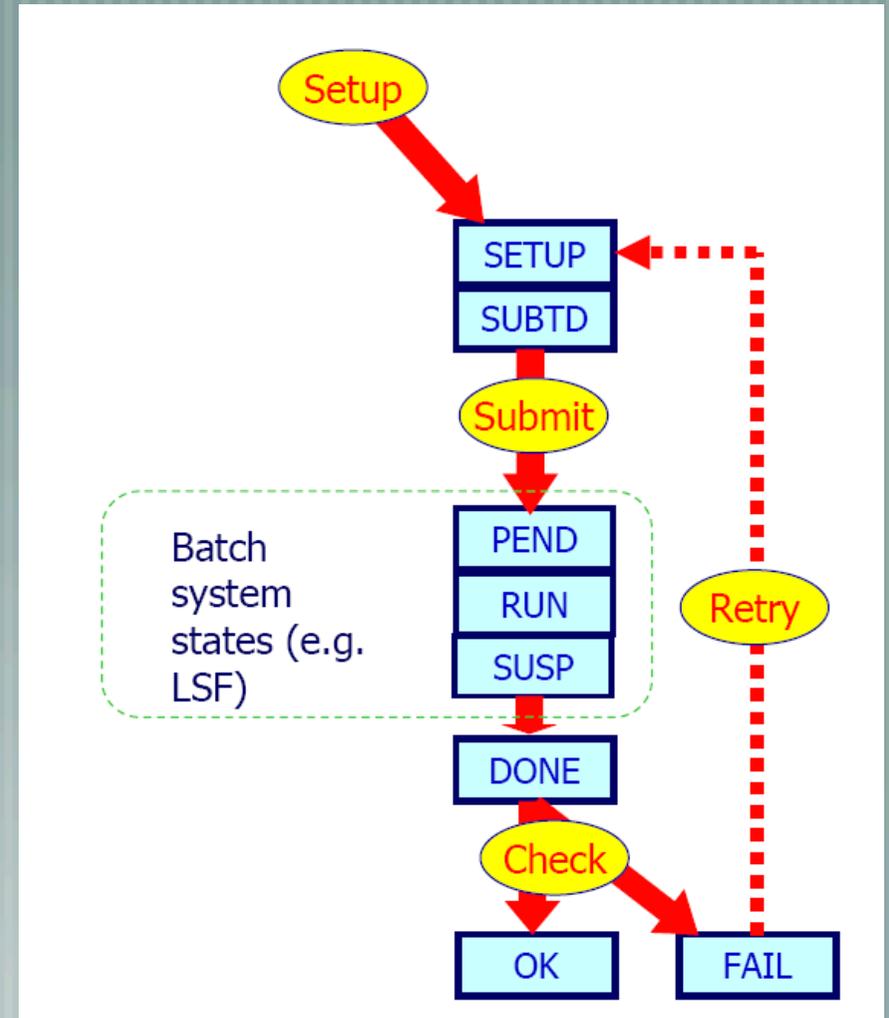
— [Muons from J/Psi and b hadron decays.

— [Isolated tracks from QCD events.

Millipede Production System

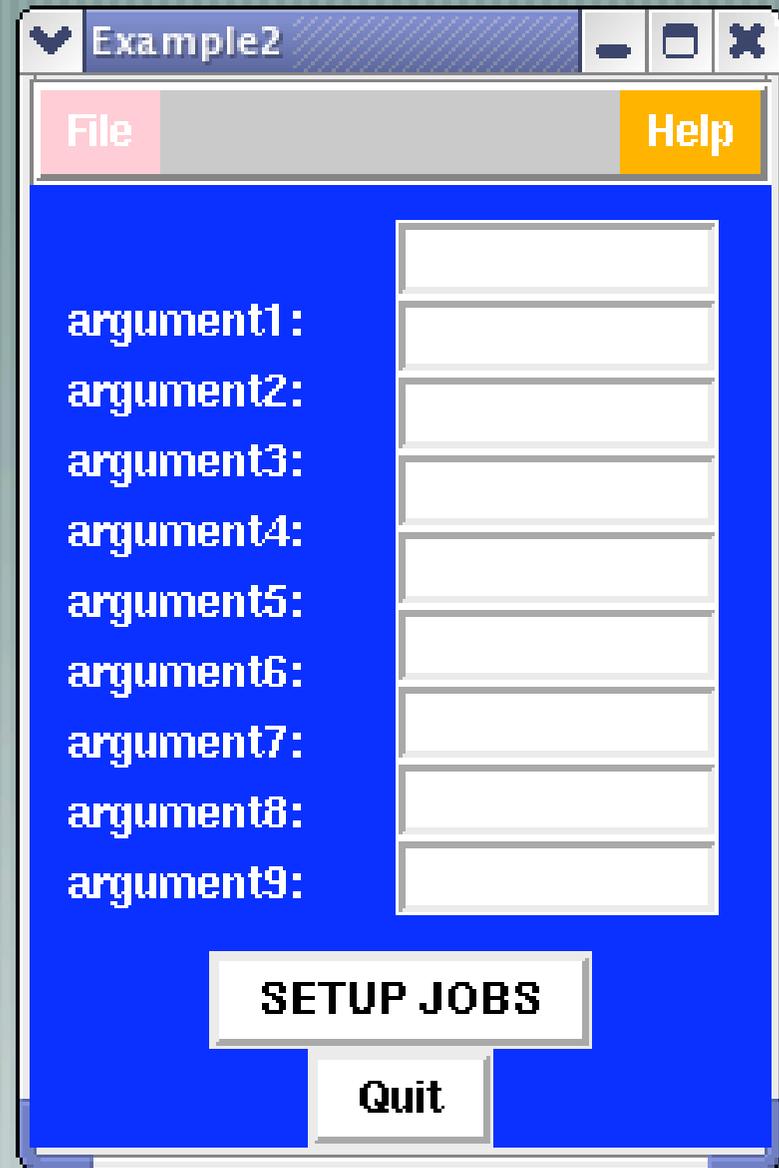
- [The Millipede production system (MPS) is a set of Perl scripts.
- [It can be used to run a large number of Mille jobs, to fetch the output.
- [Output can be feed it into the pede program.

MPS Workflow



GUI Development

First GUI implement for
`mps_setup`.



GUI Development

GUI skeleton produced by ZooZ

The screenshot shows a window titled "Project 1" with a subtitle "Millipede production environment GUI". The window contains several input fields and buttons:

- Path:** A text input field followed by a "Browse" button.
- Path to .cfg file:** A text input field followed by a "Browse" button.
- Path to data:** A text input field followed by a "Browse" button.
- Path to pedeScript:** A text input field followed by a "Browse" button.
- Path to castor directory:** A text input field.
- Jobname for batch system:** A text input field.
- Setup a Pede job?:** Two radio buttons labeled "Yes" and "No".
- Number of jobs:** A text input field with a small arrow on the right.
- Batch system queue/class:** A text input field with a small arrow on the right.
- Run:** A large button at the bottom of the form area.

The bottom half of the window is a large, empty rectangular area, likely intended for output or logs.

GUI Development

MPS Setup Input
(configuration files, input
files, castor directory,
system class, number of
jobs.

Millipede production enviroment GUI

Path: Browse yes

Path to .cfg file: Browse yes

Path to data: Browse Number of jobs:

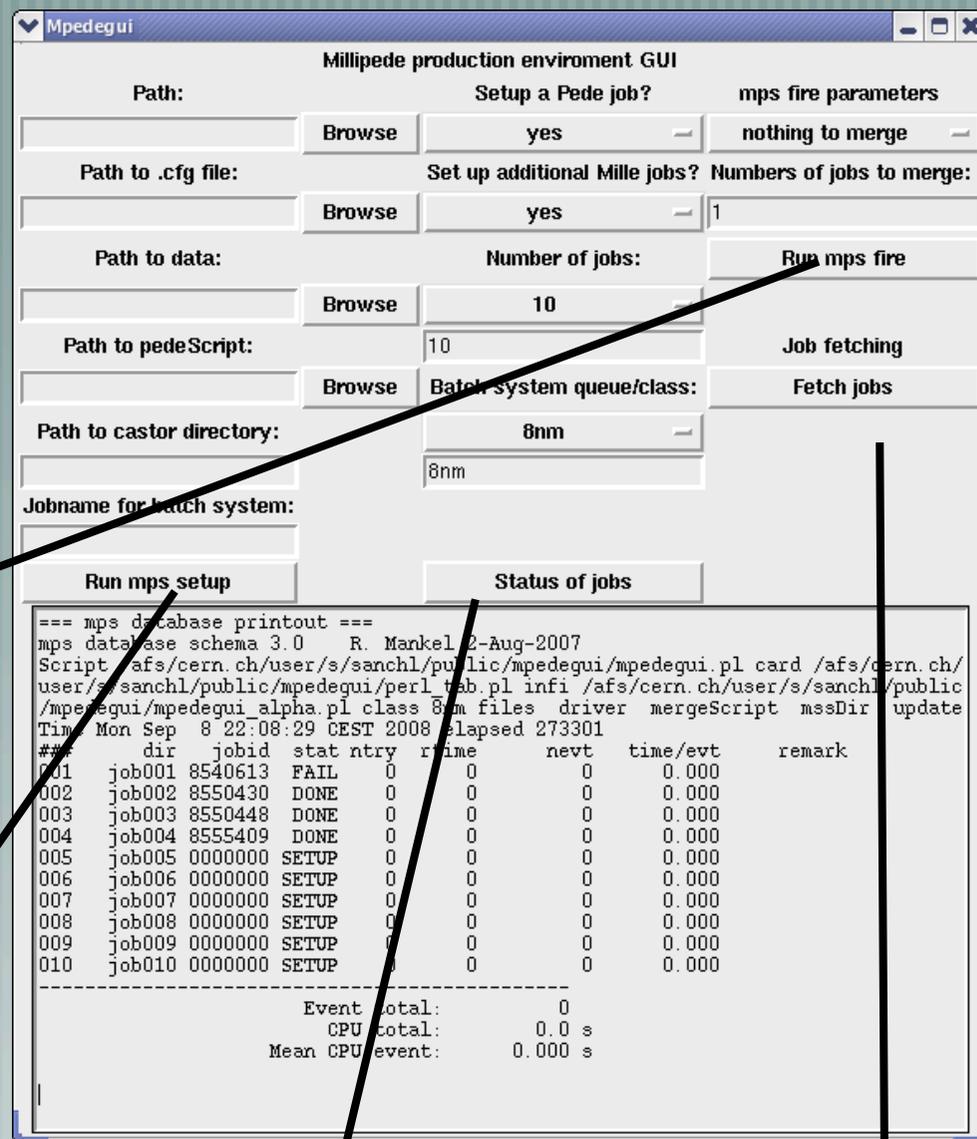
Path to pedeScript: Browse Batch system queue/class:

Path to castor directory:

Jobname for batch system:

```
=== mps database printout ===
mps database schema 3.0 R. Markel 2-Aug-2007
Script /afs/cern.ch/user/s/sanchl/public/mpedegui/mpedegui.pl card /afs/cern.ch/
user/s/sanchl/public/mpedegui/perl_tab.pl infi /afs/cern.ch/user/s/sanchl/public
/mpedegui/mpedegui_alpha.pl class 8nm files driver mergeScript mssDir update
Time Mon Sep 8 22:08:29 CEST 2008 elapsed 273301
### dir jobid stat ntry rtime nevt time/evt remark
001 job001 8540613 FAIL 0 0 0 0.000
002 job002 8550430 DONE 0 0 0 0.000
003 job003 8550448 DONE 0 0 0 0.000
004 job004 8555409 DONE 0 0 0 0.000
005 job005 0000000 SETUP 0 0 0 0.000
006 job006 0000000 SETUP 0 0 0 0.000
007 job007 0000000 SETUP 0 0 0 0.000
008 job008 0000000 SETUP 0 0 0 0.000
009 job009 0000000 SETUP 0 0 0 0.000
010 job010 0000000 SETUP 0 0 0 0.000
-----
Event total: 0
CPU total: 0.0 s
Mean CPU/event: 0.000 s
```

GUI development



mps_fire

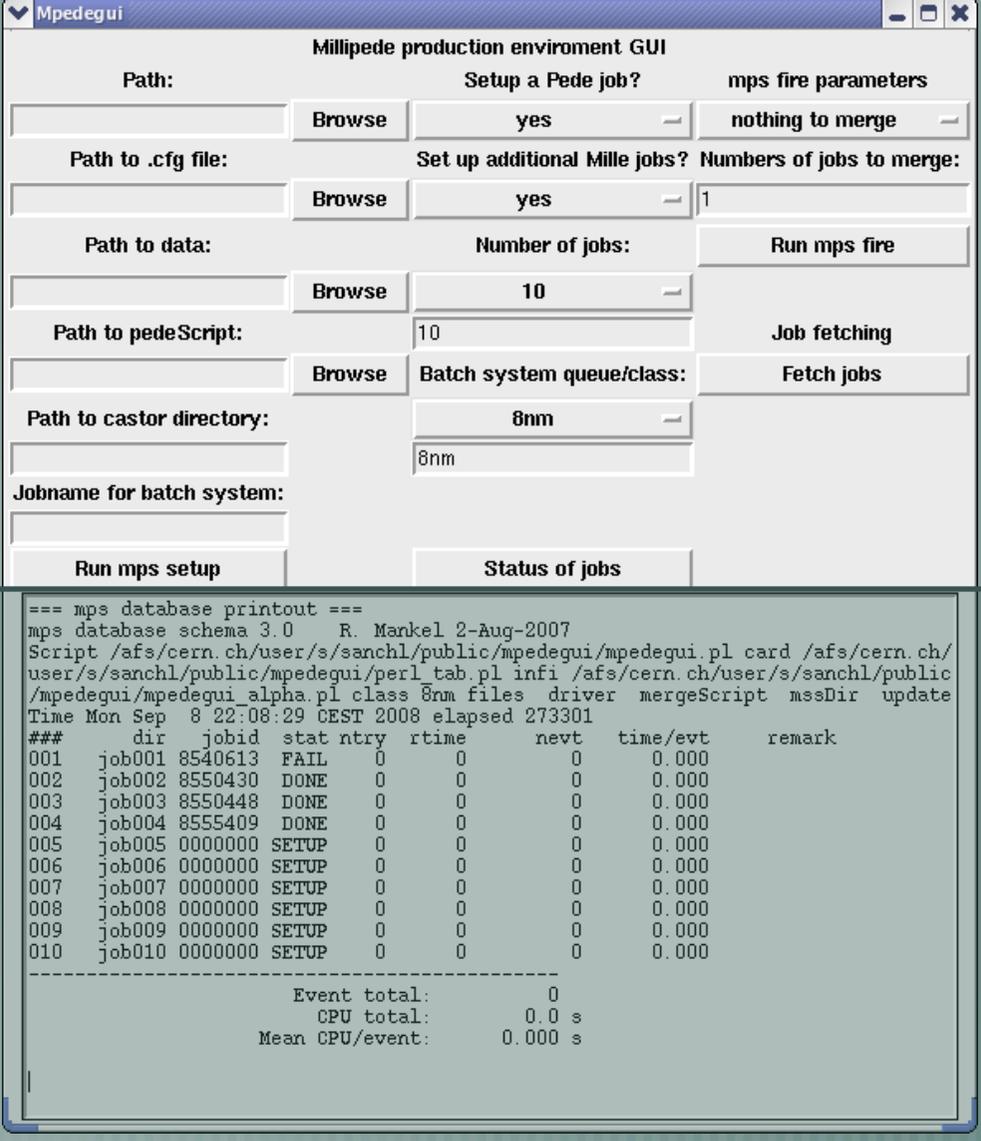
mps_setup

mps_status

mps_fetch

GUI Development

Output read-only window. The output of all commands is displayed to the user as soon as the command is executed.



The screenshot shows a window titled "Mpedegui" with the subtitle "Millipede production environment GUI". The window contains several configuration fields and buttons:

- Path:** A text field with a "Browse" button.
- Setup a Pede job?:** A dropdown menu with "yes" selected.
- mps fire parameters:** A dropdown menu with "nothing to merge" selected.
- Path to .cfg file:** A text field with a "Browse" button.
- Set up additional Mille jobs?:** A dropdown menu with "yes" selected.
- Numbers of jobs to merge:** A text field with "1" entered.
- Path to data:** A text field with a "Browse" button.
- Number of jobs:** A dropdown menu with "10" selected.
- Run mps fire:** A button.
- Path to pedeScript:** A text field with "10" entered.
- Job fetching:** A button.
- Path to castor directory:** A text field with "8nm" entered.
- Batch system queue/class:** A dropdown menu with "8nm" selected.
- Fetch jobs:** A button.
- Jobname for batch system:** A text field.
- Run mps setup:** A button.
- Status of jobs:** A button.

Below the configuration fields is a terminal window displaying the following output:

```
=== mps database printout ===
mps database schema 3.0   R. Mankel 2-Aug-2007
Script /afs/cern.ch/user/s/sanchl/public/mpedegui/mpedegui.pl card /afs/cern.ch/
user/s/sanchl/public/mpedegui/perl_tab.pl infi /afs/cern.ch/user/s/sanchl/public
/mpedegui/mpedegui_alpha.pl class 8nm files driver mergeScript mssDir update
Time Mon Sep  8 22:08:29 CEST 2008 elapsed 273301
###   dir   jobid  stat ntry  rtime   nevt   time/evt   remark
001  job001 8540613  FAIL    0      0      0     0.000
002  job002 8550430  DONE    0      0      0     0.000
003  job003 8550448  DONE    0      0      0     0.000
004  job004 8555409  DONE    0      0      0     0.000
005  job005 0000000  SETUP   0      0      0     0.000
006  job006 0000000  SETUP   0      0      0     0.000
007  job007 0000000  SETUP   0      0      0     0.000
008  job008 0000000  SETUP   0      0      0     0.000
009  job009 0000000  SETUP   0      0      0     0.000
010  job010 0000000  SETUP   0      0      0     0.000
-----
                        Event total:      0
                        CPU total:         0.0 s
                        Mean CPU/event:    0.000 s
```

Conclusions

- [We have a functional GUI for the basic MPS workflow control.
- [Further development required to add the remaining scripts.
- [The GUI still needs some “beautification”.