



“Deep Learning in KM₃NeT”

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*“Reconstruction and Machine Learning in Neutrino Experiments”
16-18 September, Hamburg*

KM3NeT Infrastructure

KM3NeT is a neutrino research infrastructure located in the Mediterranean sea.

Main features:

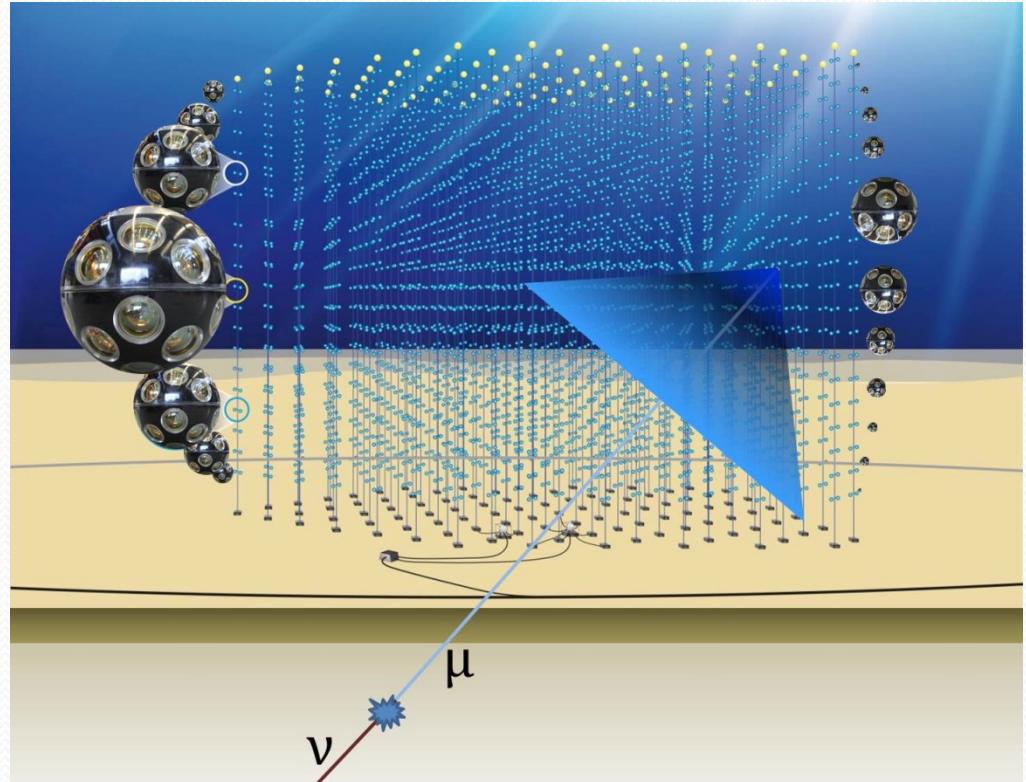
- Wide energy range: $3\text{GeV} \rightarrow 10\text{PeV}$
- Full sky coverage with the best sensitivity for galactic source
- All-flavor neutrino detection
- Good angular resolution ($<0.5^\circ$ for muons; $\sim 2^\circ$ for electrons at high energy)



KM3NeT Experiment

Main Goals:

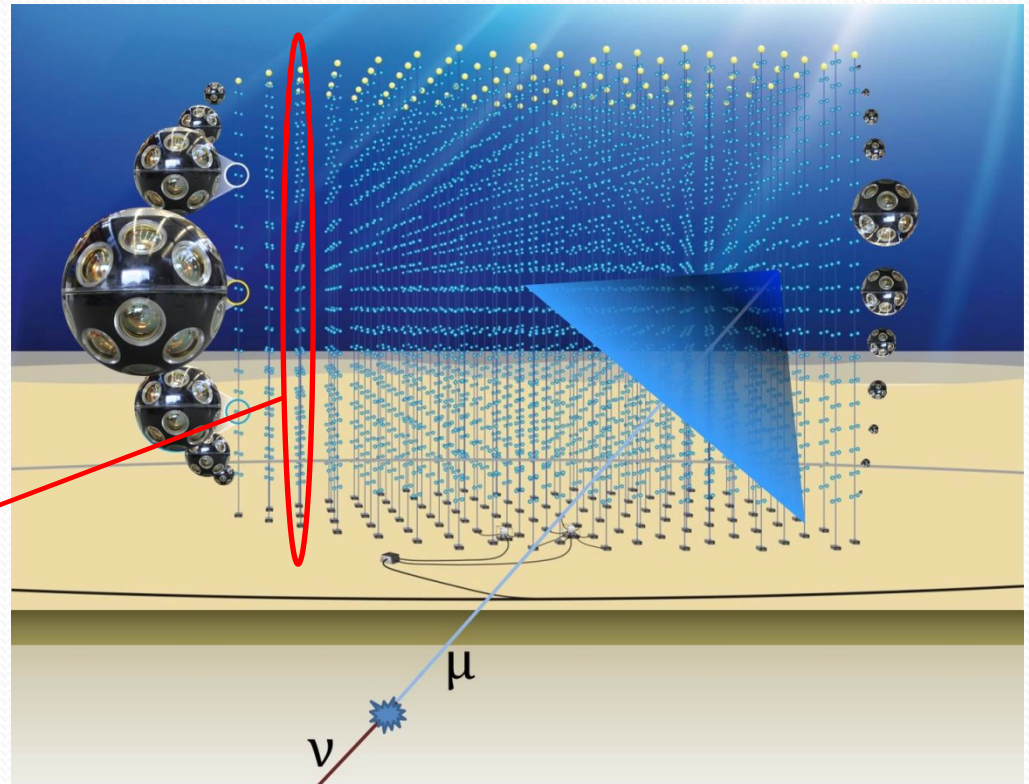
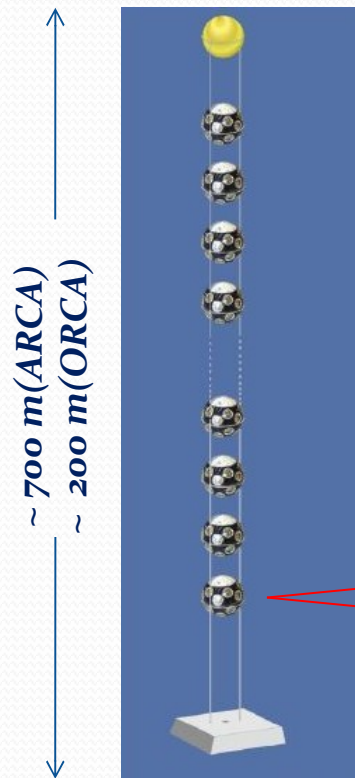
- identification of high energy astrophysical neutrino sources
- determination of neutrino mass hierarchy
- supernova core collapse
- Dark Matter



Detection principle: the neutrinos are detected by measuring the Cherenkov light emitted by secondary particle generated in neutrino interaction

KM3NeT Detector

Detection Unit: vertical string hosting 18 DOMs anchored at seabed and taut by buoys.



DOM: 17" glass sphere hosting 31 PMTs

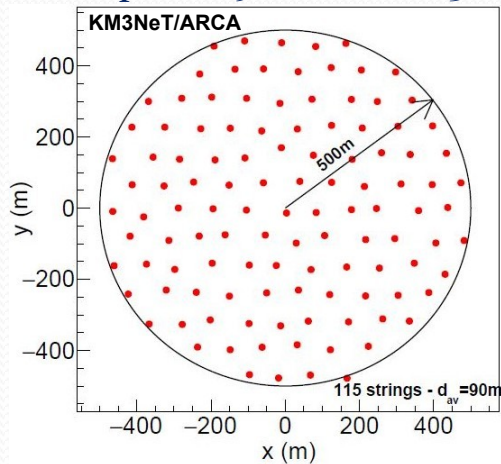
KM3NeT Site

KM₃NeT/ARCA

Astroparticle Research with Cosmic in the Abyss

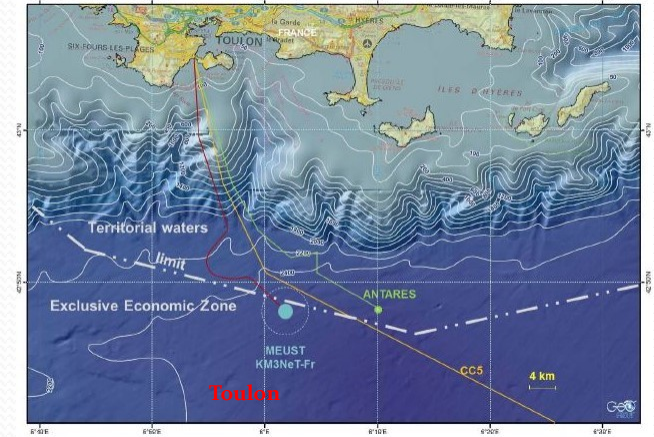


- 2 “building blocks” of 115 Detection Units each
- 700 m in height
- Depth 3500m
- DOMs spaced 90m in X-Y, 36 m in Z

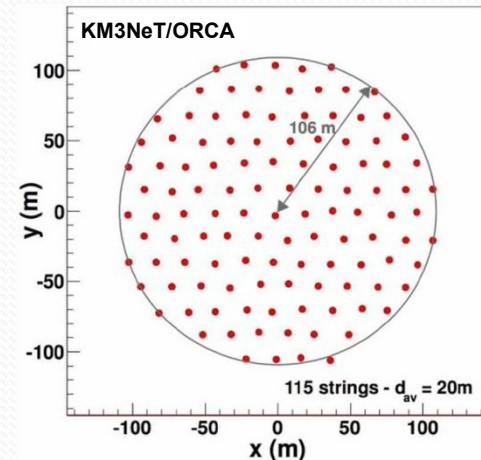


KM₃NeT/ORCA

Oscillation Research with Cosmic in the Abyss



- 1 “building blocks” of 115 Detection Units
- 200 m in height
- Depth 2500m
- DOMs spaced 20m in X-Y, 9 m in Z





Deep Learning applications in KM3NeT/ARCA

Deep Learning applications in KM3NeT/ARCA

Four Convolutional Neural Network (CNN) models designed for :

- *Classification*

- *up-going / down – going incident particle*
- *ν_μ CC / ν_e CC interaction*

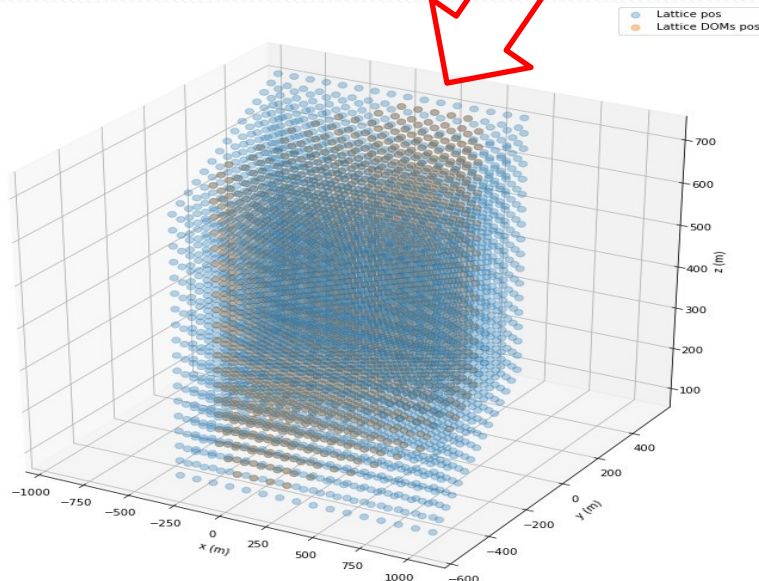
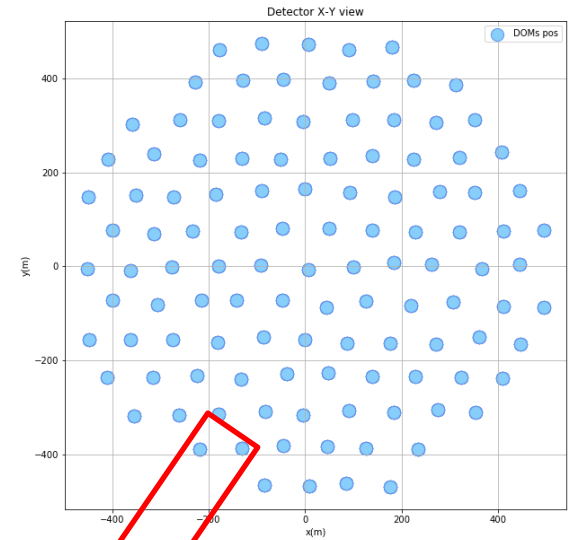
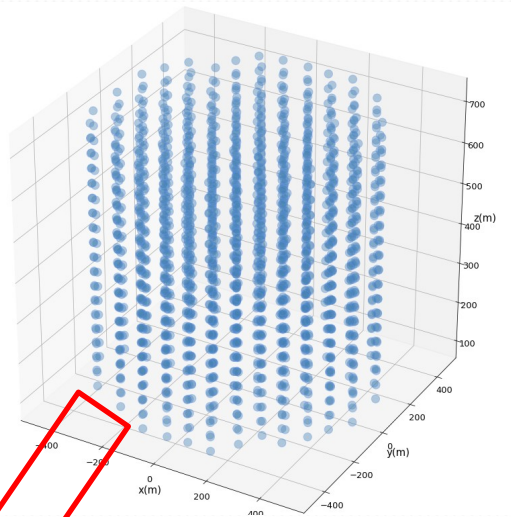
- *Regression*

- *particle energy estimation*
- *particle direction estimation*

Data Preparation

Regularised Detector Structure

- exactly 90m spaced in (X,Y)
- exactly 36m spaced in Z
- regularised detector mapped in lattice



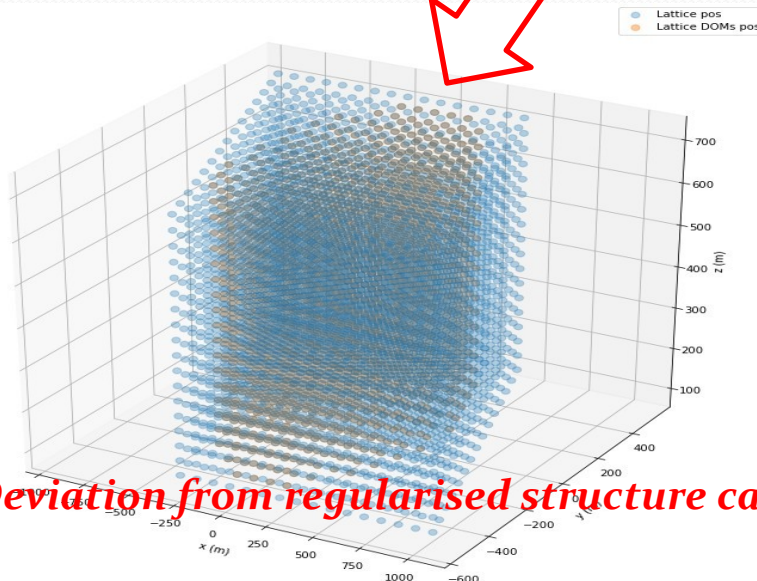
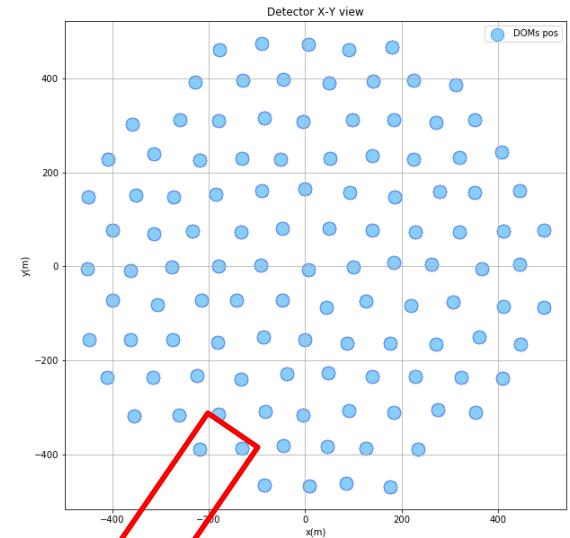
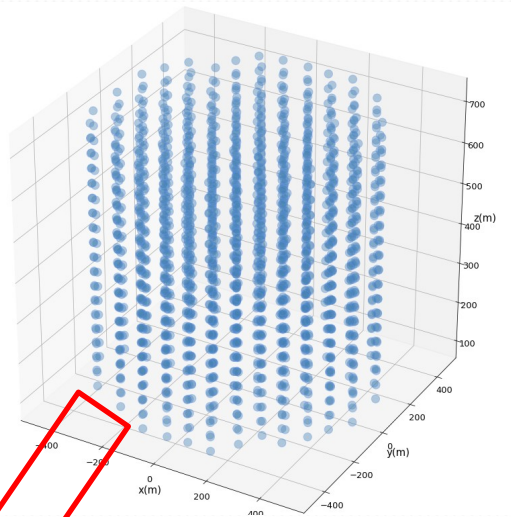
Regularized Detector XYZ-View

Regularized Detector XY-View

Data Preparation

Regularised Detector Structure

- exactly 90m spaced in (X,Y)
- exactly 36m spaced in Z
- regularised detector mapped in lattice



Deviation from regularised structure can be introduced later as a next-order correction

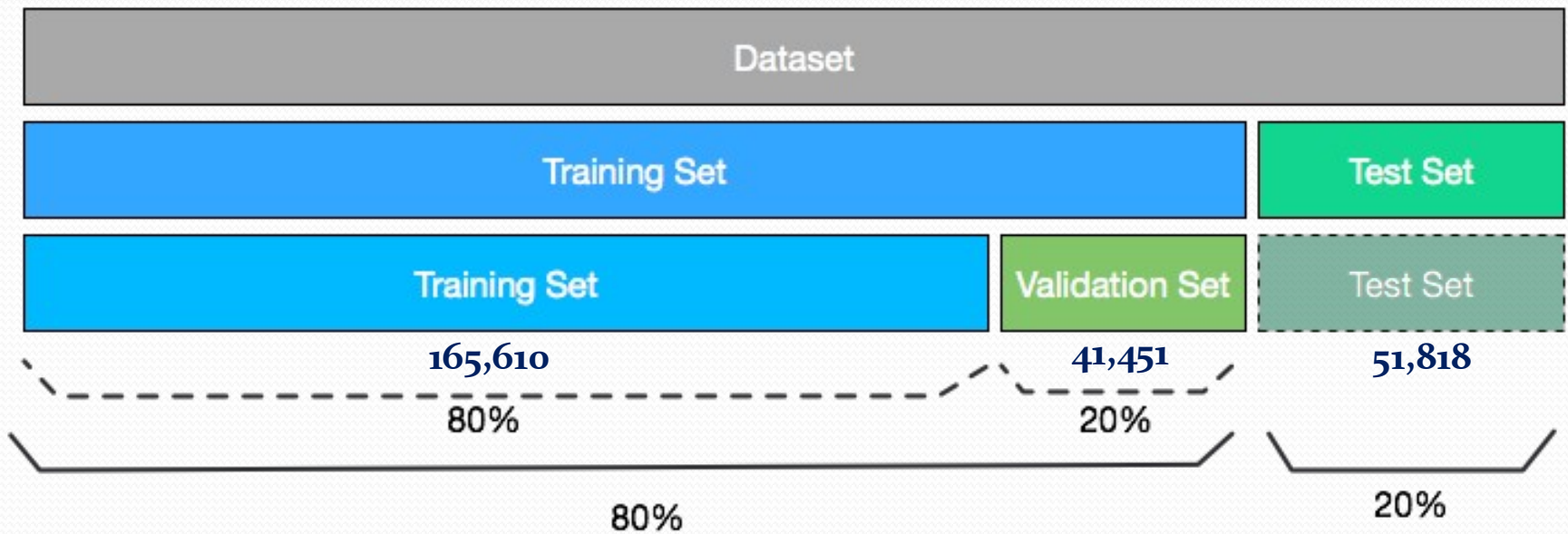
Regularized Detector XYZ-View



Regularized Detector XY-View

DATASET

258,879 total events



NVIDIA GEFORCE GTX-1080Ti GPU

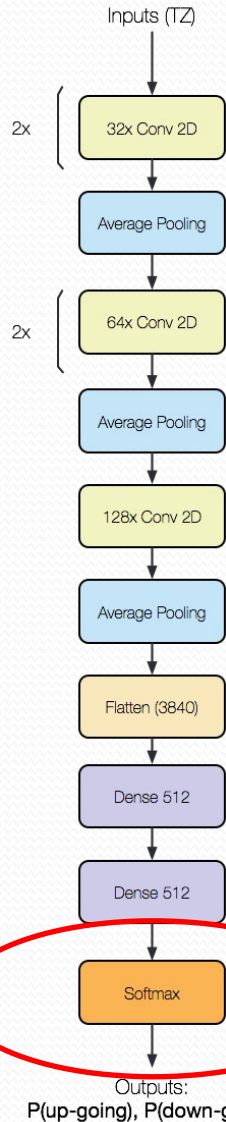
Up/Down – going Classification

Model Architecture:

➤ 3 x 2D Convolutional block

➤ 2 x 2D Conv layers+ Average Pooling layers

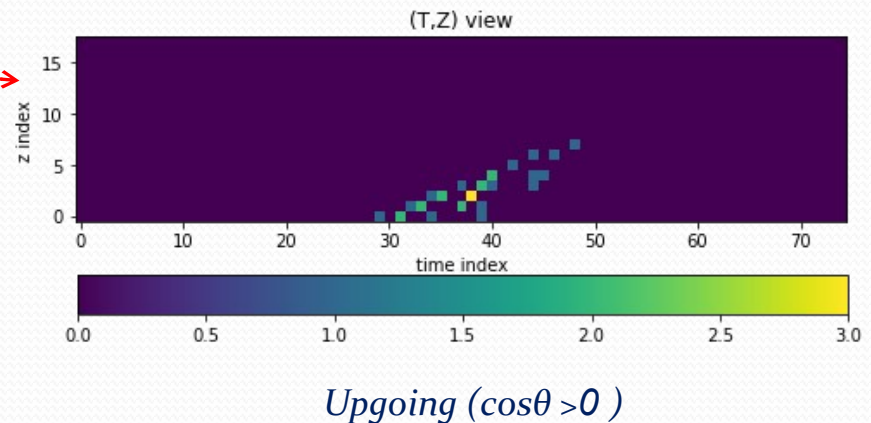
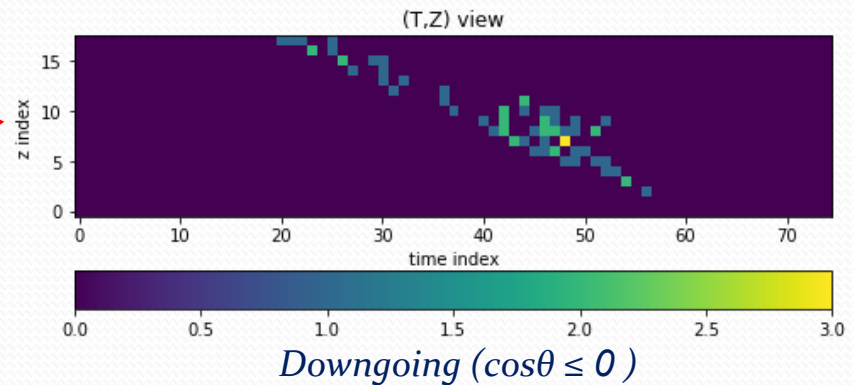
➤ 3 x Fully – Connected layers



Labels

$$y = \begin{cases} \cos\theta \leq 0 \\ \cos\theta > 0 \end{cases}$$

Classification

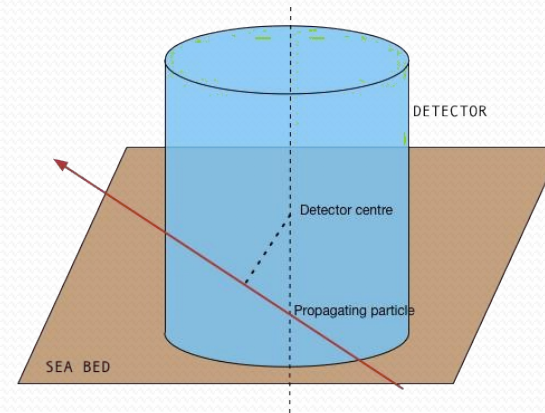


Up/Down – going Classification

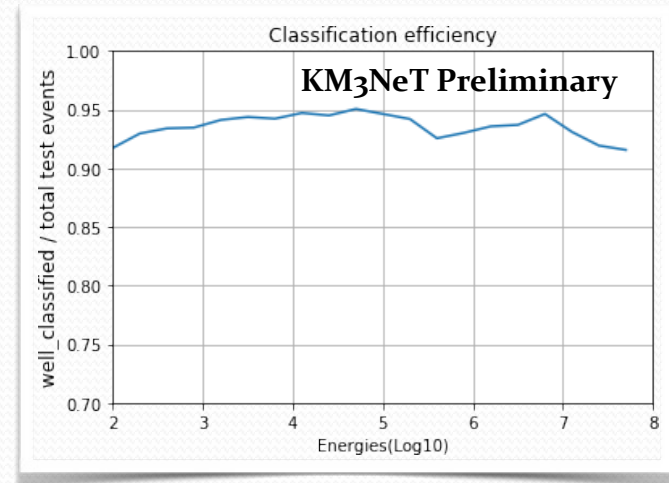
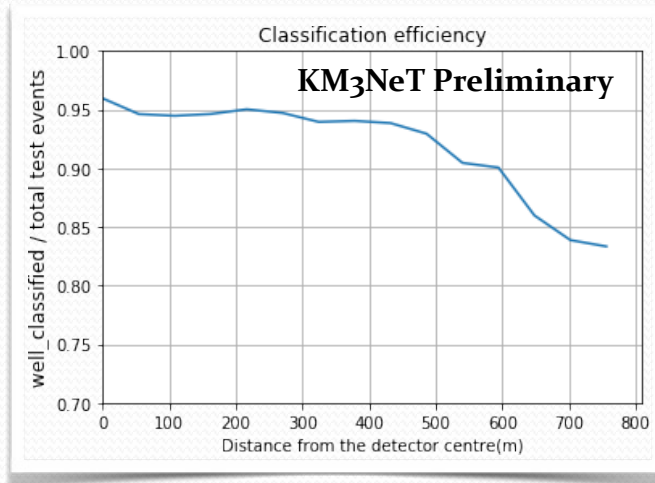
Performance depends on the track length in detector

Best performance :

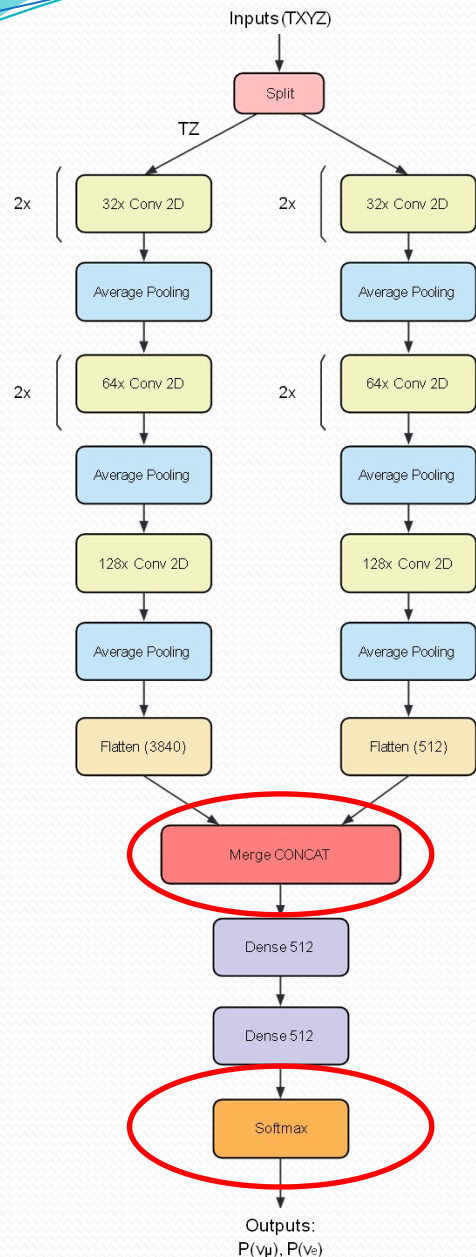
- *high energy events*
- *short distances from centre of detector*



Efficiency : numbers of well - classified events/total test events



Classification ν_μ CC - ν_e CC interactions

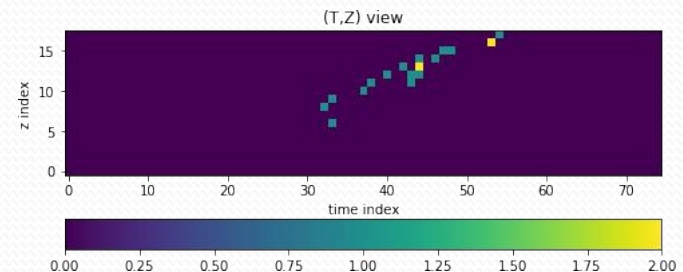
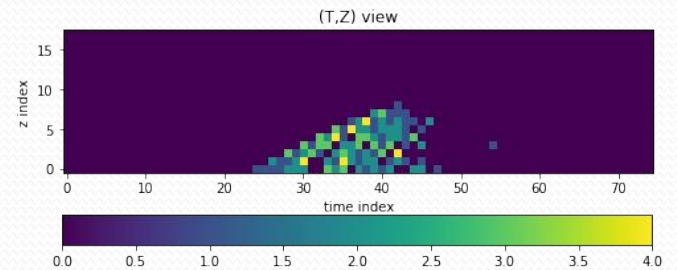


Model Architecture:

- two separated branches
 - (Z,t) evolution
 - (X,Y) evolution
- 3 x 2D Convolutional blocks
- merged to extract the common features

Labels

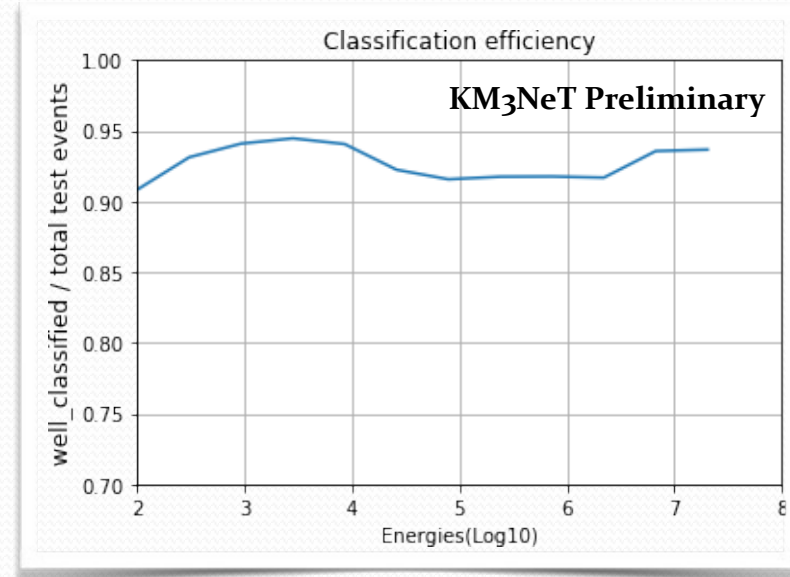
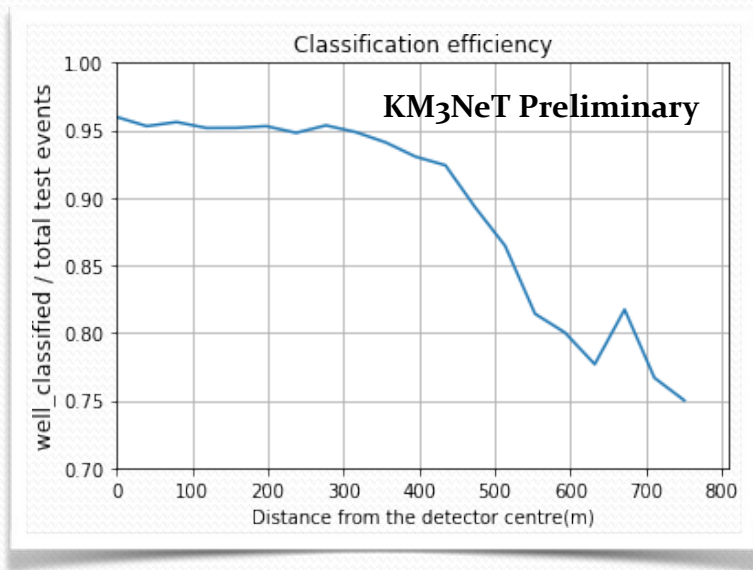
$$y = \begin{cases} 1 & \nu_e \text{ CC} \\ 0 & \nu_\mu \text{ CC} \end{cases}$$



Classification ν_μ CC - ν_e CC interactions

Best performance :

- high energy events
- short distances from centre of detector



Neutrino Energy Estimation

Model Architecture:

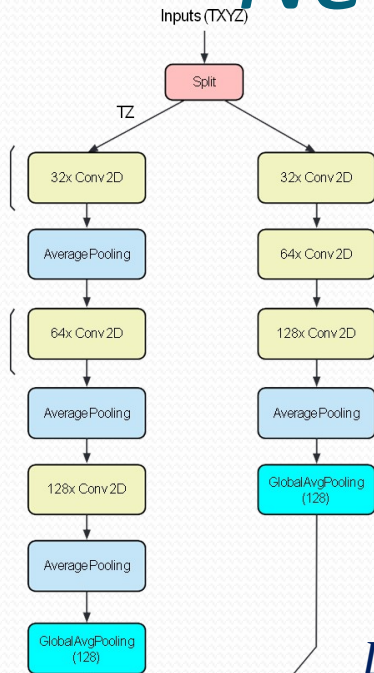
➤ two separate branches

➤ (Z,t) evolution

➤ (X,Y) evolution

➤ 2 x 2D Convolutional blocks concatenated

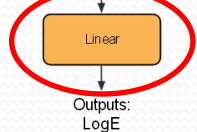
➤ 4 x fully - connected layers



Labels

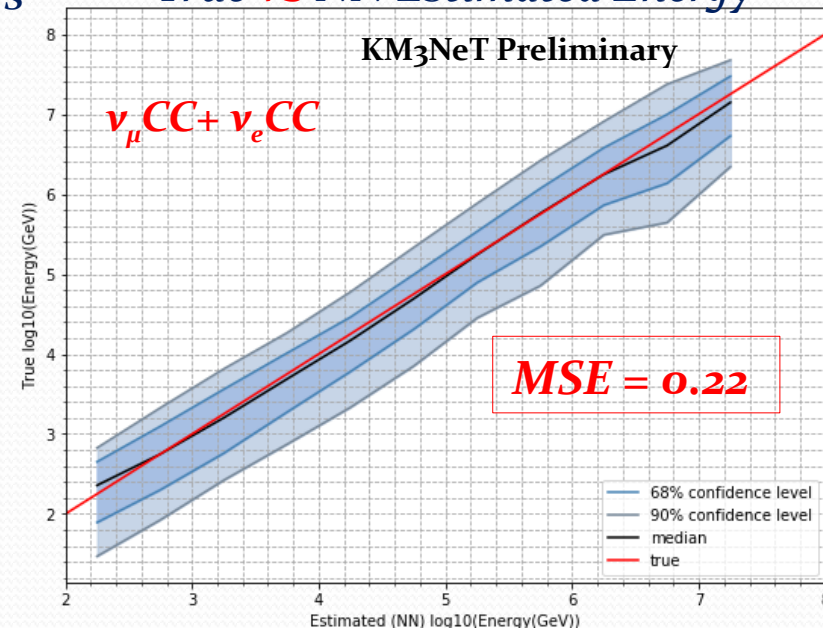
$\text{Log}_{10}(\text{Energy}) : \text{MCtruth}$

energy estimation



Outputs:
LogE

True **vs** NN Estimated Energy

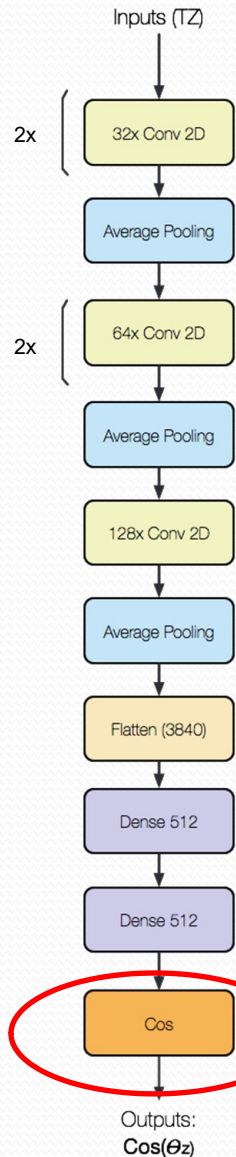


➤ Good linearity

➤ Could be improved with more statistics at high energy

Neutrino Direction Estimation

Model Architecture:



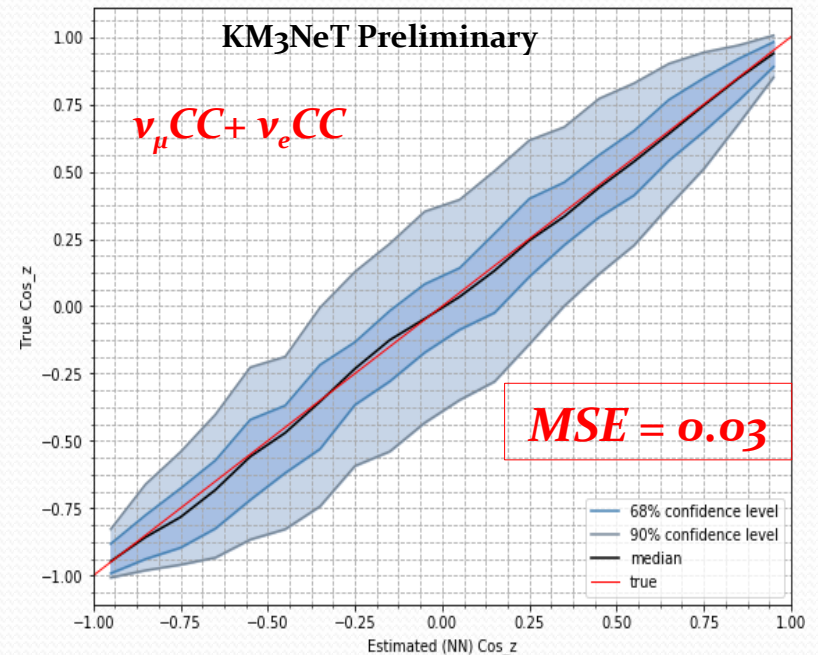
- 3 x 2D Convolutional block
- (Z,t) evolution
- 3 x Fully Connected layers

Labels

$\cos\theta_z: MCtruth$

Activation Function

True **vs** NN Estimated Direction(Z)

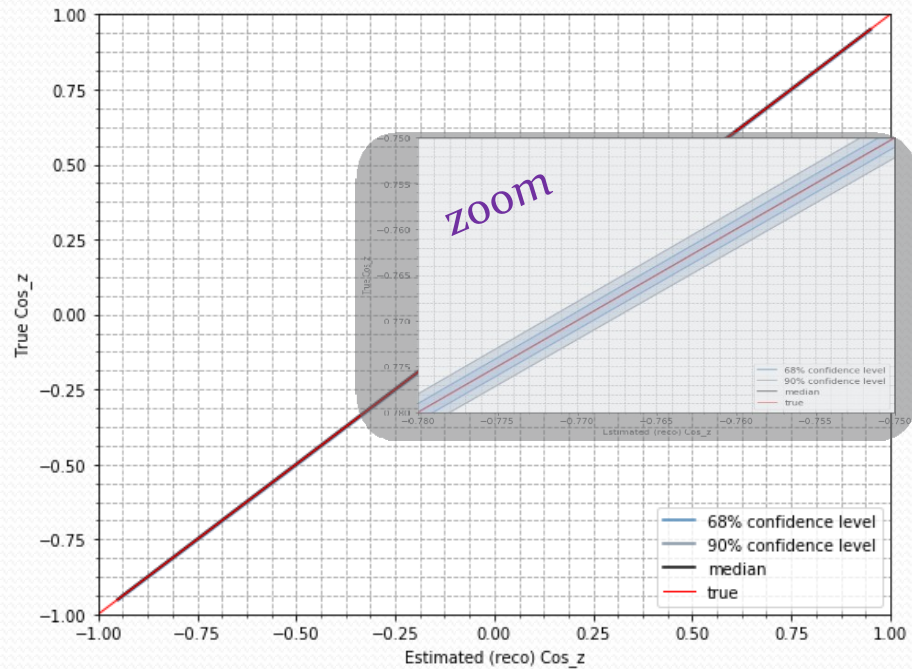




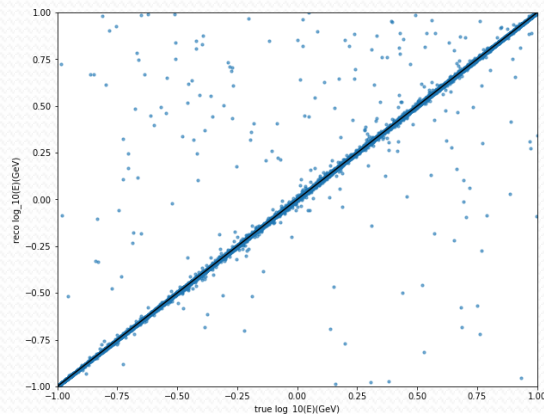
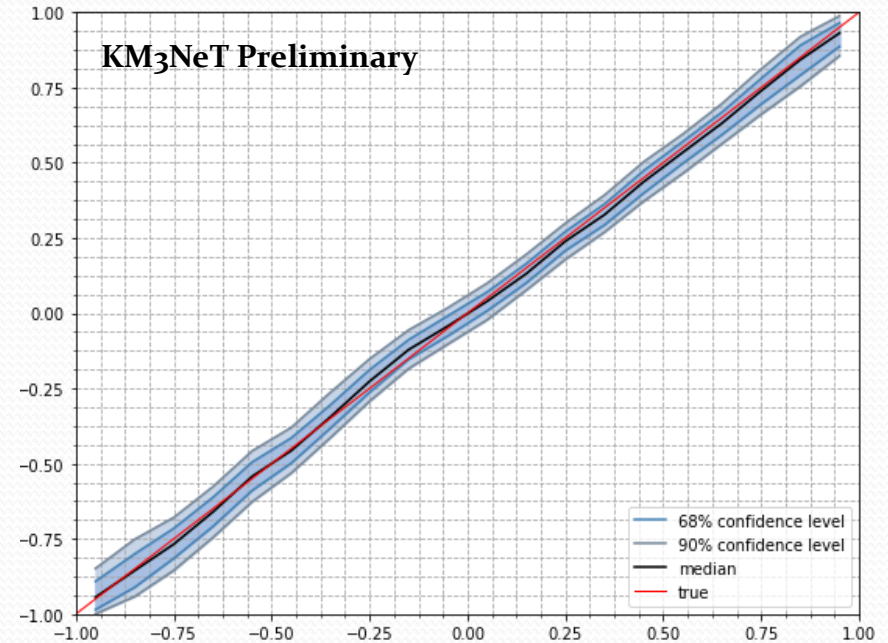
*Comparison with conventional algorithms
(KM3NeT/ARCA)*

Direction Estimation

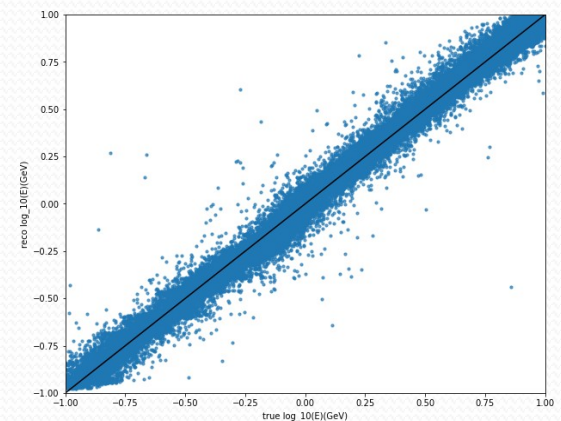
True **vs** Std. Reconstruction Direction(Z)



True **vs** CNN Reconstruction Direction(Z)



Estimated **vs** True
Neutrino direction



Comparison on Up/Down – Going Classification

➤ apply “labels” to reconstructed events

➤ $\cos(\theta_z) > 0$ “up-going”

➤ $\cos(\theta_z) \leq 0$ “down-going”

➤ compare predictions

Accuracy on Up/Down – Going Classification

KM₃NeT standard reconstruction
(-lik>60 and $\log(\beta_o)>-2.8$)

CNN classification running test on ν_μ CC
events

Classification Accuracy

Classification Accuracy

0.998

0.987

Only ν_μ CC reconstructed events with quality cuts

CNN always yields a direction, even when the conventional fit does not meet the quality requirements.



Deep Learning applications in KM3NeT/ORCA

Deep Learning applications in KM3NeT/ORCA

Convolutional Neural Network (CNN) models designed for :

➤ *Classification*

- *background suppression*
- *track/shower – like event topologies*

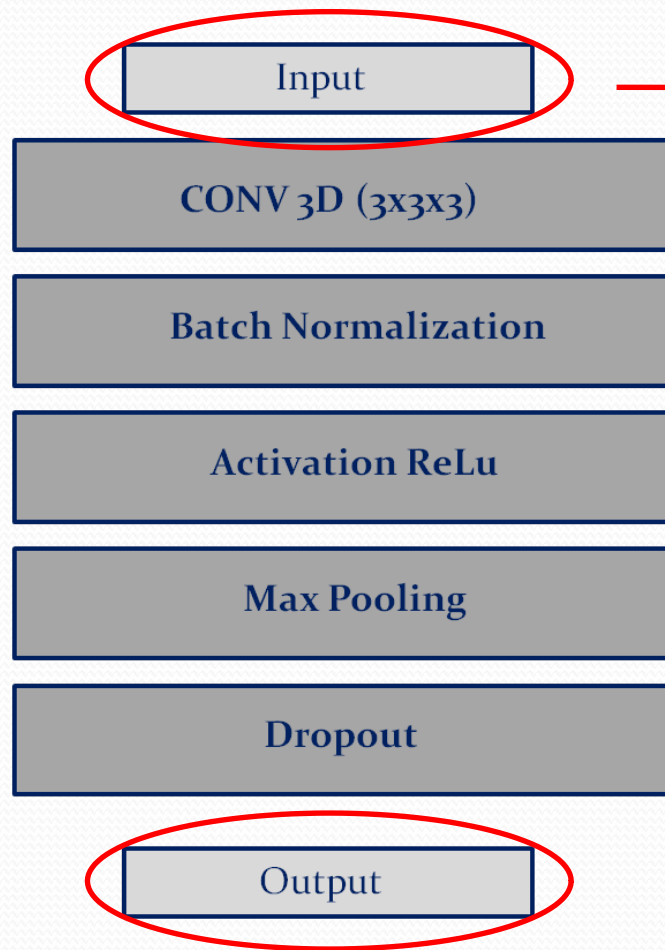
➤ *Regression*

- *particle energy estimation*
- *particle direction estimation*
- *vertex position*



Error Estimate on Regression results

Model Architectures



end of network differs depending of the tasks

$(X,Y,Z,P) \rightarrow (X,Y,Z) \text{ grid} + \text{PMT identifier}$
+
 $(X,Y,Z,T) \rightarrow (X,Y,Z) \text{ grid} + \text{time of hit recording}$



**NVIDIA TESLA
V100 GPU**

+  +  Keras

Classification: “softmax” classifier with 2 additional neurons to derivate classified output

Regression: 7 additional neurons with linear activation to regress continuous variables

Background/Signal Classification

MonteCarlo sample:

- *neutrinos*
- *atmospheric muons*
- *random noise*



Data Set :

- ❖ *Training Set (75%)*
- ❖ *Validation Set (2.5%)*
- ❖ *Test Set (22.5%)*

CNN model architecture:

3D Conv blocks + 2 fully connected layers



Output layer:

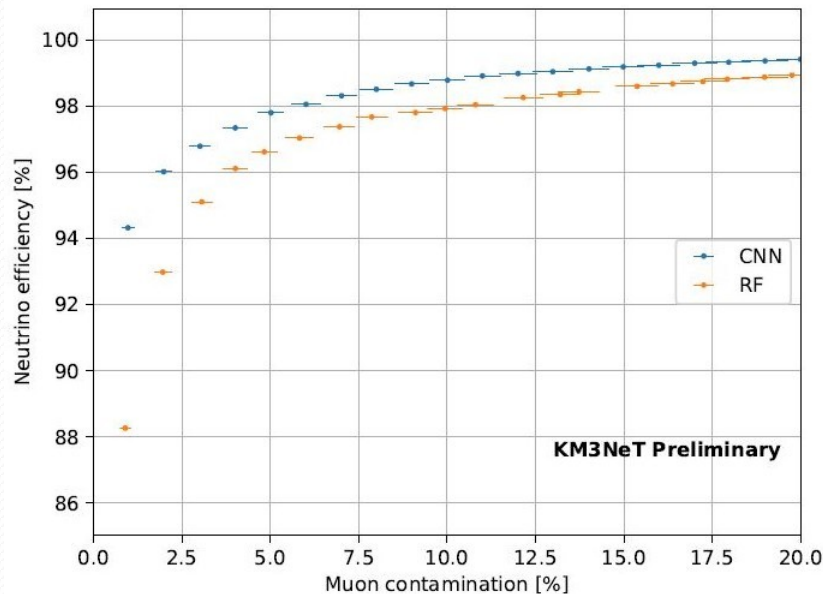
*distinction between neutrino and
no neutrino - events*

Background/Signal Classification

RESULTS

The comparison is made using *ONLY* the events from the **test set**

CNN background classifier **vs** RF classifier



discrimination threshold

$$C_{\mu}(p) = \frac{N_{\mu}(p)}{N_{tot}(p)}$$

atmospheric muon contamination

neutrino efficiency

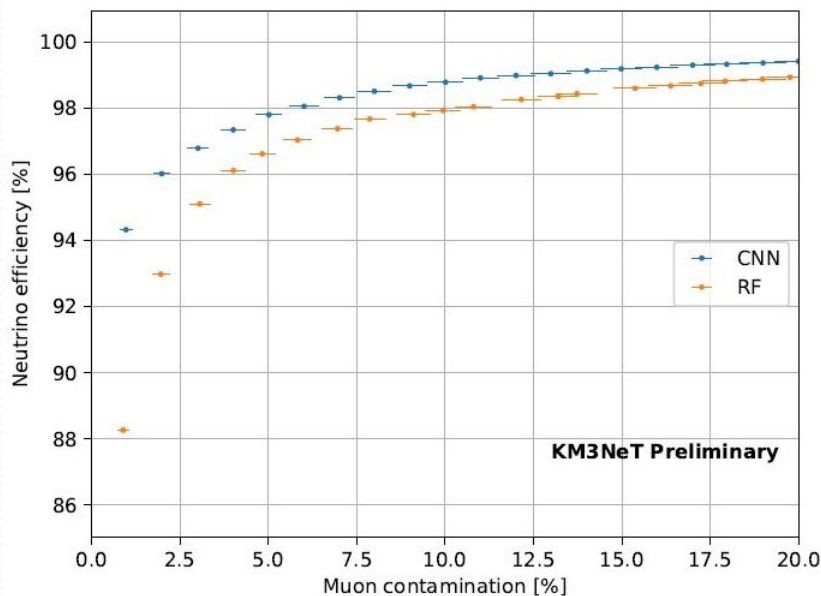
$$\nu_{eff}(p) = \frac{N_{\nu}(p)}{N_{\nu,tot}}$$

Background/Signal Classification

RESULTS

The comparison is made using *ONLY* the events from the **test set**

CNN background classifier **vs** RF classifier



discrimination threshold

$$C_{\mu}(p) = \frac{N_{\mu}(p)}{N_{tot}(p)}$$

atmospheric muon contamination

neutrino efficiency

$$\nu_{eff}(p) = \frac{N_{\nu}(p)}{N_{\nu,tot}}$$

Performance of CNN classifier are **better** than those of RF classifier .

Neutrino efficiency is significantly **higher** when atmospheric muons are suppressed

Track/Shower –like event Classification

*Events are mostly neutrino
events*

*Background events discarded
by the CNN classifier*

Track/Shower –like event Classification

Events are mostly neutrino events

Background events discarded by the CNN classifier

Sample:

- 50% track-like events (ν_μ CC)
- 50% shower-like events
 - 50% ν_e CC
 - 50% ν_e NC



The dataset is "reweighted" to make the track/shower ratio independent of neutrino energy

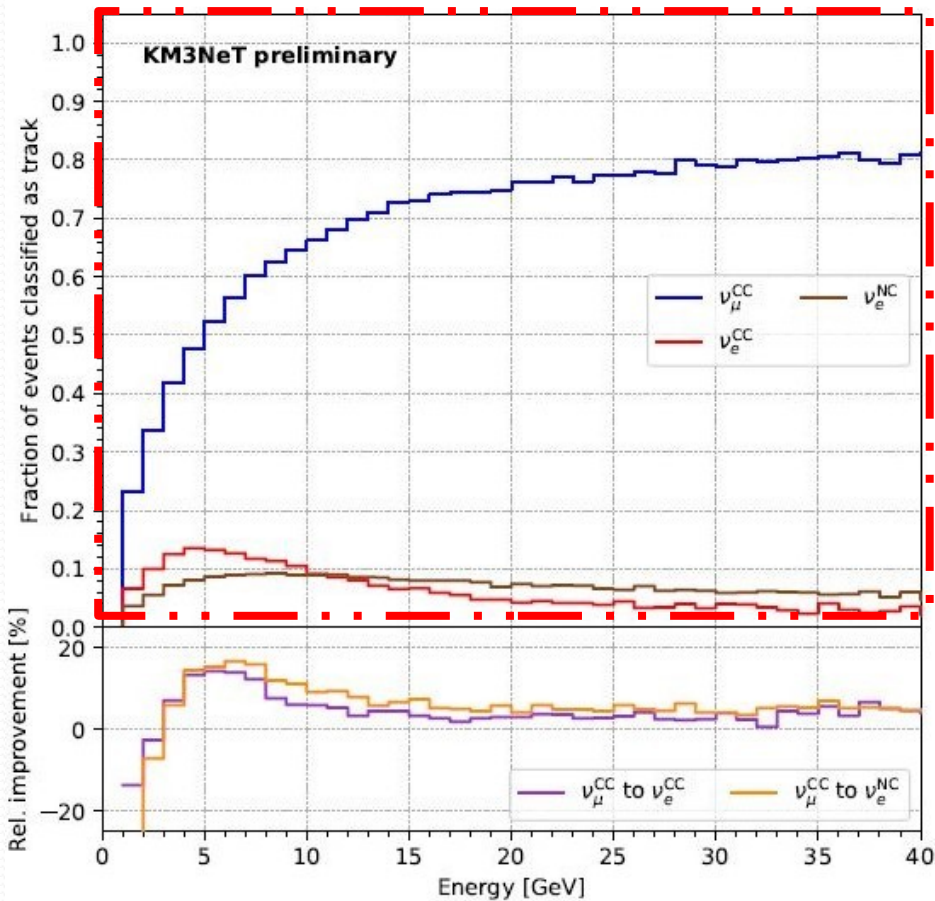


Rewighted data set :

- ❖ Training Set (70%)
- ❖ Validation Set (6%)
- ❖ Test Set (24%)

Track/Shower-like event Classification

RESULTS



Event is classified as “track-like” events only if probability is ≥ 0.5

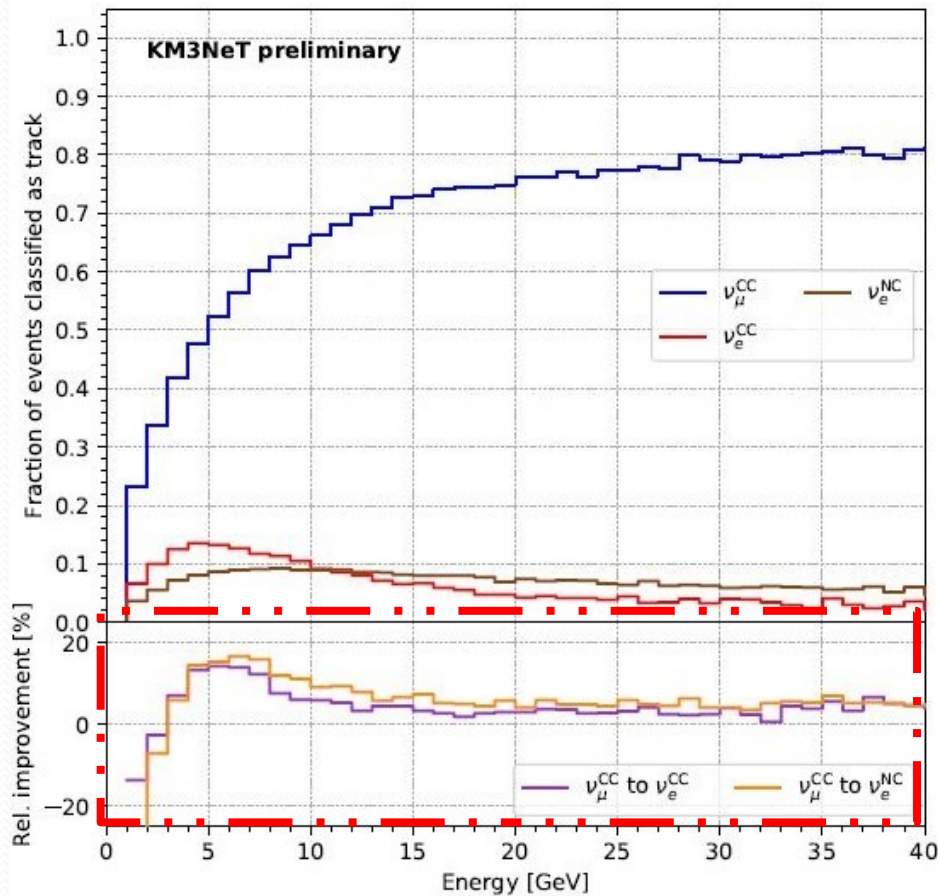
➤ Fraction of the events classified as “track-like” events

➤ $1 \text{ GeV} < E_{\nu} < 40 \text{ GeV}$

➤ Different interaction channels (ν_{μ}^{CC} , ν_e^{CC} , ν_e^{NC})

Track/Shower-like event Classification

RESULTS



➤ The performance of the CNN classifier are better than the RF classifier.

➤ The performance gain is more significant for $E_{\nu} < 15 \text{ GeV}$

Event Parameter Regression

CNN network architecture:

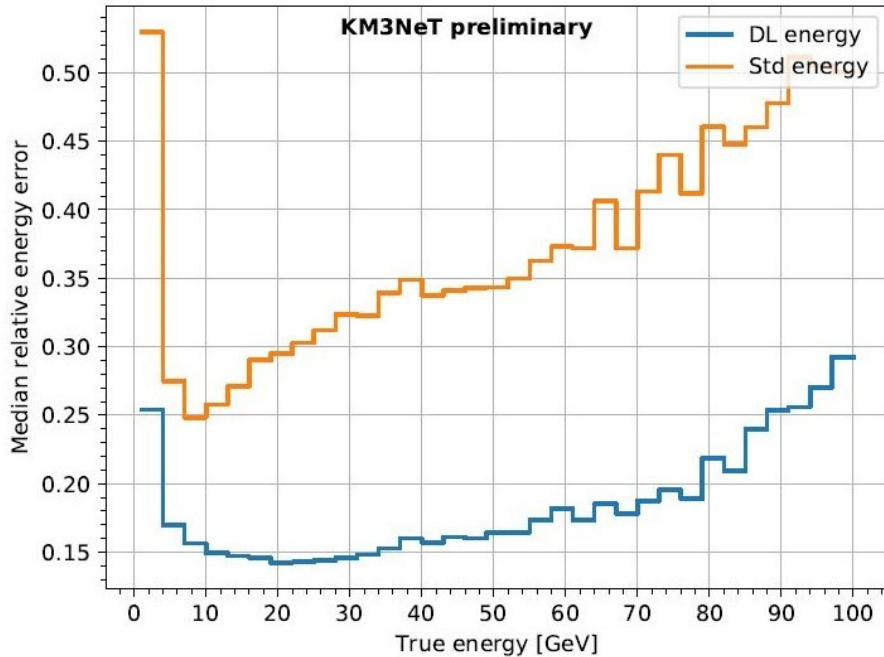
3D Conv blocks + 1 fully connected layer

Properties Estimated :

- *neutrino energy*
- *direction*
- *vertex position*

Energy Fit

CNN: Track like ($\nu_\mu - CC$)

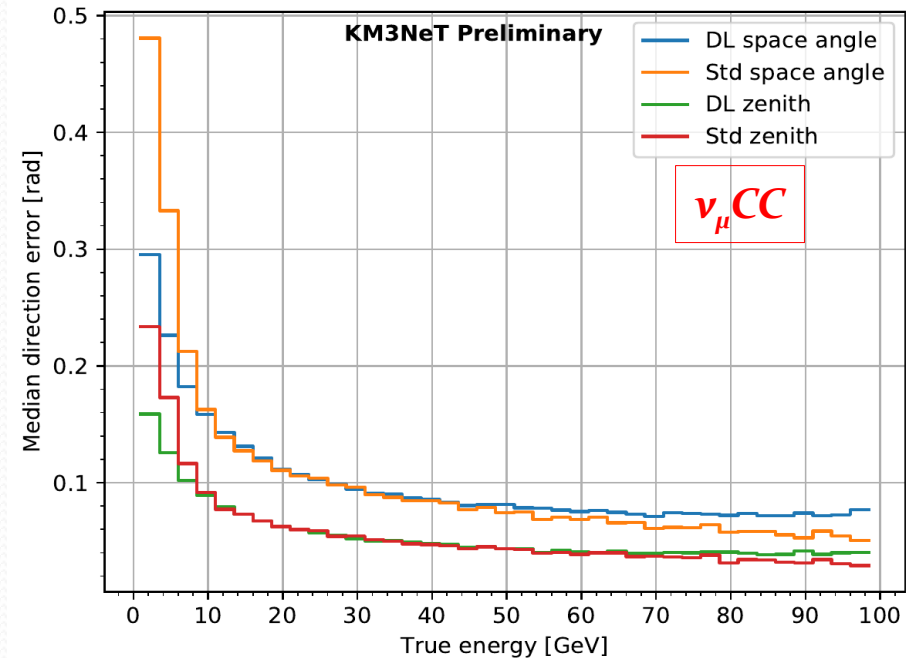
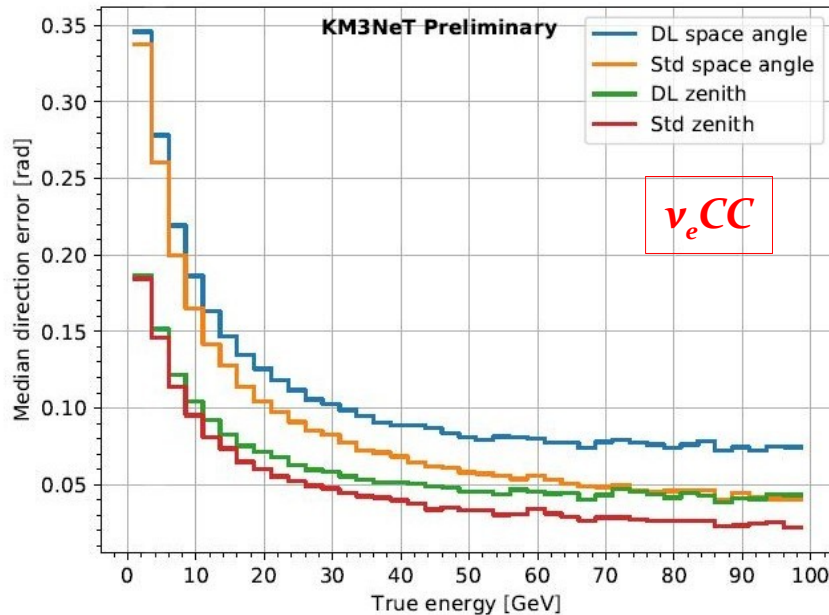


$$MRE = \left\langle \left| \frac{E_{reco} - E_{true}}{E_{true}} \right| \right\rangle$$

The performances of the CNN regressor with respect the Maximum Likelihood shower reconstructed algorithm are significantly better.

Direction Fit

The median absolute error (ME) is defined as the median of the distribution of residuals distribution for the reconstructed direction



CNN **vs** Max Likelihood method:

➤ full direction

➤ zenith angle

The performance of CNN are significantly better than the MaxLikelihood method for energies below a few GeV.

The performance of MaxLikelihood method improves with the energy.

Error Estimate

Output of the network $\rightarrow \vec{y}_{reco}$

$$\vec{y}_{reco} = (E + \text{dir}_{reco} + v t x_{reco})$$

one additional neuron to estimate the uncertainty for each component of $\vec{y}_{reco}$

Loss Function

$$L = \frac{1}{n} \sum_{i=0}^n (\sigma_{reco} - |y_{true} - y_{reco}|^2)$$

reconstructed
uncertainty

The network learns to estimate the average absolute residual $\sigma_{reco} \approx \langle y_{abs} \rangle$

Error Estimate

Output of the network $\rightarrow \vec{y}_{reco}$

$$\vec{y}_{reco} = (E + dir_{reco} + vtx_{reco})$$

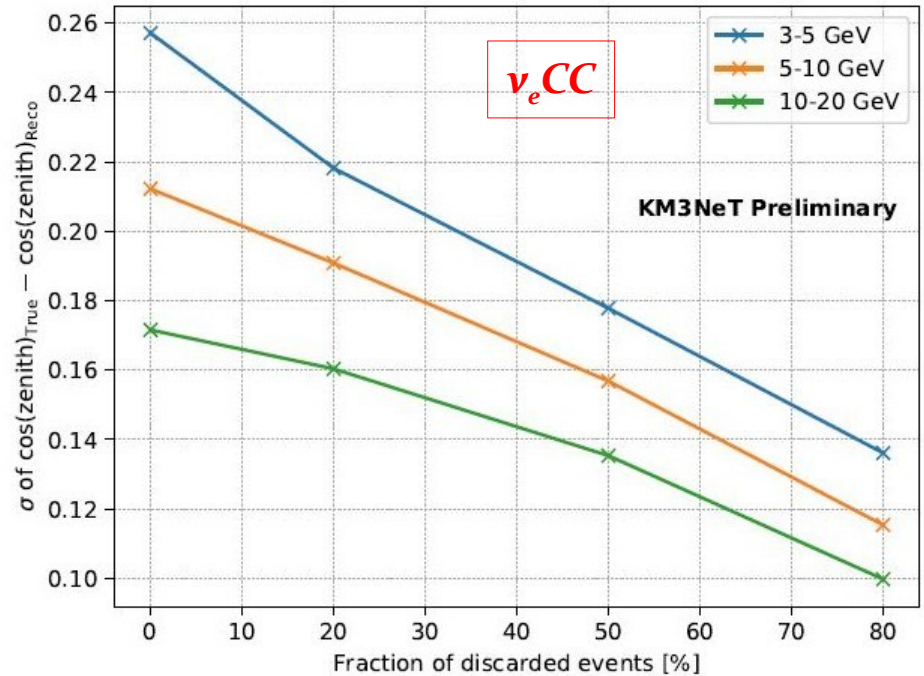
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reconstructed
uncertainty

The network learns to estimate the average absolute residual $\sigma_{reco} \approx \langle y_{abs} \rangle$



The zenith angle resolution improves significantly when the events with the largest reconstruction error are discarded.

Conclusions and Outlook

- ❖ *Deep Learning models produce very promising results*
- ❖ *They provide stable estimations comparable with the conventional reconstruction algorithms*

Next Steps

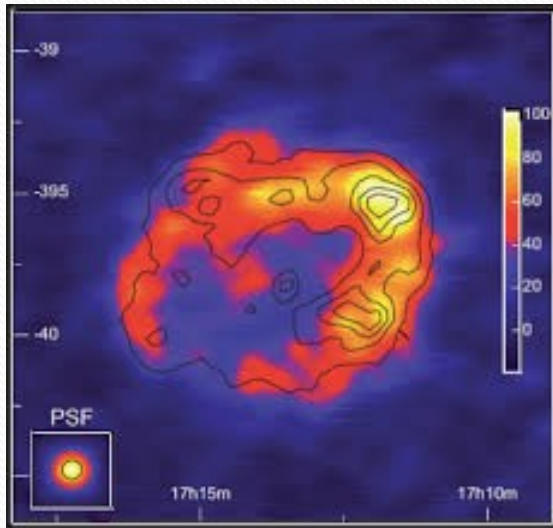
- ❖ *Detailed detector description*
- ❖ *Add ν_τ CC in topology classification*
- ❖ *Identification of neutrino flavour*



Back-up slides

KM₃NeT/ARCA

Astroparticle Research with Cosmic in the Abyss



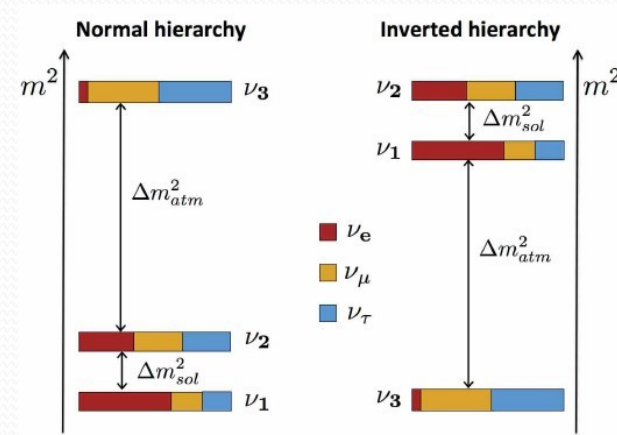
Search for point – like Galactic sources

High Energy neutrinos (100 TeV - 10 PeV):

- *Track –like events with angular resolution less than 0.2°*
- *Cascade – like events thanks to the good angular resolution ($1^\circ - 2^\circ$)*

KM₃NeT/ORCA

Oscillation Research with Cosmic in the Abyss



➤ *Determination of Neutrino Mass Hierarchy*

➤ *Indirect Dark Matter search*

➤ *Track –like and Cascade-like events induced by “low” energy neutrinos (few GeV – 10 TeV)*

Comparison Settings

(ARCA)

- *run “official” software (JGandalf) on the same test dataset used for CNN*
- *selected only ν_{μ} CC events*
- *compare results on direction estimation*
- *compare performance on up/down – going selection*