

# Update on ALPIDE telescope data analysis

Oleksandr Borysov

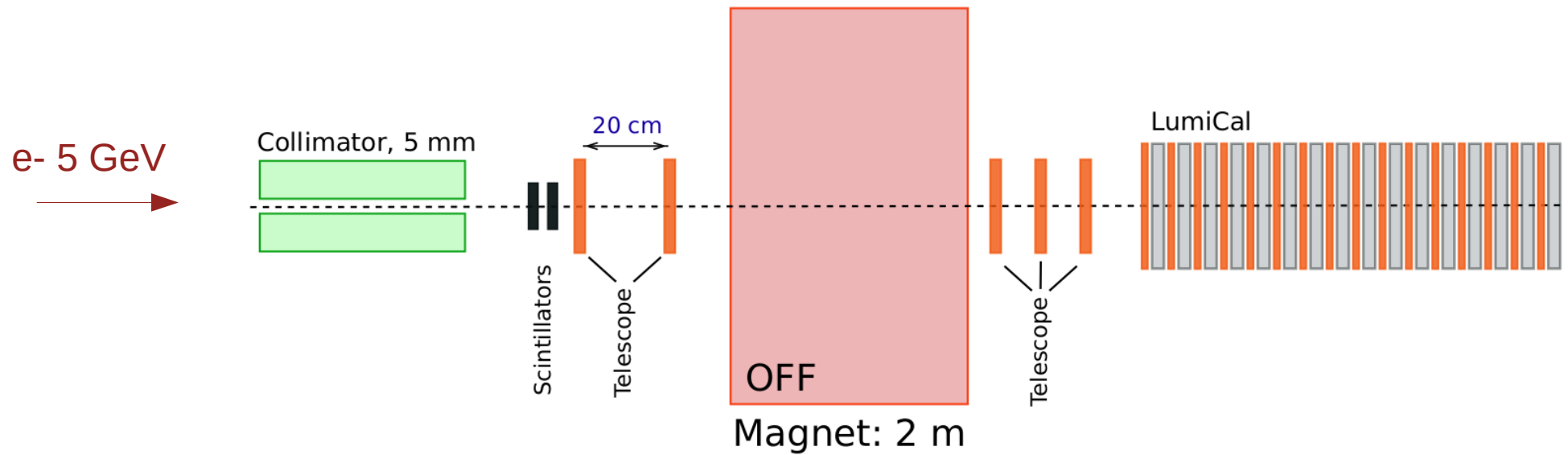


LUXE meeting  
January 16, 2020

# Outline

- Telescope planes alignment and track reconstruction performance;
  - 5 planes;
  - 3 planes;
  - 4 planes;

# Setup 1



- Measure the effect of the air  $\sim 2 \text{ m}$ .
- Collimator with 5 mm square cross section?

# Data processing

- Data converter from raw format to LCIO
- Eutelescope software. It uses ILC software:
  - for geometry settings (GEAR)
  - Marlin (Modular Analysis and Reconstruction for the LINear Collider) for data processing;
  - LCIO for input/output;
  - Converting data to root format;
  - Alignment and track reconstruction.

Noisy pixels (default settings for threshold)

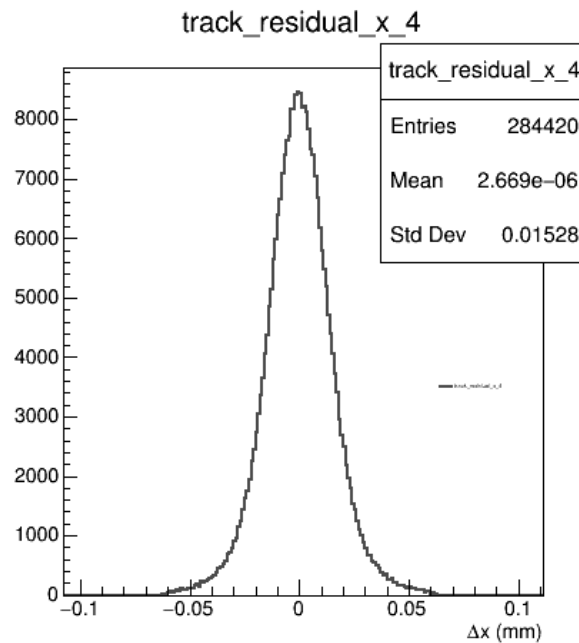
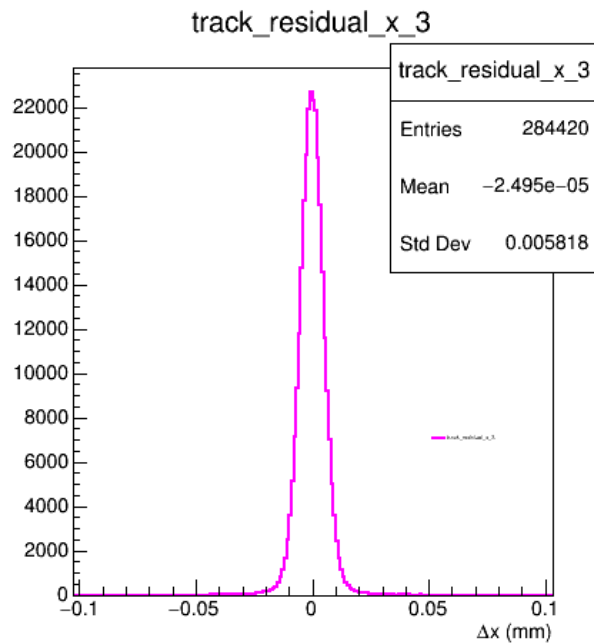
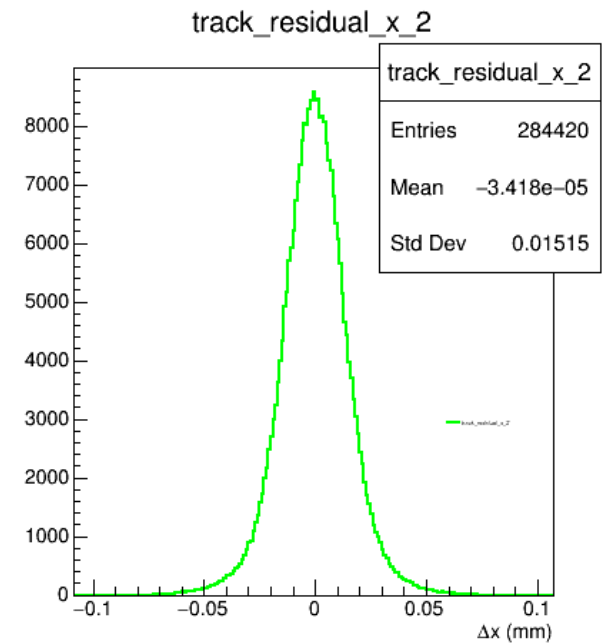
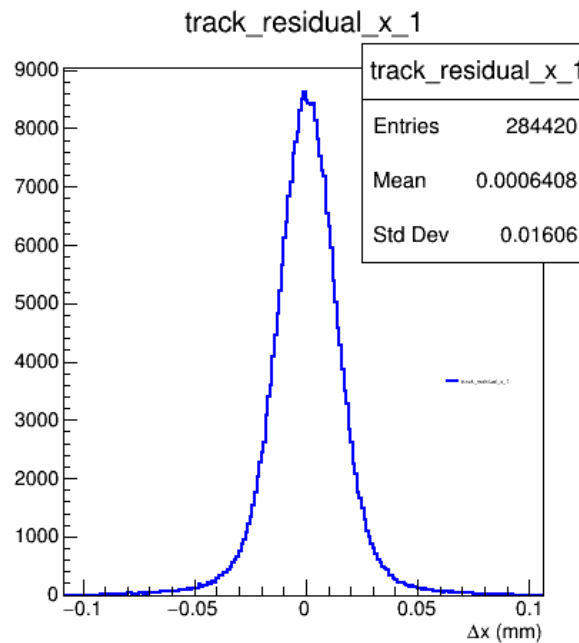
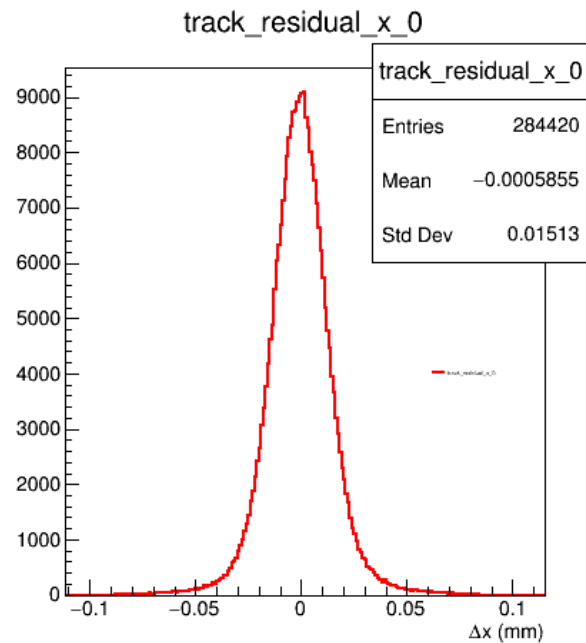
Run 49

```
jobsub.noisypixel(INFO): [ MESSAGES "HotPixelMasker"] Noisy Pixel Finder summary:
jobsub.noisypixel(INFO): [ MESSAGES "HotPixelMasker"] Found 0 noisy pixels on sensor: 0
jobsub.noisypixel(INFO): [ MESSAGES "HotPixelMasker"] Found 0 noisy pixels on sensor: 1
jobsub.noisypixel(INFO): [ MESSAGES "HotPixelMasker"] Found 0 noisy pixels on sensor: 2
jobsub.noisypixel(INFO): [ MESSAGES "HotPixelMasker"] Found 1 noisy pixels on sensor: 3
jobsub.noisypixel(INFO): [ MESSAGES "HotPixelMasker"] Found 0 noisy pixels on sensor: 4
```

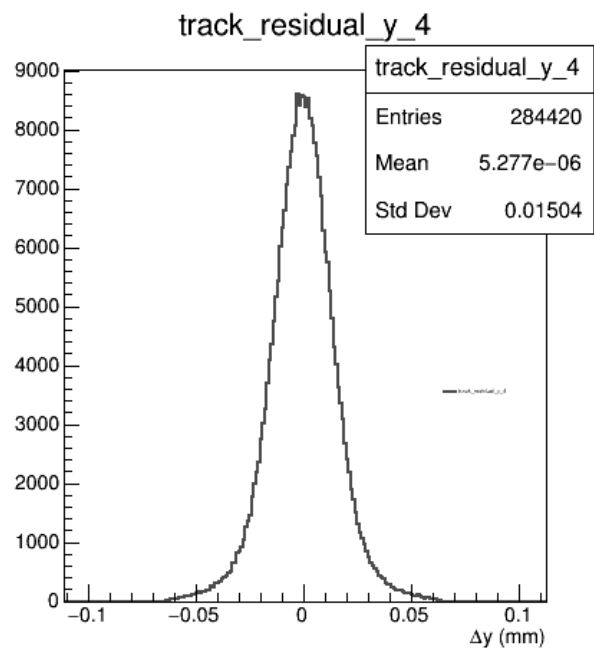
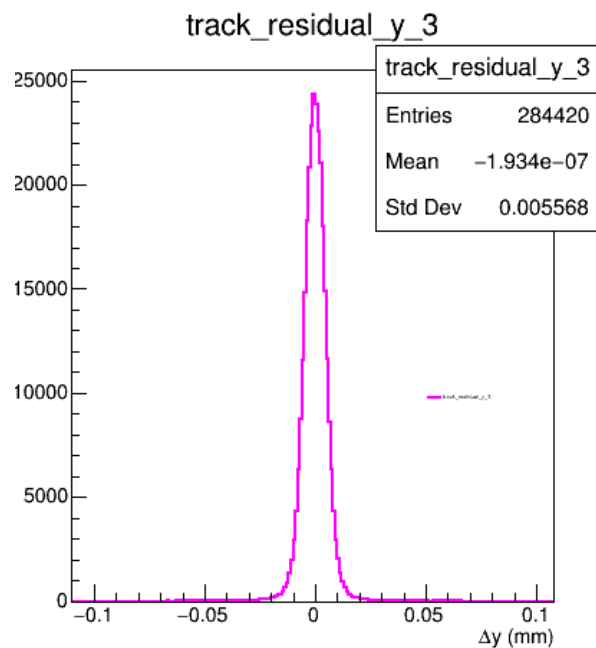
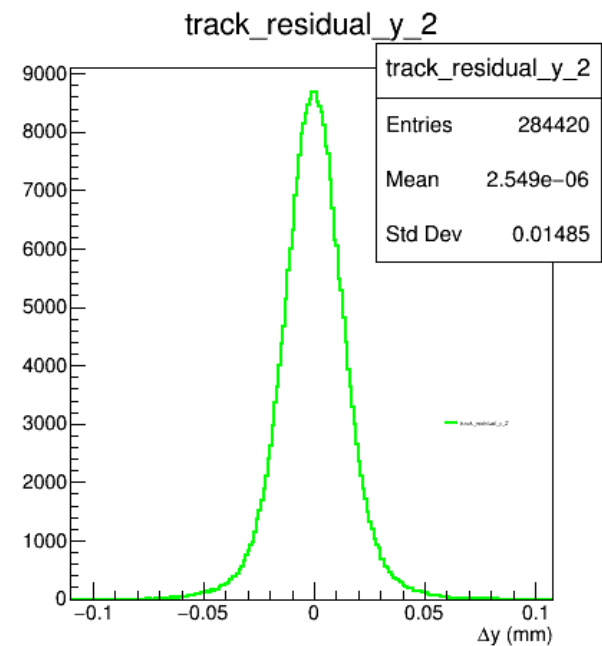
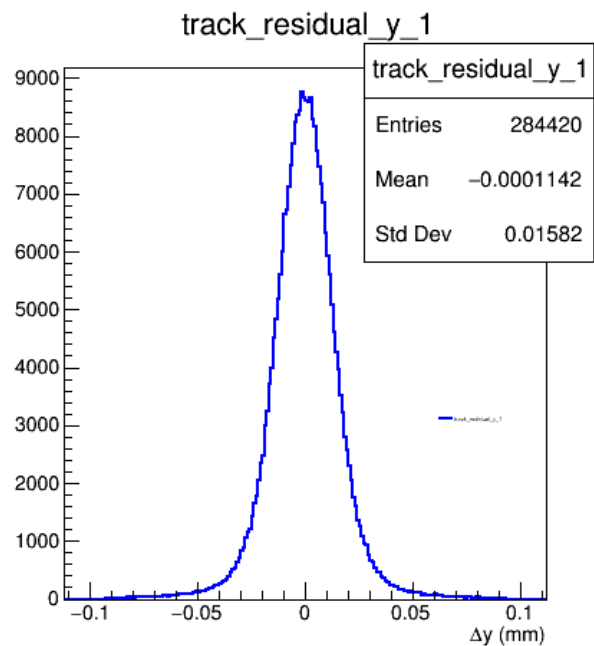
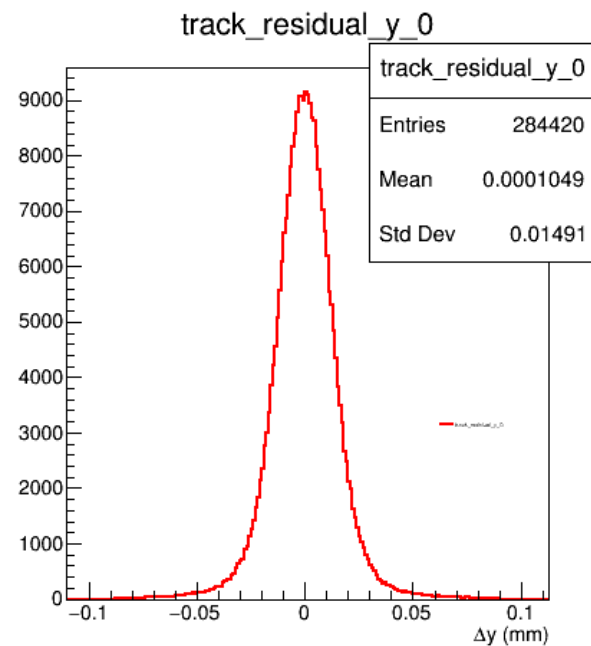
Run 60

```
jobsub.noisypixel(INFO): [ MESSAGES "HotPixelMasker"] Noisy Pixel Finder summary:
jobsub.noisypixel(INFO): [ MESSAGES "HotPixelMasker"] Found 1 noisy pixels on sensor: 0
jobsub.noisypixel(INFO): [ MESSAGES "HotPixelMasker"] Found 0 noisy pixels on sensor: 1
jobsub.noisypixel(INFO): [ MESSAGES "HotPixelMasker"] Found 0 noisy pixels on sensor: 2
jobsub.noisypixel(INFO): [ MESSAGES "HotPixelMasker"] Found 1 noisy pixels on sensor: 3
jobsub.noisypixel(INFO): [ MESSAGES "HotPixelMasker"] Found 0 noisy pixels on sensor: 4
```

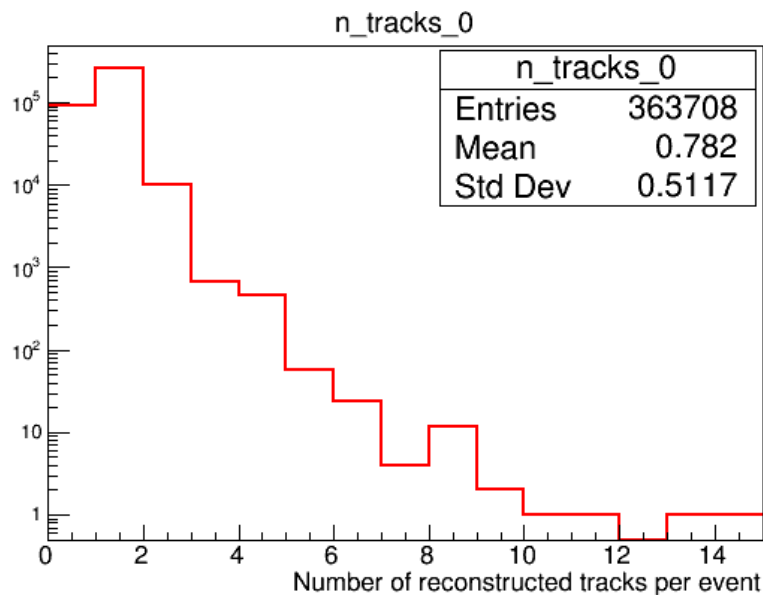
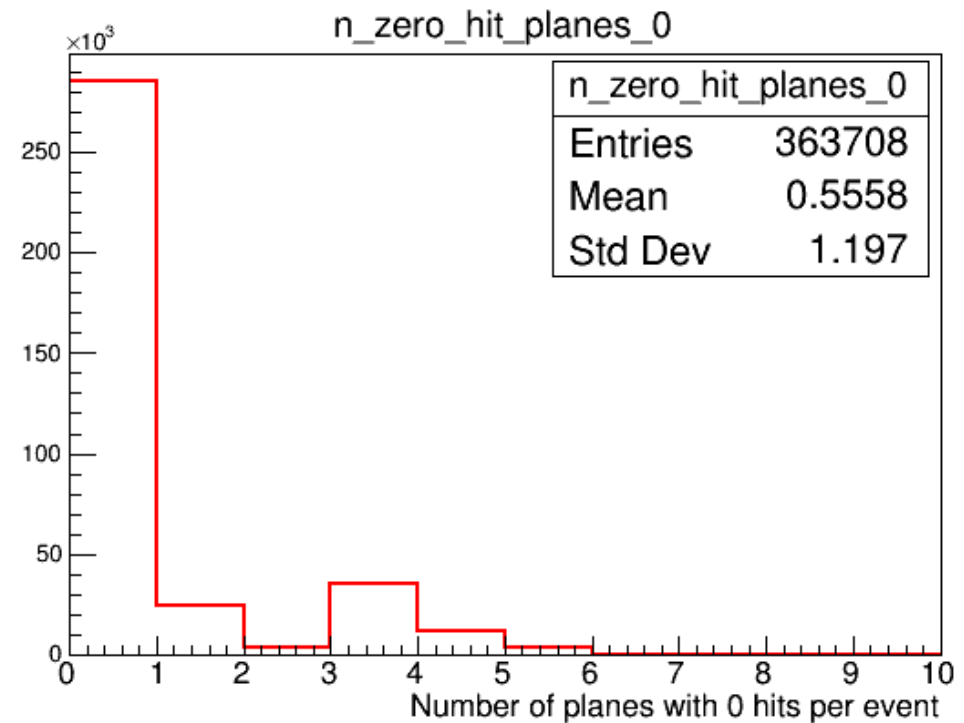
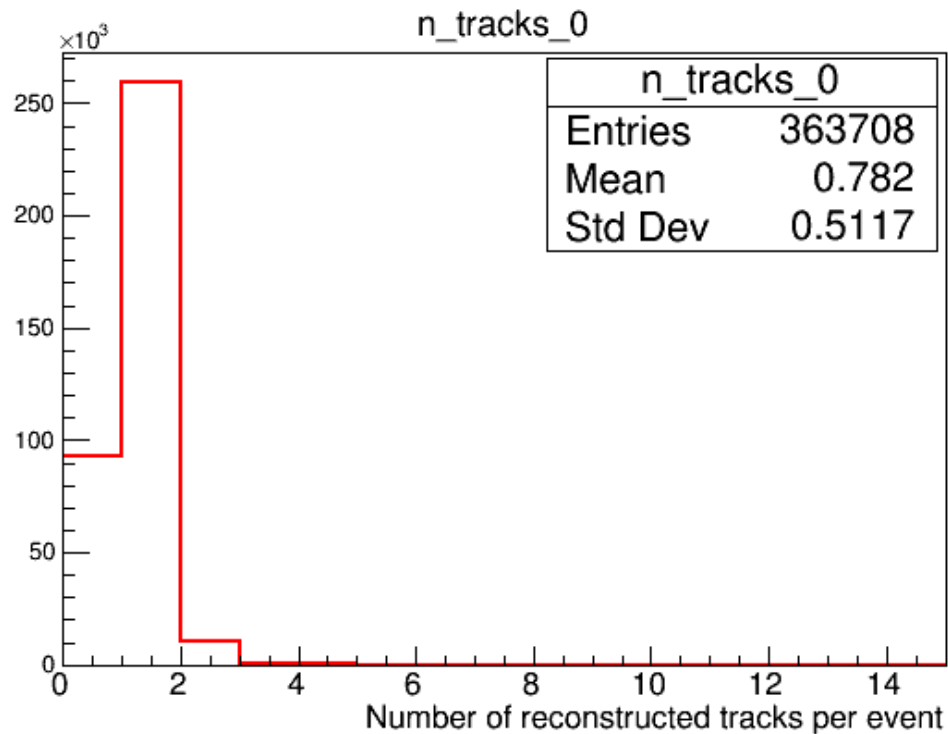
# Run 60, Single track fit for all 5 planes



# Run 60, Single track fit for all 5 planes

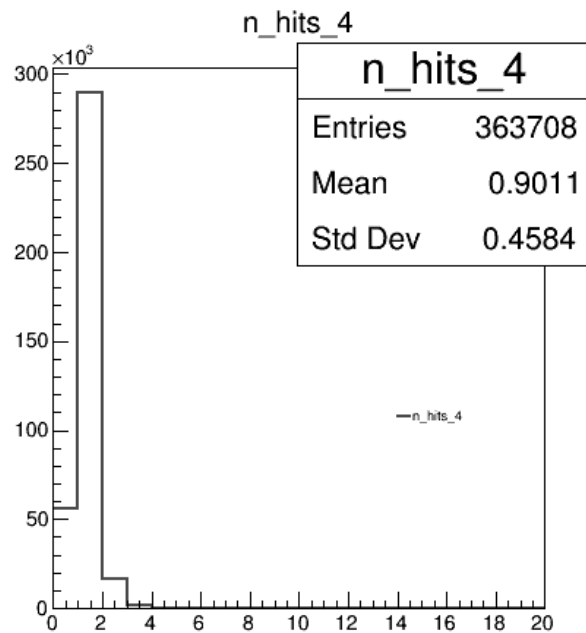
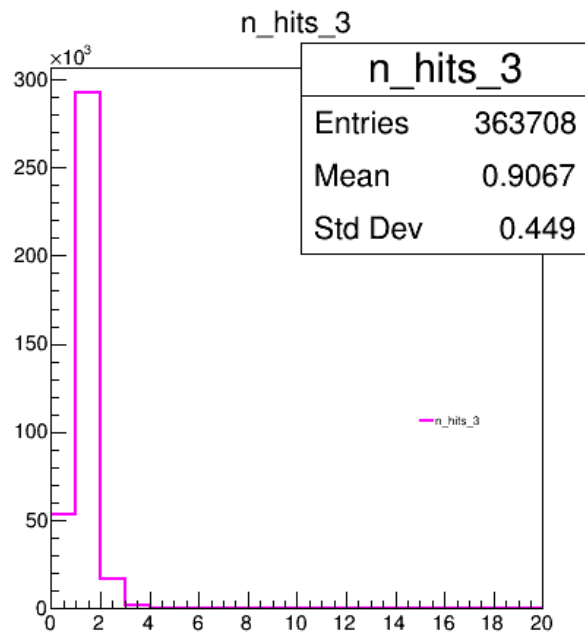
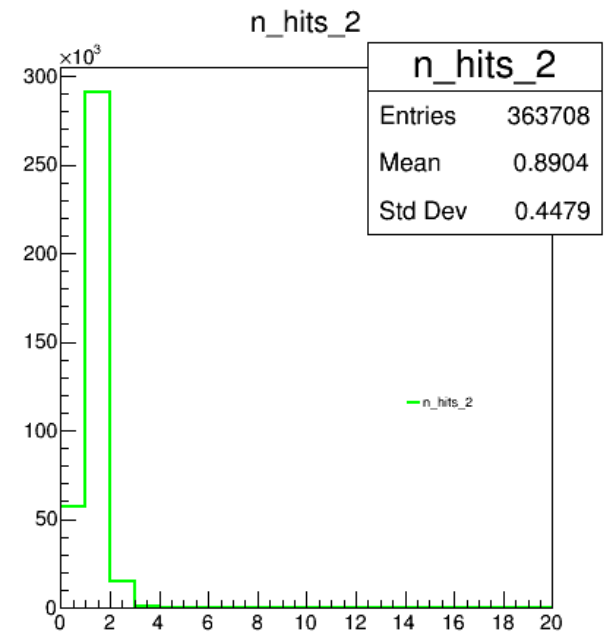
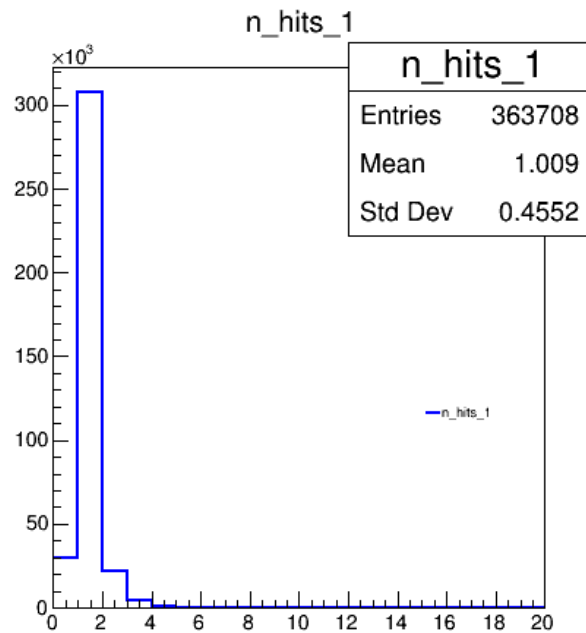
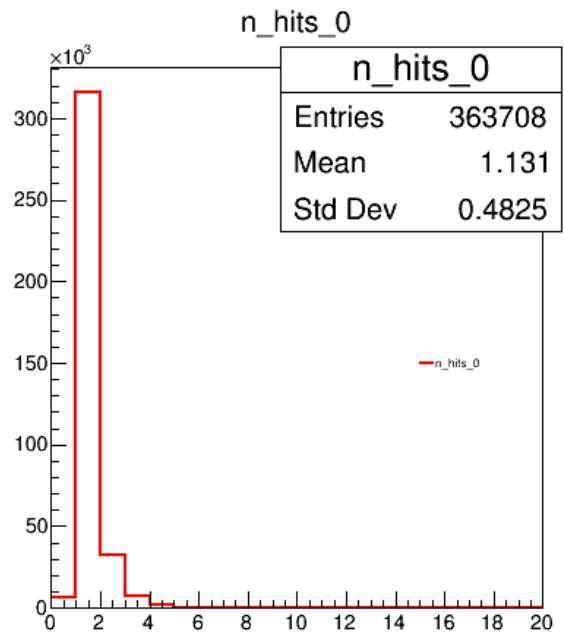


# Number of reconstructed tracks



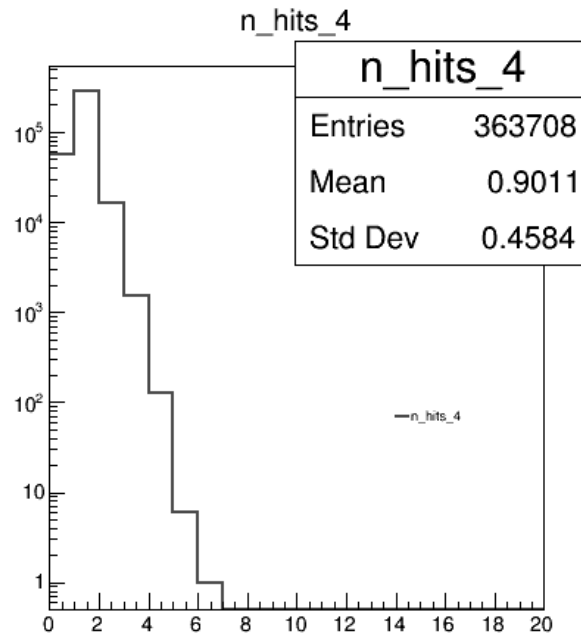
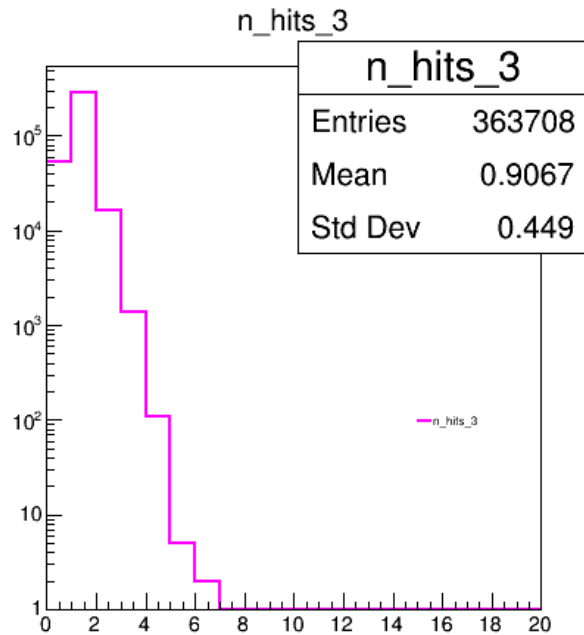
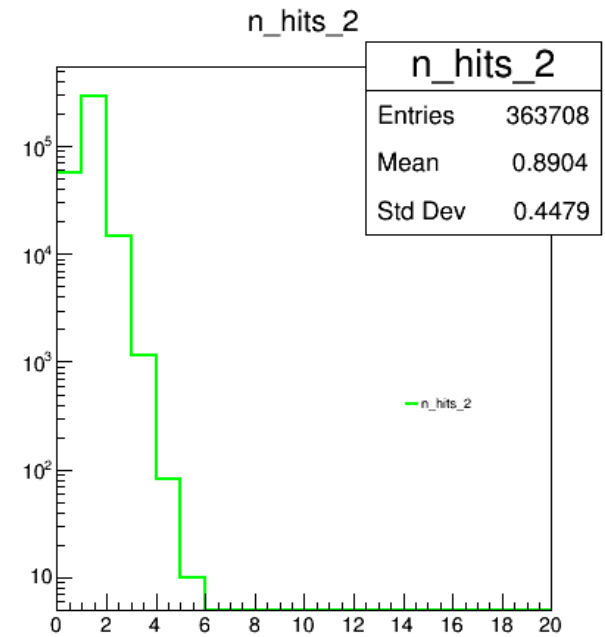
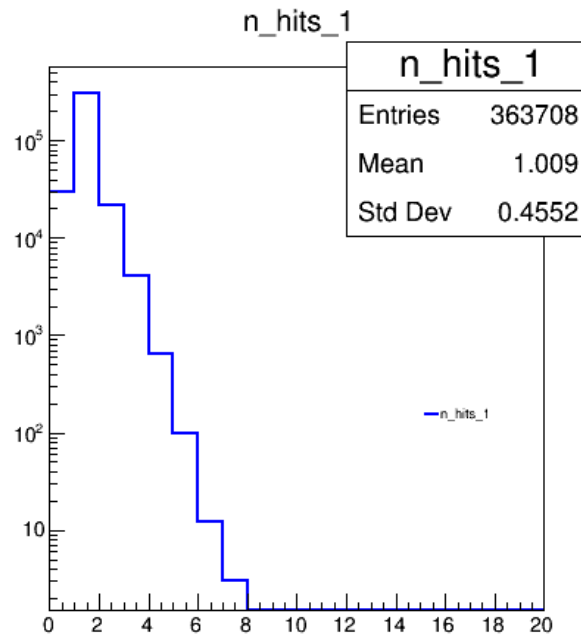
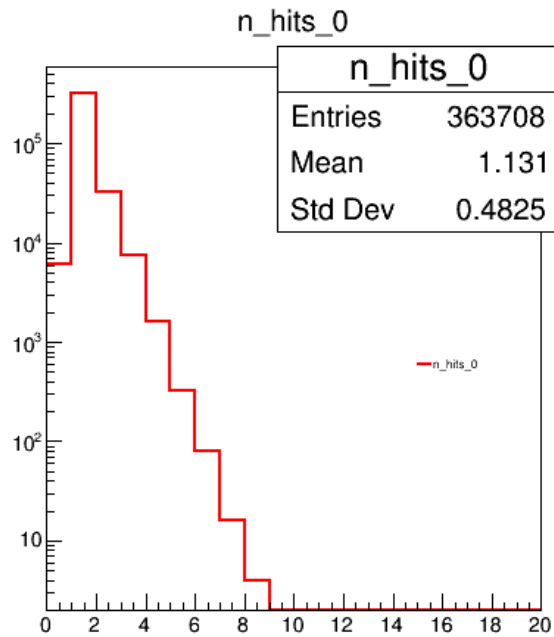
- Number of reconstructed tracks: 284420;
- Number of events with at least one plane with 0 hits: 78640;
- $363708 - 78640 = 285068$ ;
- $285068 - 284420 = 648$  - number of events without reconstructed track but with hits in all planes.

# Number of hits per plane



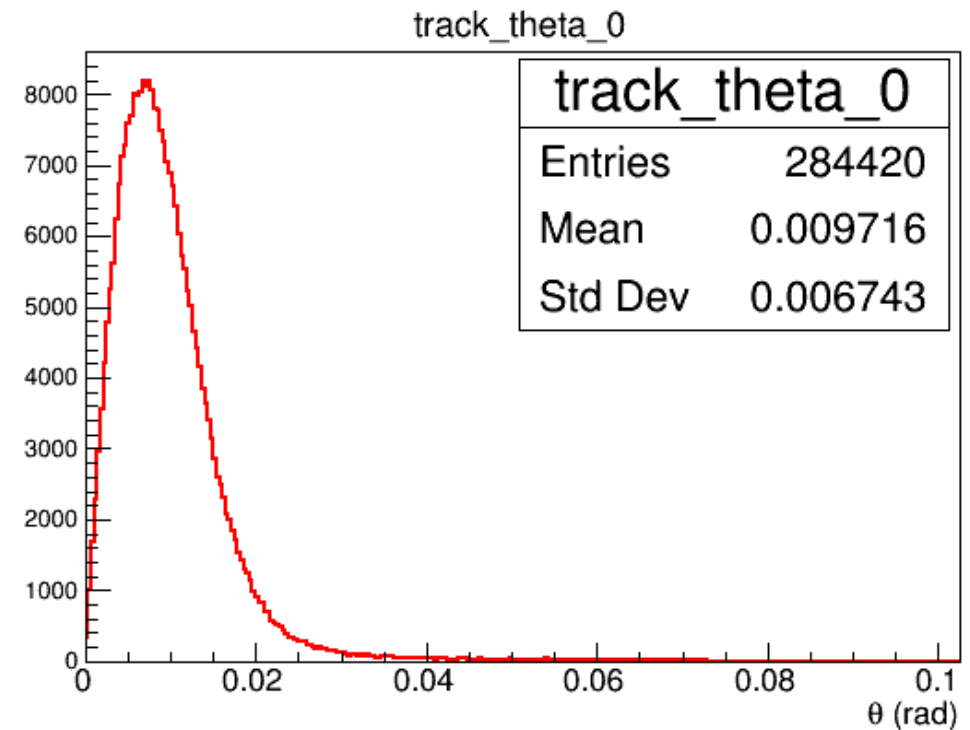
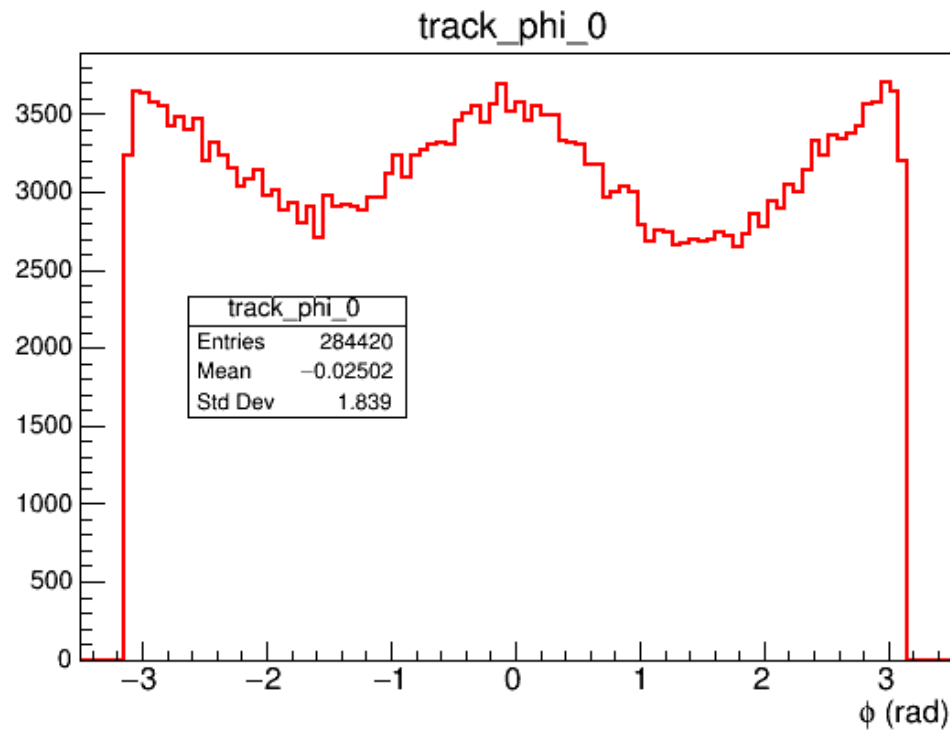


# Number of hits per plane

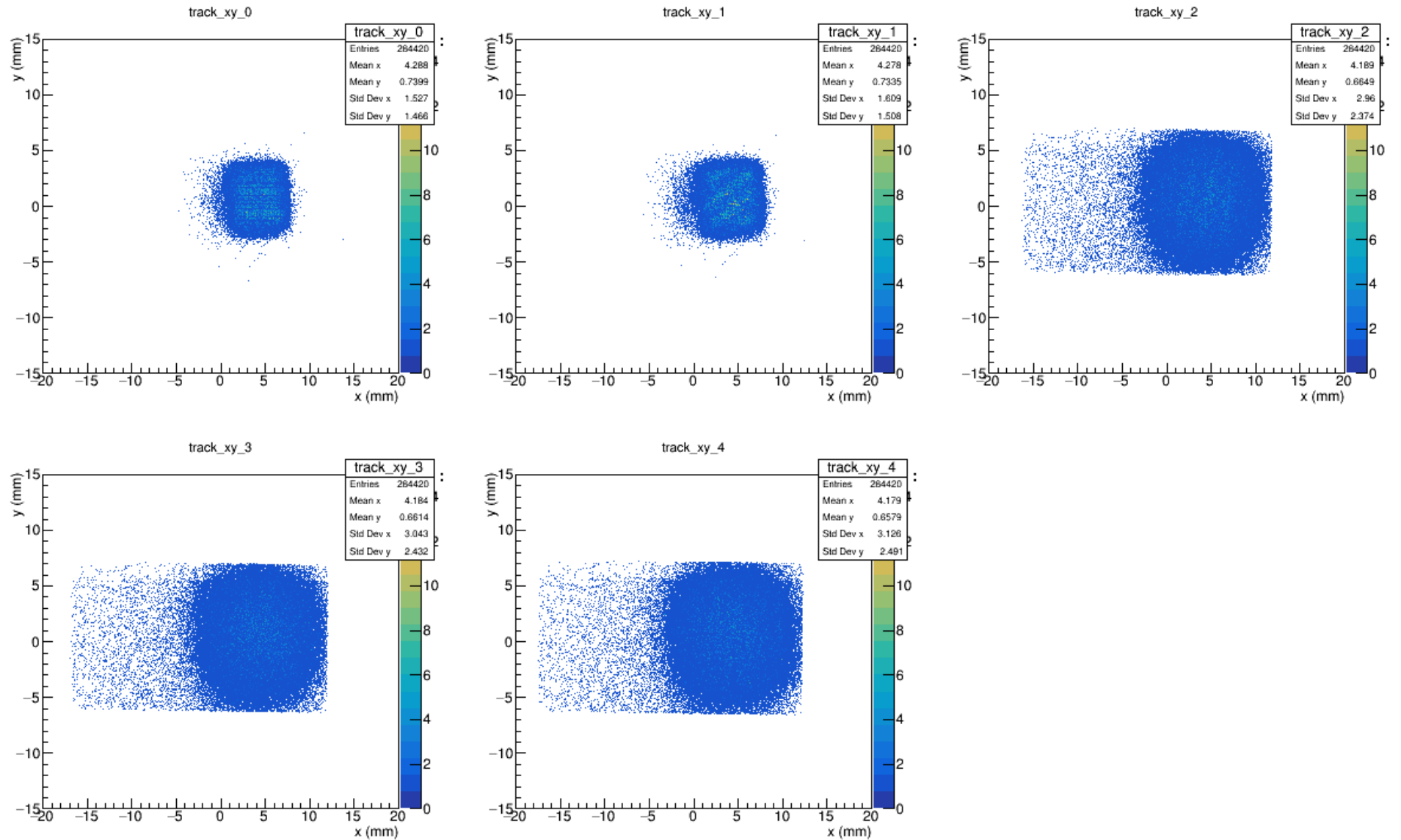


- Seems to be too many events with many (4+) tracks reconstructed;
- Need to check it.

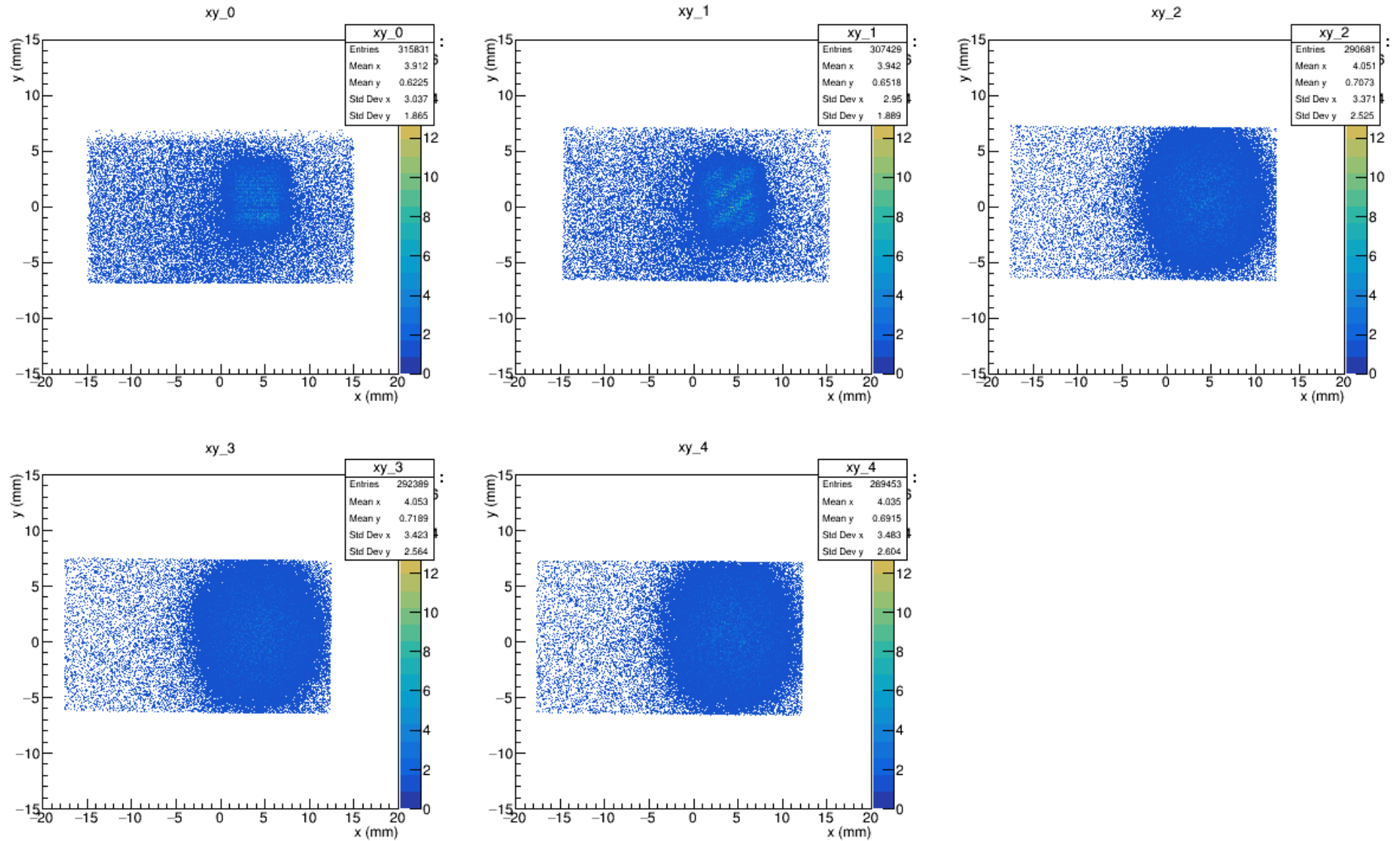
# Angular distributions of the tracks



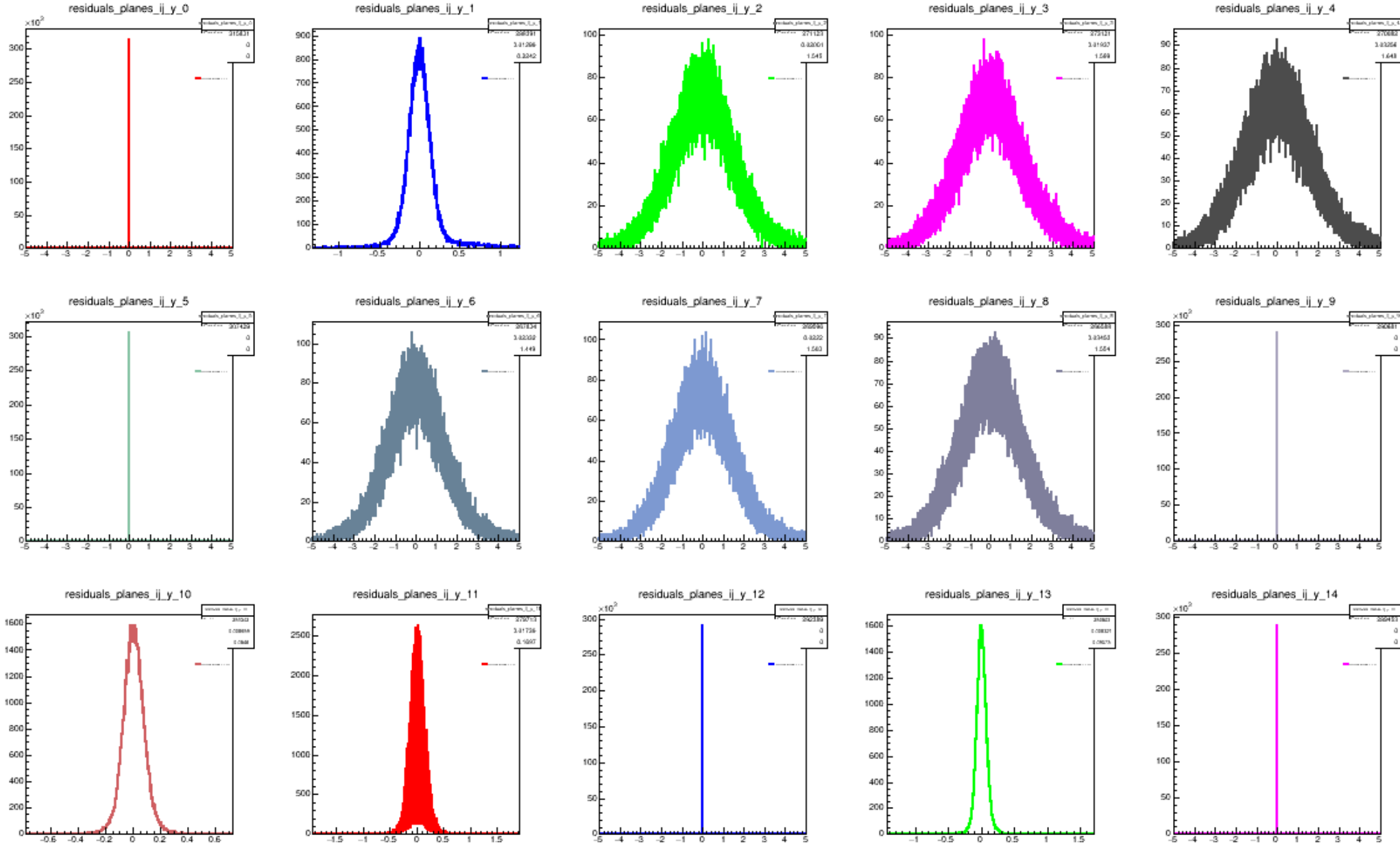
# Hits assigned to tracks



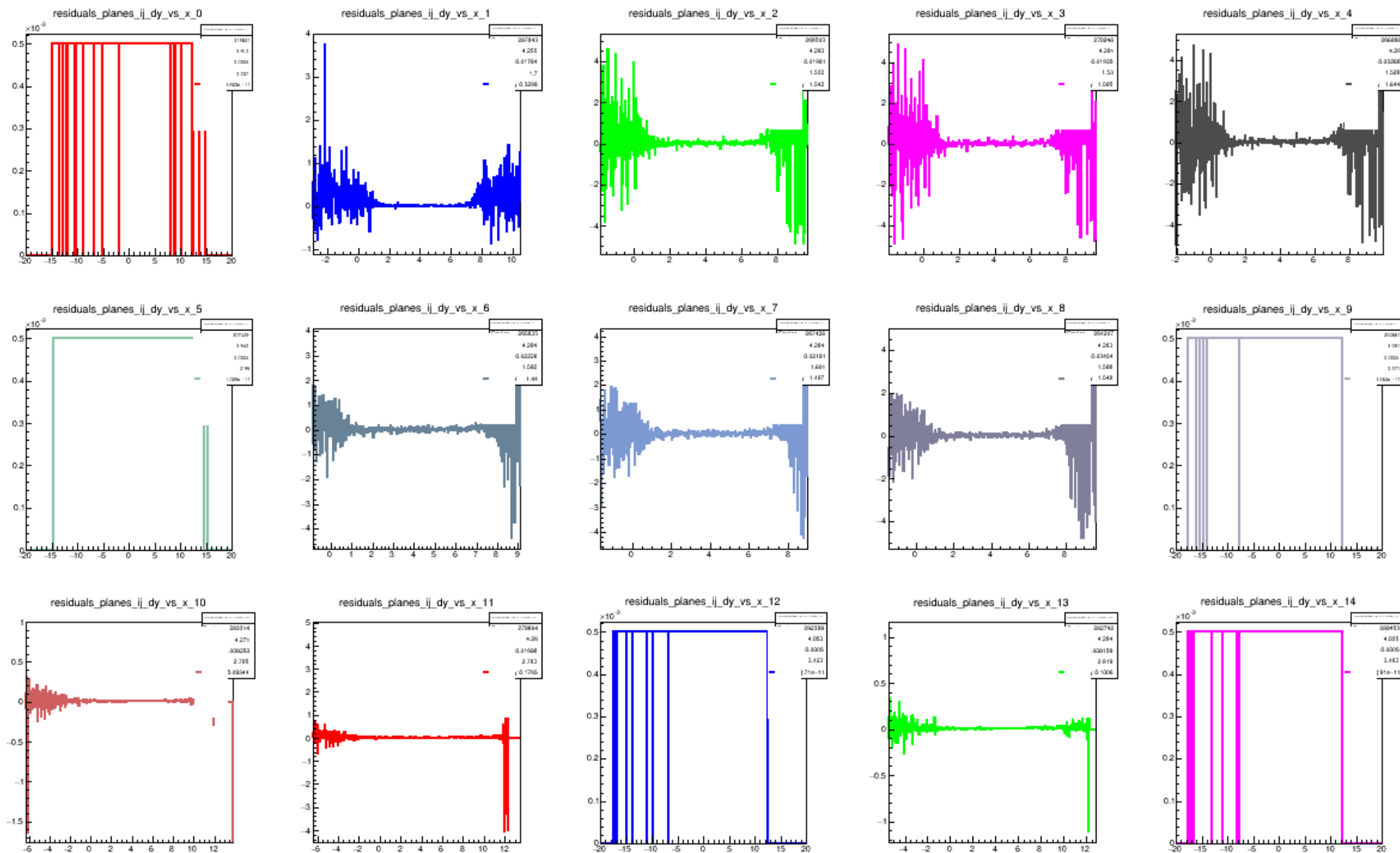
# All hits



# Prealignment. Y correlations between planes

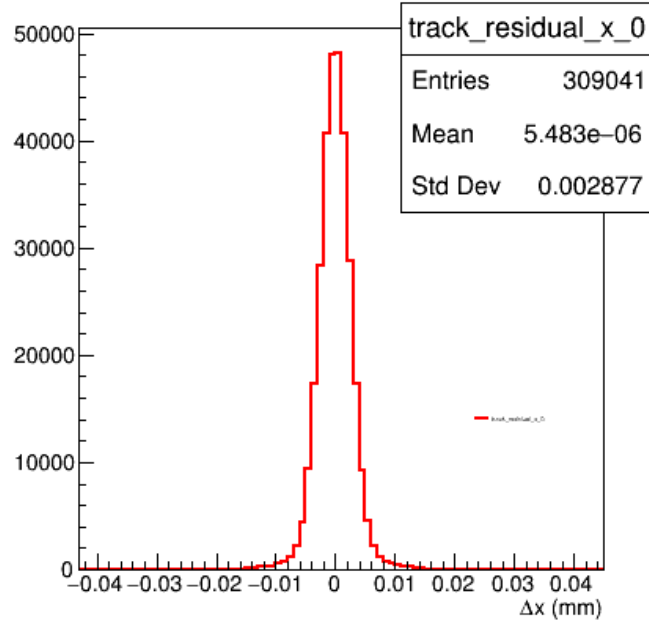


Prealignment of rotation around Z.  
Profiling plot of dy vs x distribution.

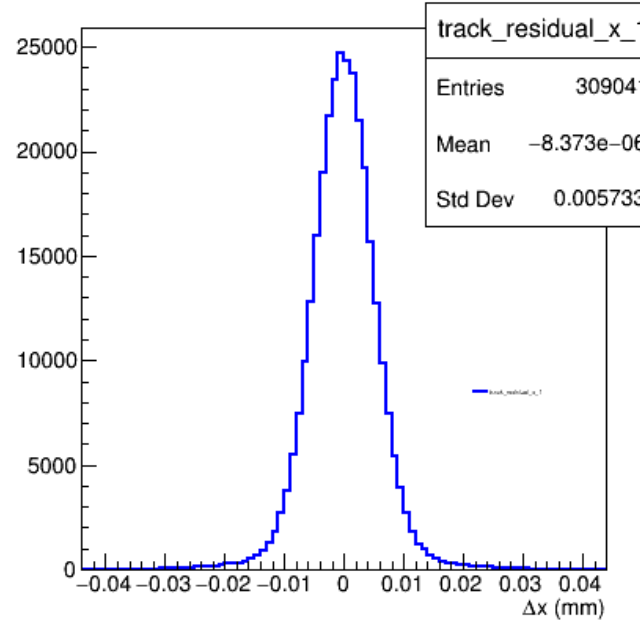


# Track reconstruction in three planes after the magnet

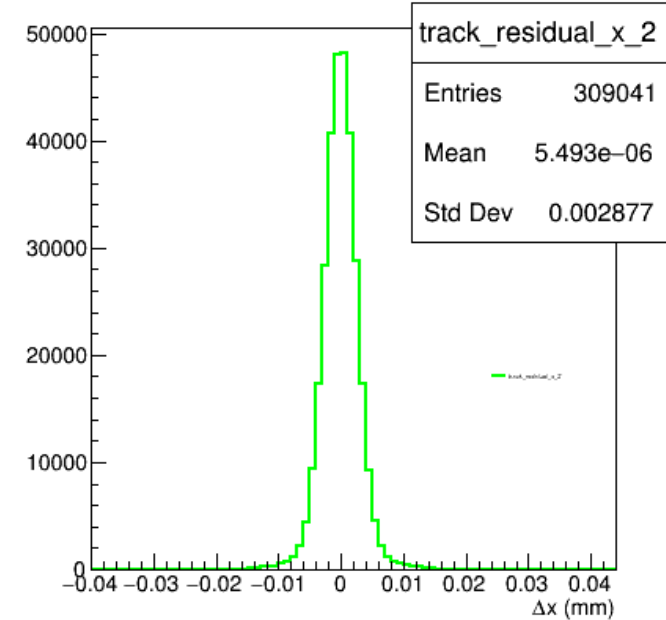
track\_residual\_x\_0



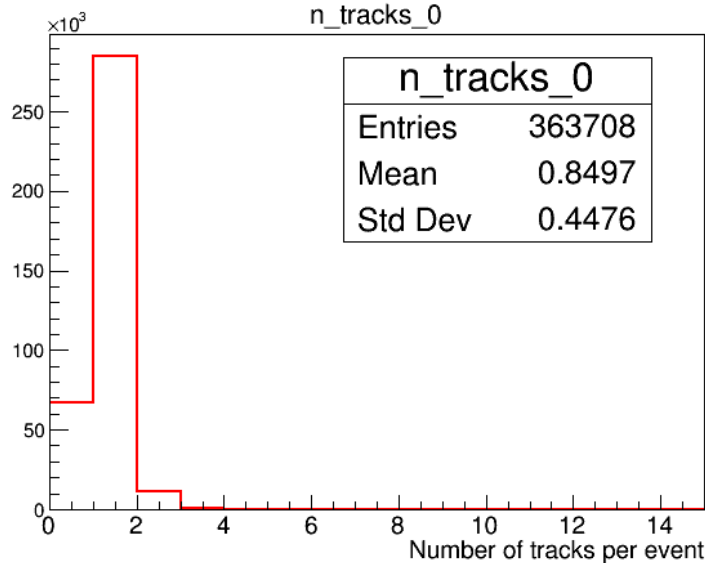
track\_residual\_x\_1



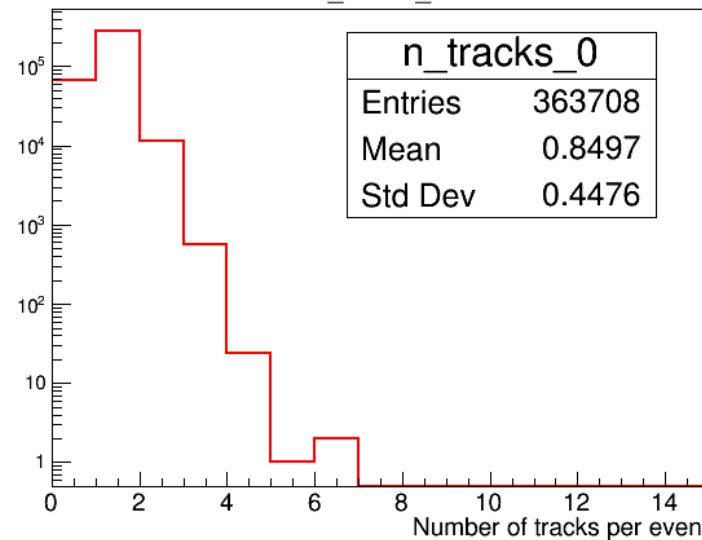
track\_residual\_x\_2



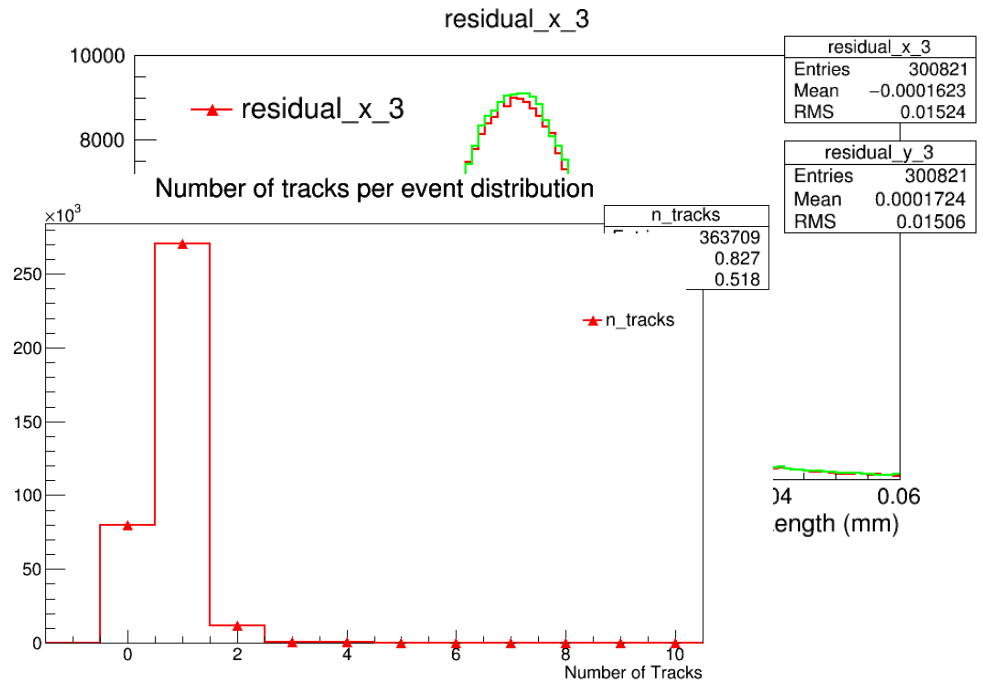
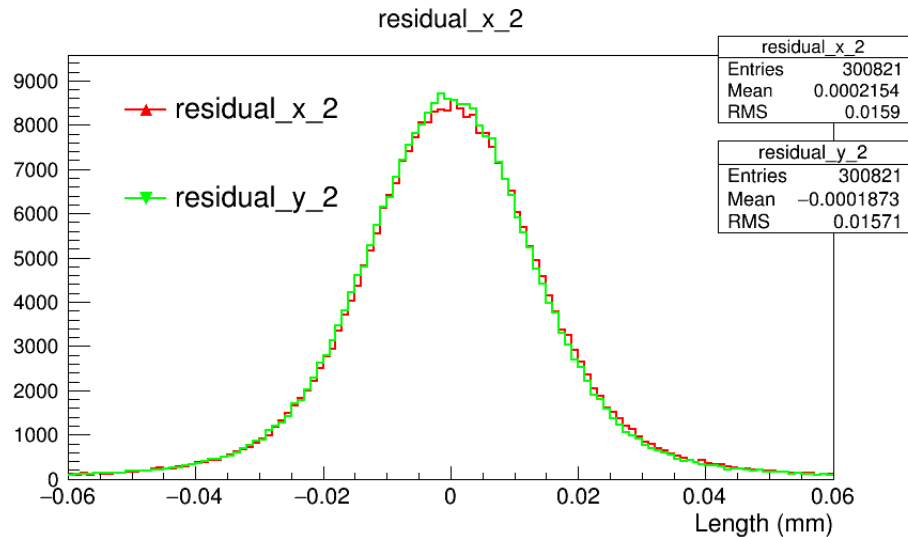
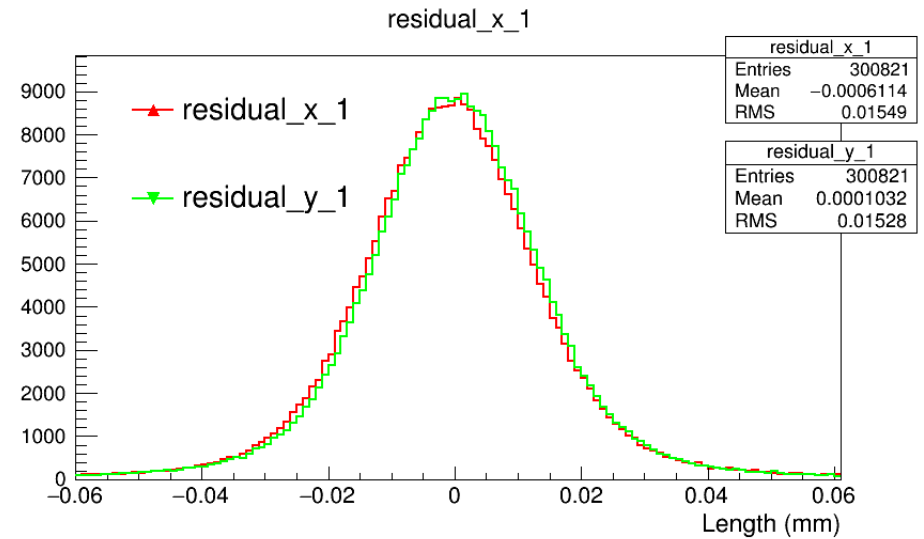
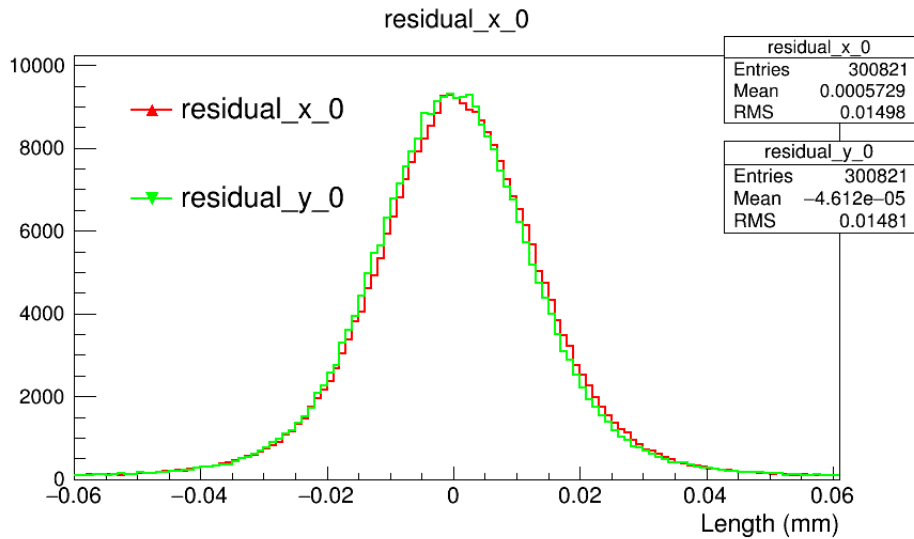
n\_tracks\_0



n\_tracks\_0



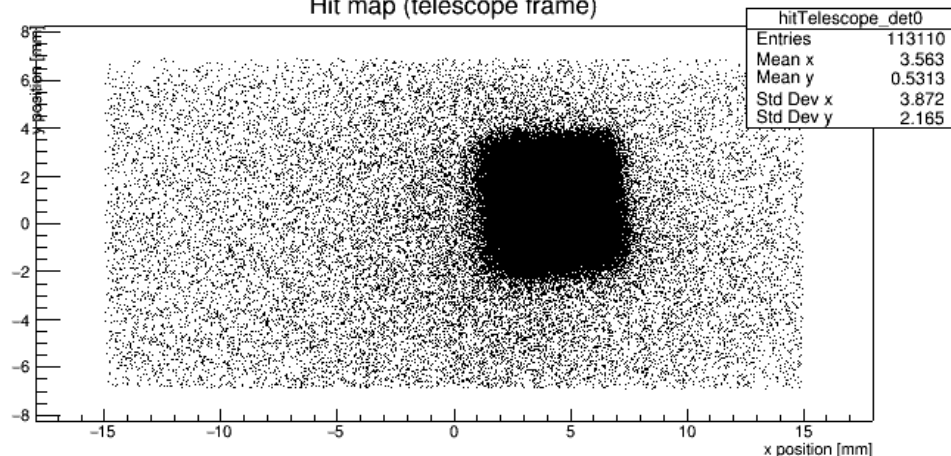
# Test with 4 planes: 1,2 and 3,5



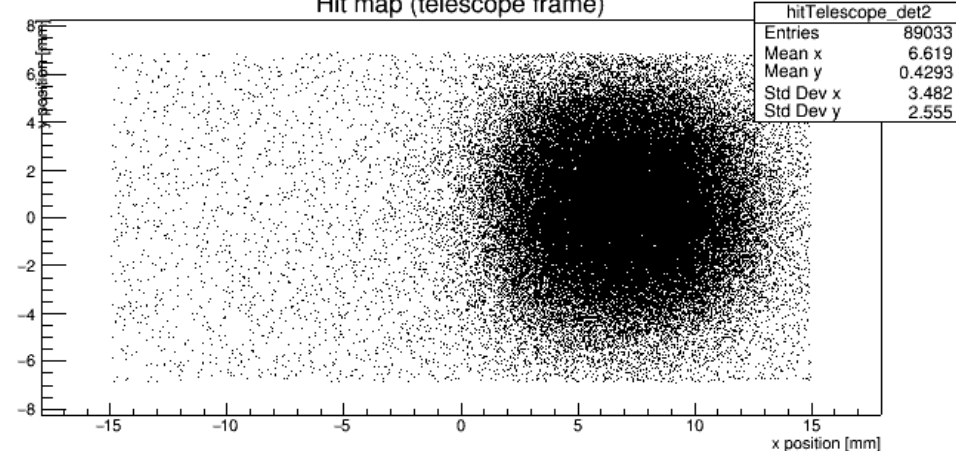


# Hits, run 60, magnet off

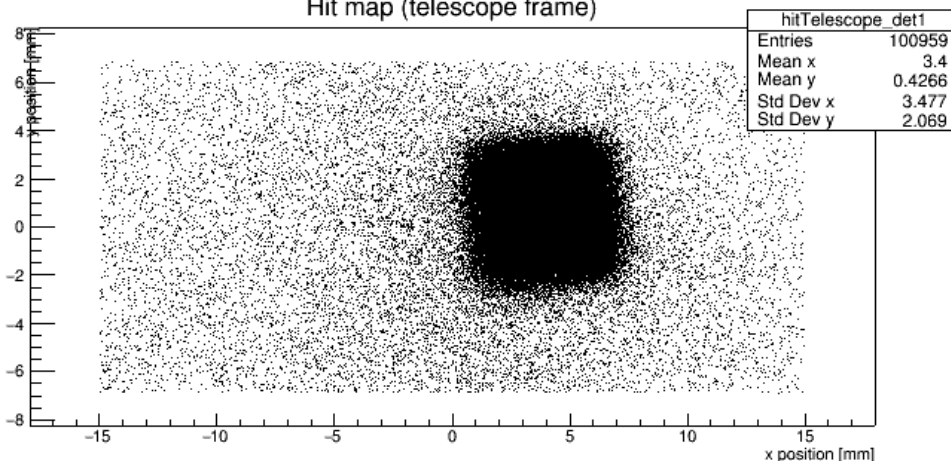
Hit map (telescope frame)



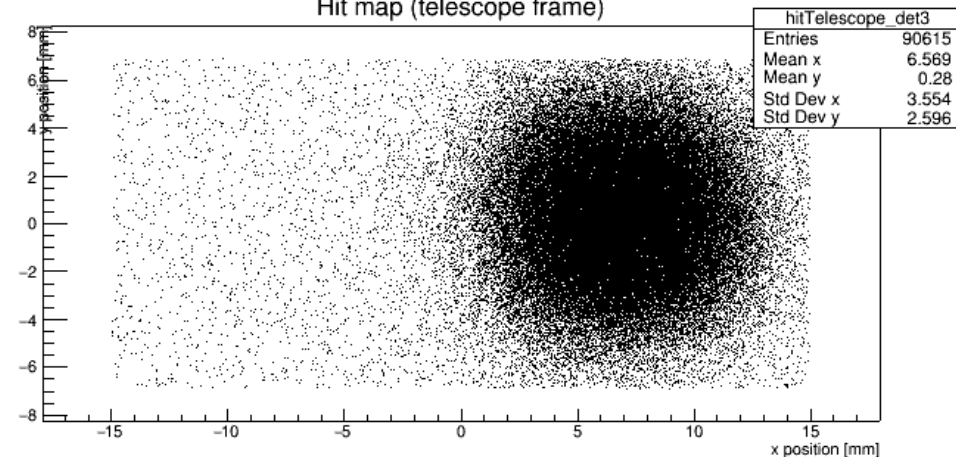
Hit map (telescope frame)



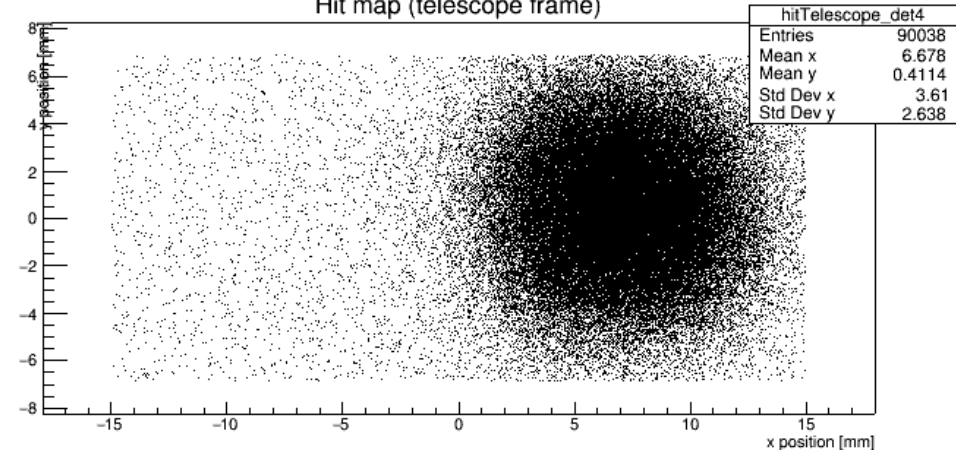
Hit map (telescope frame)



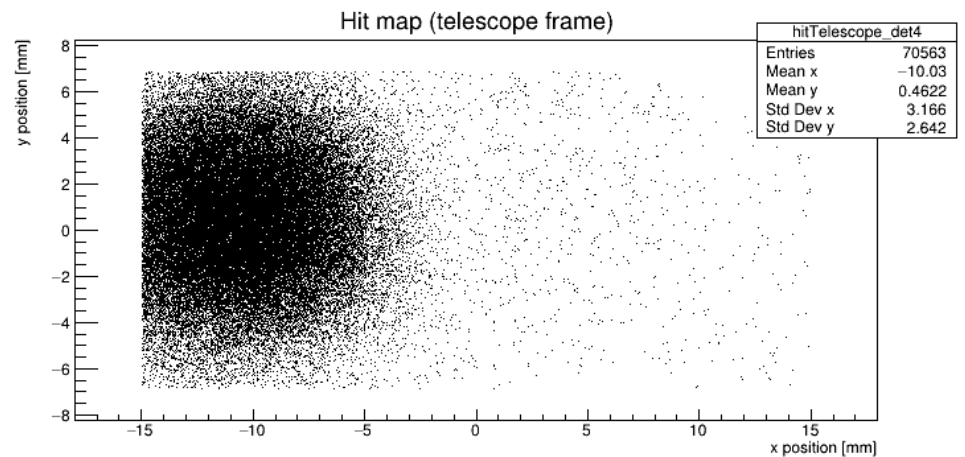
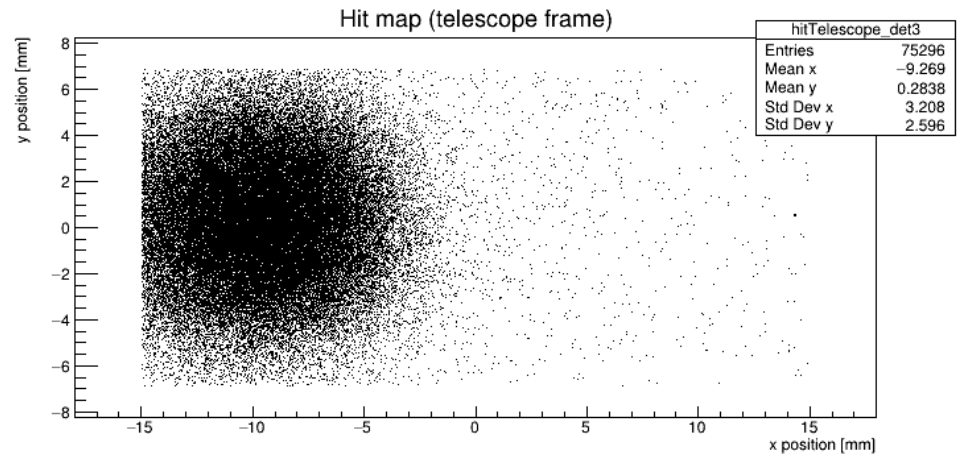
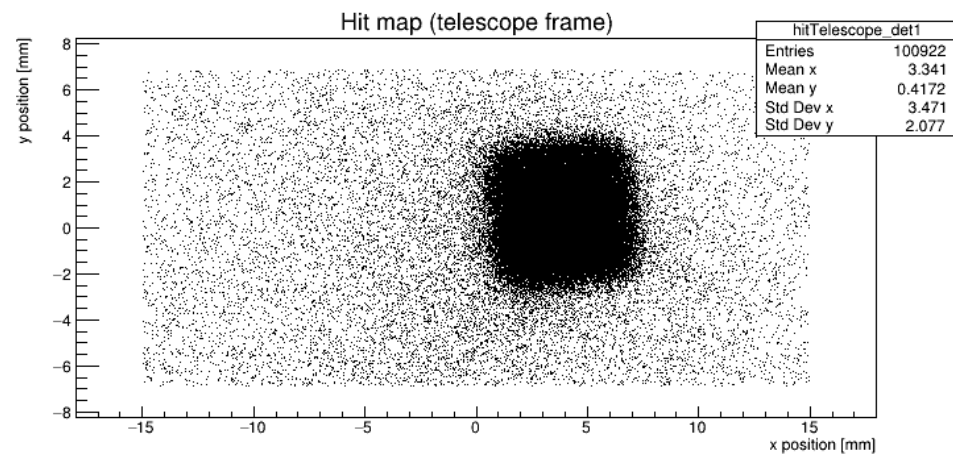
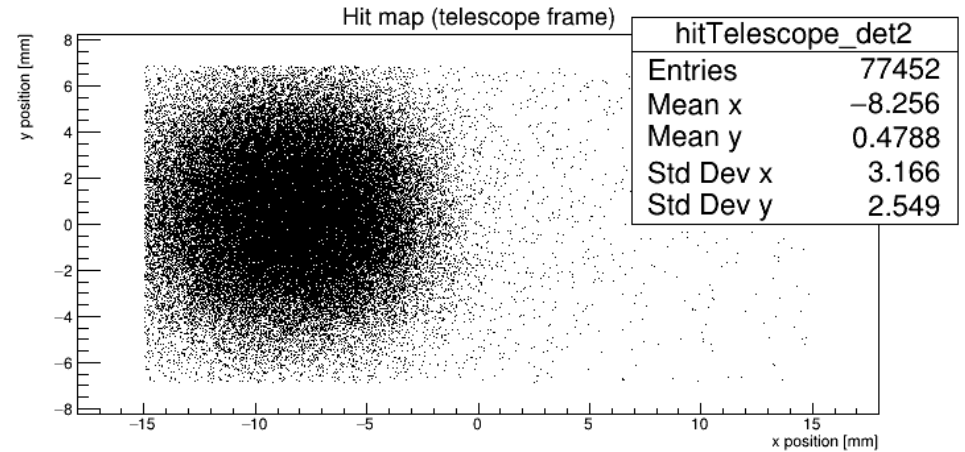
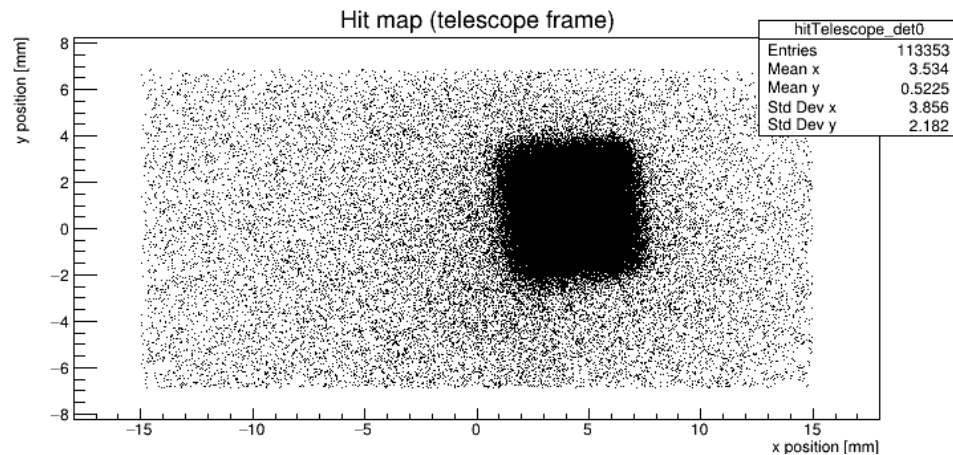
Hit map (telescope frame)



Hit map (telescope frame)



# Hits, run 49, magnet current 200A



Displacement in first plane after the magnet:  
 $6.619 + 8.256 = 14.875$  mm

# Summary

- Converter for ALPIDE raw data to LCIO works reasonably well.
- Noisy pixel analysis, clustering and hits reconstruction produces reasonable results.
- Alignment procedure converges reasonably well after good prealignment.
- Track reconstruction test for one run (run 60). Look reasonable, but some tuning of reconstruction algorithm parameters will be useful.
- Continue with other runs and analysis of scattering angle.

# Back up

# Least square fit of line to 3 points

$$\hat{\mathbf{x}} = (\mathbf{A}^T \mathbf{A})^{-1} \mathbf{A}^T \mathbf{b}$$

Slope is determined by the two outer points

The distance to outer points is twice smaller than to middle one

```
(%i1) A: matrix( [x0,1], [x0+d,1], [x0+2*d,1]);
(%o1)  $\begin{bmatrix} x_0 & 1 \\ x_0+d & 1 \\ x_0+2d & 1 \end{bmatrix}$ 

(%i2) Y: matrix( [y0], [y1], [y2]);
(%o2)  $\begin{bmatrix} y_0 \\ y_1 \\ y_2 \end{bmatrix}$ 

(%i3) B: ratsimp(invert(transpose(A) . A) . transpose(A) . Y);
(%o3)  $\begin{bmatrix} \frac{y_2 - y_0}{2d} \\ -\frac{(-3x_0 - 5d)y_0 - 2dy_1 + (3x_0 + d)y_2}{6d} \end{bmatrix}$ 

(%i4) ratsimp(A . B - Y);
(%o4)  $\begin{bmatrix} -\frac{y_0 - 2y_1 + y_2}{6} \\ \frac{y_0 - 2y_1 + y_2}{3} \\ -\frac{y_0 - 2y_1 + y_2}{6} \end{bmatrix}$ 
```

Technical drawing of a mechanical part, likely a telescope component, showing dimensions and a handwritten note.

Dimensions:

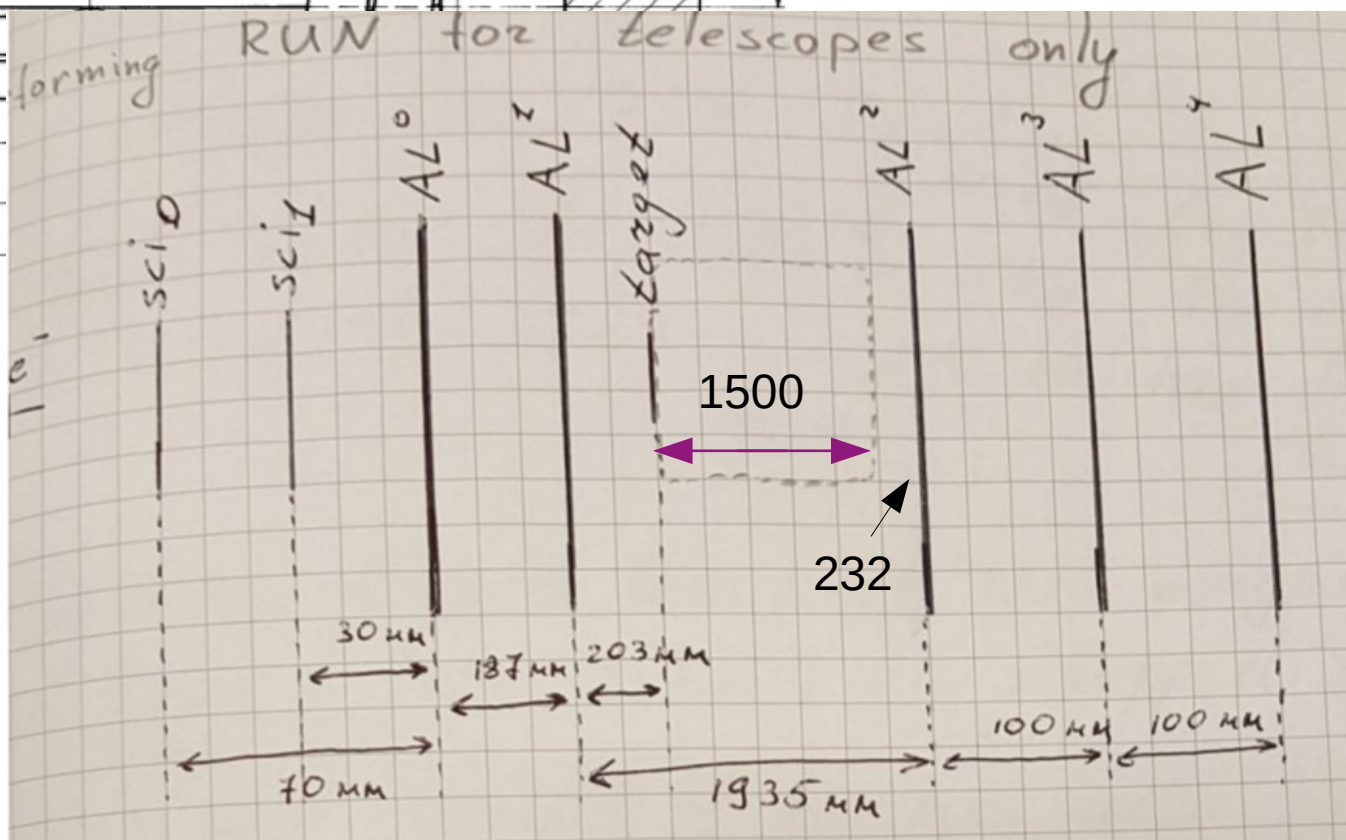
- Overall width: 1755
- Inner width: 1500 (circled in red)
- Length: 1500
- Height: 900
- Angle:  $7^\circ 2'$

Handwritten note:

forming RUN for telescopes

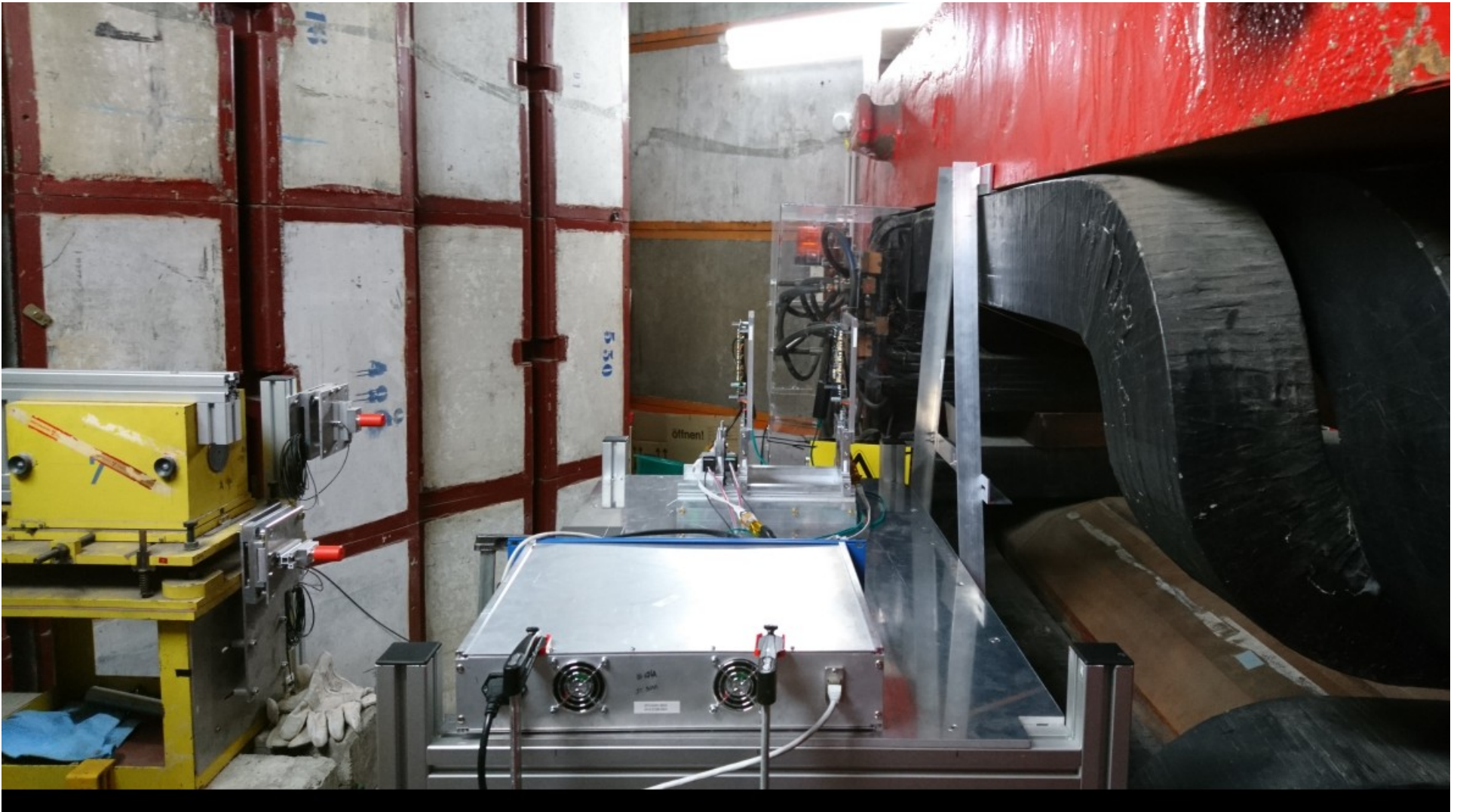
Labels:

- AL<sup>0</sup>
- AL<sup>2</sup>
- Target

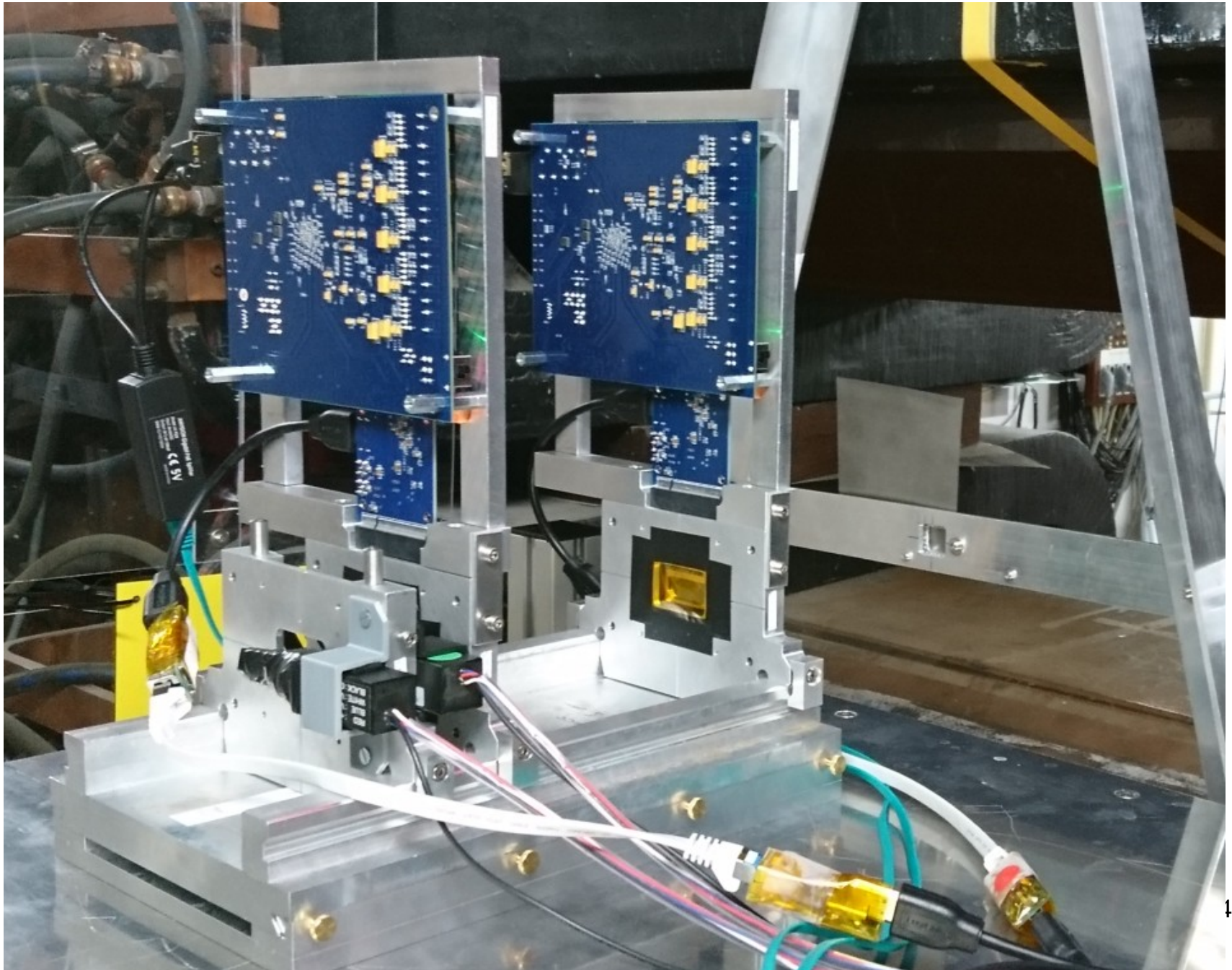




# Upstream of the target



# Upstream of the target





# Downstream of the target



# Downstream of the target

