

Multilevel solvers in lattice QCD

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Outline

Multigrid: The basic ideas

- A model problem

- Relaxation schemes

- The coarse grid

Multigrid for the Wilson-Dirac Operator

- Algebraic multigrid

- Domain decomposition and aggregation

- Krylov acceleration

- Snapshots on performance

Methods for the Overlap Operator

- Preconditioning

- Normality

- Numerical results

2d Laplace equation

Partial differential equation

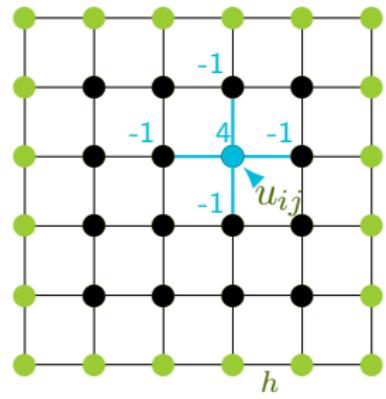
$$\begin{aligned} -\Delta u(x, y) &= f(x, y), \quad (x, y) \in \Omega = (0, 1) \times (0, 1), \\ u(x, y) &= g(x, y), \quad (x, y) \in \partial\Omega \end{aligned}$$

Discretization:

$$\text{grid } (ih, jh), i, j = 1, \dots, N, h = \frac{1}{N+1}$$

$$u_{i,j} \approx u(ih, jh)$$

$$\begin{aligned} -\Delta u(ih, jh) &= \frac{1}{h^2} (4u_{i,j} - u_{i-1,j} - u_{i,j-1} \\ &\quad - u_{i+1,j} - u_{i,j+1}) + \mathcal{O}(h^2) \end{aligned}$$

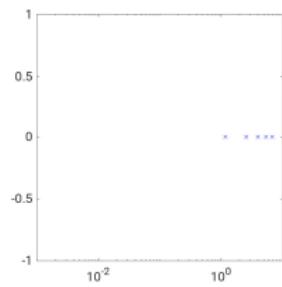


Resulting linear system: $L_h u = f$

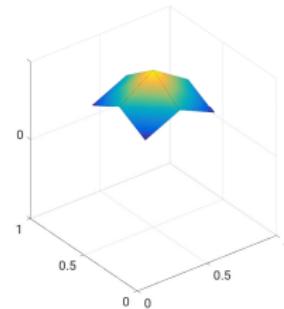
Spectral properties of L_h

Varying lattice spacing: $h = 2^{-2}$

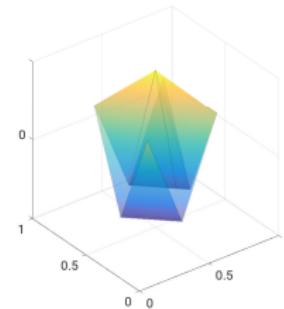
Eigenvalues



$v_{\lambda_{\min}}$



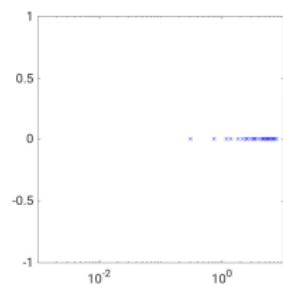
$v_{\lambda_{\max}}$



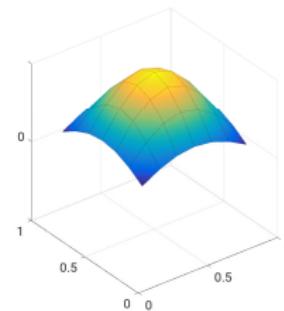
Spectral properties of L_h

Varying lattice spacing: $h = 2^{-3}$

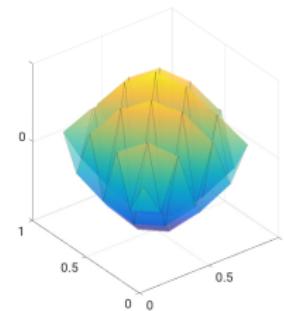
Eigenvalues



$v_{\lambda_{\min}}$



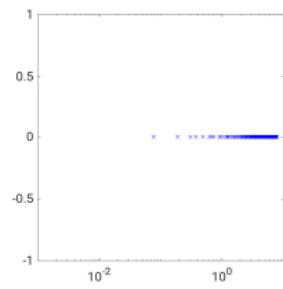
$v_{\lambda_{\max}}$



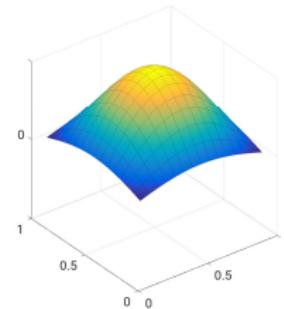
Spectral properties of L_h

Varying lattice spacing: $h = 2^{-4}$

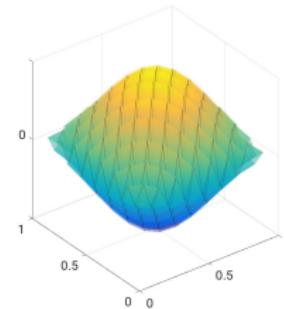
Eigenvalues



$v_{\lambda_{\min}}$



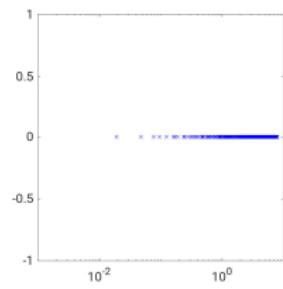
$v_{\lambda_{\max}}$



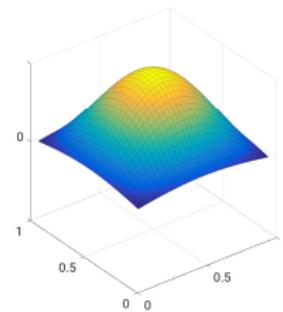
Spectral properties of L_h

Varying lattice spacing: $h = 2^{-5}$

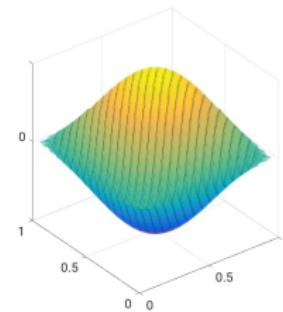
Eigenvalues



$v_{\lambda_{\min}}$



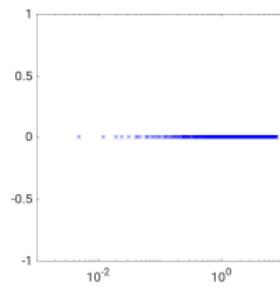
$v_{\lambda_{\max}}$



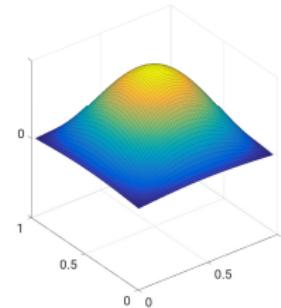
Spectral properties of L_h

Varying lattice spacing: $h = 2^{-6}$

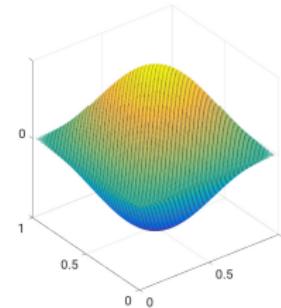
Eigenvalues



$v_{\lambda_{\min}}$



$v_{\lambda_{\max}}$



Observation:

- ▶ $\lambda_{\min} \sim h^2 \rightarrow \kappa(L_h) \sim h^{-2}$
- ▶ $v_{\lambda_{\min}}$ “looks” the same on all lattices
 - ▶ $v_{\lambda_{\min}}^{(2h)}$ approximation of $v_{\lambda_{\min}}^{(h)}$

Relaxation: Jacobi, Gauss-Seidel

Linear system $L_h u = f$.

$$4u_{i,j} - u_{i-1,j} - u_{i,j-1} - u_{i+1,j} - u_{i,j+1} = h^2 f_{ij}, \quad i, j = 1, \dots, N$$

- ▶ Jacobi iteration

$$u_{i,j}^{(k+1)} = \frac{1}{4} \left(h^2 f_{ij} + u_{i-1,j}^{(k)} + u_{i,j-1}^{(k)} + u_{i+1,j}^{(k)} + u_{i,j+1}^{(k)} \right)$$

- ▶ Gauss-Seidel iteration

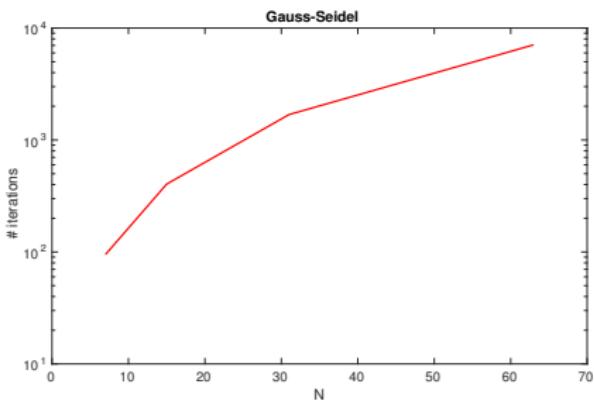
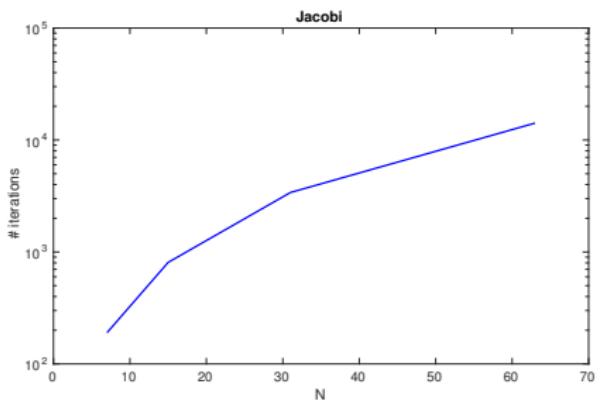
$$u_{i,j}^{(k+1)} = \frac{1}{4} \left(h^2 f_{ij} + u_{i-1,j}^{(k+1)} + u_{i,j-1}^{(k+1)} + u_{i+1,j}^{(k)} + u_{i,j+1}^{(k)} \right)$$

$$u \leftarrow (I - M L_h)u + M f$$

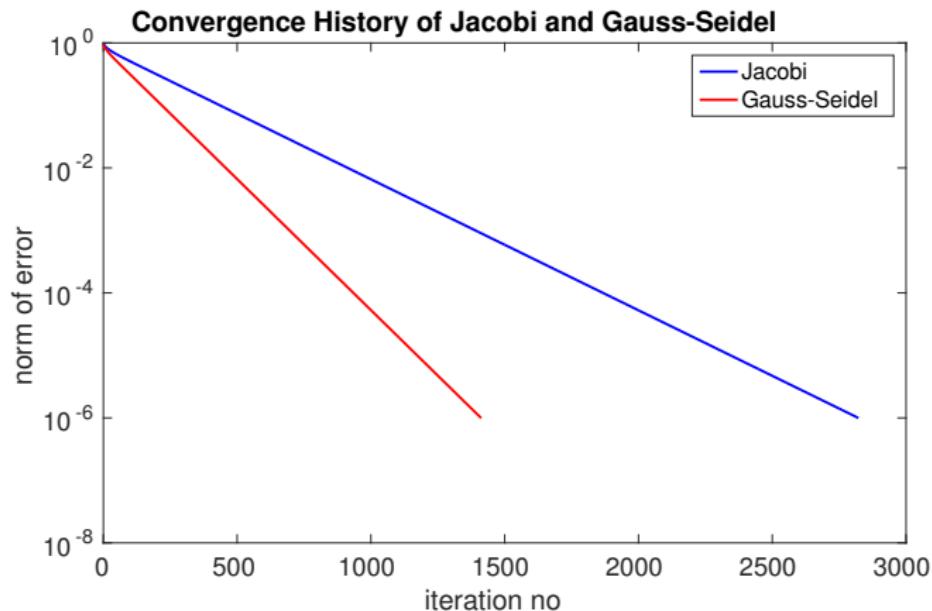
$$e \leftarrow (I - M L_h)e$$

Numerical experiments

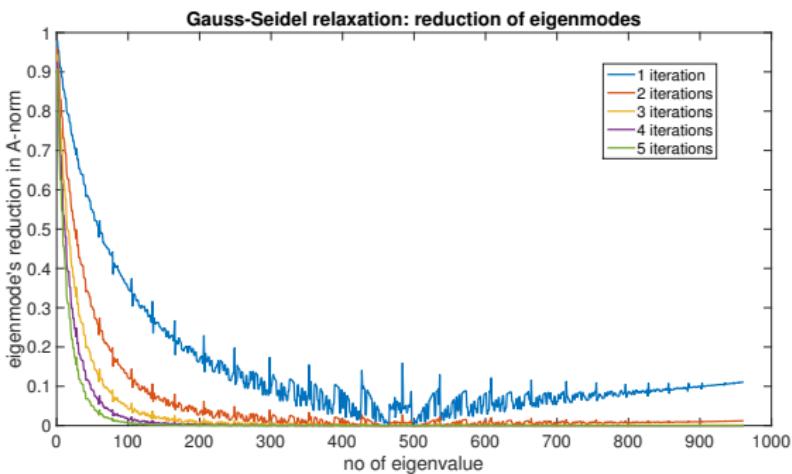
Relative tolerance 10^{-6}



Convergence history

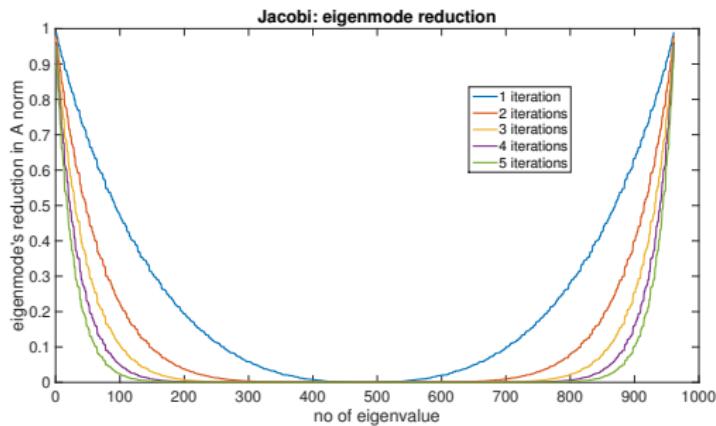


Details: action on eigenmodes – Gauss-Seidel

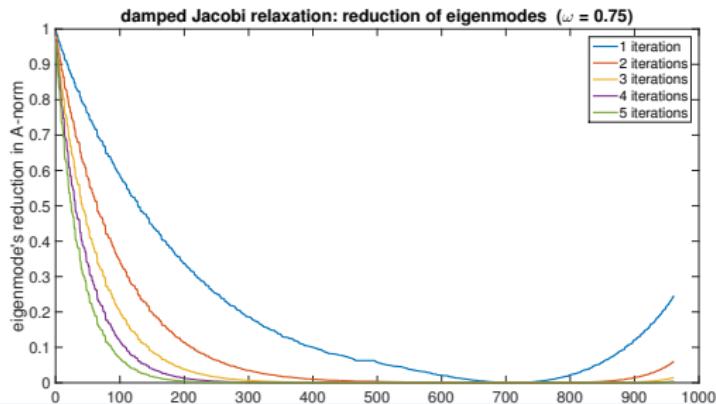


Details: action on eigenmodes – Jacobi

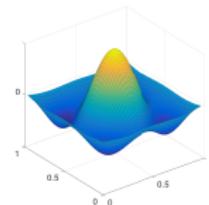
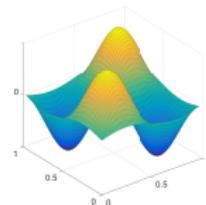
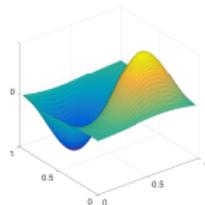
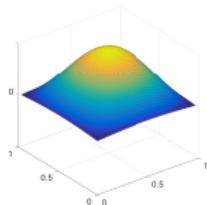
plain Jacobi



damped
Jacobi



Small eigenmodes are smooth



Observation: If the error e is composed of small eigenmodes, it is geometrically smooth.

Consequence: Smooth error can be approximated from coarser discretization.

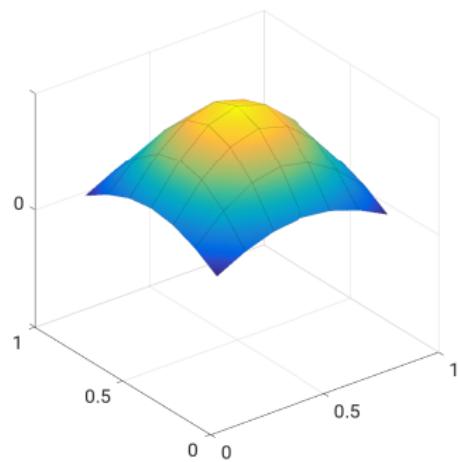
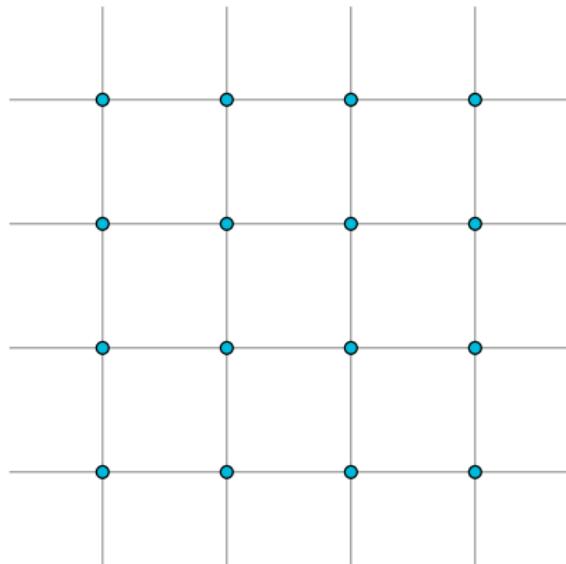
- ▶ On fine grid: $L_h e = r (= f - L_h u)$
- ▶ On coarse grid $L_{2h} e_c = Rr$, $e \approx Pe_c$, where:

R : restriction operator: fine grid to coarse grid

P : prolongation operator: coarse grid to fine grid

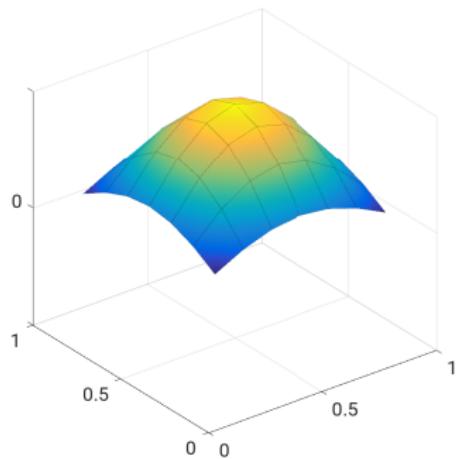
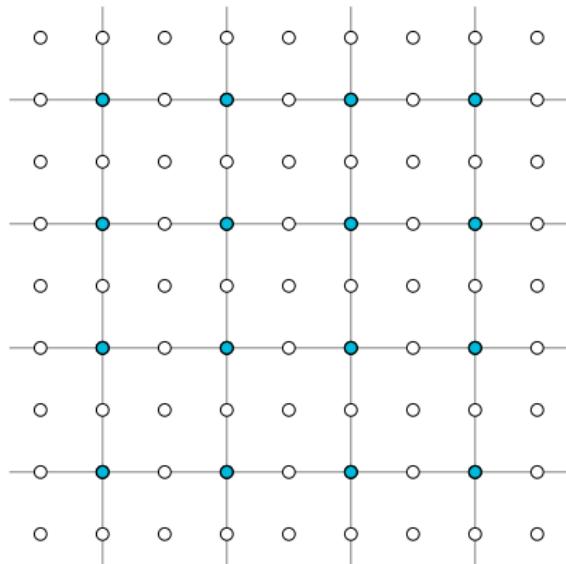
Prolongation and Restriction

Linear interpolation



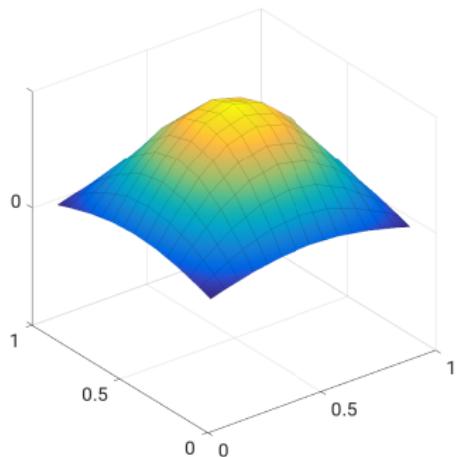
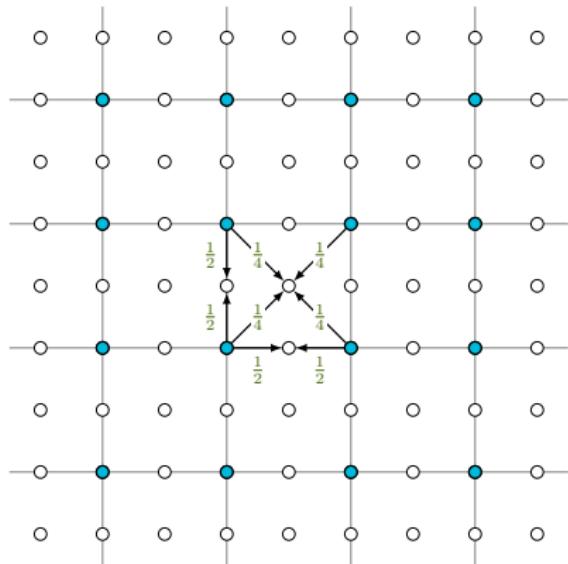
Prolongation and Restriction

Linear interpolation



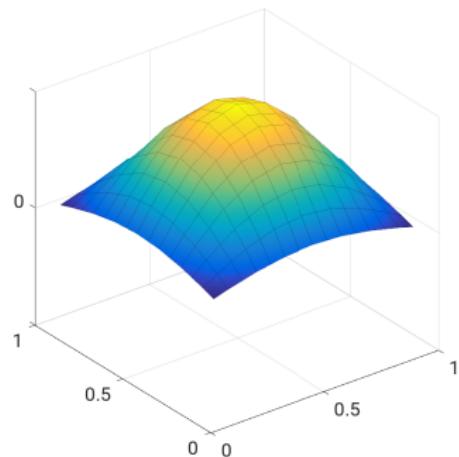
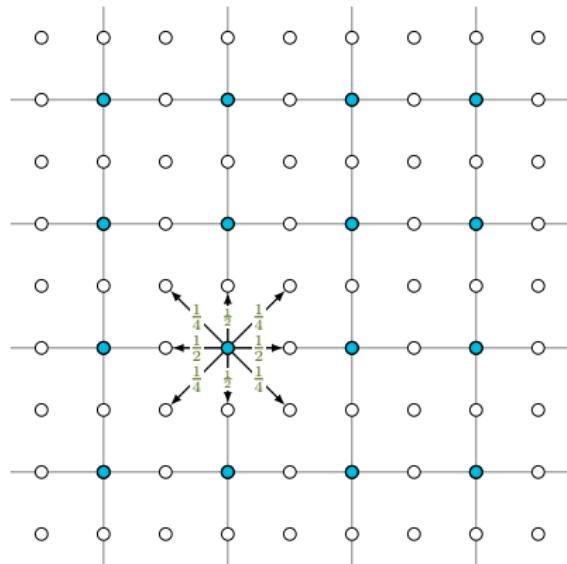
Prolongation and Restriction

Linear interpolation



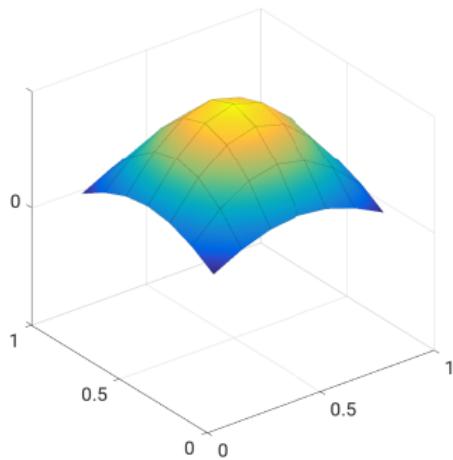
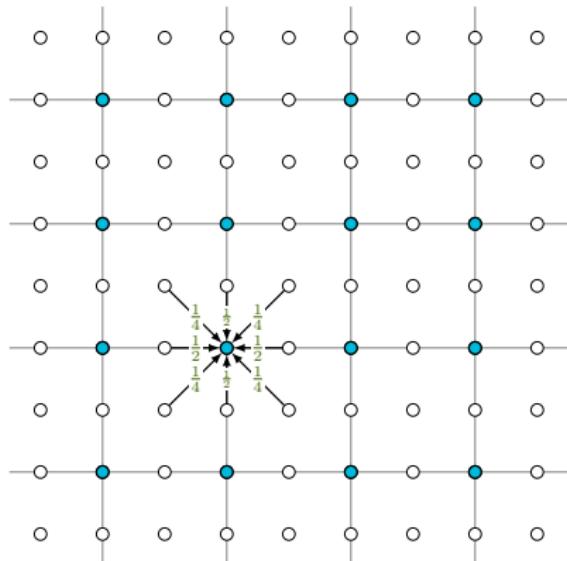
Prolongation and Restriction

Linear interpolation



Prolongation and Restriction

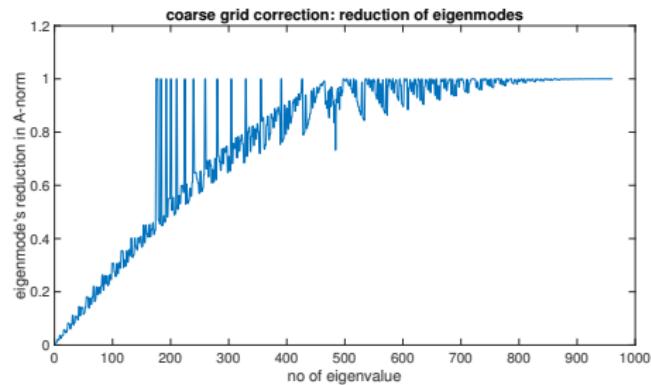
Local averaging



The coarse grid correction

Coarse grid correction for current iterate x :

- ▶ Compute $r = f - L_h u$
- ▶ Restrict $r_c = Rr$
- ▶ Solve $L_{2h} e_c = r_c$
- ▶ correct $u \leftarrow u + P e_c$



$$u \leftarrow u + PL_{2h}^{-1}R(f - L_h u)$$

$$e \rightarrow (I - PL_{2h}^{-1}RL_h)e$$

The Galerkin coarse grid operator

So far: L_{2h} obtained via same discretization scheme, but on coarser grid

Alternative: The (Petrov-)Galerkin coarse grid operator is obtained as

$$L_{2h}^G = RL_h P$$

Consequences:

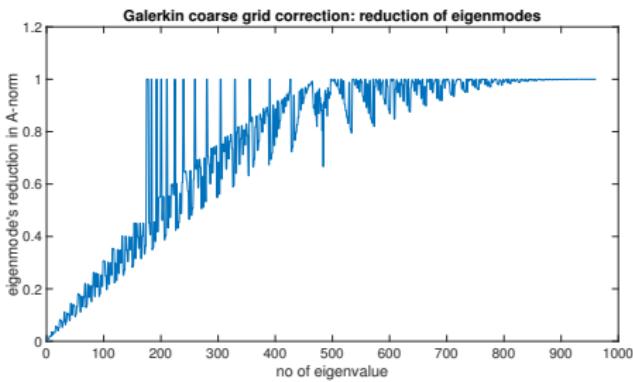
- ▶ Coarse grid projection operator $(I - P(L_{2h}^G)^{-1}RL_h)$ is indeed a projection:

$$P(L_{2h}^G)^{-1}RL_h \cdot P(L_{2h}^G)^{-1}RL_h = P(L_{2h}^G)^{-1}RL_h$$

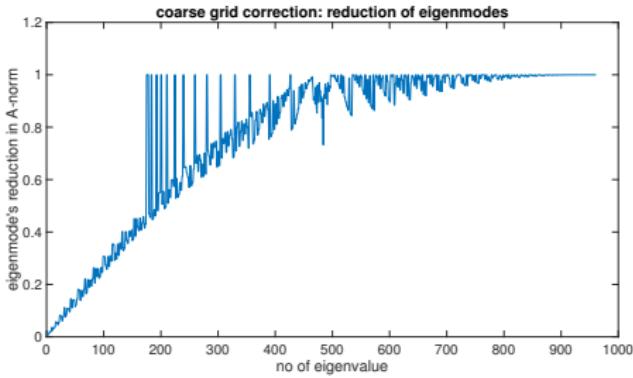
- ▶ Since $P(L_{2h}^G)^{-1}RL_h$ projects on $\text{range}(P)$, $\text{range}(P)$ should well approximate small eigenmodes.
- ▶ If $R = P^\dagger$, then $P(L_{2h}^G)^{-1}RL_h$ is an L_h -orthogonal projection (L_h is spd)

Coarse grid correction with Galerkin operator

Galerkin



L_{2h}



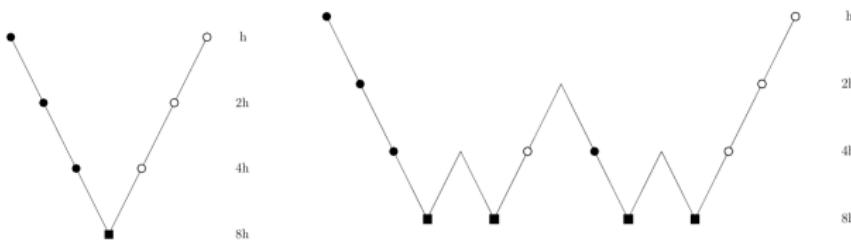
Two-grid and multigrid

Two-grid method

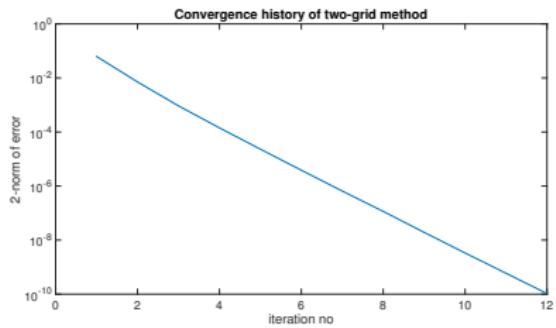
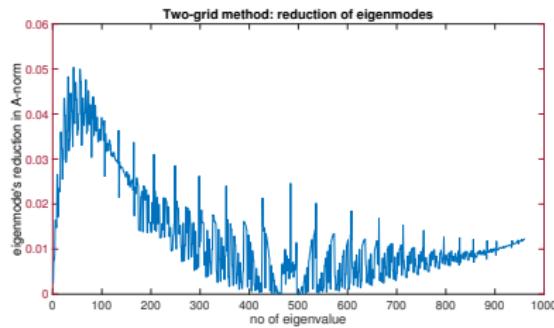
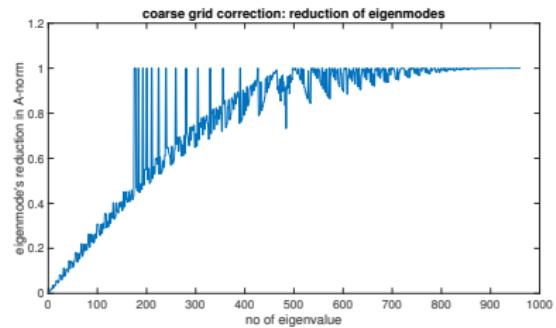
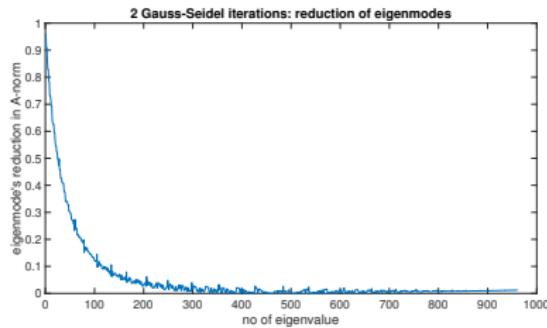
- ▶ alternate relaxation and coarse grid correction
- ▶ solve coarse system (L_{2h}) exactly

Multigrid

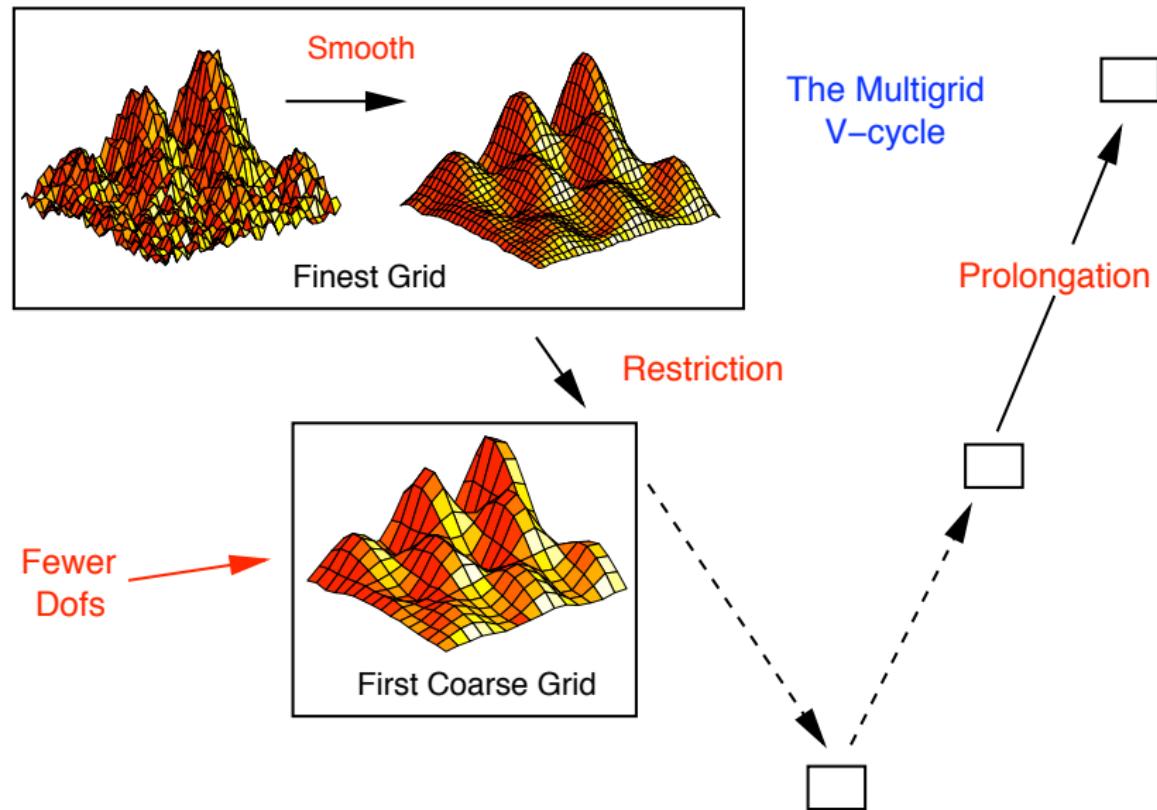
- ▶ use multigrid recursively to solve coarse system in coarse grid equation
- ▶ different **cycling strategies**



Eigenmode reduction of the two-grid scheme



In a nutshell



Convergence theory: an example

Let A be Hermitian and positive definite. Let S be the smoothing operator. Assume that

- ▶ $P = R^\dagger$,
- ▶ $A_c = RAP$ (Galerkin operator),
- ▶ $\|Se\|_A^2 \leq \|e\|_A^2 - \alpha_1 \|e\|_{AD^{-1}A}^2$ “smoothing property”,
- ▶ $\min_{v_c} \|u - Pv_c\|_D \leq \beta \|u\|_A^2$ “weak approximation prop.”.

Then

$$\|S(I - PA_c^1 RA)\|_A \leq \sqrt{1 - \frac{\alpha_1}{\beta}}.$$

Multigrid: The basic ideas

- A model problem

- Relaxation schemes

- The coarse grid

Multigrid for the Wilson-Dirac Operator

- Algebraic multigrid

- Domain decomposition and aggregation

- Krylov acceleration

- Snapshots on performance

Methods for the Overlap Operator

- Preconditioning

- Normality

- Numerical results

Framework

- ▶ D : Wilson Dirac operator
- ▶ Background gauge fields introduce randomness in couplings
- ▶ There is no “natural” $D_{2h} \rightarrow$ Galerkin construction
- ▶ Generic two-grid iteration for $D\psi = \eta$
 - ▶ current iterate ψ^k
 - ▶ apply smoother: $\psi^k \leftarrow (I - MD)\psi^k + M\eta$
 - ▶ compute residual: $r^k = \eta - D\psi^k$
 - ▶ apply coarse grid correction: $e^k = PD_c^{-1}Rr^k$
 - ▶ next iterate: $\psi^{k+1} = \psi^k + e^k$

Two-grid error propagator for ν steps of pre-smoothing

$$E_{2g}^{(\nu)} = \underbrace{(I - PD_c^{-1}P^\dagger D)}_{\text{coarse grid correction}} \underbrace{(I - MD)^\nu}_{\text{smoother}}, \quad \underbrace{D_c := P^\dagger DP}_{\text{coarse operator}}$$

- ▶ low accuracy for D_c^{-1} and M is sufficient
- ▶ introduce recursive construction for $D_c \rightarrow$ multigrid

To Do: Define interpolation P and smoother M

DD- α AMG [ArXiv:1303.1377, 1307.6101]

M : Schwarz Alternating Procedure (SAP)

[Hermann Schwarz 1870; Martin Lüscher 2003]

P : Aggregation Based Interpolation

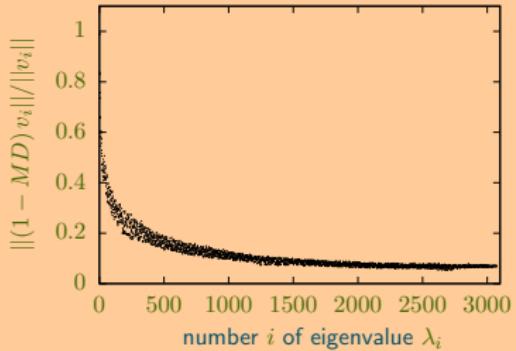
[Brannick, Clark et al. 2010]

Preview: The multigrid principle for Dirac-Wilson

Smoother: $I - MD$

- ▶ Effective on “large” eigenvectors
- ▶ “small” eigenvectors remain

SAP



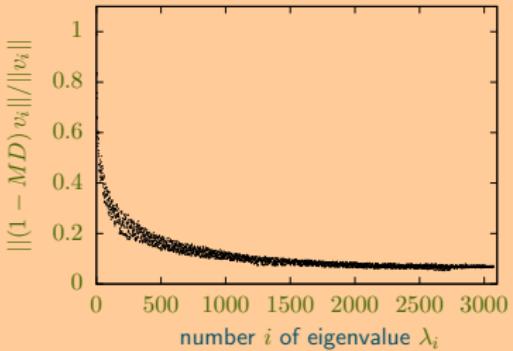
$$Dv_i = \lambda_i v_i \quad \text{with} \quad |\lambda_1| \leq \dots \leq |\lambda_{3072}|$$

Preview: The multigrid principle for Dirac-Wilson

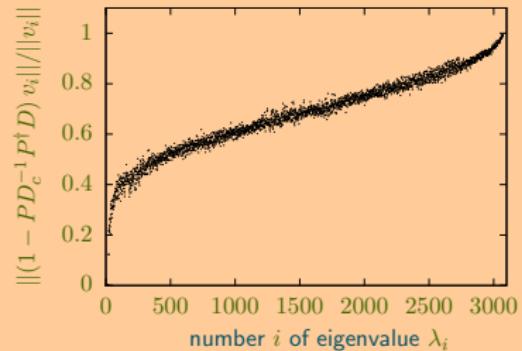
Coarse-grid correction: $I - PD_c^{-1}P^\dagger D$

- ▶ small eigenvectors built into interpolation P
- ⇒ Effective on small eigenvectors

SAP



Aggregation + Low Modes



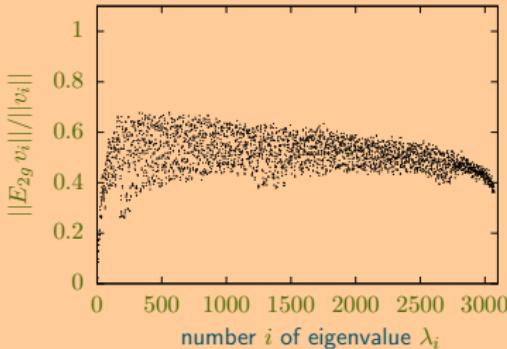
$$Dv_i = \lambda_i v_i \quad \text{with} \quad |\lambda_1| \leq \dots \leq |\lambda_{3072}|$$

Preview: The multigrid principle for Dirac-Wilson

Two-grid method: $E_{2g} = (I - MD)^\nu(I - PD_c^{-1}P^\dagger D)$

- ▶ Complementarity of smoother and coarse-grid correction
- ▶ Effective on **all eigenvectors!**

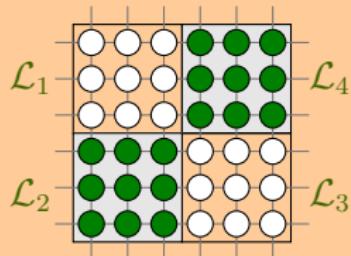
DD- α AMG



$$Dv_i = \lambda_i v_i \quad \text{with} \quad |\lambda_1| \leq \dots \leq |\lambda_{3072}|$$

SAP: Schwarz Alternating Procedure

Two color decomposition of \mathcal{L}



► canonical injections

$$\mathcal{I}_{\mathcal{L}_i} : \mathcal{L}_i \rightarrow \mathcal{L}$$

► block restrictions

$$D_{\mathcal{L}_i} = \mathcal{I}_{\mathcal{L}_i}^\dagger D \mathcal{I}_{\mathcal{L}_i}$$

► block inverses

$$B_{\mathcal{L}_i} = \mathcal{I}_{\mathcal{L}_i} D_{\mathcal{L}_i}^{-1} \mathcal{I}_{\mathcal{L}_i}^\dagger$$

```

1: in:  $\psi, \eta, \nu$  – out:  $\psi$ 
2: for  $k = 1$  to  $\nu$  do
3:    $r \leftarrow \eta - D\psi$ 
4:   for all green  $\mathcal{L}_i$  do
5:      $\psi \leftarrow \psi + B_{\mathcal{L}_i} r$ 
6:   end for
7:    $r \leftarrow \eta - D\psi$ 
8:   for all white  $\mathcal{L}_i$  do
9:      $\psi \leftarrow \psi + B_{\mathcal{L}_i} r$ 
10:  end for
11: end for

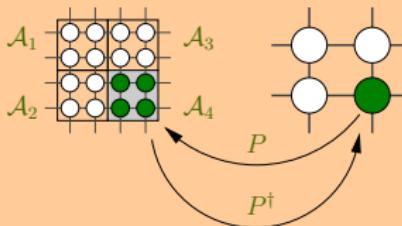
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Aggregation Based Interpolation

Construction:

- ▶ Define aggregates: domain decomposition

$$\mathcal{A}_1, \dots, \mathcal{A}_s$$

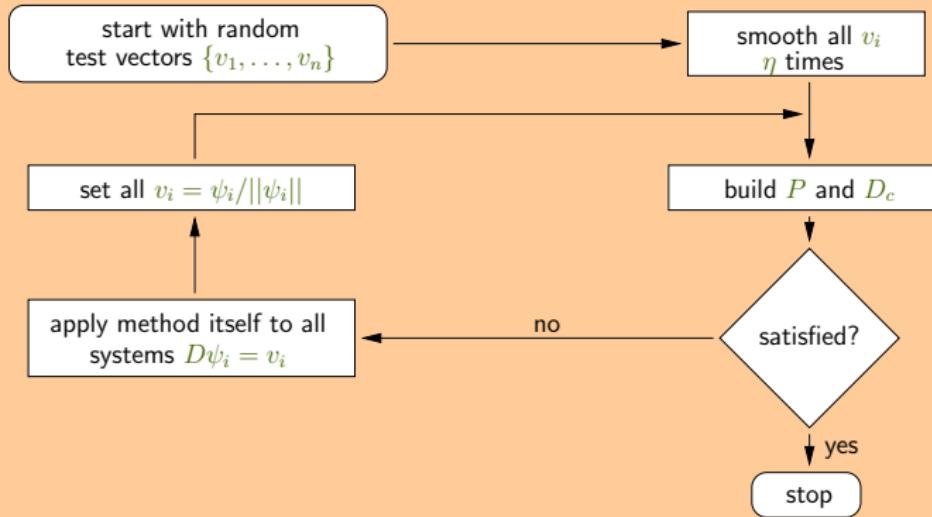


- ▶ Calculate test vectors w_1, \dots, w_N [ArXiv:1303.1377,1307.6101]
- ▶ Decompose test vectors over aggregates $\mathcal{A}_1, \dots, \mathcal{A}_s$

$$(v^{(1)}, \dots, v^{(k)}) = \begin{pmatrix} \vdots & \\ & \end{pmatrix} = \begin{pmatrix} \mathcal{A}_1 \\ \mathcal{A}_2 \\ \vdots \\ \mathcal{A}_s \end{pmatrix} \rightarrow P = \begin{pmatrix} \mathcal{A}_1 & & & \\ & \mathcal{A}_2 & & \\ & & \ddots & \\ & & & \mathcal{A}_s \end{pmatrix}$$

Setup Procedure: How to Obtain Test Vectors

Bootstrapping process



Krylov acceleration

Recall:

$$\begin{aligned}\psi^k - \psi &= (I - MD)(\psi^{k-1} - \psi) = (I - MD)^k(\psi^0 - \psi) \\ \Rightarrow \psi^k - \psi &= p_k(MD)(\psi^0 - \psi), \quad p_k(t) = (1-t)^k\end{aligned}$$

Note: $\lim_{k \rightarrow \infty} \psi^k - \psi = 0$ for any $\psi^0 \Leftrightarrow \rho(I - MD) < 1$.

Krylov acceleration

Krylov method “chooses” polynomial p_k better than $(1-t)^k$:

- ▶ CG: minimizes $\langle p_k(MD)(\psi^0 - \psi) | D | p_k(MD)(\psi^0 - \psi) \rangle$
- ▶ GMRES minimizes $\|MD(p_k(MD)(\psi^0 - \psi))\|_2$
- ▶ BiCG, QMR, BiCGStab

Terminology: M preconditioner

Some history

- ▶ **Adaptive algebraic multigrid α AMG:** Brezina, Falgout, Manteuffel, MacLachlan, McCormick, Ruge 2004
- ▶ **Inexact deflation method:** Lüscher 2007.
Solves

$$D(I - PD_c^{-1}P^\dagger D)\psi = \eta$$

using SAP as a preconditioner.

- ▶ **α AMG for lattice QCD:** Babich, Brannick, Brower, Clark, Manteuffel, McCormick, Osborn, Rebbi 2010.
- ▶ **DD- α AMG:** F., Kahl, Leder, Krieg, Rottmann 2013

Some history

- ▶ **Adaptive algebraic multigrid α AMG:** Brezina, Falgout, Manteuffel, MacLachlan, McCormick, Ruge 2004
- ▶ **Inexact deflation method:** Lüscher 2007.
Solves

$$D(I - PD_c^{-1}P^\dagger D)\psi = \eta$$

using SAP as a preconditioner.

- ▶ **α AMG for lattice QCD:** Babich, Brannick, Brower, Clark, Manteuffel, McCormick, Osborn, Rebbi 2010.
- ▶ **DD- α AMG:** F., Kahl, Leder, Krieg, Rottmann 2013
- ▶ 2013: “Inexact deflation with inexact projection”
- ▶ QPACE2: Targeted implementation of DD- α AMG
- ▶ Targeted implementations within BMWc

Current AMG solvers for D_W

	QOPQDP	OpenQCD	DD- α AMG
clover term	included	included	included
mixed precision	yes	yes	yes
smoother	GMRES	SAP	SAP
aggregation	γ_5 -comp.	arbitrary	γ_5 -comp.
setup	1)	2)	3)
typ. # test vecs (N)	20	30	20
# vars / coarse site	$2N$	N	$2N$
cycling	K-cycle	n.a.	K-cycle

- 1) inverse iterations with GMRES on sequence of test vecs
- 2) repeated inverse iteration with emerging solver on all test vecs at once
- 3) modification of 2)

Snapshots on performance

Configurations

id	lattice size $N_t \times N_s^3$	pion mass m_π [MeV]	CGNR iterations	shift m_0	clover term c_{sw}	provided by
1	48×16^3	250	7,055	-0.095300	1.00000	BMW-c
2	48×24^3	250	11,664	-0.095300	1.00000	BMW-c
3	48×32^3	250	15,872	-0.095300	1.00000	BMW-c
4	48×48^3	135	53,932	-0.099330	1.00000	BMW-c
5	64×64^3	135	84,207	-0.052940	1.00000	BMW-c
6	128×64^3	270	45,804	-0.342623	1.75150	CLS

Tabelle: Ensembles used.

Snapshots on performance

Setup time vs. solve time

number of setup steps n_{inv}	average setup timing	average iteration count	lowest iteration count	highest iteration count	average solver timing	average total timing
1	2.08	149	144	154	6.42	8.50
2	3.06	59.5	58	61	3.42	6.48
3	4.69	34.5	33	36	2.37	7.06
4	7.39	27.2	27	28	1.95	9.34
5	10.8	24.1	24	25	1.82	12.6
6	14.1	23.0	23	23	1.89	16.0
8	19.5	22.0	22	22	2.02	21.5
10	24.3	22.5	22	23	2.31	26.6

Tabelle: Evaluation of DD- α AMG-setup($n_{inv}, 2$), 48^4 lattice, configuration id 4), 2,592 cores, averaged over 20 runs.

Snapshots on performance

oe-BiCGStab vs. DD- α AMG

	BiCGStab	DD- α AMG	speed-up factor	coarse grid
setup time		22.9s		
solve iter	13,450	21		3,716(*)
solve time	91.2s	3.15s	29.0	2.43s
total time	91.2s	26.1s	3.50	

Tabelle: BiCGStab vs. DD- α AMG with default parameters,
configuration id 5, 8,192 cores, (*) : coarse grid iterations summed
up over all iterations on the fine grid.

Snapshots on performance

Mass scaling and levels

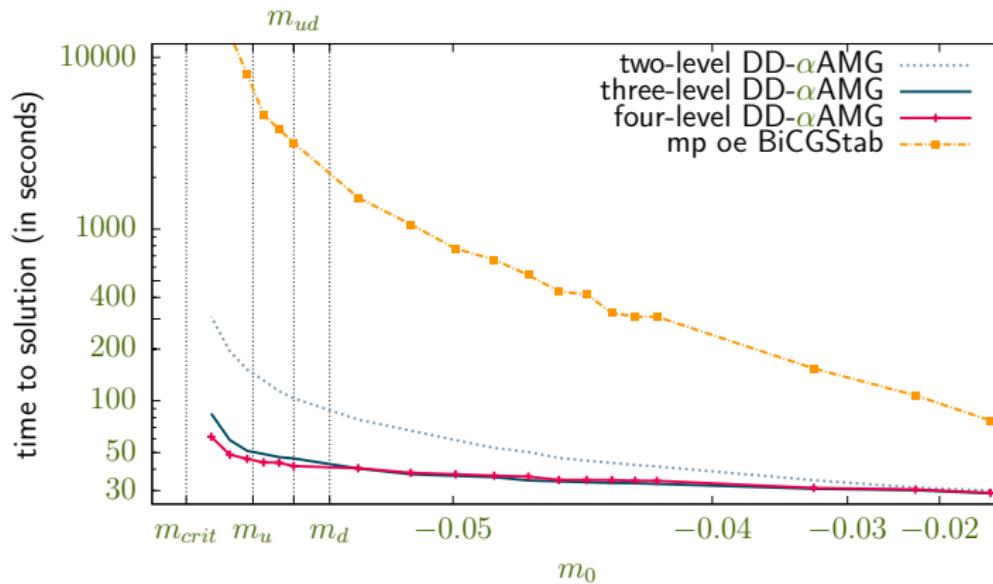


Abbildung: Mass scaling of 2, 3 and 4 level DD- α AMG, 64⁴ lattice, configuration id 5, restart length $n_{kv} = 10$, 128 cores

Snapshots on performance

Mass scaling and levels

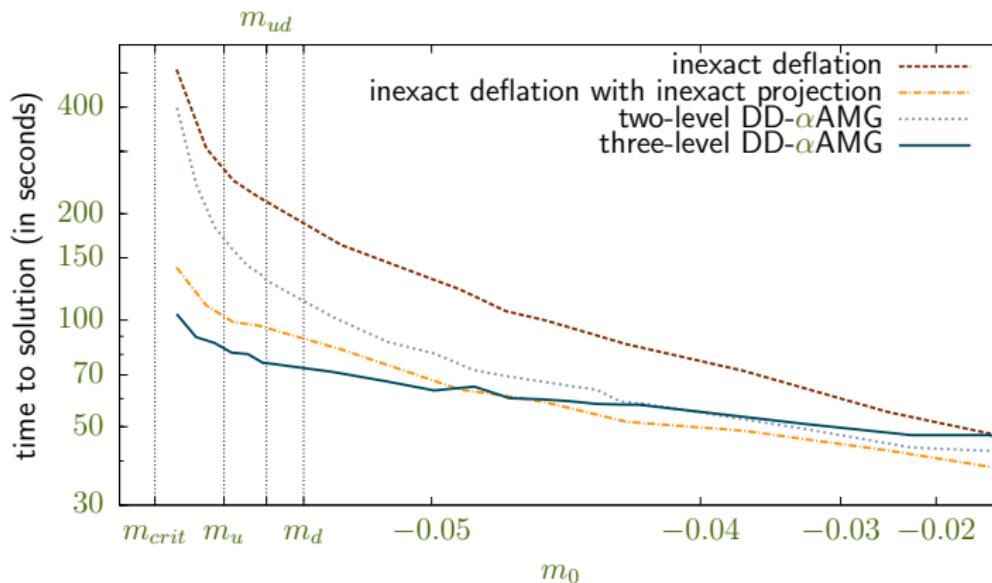
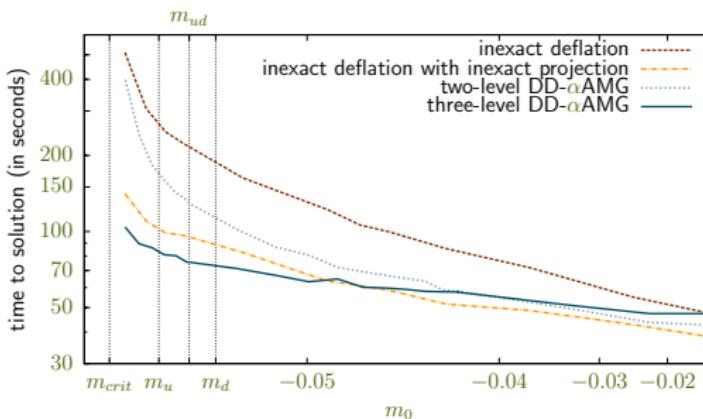


Abbildung: Mass scaling of 2, 3 and 4 level DD- α AMG, 64⁴ lattice, configuration id 5, restart length $n_{kv} = 10$, 128 cores

2 & 3 Level DD- α AMG, Inexact Deflation

Configuration 5: 64×64^3 , 128 cores



- ▶ 32 test vectors for inex. defl. w. inex. proj. [OpenQCD 1.2]
- ▶ Inex. defl. w. inex. proj. scales better than ordinary inex. defl. [DD-HMC 1.2.2] and 2 level DD- α AMG
- ▶ 3 level DD- α AMG shows best scaling behavior
- ▶ 3 levels perform best in range of m_u and m_d

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We want many nails!

Multigrid: The basic ideas

- A model problem

- Relaxation schemes

- The coarse grid

Multigrid for the Wilson-Dirac Operator

- Algebraic multigrid

- Domain decomposition and aggregation

- Krylov acceleration

- Snapshots on performance

Methods for the Overlap Operator

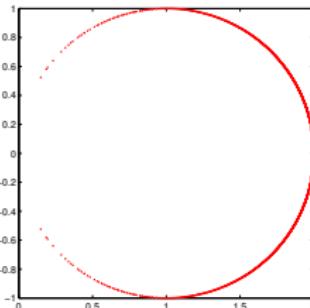
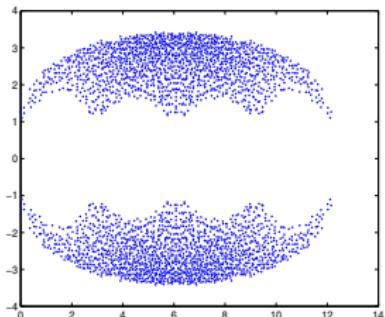
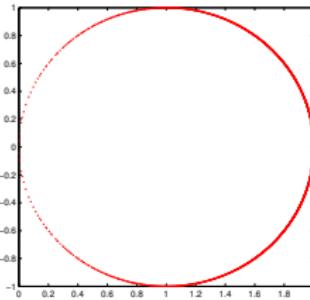
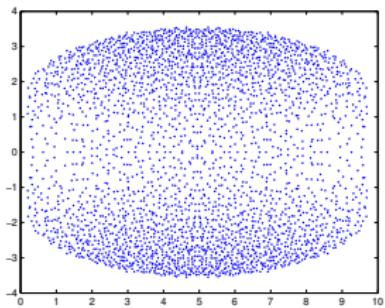
- Preconditioning

- Normality

- Numerical results

The overlap operator

$$D_N = I + \rho \gamma_5 \underbrace{\text{sign}(\gamma_5 D_W)}_{:=Q}$$



Solving $D_N\psi = \eta$

$$D_N = I + \rho \cdot \gamma_5 \cdot \text{sign}(Q(m_k))$$

Generic Krylov subspace iteration for $D_N\psi = \eta$

- 1: **while** error too large **do**
- 2: compute next basis vector (involves computation D_Nv)
- 3: update current iterate
- 4: **end while**

Solving $D_N\psi = \eta$

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Generic Krylov subspace iteration for $D_N\psi = \eta$

- 1: **while** error too large **do**
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- 3: update current iterate
- 4: **end while**

Challenges:

- i) Evaluating $\text{sign}(Q(m_k))v$ is quite costly within D_Nv
- ii) Iteration counts of $\mathcal{O}(1000)$ → **preconditioning**

Current approach: recursive preconditioning

Idea: Preconditioner = “inner” iteration with GMRES for D_N

Consequences:

- ▶ inner iteration requires **low accuracy** only
- ▶ needs “flexible” outer iteration (FGMRES, GCR)
- ▶ requires low accuracy for $\text{sign}(Q(m_k))c$ only
- ▶ accuracy for **sign** in outer iteration can be decreased as iteration proceeds

Simoncini, Szyld [03], van den Eshof, Sleijpen [04]

Cundy, van den Eshof, F., Krieg, Schäfer 2005

New approach: use multigrid solver for D_W

Definition: D_W is **normal** if $D_W^\dagger D_w = D_W D_W^\dagger$

Equivalently: D_W admits an orthonormal basis of eigenvectors

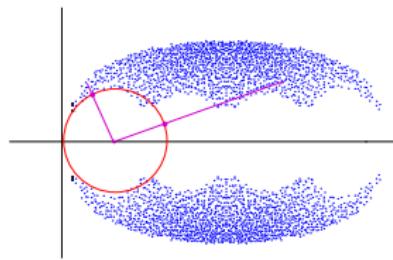
Proposition

Assume $D_W(0)$ is normal. Then

$$D_W(0)x = \lambda x$$

$$\iff$$

$$D_N(m_k)x = (\rho + \text{csgn}(\lambda + m_k))x$$



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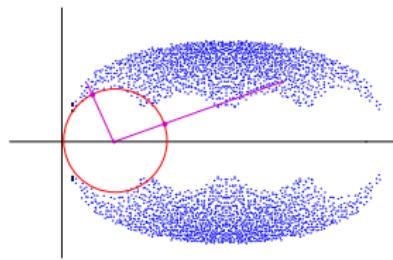
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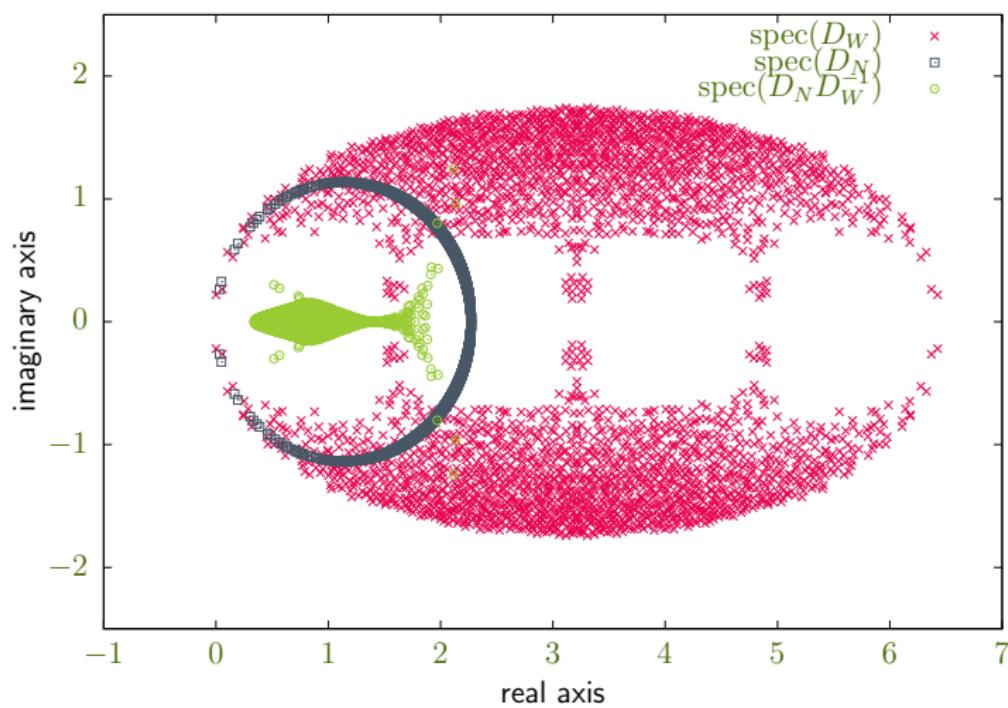
$$\iff$$

$$D_N(m_k)x = (\rho + \text{csgn}(\lambda + m_k))x$$



- adapt α, m_0 s.t. small evs of $\alpha D_W(m_0)$ and D_N match.

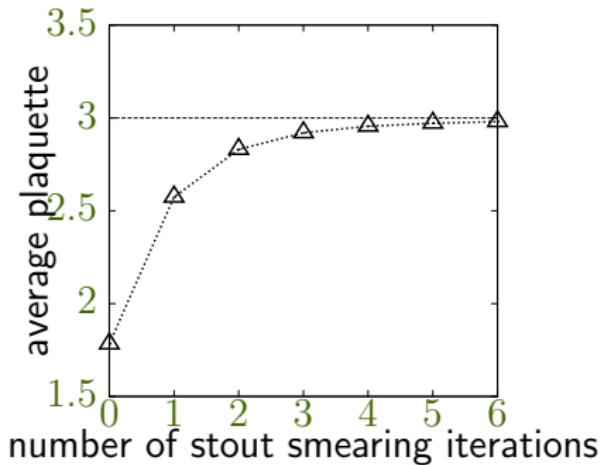
Spectra



Smearing drives towards normality I

Fact 1: We have

$$\|D_W^\dagger D_W - D_W D_W^\dagger\|_F = 16N_Q(3 - Q_{avg})$$



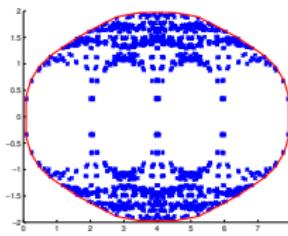
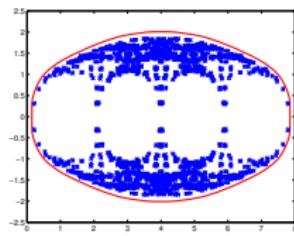
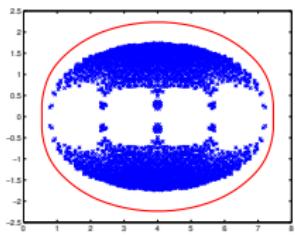
Smearing drives towards normality II

Fact 2

If D is normal, its field of values

$$\mathcal{F}(D) = \left\{ \frac{\langle x, Dx \rangle}{\langle x, x \rangle}, x \neq 0 \right\}$$

is the convex hull of the spectrum.



Numerical results

Configurations

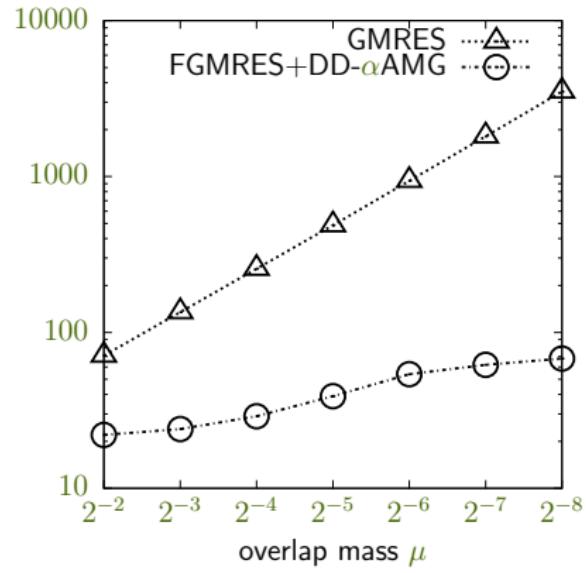
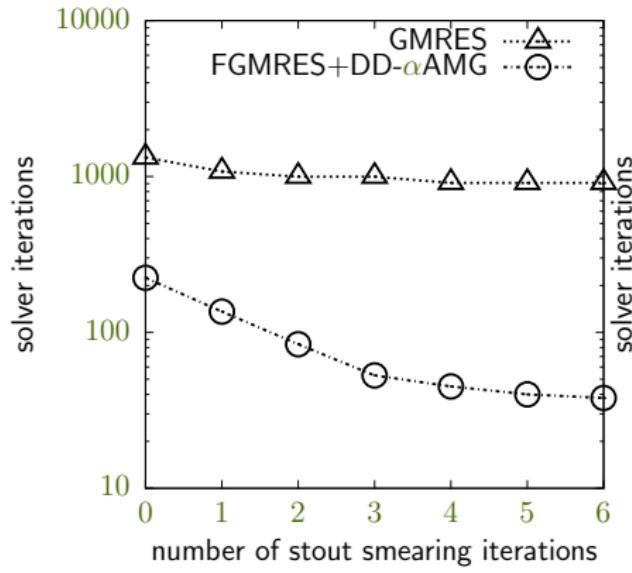
ID	lattice size $N_t \times N_s^3$	kernel mass m_0^{ker}	default overlap mass μ	smearing s	provided by
1	32×32^3	$-1 - \frac{3}{4}\sigma_{\min}$	0.0150000	{0, ..., 6}-stout	J. Finkenrath
2	32×32^3	-1.3	0.0135778	3HEX	BMW-c 2013

- We used 1024 processors of Juropa@FZ-Jülich

$$\rho = \frac{-\mu/2 + m_0^{ker}}{\mu/2 + m_0^{ker}}$$

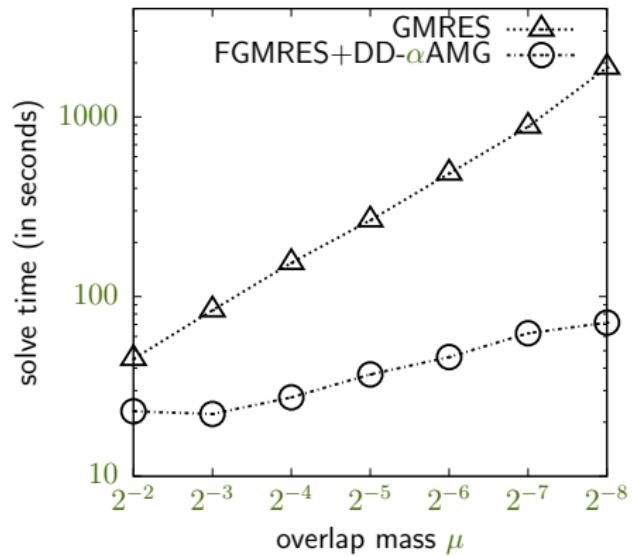
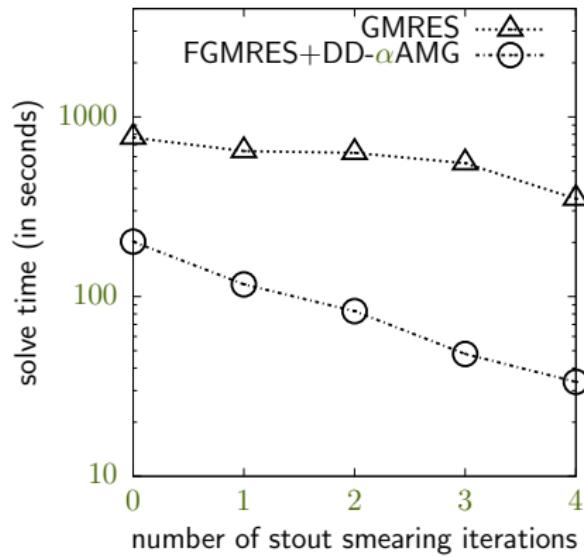
Comparison of iterations

Configuration 1

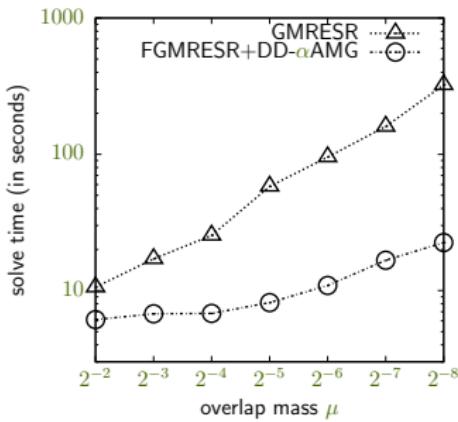
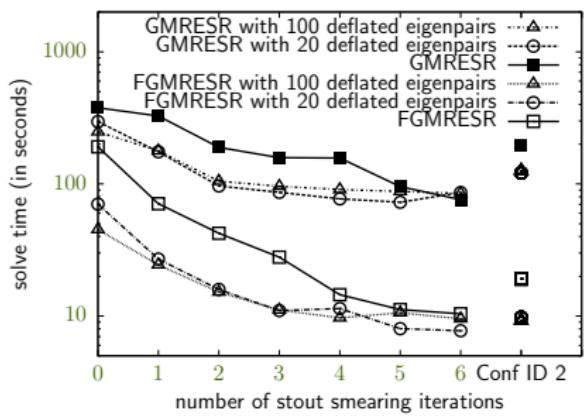


Comparison of time to solution

Configuration 1



Comparison of time to solution, play every trick



Conclusions

- ▶ Adaptivity is the key to success in AMG for LQCD
- ▶ Setup in AMG is expensive
- ▶ More levels require coarse grain parallelism
- ▶ AMG outperforms other solvers, especially for multiple sources
- ▶ AMG allows to use D_W as a preconditioner for D_N
- ▶ Performance gains increase as D_W gets more normal through smearing