

Theoretical uncertainties: selected issues

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1. Types of uncertainties
2. Perturbation theory and beyond
3. Uncertainties in parton density fits
4. Summary

Different sources of theoretical uncertainties

“observable = theoretical expression”

1. theoretical expression is only approximate
often obtained by expansion in small parameter
 \rightsquigarrow estimate size of uncalculated/neglected terms
2. input parameters from standard model:
 α_s , $m_{c,b}$, m_t , $m_{W,Z}$, m_H , CKM matrix elements
note: running $\alpha_s(\mu)$ depends implicitly on quark masses
3. nonperturbative QCD parameters or functions, e.g.
parton densities, fragmentation functions,
decay constants, wave functions (e.g. for $B \rightarrow D\ell\nu$, $B \rightarrow \pi K$)
note: PDFs and fragmentation fcts. depend on $\alpha_s(\mu)$ via evolution

quantities in 2., 3. may be obtained from

- comparison “measured observable = theor. expression”
- nonperturbative calculation (e.g. lattice)

Higher orders, power corrections, and all that
 observables in high-energy collisions typically evaluated from
 factorization formula*, e.g.

$$\frac{d\sigma}{d(\text{variables})} = \frac{1}{Q^n} \text{PDF}(\mu_F, \alpha_s(\mu_F)) \otimes_x C\left(\frac{\mu_F}{Q}, \frac{\mu_R}{Q}, \alpha_s(\mu_R), \dots\right) \\ + \mathcal{O}\left(\frac{1}{Q^{n+1}} \text{ or } \frac{1}{Q^{n+2}}\right)$$

- ▶ Q = hard momentum scale x = scaling variable
- ▶ convolution $f \otimes_x g = \int_x^1 \frac{dz}{z} f\left(\frac{x}{z}\right) g(z)$
- ▶ in $C(\dots)$ possible dependence on $m_t, m_{W,Z}, m_H$ etc.
- ▶ now discuss in turn:
 - higher-order corrections (1st line)
 - power corrections (2nd line)

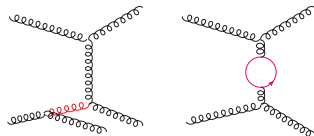
* in some rare cases have factorization theorems

Higher orders

$$\frac{d\sigma}{d(\text{variables})} = \frac{1}{Q^n} \text{PDF}(\mu_F, \alpha_s(\mu_F)) \otimes_x C\left(\frac{\mu_F}{Q}, \frac{\mu_R}{Q}, \alpha_s(\mu_R), \dots\right) + \mathcal{O}(\dots)$$

- ▶ have α_s expansions for C and for $\frac{d}{d\mu_F} \text{PDF}$

- ▶ in hard scattering
 - $\mu_R \leftrightarrow$ UV divergences
 - $\mu_F \leftrightarrow$ collinear divergences
 may keep separate



- ▶ in general **not** inconsistent to take different orders in α_s expansion of C and of PDF evolution
 overall accuracy is of course given by least accurate term
 usefulness to be discussed case by case
- ▶ analogous comment for order in C and in running of α_s

Renormalization scale dependence

on next slides write μ instead of μ_R for brevity

- ▶ renormalization group equation

$$\frac{d}{d \log \mu^2} \alpha_s(\mu) = \beta(\alpha_s(\mu))$$

$$\text{with } \beta(\alpha_s) = -\alpha_s^2 (b_0^{n_f} + b_1^{n_f} \alpha_s + b_2^{n_f} \alpha_s^2 + b_3^{n_f} \alpha_s^3 + \dots)$$

- ▶ in practice truncate series of $\beta(\alpha_s)$ and solve RGE numerically or by expansion of $\alpha_s(\mu)$ in $\frac{1}{\log(\mu^2/\Lambda_{\text{QCD}}^2)}$
- ▶ higher-coefficients in α_s expansion of hard-scattering coefficient are μ dependent

$$C = \alpha_s^m(\mu) C_0 + \alpha_s^{m+1}(\mu) C_1\left(\frac{Q}{\mu}\right) + \alpha_s^{m+2}(\mu) C_2\left(\frac{Q}{\mu}\right) + \dots$$

but C independent of μ to any given accuracy in α_s :

$$\frac{d}{d \log \mu^2} C(\mu) = 0$$

see how this works:

- set $\mu = Q$ in expansion:

$$\begin{aligned} C &= \alpha_s^m(\mu) C_0 + \alpha_s^{m+1}(\mu) C_1\left(\frac{Q}{\mu}\right) + \alpha_s^{m+2}(\mu) C_2\left(\frac{Q}{\mu}\right) + \dots \\ &= \alpha_s^m(Q) C_0 + \alpha_s^{m+1}(Q) C_1(1) + \alpha_s^{m+2}(Q) C_2(1) + \dots \end{aligned}$$

- expand $\alpha_s(Q) = \alpha_s(\mu) + a_1\left(\frac{Q}{\mu}\right) \alpha_s^2(\mu) + a_2\left(\frac{Q}{\mu}\right) \alpha_s^3(\mu) + \mathcal{O}(\alpha_s^4)$

$$\begin{aligned} \frac{d}{d \log Q^2} (\text{l.h.s.}) &= \beta(\alpha_s(Q)) = -b_0 \alpha_s^2(Q) - b_1 \alpha_s^3(Q) + \mathcal{O}(\alpha_s^4) \\ &= -b_0 \alpha_s^2(\mu) - 2a_1 b_0 \alpha_s^3(\mu) - b_1 \alpha_s^3(\mu) + \mathcal{O}(\alpha_s^4) \\ \frac{d}{d \log Q^2} (\text{r.h.s.}) &= \frac{da_1}{d \log Q^2} \alpha_s^2(\mu) + \frac{da_2}{d \log Q^2} \alpha_s^3(\mu) + \mathcal{O}(\alpha_s^4) \end{aligned}$$

- compare coefficients of $\alpha_s^n(\mu)$:

$$\begin{aligned} \frac{da_1}{d \log Q^2} &= -b_0 \quad \Rightarrow \quad a_1\left(\frac{Q}{\mu}\right) = -b_0 \log \frac{Q^2}{\mu^2} \\ \frac{da_2}{d \log Q^2} &= -2a_1 b_0 - b_1 \quad \Rightarrow \quad a_2\left(\frac{Q}{\mu}\right) = +b_0^2 \log^2 \frac{Q^2}{\mu^2} - b_1 \log \frac{Q^2}{\mu^2} \end{aligned}$$

► inserting

$$\alpha_s(Q) = \alpha_s(\mu) \left[1 - \alpha_s(\mu) b_0 \log \frac{Q^2}{\mu^2} + \alpha_s^2(\mu) \left(b_0^2 \log^2 \frac{Q^2}{\mu^2} - b_1 \log \frac{Q^2}{\mu^2} \right) + \dots \right]$$

into $C = \alpha_s^m(Q) \left[C_0 + \alpha_s(Q) C_1(1) + \alpha_s^2(Q) C_2(1) + \dots \right]$ get

$$\begin{aligned} C &= \alpha_s^m(\mu) \\ &\times \left[1 - \alpha_s(\mu) m b_0 \log \frac{Q^2}{\mu^2} + \alpha_s^2(\mu) \left(\frac{m(m+1)}{2} b_0^2 \log^2 \frac{Q^2}{\mu^2} - m b_1 \log \frac{Q^2}{\mu^2} \right) \right] \\ &\times \left[C_0 + \alpha_s(\mu) C_1(1) + \alpha_s^2(\mu) \left(C_2(1) - C_1(1) b_0 \log \frac{Q^2}{\mu^2} \right) \right] + \mathcal{O}(\alpha_s^{m+3}) \end{aligned}$$

► in $C = \alpha_s^m(\mu) C_0 + \alpha_s^{m+1}(\mu) C_1\left(\frac{Q}{\mu}\right) + \alpha_s^{m+2}(\mu) C_2\left(\frac{Q}{\mu}\right) + \dots$
have coefficients

$$C_1\left(\frac{Q}{\mu}\right) = C_1(1) - m b_0 C_0 \log \frac{Q^2}{\mu^2}$$

$$C_2\left(\frac{Q}{\mu}\right) = C_2(1) - \left[(m+1) b_0 C_1(1) + m b_1 C_0 \right] \log \frac{Q^2}{\mu^2} + \frac{m(m+1)}{2} b_0^2 C_0 \log^2 \frac{Q^2}{\mu^2}$$

► check (exercise): $\frac{d}{d \log \mu^2} C\left(\frac{Q}{\mu}, \alpha_s(\mu)\right) = \left[\frac{\partial}{\partial \log \mu^2} + \beta \frac{\partial}{\partial \alpha_s} \right] C = 0$

► have

$$C = \alpha_s^m(\mu) C_0 + \alpha_s^{m+1}(\mu) C_1\left(\frac{Q}{\mu}\right) + \alpha_s^{m+2}(\mu) C_2\left(\frac{Q}{\mu}\right) + \dots$$

with

$$C_1\left(\frac{Q}{\mu}\right) = C_1(1) - mb_0 C_0 \log \frac{Q^2}{\mu^2}$$

$$C_2\left(\frac{Q}{\mu}\right) = C_2(1) - \left[(m+1)b_0 C_1(1) + mb_1 C_0\right] \log \frac{Q^2}{\mu^2} + \frac{m(m+1)}{2} b_0^2 C_0 \log^2 \frac{Q^2}{\mu^2}$$

- calculating C_0 (LO) get also terms $\alpha_s^{m+1} \log \frac{Q^2}{\mu^2}, \alpha_s^{m+2} \log^2 \frac{Q^2}{\mu^2}, \dots$
 calculating $C_1(1)$ (NLO) get also terms $\alpha_s^{m+2} \log \frac{Q^2}{\mu^2}, \alpha_s^{m+3} \log^2 \frac{Q^2}{\mu^2}, \dots$
 \rightsquigarrow recover logarithmic terms at higher orders, but **not** coefficients $C_n(1)$

- varying μ in N^l LO result get variation at N^{l+1} LO corresponding to

$$\alpha_s^{l+1} \sum_{i=1}^{l+1} (\text{known coefficient}) \times \log^i \frac{\mu^2}{Q^2} + \mathcal{O}(\alpha_s^{l+2})$$

but **no** information on $\alpha_s^{l+1} C_{l+1}(1)$

Renormalization scale dependence

- ▶ varying μ in N^l LO result get variation at N^{l+1} LO corresponding to

$$\alpha_s^{l+1} \sum_{i=1}^{l+1} (\text{known coefficient}) \times \log^i \frac{\mu^2}{Q^2} + \mathcal{O}(\alpha_s^{l+2})$$

but **no** information on $\alpha_s^{l+1} C_{l+1}(1)$

consequences:

- ▶ when calculate higher orders, expect that **scale dependence** decreases
- ▶ **scale variation** in N^l LO result estimates size of certain higher-order terms, but **not** of all
 - ▶ uncalculated higher orders often estimated by varying μ between 1/2 and 2 times some central value
is a conventional choice
 - ▶ but what to take for central value?

Renormalization scale choice

- ▶ prescriptions for **scale choice** aiming to minimizing size of higher-order terms

take NLO calc. of $C(\mu) = \alpha_s^m C_0 + \alpha_s^{m+1} C_1(\mu) + \mathcal{O}(\alpha_s^{m+2})$

- ▶ μ = typical virtuality in hard-scattering graphs
useful guidance, but obviously not a well-defined quantity
- ▶ fastest apparent convergence (FAC): $\frac{d}{d\mu^2} \sum_{i=0}^1 \alpha_s^{m+i} C_i(\mu) = 0$
- ▶ principle of minimal sensitivity (PMS): $C_1(\mu) = 0$
- ▶ Brodsky-Mackenzie-Lepage (BLM): $C_1(\mu)$ independent of n_f
recall: coefficients b_0, b_1, \dots of β function depend on n_f
- ▶ how much these reduce higher orders depends on process
cannot “predict” higher orders without calculating them

Factorization scale dependence

- ▶ scale dependence of PDF given by DGLAP equation:

$$\frac{d}{d \log \mu_F^2} \text{PDF}(x, \mu_F) = \text{PDF}(\mu_F) \otimes_x P(\alpha_s(\mu_F))$$

evolution kernels have perturbative expansion in α_s :

$$P(z, \alpha_s(\mu_F)) = \alpha_s(\mu_F) P_0(z) + \alpha_s^2(\mu_F) P_1(z) + \mathcal{O}(\alpha_s^3)$$

- choose approx. of evolution kernel (LO, NLO, NNLO)
- solve DGLAP equations numerically
 \Rightarrow obtain $\text{PDF}(\mu_1)$ from $\text{PDF}(\mu_0)$

- ▶ hard-scattering coefficient contains powers of $\log(\mu_F/Q)$
 μ_F independence of $\text{PDF}(\mu_F) \otimes C(\mu_F)$ implies

$$\frac{d}{d \log \mu_F^2} C(x, \mu_F, \mu_R, \alpha_s(\mu_R)) = -P(\alpha_s(\mu_F)) \otimes_x C(\mu_F, \mu_R, \alpha_s(\mu_R))$$

Factorization scale dependence

$$\frac{d}{d \log \mu_F^2} C(x, \mu_F, \alpha_s(\mu_R), \dots) = -P(\alpha_s(\mu_F)) \otimes_x C(\mu_F, \mu_R, \alpha_s(\mu_R))$$

using renormalization group equation can rewrite

$$\alpha_s(\mu_R) = \alpha_s(\mu_F) + \sum_{i>1} c_i(\mu_R/\mu_F) \alpha_s^i(\mu_F)$$

with expansions

$$C(\mu_F, \alpha_s(\mu_F), \mu_R) = C_0(\mu_R) + \alpha_s(\mu_F) C_1(\mu_F, \mu_R) + \mathcal{O}(\alpha_s^2)$$

$$P(\alpha_s(\mu_F)) = \alpha_s(\mu_F) P_0 + \alpha_s^2(\mu_F) P_1 + \mathcal{O}(\alpha_s^3)$$

can match coefficients order by order

$$\Rightarrow C_1(\mu_F, \mu_R) = C_1(Q, \mu_R) - C_0(\mu_R) \otimes P_0 \log \frac{\mu_F^2}{Q^2} \quad \text{etc.}$$

Factorization scale dependence

- ▶ try to chose μ_F such as to avoid large higher-order coefficients
- ▶ with C calculated to $N^l\text{LO}$ have μ_F dependence of order $N^{l+1}\text{LO}$ in convolution $\text{PDF} \otimes C$
 - if evolve PDFs with DGLAP kernels up to $\alpha_s^l P_{l-1}$ or higher
- ▶ as for μ_R may estimate certain higher-order terms by varying μ_F between e.g. 1/2 and 2 times some central value
- ▶ as for μ_R no general solution for finding μ_F that minimizes higher orders

Multi-scale problems

- ▶ scale choice even less obvious when have several hard scales
e.g. Q and p_T , Q and m_c , p_T and m_W , ...
may try to identify typical virtualities in graphs
- ▶ for small/large ratios of hard scales
(or small/large values of scaling variables, e.g. $x \rightarrow 0$ or $x \rightarrow 1$)
then have large logarithms in C for any choice of μ_R, μ_F

Multi-scale problems

- ▶ for certain cases can resum large logarithms to all orders

e.g. $\alpha_s^n \log^{n+i}$ for all n with given $i = 0, 1, \dots$

- ▶ transverse-momentum logs: $\log \frac{p_T}{Q} \rightsquigarrow$ Sudakov factors

- ▶ threshold logs: $\log \frac{M^2}{\hat{s}}$

for production of mass M with partonic collision energy $\sqrt{\hat{s}}$

$$\sigma(ep) \sim \int dz \text{PDF}(z) C(\hat{s} = zW^2)$$

$$\sigma(pp) \sim \int dz_1 dz_2 \text{PDF}(z_1) \text{PDF}(z_2) C(\hat{s} = z_1 z_2 s)$$

- ▶ high-energy logs: $\log \frac{1}{x} \rightsquigarrow$ BFKL logs

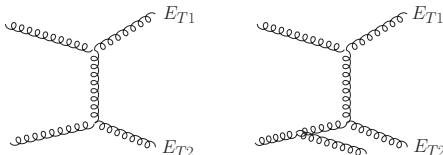
- resummation procedure may have its own uncertainties

e.g. from integrals of type $\int_0^Q d\mu f(\alpha_s(\mu)) \rightsquigarrow$ Landau pole



LO, NLO, and higher

- ▶ instead of varying scale(s) may estimate higher orders by comparing $N^l\text{LO}$ result with $N^{l-1}\text{LO}$
 - ▶ caveat: comparison NLO vs. LO may not be representative for situation at higher orders
- often have especially large step from LO to NLO
- ▶ certain types of contribution may first appear at NLO
e.g. terms with gluon density $g(x)$ in DIS, $pp \rightarrow W + X$, etc.
 - ▶ final state at LO may be too restrictive
e.g. in inclusive DIS
or in $\frac{d\sigma}{dE_{T1} dE_{T2}}$ for dijet production



Power corrections

- ▶ for certain observables (typically those for which have operator product expansion) can identify and estimate size of power-suppressed terms
- ▶ example: τ decay ($\mu_R = m_\tau$)

$$R_\tau = \frac{\Gamma(\tau \rightarrow \nu_\tau + \text{hadrons})}{\Gamma(\tau \rightarrow \nu_\tau + e \nu_e)} = R_0 \left[1 + \frac{\alpha_s}{\pi} + 5.2 \frac{\alpha_s^2}{\pi^2} + 26.4 \frac{\alpha_s^3}{\pi^3} + c_2 \frac{m_q^2}{m_\tau^2} + c_4 \frac{\langle m \bar{\psi} \psi \rangle}{m_\tau^4} + c_6 \frac{\langle \bar{\psi} \psi \bar{\psi} \psi \rangle}{m_\tau^6} \right]$$

with (schematically) m_q^2 = combination of squared light quark masses
 $\langle m \bar{\psi} \psi \rangle, \langle \bar{\psi} \psi \bar{\psi} \psi \rangle$ = expectation values of quark operators in vacuum

used for determination of $\alpha_s(m_\tau)$

see PDG 2008, sect. 9

Power corrections

- ▶ for certain observables (typically those for which have operator product expansion) can identify and estimate size of power-suppressed terms
- ▶ example: sum rules for deep inelastic structure functions

Bjorken sum rule for polarized str. fcts.

($\mu_R = Q$)

$$\int_0^1 dx (g_1^p(x, Q^2) - g_1^n(x, Q^2)) = \frac{g_A}{6} \left[1 - \frac{\alpha_s}{\pi} - 3.58 \frac{\alpha_s^2}{\pi^2} - 20.32 \frac{\alpha_s^3}{\pi^3} \right] + \frac{\langle t \rangle}{Q^2} - \frac{2m_N^2}{9Q^2} \int_0^1 dx x^2 (g_1^p(x, Q^2) - g_1^n(x, Q^2))$$

$\langle t \rangle$ = defined from expectation values of $\bar{\psi} G_{\mu\nu} \gamma_\lambda \psi$ between nucleon states

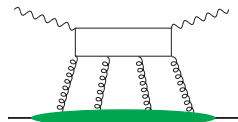
Power corrections

- ▶ for factorization formulae of type

$$\frac{d\sigma}{d(\text{variables})} = \frac{1}{Q^n} \text{PDF}(\mu_F, \alpha_s(\mu_F)) \otimes_x C\left(\frac{\mu_F}{Q}, \frac{\mu_R}{Q}, \alpha_s(\mu_R), \dots\right) + \mathcal{O}\left(\frac{1}{Q^{n+1}} \text{ or } \frac{1}{Q^{n+2}}\right)$$

in general have **no** theoretical expression for power corrections

- ▶ exceptions: inclusive DIS **and γ^* , W or Z production in pp**
hardly used: too many unknown non-perturbative functions

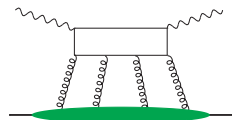




Power corrections

special case: very small x

- ▶ exchange of 4 **transverse** gluons
suppressed by $\frac{1}{Q^2}$ relative to 2 gluons
- ▶ but has steeper growth with energy
- ▶ at given Q^2 will eventually dominate as x decreases
 \rightsquigarrow change theoretical framework: BFKL, color dipoles,
parton saturation
- ▶ primary expansion parameter is not $\frac{1}{Q^2}$ but x
full BFKL contains more than $\log \frac{1}{x}$ resummation at leading twist
- ▶ in perturbative accuracy (**no full NLO for DIS yet**) can presently
not compete with collinear factorization
but allows estimate of power suppressed terms



Jet production

- ▶ fundamental problem: factorization formulae are for prod'n of high- p_T **partons**, not high- p_T **hadrons**
 note: due to collinear and soft radiation “momentum of final-state parton” is only defined at LO
- ▶ if apply jet algorithm to partons in theory formula and to hadrons in measurement
 \rightsquigarrow kinematical ambiguities: energy vs. momentum
 (light quarks and gluons taken as massless, hadrons are not)
- ▶ event generators **model** the parton \rightarrow hadron transition
 uncertainty of “hadronization corrections” typically determined by comparing different models
- ▶ may instead use fragmentation functions (theory \sim for PDFs)
 if measure individual hadrons
 e.g. $\gamma^* p \rightarrow D^* + X$ instead of $\gamma^* p \rightarrow c + X$

Parton density fits

Principle of PDF determinations:

- ▶ compare data with factorization formulae for selected processes and kinematics
- ▶ specify PDF at reference scale Q_0
use DGLAP to evolve to scales used in fact. formulae

e.g. CTEQ : $Q_0 = 1.3 \text{ GeV}$ use data with $Q > 2 \text{ GeV}$

MSTW : $Q_0 = 1 \text{ GeV}$ use data with $Q > 1.4 \text{ GeV}$

- ▶ conventional determinations parameterize PDFs at Q_0 and determine parameters by χ^2 fit to data

NNPDF collab. uses neural networks, avoids choice of function claims “unbiased” representation of PDFs

however, theoretical bias regarding shape and smoothness of PDFs
is not illicit

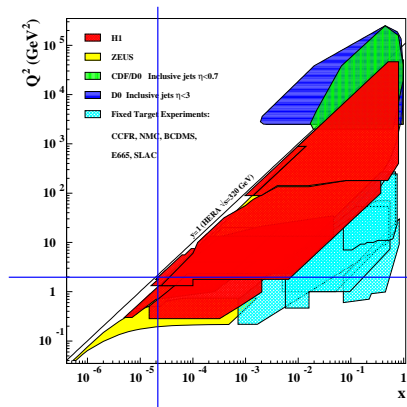


Evolution

$$\frac{d}{d \log \mu_F^2} \text{PDF}(x, \mu_F) = \int_x^1 \frac{dz}{z} \text{PDF}(z, \mu_F) P\left(\frac{x}{z}\right)$$

\Rightarrow specifying $\text{PDF}(x, \mu_F)$ for **all** $x > x_0$ at **one** μ_F
fixes PDF for $x > x_0$ at **all** other μ_F

- ▶ **no** inform'n about PDFs at $x < x_0$ without data at $x < x_0$
- ▶ indirect inform'n about PDFs at large x via convolution integrals



Uncertainties on extracted PDFs

- ▶ selection of data sets and kinematics
- ▶ perturbative order of evolution and hard-scattering coefficients
- ▶ values of α_s and m_c, m_b and possibly other constants
if taken as external parameters i.e. not fitted
some PDF sets available for different values of α_s
- ▶ fine details of perturbative calculations
e.g. treatment of heavy quarks, resummation
- ▶ power corrections (typically try to avoid by minimal Q in data)
- ▶ corrections for data with nuclear targets

errors on fitted parameters

- ▶ reflect errors (stat. and syst.) of fitted data
discuss on the following slides

Parametric errors in PDF fits

see e.g. [hep-ph/0201195](#) (CTEQ6), [arXiv:0802.0007](#) (CTEQ6.6)

[arXiv:0901.0002](#) (MSTW 2008)

- errors obtained in χ^2 fit

$$\text{simplest version: } \chi^2 = \sum_i \frac{[D_i - T_i(\mathbf{p})]^2}{\sigma_{i,\text{stat}}^2 + \sigma_{i,\text{syst}}^2}$$

D_i = data point number i

T_i = corresponding theory prediction

$\mathbf{p} = \{p_1, \dots, p_k\}$ = set of fitting parameters

more sophisticated treatment for correlated systematic errors,
i.e. **overall normalization**

$$\chi^2 = \sum_i \frac{[D_i - T_i(\mathbf{p})]^2}{\sigma_{i,\text{stat}}^2 + \sigma_{i,\text{syst}}^2}$$

if assume that errors of D_i follow a **Gaussian** distribution, then

- ▶ fitted \mathbf{p} follow a k -dim. Gaussian dist. around true values \mathbf{p}_0
- ▶ have k -dim. χ^2 distribution for

$$\Delta\chi^2(\mathbf{p}) = \chi^2(\mathbf{p}) - \chi_{\min}^2 = \sum_{ij} (p - p_0)_i H_{ij} (p - p_0)_j$$

H = **Hesse matrix** = **inverse of covariance matrix** V

- ▶ observable $\mathcal{O}(\mathbf{p})$ follows Gaussian dist. with error

$$\Delta\mathcal{O} = T \sqrt{\sum_{ij} \frac{\partial\mathcal{O}}{\partial p_i} H_{ij}^{-1} \frac{\partial\mathcal{O}}{\partial p_j}}$$

with $T = 1$ for 68% C.L., $T = 2.71$ for 95% C.L. etc.

readily generalizes to several obs. and their correlated errors

\leadsto complicated in practice, would need derivatives $\partial\mathcal{O}/\partial p_i$

$$\Delta\mathcal{O} = T \sqrt{\sum_{ij} \frac{\partial\mathcal{O}}{\partial p_i} H_{ij}^{-1} \frac{\partial\mathcal{O}}{\partial p_j}}$$

- ▶ diagonalize Hesse matrix H and rescale eigenvectors
 \Rightarrow linear combinations z_i of $(p - p_0)_j$ satisfying

$$\Delta\chi^2 = \sum_i z_i^2$$

$$\Delta\mathcal{O} = T \sqrt{\sum_i \frac{\partial\mathcal{O}}{\partial z_i} \frac{\partial\mathcal{O}}{\partial z_i}} = \sqrt{\sum_i \left[\frac{\mathcal{O}(S_i^+) - \mathcal{O}(S_i^-)}{2} \right]^2}$$

with **eigenvector PDF sets** S_i^\pm

corresponding to parameters $z_i = \pm T$ and $z_j = 0$ for $j \neq i$

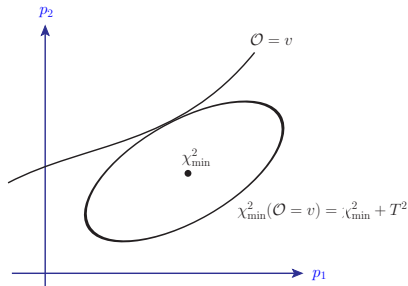
in last step have linearized \mathcal{O} around $z = 0$

- ▶ for large errors $\Delta\chi^2$ not quadratic in $(p - p_0)_i$ or z_i
 - \rightsquigarrow linear error propagation not reliable
 - \rightsquigarrow Legendre multiplier method



Legendre multiplier method

- ▶ minimize $\chi^2(\mathbf{p})$ with constraint $\mathcal{O} = v$ uses Legendre mult.
- ▶ determine values v with $\chi_{\min}^2(\mathcal{O} = v) = \chi_{\min}^2 + T^2$
min/max of $v - \mathcal{O}_{\chi_{\min}^2}$ gives lower/upper error on \mathcal{O}
- ▶ equiv. to Hesse method if χ^2 quadratic and \mathcal{O} linear in \mathbf{p}
- ▶ requires separate fits for each considered observable \mathcal{O}



The tolerance criterion

- ▶ if data points D_i follow Gaussian dist.
then for experiment with N_j data points
expect contribution $\chi_{j,\min}^2 \sim N_j$ to global χ_{\min}^2
- ▶ often not seen in practice: for some cases
 - ▶ $\chi_{j,\min}^2$ significantly below or above N_j
 - ▶ $\chi_{j,\min}^2$ much larger than χ^2 minimized separately for experiment
 - ▶ get inconsistent errors on p when fitting subsets of data
 indicates that some data sets not consistent with each other
in such a case standard χ^2 errors misrepresent uncertainty
- ▶ modified criterion for T CTEQ: $T^2 \sim 100$, MSTW: $T^2 \approx 50$
 - ▶ obtained by procedure/algorithm looking at χ^2 from individual experiments
 - ▶ may be seen as ad hoc deviation from “standard statistics”
but “standard criterion” for T requires that all data points
have Gaussian dist. with quoted uncertainties

Summary

- ▶ estimating theoretical uncertainties \neq an exact science
- ▶ “scale uncertainty” based on renormalization group eq. estimates **certain** higher-order terms in α_s
prescriptions for scale choice = educated guesses
- ▶ higher-order terms **not** the only source of uncertainty
power corrections, hadronization corrections, ... more difficult to assess
- ▶ errors of PDF fits reflect uncertainties of fitted data
(**not a straightforward exercise in textbook statistics**)
do **not** include uncertainties of theory used to fit data