

# Binary Readout

Detector WS 2016  
Freiburg  
2016-04-07

Marius Preuten

1. Physikalisches Institut B



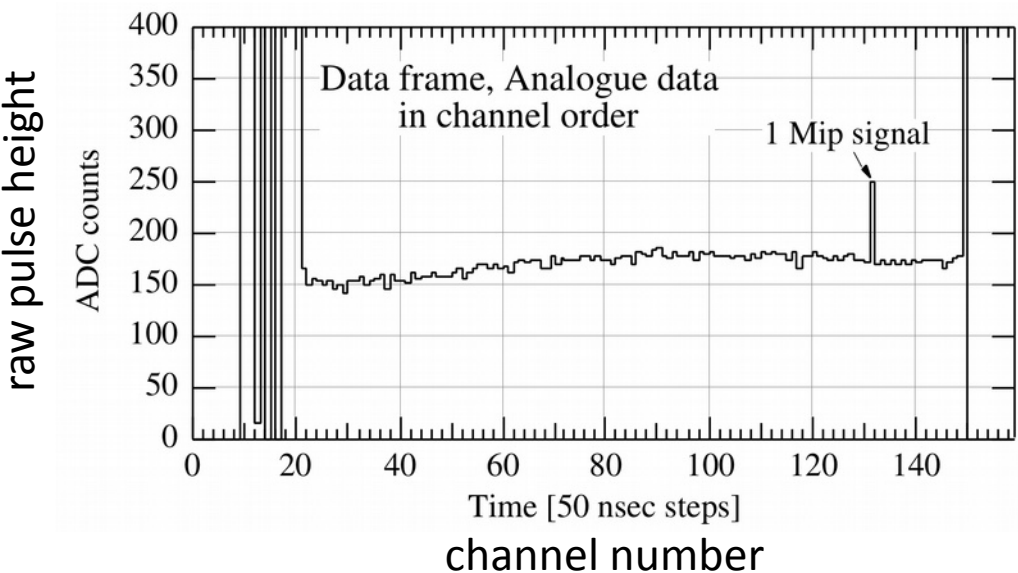
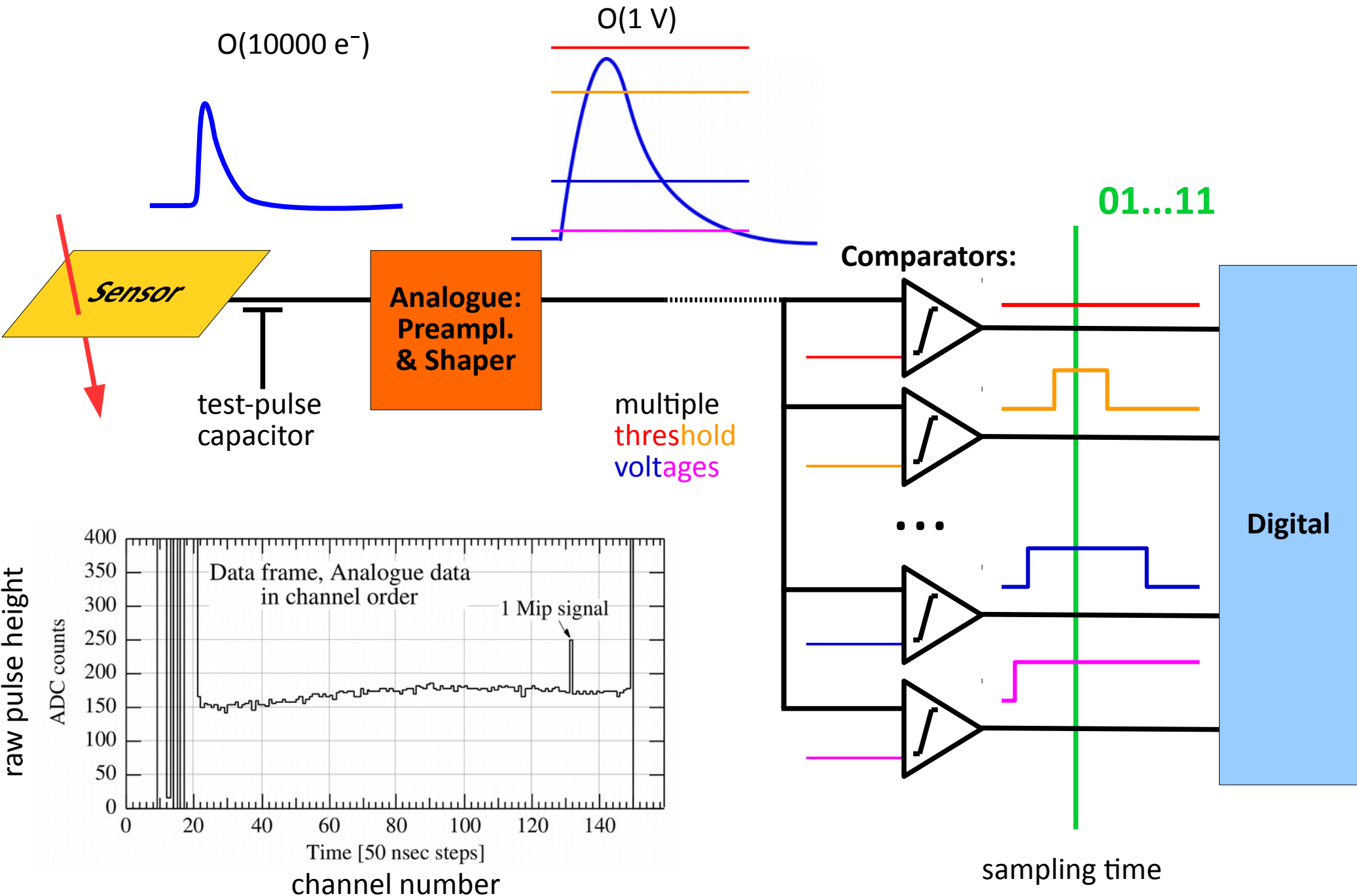
**RWTH**AACHEN  
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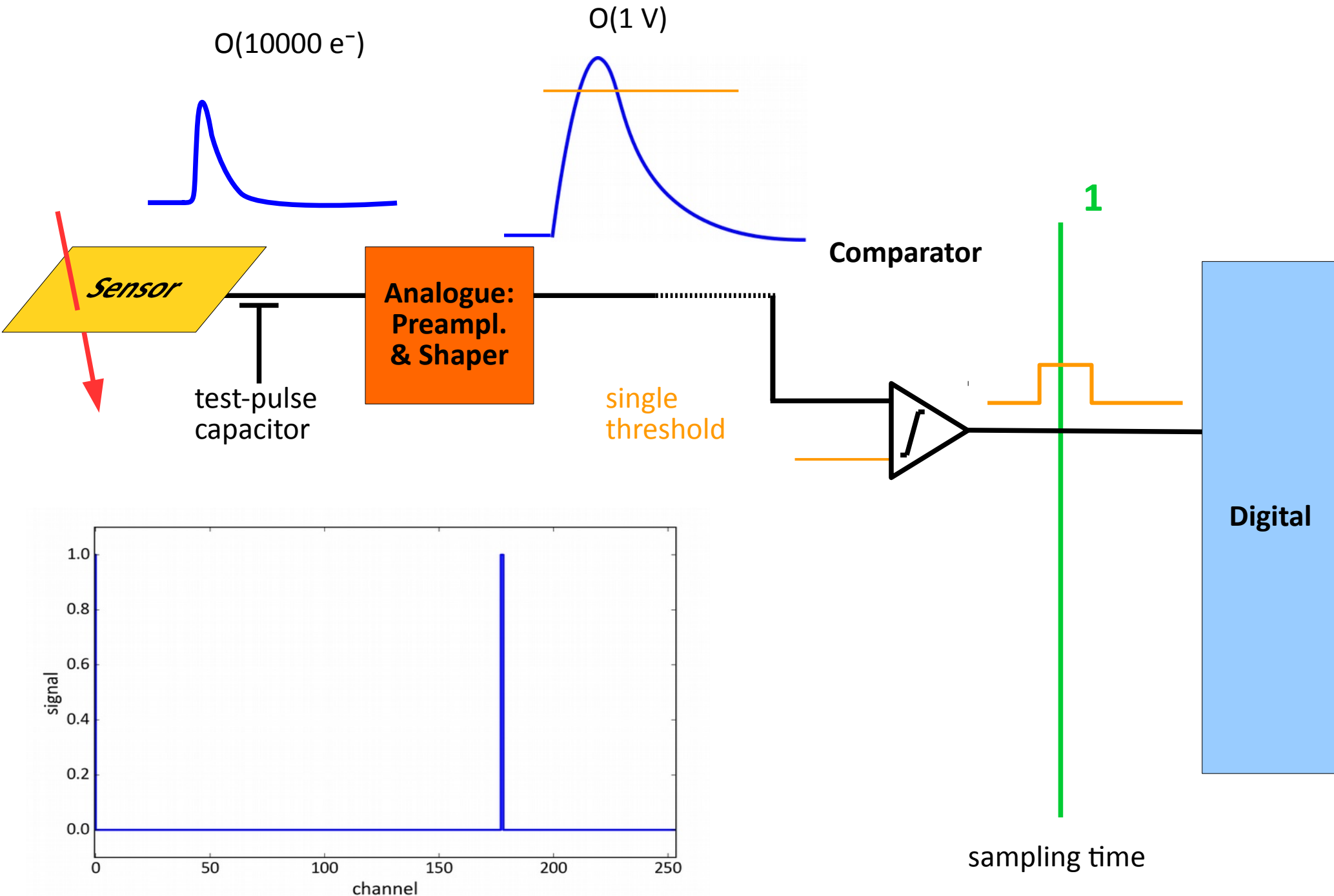
GEFÖRDERT VOM

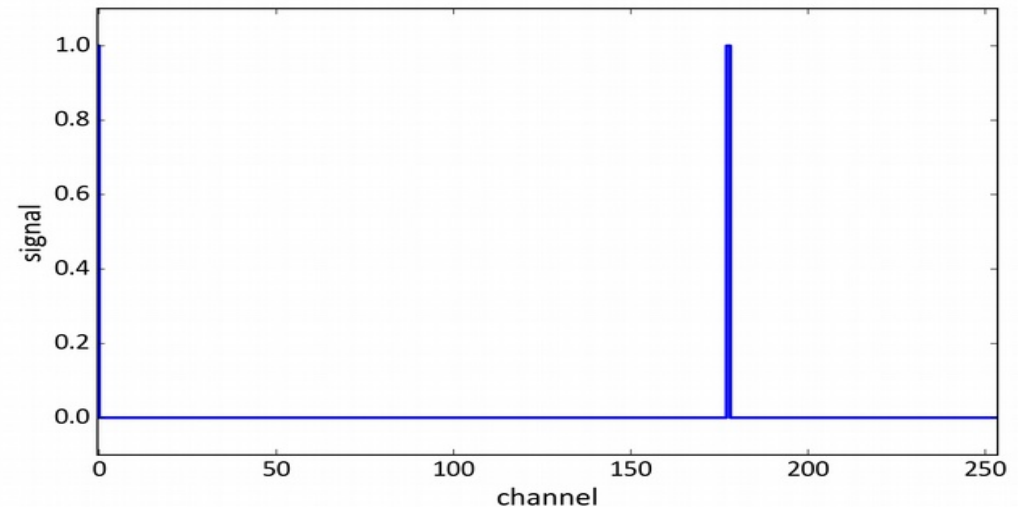
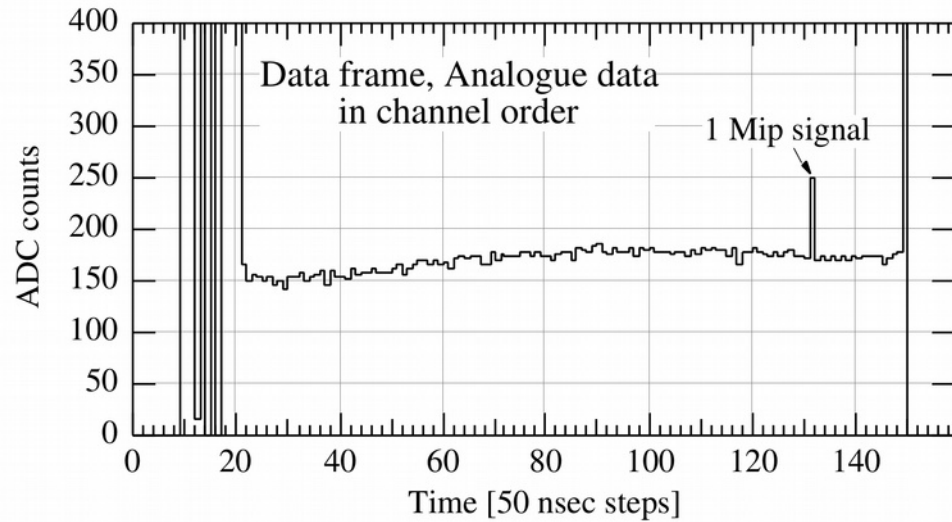


Bundesministerium  
für Bildung  
und Forschung

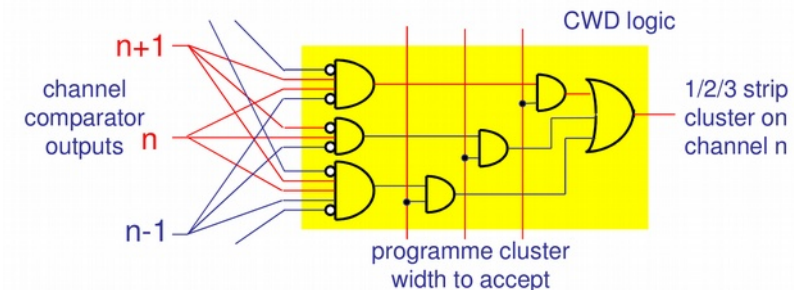
- introduction
  - micro-strip detector readout
  - motivation for binary readout
  
- noise
  - single channel noise
  - common mode noise
  
- signal
  - test-pulses
  - x-rays
  - mips (Sr90 betas)





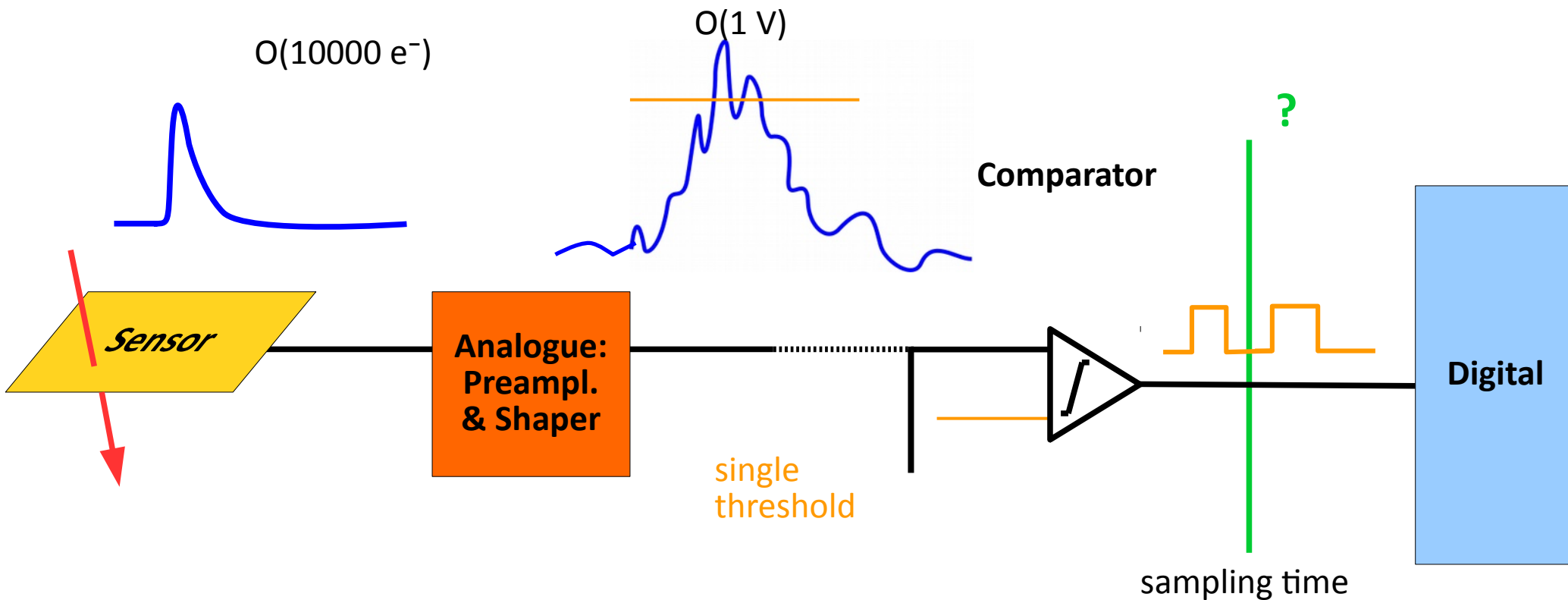


- in binary readout system the only information you can extract is a lower bound on the signal height
- cons: during *normal* operation no measurement of the (common mode) noise, no  $dE/dx$
- pros:
  - more efficient in terms of bandwidth & cache ( $\sim x10$  without any zero suppression)
  - for CMS Phase2 Tracker: incorporate fast binary logic on read-out chip:
    - simple clustering, “stub” building ... with handfull ORs / ANDs / NEGs (fast and power-efficient, *coarse*)
- identify and quantify noise & signals to distinguish them

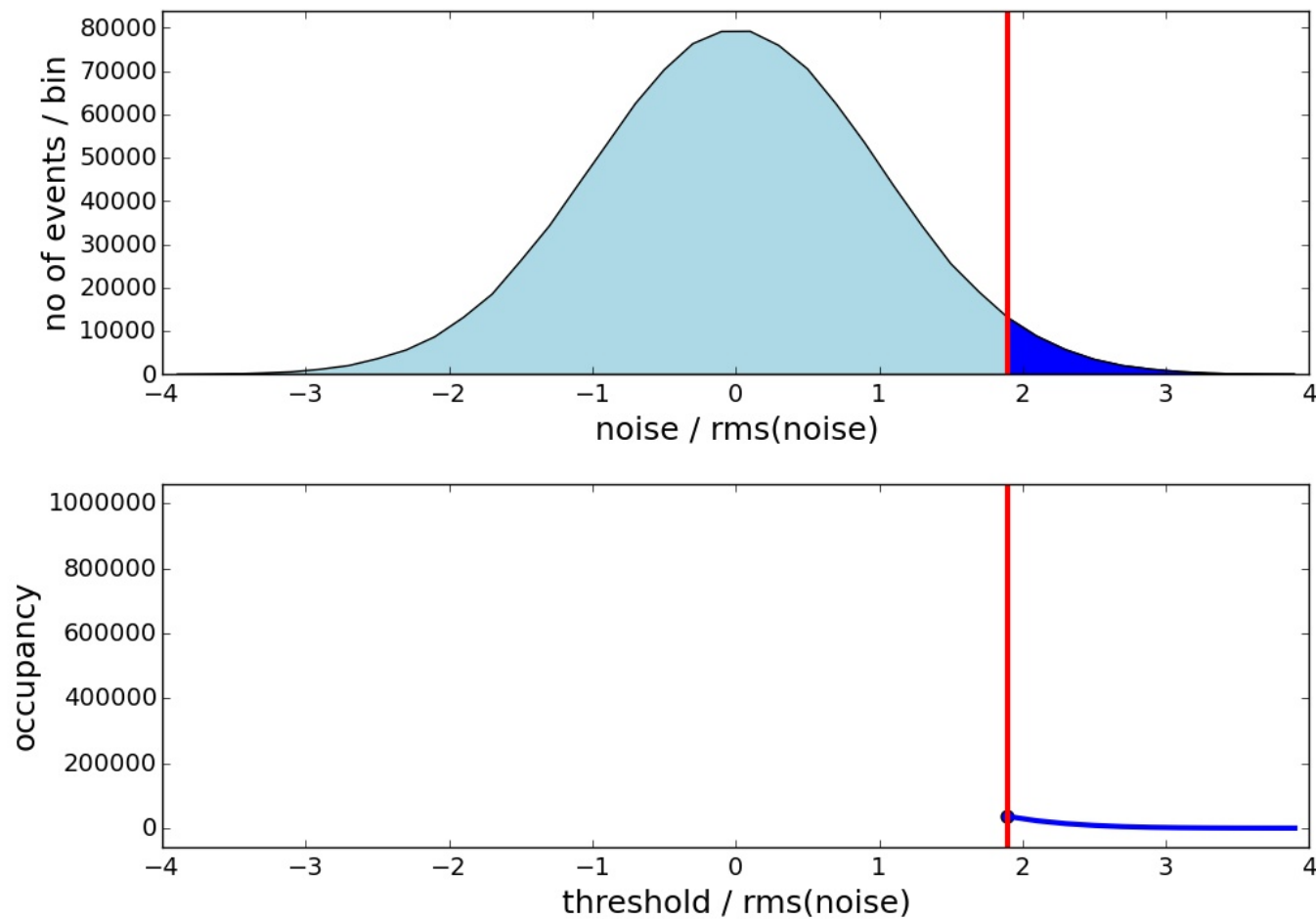


- single channel / intrinsic noise
- common mode noise

- definition: noise is a random fluctuation in an electrical signal

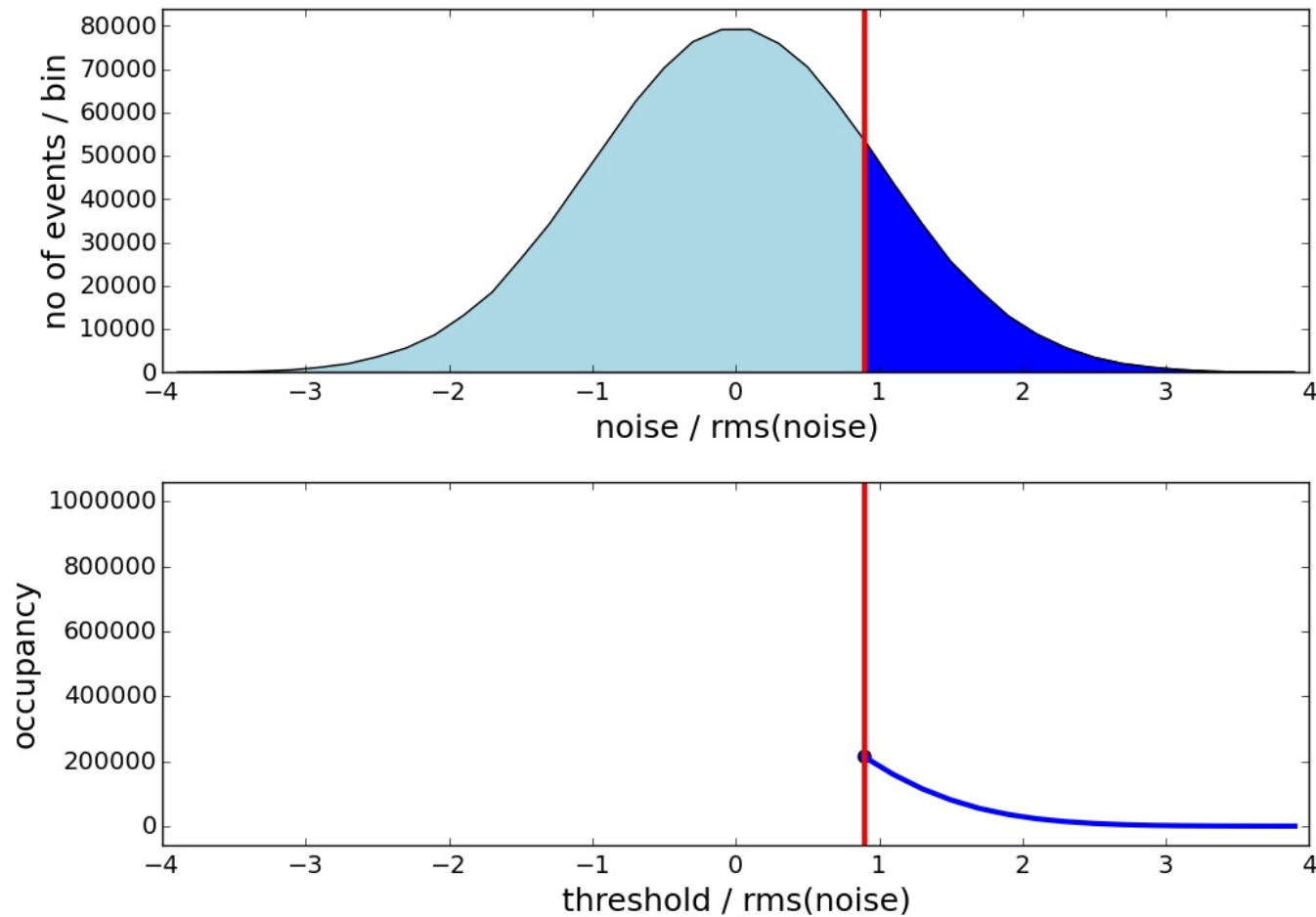


- if not (noise  $\ll$  signal): potential challenges / problem
- one needs to verify that in a complete system (modules, petal, ...) the signal pulse height (S) is sufficiently large compared to the noise (N)
  - trackers:  $S/N > 10$

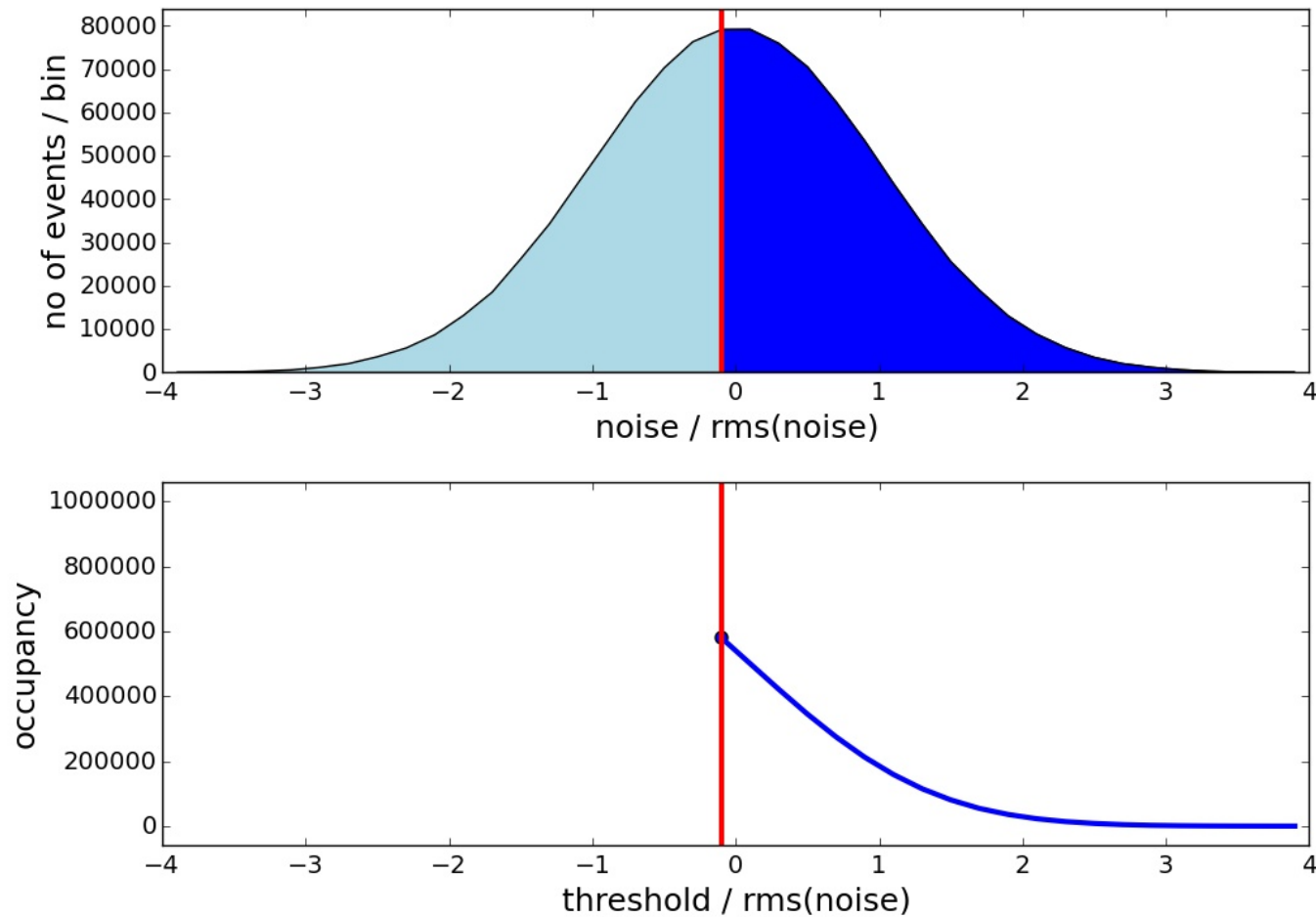


- assume Gaussian distributed noise:  $\rightarrow$  mean  $\mu$ , width  $\sigma$
- if signal exceeds threshold  $\tau$  is converted into a hit

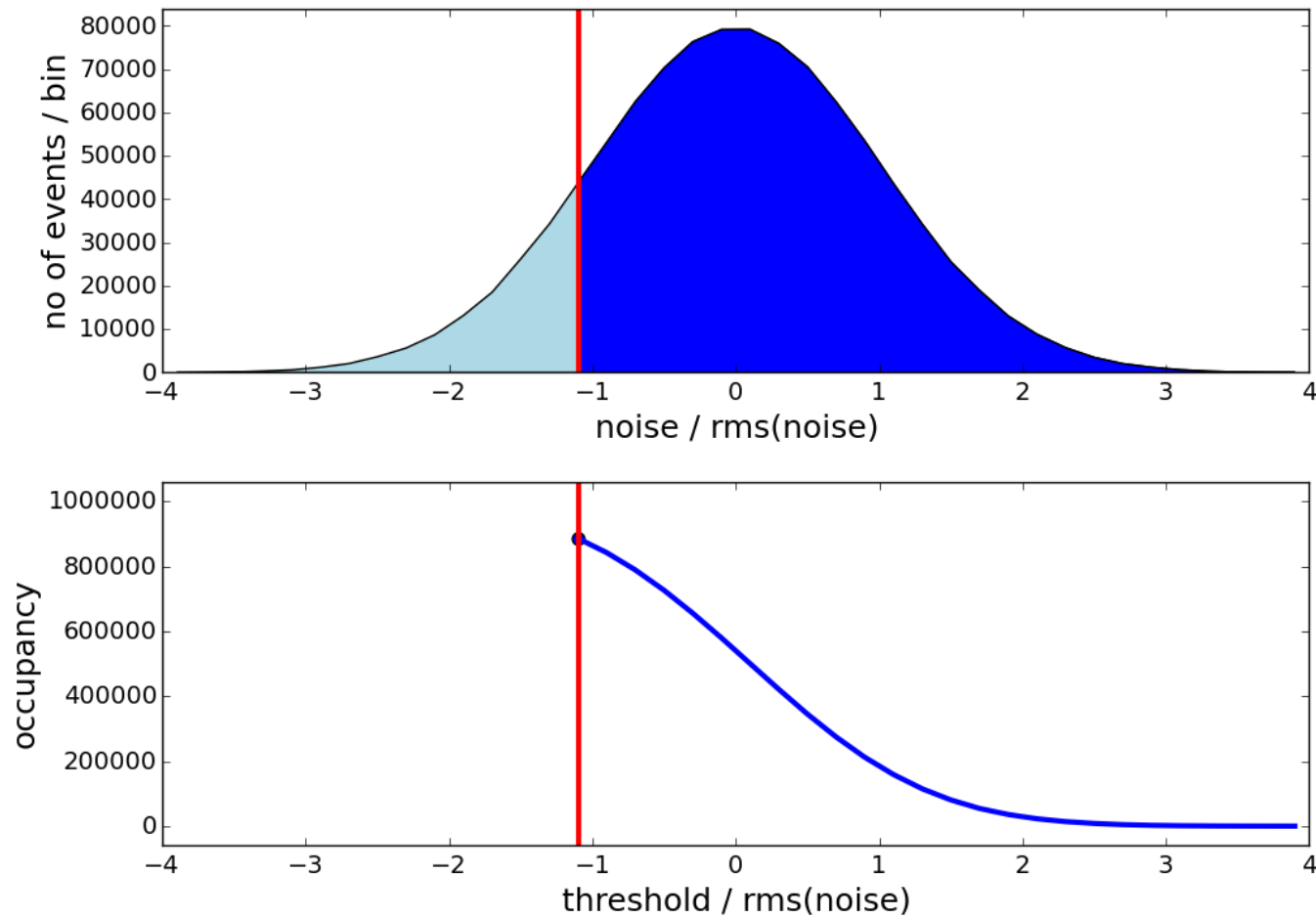




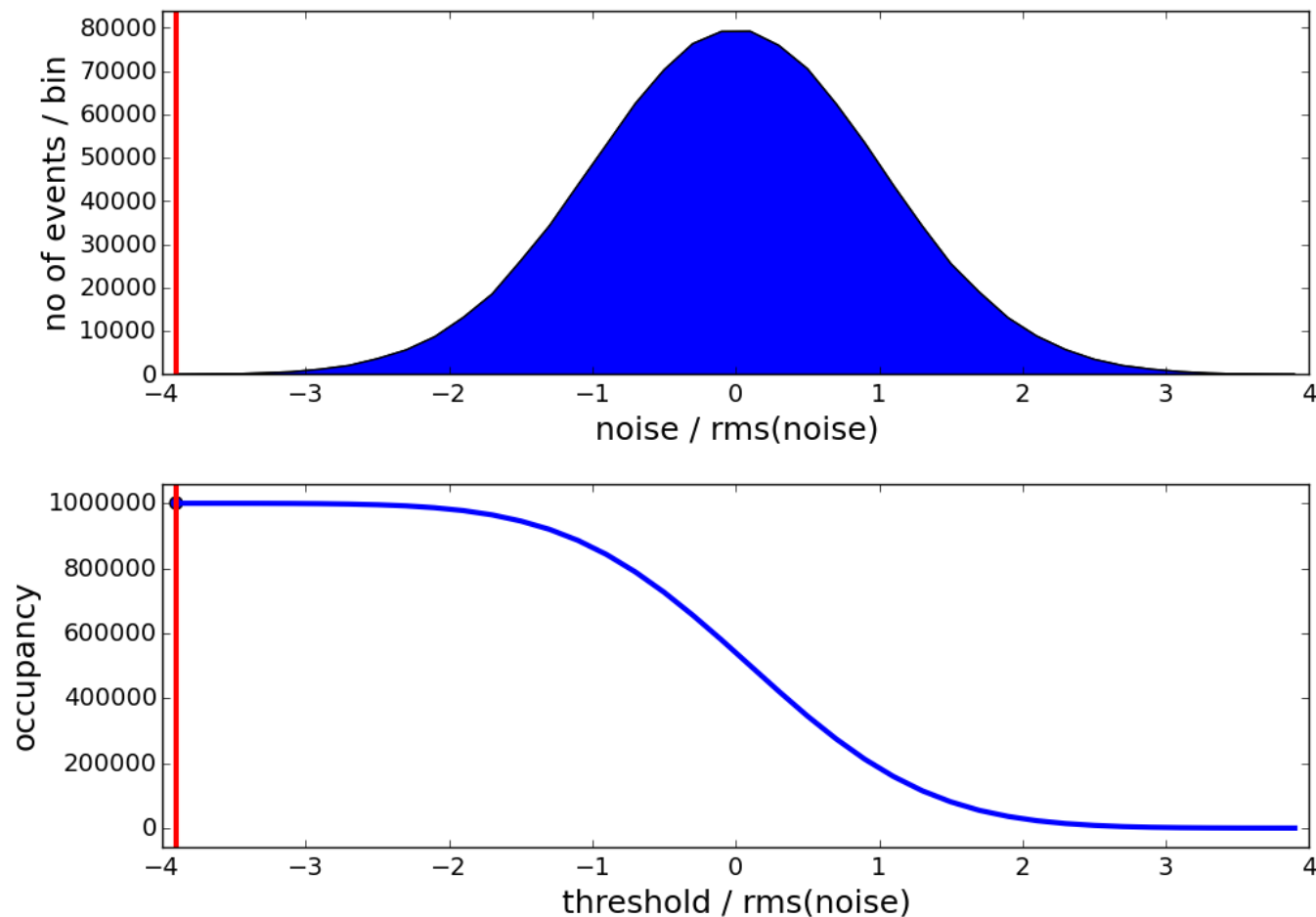
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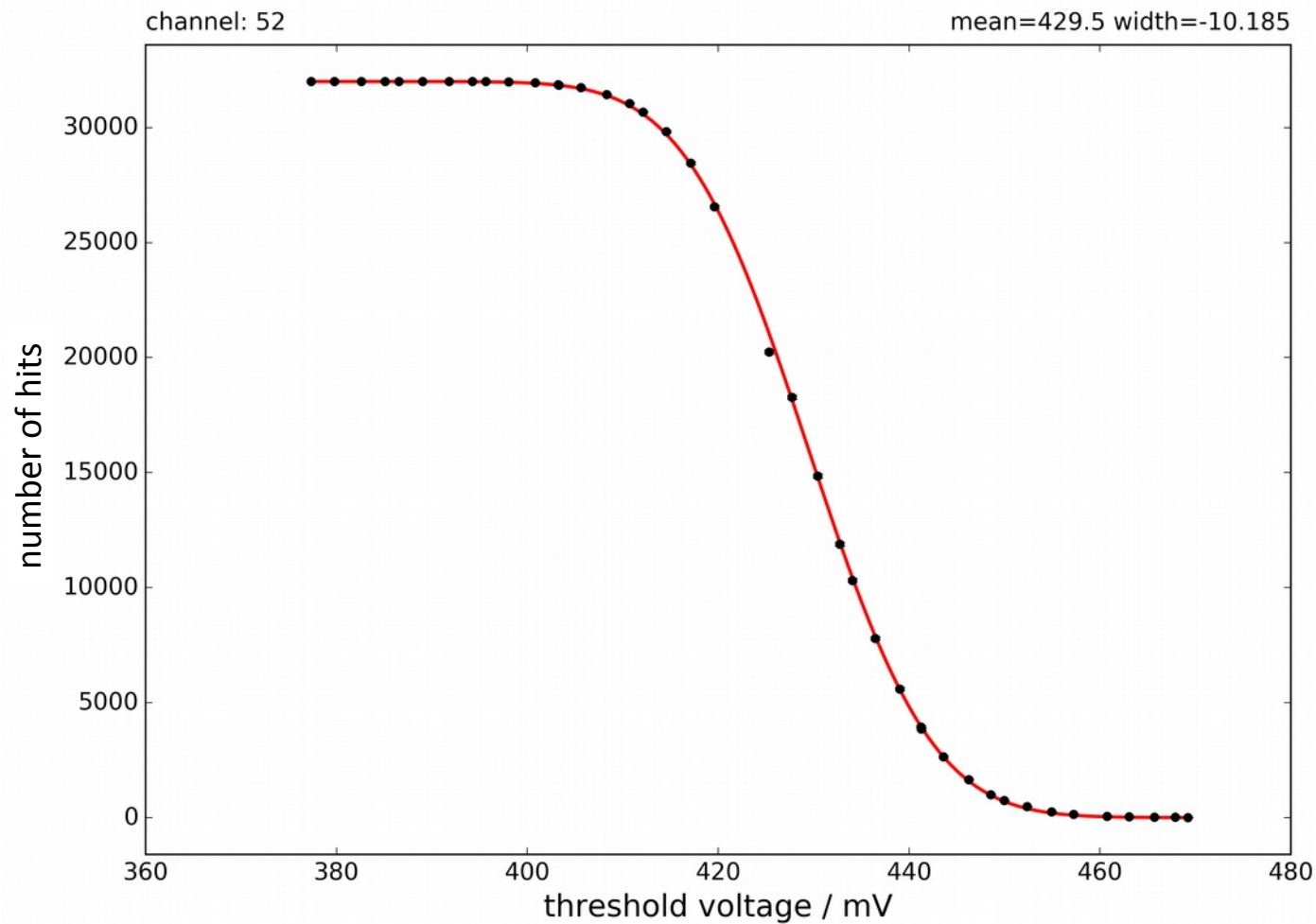
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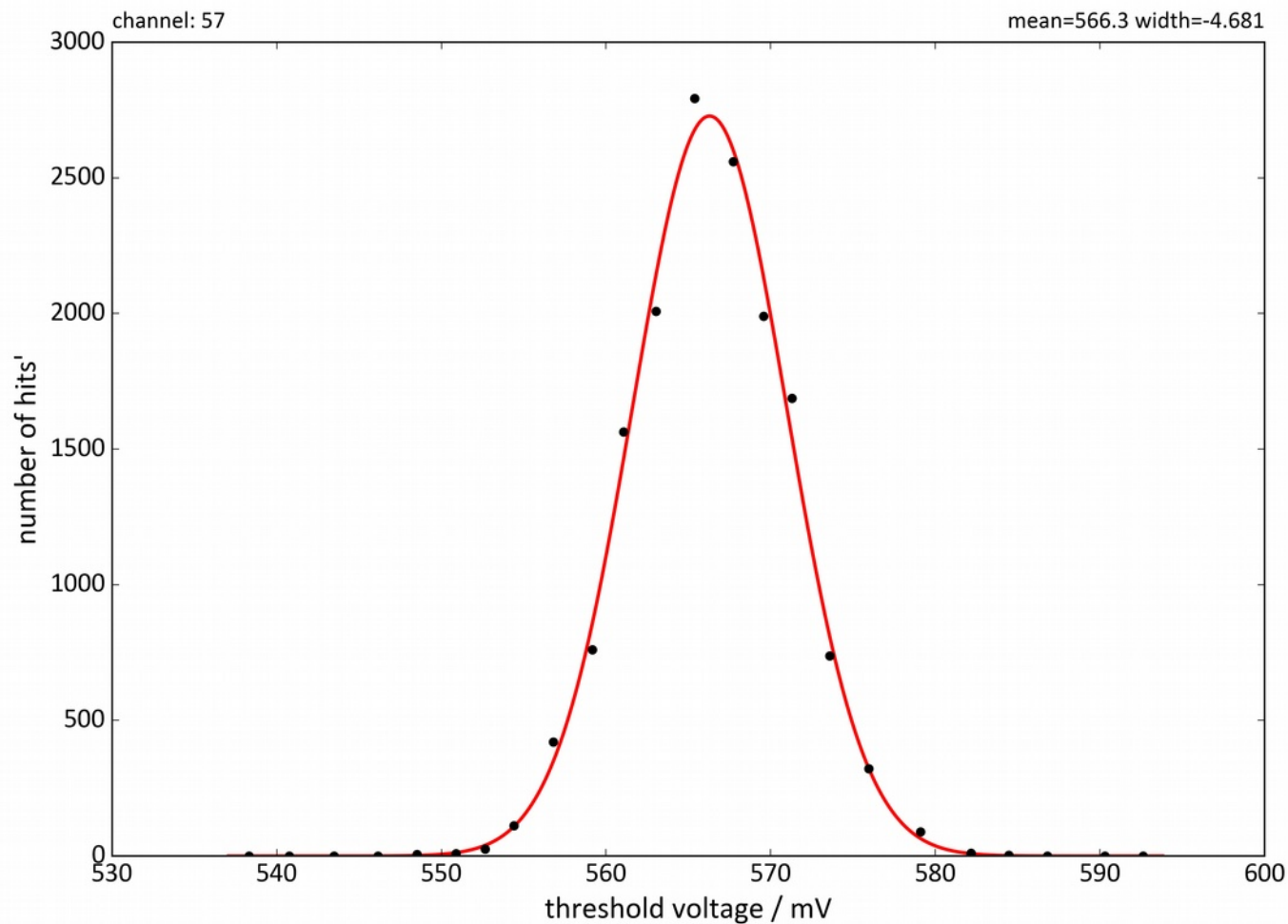
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- probability of a noise hit: 
$$p(\mu, \sigma, \tau) = \frac{1}{\sigma \sqrt{2\pi}} \int_{\tau}^{\infty} \exp\left(-\frac{1}{2} \left(\frac{\tau' - \mu}{\sigma}\right)^2\right) d\tau' = \frac{1}{2} \left(1 + \operatorname{erf}\left(\frac{\tau - \mu}{\sqrt{2}\sigma}\right)\right)$$

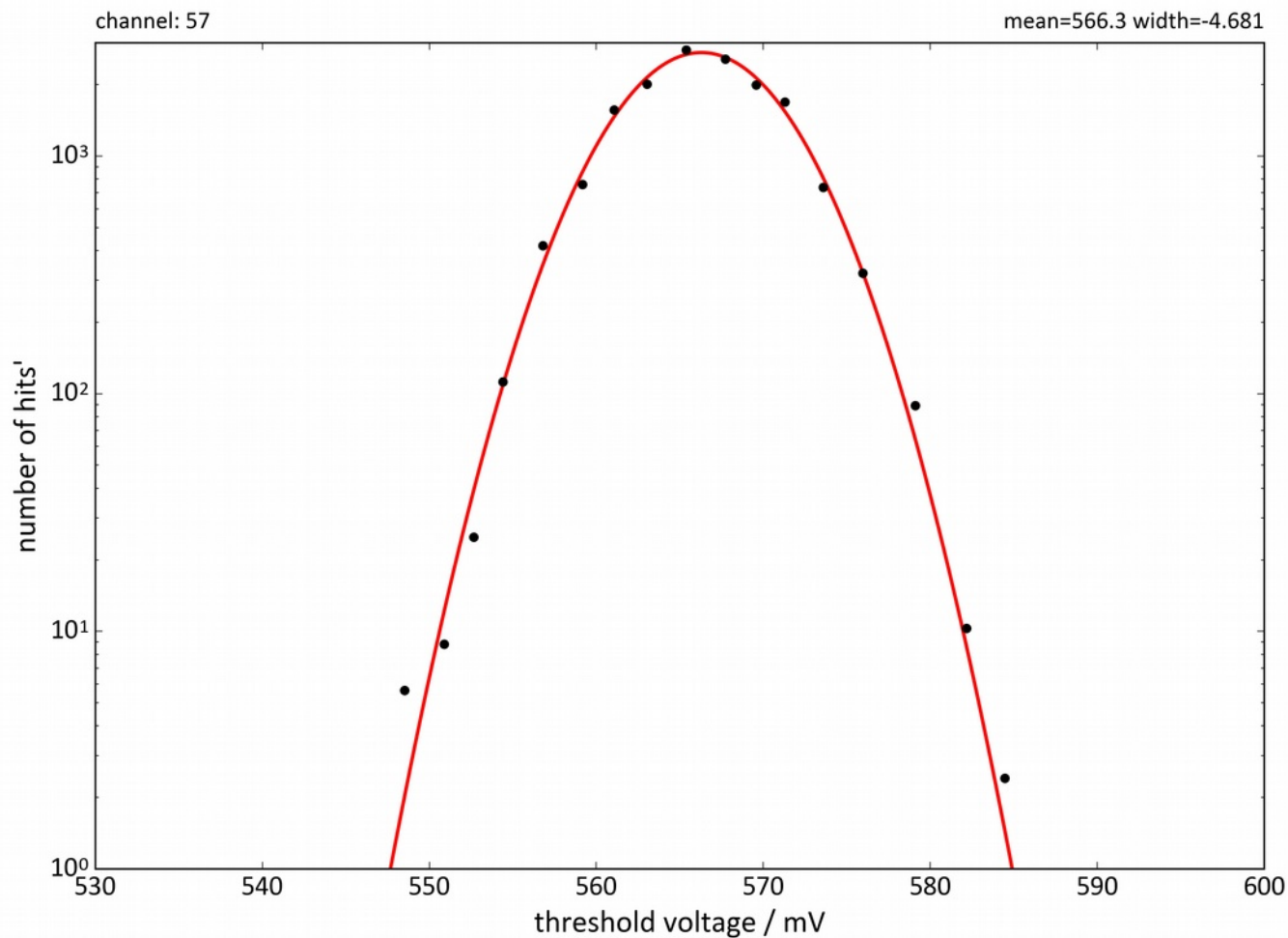
- extract the width and mean of the noise from a 'signal depleted' threshold scan
  - fitting number of hits vs. threshold with an error-function
  - in units of the threshold

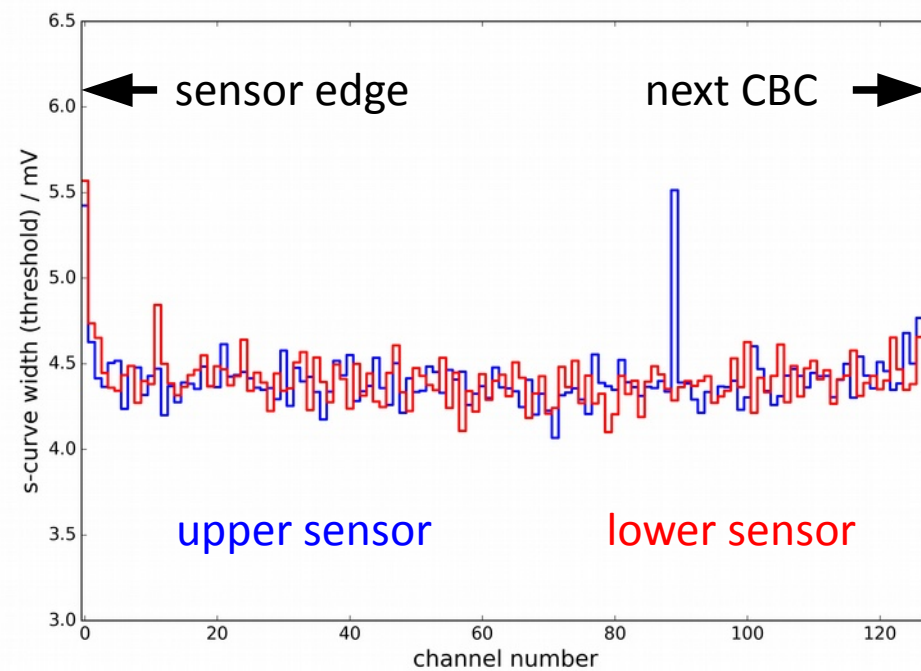
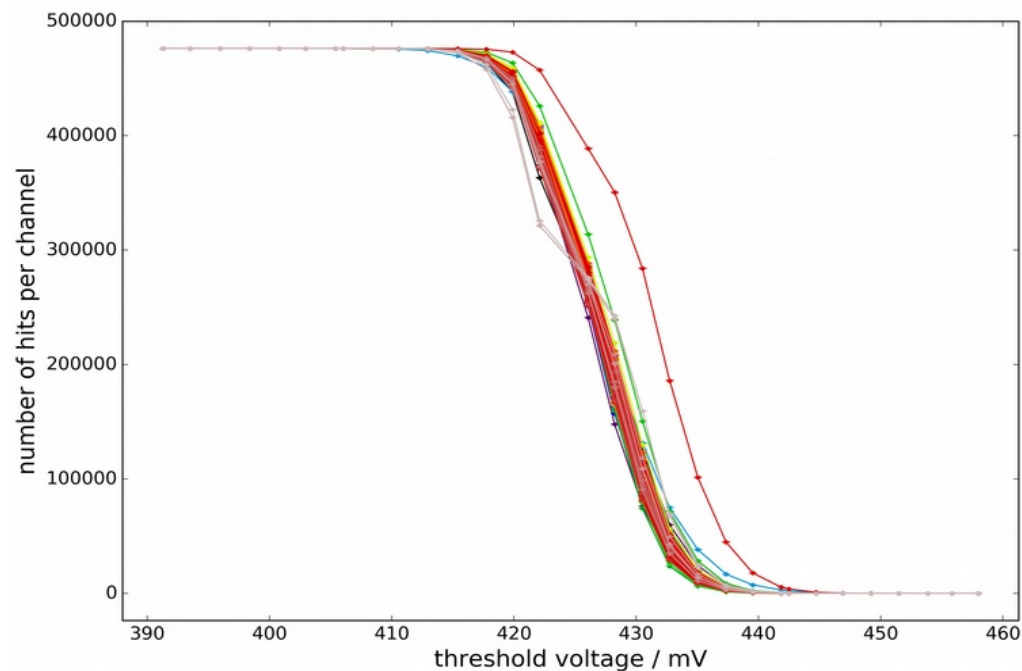


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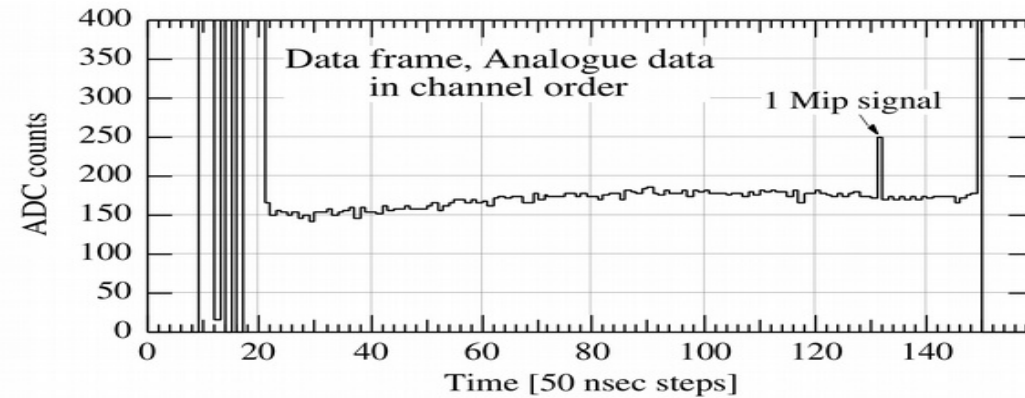




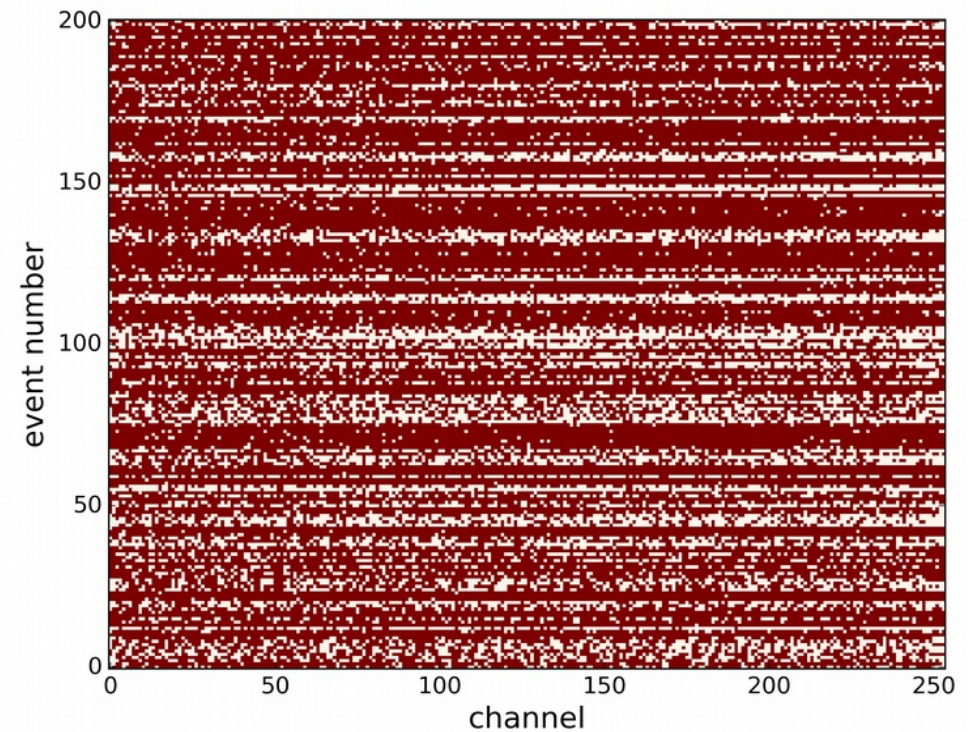
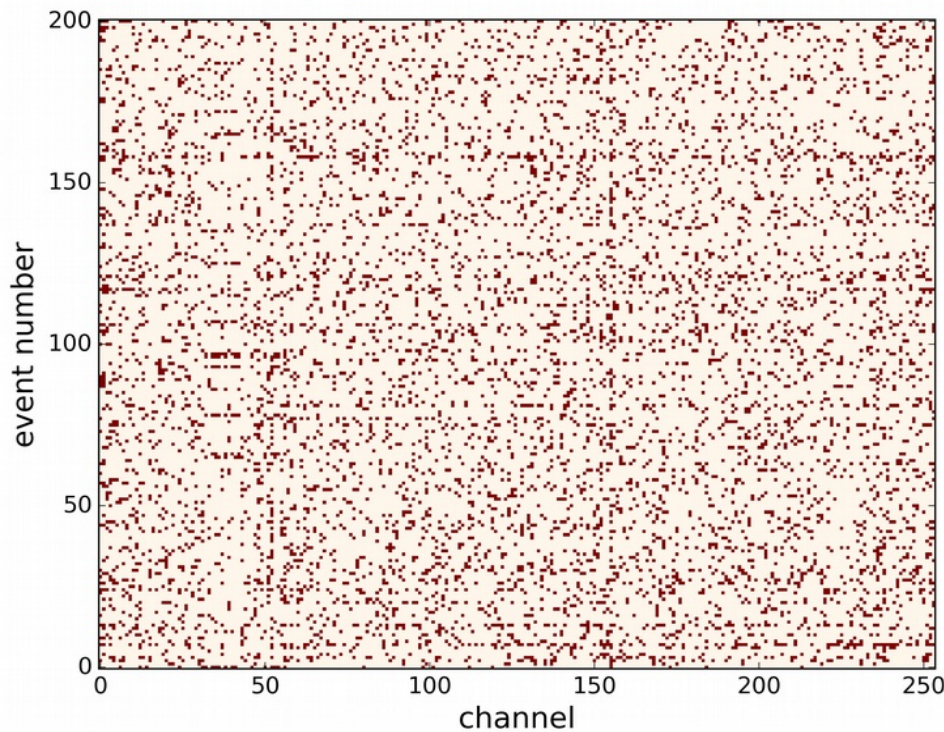
- channels have been tuned to the same 50% occupancy point
  - where nominally no charge is entering the analogue front-end

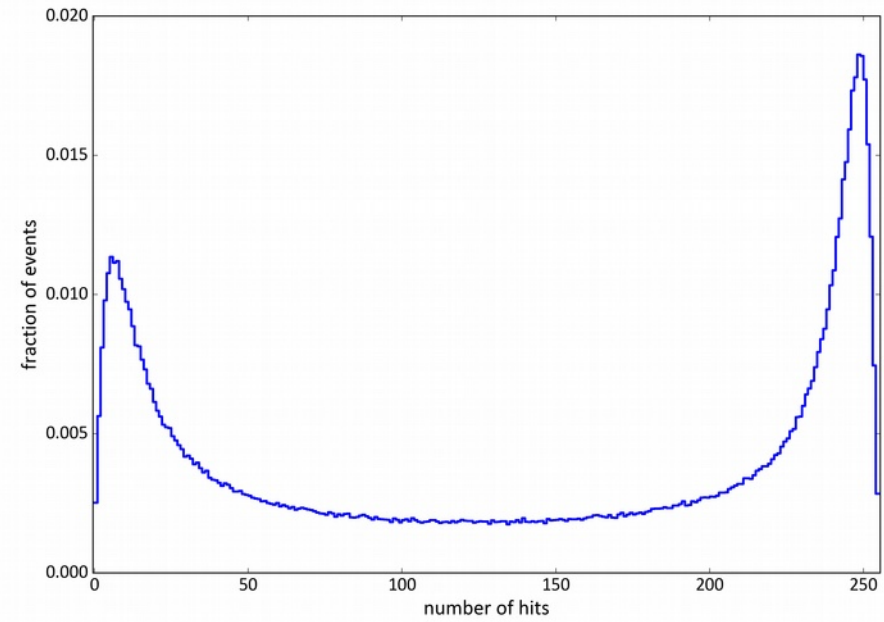
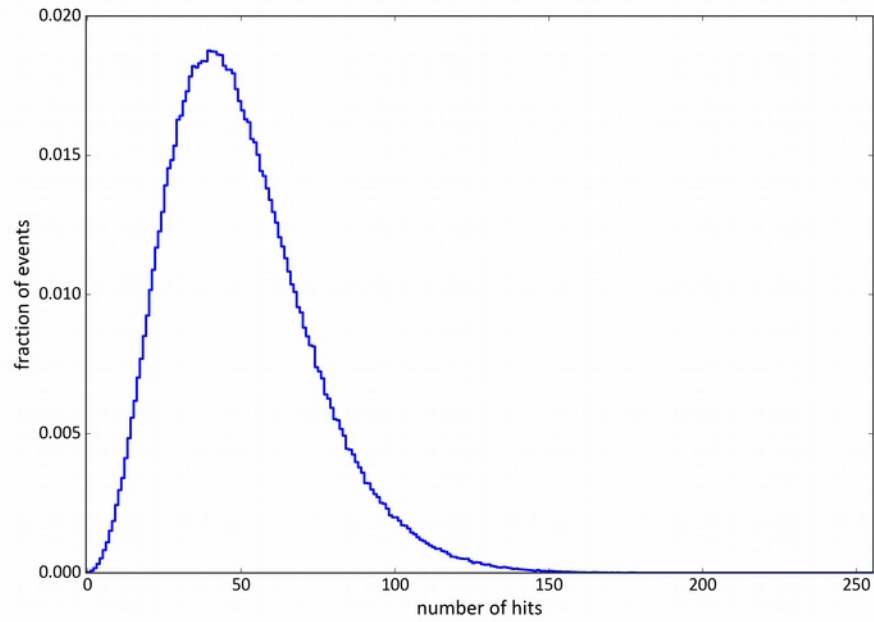


- channels are not isolated, coupled via:
  - inter-strip capacitance in sensor, ...
  - ground, power rails, threshold voltage

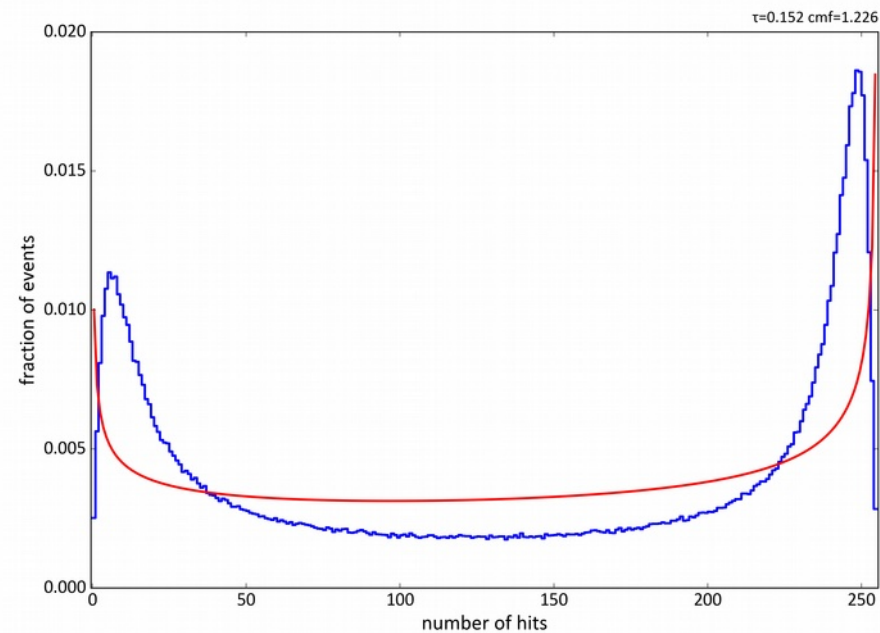
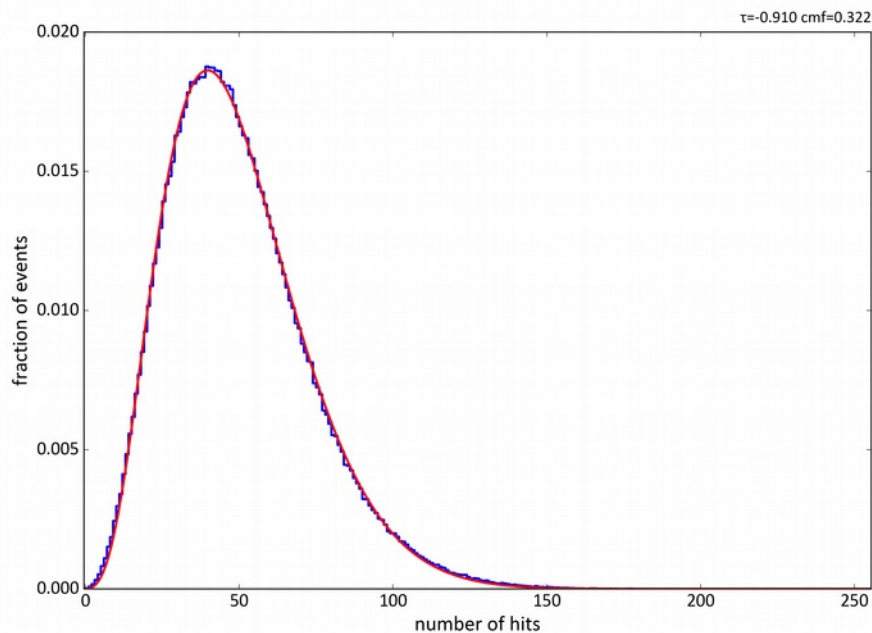


- common mode noise: coherent pulse-height variations in groups of multiple channels
- analogue / digital (non zero suppressed) readout: monitor (common mode) noise during operation → suppression on per event basis
- binary readout scheme: measure noise in common mode between operation e.g. [Measurement of common mode noise in binary read-out systems \(L. Feld et. al\) NIM A 487 \(2002\) 557–564](#)



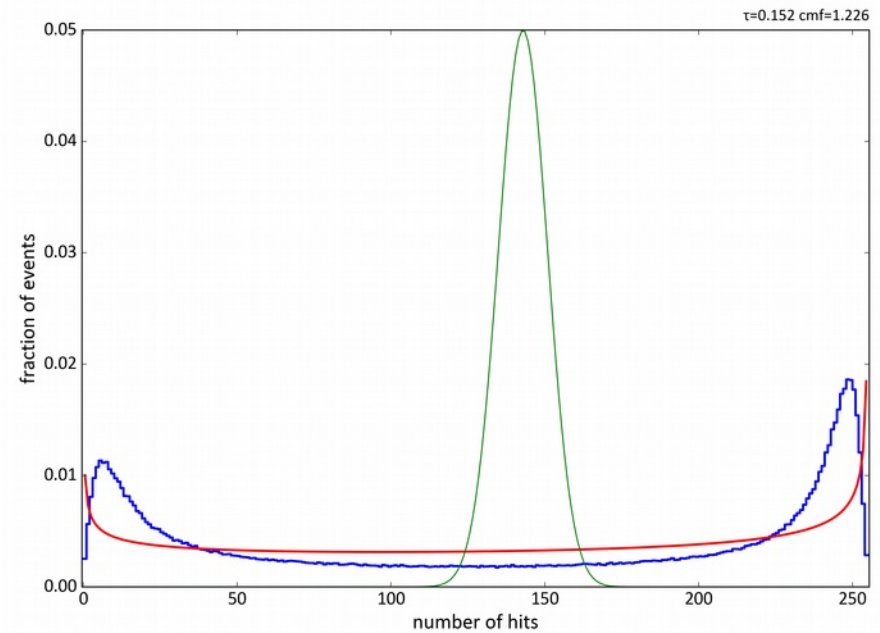
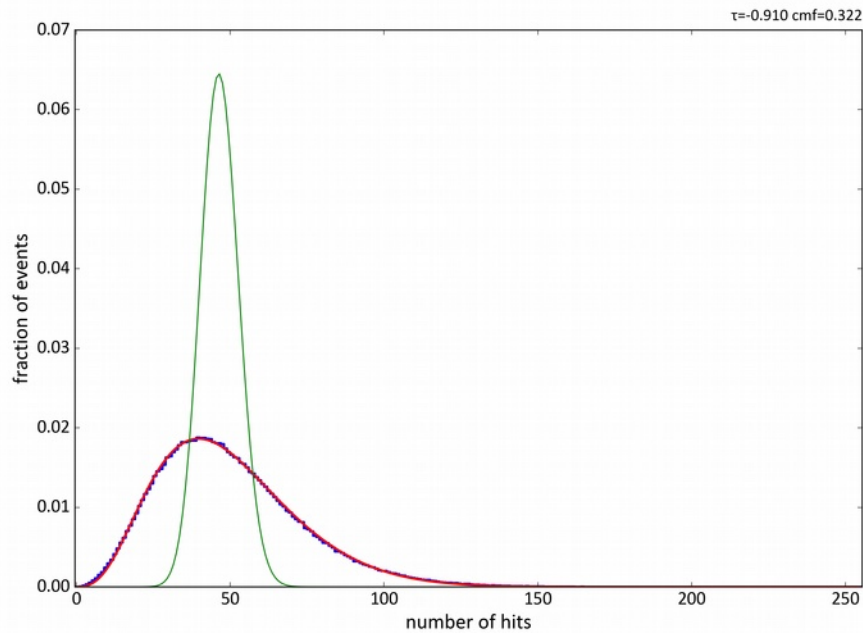


measurement



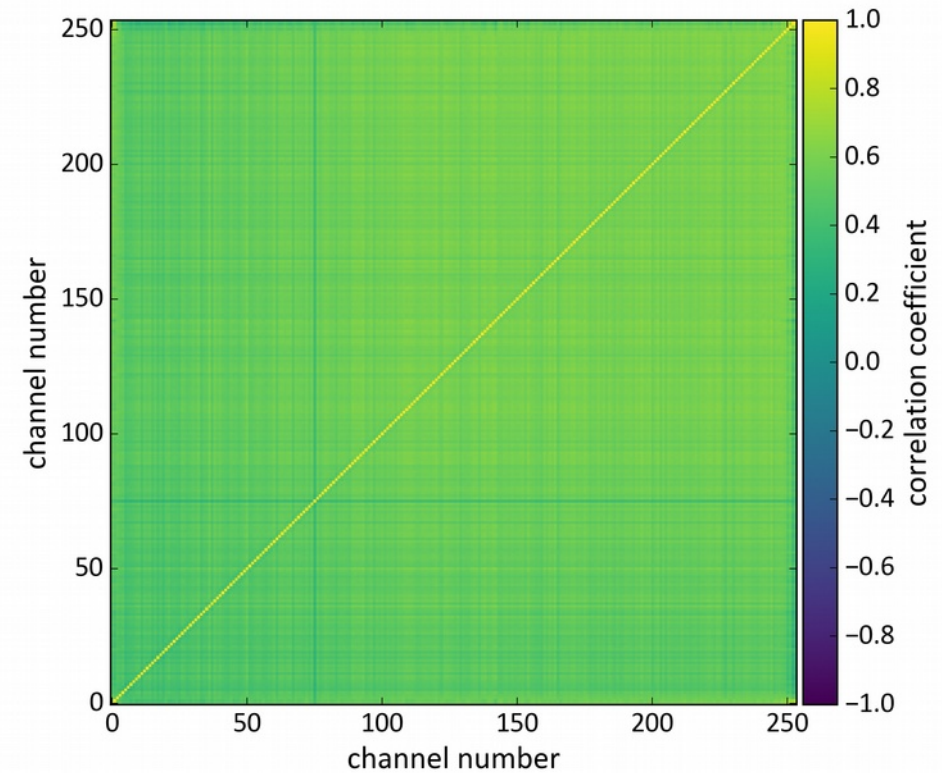
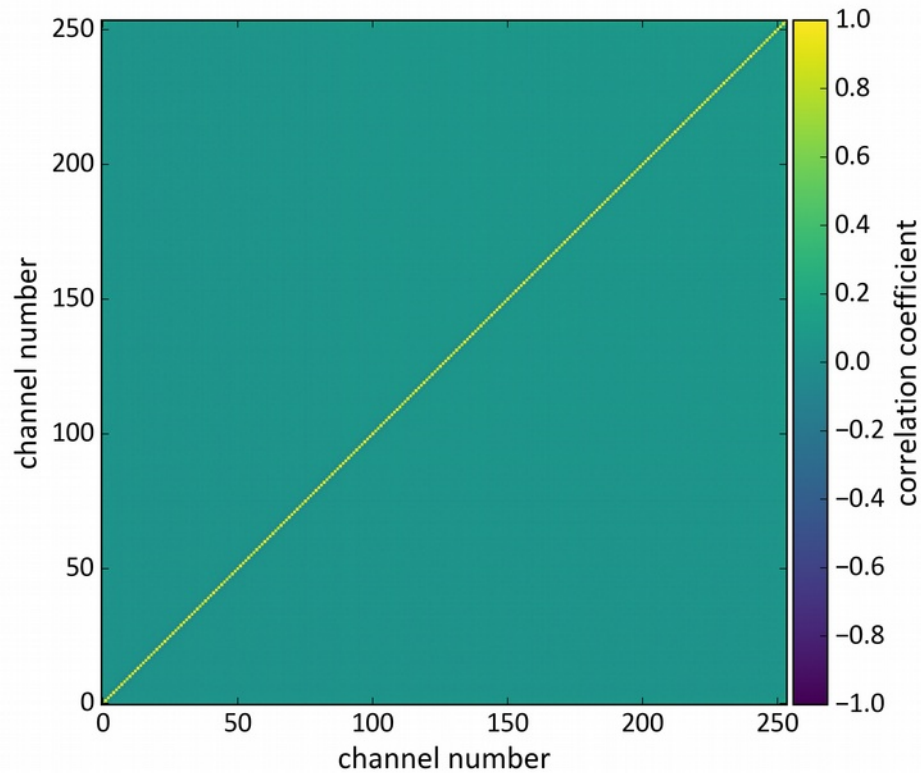
measurement fit

- fit number of hits distribution → extract fraction of common mode in overall noise
  - single channel hit prop.:  $p(\sigma, \mu, \tau) = \text{norm}_{\text{CDF}}(\sigma, \mu, \tau)$
  - k out of N strips:  $b(N, k, \sigma, \mu, \tau) = \text{binom}_{\text{PDF}}(N, k, p(\sigma, \mu, \tau))$
  - express common mode as threshold variation:  $a(\tau, \sigma_{\text{CM}}) = \text{norm}_{\text{PDF}}(\tau, \sigma_{\text{CM}})$
- number of hits  $(\mu, \tau, \mu_{\text{CM}}) = \text{int}( b(N, k, \sigma, \mu, \tau_{\text{CM}}) \cdot a(\mu - \tau_{\text{CM}}, \sigma_{\text{CM}}), \tau_{\text{CM}} = -\infty \dots \infty)$  for  $k=0..N$ 
  - evaluate numerically
  - assumes identical  $p(\sigma, \mu, \tau)$  for all channels



measurement   fit   no common mode

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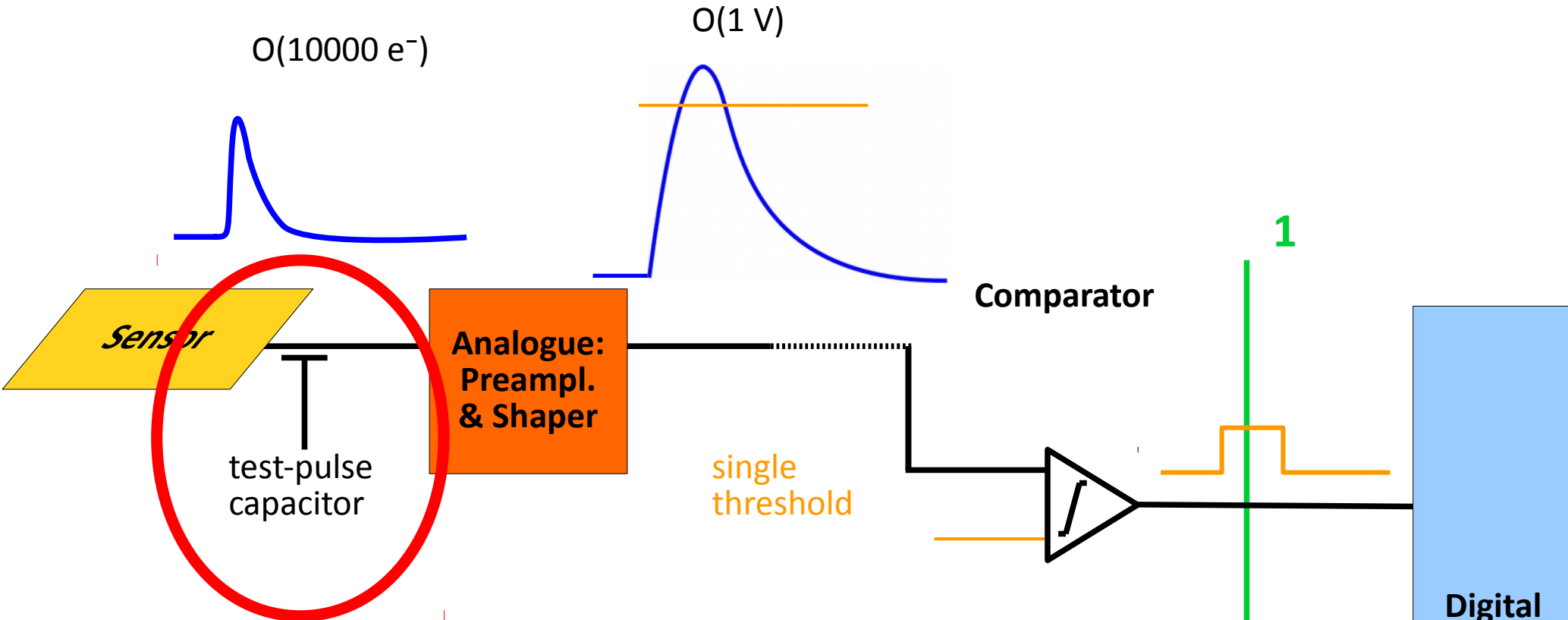


$$\text{cor}_{xy} = \frac{\langle xy \rangle - \langle x \rangle \langle y \rangle}{\sigma_x \sigma_y} = \frac{\Omega_{x \cdot y} - \Omega_x \Omega_y}{\sqrt{\Omega_x - (\Omega_x)^2} \sqrt{\Omega_y - (\Omega_y)^2}}$$

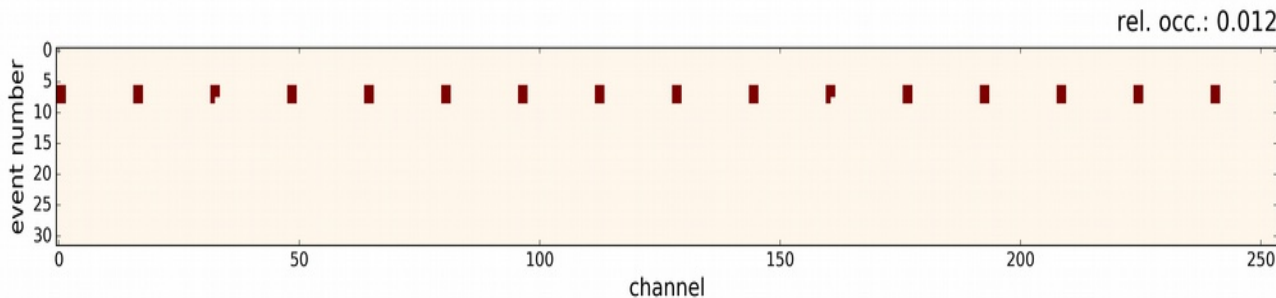
$\Omega_x$  = number of events with hit in channel x / number of total events

$\Omega_{xy}$  = number events with hit in channels x AND y / number of total events

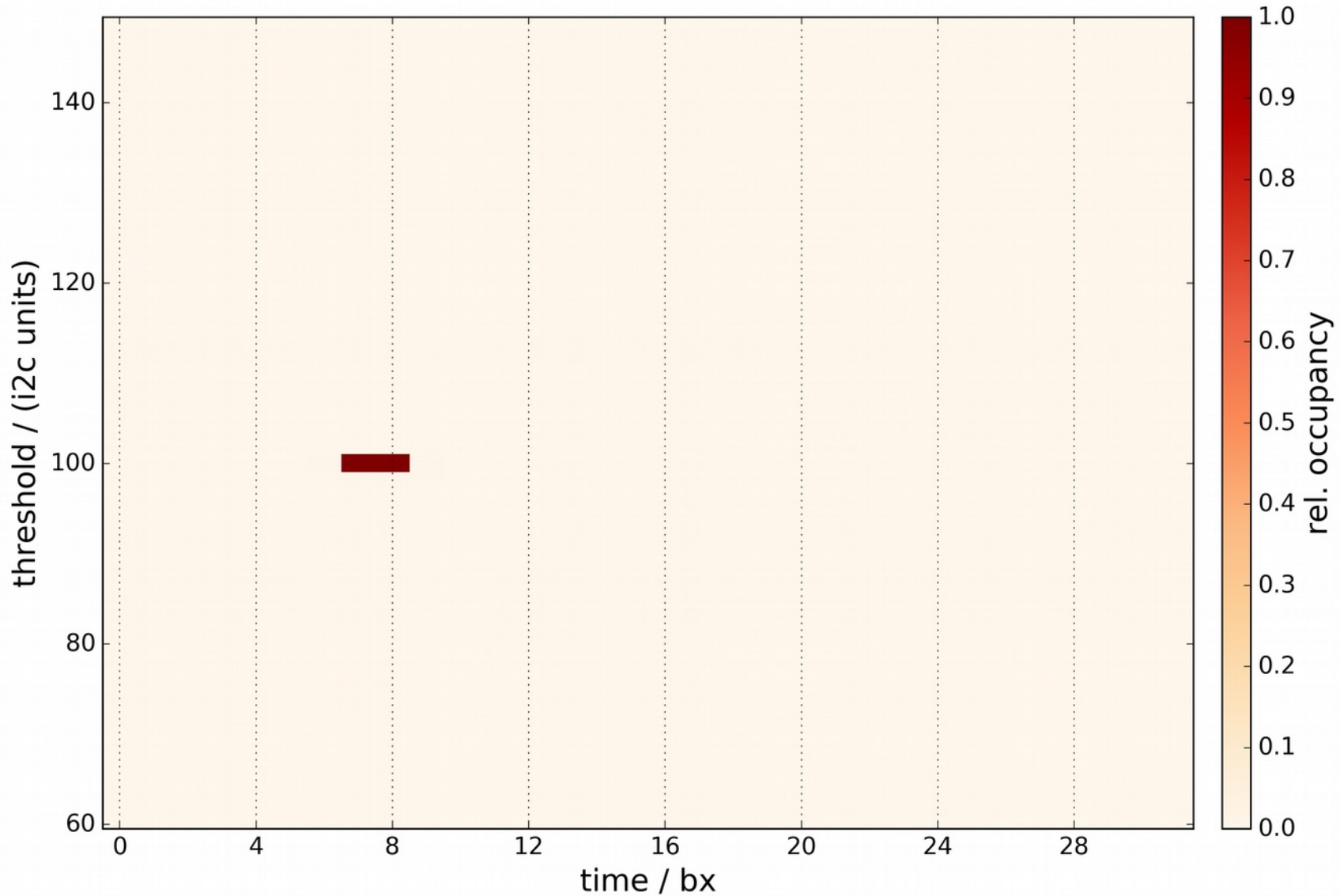
- test-pulses
- x-rays
- betas / mips



- “known” capacitance (e.g. 22fF)  $\rightarrow Q = CU$
- control on discharge time w.r.t. sampling time
- $\rightarrow$  inject configurable charge pulse into front-end
  - can be used to test and measure key quantities

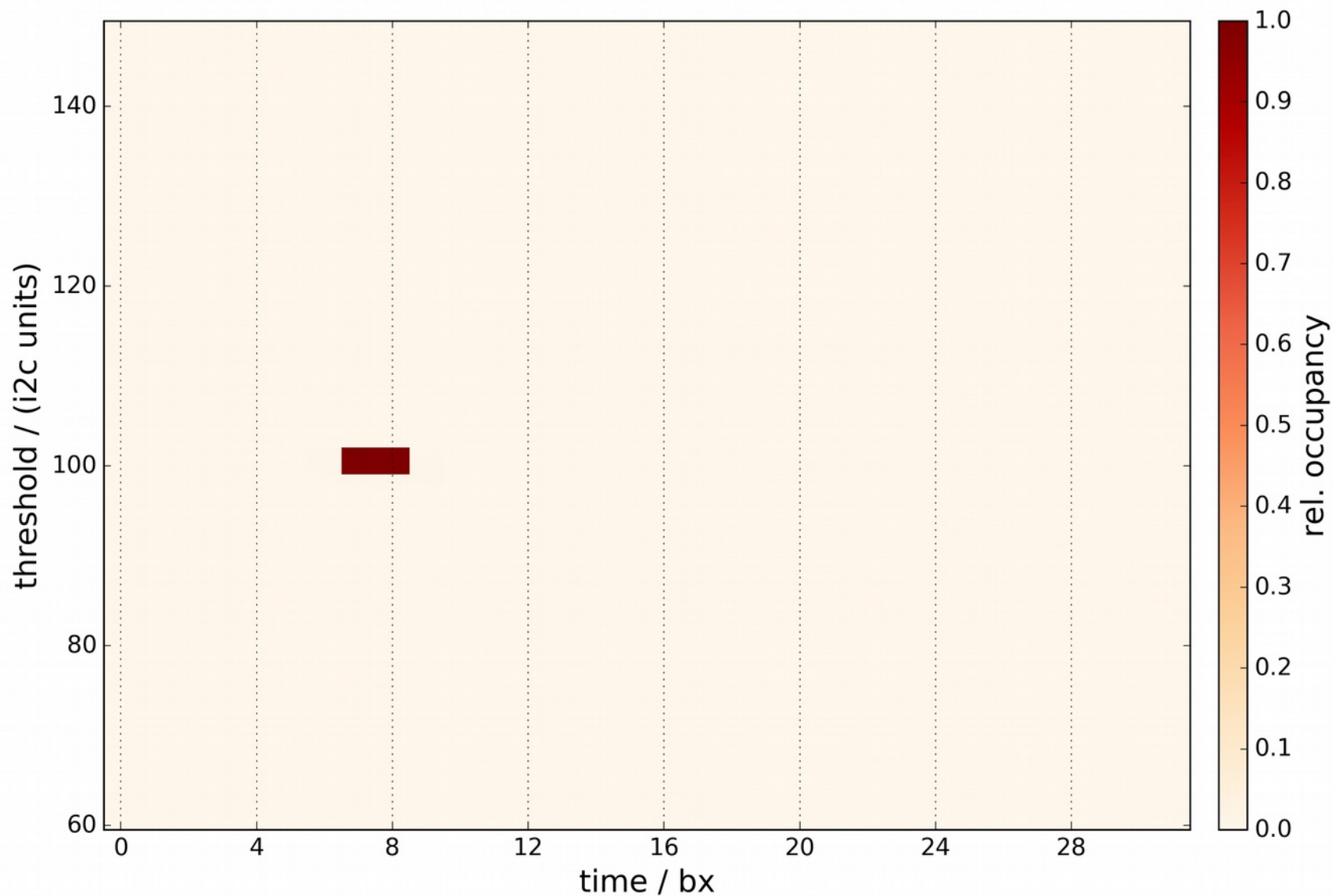


sampling time

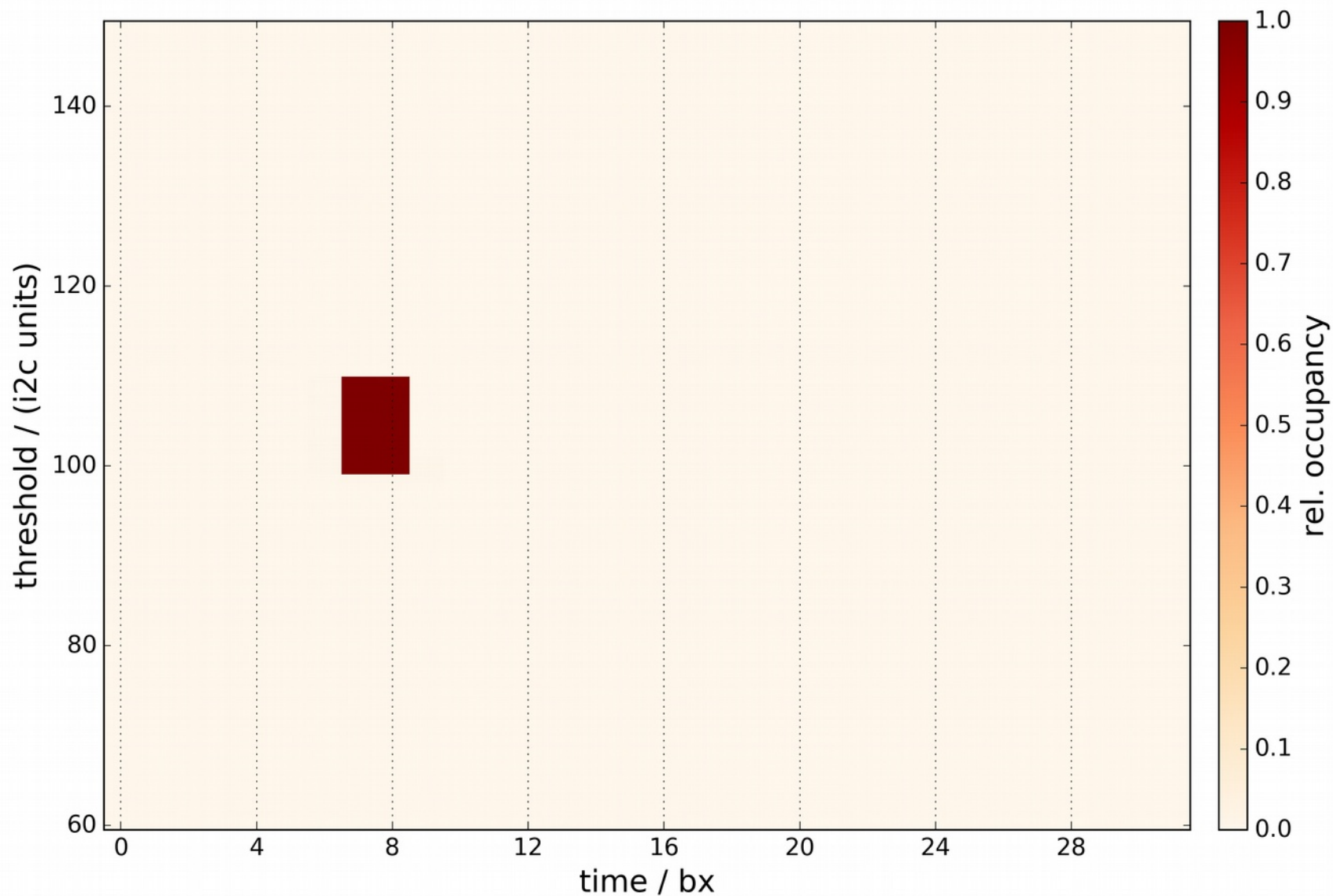


- inject many test-pulses and read frames of 32 consecutive events

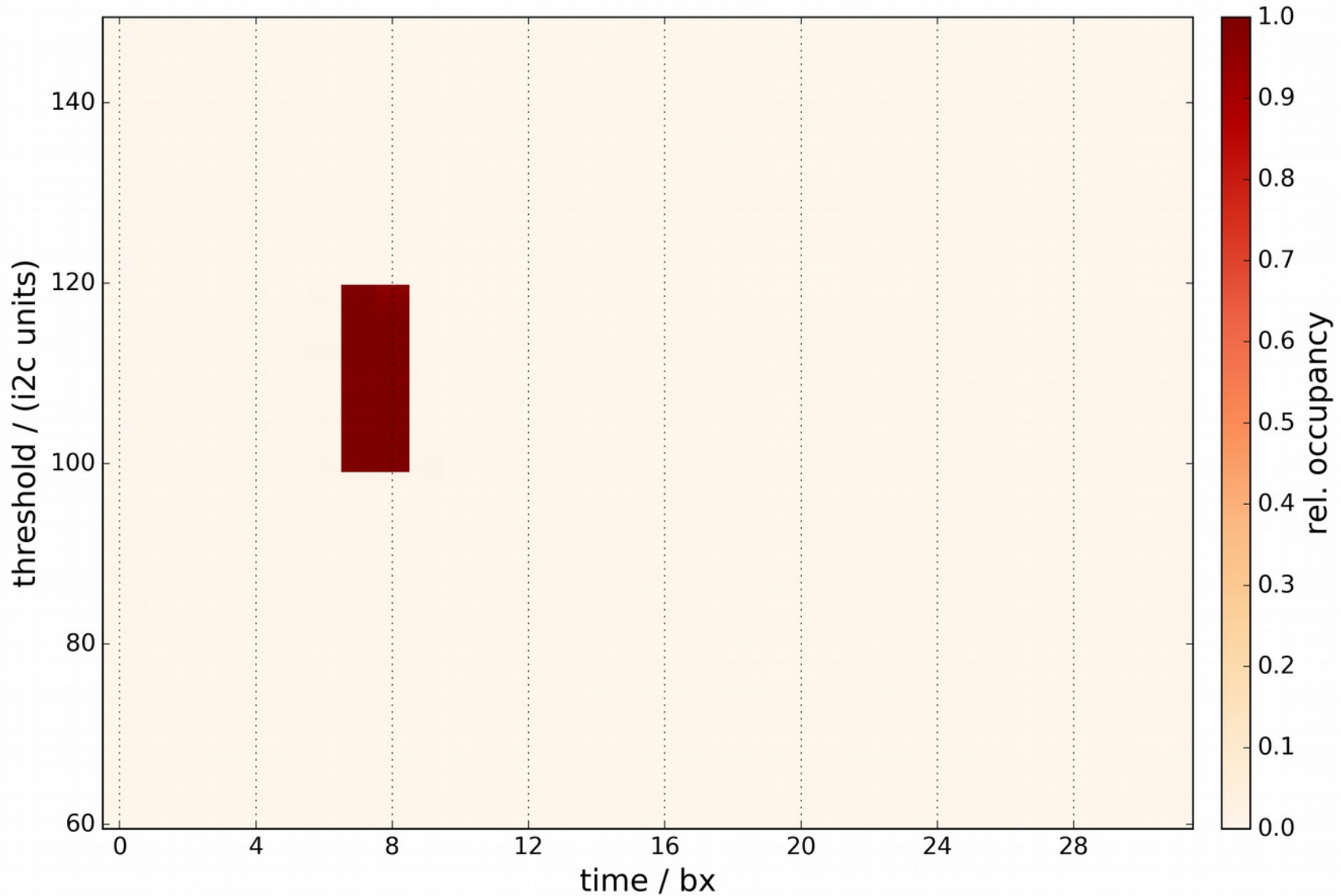




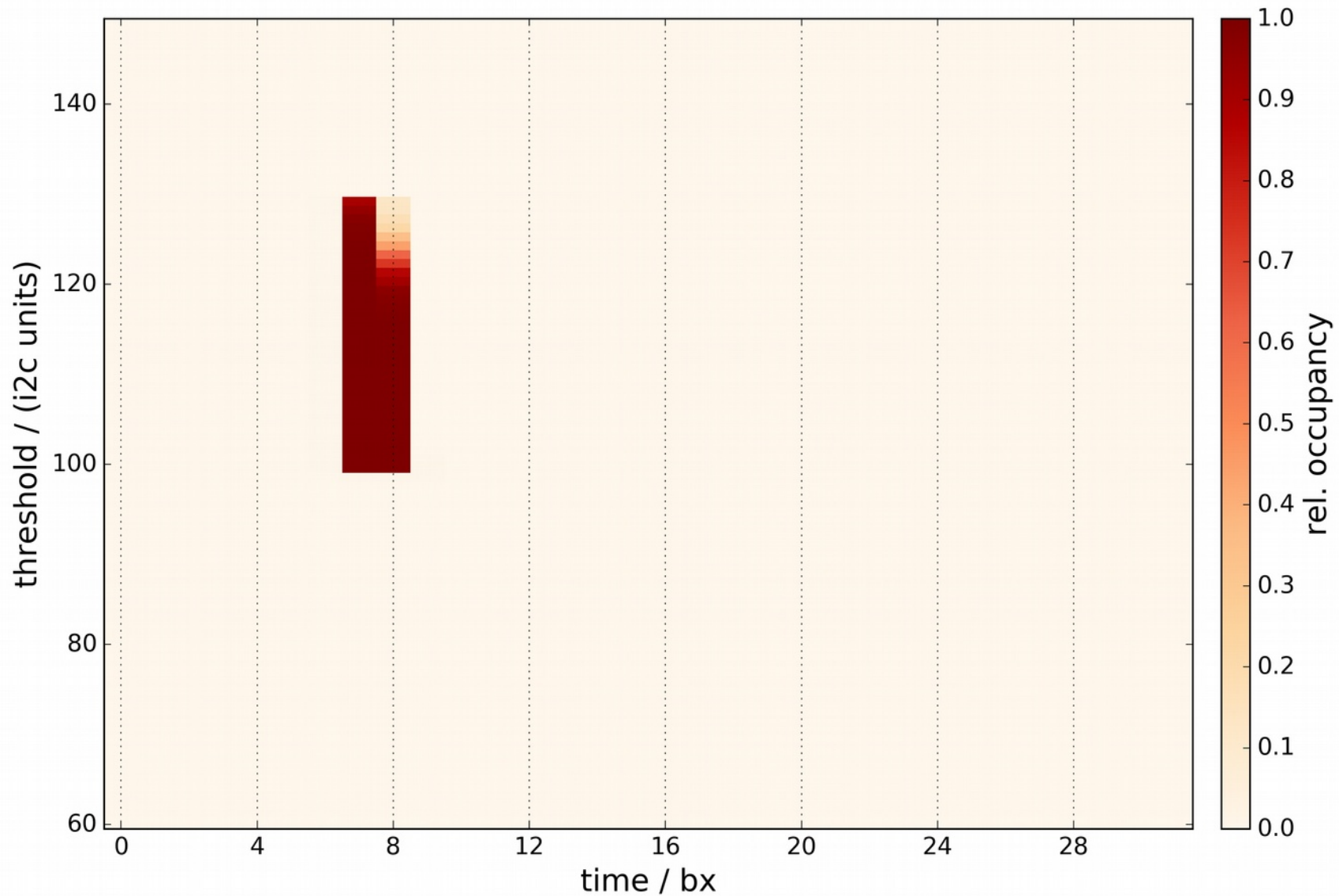
- inject many test-pulses and read frames of 32 consecutive events
- + threshold scan



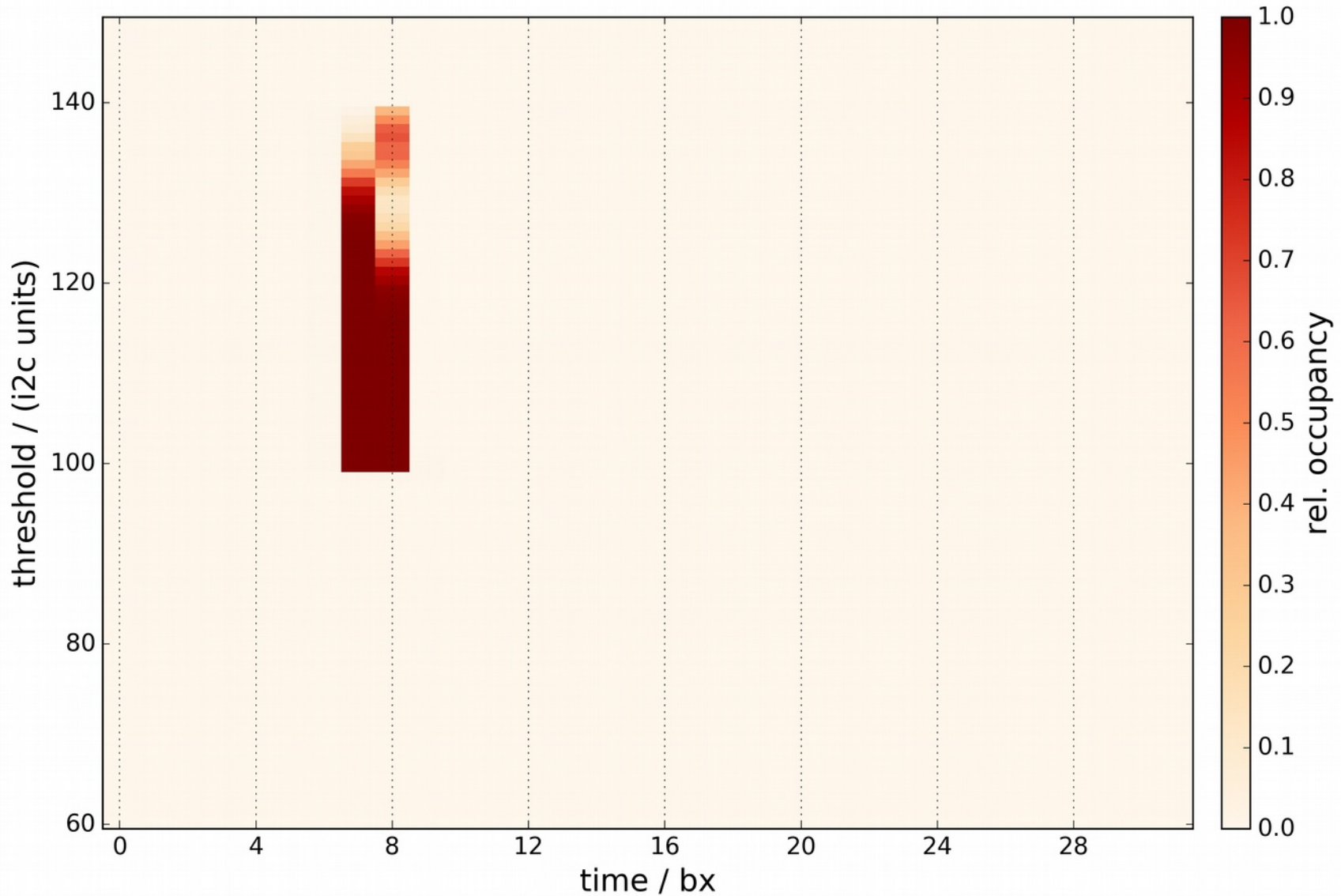
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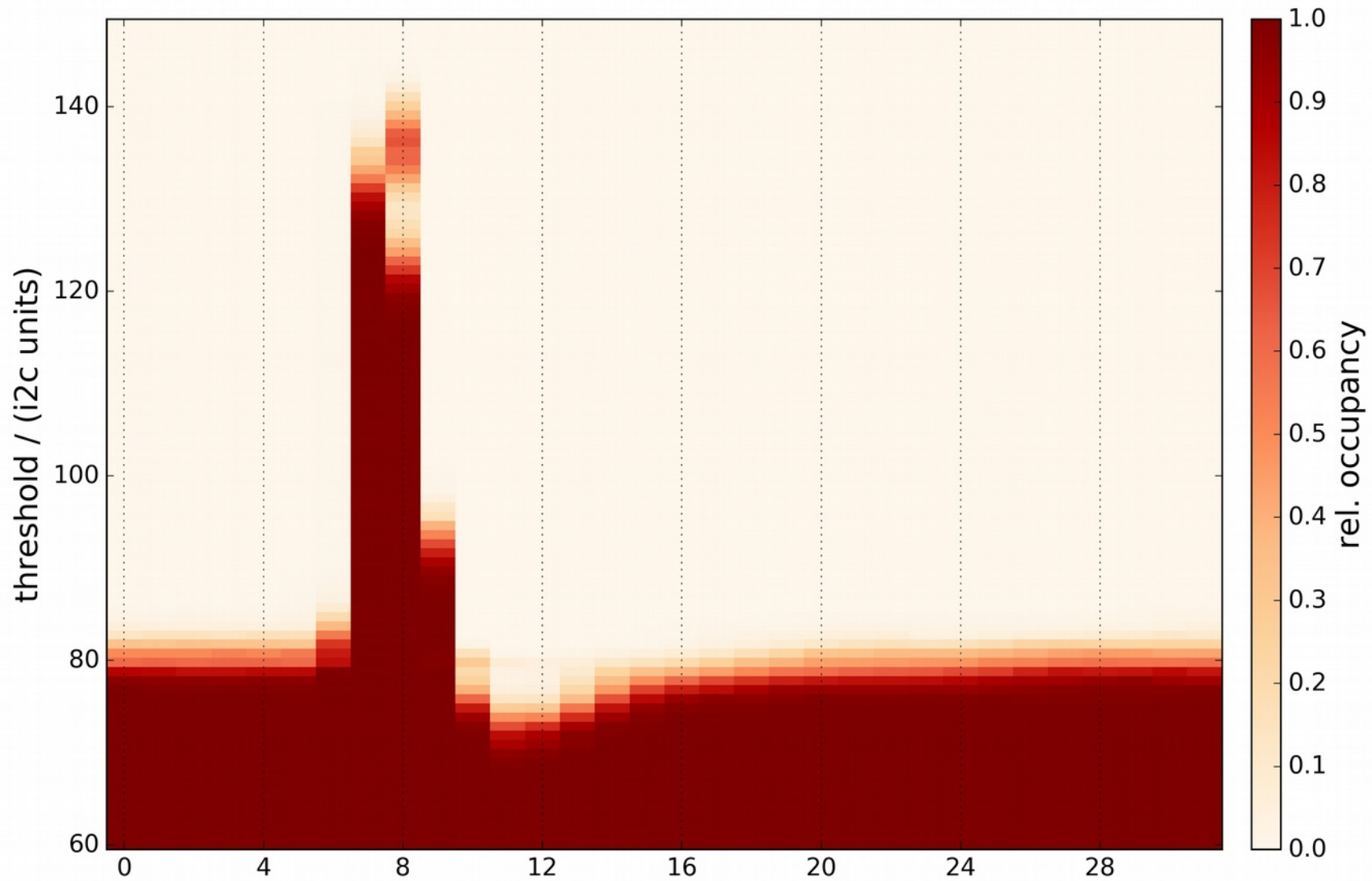
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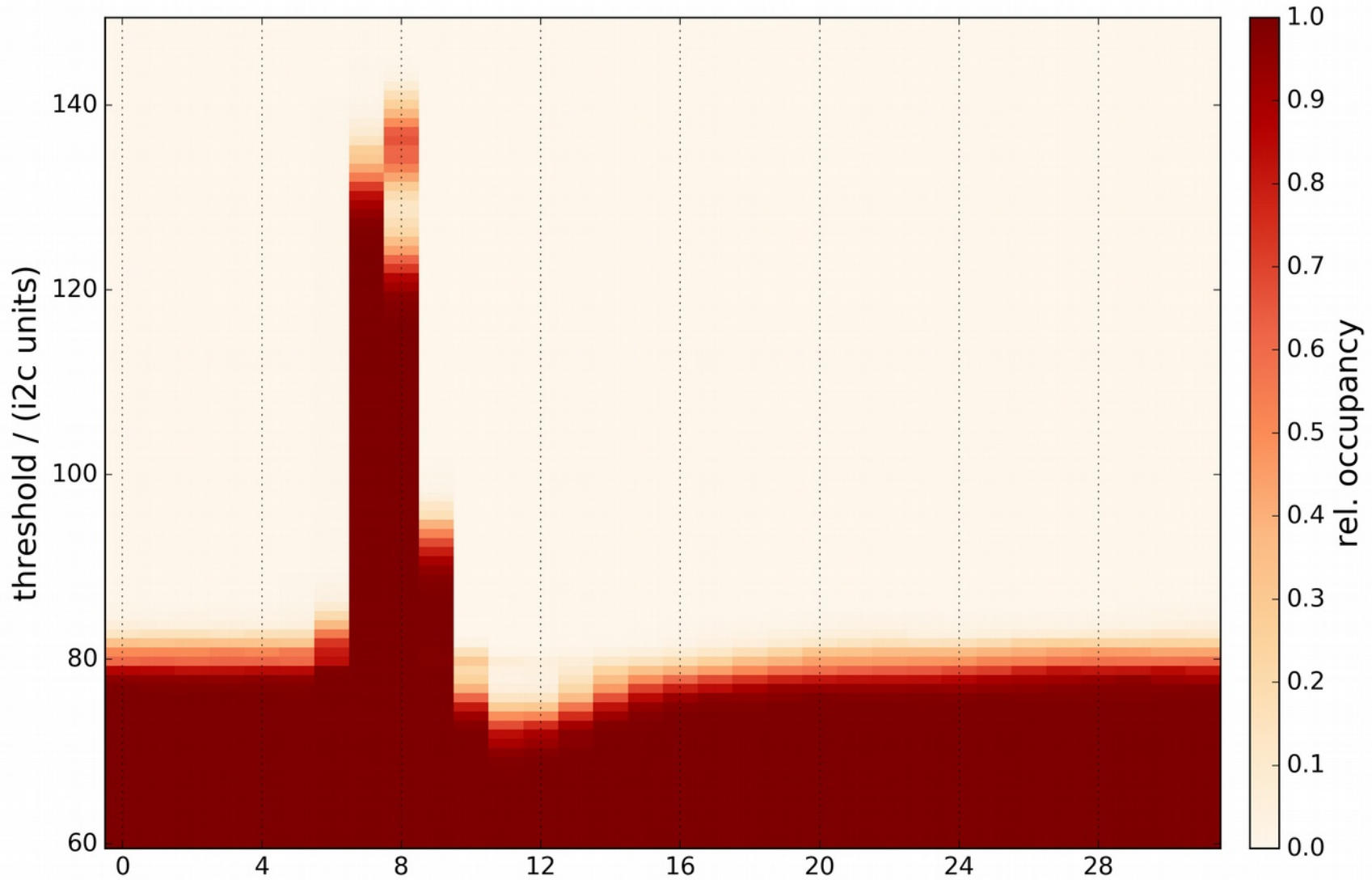
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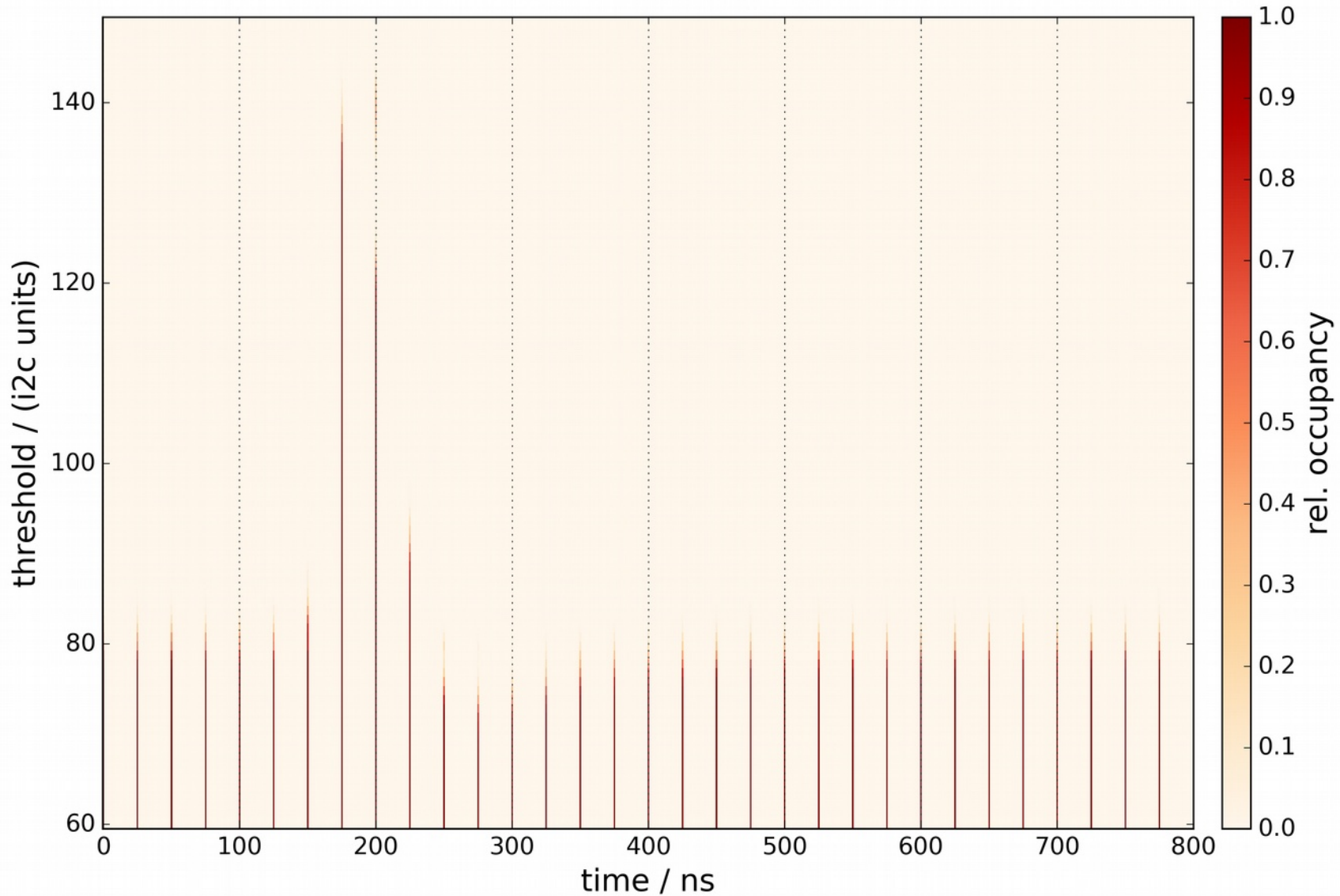
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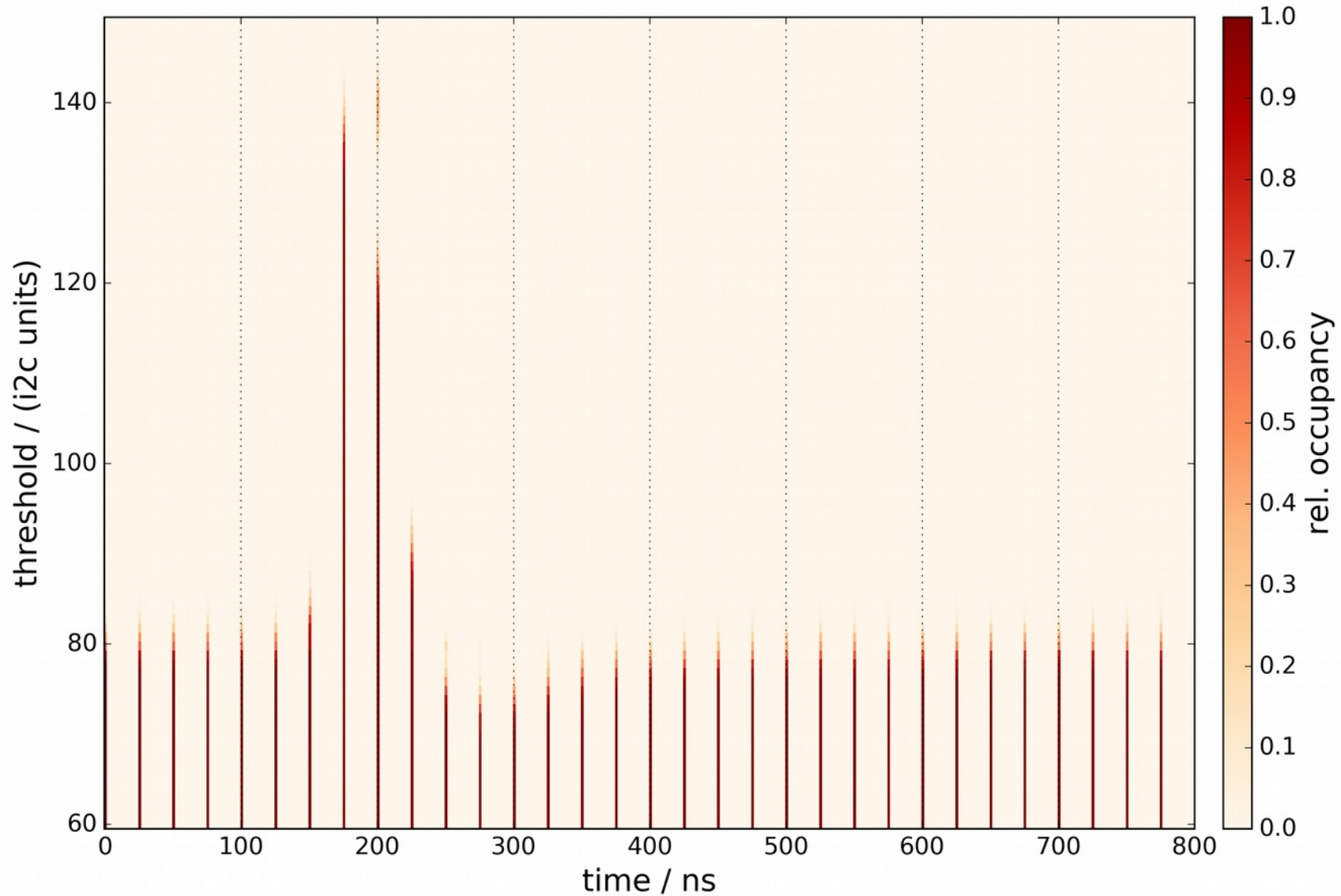


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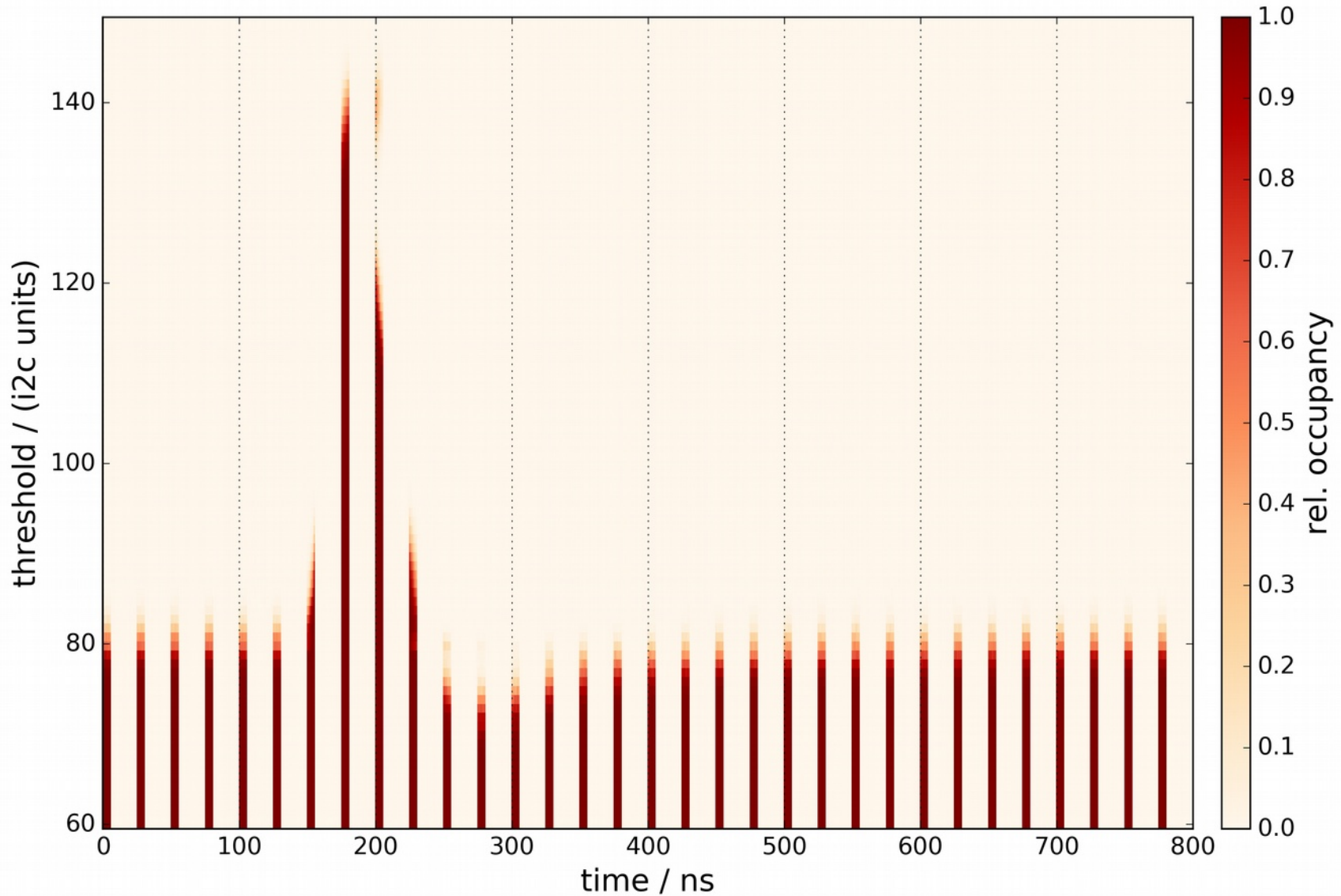


- inject many test-pulses and read frames of 32 consecutive events
- + threshold scan
- + variation of test-pulse release time (1ns steps)

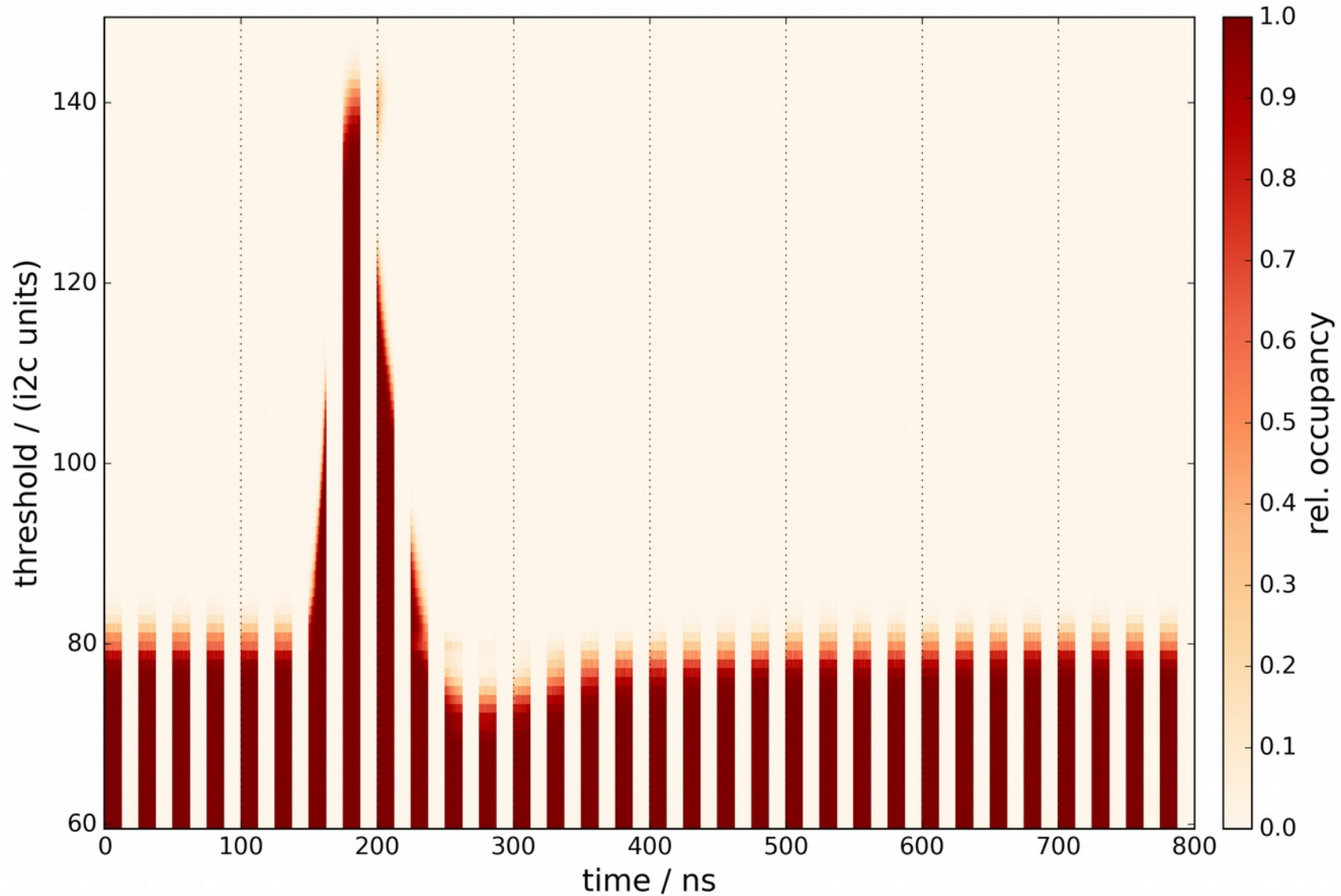




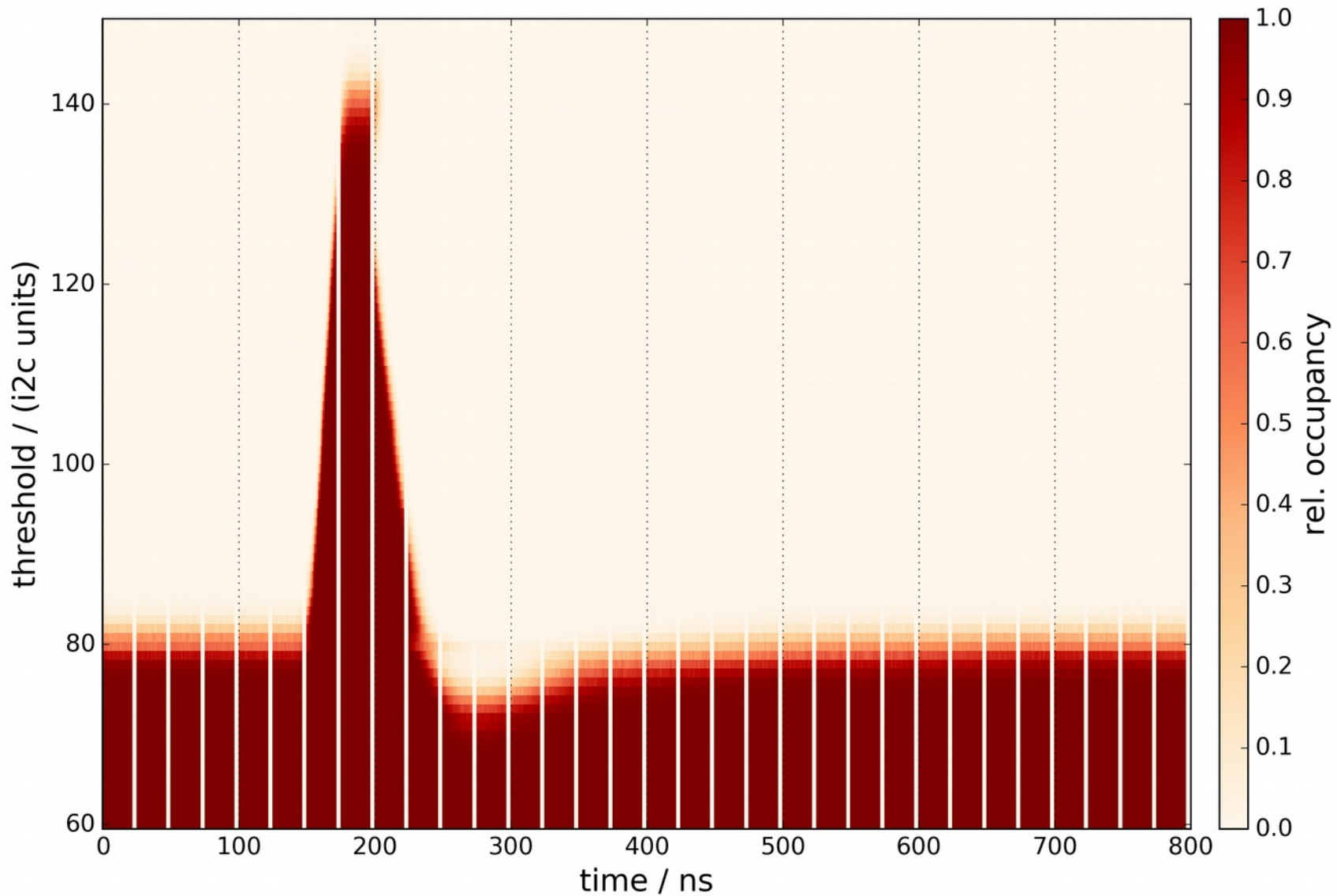
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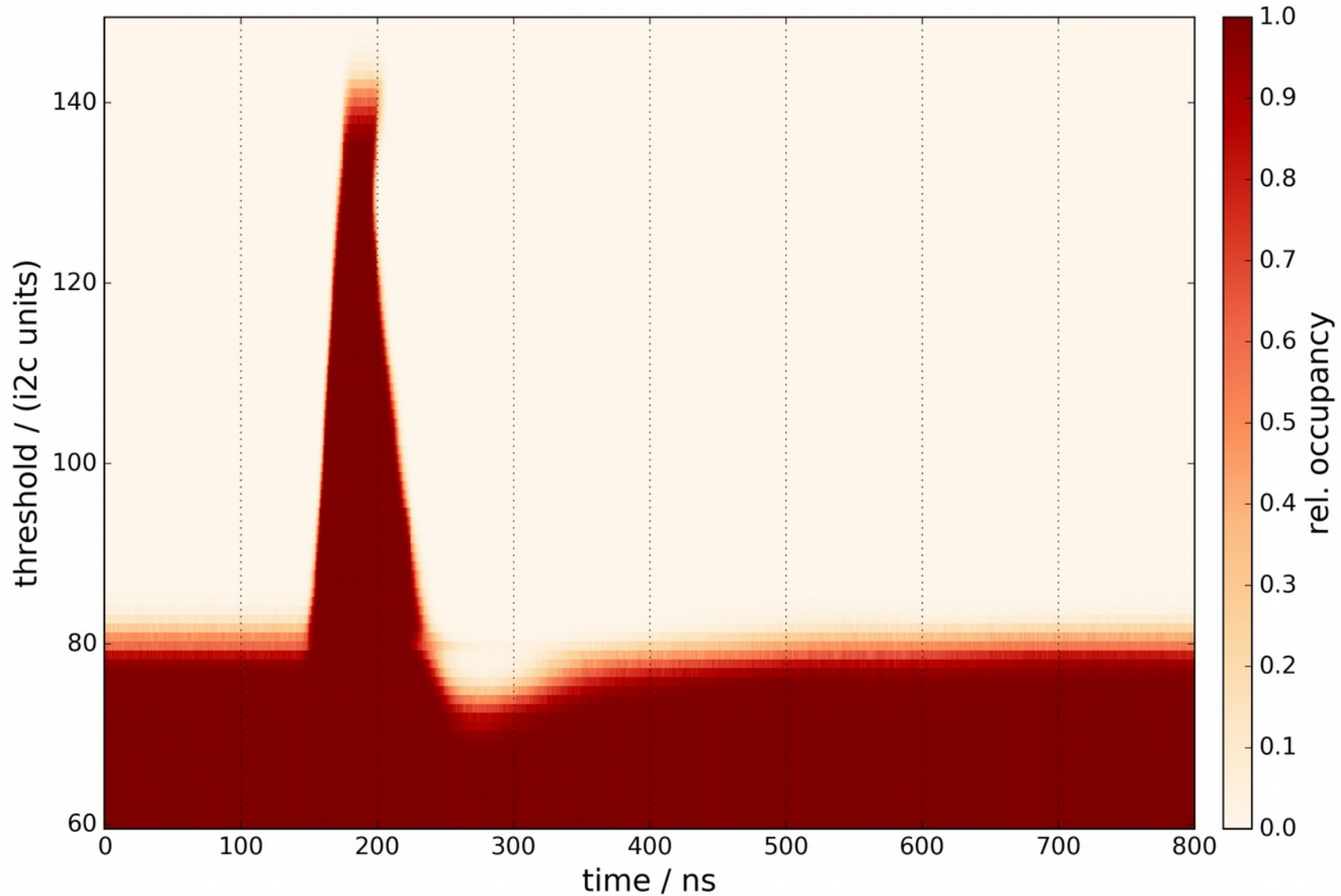
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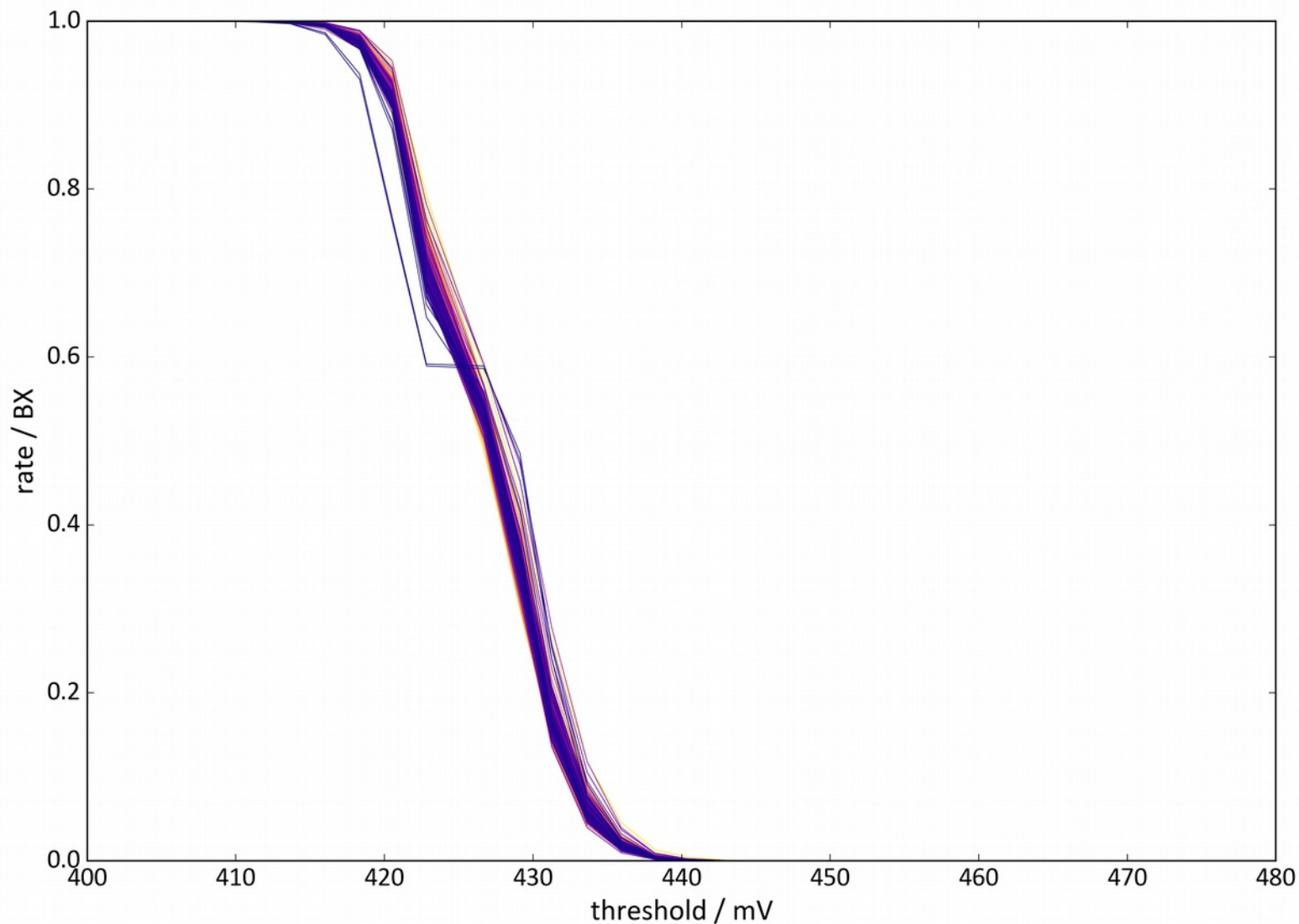


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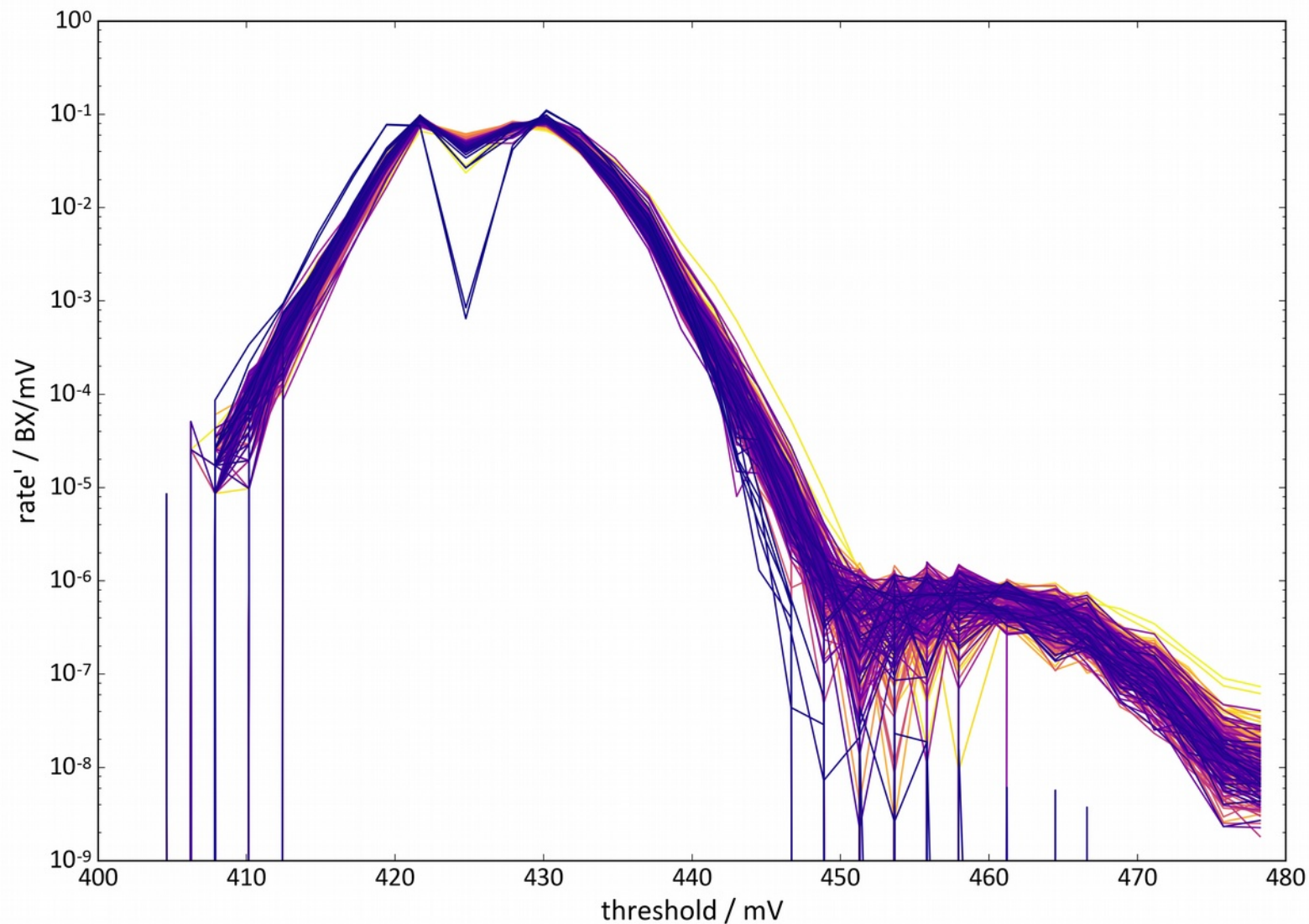


- inject many test-pulses and read frames of 32 consecutive events
  - + threshold scan
  - + variation of test-pulse release time (1ns steps)
- reconstruction of the pulse shape

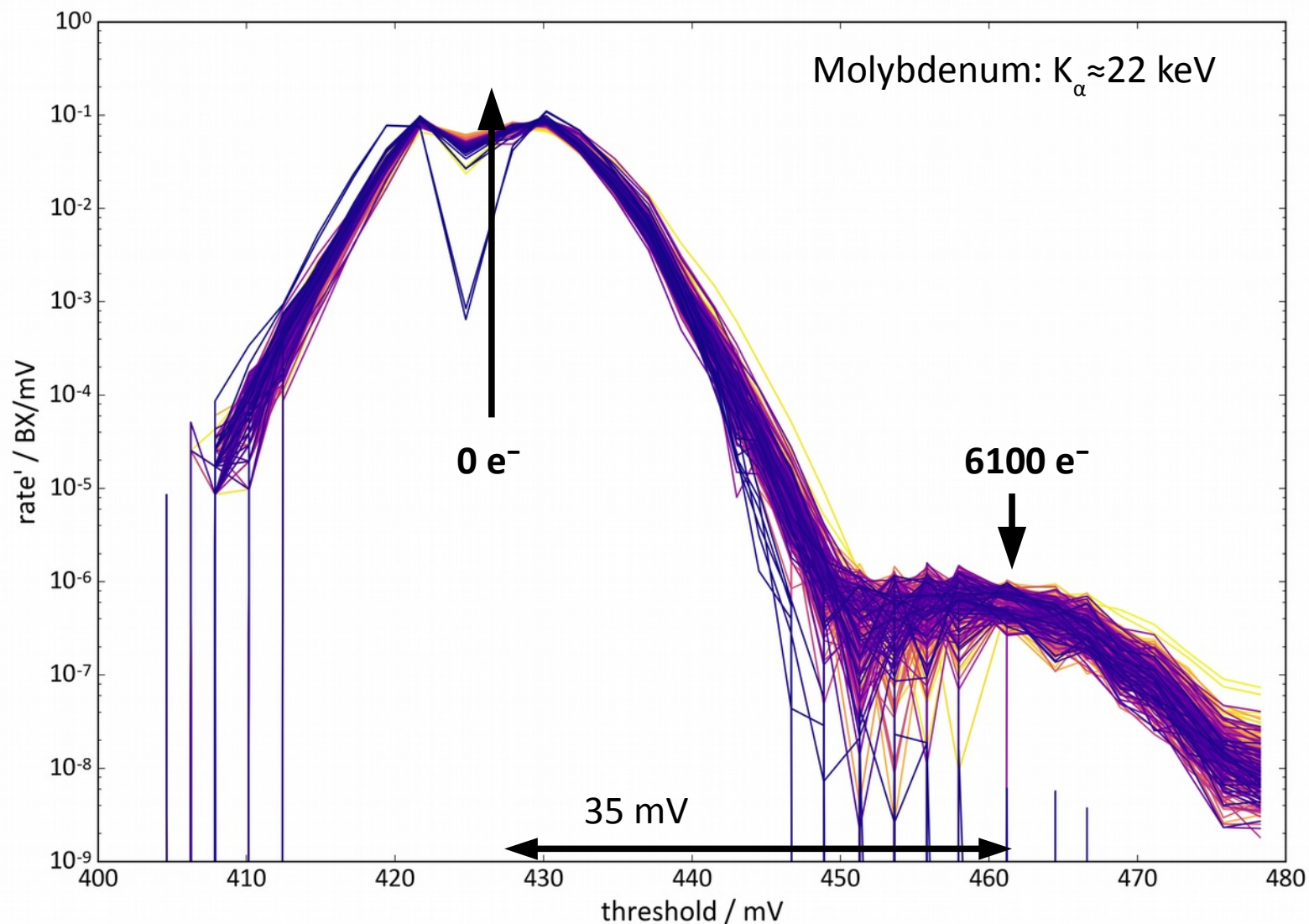
- until now no 'real' signal in the sensor (can do everything on a bare hybrid)
- x-rays in silicon: prop. of interaction of photon with silicon  
→ full photon energy is deposited in the silicon sensor (keV x-rays) →  $Q = E / 3.65 \text{ V}$



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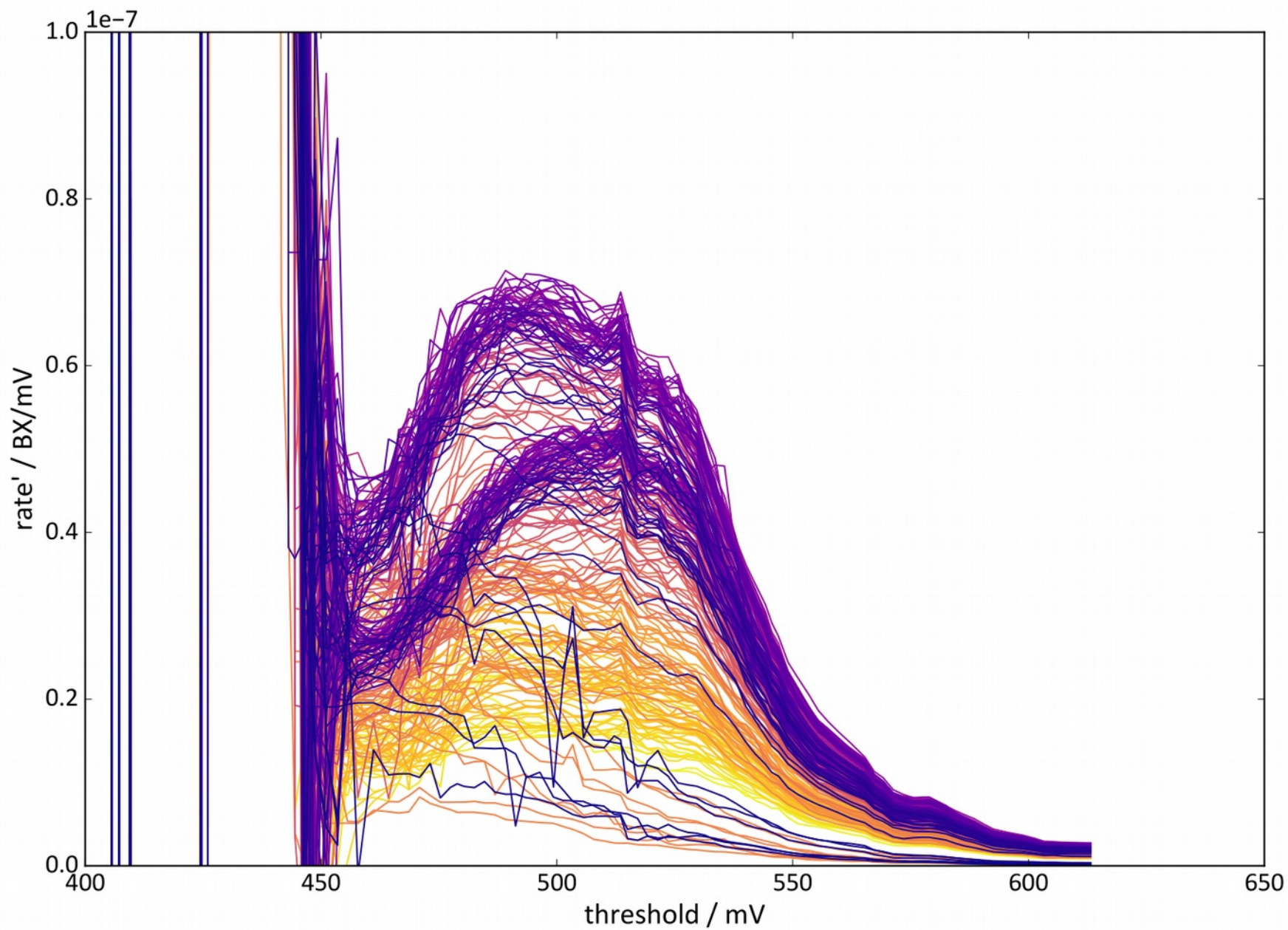


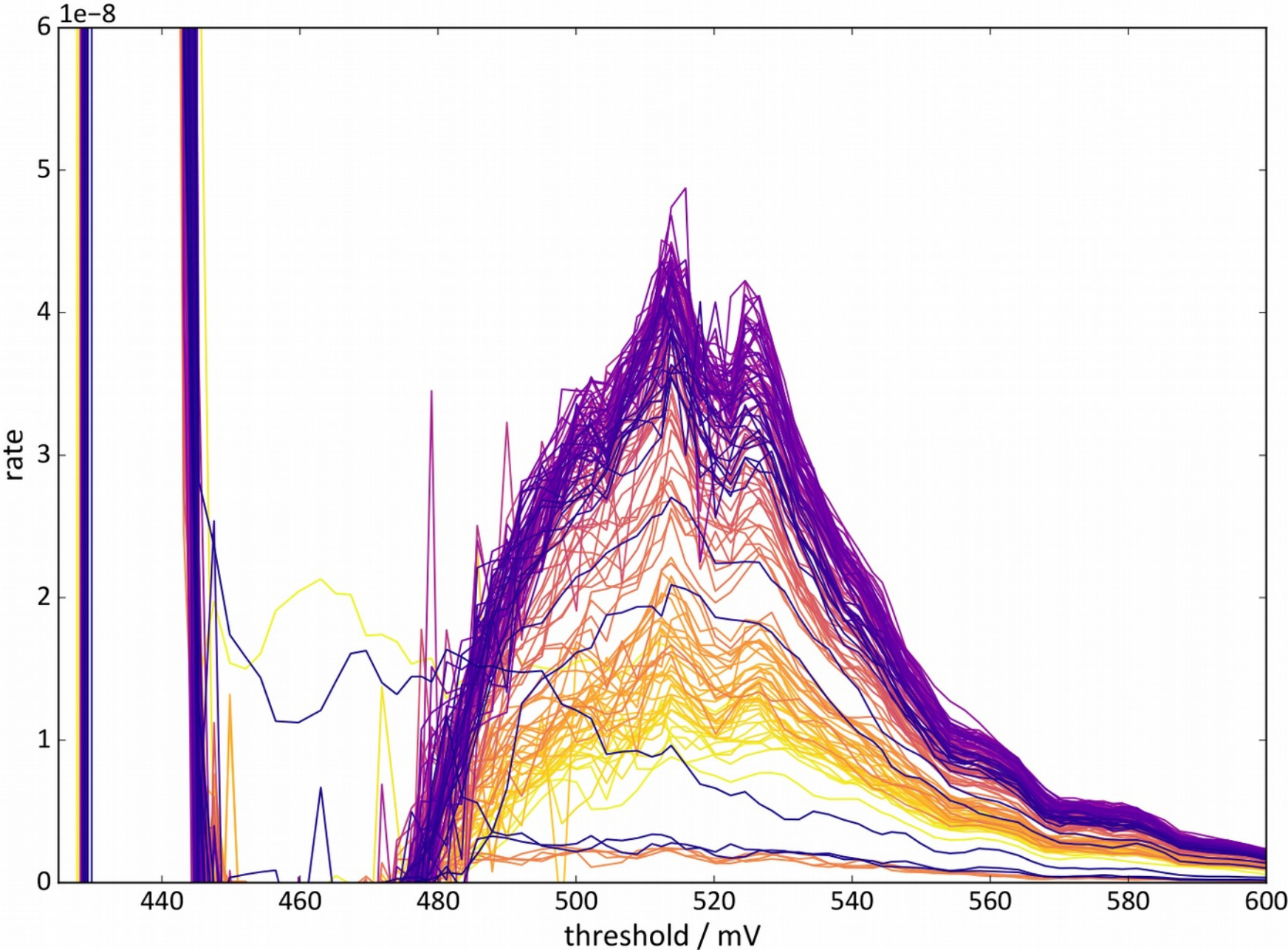
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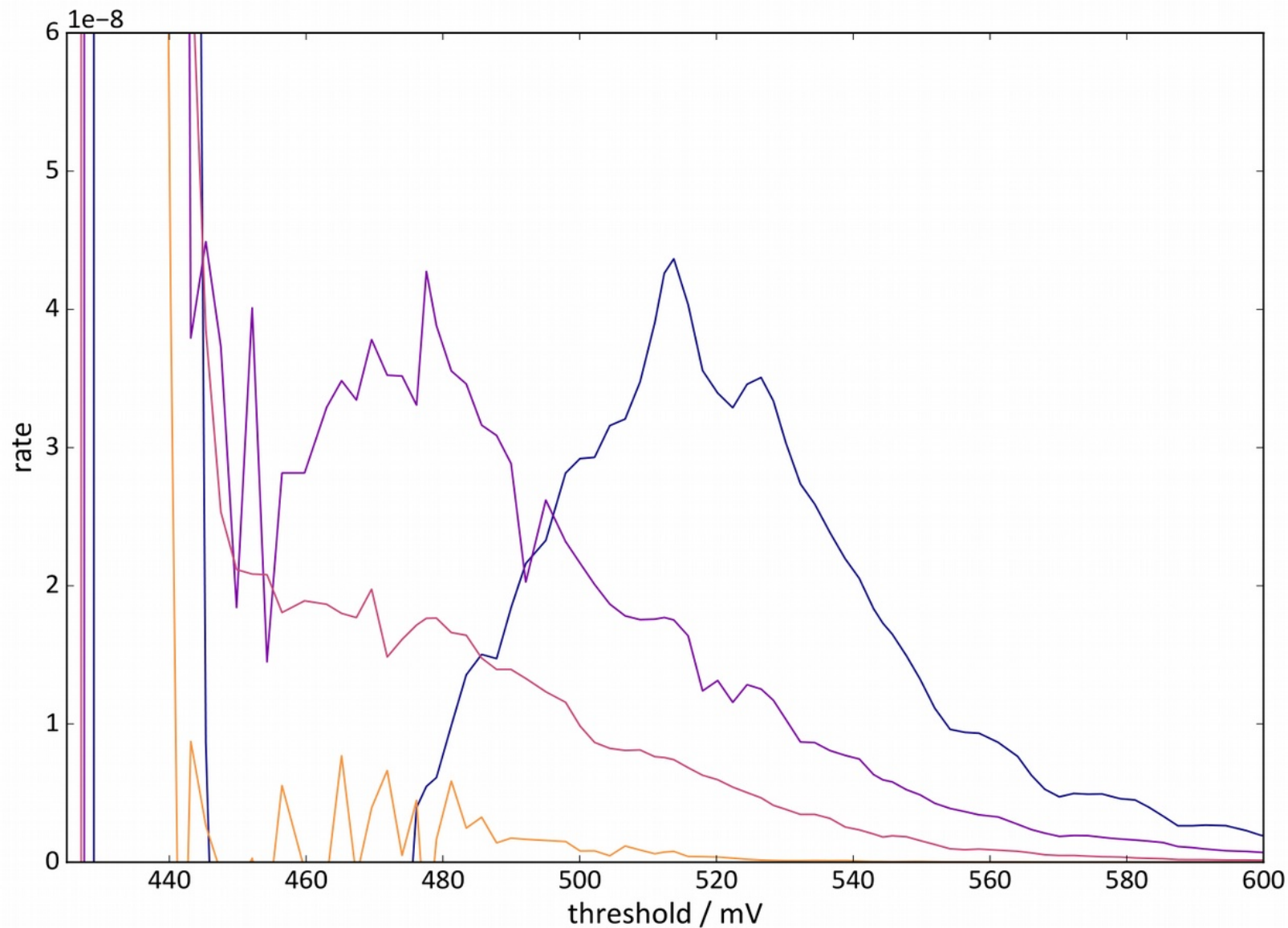


Gain  $\approx 6 \text{ ke}^{-} / 35 \text{ mV}$  → Noise  $\approx 4.5 \text{ mV} * 6 \text{ ke}^{-} / 35 \text{ mV} \approx 780 e^{-}$

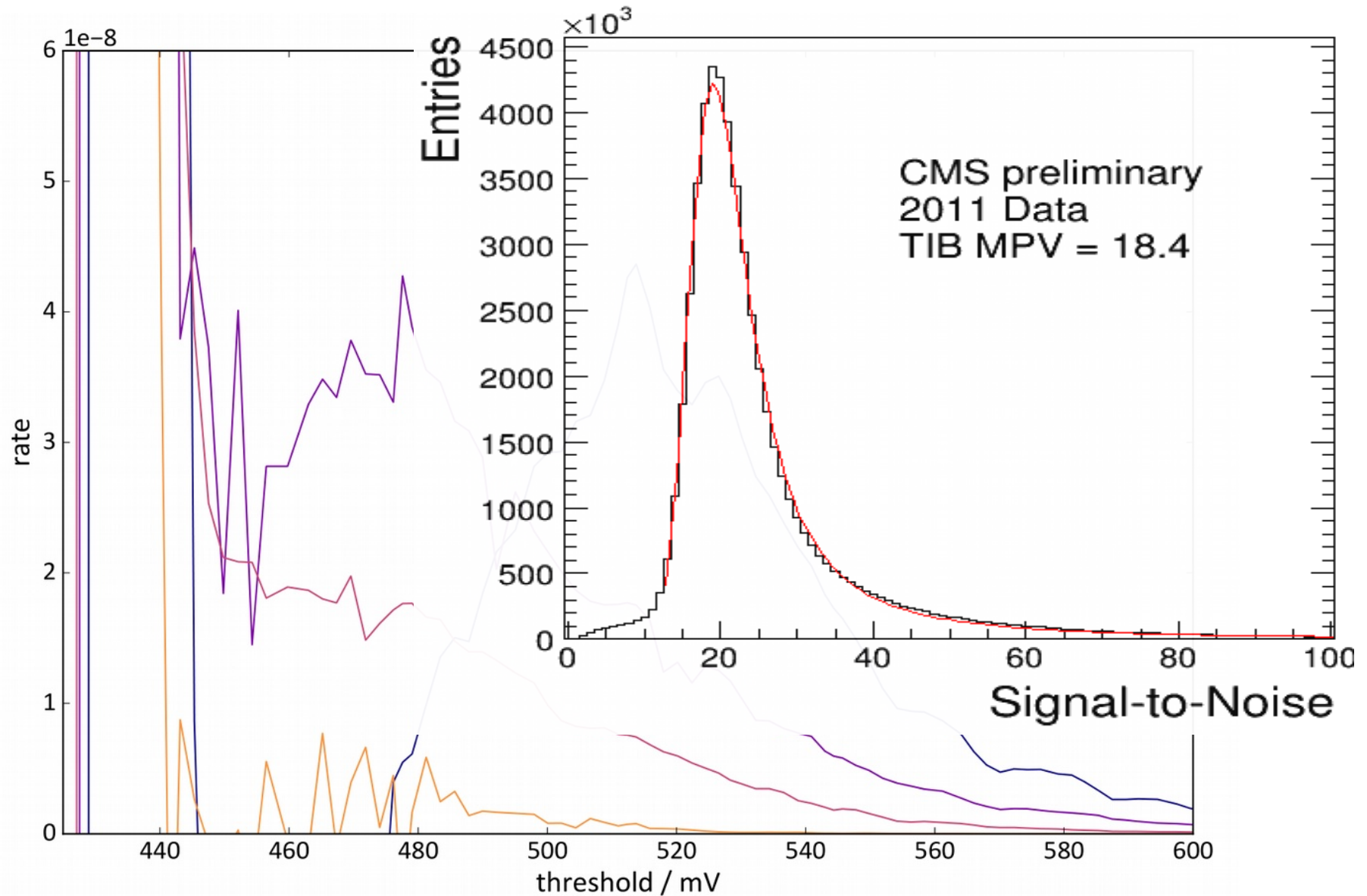








- signal height / MPV:  $100\text{mV} * 6 \text{ ke}^- / 35 \text{ mV} \approx 17 \text{ ke}^-$  (MIP  $300\mu\text{m Si} \sim 22\text{ke}^-$ )



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- ideas / references how to fully reconstruct the expected landau-distribution are most welcome!

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Backup