

Urša Rojec

# Integration of MTCA.4 Components in Medical and Scientific Applications

System Design Best Practices

# Overview

- Motivation → Leveraging MTCA.4 properties to simplify system architecture



- **Example 1** - Dose Delivery System for MedAustron Proton Therapy Machine
  - Handling different hardware interfaces
  - Leveraging MTCA.4 for redundant and critical signals (interlocks)
  - Leveraging MTCA.4 diagnostics
- **Example 2** - Diagnostic Devices (BPM, BCM) and LLRF for ESS
  - Minimizing the code base
  - Building on common properties of such devices (high-speed DAQ)
  - Leveraging MTCA.4 RTM concept for hardware (and software) reuse

# Two Different Architectural Challenges

## Dose Delivery System

Systems that perform the same function but can have vendor-specific I/O interfaces

→ abstract away custom I/O



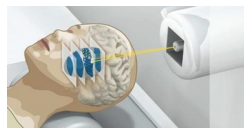
## Diagnostics (BPM, BCM) and LLRF

Systems that perform different functions but have a lot in common in terms of I/O - how they gather, process and output data

→ common base



# Ex1: Dose Delivery System

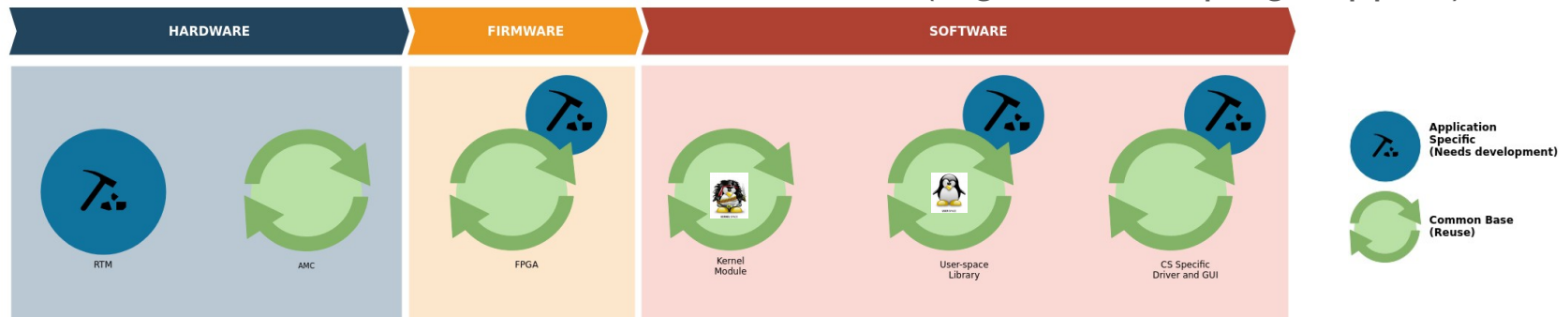


- Several components
  - **Unified interface** - Clear and fixed interface within DDS
  - Vendor specific I/O to the outside → **FMC modules**
- Modularity – handles different nozzle topologies
- Redundancy of safety critical functionality
- **MTCA.4 Properties used:**
  - Hotplug for replacing failed boards with system on-line
  - PTP links for interlocks
  - MCH diagnostics for monitoring card status and slot occupancy → safety
  - Backplane connections – more rugged compared to cables outside



# Ex2: Diagnostics (BPM, BCM) and LLRF

- Custom analog front-end on RTMs
- Reuse digitizer board
- Reuse software base, add only application specific functionality
- Software is not immune to entropy
  - Keep things in functionally complete and manageable chunks
- Add custom common features to the firmware (e.g. timestamping support)



# Generic DAQ Solution

## ToDo at the beginning ✓

- **Identify devices** with similar principle of operation (non-physics)
- **Select board** that matches requirements
- **Develop** the generic support



## ToNotDo ✗

- Unify just for the sake of unifying - devices need to have something in common → remember entropy!




Benefit in immediate **support when prototyping** (data display and export, GUIs, scripting and Matlab interface) and well tested core SW base



# Generic DAQ Solution

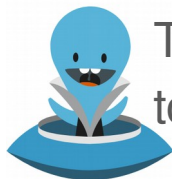
## ToDos ✓

- **Be strict about interface specification**
- Software and firmware collaboration on interface spec 



## ToNotDos

- Exceptions to the point that they become common-practice
- Sacrifice final simplicity to save development time on one device
- **Treat every system as special**



This pays off in maintenance, debugging, amount of different spares that need to be kept on stock, training of new employees and less headaches in general

# QUESTIONS?