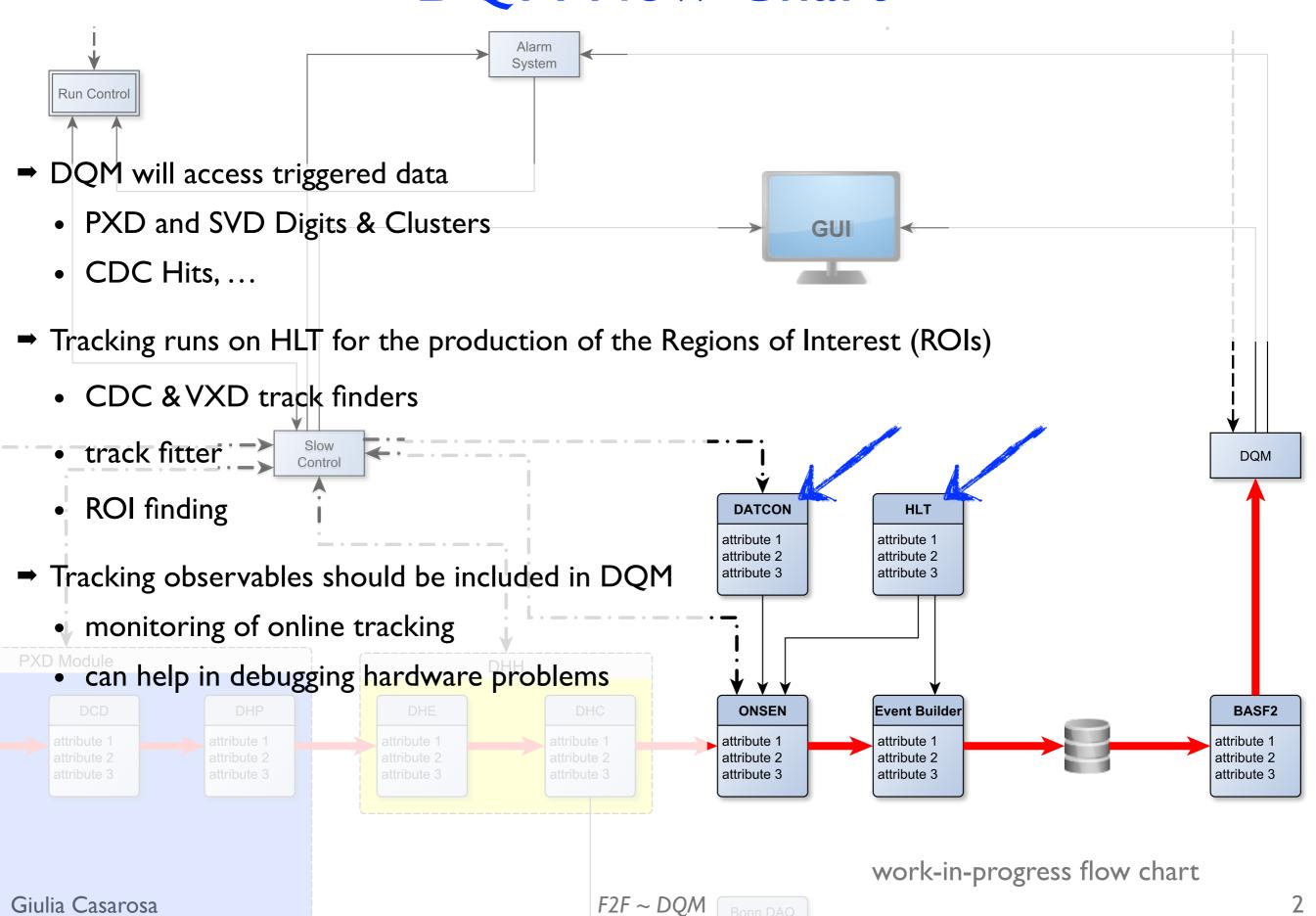
# DATA QUALITY MONITORING & TRACKING

### Giulia Casarosa

M. Hoek, B. Spruck, C. Sfienti



## DQM Flow Chart



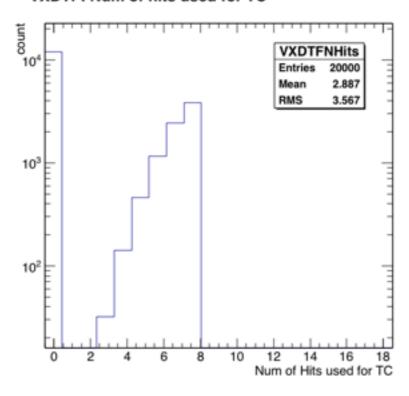
## existing DQM & future DQM

- → DQM Modules developed for the 2014 test beam
  - VXD Track Finder (8 histo)
  - Track Fitter (histo: 10 + 8 x VXD layer + 2 graph)
  - Intercepts (histo: I + 2I x PXD layer)
  - ROIs (histo:3 + 7 x PXD layer)
- → The DQM modules where developed with the idea that only the experts would have looked at them
  - many histograms, apparently all with the same importance
  - many histograms inserted a posteriori to debug problems
- → We want a user friendly DQM that
  - shows the relevant plots for the person who is looking at them: shifter vs expert
  - as much as automatically as possible detects the status of the system
  - direct the expert/shifter to the plots that should be checked
  - requires to contact the expert as less as possible

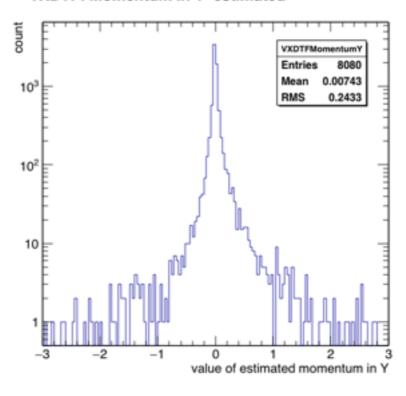
# VXDTF DQM @ DESY 2014

- → DQM Modules developed for the 2014 test beam
  - VXD Track Finder (8 histo)
  - Track Fitter
  - Intercepts
  - ROIs

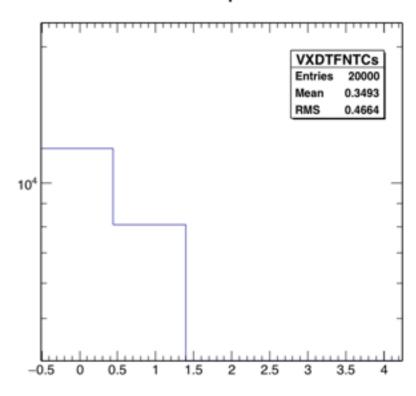
#### VXDTF: Num of hits used for TC



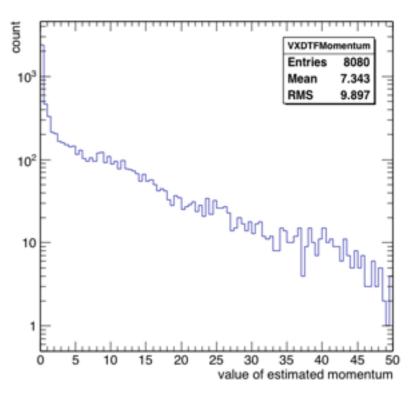
#### VXDTF: Momentum in Y estimated



#### VXDTF: Total num of TCs per event



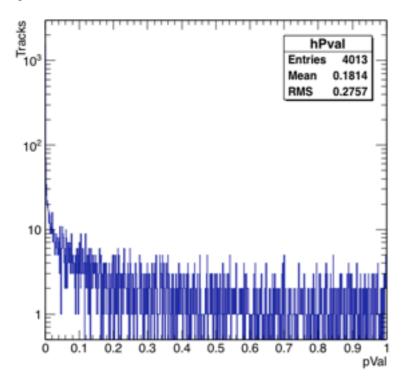
#### VXDTF: Total momentum estimated



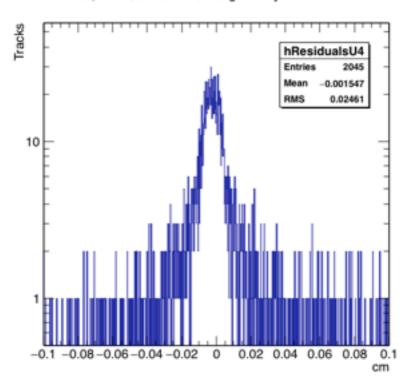
# Track Fitter DQM @ DESY 2014

- → DQM Modules developed for the 2014 test beam
  - VXD Track Finder
  - Track Fitter (histo: 10 + 8 x VXD layer + 2 graph)
  - Intercepts
  - ROIs

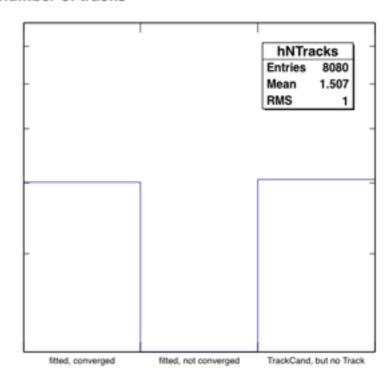
#### p-values of tracks



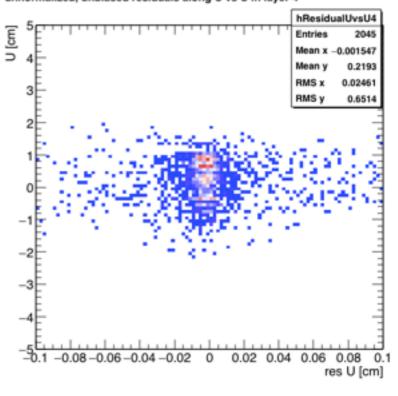
#### unnormalized, unbiased residuals along U in layer 4



#### number of tracks

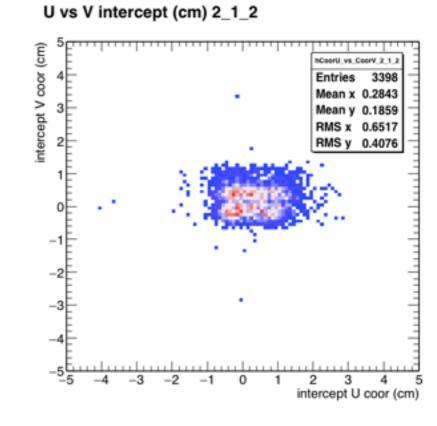


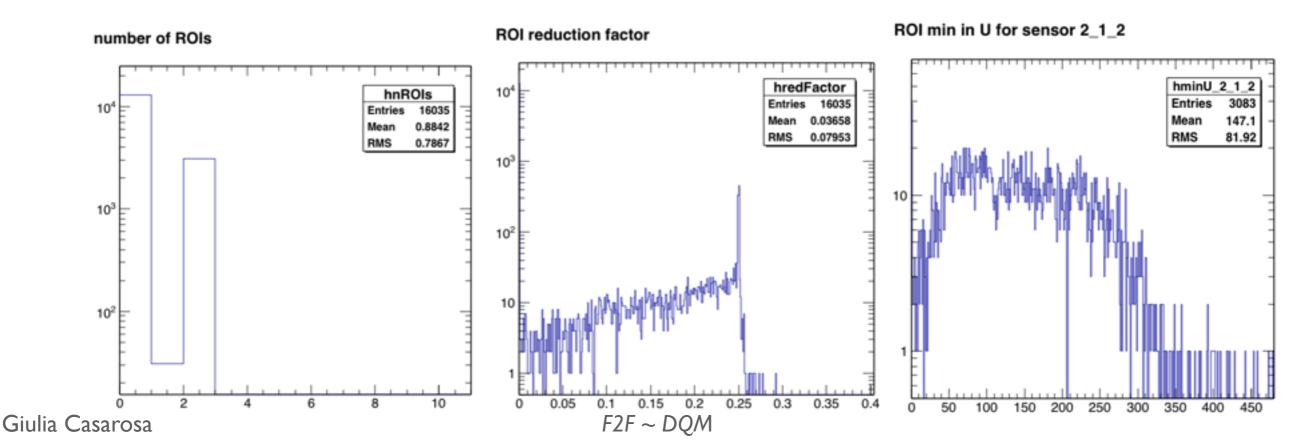
#### unnormalized, unbiased residuals along U vs U in layer 4



# ROI finding DQM @ DESY 2014

- → DQM Modules developed for the 2014 test beam
  - VXD Track Finder
  - Track Fitter
  - Intercepts (histo: I + 2I x PXD layer)
  - **ROIs** (histo:3 + 7 x PXD layer)





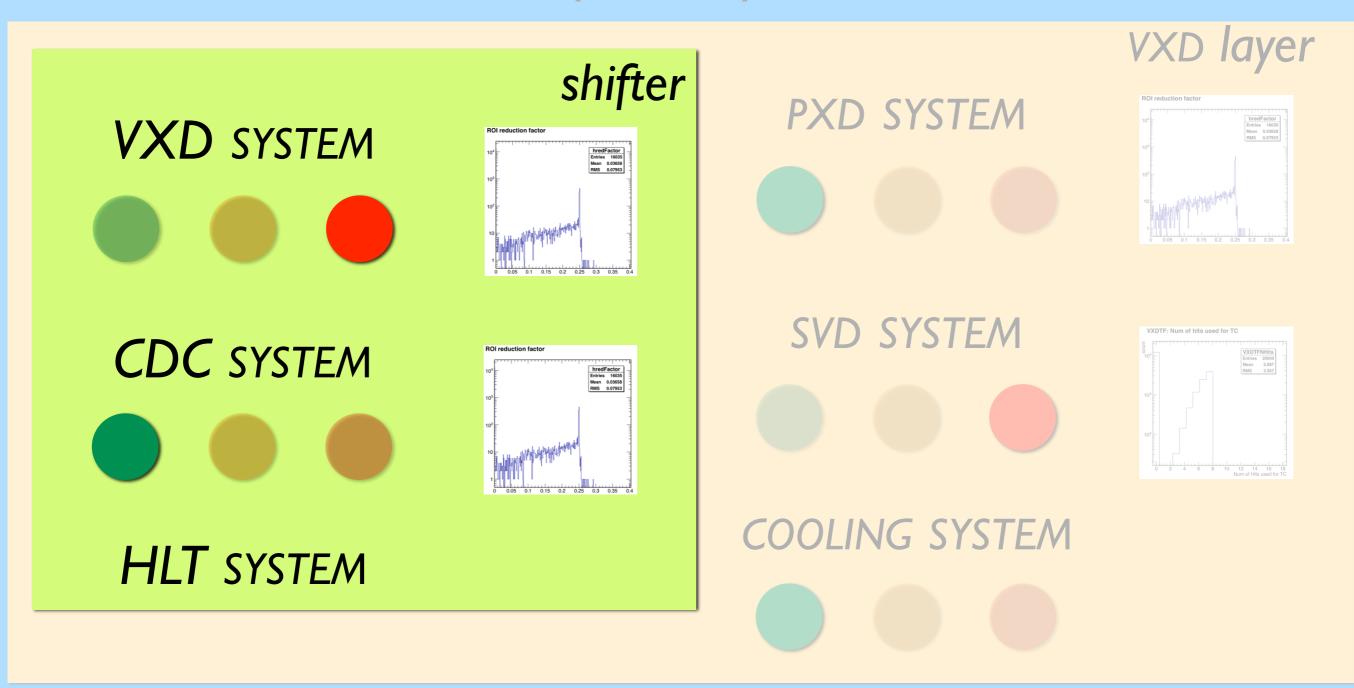
## What's Needed from the Tracking

Each developer who has a module running on the HLT should:

- 1. Define the minimum set of observables that tell us if our system/module is
  - properly working / in development / not working
- 2. Define the limits on these observables that classify it in one of the three categories:
  - properly working / in development / not working
- 3. Define the geometry of application of these observables
  - e.g. one histogram per layer, one number per track, one histogram per event, ...
- → There will be people with different levels of expertise looking at these observables:
  - standard shifter
  - expert, called in case of emergency (not all the time one thing is not green)
  - super-expert
  - God

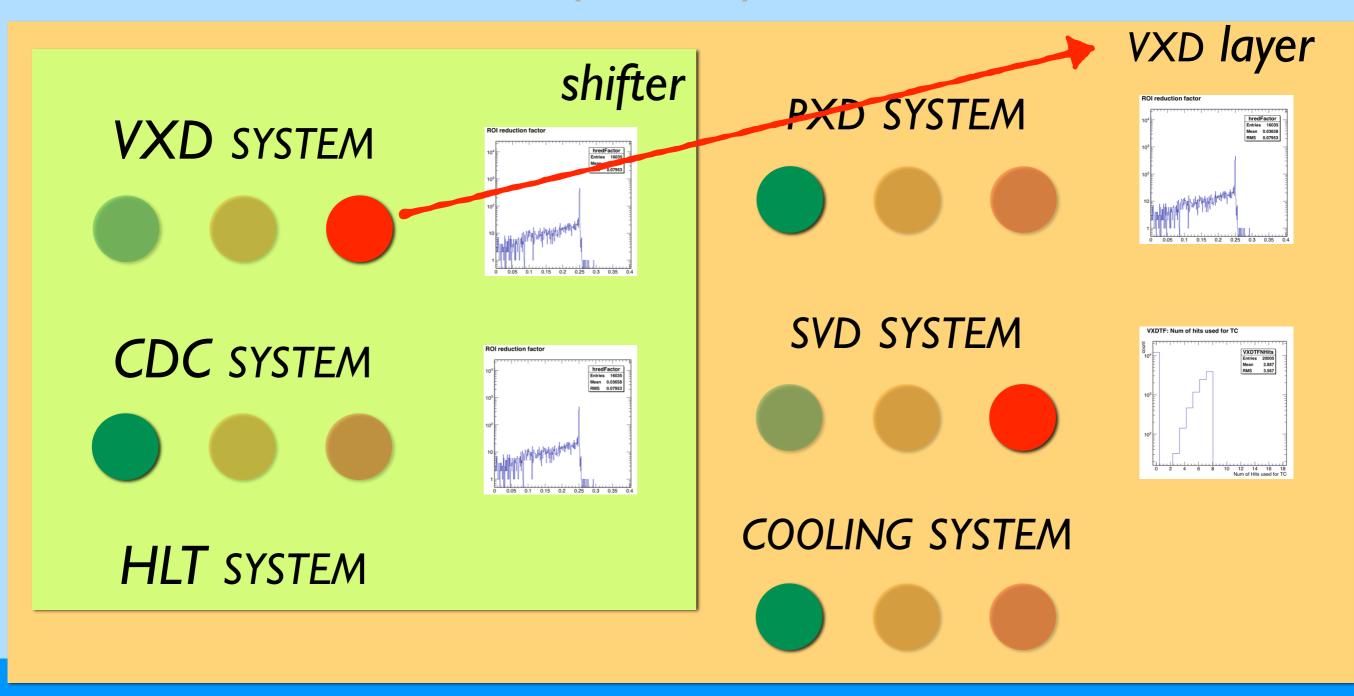
# a Top-Down Approach

## SVD system layer

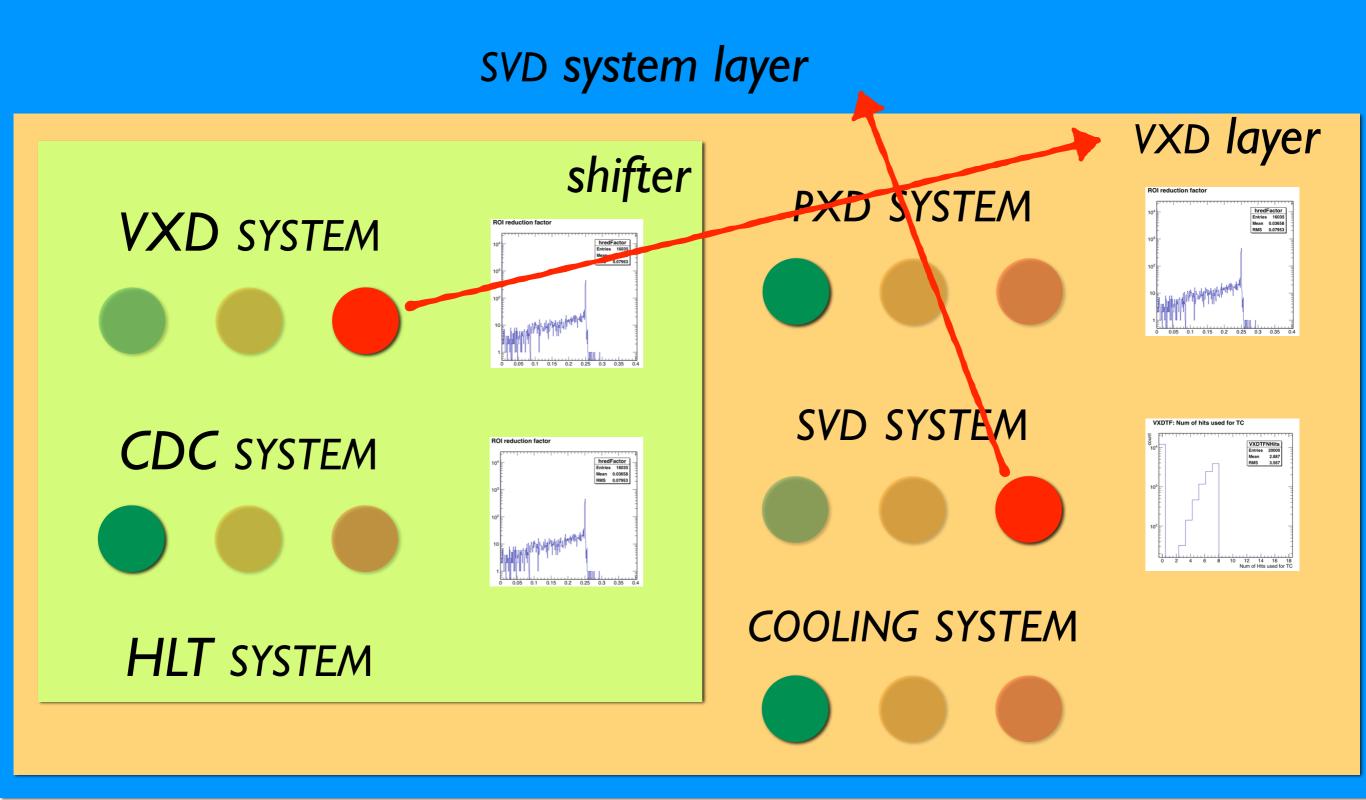


## a Top-Down Approach

## SVD system layer



# a Top-Down Approach



## Conclusions

→ We ask you to think:

minimum set of observables with limits and geometry that tell us if the tracking / VXD track finder / CDC track finder / fitter / ROI finding is

properly working / in development / not working

with a top-down approach in principle the observable does not have to be related to a single module

Next test-beam (April 2017) could be an opportunity to test the first version of the Mainz-DQM