

Operational experience and performance of the CMS pixel detector during the first LHC beams



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On behalf of the CMS Collaboration

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- The CMS pixel system and operating conditions
- Detector present status
- Calibrations
- Performance with first LHC beams
- Conclusions



The CMS Pixel System



- Total pixel area: 1 m² ⁻⁻⁻ 66 M pixels ⁻⁻⁻
- 3 barrel layers at 4.3, 7.3, 10.2cm; 53cm length
- 4 disks from 4.8 to 14.4 cm radius
- 3-hit coverage for tracks |η|<2.2
 2-hit coverage for tracks |η|<2.5
- Si Sensors: n on n, 150 x 100 µm pixels
 285-270 µm thick (BPIX/FPIX)
 - p-spray BPIX and p-stop FPIX
- PSI-46 Read Out Chips (ROC)

10 years of design, construction and commissioning.

Installation in Summer 2008





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Cosmics and LHC first beams



Fall 2008 CMS running with cosimcs Nov 2009 beams circulating at 450 GeV Recorded about 10 μb^{-1} at $\sqrt{s}=900$ GeV Dec 2009 beam energy of 1.18 TeV Recorded about 0.4 μ b⁻¹ at $\sqrt{s}=2.36$ TeV 23rd March 2010 beams circulating in LHC at 3.5 TeV 30^{th} March 2010 first collisions at $\sqrt{s}=7\text{TeV}$ Recorded 18 nb⁻¹ at $\sqrt{s}=7$ TeV (up to now)



The CMS Pixel System





 $V_{bias} = 150V BPIX / 300V FPIX$ Coolant temperature 7.4°C Sensor temperatures ~ coolant +6°C



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Detector status



- 2008 insertion of the pixel detector into CMS
 - Calibration/cosmic running
- Spring 2009 extraction of the FPIX, recovered 5%, re-insertion
 - re-calibration, cosmic running and first beams
- 2010 running at $\sqrt{S}=7TeV$
- 98.4% of the pixel detector is in operation (99% of BPIX, 96.9% of FPIX)
- Dead modules, excluded from the read out, mainly due to:
 - broken wire bonds
 - missing HV connections
 - no\slow analog readout
- Most failures are present since installation



Clusters Lavert (on track)

-2

-30

2

-2

-3

Clusters Layer3 (on track)

2

0

-1

-2

-3

Layer2 (on track)

Global

Globalo

Globalo



-20





- Dead pixels due to:
 - (a) ROC pixel cells which do not work for some reason (known from module tests)
 - (b) Si-sensor cells which do not work
 - (c) The bump-bond between the ROC and sensor is broken
- Dead pixel maps:
- only modules in the read out
- all modules superimposed on ONE single module per Layer
- includes masked pixels, double column

Layer 1	1.8x10 ⁻⁴
Layer 2	1.9x10 ⁻⁴
Layer 3	1.2x10 ⁻⁴



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Detector calibration



- with calibration runs:
 - Standard DAQ parameter calibration
 - ADC gain and pedestal determination: convert the pixel charge measurements from ADC counts --> charge units
 - absolute threshold optimization
- with cosmic runs and colliding beams:
 - Spatial alignment
 - Timing alignment
 - Effective threshold evaluation
 - Lorentz angle measurements





- Pixel detector more sensitive to smaller charges
 - Reduce the mean and the spread of the comparator thresholds (Vthr) from the values used during the module tests and 2008 cosmic runs.
 - Iterative procedure, using lower and lower internal calibration signals (Vcal) and measuring the Vthr at which the pixels are still 100% efficienct
 - Trim bits are used to equalize pixel to pixel Vthr variation

Mean absolute threshold value of 2457e-REMARK: Due to time walk the minimum hit signal that fires the discriminator threshold in time with the trigger bunch crossing is higher (~800e-) than the absolute threshold In-time threshold can be evaluated comparing data/MC





Timing alignment



- First timing alignment: equalization of pixel module delays measuring the length of the optical fibers, cables
- Coarse scan of the pixel detector latency in steps of 25ns measuring the pixel hit efficiency with cosmic tracks
- Fine adjustment (steps of 6ns) of the clock phase vs trigger signal with first beams (2009): optimal clock phase maximizes cluster charge and size





Timing alignment



- More accurate timing optimization with efficiency measurements @ 7TeV (2010)
 - BPIX to be delayed by additional 2ns vs FPIX









- A bias scan check for data at 7TeV
 - Hit efficiency vs V_{bias}
 - Hit detection efficiency -> extrapolating a track to the pixel sensor to check a compatible hit (valid hit)
 - ε = Σ valid / Σ(expected)





Lorentz Angle



- Measure the Lorentz Angle (Θ_{IA}) with two methods.
 - n-in-n pixels and large B -> Lorenz drift of the carriers along x direction in the barrel
 - Measure of Θ_{LA} to correct hit position.

(1) minimum cluster size (cosmics)

- the charge spread over neighboring pixels depends on α (track incident angle)
- minimum cluster size for charges produced along the drift direction: $\cot \alpha_{min} = \tan \theta_{LA}$

 $\Theta_{LA} = 22.2 + 0.1^{\circ}$

this method is not suitable for collision data where $80^{\circ} < \alpha < 100^{\circ}$







Lorentz Angle



track

(2) grazing angle method (collision data in BPIX)

- use well reconstructed tracks so that the path through the detector is known
- for each pixel in a cluster determine the drift distance in x from the track (d)
- averaging over many tracks: evaluate d vs depth
- slope of the linear fit $--> \Theta_{LA}$
- long clusters in y needed -> select tracks with shallow

impact ("grazing") angle

 $\Theta_{1A} = 21.4 + 0.6^{\circ}$



√s=900GeV B=3.8Tesla

z.E

The results from collision data and cosmic data agree !!!

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- Number of pixel clusters in minbias events @900GeV
- Data compared with PYTHIA MC event generator^(*)
- Good agreement BUT excess of large multiplicity events
- High occupancy events observed since the first collisions
- large multiplicity of pixels in a cluster, clusters, tracks and bad quality reconstructed tracks



^(*)A. Moraes, C. Buttar and I. Dawson. European Physics Journal C, 50 (2007) 435

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Background events





- many pixel clusters in the FPIX and long clusters (horizontal tracks) L1 L2 BPIX
- source of these events could be beam-gas interactions in the vicinity the interaction point or satellite collisions.
- large event size >1Kpixels/FEDch. -> in error cascade (overflow, timeout, loss of synchronization) -> FED firmware upgraded to automatic resync

Beam-gas trigger veto or combined cuts on cluster shape, track quality, and good vertexing requirements efficiently remove background



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- Number of clusters measured in the pixel detector in minbias events @ 7TeV
- Different MC tuning compared



- Data and MC in good agreement
 @ 0.9, 2.36, 7 TeV
- Discrepancies depend on MC tuning
- No single tuning which satisfies the comparison at all energies and cluster multiplicities





- Normalized cluster charge and size distribution in barrel and endcaps @ 7TeV
 - Charge scaled by track path length in the pixel sensor to the sensor thickness





Performance – Hit Resolution



Intrinsic position resolution measured for the barrel in the overlapping regions:

- Select tracks p_{t} >2.5GeV/c with two hits in the same layer
 - $\Delta x_{hit} = x(hit1) x(hit2)$ measured hit difference
 - $\Delta x_{pred} = x(pred1) x(pred2)$ predicted hit difference
 - $dd = \Delta x_{hit} \Delta x_{pred}$ double difference
 - $\sigma(dd)^2 = \sigma(\Delta x_{hit})^2 + \sigma(\Delta x_{pred})^2$
 - $\sigma(\Delta x_{hit})^2 = 2 \sigma(x_{hit})^2$ same resolution both modules
 - $\sigma(\Delta x_{pred})^2$ includes MS and rotational misalignment
- Advantages of overlap method:
 - $\sigma(\Delta x_{pred})$ more precise than $\sigma(x_{pred})$
 - extrapolation of tracks over short distances (~1cm)
 - $\sigma(dd)$ independent on translational misalignment





Extrapolated track excluding the layer under study



Performance – Hit Resolution



- Use overlap regions at least 20 tracks
- big pixels at the edge excluded
- Resolution evaluated both in x (top plot) and y (bottom plot)

 $\begin{array}{l} 12.7 \pm 2.3 \ \mu m \ along \ X \\ 28.1 \pm 1.9 \ \mu m \ along \ Y \\ \end{array}$ Simulation: $\begin{array}{l} 14.1 \pm 0.5 \ \mu m \ along \ X \\ 24.1 \pm 0.2 \ \mu m \ along \ Y \end{array}$

- Good agreement between data and simulation
- More statistics needed with high luminosity runs!
- Study the dependence on the track pt









- The pixel detector has been commissioned with cosmic muons and first beam collisions
 - Timing adjustment
 - Lorentz angle
 - Absolute threshold
- Overall 66M channels, 98.4% detector is operational
- Pixel detector performance with data at 0.9, 2.36, 7 TeV collisions:
 - data-MC comparison: good agreement -> detector behavior well under control
 - efficient removal of background events
 - detection efficiency over 99%
 - hit resolution 12.7 μ m along X 28.1 μ m along Y

Ready for physics analysis with LHC data !



Backup slides





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In-time threshold



Small pulse (blue) reaches a given threshold value later than large pulse (red)

- Time Walk is difference in time to reach the same threshold
- Effective in-time threshold corresponds to the minimum signal that fires the discriminator threshold in time with the trigger bunch crossing
- Smaller signal will be associated to the wrong bunch crossing

