

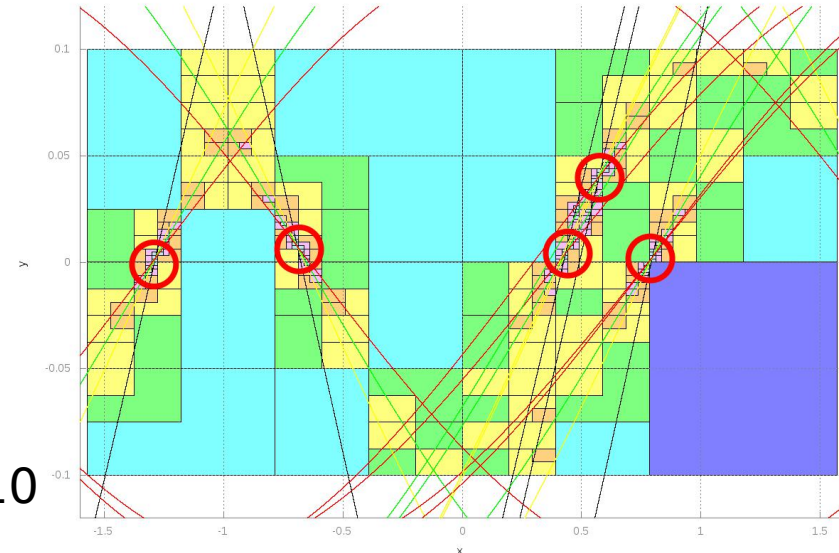
Status of DATCON - Simulation

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- Tracking was performed with fast "Divide & Conquer" Hough Trafo also in simulation with BASF2
 - By dividing the Hough Space (HS) in half, the number of sectors for horizontal and vertical direction in the HS was the same
 - >95% track reconstruction efficiency
 - >95% ROI finding efficiency with $\text{DRF} \geq 10$
 - especially limited in the low p_T region due to multiple scattering and energy loss of low-energy particles (as expected)



- Implementation and testing of HT without D&C but with checking every (predefined) sector (as on the FPGA)
 - all combinations of sector numbers possible, not only powers of 2
 - decreased number of fakes (less active sectors)
 - increased computation time on PC
- New approach for clustering of HS, not used as default
- Bachelor student helped with MVA to find maximum in performance
 - Used set of 6 parameters of the DATCON algorithm
 - Optimum ROI size (u x v) 110 x 120 pixel fixed size
 - Simulations with variable ROI size were performed, but not yet analyzed with the MVA
 - Future plan: use the MVA with all ($O(20)$) free parameters

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- Figure can be found here: [https://www.belle2.org/doc/BELLE2/PAGES/1411/](#)

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- Workflow inside the DATCON simulation

TRACKING:

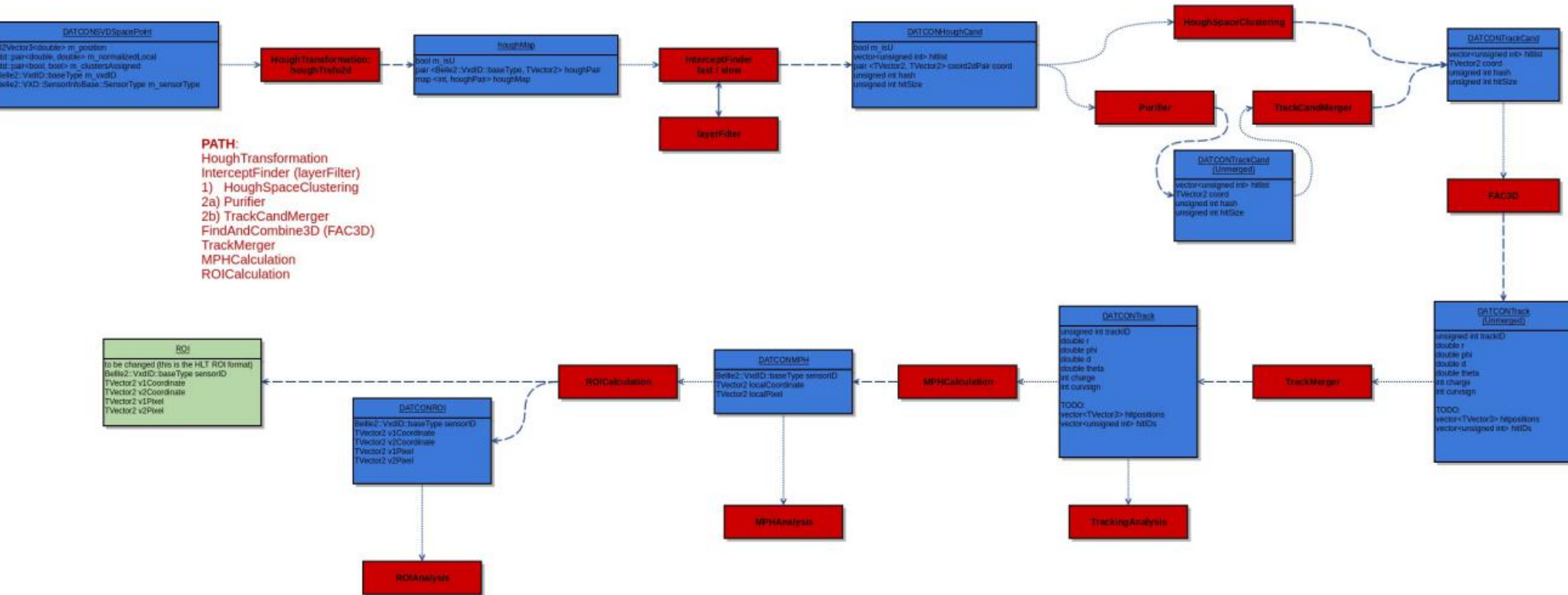
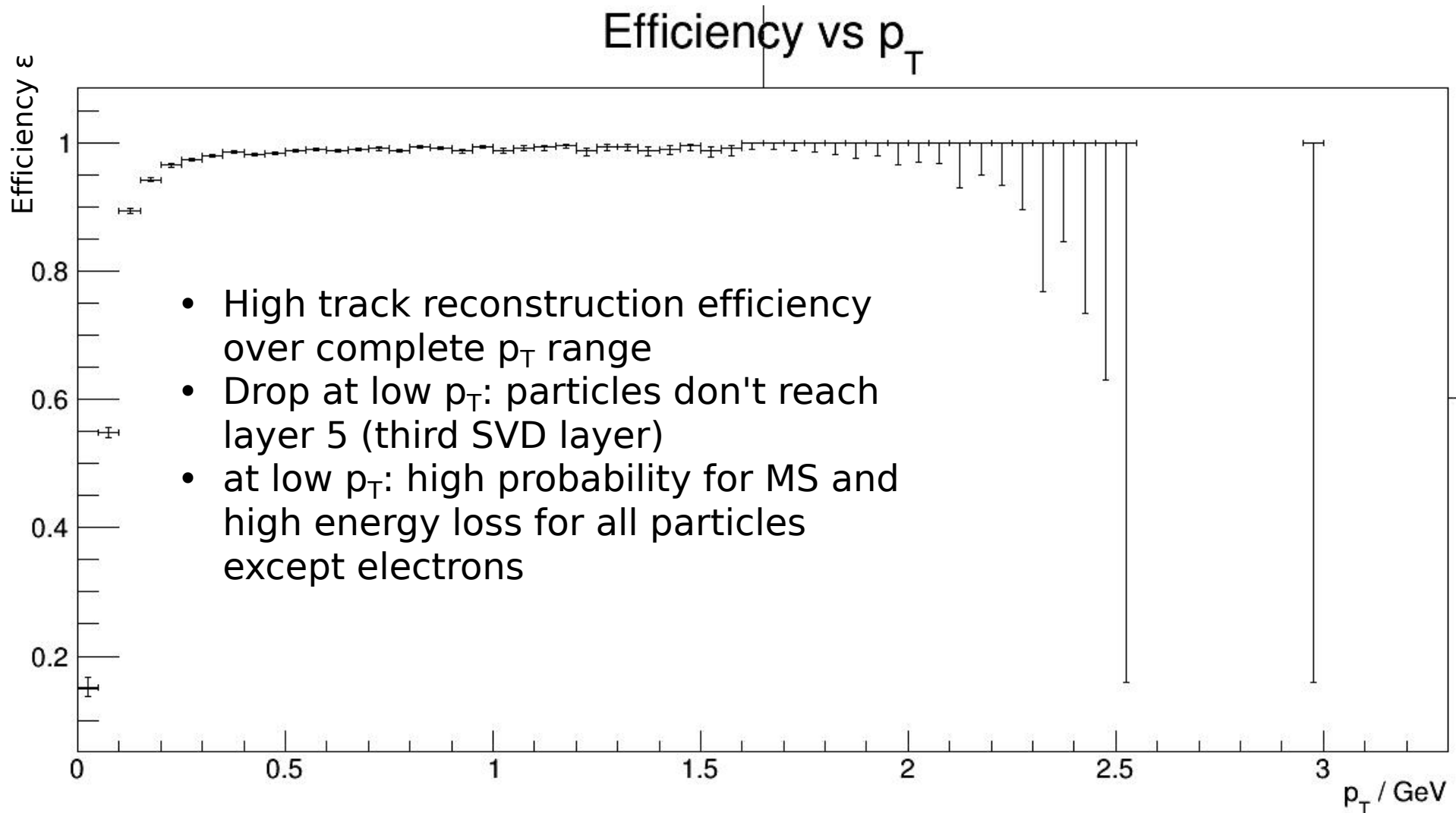


Figure can be found here:

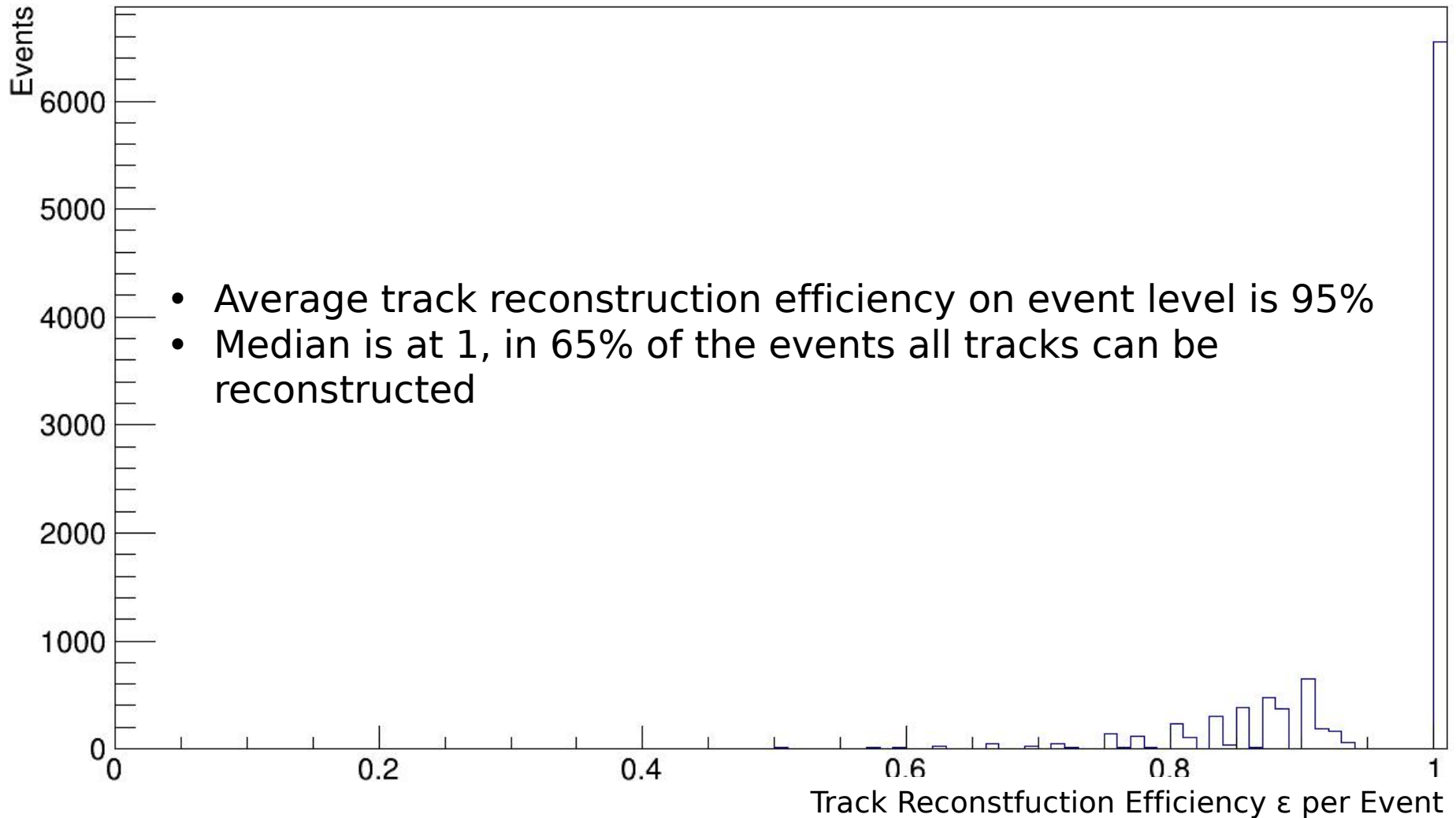
https://confluence.desy.de/display/BI/DATCON_BASF2_dataflow

Tracking - Results

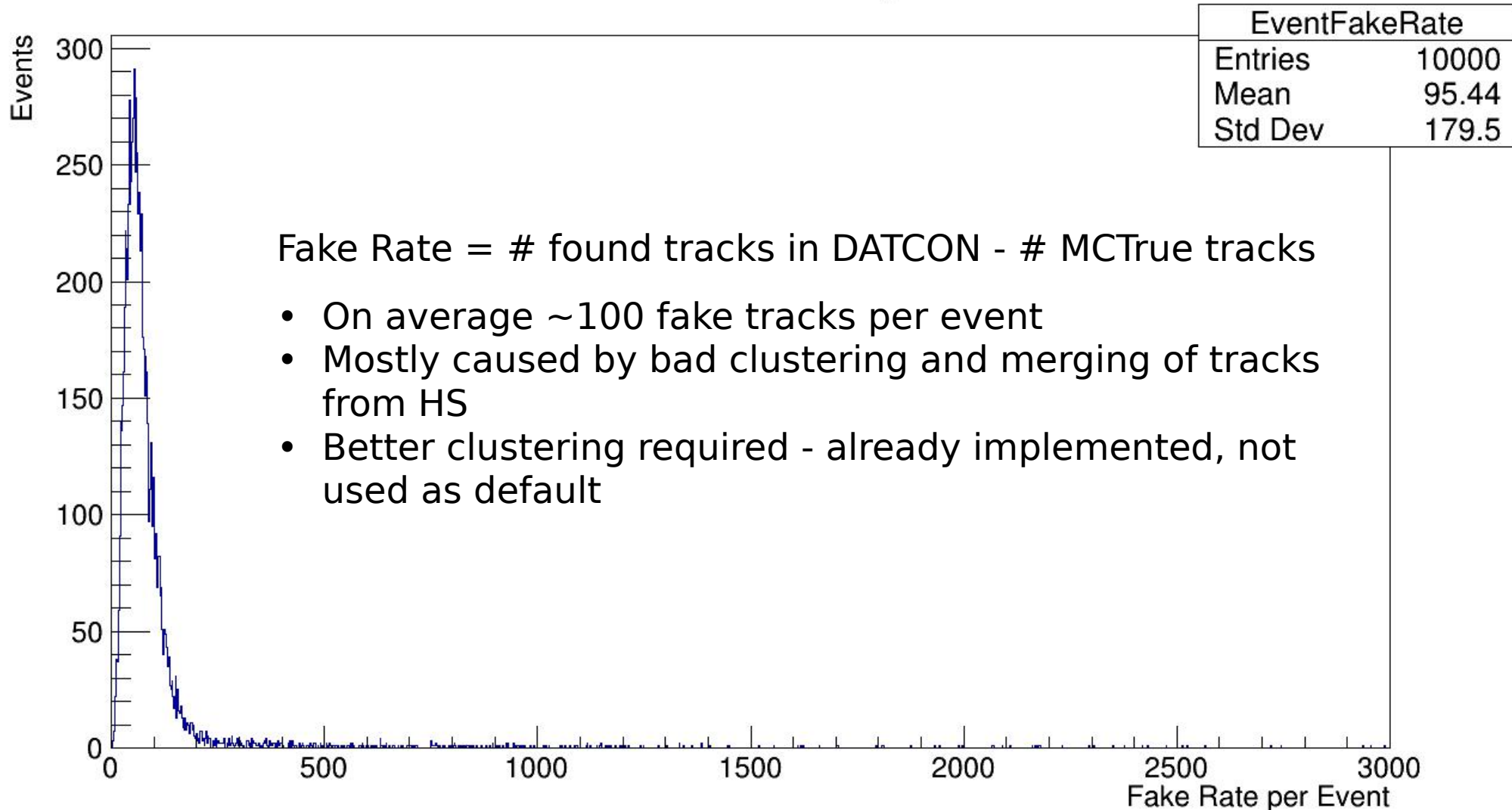
Simulation with generic Y(4S) events using full background of campaign 15

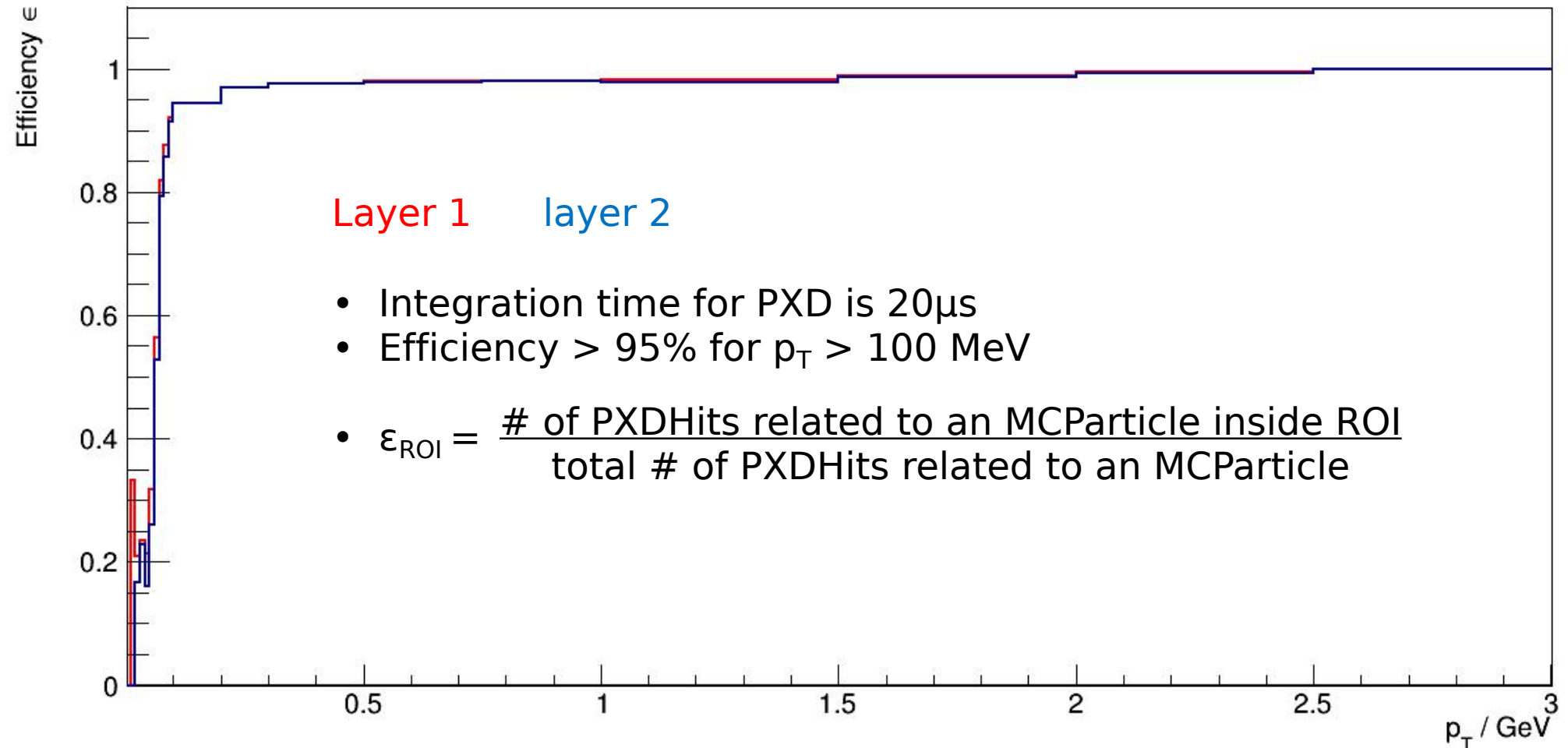


Overview of Track Reconstfuction Efficiency per Event



Overview of Fake Rate per Event

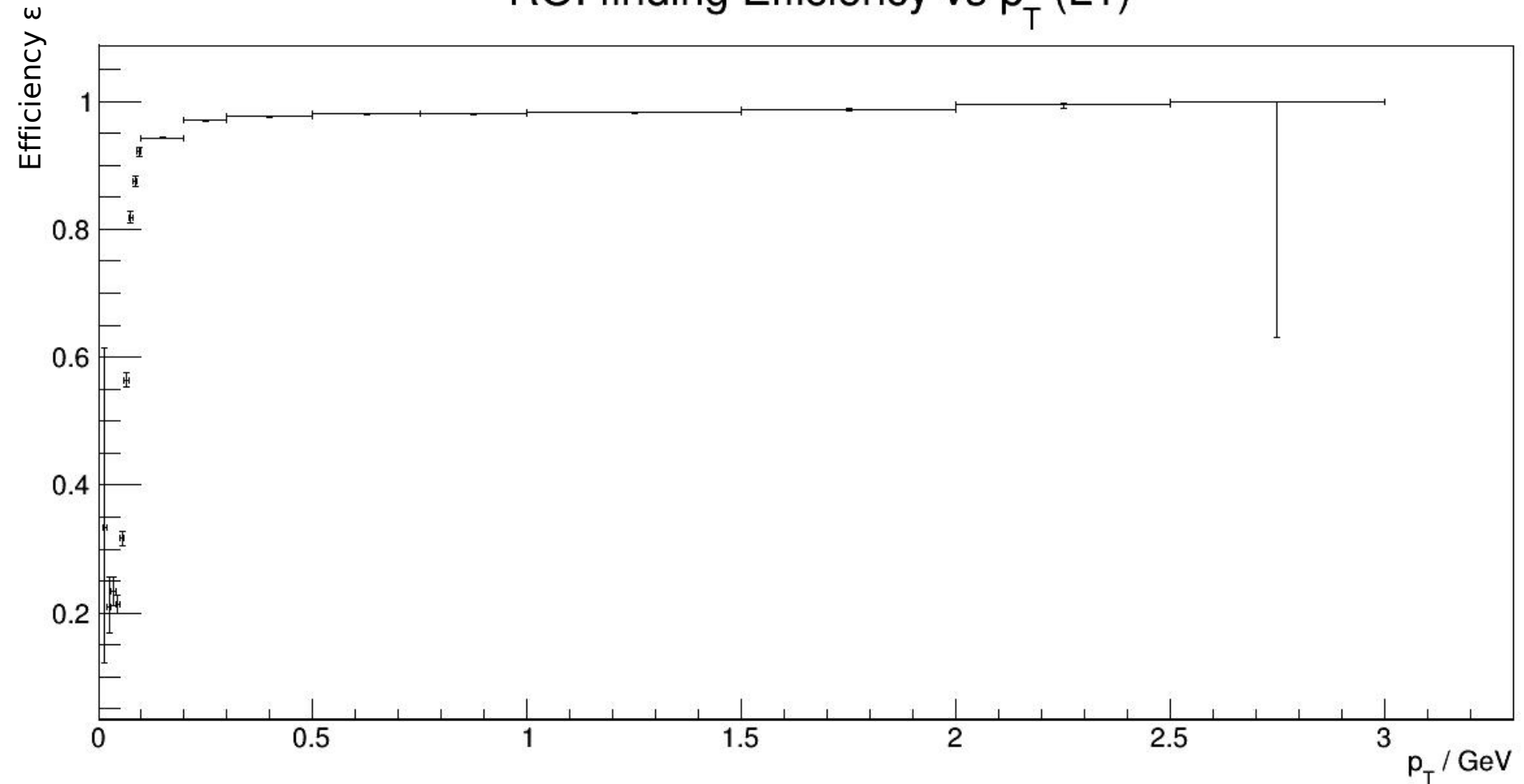




ROI Finding - Results

Same data for L1 as on last slide, but with (small) error bars

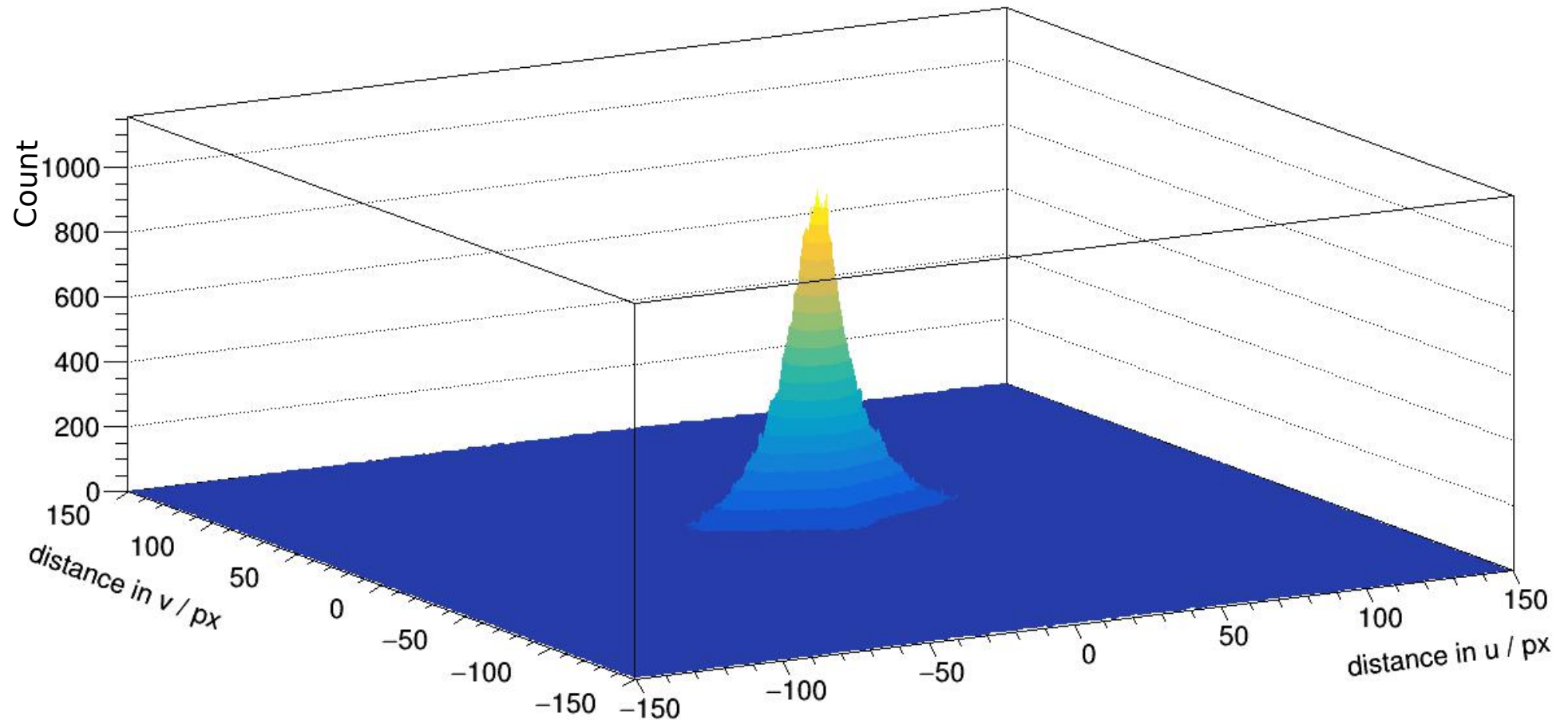
ROI finding Efficiency vs p_T (L1)



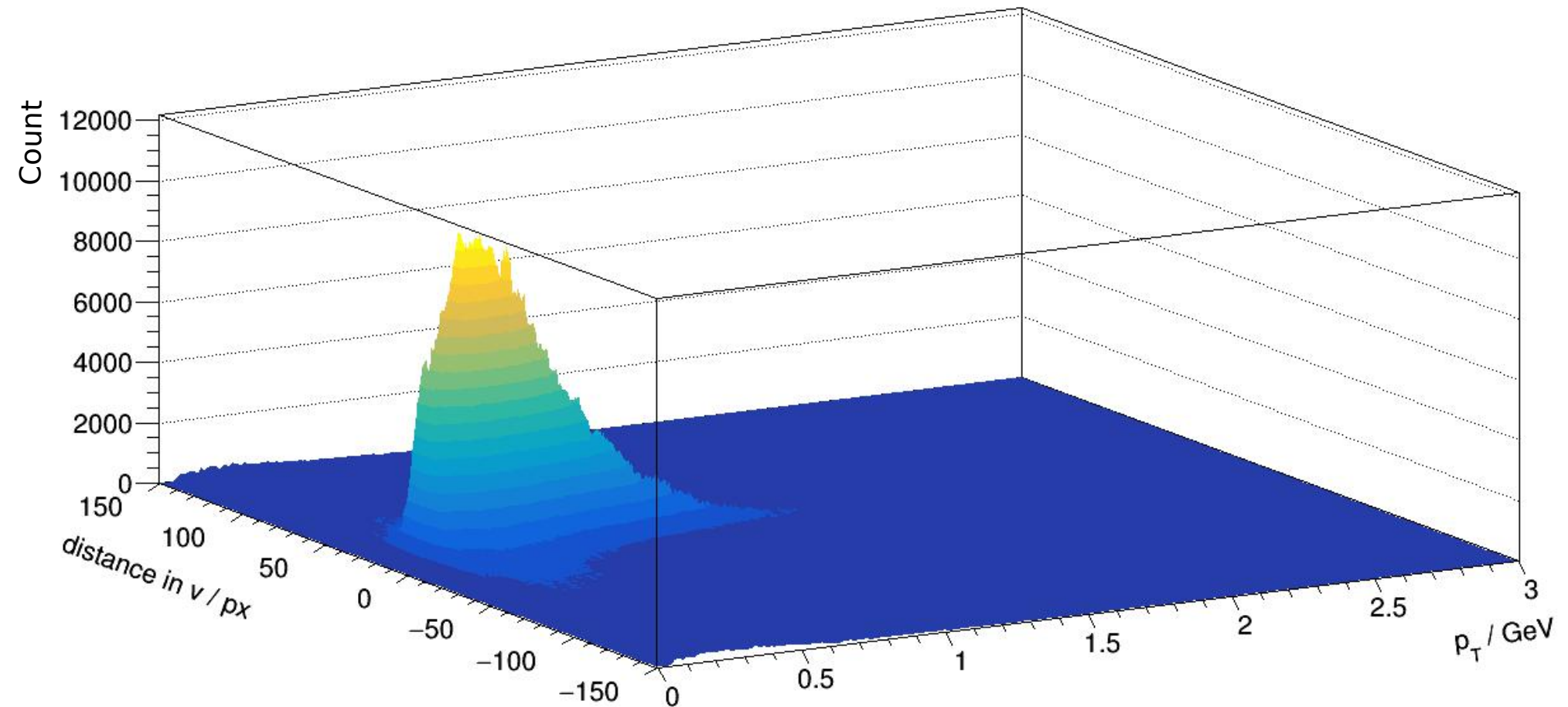
ROI Finding - Results

Residual: extrapolated (u/v) - true MC (u/v) position

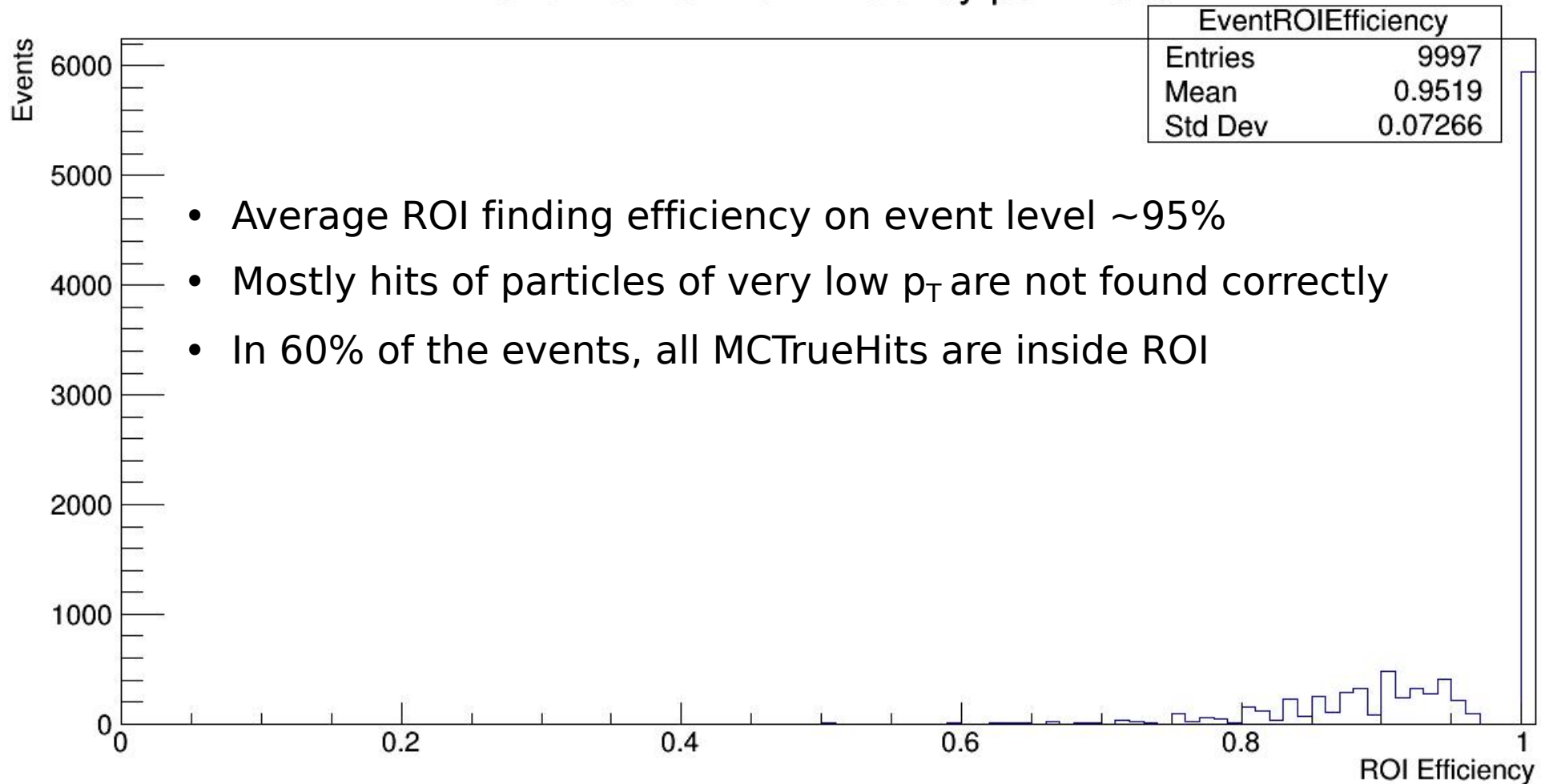
Residuals in u and v



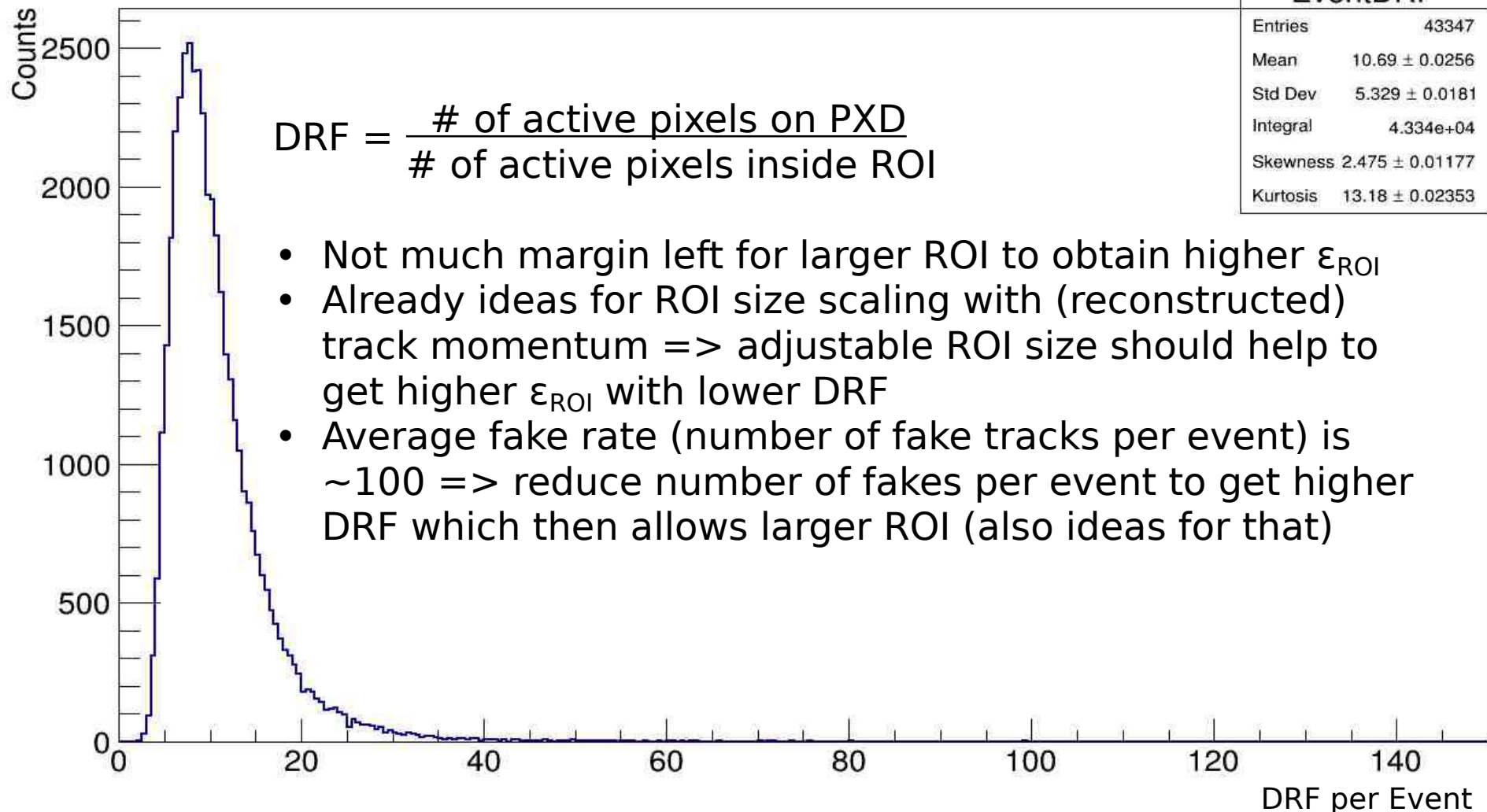
Difference in v vs p_T (in pixels)



Overview of ROI Efficiency per Event



Overview of Data Reduction Factor (DRF)



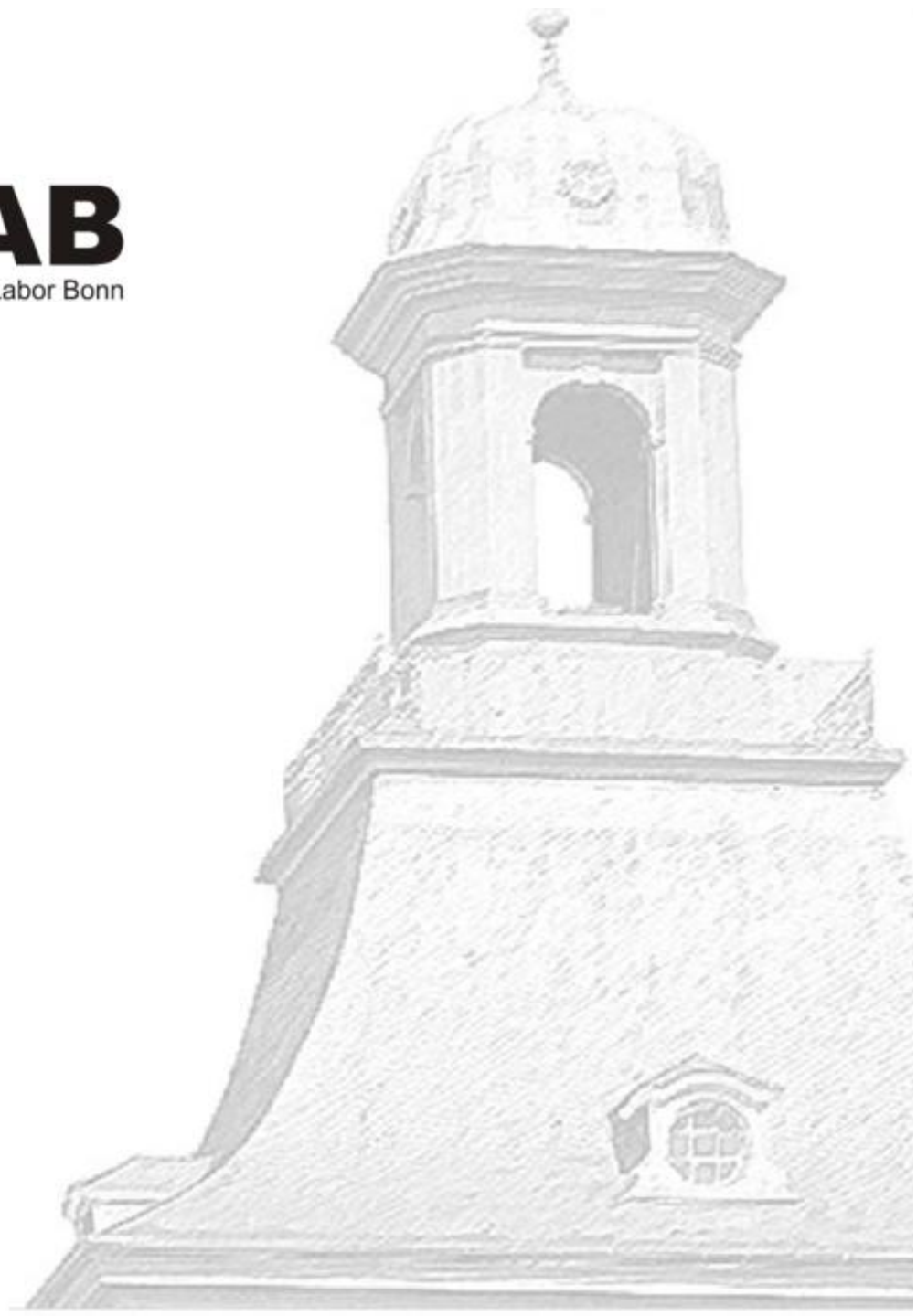
- Very good tracking performance of BASF2 DATCON algorithm ($> 97\%$) for generic $Y(4S)$ events with background of campaign 15, but
 - Quite high number of fake tracks \rightarrow crucial for data reduction factor
- Good ROI finding efficiency of $>96\%$ (complete p_T range) and DRF ≈ 10
- $O(20)$ parameters to tune for optimisation of tracking and ROI calculation
- DRF can be increased by using ROI of variable size instead of fixed size
 - $\propto 1/p_T$ or $\propto -p_T$ (first test proved the potential of this)
- Still need for optimisation of ROI finding performance for (very) low p_T tracks ($p_T < 100$ MeV) \rightarrow maybe via variable ROI sizes

- Implementation and test of complete SVD-like data chain
 - DATCON only receives SVDDigits and strip ID, not SVDClusters or space points → create these ourselves
 - trying to be as close as possible to BASF2 / real SVD data chain, considering what is possible to do on FPGA
- Change BASF2 implementation of DATCON to be very close to hardware implementation
- Simplify and refactor the DATCON BASF2 implementation
- Optimisation of parameters for HT, TrackMerger, ROI sizes (variable or fixed size),

Thank you



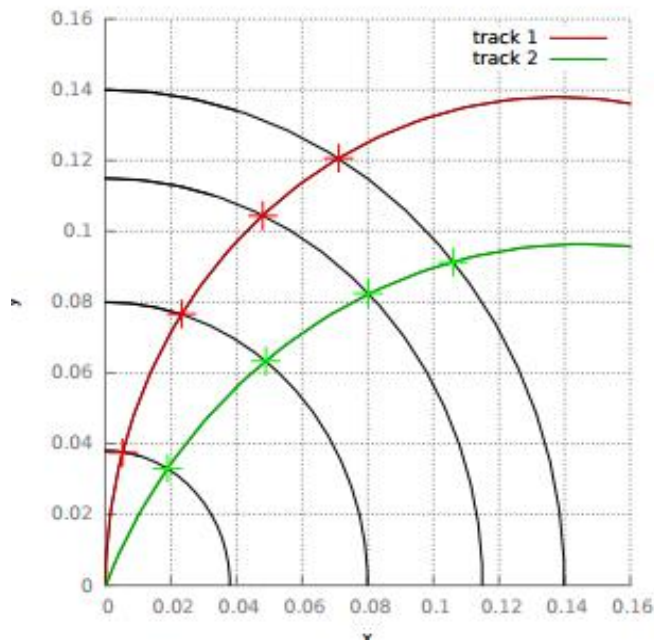
Backup



- Use of the Hough transformation:

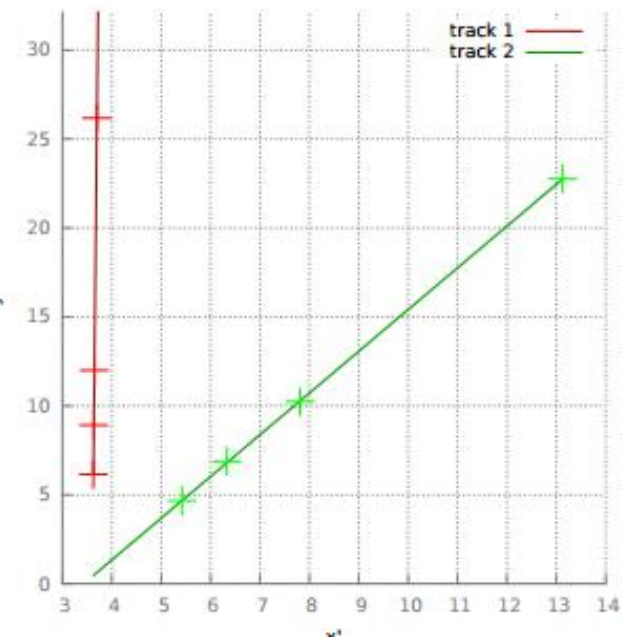
$$d = x \cdot \cos \alpha + y \cdot \sin \alpha$$

- Drawack: Can only be applied for straight line (as previously implemented on FPGA)
- For circular track a conformal transformation is needed



$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \frac{1}{r^2} \cdot \begin{pmatrix} x \\ y \end{pmatrix}$$

A large black arrow points from this equation towards the right plot.



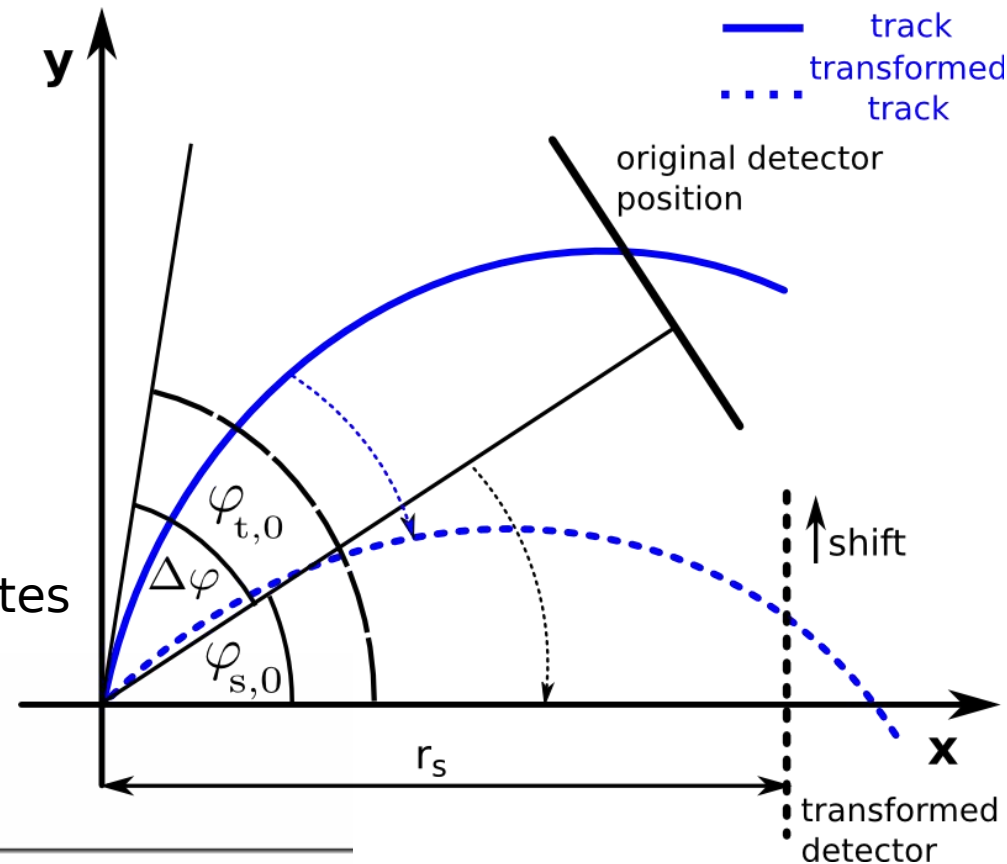
- Simulations with Y(4S) events are performed
→ results look promising, but further improvements necessary

- Also new extrapolation method implemented:
intersection of circle (= track) with straight line (= detector plane)
- Afterwards: multiplication of (x,y) with rotation matrix to obtain 3d MPH (most probable hit) coordinates

$$\Delta\varphi = \varphi_t - \varphi_s$$

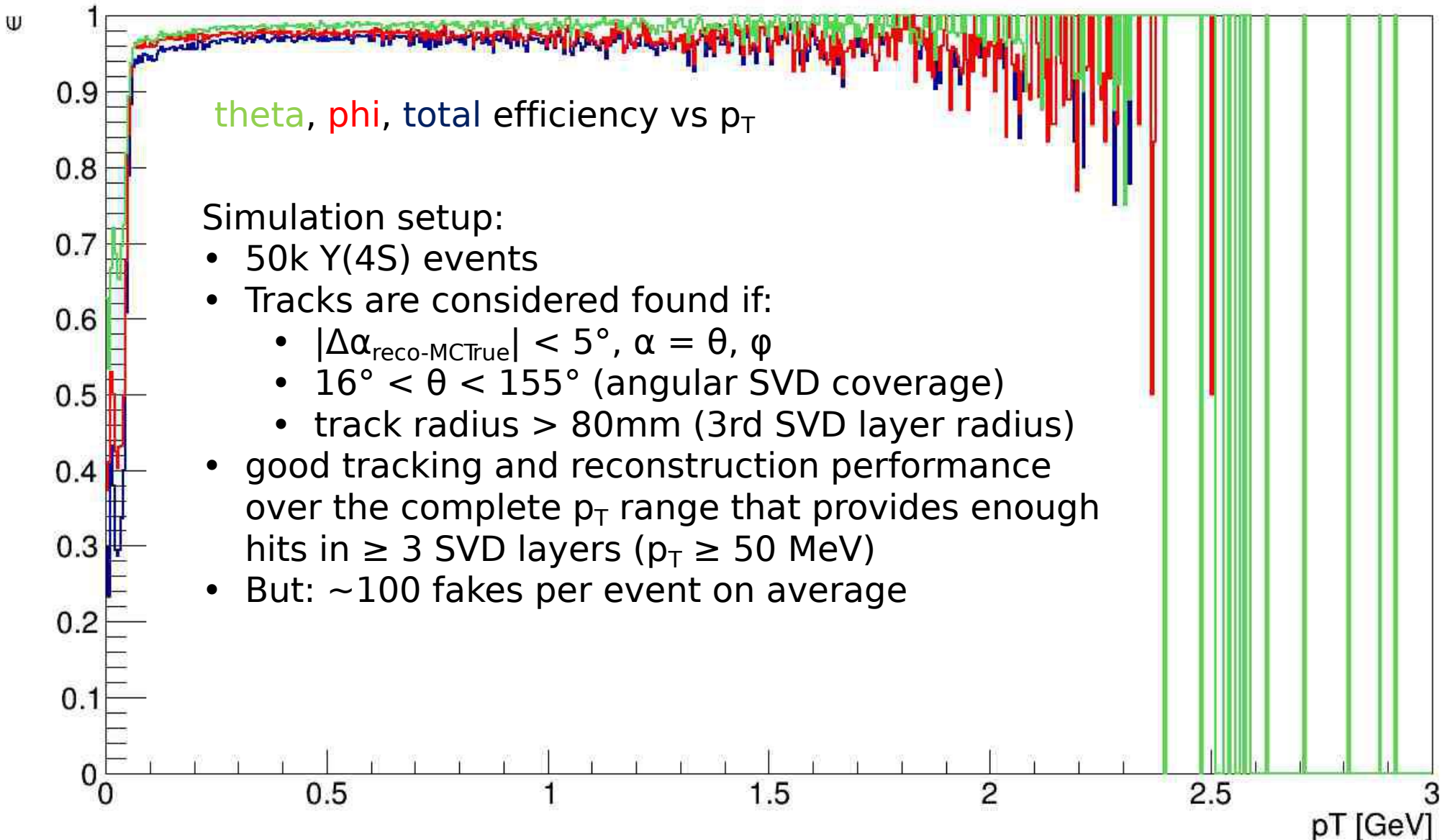
$$x = r_s$$

$$y = r_t \cdot \cos \Delta\varphi + \sqrt{r_t^2 - (r_s - r_t \cdot \sin \Delta\varphi)^2}$$

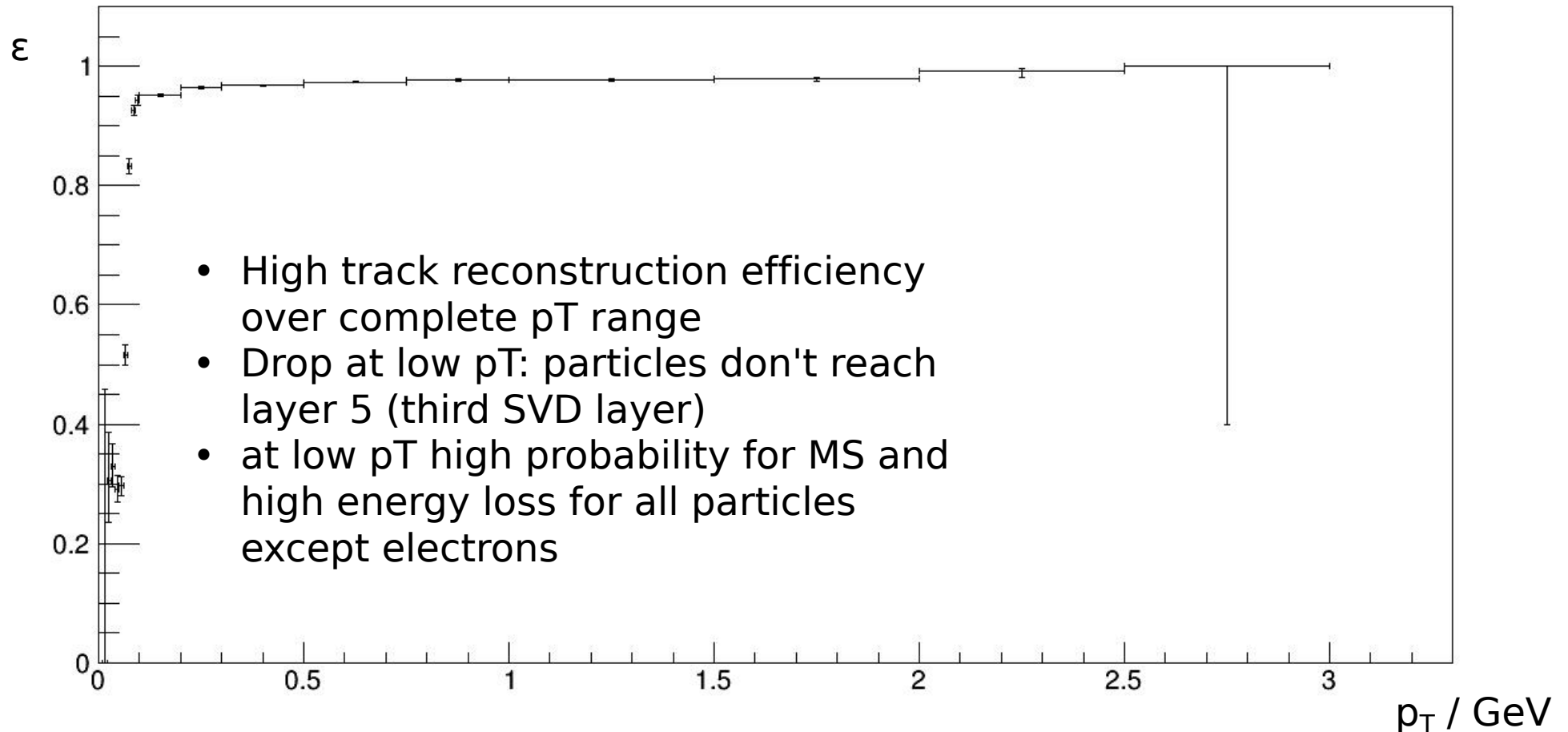


Simulation Results - Tracking Performance

Efficiency vs p_T



Efficiency vs p_T



Tracking - Results

Efficiency vs p_T

