Analytical derivates of neural networks: making a fit faster

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MAPPING THE PROTON IN 3D

3DSP

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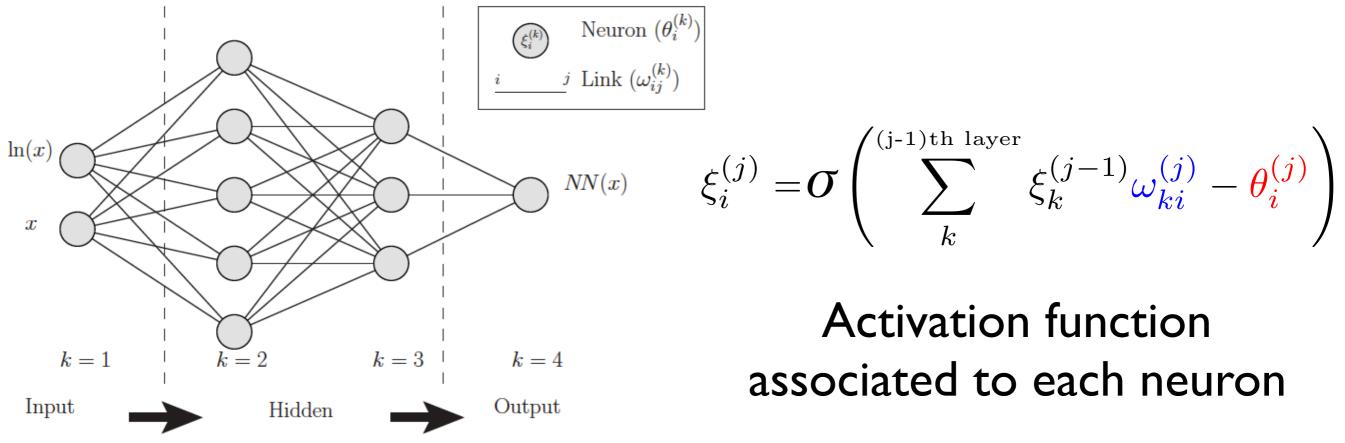
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Therefore the theoretical prediction is a **functional** of the initial-scale distributions and so is the χ^2 :

 $\hat{F} \equiv \hat{F}[\{N_i\}]$ and $\chi^2 \equiv \chi^2[\{N_i\}]$

A feed-forward neural network (NN) is parameterised in terms of links and biases, e.g.:



Effectively, a NN is nothing but a parametric function:

$$N_{i} \equiv N_{i}(x; \{\omega_{ij}^{(\ell)}, \theta_{i}^{(\ell)}\}) = \sigma_{L} \left(\sum_{j^{(1)}=1}^{N_{L-1}} \omega_{ij^{(1)}}^{(L)} y_{j^{(1)}}^{(L-1)} + \theta_{i}^{(L)}\right)$$
$$= \sigma_{L} \left(\sum_{j^{(1)}=1}^{N_{L-1}} \omega_{ij^{(1)}}^{(L)} \sigma_{L-1} \left(\sum_{j^{(2)}=1}^{N_{L-2}} \omega_{j^{(1)}j^{(2)}}^{(L)} y_{j^{(2)}}^{(L-2)} + \theta_{j^{(1)}}^{(L-1)}\right) + \theta_{i}^{(L)}\right)$$
$$= \dots$$

• In order to minimise the χ^2 optimally, we want to be able to compute the following derivatives:

$$\frac{\partial \chi^2}{\partial \omega_{ij}^{(\ell)}} = 2\left(\frac{\mathbf{C} \otimes \mathbf{N} - F}{\sigma^2}\right) \mathbf{C} \otimes \frac{\partial \mathbf{N}}{\partial \omega_{ij}^{(\ell)}}$$

$$\frac{\partial \chi^2}{\partial \theta_i^{(\ell)}} = 2 \left(\frac{\mathbf{C} \otimes \mathbf{N} - F}{\sigma^2} \right) \mathbf{C} \otimes \frac{\partial \mathbf{N}}{\partial \theta_i^{(\ell)}}$$

- This boils down to computing the **derivative of the NN** w.r.t. to its free parameters.
- We can surely do it **numerically** (incremental ratio).
- Can we also do it **analytically** for a generic architecture?
 - better numerical stability,
 - 🍯 faster.

Deriving a Neural Network

• Yes, we can derive a feed-forward NN by using the **chain rule**:

$$\frac{\partial N_k}{\partial \theta_i^{(\ell)}} = \Sigma_{ki}^{(\ell)} z_i^{(\ell)} \quad \text{and} \quad$$

$$\frac{\partial N_k}{\partial \omega_{ij}^{(\ell)}} = \Sigma_{ki}^{(\ell)} z_i^{(\ell)} y_j^{(\ell-1)}$$

with:

$$\begin{split} x_i^{(\ell)} &= \sum_{j=1}^{N_{\ell-1}} \omega_{ij}^{(\ell)} y_j^{(\ell-1)} + \theta_i^{(\ell)} , \qquad \Sigma^{(\ell)} = \prod_{\alpha=L}^{\ell+1} \mathbf{S}^{(\alpha)} \\ y_i^{(\ell)} &= \sigma_\ell \left(x_i^{(\ell)} \right) , \qquad z_i^{(\ell)} \omega_{ij}^{(\ell)} = S_{ij}^{(\ell)} \left(= \frac{\partial y_i^{(\ell)}}{\partial y_j^{(\ell-1)}} \right) \\ z_i^{(\ell)} &= \sigma_\ell' \left(x_i^{(\ell)} \right) , \end{split}$$

Tests against numerical derivatives show that it works beautifully!

Exploiting analytic derivatives Use **APFEL/APFELgrid** as it give access to the initial-scale PDFs:

$$F(Q) = \underbrace{C(Q) \otimes \Gamma(Q, \mu_0)}_{\text{FK table}} \otimes f(\mu_0)$$

Use **ceres-solver** to assess the impact of different derivation strategies:

- analytic derivatives,
- numerical derivatives (incremental ratio: forward/backward/central),
- automatic derivatives:

Dual Numbers & Jets

Dual numbers are an extension of the real numbers analogous to complex numbers: whereas complex numbers augment the reals by introducing an imaginary unit ι such that $\iota^2=-1$, dual numbers introduce an *infinitesimal* unit ϵ such that $\epsilon^2=0$. A dual number $a+v\epsilon$ has two components, the *real* component a and the *infinitesimal* component v.

http://ceres-solver.org/automatic derivatives.html#chapter-automatic-derivatives

Dual numbers and Jets

For example, consider the function

$$f(x)=x^2,$$

Then,

$$egin{aligned} f(10+\epsilon) &= (10+\epsilon)^2 \ &= 100+20\epsilon+\epsilon^2 \ &= 100+20\epsilon \end{aligned}$$

Observe that the coefficient of ϵ is Df(10) = 20. Indeed this generalizes to functions which are not

A Jet is a *n*-dimensional dual number, where we augment the real numbers with *n* infinitesimal units ϵ_i , i = 1, ..., n with the property that $\forall i, j : \epsilon_i \epsilon_j = 0$. Then a Jet consists of a *real* part *a* and a *n*-dimensional *infinitesimal* part **v**, i.e.,

$$x=a+\sum_{j}v_{j}\epsilon_{j}$$

The summation notation gets tedious, so we will also just write

$$x = a + \mathbf{v}.$$

where the ϵ_i 's are implict. Then, using the same Taylor series expansion used above, we can see that:

$$f(a + \mathbf{v}) = f(a) + Df(a)\mathbf{v}$$

Automatic derivation

Automatic derivatives are available through ceres if one templates the function to be derived in such a way to evaluate it, not just on real numbers, but also on dual numbers/jets:

```
template<class T>
class FeedForwardNN
{
  public:
```

Ouring the fit ceres takes care of computing the derivatives w.r.t. the free parameters by evaluating the (jet-valued) function on a jet.

Performance

Fit 100 points of a sine function using a NN with one single hidden layer with an increasing number of nodes:

> - Exp -**--** NN $\chi^2 = 0.000000$ 0.5 0 -0.55 3 6

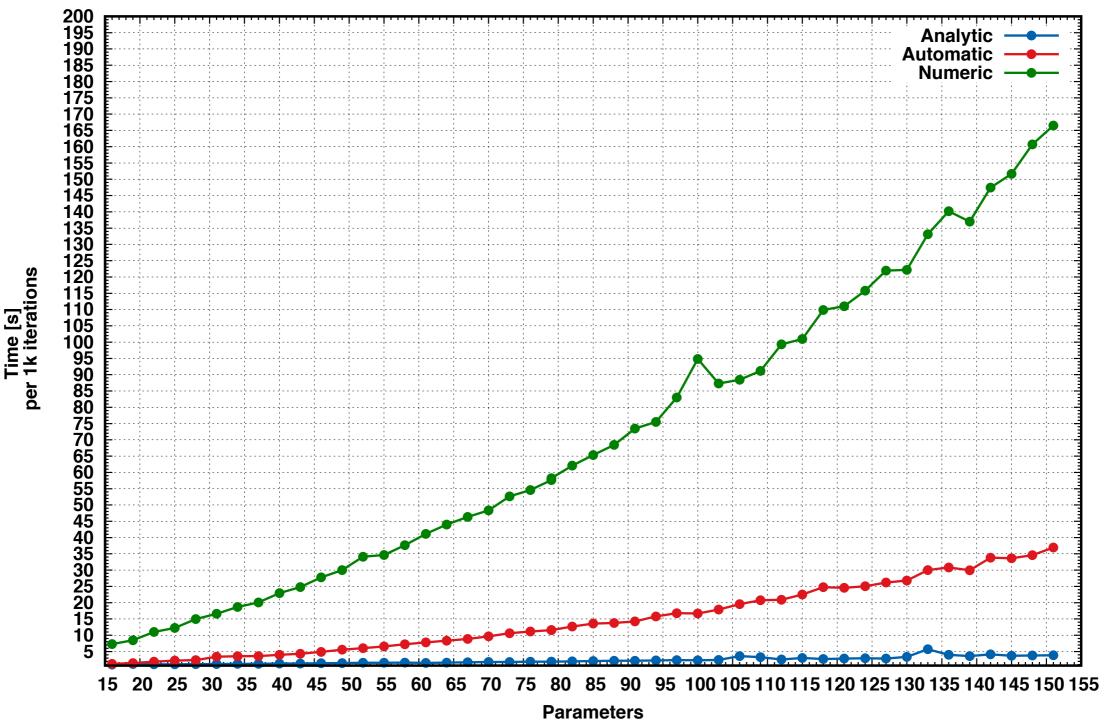
• Let the code run for **1k iterations** ($\chi^2 \approx 10^{-9} - 10^{-12}$).

Title

Performance

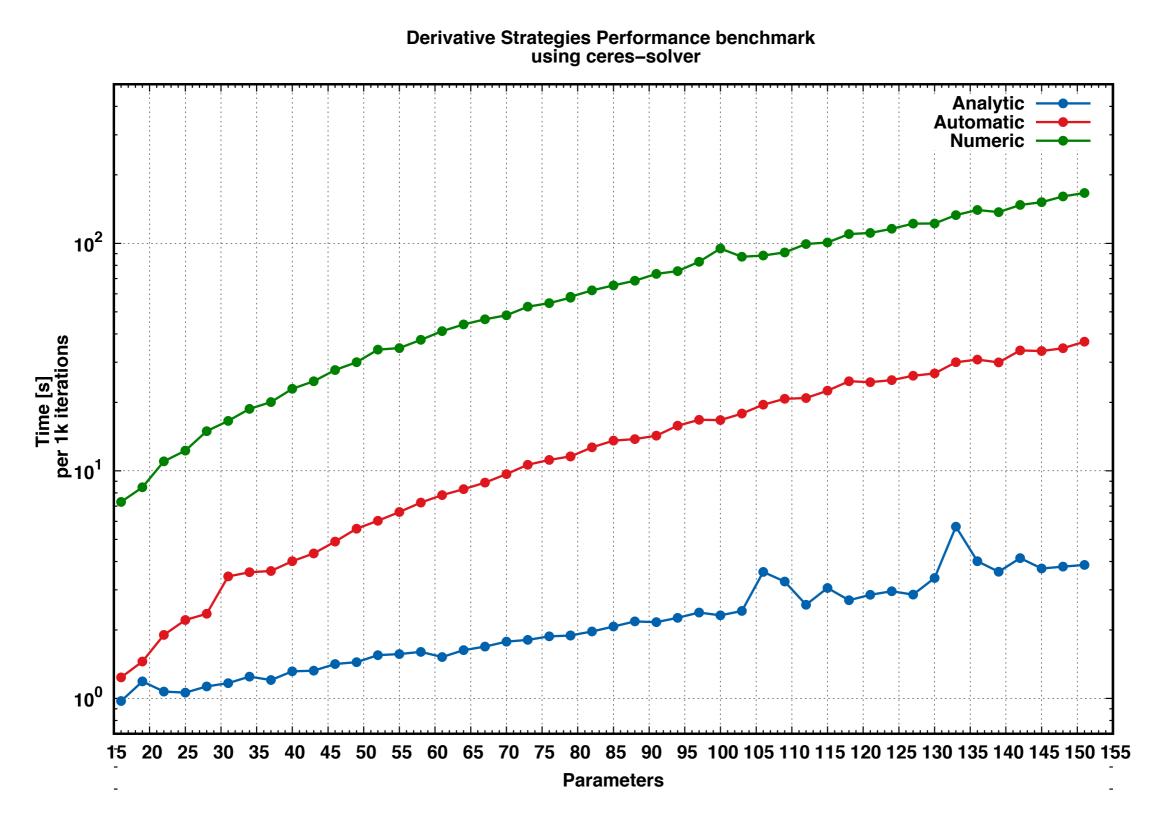
NNAGD^{A Neural Network library for} Analytical Gradient Descent

Derivative Strategies Performance benchmark using ceres-solver



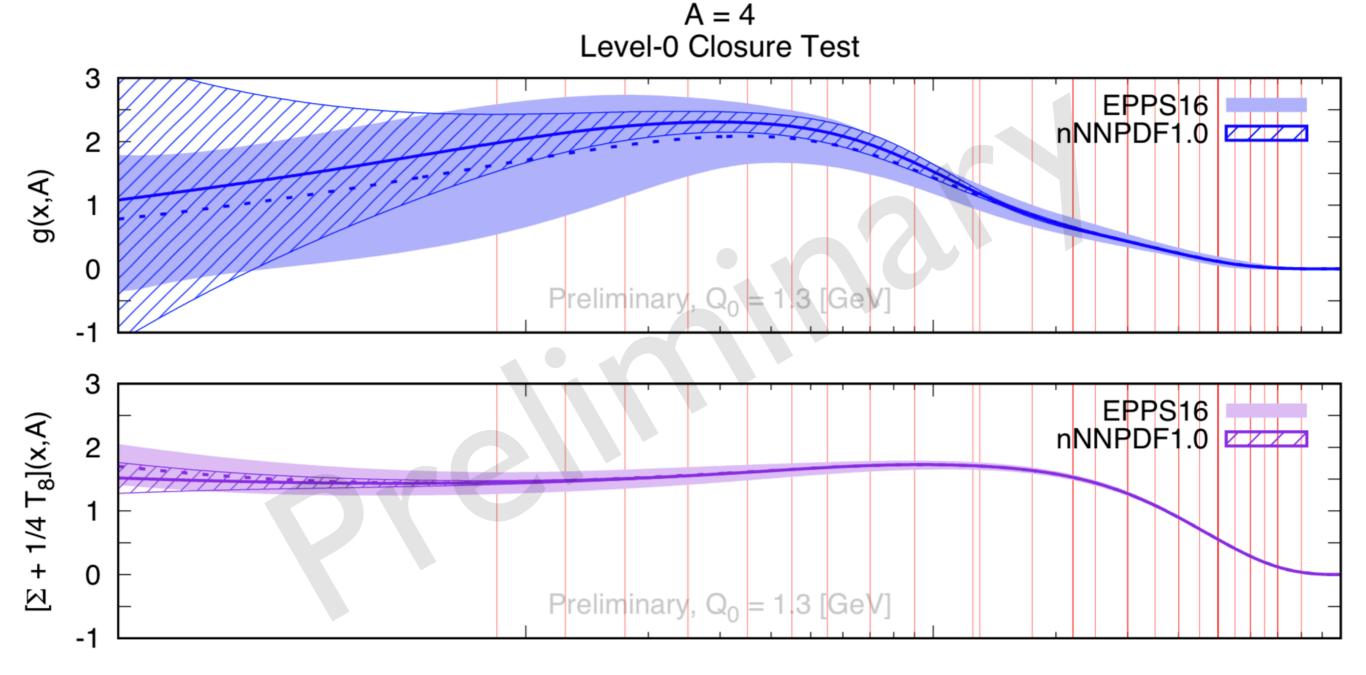
Performance

NNAGD A Neural Network library for Analytical Gradient Descent



Preliminary closure tests

Use analytic derivatives of a feed-forward NN to extract nuclear PDFs from DIS pseudo-data (closure test) using APFELgrid and ceres:





- Feed-forward NNs can be derived analytically by using the chain rule,
- for this allows one to compute the gradient of the χ^2 analytically:
 - provided that one uses an **APFELgrid-like computation**.
- The analytic knowledge of the gradient of the χ^2 makes a fit much faster.
- We have used ceres to assess the performance of analytic, numeric, and automatic differentiation.
- Analytic derivatives seem to perform substantially better.