ROI FINDING STATUS & PLANS





F2F Tracking Meeting, DESY ~ November 22nd 2016

Recent Developments

- finally moved from genfit::Tracks to RecoTracks
- extrapolation is limited to the sensor that are expected to be hit by the track
 - modified ROIGeometry and PXDIntercept classes
- ➡ function in the tracking script dedicated to the online tracking for the ROI finding
- in the add_simulation(...) python function the user can specify whether to simulate on not the PXD Data reduction (the default value is False)

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30/09/2014	Name	Calls	Memory(MB)	Time(s)	Time(ms)/Call	
	VXDTF	10000	9	97.09	9.71 +- 86.97	•
	PXDDataReduction	10000	1799	16890.74	1689.07 +-3551.01	
	PXDdigiFilter	10000	0	34.32	3.43 +- 0.47	
	PXDClusterizer	10000	0	2.03	0.20 +- 0.04	gained a factor
		=======================================				25 in
19/11/2016	Name	Calls	Memory(MB)	Time(s)	Time(ms)/Call	execution speed
	SetupGenfitExtrapolation	2500	0	0.00	0.00 +- 0.00	
	SVD-only VXDTF	2500	0	13.92	5.57 +- 59.51	
	RecoTrackCreator	2500	0	0.93	0.37 +- 0.09	
	SVD-only GenFitter	2500	0	64.90	25.96 +- 10.94	₩ &
	SVD-only DAFRecoFitter	2500	0	63.42	25.37 +- 10.72	~65
	SVD-only TrackCreator	2500	0	7.44	2.98 +- 0.86	
	PXDDataReduction	2500	0	25.33	10.13 +- 4.15	
	PXDdigiFilter	2500	0	0.59	0.23 +- 0.07	DOI officiency
	PXDClusterizer	2500	0	0.26	0.10 +- 0.02	ROI efficiency
Giulia Casar	osa		F2F ~ ROI			unchanged

Efficiency Comparison



Comparable efficiency with the 40 planes extrapolation, or the automatic plane selection extrapolation

The Net ROI–Simulation Effect

	with ROIs	tracking efficiency	efficiency factoring out geom. accept.	Pattern Recognition efficiency
no bla	no	85.5 ± 0.2	94.0 ± 0.1	84.4 ± 0.1
no bkg	yes	84.1 ± 0.2	94.I ± 0.I	87.6 ± 0.1
	no	81.7 ± 0.2	90.0 ± 0.2	82.7 ± 0.1
std bkg	yes	82.1 ± 0.2	91.9 ± 0.2	84.4 ± 0.1

- Simulating the ROI-finding helps the Pattern Recognition algorithm
- tracking efficiency factoring out geometrical acceptance benefits form ROI simulation when standard background is simulated
- ➡ ROI finding is doing a pattern recognition job
- → This study should be repeated vs p_T and adding a column "fraction of tracks with PXD hits"

Plans Towards a "Maintenance Mode"

➡ What is completely missing:

- *validation* plots for the simulation:
 - efficiency vs p_T and polar angle
 - reduction factor
 - mean and RMS of the distribution of the number of ROIs per module
 - statistical error of the intercept in the two directions, per layer
- ➡ What I would like to improve:
 - efficiency (...)
 - speed \checkmark
 - carefully check the tracking script add_tracking_for_PXDDataReduction_simulation(path, components=None, skipGeometryAdding=False)

➡ What needs to be re-thought:

• DQM plots: most of the validation plots + something else