## Direct Integration for Multi-leg Amplitudes: Tips, Tricks, and When They Fail

[arXiv:1712.02785] with J. Bourjaily, A. Mcleod, M. Spradlin, and M. Wilhelm
[arXiv:1805.09326] with J. Bourjaily, Y.-H. He, A. Mcleod, and M. Wilhelm
[arXiv:1805.10281] with J. Bourjaily, A. Mcleod, and M. Wilhelm
[arXiv:1810.07689] with J. Bourjaily, A. Mcleod, and M. Wilhelm
[arXiv:1910.01534] with J. Bourjaily, A. Mcleod, C. Vergu, M. Volk, and M. Wilhelm
[arXiv:1910.14224] with J. Bourjaily, A. Mcleod, C. Vergu, M. Volk, and M. Wilhelm
[arXiv:1912.05690] with J. Bourjaily, M. Volk

#### Matt von Hippel (Niels Bohr International Academy)

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## Disclaimer: Speaker is Supersymmetric



- I work with  $\mathcal{N} = 4$  SYM
  - Thus multi-leg: beta function vanishes, amplitudes through five points known in the planar limit [see Papathanasiou's and Bartels's talks]
  - Integrals chosen UV finite, can IR regulate with masses to stay in four dimensions
  - Uniform transcendentality [see Henn's talk]

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• Nice integrals, even as a basis for other theories!

## What I mean by Direct Integration

Direct hyperlogarithmic integration:

- Rewrite hyperlogarithms in the integrand so that the integration variable appears only in the argument, via a fibration basis
- Partial-fraction rational functions in the integrand in terms of the integration variable
- Up to integration by parts (and regularizing singularities), can then just apply the definition of the hyperlogarithm

$$G(w_1, w_2, \ldots; z) = \int_0^z \frac{1}{x - w_1} G(w_2, \ldots; x) dx$$

• Implemented in Erik Panzer's HyperInt, [Also see his talk]

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## What can go wrong: Algebraic Roots

- Both the fibration basis and partial-fractioning can introduce algebraic roots in the remaining integration variables
- This stops the algorithm: can't fiber or partial-fraction if integration variable is in an algebraic root not linearly reducible
- In some cases, can find systematic change of variables to fix this [see Besier, Van Straten, Weinzierl, also Raab's talk]

$$\begin{split} \int_0^\infty & \frac{d\alpha}{\alpha^2 + 2f\alpha + g} \\ &= \int_0^\infty & \frac{d\alpha}{2\sqrt{f^2 - g}} \left( \frac{1}{\alpha + f - \sqrt{f^2 - g}} - \frac{1}{\alpha + f + \sqrt{f^2 - g}} \right) \\ &= \frac{1}{2\sqrt{f^2 - g}} \log \left( \frac{f - \sqrt{f^2 - g}}{f + \sqrt{f^2 - g}} \right) \end{split}$$

## Tips, Tricks, and When They Fail

From my "supersymmetric perspective", looking at a variety of integrals, attempting direct integration

- Sometimes, tricks to avoid algebraic roots (simple, but unexpectedly powerful!)
- Sometimes, roots cancel seeing this can be tricky!
- Sometimes, tricks fail in interesting ways!

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## Introduction

- 2 Tips and Tricks for a Rational Result
- 8 Kinematic Square Roots at Symbol Level
- 4 Parametric Square Roots: Elliptic and Beyond
  - 5 Conclusions

#### Introduction

#### 2 Tips and Tricks for a Rational Result

Kinematic Square Roots at Symbol Level

Parametric Square Roots: Elliptic and Beyond

#### 5 Conclusions

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## Minimal Representations: Loop-by-Loop

- Conjecturally, hyperlogarithms in Feynman integrals in 4D have bounded transcendental weight  $\leq 2L$
- When possible, want to represent as 2L-fold integrals
- This is not generally true for Symanzik form, one variable per propagator
- Can get closer by parametrizing "loop by loop" [Analogous to loop-by-loop Baikov, see Frellesvig's talk]
- $\bullet\,$  Heuristically, fewer "extra integrals"  $\to\,$  fewer chances to introduce spurious algebraic roots

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## Good Variables: Momentum Twistor Parametrizations

#### [1805.10281, Bourjaily, McLeod, MvH, Wilhelm]

- Planar N = 4 SYM has dual conformal symmetry: conformal in dual space x<sub>i</sub> x<sub>i+1</sub> = p<sub>i</sub>
- Momentum twistor variables are linear in this symmetry, trivialize momentum conservation, masslessness, by assigning each dual point x<sub>i</sub> to a line {z<sub>i−1</sub>, z<sub>i</sub>} in P<sup>3</sup> [Hodges]
- Space of lines is six-dimensional, so these variables make Gramian matrices  $G = \{G_b^a = (x_a x_b)^2\}$  generically rank six
- Minors larger than 6 × 6 should vanish, implying relations between kinematic variables that involve square roots of 6 × 6 determinants. Momentum twistors rationalize these square roots.

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## Sometimes, this is enough...



These seven- and eight-point classes of integrals run "out of the box" through four loops!

## Sometimes it isn't



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## Splitting the Integration Path

$$\mathcal{I}(\alpha,\beta) \xrightarrow{\int d^{2}\beta} \mathcal{I}(\alpha) = \begin{cases} \int d\alpha_{1}, \int d\alpha_{2} \left\{ \mathcal{I}_{A_{0}}[\not \ni \sqrt{q_{1}}, \sqrt{q_{2}}] \\ \mathcal{I}_{A_{1}}[\ni \sqrt{q_{1}(\alpha_{3}, \alpha_{4})}] \\ \mathcal{I}_{A_{2}}[\ni \sqrt{q_{2}(\alpha_{3}, \alpha_{4})}] \\ \mathcal{I}_{A_{2}}[\ni \sqrt{q_{2}(\alpha_{3}, \alpha_{4})}] \\ \mathcal{I}_{B_{2}}[\ni \sqrt{q_{2}(\alpha_{1}, \alpha_{2})}] \\ \mathcal{I}_{B_{2}}[\ni \sqrt{\widetilde{q}_{2}(\alpha_{1}, \alpha_{2})}] \\ \mathcal{I}_{B_{2}}[\ni \sqrt{\widetilde{q}_{2}(\alpha_{1}, \alpha_{2})}] \\ \mathcal{I}_{B_{2}}[\ni \sqrt{\widetilde{q}_{2}(\alpha_{1}, \alpha_{2})}] \\ \end{cases} \xrightarrow{\mu = 0} \begin{pmatrix} \mathcal{I}_{A_{0}}[\not \Rightarrow \sqrt{q_{1}}, \sqrt{q_{2}}] \\ \mathcal{I}_{B_{1}}[\neg \sqrt{q_{1}(\alpha_{1}, \alpha_{2})}] \\ \mathcal{I}_{B_{2}}[\neg \sqrt{\widetilde{q}_{2}(\alpha_{1}, \alpha_{2}, \alpha_$$

Two types of tricks:

- Divide integrand into pieces which are linearly reducible via one path vs. another, by which contain specific polynomials
- Divide integrand into pieces depending on different square roots, use different change of variables in each

Some integrals require both!

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## Kinematic Roots Remain

- Not all kinematic roots are rational in momentum twistors.
- Some are spurious, introduced by the splitting procedure, while some are physical.
- Example of the latter: four-mass box cuts



#### Introduction



#### 3 Kinematic Square Roots at Symbol Level

Parametric Square Roots: Elliptic and Beyond

#### 5 Conclusions

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## Identifying Spurious Roots

- Sometimes can rationalize with a change of variables (e.g. Euler substitution), fibrate, then transform back and see the roots cancel
- Sometimes can match series expansion to expansion of an ansatz without square roots
- If these don't work, can at least check the symbol

$$df^{(n)} = \sum f_i^{(n-1)} d \ln \phi_i \quad o \quad S(f^{(n)}) = \sum S(f_i^{(n-1)}) \otimes \phi_i$$

## (Lack Of) Unique Factorization

 "The symbol trivializes all identities" if all letters are rational - factor all letters, then expand

 $\cdots \otimes \mathbf{a} \times \mathbf{b} \otimes \cdots = \cdots \otimes \mathbf{a} \otimes \cdots + \cdots \otimes \mathbf{b} \otimes \cdots$ 

• This fails for algebraic letters: no unique factorization

$$9 = 3 \times 3 = (2 + \sqrt{-5})(2 - \sqrt{-5})$$

- For small number of letters, can find relations by brute force
- Works for example for seven-point two-loop MHV in planar  $\mathcal{N} = 4$ : 22 letters can be written in terms of 5, which all drop out [1912.05690 Bourjaily, Volk, MvH]

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## Factorization in Prime Ideals

- For more complicated cases, want to do something systematic
- Let's focus on a specific kinematic point: all our symbol entries are (algebraic) numbers
- Instead of working with numbers, work with *ideals*:

$$(a) = \{ma | m \in \mathbb{Z}\}, \quad (a, b) = \{ma + nb | m, n \in \mathbb{Z}\}$$

• Then for the previous example (3),  $(2 + \sqrt{-5})$ , and  $(2 - \sqrt{-5})$  all factor further, giving a unique factorization in prime ideals:

$$(9) = (3)(3) = (2 + \sqrt{-5})(2 - \sqrt{-5}) = (3, 1 + \sqrt{-5})^2(3, 1 - \sqrt{-5})^2$$

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## Application: an NMHV Octagon

#### [1910.14224 Bourjaily, Mcleod, Vergu, Volk, MvH, Wilhelm]

• Particular supercomponent of eight-point two-loop NMHV amplitude:

$$\int d\eta_1^1 d\eta_3^2 d\eta_5^3 d\eta_7^4 \mathcal{A}_8^{L=2} = \frac{1}{\langle 1357 \rangle} \begin{bmatrix} 7 & 1 & 1 & 1 & 2 & 3 \\ 6 & N_1 & N_1 & -2 & -8 & N_1 & N_1 & -4 \\ 5 & 4 & 3 & -8 & -6 & 5 \end{bmatrix}$$

- After integration: symbols in 2000 letters with 10 million terms, many distinct algebraic roots
- After factorizing letters: symbols in 35 letters with 5000 terms, only two distinct "physical" square roots
- Cancel in the difference!

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## When the Tricks Fail

- In all of the above cases, we could at least complete the integration, getting hyperlogarithms (that depend on some kinematic root)
- This is not always the case: sometimes, still have non-rationalizable square roots in integration parameters:

$$\sqrt{P(\overrightarrow{\alpha})}$$

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- Kinematic Square Roots at Symbol Level



### Parametric Square Roots: Elliptic and Beyond

## Simplest Cases are Elliptic

$$\sqrt{(\alpha - e_1)(\alpha - e_2)(\alpha - e_3)(\alpha - e_4)}$$



[see Weinzierl's talk]

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## (Some) More Complicated Cases are Calabi-Yau



[Bloch, Kerr, Vanhove; Broadhurst] [Bourjaily, He, Mcleod, MvH, Wilhelm]



 $\sqrt{P(\alpha_1, \alpha_2, \cdots)}$ 

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## What is a Calabi-Yau?

- Compact Kähler manifold with vanishing first Chern class
- Ricci-flat
- Preserves N=1 supersymmetry of compactifications

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## What is a Calabi-Yau?

- Compact Kähler manifold with vanishing first Chern class
- Ricci-flat
- Preserves N=1 supersymmetry of compactifications
- ...not helpful!

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Embed the patient in a weighted projective space!



Embed the patient in a weighted projective space!

projective space:

$$(x_1, x_2, \ldots) \sim (\lambda x_1, \lambda x_2, \ldots)$$



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• weighted projective space:

$$(x_1, x_2, \ldots) \sim (\lambda^{w_1} x_1, \lambda^{w_2} x_2, \ldots)$$



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• weighted projective space:

$$(x_1, x_2, \ldots) \sim (\lambda^{w_1} x_1, \lambda^{w_2} x_2, \ldots)$$

• Polynomial should scale uniformly in  $\lambda$  (homogeneous polynomial)



Embed the patient in a weighted projective space!

• weighted projective space:

$$(x_1, x_2, \ldots) \sim (\lambda^{w_1} x_1, \lambda^{w_2} x_2, \ldots)$$

- Polynomial should scale uniformly in  $\lambda$  (homogeneous polynomial)
- If the sum of the coordinate weights equals the overall scaling (degree), it's Calabi-Yau!

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## Cleanest Example: Scalar Marginal Integrals

• Start with Symanzik form:

$$\Gamma(E-LD/2)\int_{x_i\geq 0} [d^{E-1}x_i]\frac{\mathfrak{U}^{E-(L+1)D/2}}{\mathfrak{F}^{E-LD/2}}$$

 $\bullet$  Graph polynomials  ${\mathfrak U}$  and  ${\mathfrak F}$  defined by:

$$\mathfrak{U} \equiv \sum_{\{\mathcal{T}\}\in\mathfrak{T}_1}\prod_{e_i\notin\mathcal{T}}x_i, \quad \mathfrak{F} \equiv \left[\sum_{\{\mathcal{T}_1,\mathcal{T}_2\}\in\mathfrak{T}_2}s_{\mathcal{T}_1}\left(\prod_{e_i\notin\mathcal{T}_1\cup\mathcal{T}_2}x_i\right)\right] + \mathfrak{U}\sum_{e_i}x_im_i^2$$

## Cleanest Example: Scalar Marginal Integrals

Two cases where things simplify, both for even dimensions:

• E = LD/2: Explored by mathematicians. Superficial divergence from gamma function, if there are no subdivergences can strip this off, no further need for dim reg. Only  $\mathfrak{U}$  contributes.

$$\int_{x_i \ge 0} [d^{E-1}x_i] \frac{1}{\mathfrak{U}^{D/2}}$$

• E = (L+1)D/2: Marginal. If finite, can again avoid dim reg. Only  $\mathfrak{F}$  contributes.

$$\int_{x_i \ge 0} [d^{E-1}x_i] \frac{1}{\mathfrak{F}^{D/2}}$$

- In D = 2, these are the sunrise/banana graphs!
- Many more cases in D = 4

## Marginal Integrals are Calabi-Yau

Let's look at our "special cases".

[Brown 0910.0114] explored the E = LD/2 case, argument for marginal integrals (E = (L + 1)D/2) similar:

- 𝔅 is homogenous, degree L + 1, so 𝔅<sup>D/2</sup> has degree (L + 1)D/2 = E in E variables
- Direct integration preserves this: each integration removes one variable, and decreases the degree of the denominator by one.
- Suppose we encounter a square root. Root  $\sqrt{Q(x_i)}$  will contain a degree 2m polynomial in m variables.
- $y^2 = Q(x_i)$  defines a variety. Give the  $x_i$  weight 1, y weight m. Then sum of the weights is equal to degree  $\rightarrow$  diagnosed Calabi-Yau!

## Example: Massless D = 4

• Specialize to D = 4, massless propagators:

$$\int_{x_i \ge 0} [d^{2L+1}x_i] \frac{1}{\mathfrak{F}^2}$$

ℑ is linear in every variable (x<sub>i</sub><sup>2</sup> only shows up in the mass term). We may integrate out any one parameter x<sub>j</sub>. Writing ℑ ≡ ℑ<sub>0</sub><sup>(j)</sup> + x<sub>j</sub> ℑ<sub>1</sub><sup>(j)</sup>:

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$$\int_{x_i\geq 0} [d^{2L}x_i] rac{1}{\mathfrak{F}_0^{(j)}\mathfrak{F}_1^{(j)}}$$

• Each factor is still linear, so we can integrate in another variable  $x_k$ . Writing  $\mathfrak{F}_i^{(j)} \equiv \mathfrak{F}_{i,0}^{(j,k)} + x_k \mathfrak{F}_{i,1}^{(j,k)}$ :

$$\int_{x_i \ge 0} [d^{2L-1}x_i] \frac{\log \left(\mathfrak{F}_{0,0}^{(j,k)}\mathfrak{F}_{1,1}^{(j,k)}\right) - \log \left(\mathfrak{F}_{0,1}^{(j,k)}\mathfrak{F}_{1,0}^{(j,k)}\right)}{\mathfrak{F}_{0,0}^{(j,k)}\mathfrak{F}_{1,1}^{(j,k)} - \mathfrak{F}_{0,1}^{(j,k)}\mathfrak{F}_{1,0}^{(j,k)}}$$

### Example: Massless D = 4

$$\int_{x_i \ge 0} [d^{2L-1}x_i] \frac{\log \left(\mathfrak{F}_{0,0}^{(j,k)}\mathfrak{F}_{1,1}^{(j,k)}\right) - \log \left(\mathfrak{F}_{0,1}^{(j,k)}\mathfrak{F}_{1,0}^{(j,k)}\right)}{\mathfrak{F}_{0,0}^{(j,k)}\mathfrak{F}_{1,1}^{(j,k)} - \mathfrak{F}_{0,1}^{(j,k)}\mathfrak{F}_{1,0}^{(j,k)}}$$

- Denominator is at most quadratic in each remaining variable.
- If irreducibly quadratic in all variables (and discriminants irreducibly cubic or quartic in all other variables), then Calabi-Yau with dimension 2L 2.
- Thus for massless marginal integrals in 4*D*, Calabi-Yau dimension is **bounded**.

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## Is this bound saturated?



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## Observations:

- The L = 2 tardigrade is a two-loop, five-point (three external masses) K3!
- We've looked at other marginal integrals through seven loops, the majority have maximal dimension Calabi-Yaus.
- The L = 3 amoeba is oddly enough *not* maximal dimension.

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## What about the Traintracks?



- Not marginal:  $E = 3L + 1 \neq (L + 1)D/2$  for  $L \neq 1$
- Not Symanzik, loop-by-loop:

$$\int_{0}^{\infty} [d^{L}\alpha] d^{L}\beta \frac{1}{(f_{1}\cdots f_{L})g_{L}}$$

$$f_{k} \equiv (a_{0}a_{k-1};a_{k}b_{k-1})(a_{k-1}b_{k};b_{k-1}a_{0})(a_{k}b_{k};a_{k-1}b_{k-1})f_{k-1} + \alpha_{0}(\alpha_{k}+\beta_{k}) + \alpha_{k}\beta_{k}$$

$$+ \sum_{j=1}^{k-1} \left[ \alpha_{j}\alpha_{k}(b_{j}a_{0};a_{j}a_{k}) + \alpha_{j}\beta_{k}(b_{j}a_{0};a_{j}b_{k}) + \alpha_{k}\beta_{j}(a_{0}a_{j};a_{k}b_{j}) + \beta_{j}\beta_{k}(a_{0}a_{j};b_{k}b_{j}) \right]$$

$$g_{L} \equiv \alpha_{0} + \sum_{j=1} \left[ \alpha_{j}(b_{j}a_{0};a_{j}b_{0}) + \beta_{j}(a_{0}a_{j};b_{0}b_{j}) \right]; \quad (ab;cd) \equiv \frac{X_{a,b} \times C,d}{X_{a,c} \times X_{b,d}}$$

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## Three-Loop K3

- Take codimension L + 1 residue, obstructed by a square root
- Get  $\sqrt{Q}$ , where Q is degree 4 in  $\alpha_2$  and degree 6 in  $\alpha_1$  and  $\alpha_0$
- Weights 3 + 1 + 1 + 1 = 6, like the marginal integrals

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## Wheel/Coccolithophore



- Once again, not marginal, not Symanzik
- Planar, relevant to  $\mathcal{N}=4~\text{sYM}$
- Can take a similar series of residues (and a handy re-projectivization) to find weights 4 + 1 + 1 + 1 + 1 = 8, CY<sub>3</sub>!

# The Theme: Every Example We Understand is $\mathbb{WP}^{k,1,1,1,...}$

- Marginal integrals, the three-loop traintrack, the wheel, all have weights  $k + 1 + 1 + 1 \dots = 2k$
- Can think of our singular manifolds as special cases of smooth  $\mathbb{WP}^{k,1,1,1,\dots}$ , reach through complex structure deformation
- Can calculate Hodge diamonds, etc.

## Further Questions

- How often can "planar  $\mathcal{N} = 4$  -like" integrals be used?
- Can we do better than tips and tricks, more deterministic algorithm?
- Does direct integration uncover the same Calabi-Yau geometries as other methods? For example, recent leading singularity calculations for traintracks by Vergu & Volk.
- How special/rare is the Calabi-Yau property?

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Matt von Hippel (NBIA)

Direct Integration for Multi-leg Amplitudes

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