



## VXD Alignment: Phase II

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# Outline

## VXD Alignment of Phase II

Alignment validation using collision and cosmic data

Planar deformation and their effects to alignment

Summary



## Status of VXD alignment

- The older alignment is published in GT "Calibration\_Offline\_Development".
- The newer alignment is stored locally only:

`/home/belle2/jkandra/basf2/beam/alignment/phase2/data/cosmicAndBeam/database.txt`

- We are calculate VXD alignment separately to check alignment parameters.
- The both alignments were discussed last week.
- We are focused to validation on collision and cosmic data.
- We will show validation results.
- We will show planar effects to VXD alignment.

## VXD Alignment of Phase II

### Alignment validation using collision and cosmic data

### Planar deformation and their effects to alignment

### Summary



# VXD Alignment validation procedure

## Collision data

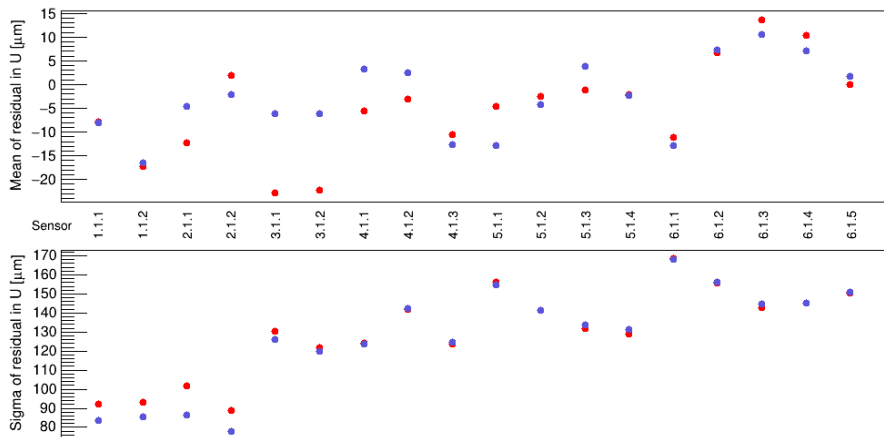
- (Experiment 3) Runs [488, 490], 577, 578, 579, 580, 674, 677, 686, [782, 783, 785, 786], 1905, 1928, 1935, 1937, 1938, 1990, 2009, 2022, 2050, 2165, 2180, 2180, 2181, 2184, 2186, 2189 are used for validation VXD alignment.
- PXD was not included in all runs. These runs are marked as [..].
- Tracking information looks very good.
- Applied PXD and SVD masking procedure during reconstruction.

## Cosmic rays data

- (Experiment 2 and 3) Runs 904, 905, 906, 919, 920, 938, 1107, 1110, [152, 153], 158, 173, 182, 185, 1512, 1514, 1516, 1516, 1517, [1520, 1525, 1527, 1528, 1529, 1614, 1615] are used for validation.
- Validation VXD alignment on cosmic are worse as on beam, because of extrapolation from CDC, ...
- Means are fine, but dispersion of residual histograms are high.



# VXD alignment validation using cosmic rays



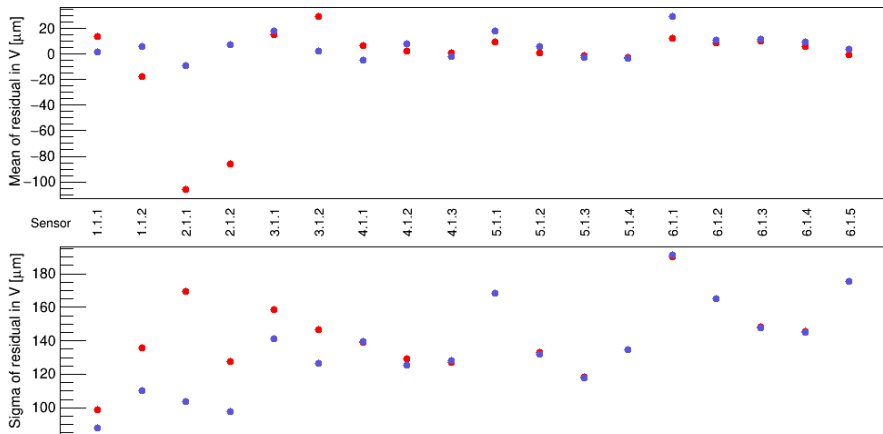
Unbiased residuals for all VXD sensors in phase 2 in U side.

Results calculated using **Global Tag** are marked as **red dots**.

Results calculated using **new alignment** are marked as **blue dots**.



# VXD alignment validation using cosmic rays



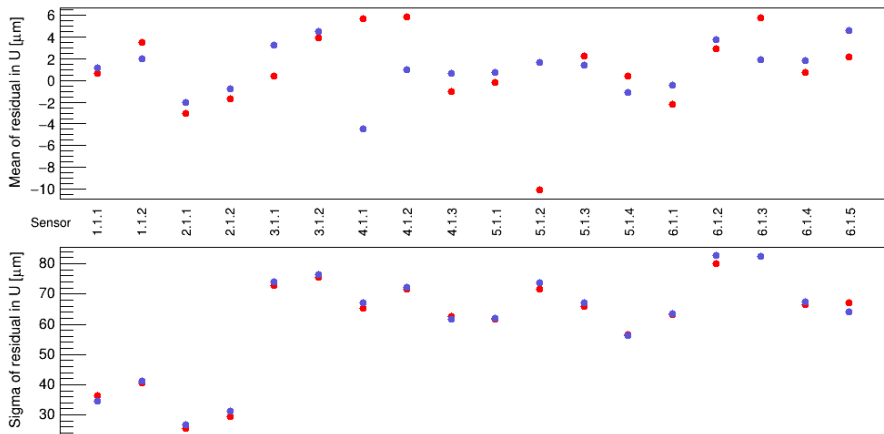
Unbiased residuals for all VXD sensors in phase 2 in V side.

Results calculated using **Global Tag** are marked as **red dots**.

Results calculated using **new alignment** are marked as **blue dots**.



# VXD alignment validation using collision data



Unbiased residuals for all VXD sensors in phase 2 in U side.

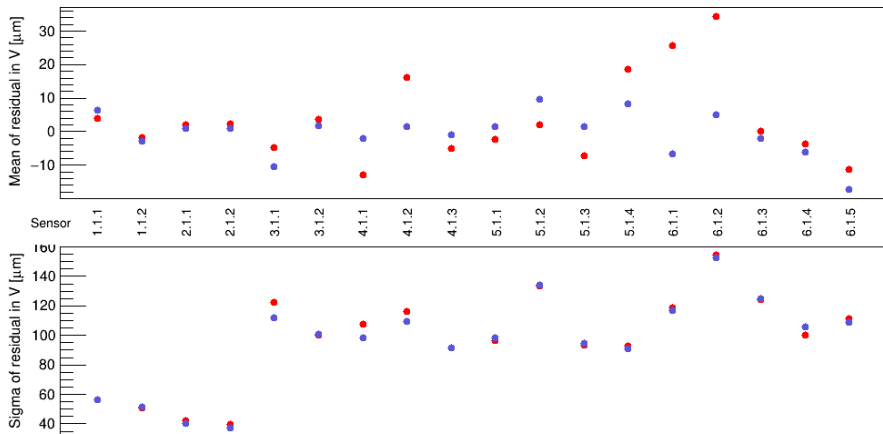
Results calculated using **GT** are marked as **red dots**.

Results calculated using **new alignment** are marked as **blue dots**.





# VXD alignment validation using collision data



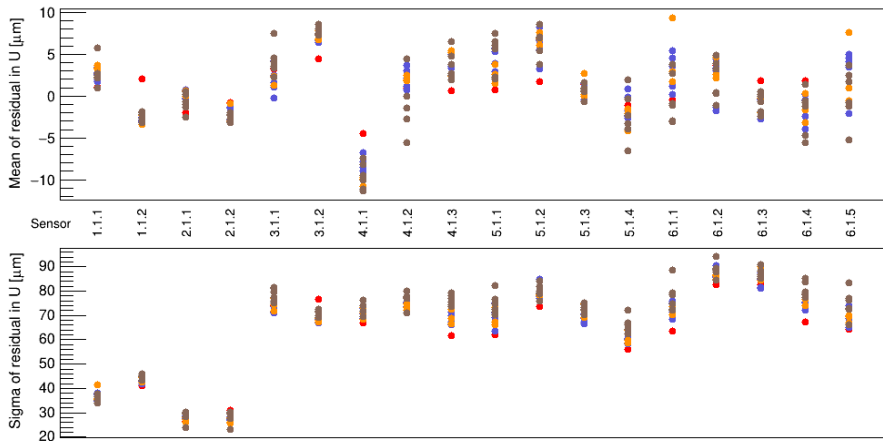
Unbiased residuals for all VXD sensors in phase 2 in V side.

Results calculated using **GT** are marked as **red dots**.

Results calculated using **new alignment** are marked as **blue dots**.



# VXD alignment validation using collision data

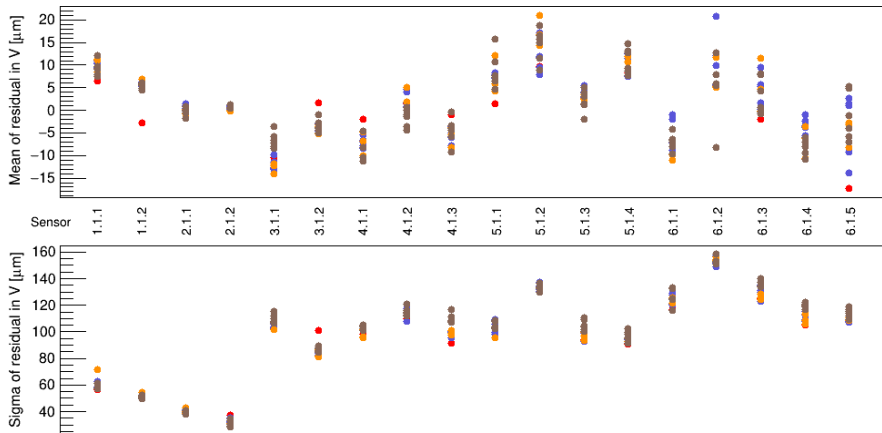


Unbiased residuals for all VXD sensors in phase 2 in U side.

Residuals for **Aligned runs (red)**, **runs from 1900 to 2000 (blue)**,  
**runs from 2000 to 2100 (orange)** and **runs from 2100 to 2200 (brown)**.



# VXD alignment validation using collision data



Unbiased residuals for all VXD sensors in phase 2 in V side.

Residuals for **Aligned runs (red)**, **runs from 1900 to 2000 (blue)**,  
**runs from 2000 to 2100 (orange)** and **runs from 2100 to 2200 (brown)**.

## VXD Alignment of Phase II

Alignment validation using collision and cosmic data

Planar deformation and their effects to alignment

Summary



# Planar deformation of sensors

- We are looking for dependence of residuals (in U or V direction) as function of U and V coordinate of hits.
- We are looking for extrapolation from residuals to W coordinate.
- We are using formula [Claus]:

$$du = \frac{\partial u}{\partial w} dw, dv = \frac{\partial v}{\partial w} dw$$

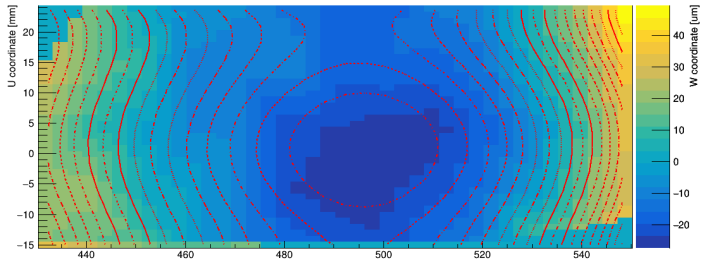
where  $\partial\{u, v\}/\partial w$  is slope (stored in basf2).

- We selected residuals smaller than 500  $\mu\text{m}$  and without  $\partial\{u, v\}/\partial w = 0$ .
- The plots are weighed using  $(\partial\{u, v\}/\partial w)^2$ .
- We produce plots for all sensors, but only some of them will be shown.
- All plots can be found in back-up

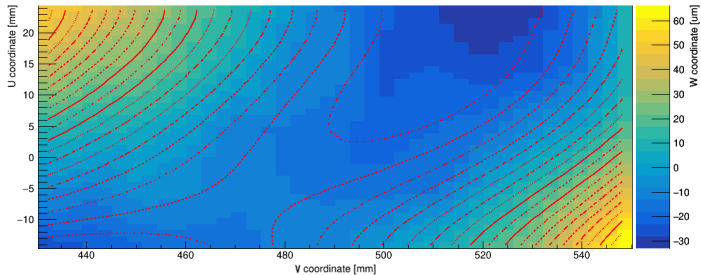


# Survey measurements (mounting phase 3)

Planarity of 3.7.1 sensor

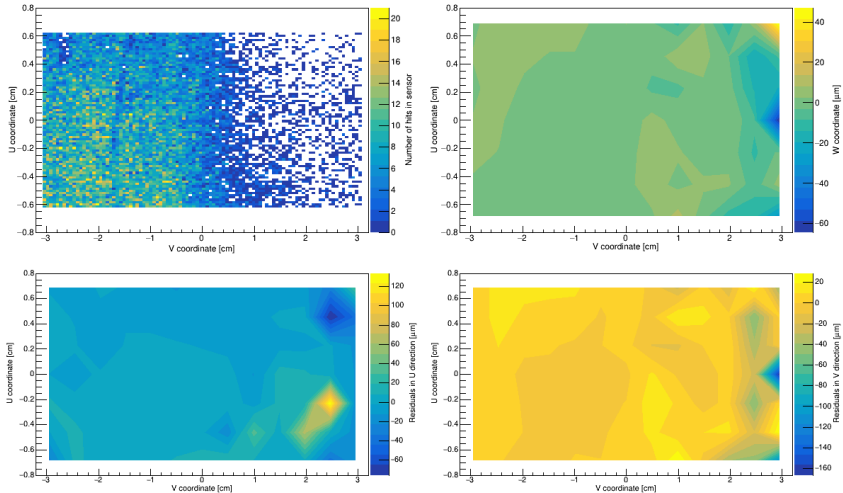


Planarity of 3.3.1 sensor





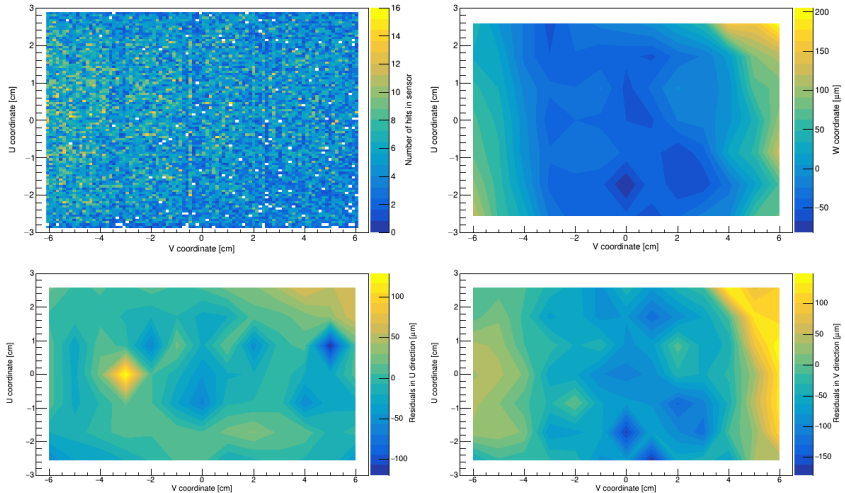
# Planar (non-)deformation of sensor 2.1.1



Some sensors are really smooth as software expects.  
The validation results are stable with minimal dispersion.



# Planar deformation of sensor 5.1.3

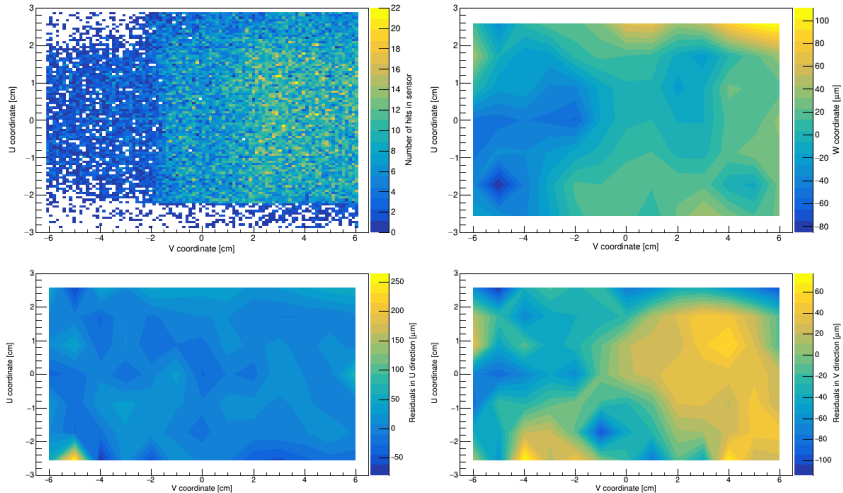


Huge deformation of sensor, calculated from observed residuals.  
Validation is affected by this planar deformation.





## Planar deformation of sensor 4.1.3



Huge deformation of sensor, calculated from observed residuals.  
Validation is affected by this planar deformation.



# Discussion of planar deformation

- We will fit measured deformation for comparison with survey measurements.
- For fitting we use Legendre polynomials from second to fourth order (12 parameters).
- The software framework should be extended for application planar deformation (creating JIRA ticket?).
- Then alignment procedure can be extended to calculate of planar deformation.
- Before extension it is impossible to get better alignment as shown.
- If validation shows worse results, we can re-aligned VXD sensors.



## Summary

- We were calculate two independent alignment for checking alignment procedure.
- One of them is published in GT "Calibration\_Offline\_Development" (back-up)
- Second is stored locally only

`/home/belle2/jkandra/basf2/beam/alignment/phase2/data/cosmicAndBeam/database.txt`

- Systematic and statistical errors are  $\approx 100 \mu\text{m}$  and  $1.0 \text{ mrad}$ .
- Alignment constants are validated using cosmic rays and collisions.
- Time dependent analysis of validation variables (residuals).
- Planar deformation studies shows limits of alignment procedure.
- For better alignment we need some software updates.

## Plans for next weeks

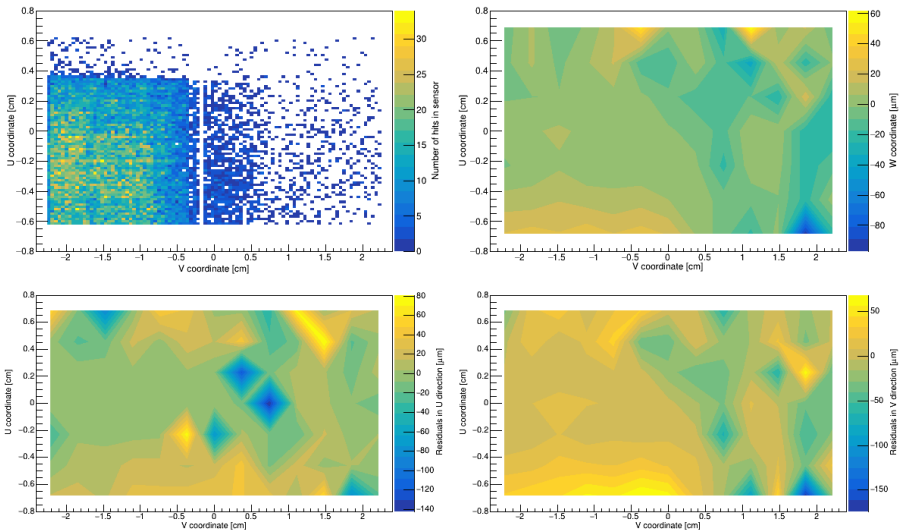
- We will validate VXD alignment with possibility re-aligned data.
- The second alignment parameters will be updated to GT soon.

# Backup



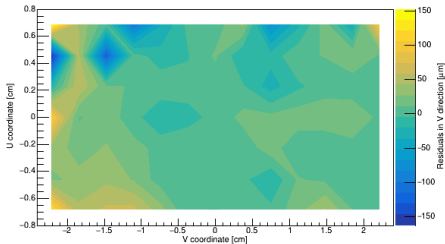
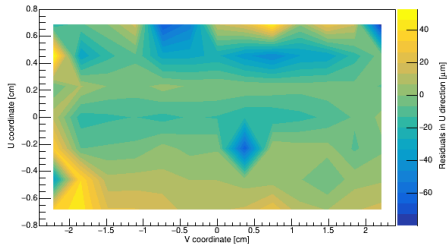
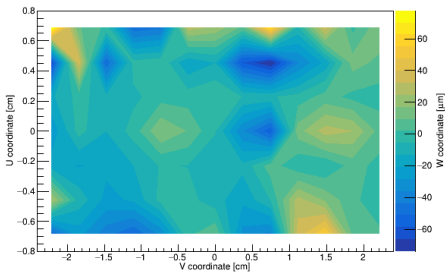
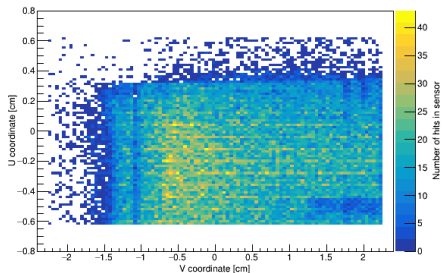
# Planar deformation in collision data

Sensor in layer 1 with sensor number 1 (ladder number 1)



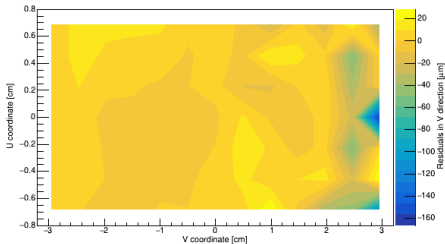
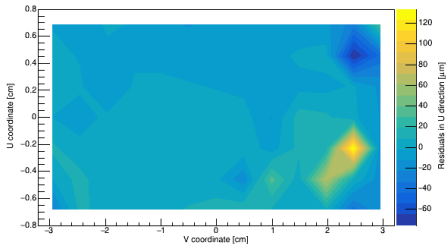
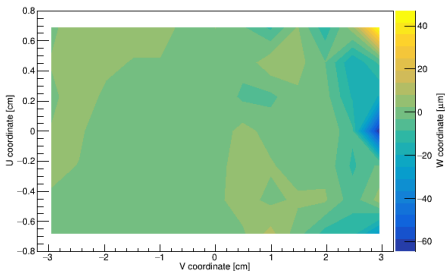
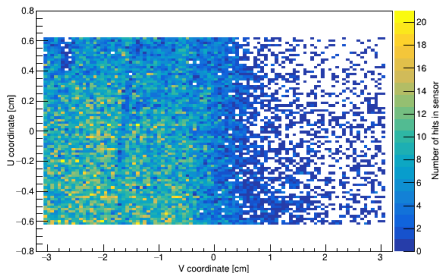
# Planar deformation in collision data

Sensor in layer 1 with sensor number 2 (ladder number 1)



# Planar deformation in collision data

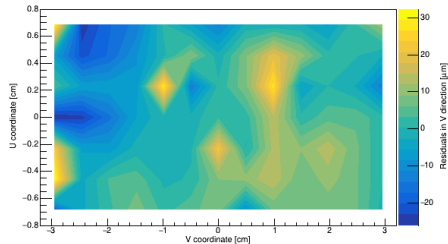
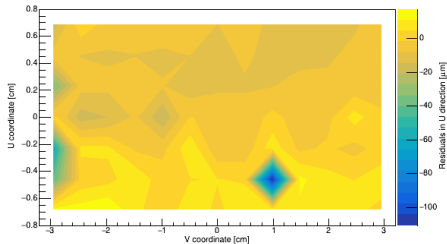
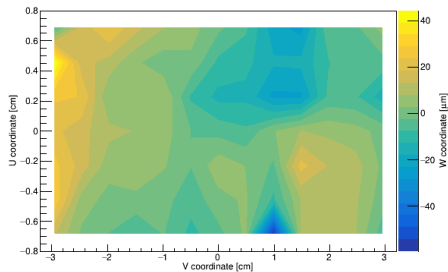
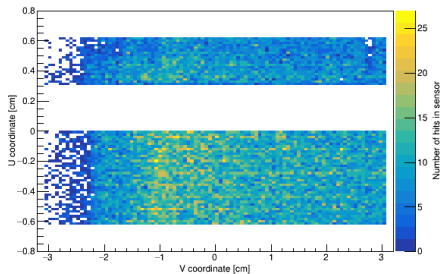
Sensor in layer 2 with sensor number 1 (ladder number 1)



# Planar deformation in collision data



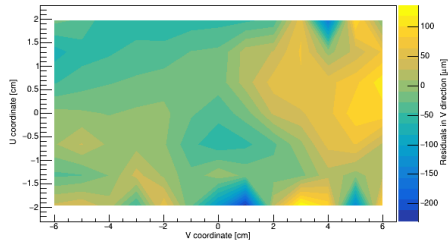
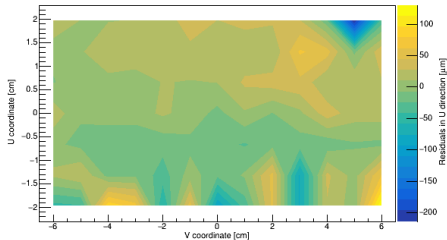
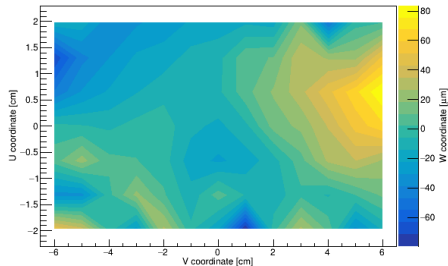
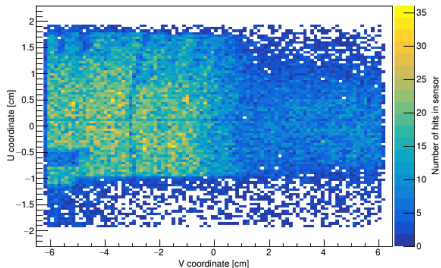
Sensor in layer 2 with sensor number 2 (ladder number 1)





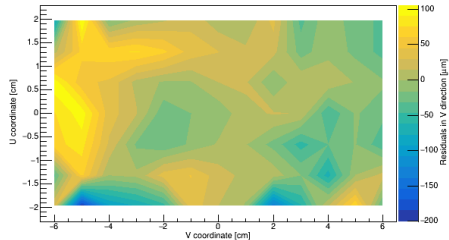
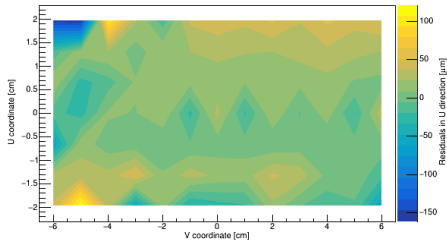
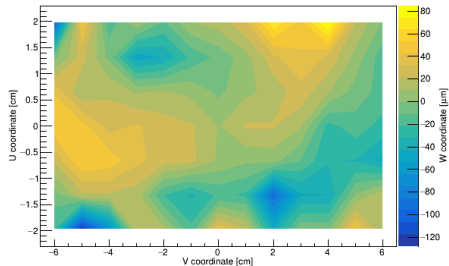
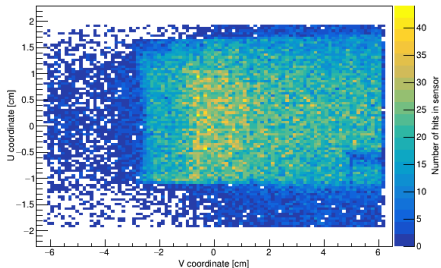
# Planar deformation in collision data

Sensor in layer 3 with sensor number 1 (ladder number 1)



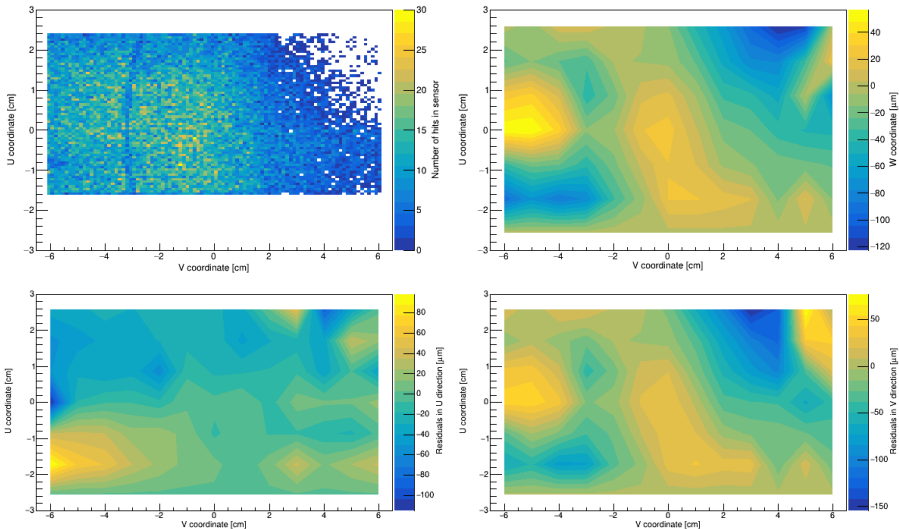
# Planar deformation in collision data

Sensor in layer 3 with sensor number 2 (ladder number 1)



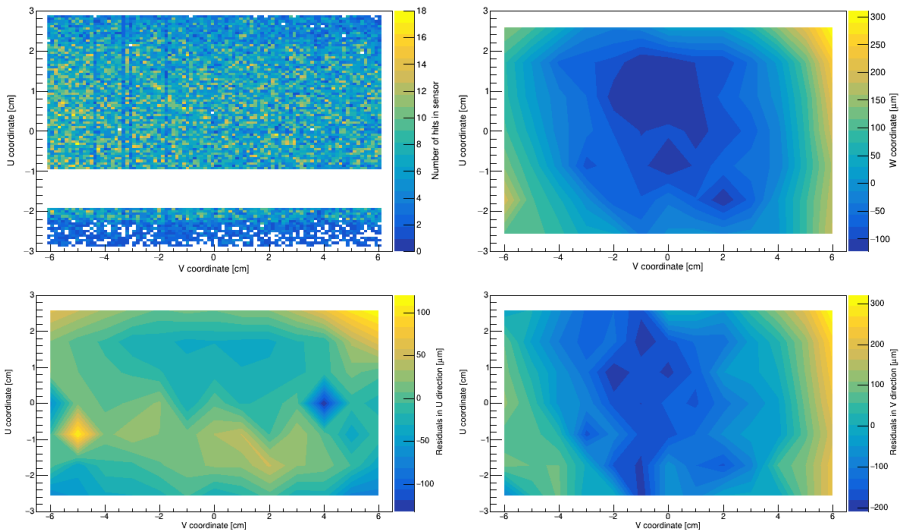
# Planar deformation in collision data

Sensor in layer 4 with sensor number 1 (ladder number 1)



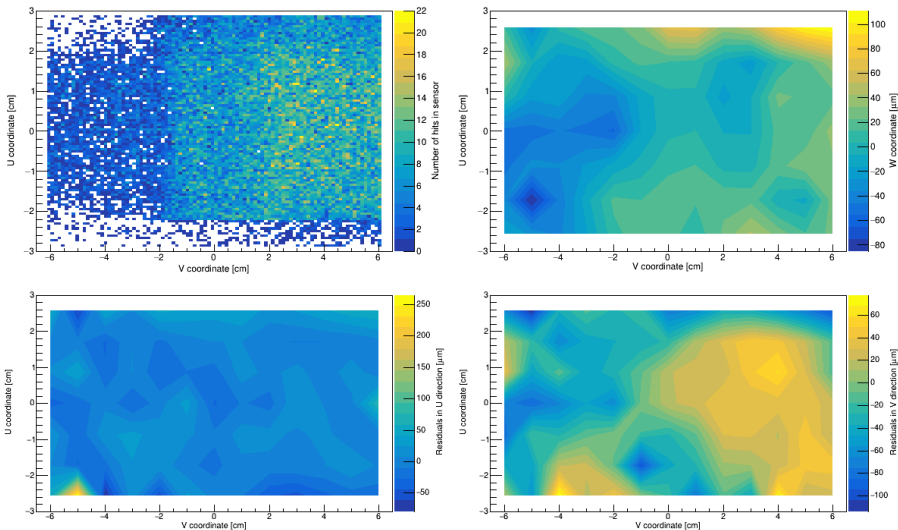
# Planar deformation in collision data

Sensor in layer 4 with sensor number 2 (ladder number 1)



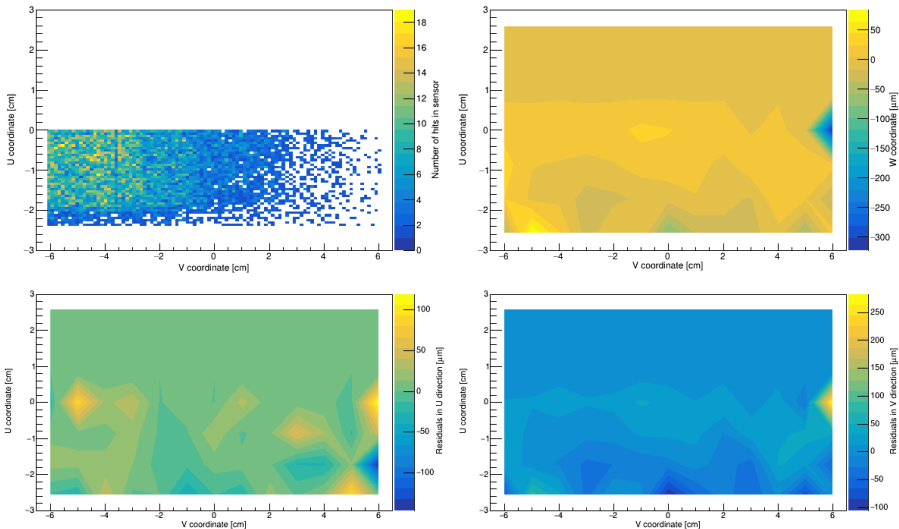
# Planar deformation in collision data

Sensor in layer 4 with sensor number 3 (ladder number 1)



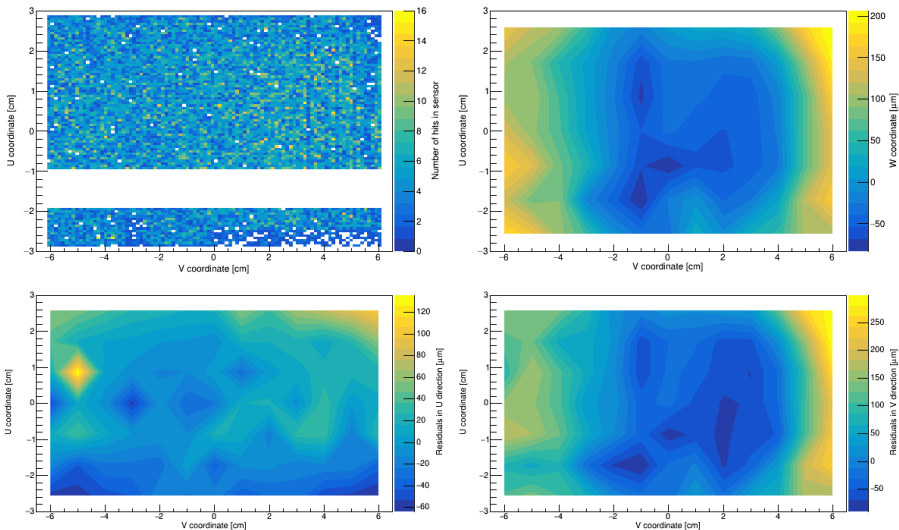
# Planar deformation in collision data

Sensor in layer 5 with sensor number 1 (ladder number 1)



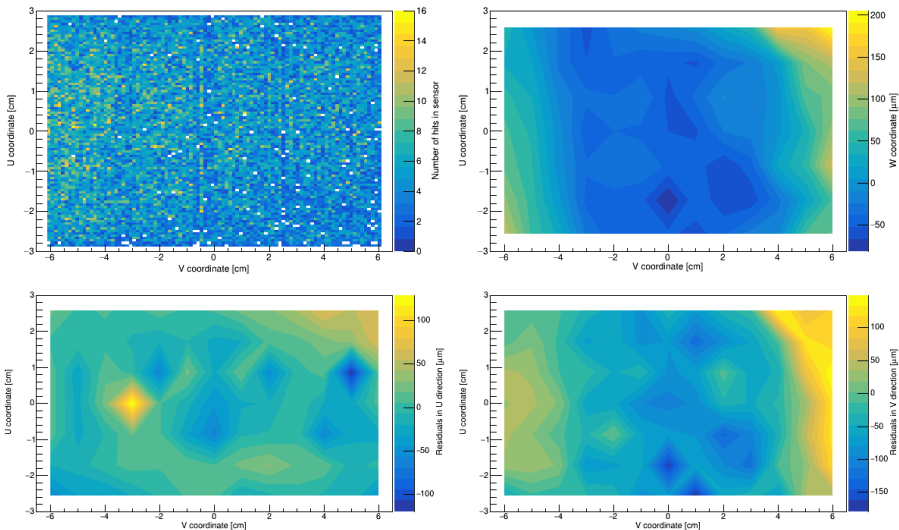
# Planar deformation in collision data

Sensor in layer 5 with sensor number 2 (ladder number 1)



# Planar deformation in collision data

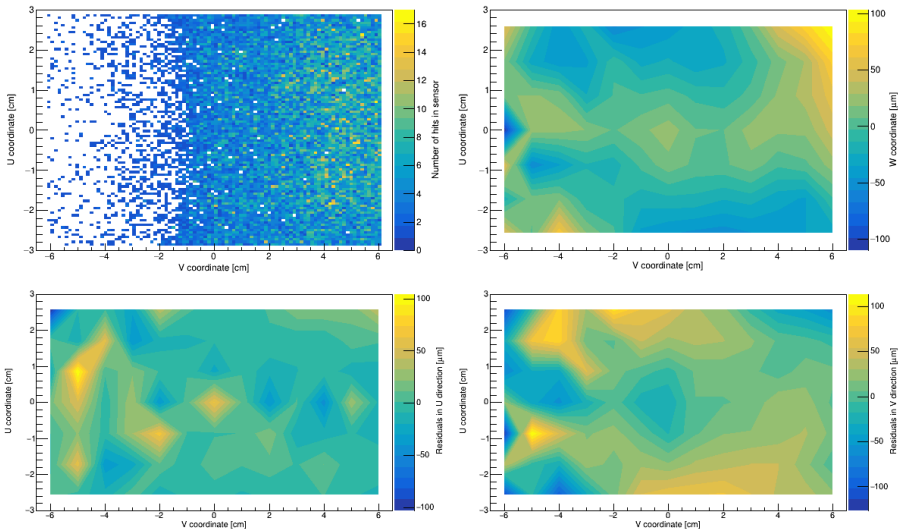
Sensor in layer 5 with sensor number 3 (ladder number 1)





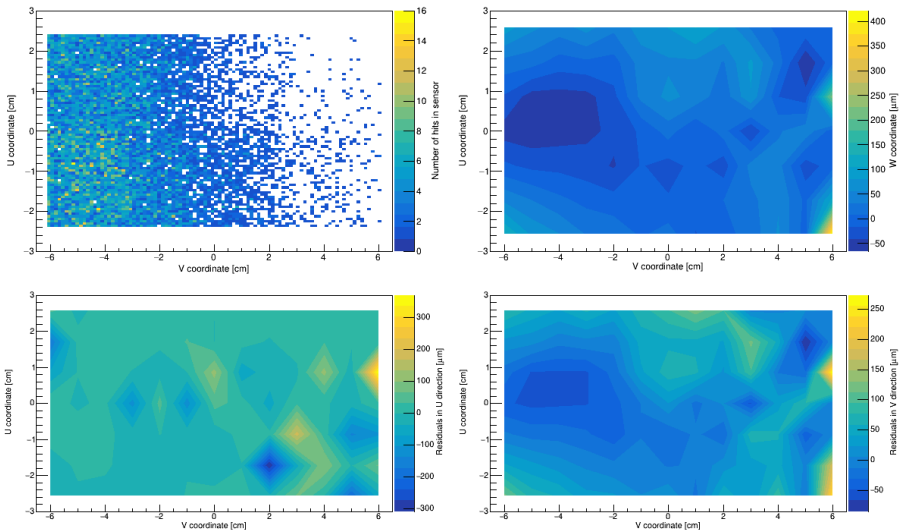
# Planar deformation in collision data

Sensor in layer 5 with sensor number 4 (ladder number 1)



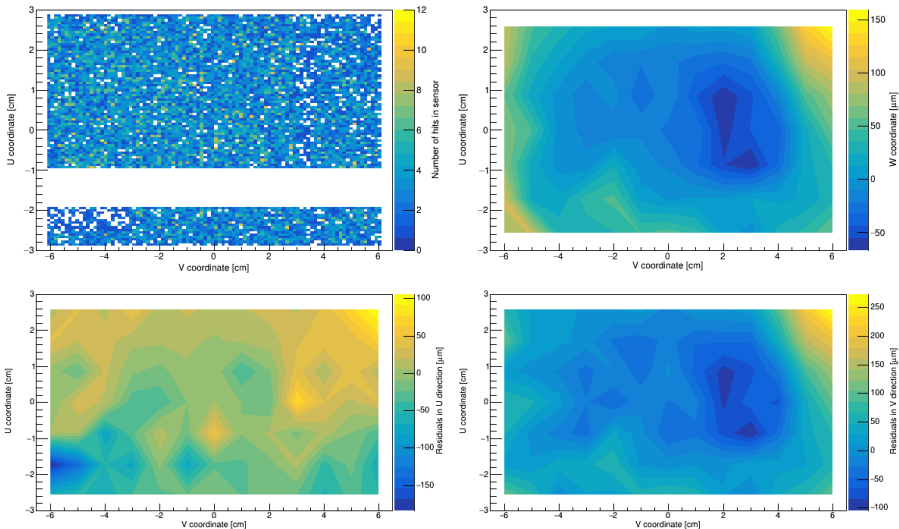
# Planar deformation in collision data

Sensor in layer 6 with sensor number 1 (ladder number 1)



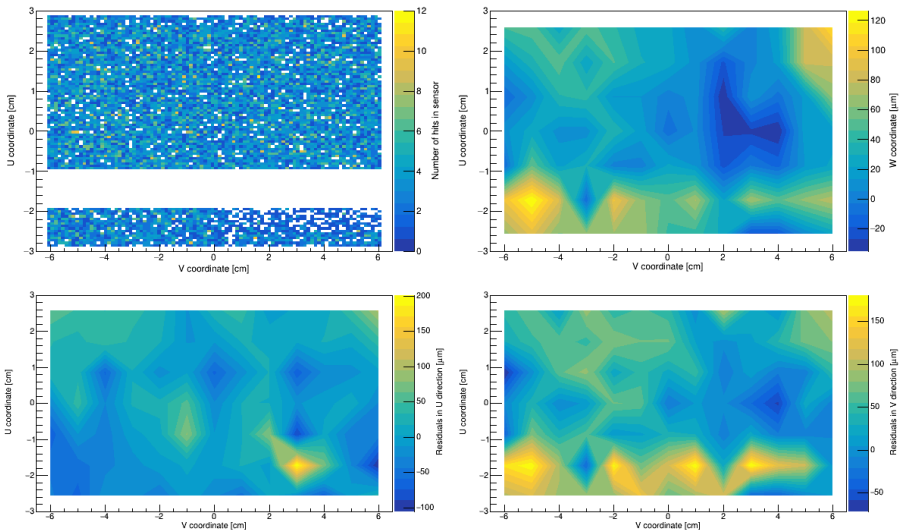
# Planar deformation in collision data

Sensor in layer 6 with sensor number 2 (ladder number 1)



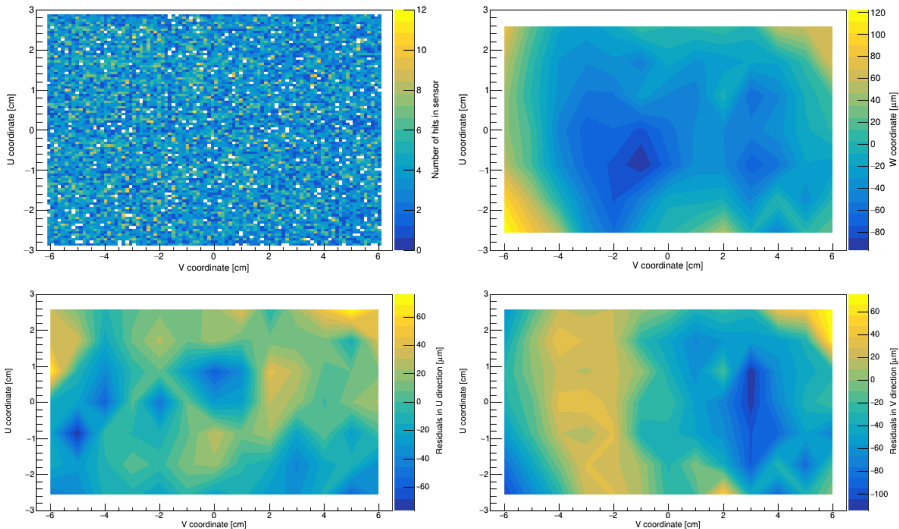
# Planar deformation in collision data

Sensor in layer 6 with sensor number 3 (ladder number 1)



# Planar deformation in collision data

Sensor in layer 6 with sensor number 4 (ladder number 1)



# Planar deformation in collision data

Sensor in layer 6 with sensor number 5 (ladder number 1)

