



# **Update on Kinematic Fits**

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## **Some Definitions**



- $N_{\text{tot}}$ : Total number of fitted events (= 87)
- $p_i$ : kinematic fit probability (mass and momentum balance constraints only)
- $p_{\text{cut}}$ : probability cut (definition of convergence) (=0.01)
- $Np_{\text{converged}}$ : Number of events with  $p > p_{\text{cut}}$
- $L_i$ : combined likelihood  $p \times LR$  with  $LR = \prod_{i=1}^N \frac{\mathcal{L}_{\text{sig}}(\cos \theta_i^*)}{\mathcal{L}_{\text{sig}}(\cos \theta_i^*) + \mathcal{L}_{\text{bg}}(\cos \theta_i^*)}$
- $L_{cut}$ : Likelihood cut (definition of convergence) (=0.001)
- $NL_{\text{converged}}$ : Number of events with  $L > L_{\text{cut}}$

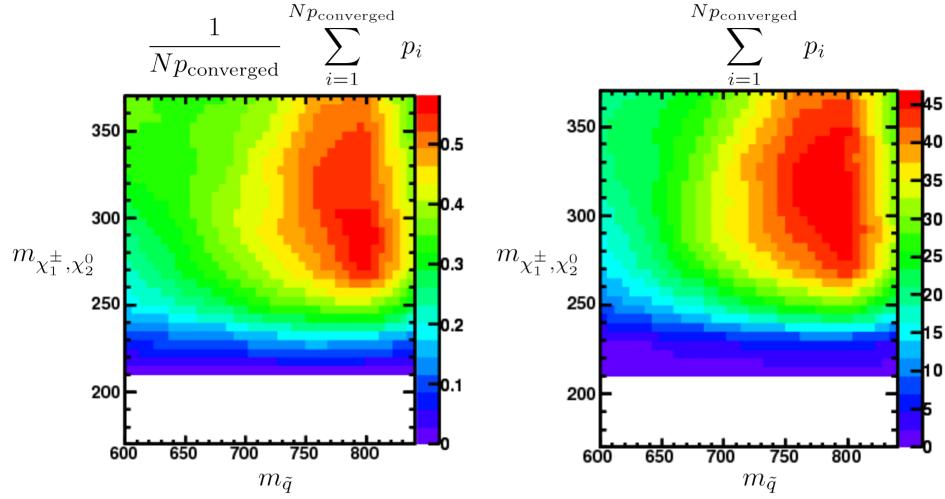
#### Here:

- Signal events (LM5) contain only Ws
- Full combinatorics
- ullet Angular distributions of squarks and charginos for calculation of LR



### Discriminators I





#### Average fit probability:

- Normalized
- Sensitive to singe accidentally good fits

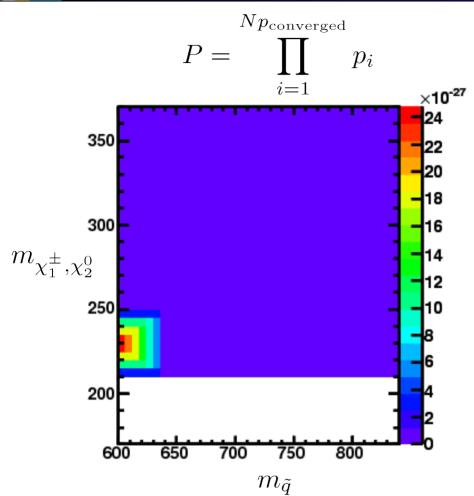
#### Frational event count:

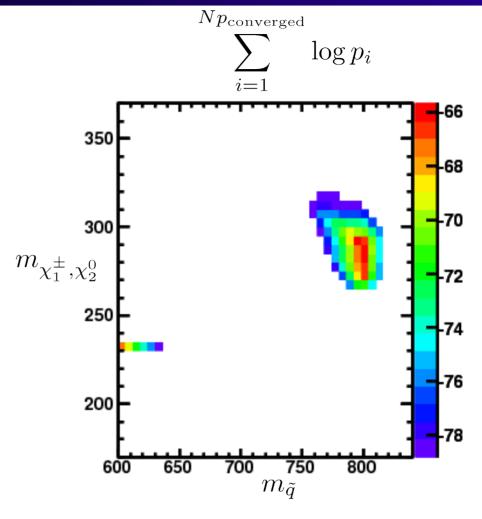
- Sensitive to number of converged events
- Peaks where most good events



### Discriminators II







Total probability of event sample:

Sensitive to number of converged events

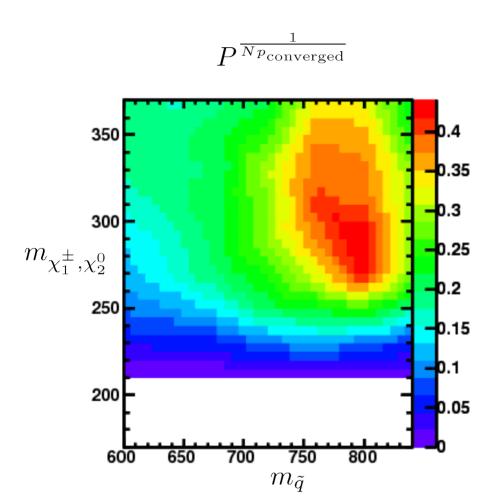
Logarithm of total probability:

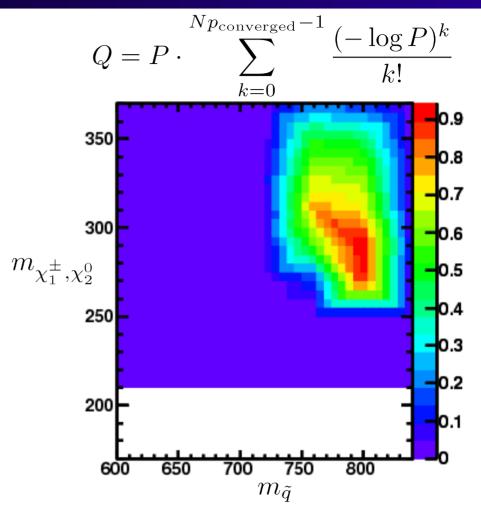
- Sensitive to number of converged events
- More stable



### **Discriminators III**







Normalized total fit probability:

- Normalized
- Sensitive to singe accidentally good fits

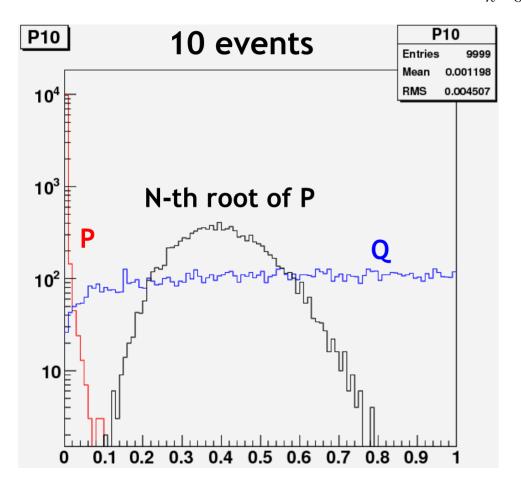
Given N equally distributed variables, Q is also equally distributed:

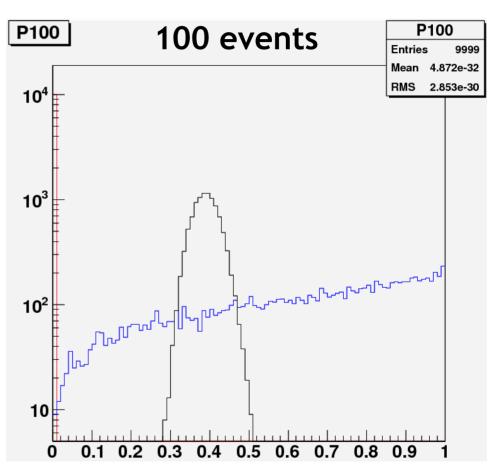
- Normalized
- Sensitive to singe accidentally good fits





$$Q = P \cdot \sum_{k=0}^{Np_{\text{converged}}-1} \frac{(-\log P)^k}{k!}$$



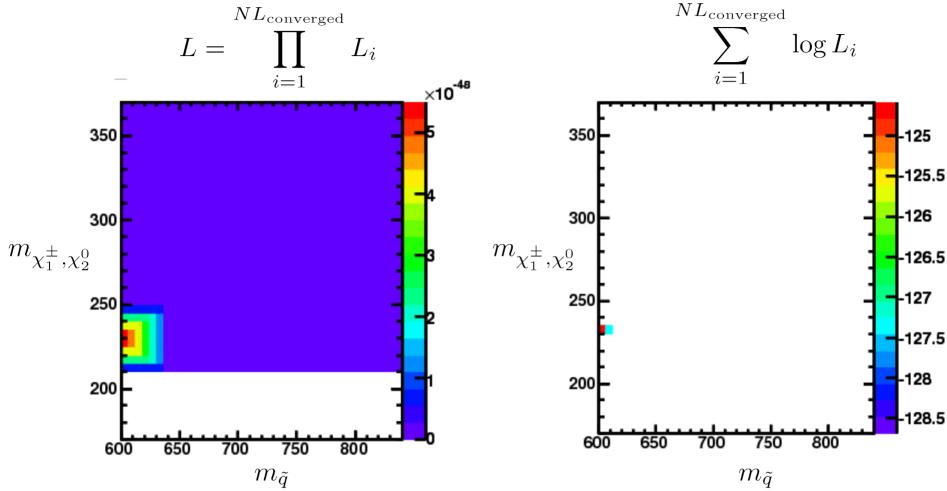


• Pcut = 0.01 (Q deviates from flat distribution, can be modelled)



#### **Discriminators IV**





Total combined likelihood of event sample:

Sensitive to number of converged events

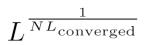
Logarithm of total combined likelihood of event sample:

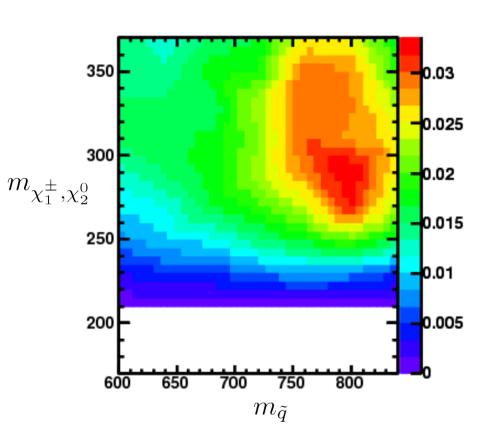
- Sensitive to number of converged events
- More stable

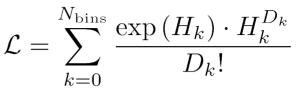


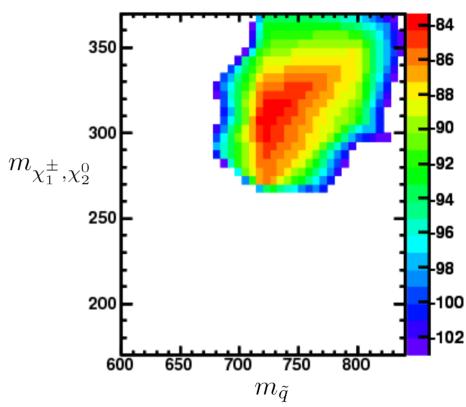
#### **Discriminators V**











Normalized total combined likelihood:

- Normalized
- Sensitive to singe accidentally good fits

Binned likelihood of fit probability:

 Contains information of whole distribution as well as proper normalization



## Conclusion



- Many possible choices of discriminator!
- Which one is the best?