Scalability of Detector Technologies ATLAS High Granularity Timing Detector

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Outline

- Introduction
- Overall design
 - Constraints + (vs.) requirements \rightarrow design choices
- Some more details
 - Electronics, assembly, mechanics, cooling
- Conclusion







High Luminosity LHC



• Run 3

- instantaneous luminosity 2x10³⁴cm⁻²s⁻¹
- integrated luminosity 300/fb

• Run 4

- instantaneous luminosity 7.5x10³⁴cm⁻²s⁻¹
- integrated luminosity 3000/fb



The challenge

- The price for higher instantaneous luminosity is higher pile-up
 - About 200 collisions per bunch crossing (150 ps, 50 mm)
 - Overlapping vertices, high noise in calorimeter endcaps and forward region





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One of the tasks



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Required performance

a.k.a. what is good enough?



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Choice of technology

- Detectors with 30-50 ps time resolution and 1.3x1.3 mm² granularity?
 - Low Gain Avalanche Detectors

- Known for a few years: excellent performance before irradiation when read out by oscilloscope with high sampling rate
 - What else is needed to make a detector out of these sensors?



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see yesterday's talk by

J. Lange

Available space

Minimum Bias Trigger Scintillators to be removed → space can be used by HGTD



Radially constrained by ITk services (64cm) and beam pipe (12cm) Corresponding to 2.4 < η < 4.0 Thickness constrained to Δz = 7.5 cm (+ 5 cm moderator)



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Radiation hardness



- Max neutron fluence and dose after 4 ab⁻¹, including safety factors (not in the plots):
 - At r = 12 cm: $9 \times 10^{15} n_{eq}/cm^2$ and 9 MGy
 - 20% of sensors and ASICs (r < 30 cm) need replacement at half lifetime of HL-LHC
- To reduce radiation damage:

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 Operation of silicon detectors at -30°C using CO₂ cooling from inner detector



Moderator for tracker

Radiation level on ITk must not be increased by inserting the HGTD Moderator (borated polyethylene) needed to shield tracker from back-scattered neutrons



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Reducing the cost

• Sensors are the most expensive single component

- But, reducing number of hits per track (number of layers) degrades time resolution
- Make use of different radiation levels at different radii and pileup dependence on η Time resolution per layer is less affected at high radius and there is less pileup to get rid of

Currently proposed solution

- More hits per track at small radii by increasing overlap between sensors
- Total decrease in number of layers
- Saves both on sensors and on services and mechanics





Current design

- Two layers per endcap with sensors on both sides and higher overlap at low radii to ensure 3 hits per track
- Inner ring separated from outer staves to allow for easier replacement at half lifetime



Putting it all together





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Modules and staves

• Module

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- Sensor: 4x2 cm² with 1.3x1.3 mm² pads
- 2 ASICs: 2x2 cm² each bump bonded to sensor
- Flex: wire bonded to sensor (bias voltage) and to ASICs (signals and voltages)

Reverse order of stack-up currently preferred





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Front end ASIC

• Functionalities

- Amplifier, discriminator, time walk correction, time-to-digital converters
- Requirements

Pad size	$1.3 \times 1.3 \text{ mm}^2$]
Detector capacitance	3.4 pF	
TID and neutron fluence	Inner region: 4.5 MGy, $4.5 \times 10^{15} n_{eq}/cm^2$	
	Outer region: 2.1 MGy, $4.0 \times 10^{15} n_{eq}/cm^2$	
Number of channels/ASIC	225	
Collected charge (1 MIP) at gain=20	9.2 fC	
Dynamic range	1-20 MIPs	
(preamplifier+discr.) jitter at gain = 20	< 20 ps	
Time walk contribution	< 10 ps	
TDC binning	20 ps (TOA) and 40 ps (TOT)	
TDC range	2.5 ns (TOA) and 10 ns (TOT)	
Number of bits / hit	7 for TOA and 9 for TOT	
Luminosity counters per ASIC	7 bits (sum) + 5 bits (outside window)	
Total power per area (ASIC)	$<200 \text{ mW/cm}^2 (<800 \text{ mW})$	
e-link driver bandwidth	320 Mb/s, 640 Mb/s or 1.28 Gb/s	





Front end ASIC







Kapton Flex

• Functionalities

- Connect electrical signals between sensors/ASICs and off-detector electronics
- Mechanical requirements
 - Limited total thickness per stave allows for 300 µm per flex
 - No damage to wire bonds
- Electrical requirements



Signal type	Signal name	Number of wires	Comments
HV	1 kV max.	2	Clearance
POWER	$1 \mathrm{x} \mathrm{V}_{vdda}, 1 \mathrm{x} \mathrm{V}_{vddd}$	2	Minimize voltage drop
GROUND		1 plane	Dedicated layer
Slow control	Data, ck, (opt. +rst, error)	2 to 4	I2C link
Input clocks	320 MHz, Fast command e-link, (opt. 40 MHz(L1))	6 or 8	LVDS
Data out lines	Readout data (TOT,TOA,Lumi)	4 pairs	4 e-links differential SLVS.
ASIC reset	ASIC_rst	1	Digital





Off-detector electronics

• Functionalities

• DC/DC converters for LV, HV distribution, data serialisation, transceivers/ transmitters for optical links



Cooling

• Requirements

- To be integrated with ITk cooling system
- Operation of sensors at -30°C with stability of few degrees
- Operation of off-detector electronics at about +18°C
- Total cooling power of 20 kW



Mechanical integration

Need exact drawing of all components and plan of steps needed for installation



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R&D status

• Sensor

 Very active community also beyond HGTD: LGAD tests and sensor improvements in time resolution, active area, radiation hardness → yesterday's talk by J. Lange

• Front end ASIC

 ALTIROC0 prototype in TSMC 130 nm technology with 4 channels bump bonded to LGAD array and tested with beam in Summer 2017. Only analog part, no TDC and FIFO. Good performance, but improvements in noise level and bandwidth needed





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R&D status

• Flex

- Prototype design to test signal transmission and isolation of HV line being finalised
- Optimisation of design for full detector ongoing

• Module stack up

- Identified possible materials and glues
- Services and off-detector electronics
 - Design and optimisation of distribution ongoing
- Mechanics and cooling
 - Optimisation ongoing within task-force together with ITk and ATLAS technical coordination





Next steps

• Sensor

- More tests with newest technologies
- Arrays with larger surface and more pads
- Front end ASIC
 - ALTIROC1 prototype with 25 channels and full single pixel readout (analog+TDC+FIFO) to be tested after bump bonding to sensor in Fall 2018

• Flex

• Production and test of first prototype with few lines over longest expected distance in the next months

Module stack up

 "Dummy" (no electrical functionalities) mechanical prototype of few modules in a stave in the next months





Next task in Mainz





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Summary and outlook

- Many steps from identification of problem and possible solution to design (and construction) of a full detector
- ATLAS HGTD has to cope with very tight mechanical and radiation hardness constraints together with challenging performance requirements
- All tests done so far look promising, but a lot of work is still needed in all components
- Start in 2015 → tighter schedule than for other ATLAS phase II projects
- Prolonged R&D phase will help improving technology, but challenging for qualification of production sites and production itself

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• There is room for more collaborators to join the fun!

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