

RAPP Center and Leopold Franzens Universität Innsbruck

# Progress of the momentum diffusion module

Lukas Merten

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# Contents



## Recapitulation of Diffusion in CRPropa

- DiffusionSDE, AdvectionField, AdiabaticCooling, etc.

## Momentum Diffusion

## Current status in CRPropa

- Techniques and examples

## Summary / Outlook

- Prospects and problems

# TRANSPORTEQUATION

# Transport Equation

$$\frac{\partial n(\vec{r}, p, t)}{\partial t} + \underbrace{\vec{u} \cdot \nabla n}_{\text{Advection}} = \underbrace{\nabla \cdot (\hat{\kappa} \nabla n)}_{\text{Spatial Diffusion}} + \underbrace{\frac{p}{3} (\nabla \cdot \vec{u}) \frac{\partial n}{\partial p}}_{\text{Adiabatic effects}} + \underbrace{S}_{\text{Sources}}$$

Partial (Fokker-Planck) Differential Equation (PDE) for particle density  $n$



**Equivalence**

Assumption:

- Isotropic CR density ( $n \neq n(\vec{p})$ )
- No CR feedback on magnetic fields

Stochastic Differential Equation (SDEs)

From here on:

- Solving the SDE in the local magnetic field line frame
- Neglect momentum diffusion

$$d\vec{x} = \underline{\vec{u} dt} + \underline{\hat{D} d\vec{w}}$$

$$dp = \underline{-\frac{p}{3} (\nabla \cdot \vec{u}) dt}$$

# Comparison grid vs. SDE

Grid-based:

GalProp, DRAGON, PICARD, ...

## Advantages

- ✓ Implement collective behavior
- ✓ Tested and well understood
- ✓ (nearly) complete
  
- ✓ PICARD: Explicit stationary solver

## Disadvantages

- Huge RAM
- Not possible to reweight
- No information on single particles

SDE-based:

CRPropa, Kopp+ ('12), Miyake+ ('14), ...

## Advantages

- ✓ Scales linearly with number of processors
- ✓ Reweighting is possible
- ✓ Not restricted to grid
- ✓ Backtracking possible
- ✓ Discontinuities can be handled

## Disadvantages

- Averaging of results necessary  
→ Many pseudo particles
- Not all interactions implemented yet
- Conceptually more complicated

# Numerical integration scheme

## New modules

- DiffusionSDE
- AdvectionField
- AdiabaticCooling
- Homogeneous, Spherical Shock, etc.

## Numerical solver: Euler-Maruyama Integration

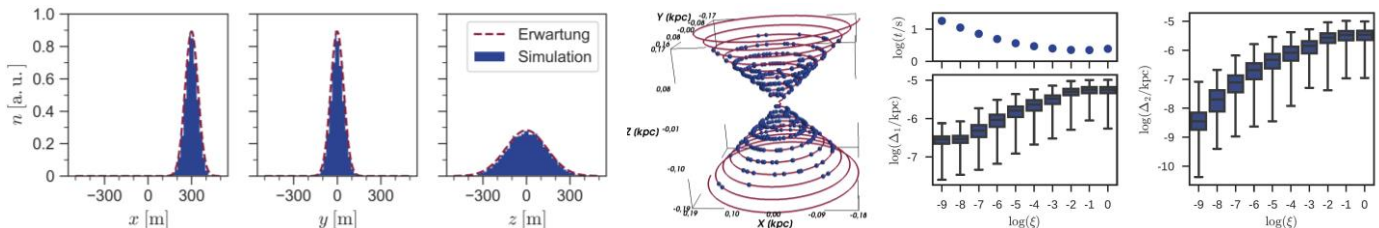
$$x_{n+1} - x_n = (u_x \vec{e}_x + u_y \vec{e}_y + u_z \vec{e}_z) \cdot h$$

$$+ (\sqrt{2\kappa_{\parallel}\eta_{\parallel}} \vec{e}_t + \sqrt{2\kappa_{\perp}\eta_{\perp,1}} \vec{e}_n + \sqrt{2\kappa_{\perp}\eta_{\perp,2}} \vec{e}_b) \cdot \sqrt{h}$$

$$p_{n+1} - p_n = -p_n/3 (\nabla \cdot \vec{u}) \cdot h$$

**Validation I:** Homg. magn. field  $\vec{B} = B_0 \vec{e}_z$ , wind  $\vec{u} = u_0 \vec{e}_x$  and aniso. Diffusion  $\epsilon = 0,1$

**Validation II:** Spiral magn. Field, no wind and parallel Diffusion  $\epsilon = 0$  only



# Stat. Solution / Finite Source duration

For the Galactic CR distribution often a stationary solution ( $\partial n / \partial t = 0$ ) or finite source duration, e.g., ( $S = S_0 \cdot \Theta(t - t_0)\Theta(t_1 - t)$ ,  $t_1 > t_0$ ) is of interest

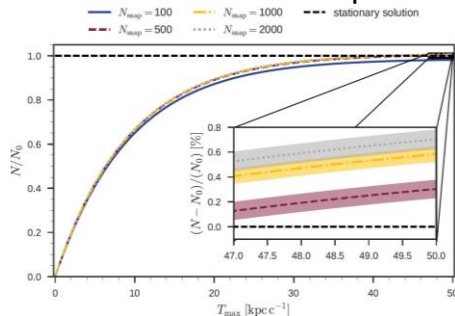
## Problem

CRPropa does only simulate a bursting source  $S \propto \delta(t - t_0)$

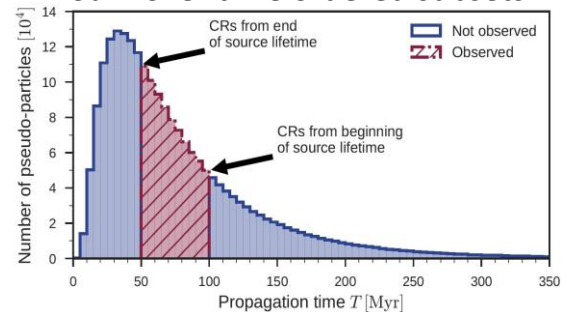
## Solution

Clever data taking and reweighting of simulation results

- Register all CRs in the simulation volume several times
- Sum over all these snapshots



- Continuously register all CR at a given observer
- Sum over time ordered subsets



# MOMENTUM DIFFUSION



# Transport Equation

$$\frac{\partial n(\vec{r}, p, t)}{\partial t} + \vec{u} \cdot \nabla n = \nabla \cdot (\hat{\kappa} \nabla n) + \underbrace{\frac{1}{p^2} \frac{\partial}{\partial p} \left( p^2 \kappa_{pp} \frac{\partial n}{\partial p} \right)}_{\substack{\text{Momentum} \\ \text{Diffusion}}} + \frac{p}{3} (\nabla \cdot \vec{u}) \frac{\partial n}{\partial p} + S$$

$$d\vec{x} = \vec{u} dt + \hat{D} d\vec{w}$$

$$dp = -p/3 (\nabla \cdot \vec{u}) dt + \underbrace{\left( \frac{\partial \kappa_{pp}}{\partial p} - 2/p \kappa_{pp} \right) dt + D_{pp} dw_p}_{\text{Momentum Diffusion}}$$

$$\begin{aligned} x_{n+1} - x_n &= (u_x \vec{e}_x + u_y \vec{e}_y + u_z \vec{e}_z) \cdot h \\ &\quad + (\sqrt{2\kappa_{\parallel}} \eta_{\parallel} \vec{e}_t + \sqrt{2\kappa_{\perp}} \eta_{\perp,1} \vec{e}_n + \sqrt{2\kappa_{\perp}} \eta_{\perp,2} \vec{e}_b) \cdot \sqrt{h} \\ p_{n+1} - p_n &= \left( -p_n/3 (\nabla \cdot \vec{u}) + \frac{\partial \kappa_{pp}}{\partial p} - 2 \cdot \kappa_{pp}/p \right) \cdot h \\ &\quad + (\sqrt{2\kappa_{pp}} \eta_p) \cdot \sqrt{h} \end{aligned}$$

# Relation of spatial and momentum diffusion

1. The momentum diffusion is generally defined as:  $\kappa_{pp} = \frac{\langle \Delta p^2 \rangle}{\tau}$   
(see, e.g., TKG formulation [Taylor 1922, Green 1951, Kubo 1958])
2. The mean momentum transfer for diffusion in Alfvén waves per scattering process is:  $\Delta p \propto v_A p$
3. The scattering time is connected to the spatial diffusion  $\tau \propto \hat{\kappa}(p)$

$$\kappa_{pp} \propto \frac{v_A^2 p^2}{\kappa(p)}$$

This allows to easily implement a model for momentum diffusion, when the spatial diffusion is established.

**STATUS**

# Work in progress...

- First implementation of momentum diffusion is done
- Up to now it is planned to be part of the DiffusionSDE-module
  - Make use of the existing structure
  - Avoid code duplication
  - Make use of calculation that have to be done anyway
- Makes the module even longer
- Maybe hard to debug and maintain
- There is version on my GitHub-page
  - **WARNING:** Not tested extensively, yet.

# The process routine

```
23 void MomentumDiffusion::process(Candidate *c) const {
24
25     double p = c->current.getEnergy()/c_light; // Note we use E=p/c (relativistic limit)
26     double rig = p*c_light / c->current.getCharge();
27     double dt = c->getCurrentStep() / c_light;
28
29     std::cout <<dt<<"\n";
30     double eta = Random::instance().randNorm();
31     double domega = eta * sqrt(dt);
32
33
34     double AScal = calculateAScalar(rig, p);
35     double BScal = calculateBScalar(rig, p);
36
37     double dp = AScal * dt + BScal * domega;
38     std::cout <<dp<<"\n";
39     c->current.setEnergy((p + dp)*c_light);
40
41     //c->limitNextStep(limit * p / ((AScal + BScal/sqrt(dt)) * c_light));
42     c->limitNextStep(limit * p / ((AScal + BScal/sqrt(dt)) * c_light)); //Check for the factor c_light
43
44 }
45
```

# The physics behind

```
49 double MomentumDiffusion::calculateBScalar(double rig, double p) const{
50
51     double Dxx = scale * 6.1e24 * pow((std::abs(rig) / 4.0e9), alpha);
52     double Dpp = ( 4*vA*vA*p*p ) / ( 3*alpha*(4-alpha*alpha)*(4-alpha) ) / Dxx; // Astroparticle Physics: Theory and Phenomenology, G. Sigl,
53     double BScal = sqrt( 2 * Dpp);
54     return BScal;
55
56 }
57
58 // What is the physical interpretation of this term? 7/27/19 LM
59 double MomentumDiffusion::calculateAScalar(double rig, double p) const {
60
61     double Dxx = scale * 6.1e24 * pow((std::abs(rig) / 4.0e9), alpha);
62     double Dpp = ( 4*vA*vA*p*p ) / ( 3*alpha*(4-alpha*alpha)*(4-alpha) ) / Dxx;
63     double partialDpp = (2 - alpha) / p * Dpp; //check the sign: Should be correct 7/27/19 LM
64
65     double AScal = partialDpp -2. / p * Dpp; //=-alpha / p * Dpp
66     return AScal;
67
68 }
```

# SUMMARY / OUTLOOK

# Open problems / Solutions



Implement momentum diffusion as part of Diffusion SDE

Make it flexible

- Connected to implementation of  $\left(\frac{\delta b}{B}\right)$ -dependence of the spatial diffusion tensor

Validation and testing

- Compare to earlier results, e.g., by Tobias (arXiv:1612:03675v2)