



GNA fitter and detector response impact on JUNO mass hierarchy sensitivity

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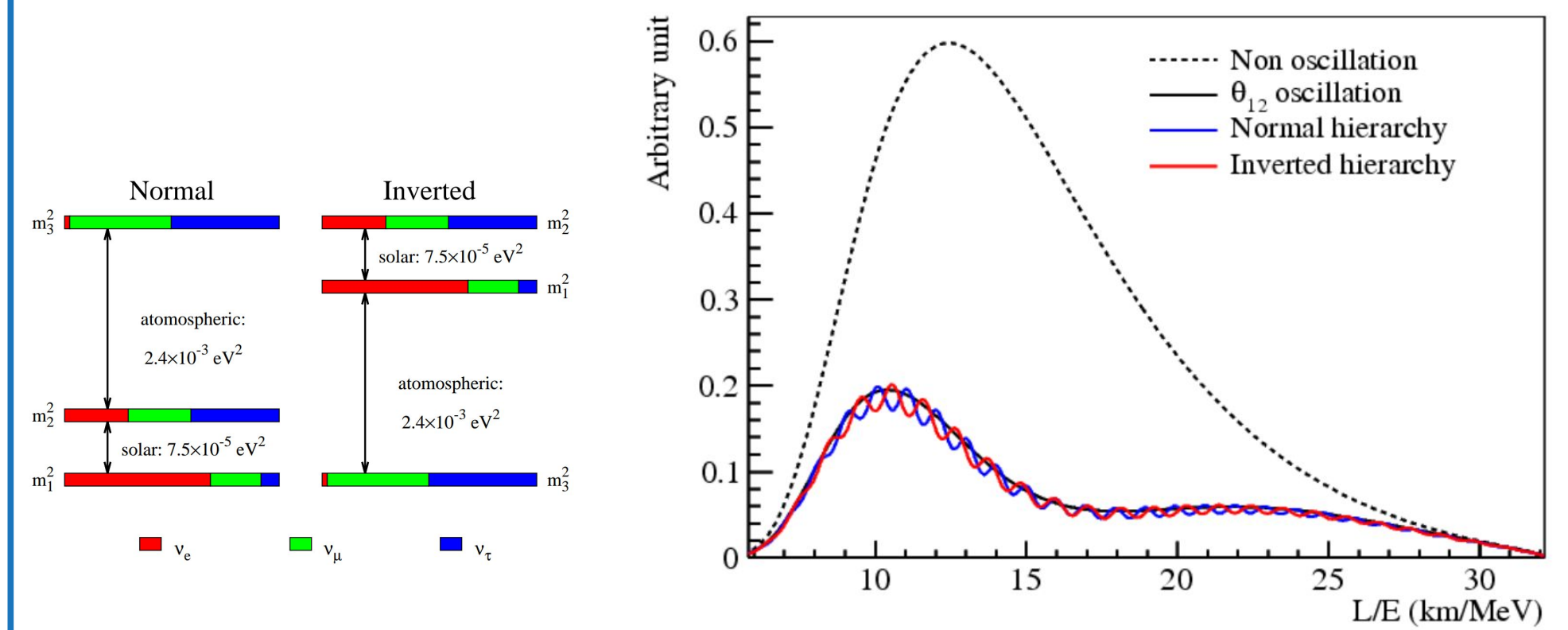


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Introduction

The Jiangmen Underground Neutrino Observatory (JUNO) is a 20 kt liquid scintillator detector that will be located at Kaiping, Jiangmen city in South China. An energy resolution of 3% at 1 MeV is required to determine the neutrino mass hierarchy (MH) by spectral analysis. In this world largest liquid scintillator detector, a good understanding of the energy response is essential for MH determination.



Statistical method

The χ^2 is constructed the following way:

$$\chi^2 = (x - \mu(\theta, \eta))^T V_{stat}^{-1} (x - \mu(\theta, \eta)) + (\eta - \eta_0)^T V_{\eta}^{-1} (\eta - \eta_0)$$

where:

- x, μ — vectors with data and model prediction.
- θ — vector with free parameters.
- η — vector with uncertainties, propagated via penalty terms.
- η_0 — default values of η .
- V_{η} — error matrix for η .

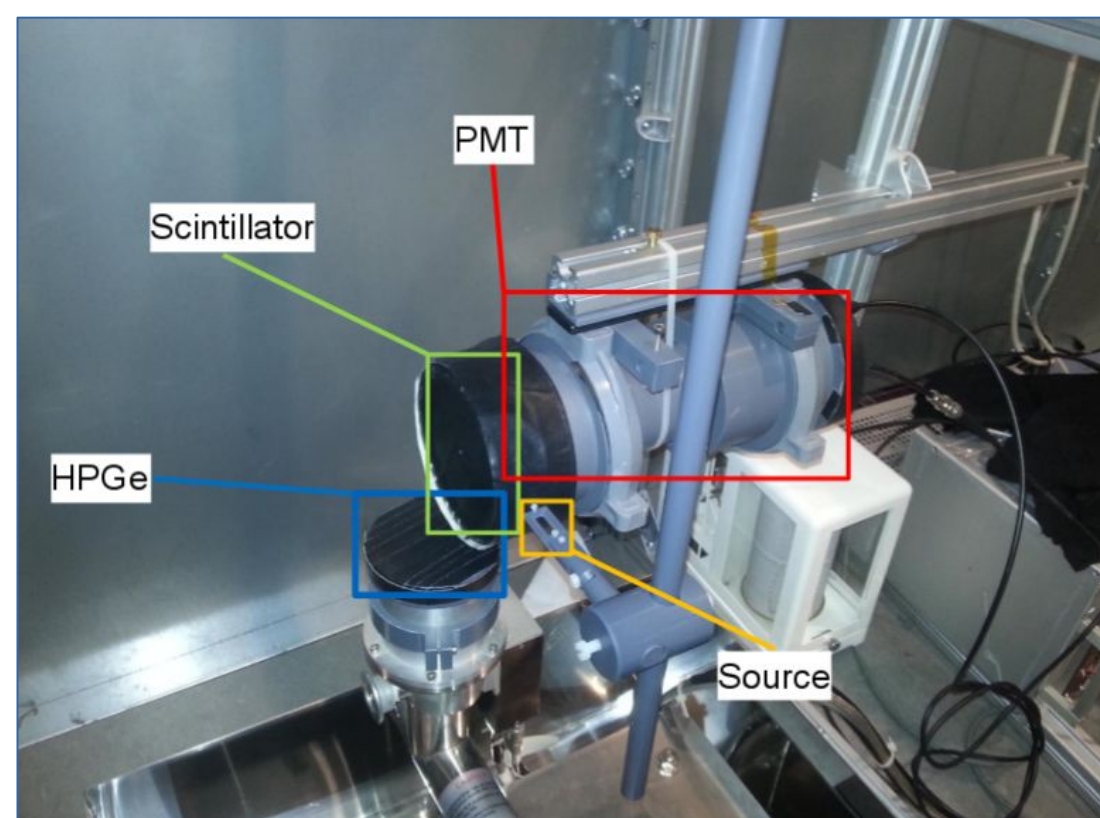
LS NL measurement

Several groups from Prague, TUM, Milan are working on LS non-linearity (NL) measurement now. The basic principle is compton coincidence technique.

$$E_{vis}^{e^+} = E_{vis}^{e^-} + 2 * E_{vis}^{\gamma(0.511MeV)}$$

$$E_{vis}^{\gamma} = \int E_{vis}^e * \frac{dN}{dE}(E_{true}^e) * dE_{true}^e$$

The method to propagate LS response from e^- to e^+ is based on the assumption that e^- and e^+ have identical behaviour while depositing kinetic energy in LS and then the gamma NL can be deduced from e^-/e^+ .



GNA features and JUNO calculation scheme

- GNA — a fitter for comprehensive physical models with large number of parameters.
- Design is based on the Daya Bay experience.
- Dataflow programming paradigm: model is built as directed lazily-evaluated graph that operates on vectors.
- Implementation: C++ (core), Python (interface).
- Built on top of: Eigen (linalg), ROOT (minimization), boost.
- Transparent multicore/GPGPU computations are on the way.
- Statistical approaches implemented:
 - χ^2 and Poisson test statistics.
 - Feldman-Cousins approach.
 - Likelihood profiling.
 - Propagation of systematics via pull term and covariance matrix.

<http://astronu.jinr.ru/wiki/index.php/GNA>

The energy spectra prediction is done in this way:

$$N_k = \sum_b D_b^k + \epsilon TM \sum_{kj} C_j^k \times$$

$$\times \int_{-1}^{+1} d \cos \theta \int_{E_{vis}^*}^{E_{vis}^{*+1}} dE_{vis} \frac{d\sigma(E_{vis}, \cos \theta)}{d \cos \theta} \frac{dE_{vis}(E_{vis}, \cos \theta)}{dE_{vis}} \times$$

$$\times \sum_r \frac{1}{4\pi (L_r)^2} \sum_c \omega_c(\vec{\theta}) P_r(E_{vis}, L_r, \Delta m_{ce}^2) \times$$

$$\times \frac{W_r}{\sum_{i'} f_{i'}(e)_{i'}} \sum_i f_{ir} S_i(E_{vis})$$

- Detector effects: energy scale nonlinearity, resolution.
- Huber-Muller antineutrino spectra for isotopes.
- SNF/off-equilibrium are not considered for sensitivity.

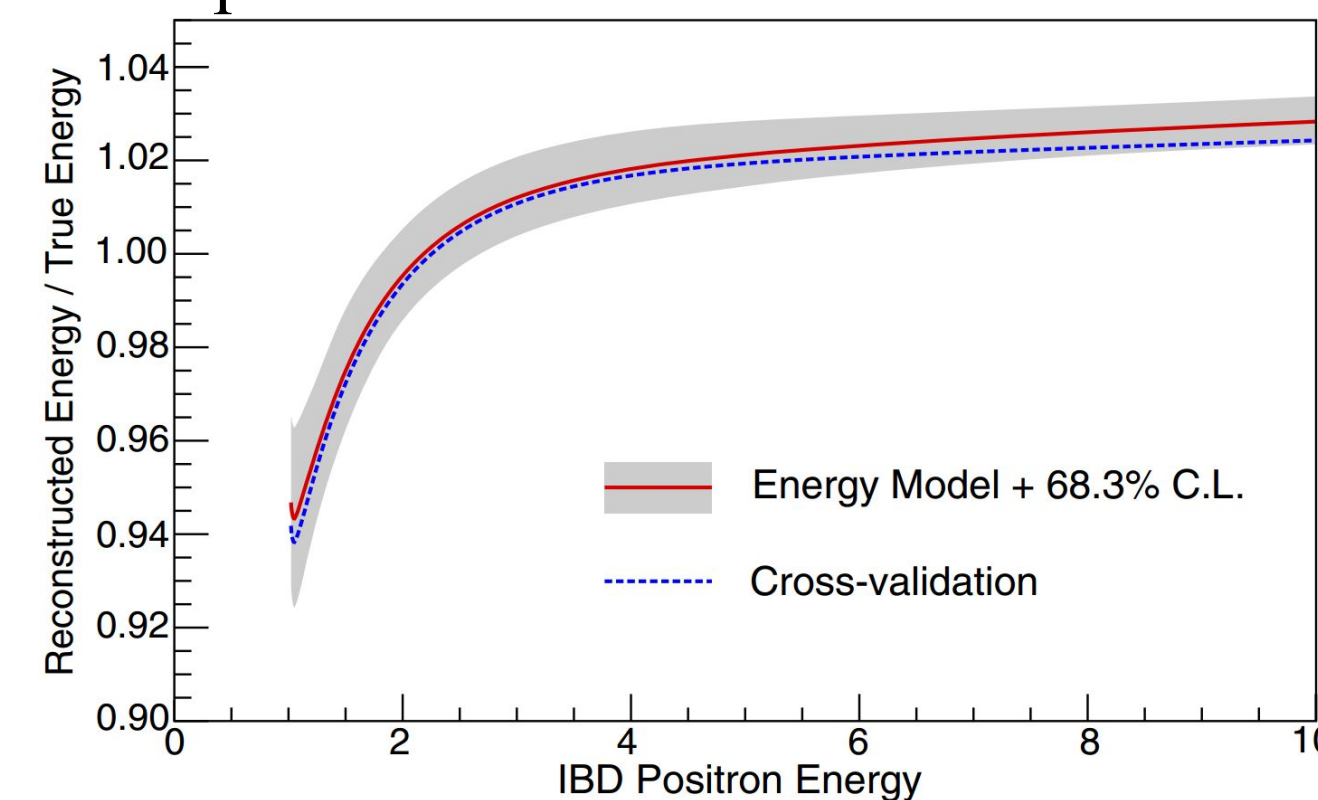
Non-linearity study based on DYB model

The Daya Bay (DYB) non-linearity (NL) curve is tuned based on various DYB gamma calibration sources and the continuous beta spectrum of ^{12}B is also used (Ref. [1]).

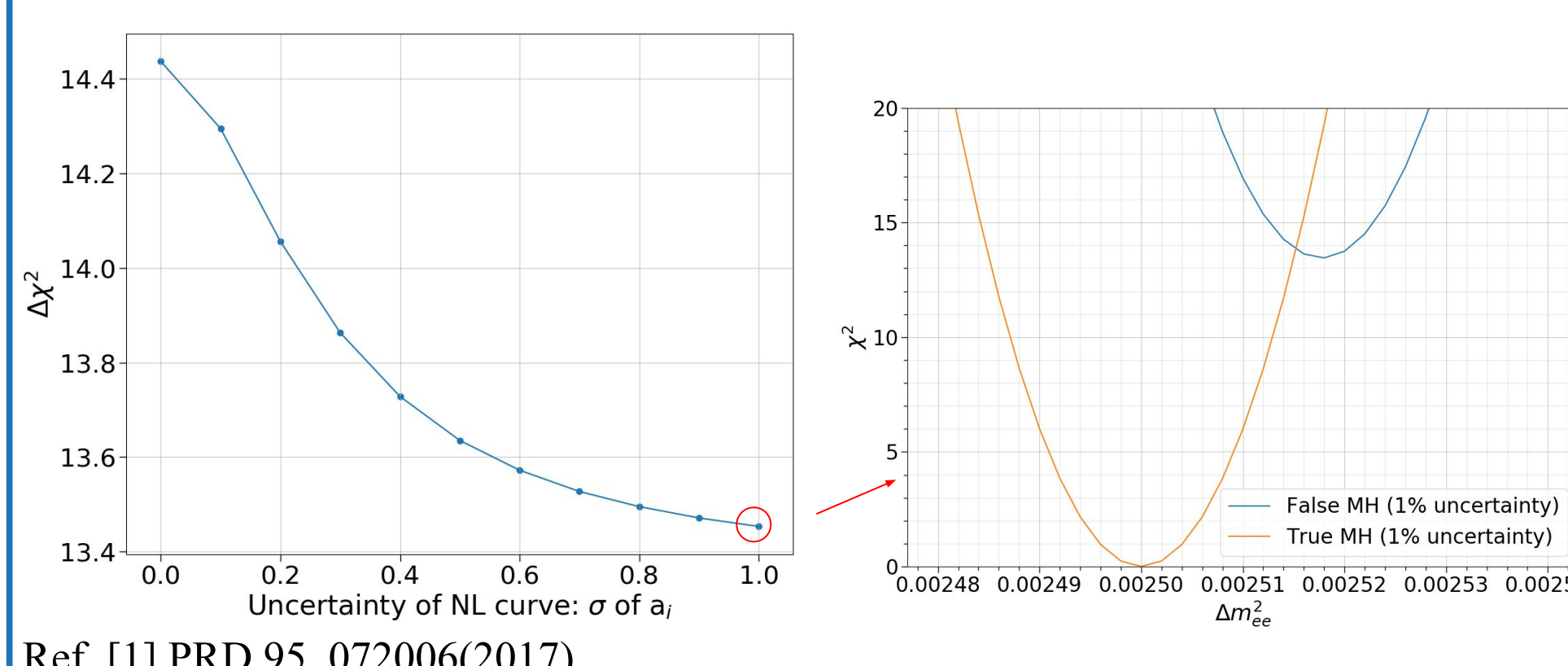
The Daya Bay energy nonlinearity is parametrized in this way:

$$\frac{E_{rec}}{E_{true}} = f_0(E) + \sum a_i (f_i(E) - f_0(E))$$

Function $f_0(E)$ is the nominal model. The functions $f_i(E)$ represent the alternative curves chosen in order to parametrize $f_0(E)$ uncertainty with parameters $a_i=0\pm 1$. From the NL curve, we can get NL response matrix.



Change the uncertainty of NL curve by changing the sigma value of a_i . Adding pull terms for a_i , and use the measured spectrum itself to calibrate the NL model. Varying the uncertainty of the NL curve and studying its impact by inspecting the $\Delta\chi^2$ between False MH and true MH. **From the left plot, we can see the overall change in $\Delta\chi^2$ is less than 1.** The right plot is the scan result for sigma(a_i)=1.



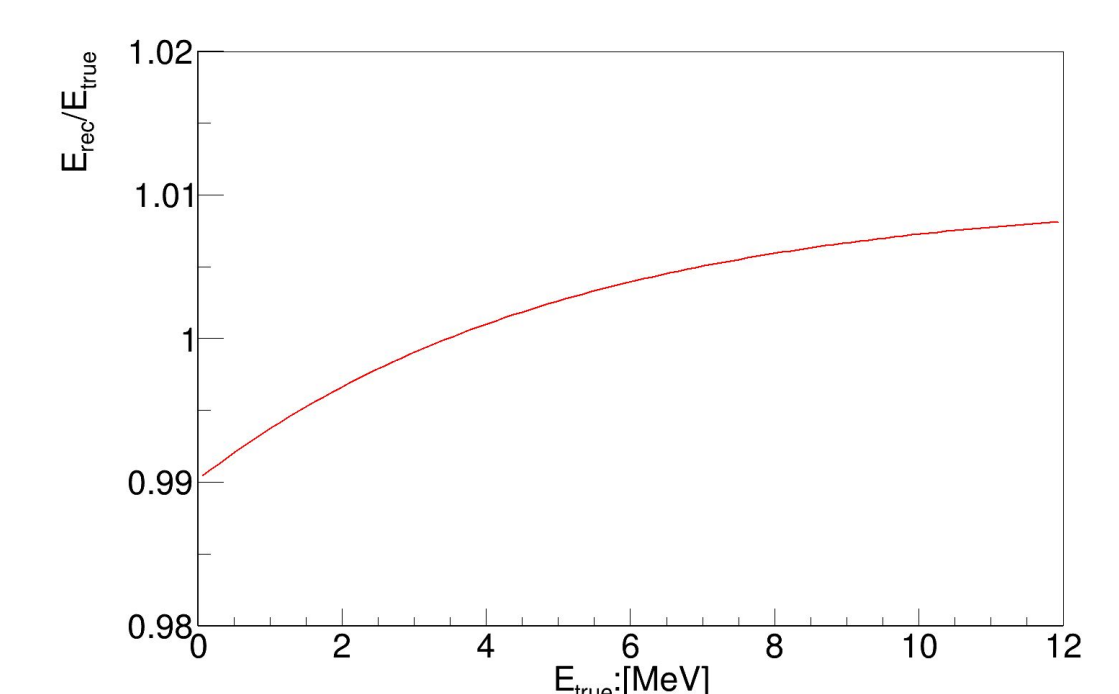
Ref. [1] PRD 95, 072006(2017)

Non-linearity study based on analytical model

Assume after the energy non-linearity correction, we have a residual nonlinearity with the form like this (Ref. [2]):

$$\frac{E_{rec}}{E_{true}} = \frac{1 + p_0}{1 + p_1 * exp(-p_2 E_{true})}$$

Here $p_2 = 0.2/\text{MeV}$, we studied p_0 and p_1 with combinations like (p_0, p_1)=(0.5%, 1%) (1%, 2%) (1.5%, 3%)
If $p_0=1\%$ and $p_1=2\%$, we will have a residual NL like this:

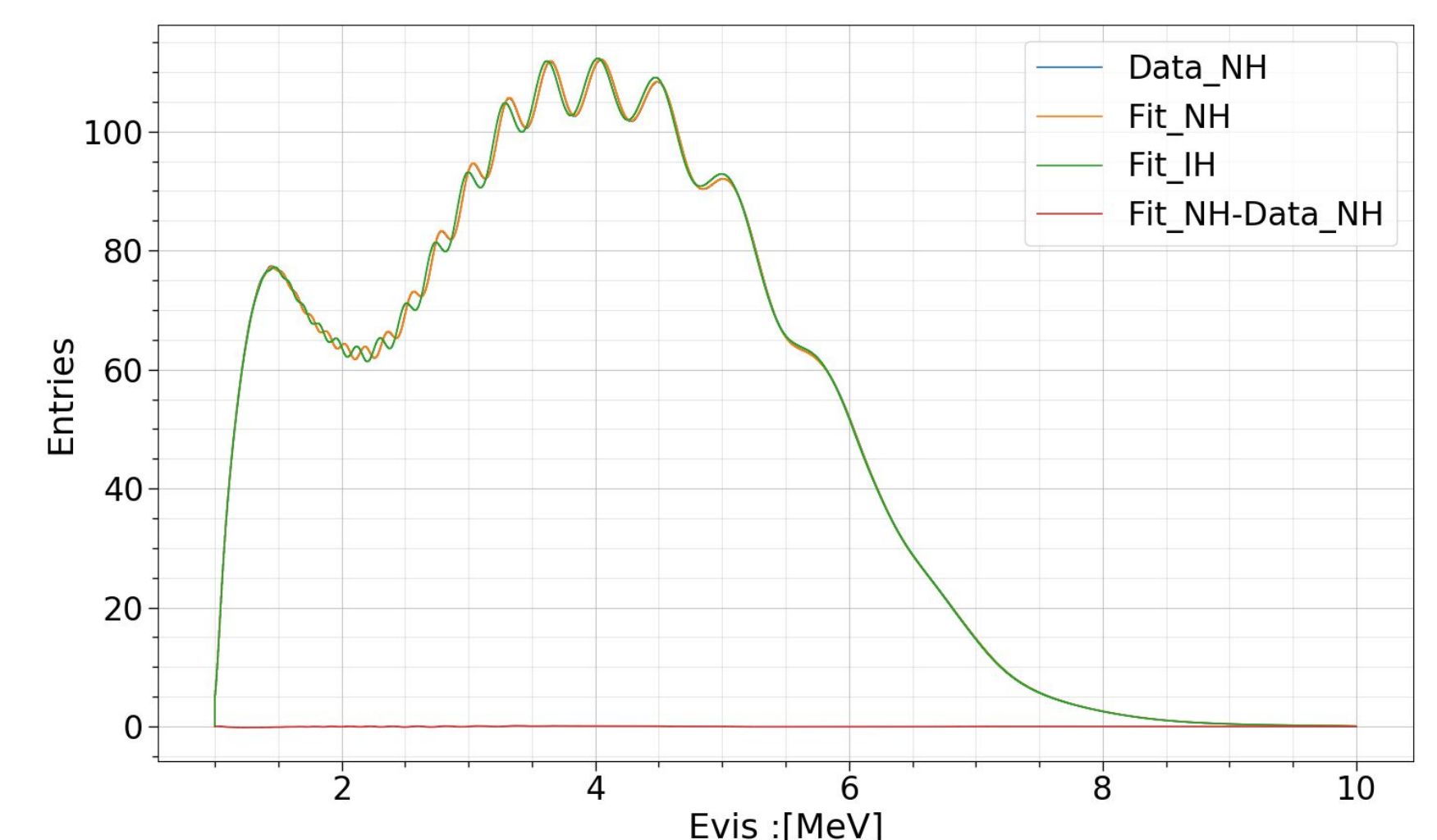


According to Ref. [2], we can measure this residual nonlinearity to some extent by the spectrum itself, based on the multiple peaks induced by Δm_{ee}^2 oscillation.

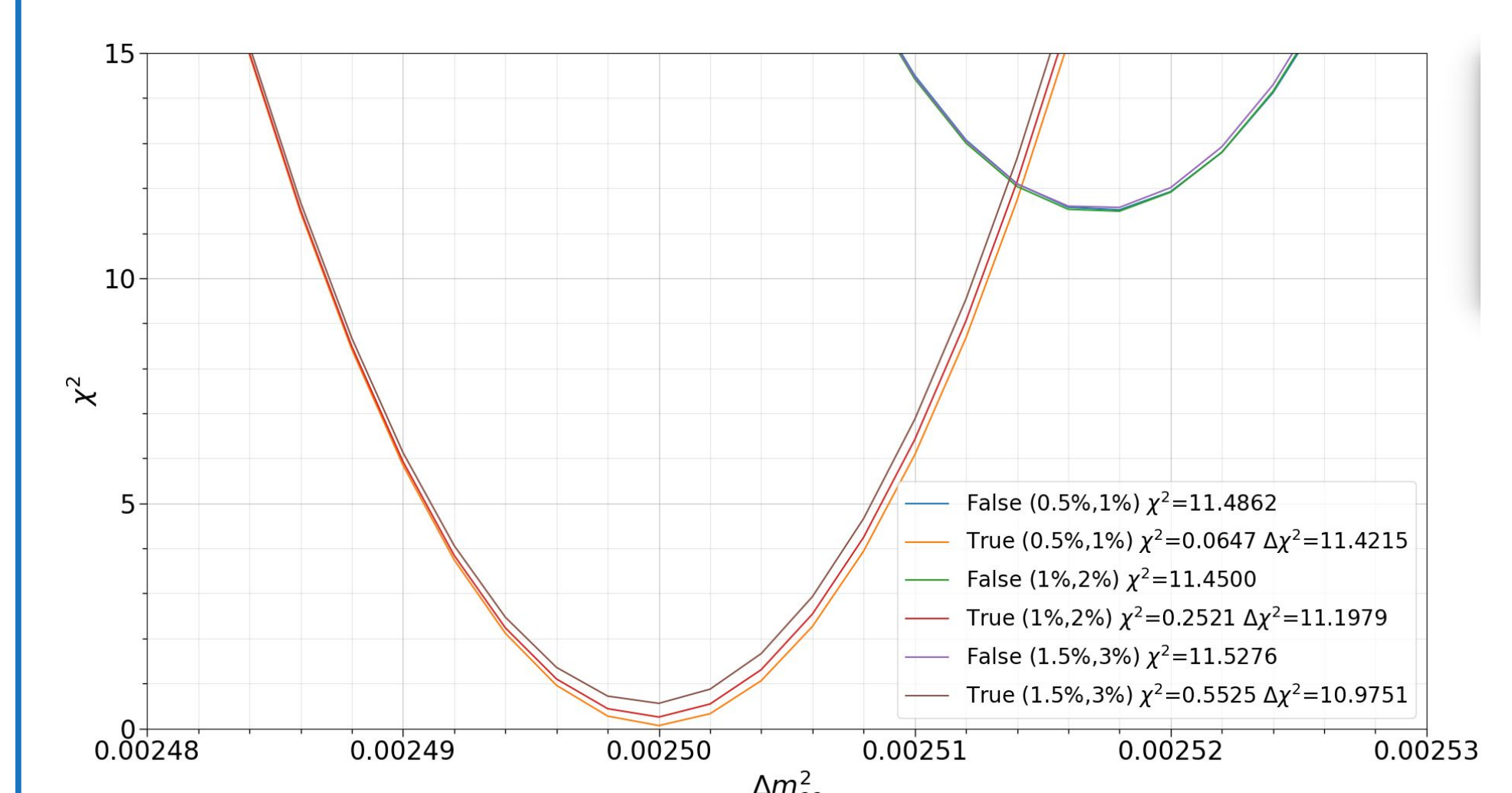
A test quadratic nonlinear function can be used in the prediction, pull terms are added, here we consider the sigma of q_1, q_2 , and q_3 are 0.02.

$$E_{rec} = q_0 + (1 + q_1) * E_{true} + q_2 * E_{true}^2$$

The best fit results for $p_0=1\%$, $p_1=2\%$ is:



Assume that the true MH is normal, then with different intensities of residual NL (represented by p_0 and p_1), using the quadratic NL function in two prediction scenarios NH (true MH) and IH (false MH), the results are as follows, the $\Delta\chi^2$ is quite stable inside this residual NL range



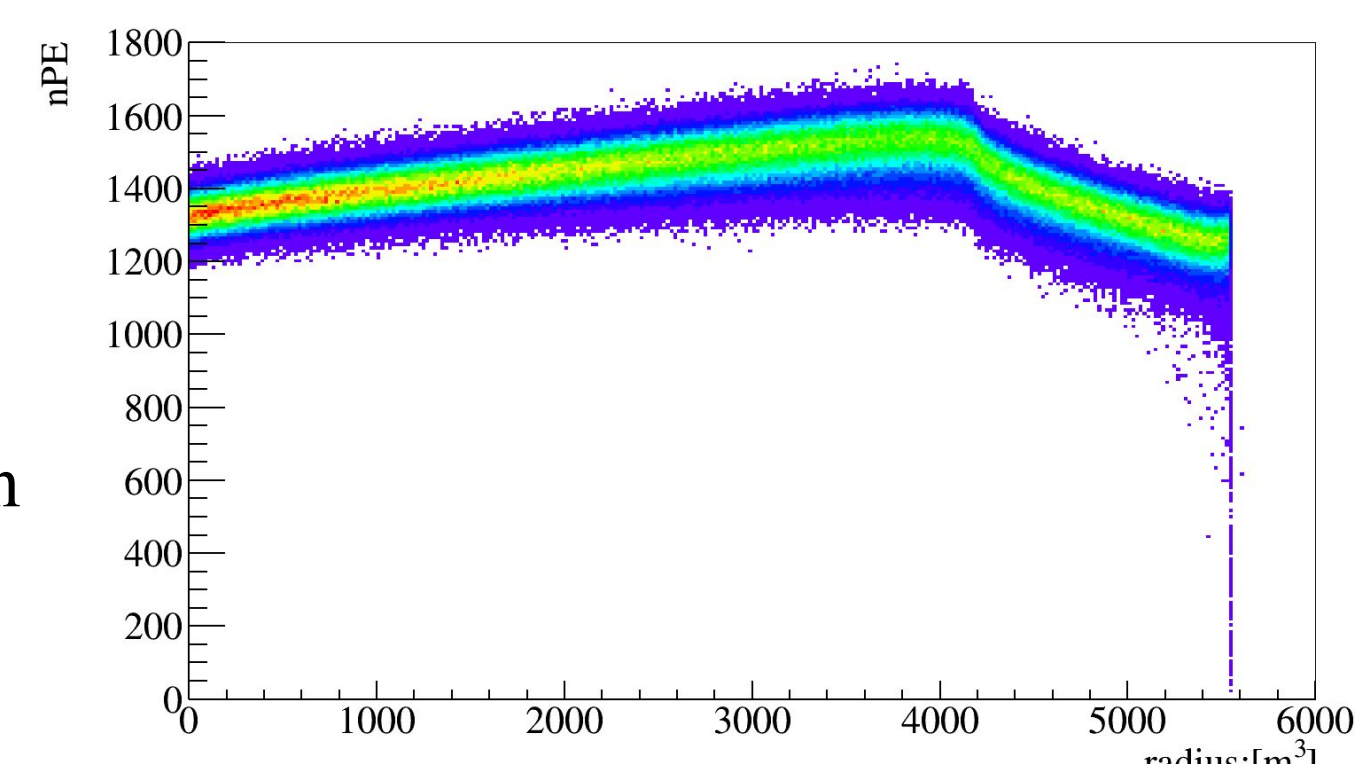
Ref. [2] PRD 88, 013008 (2013)

Non-Uniformity study

From detector center to edge, we can see clear change in the number of photoelectrons (nPE) per MeV wrt radius. Since b in the energy resolution parametrization

$$\frac{\sigma}{E} = \sqrt{a^2 + \left(\frac{b}{\sqrt{E}}\right)^2 + \left(\frac{c}{E}\right)^2}$$

is related to photon fluctuation, we can use different energy resolution at different radius. Coefficient b can be updated as the reciprocal of the square root of mean nPE/MeV at the certain radius.



How many layers is enough to catch the structure in nPE/MeV curve? A scan results is shown below. Divide the whole LS region into equal-volumed shells, apply different energy resolution in each shell.

From this plot, we can see that small improvements can be made, $\Delta\chi^2$ increase ~ 0.25 . From 10 layers on, the $\Delta\chi^2$ is almost stable.

