LCLS-I undulator horizontal gradient modeling for THz@PITZ

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THz SASE FEL

e.g., 200A (4nC) 17 MeV beam \rightarrow 1.2 mJ@100um



• Two LCLS-I undulators have arrived at Hamburg in 08/2019

 The fields of the undulator L143-112000-26 have been remeasured at DESY Hamburg and are consistent with SLAC measurement (discrepancy < 0.02 T)



LCLS-I undulators (on load from SLAC)

Properties	Details
Туре	fixed gap planar hybrid (NeFeB)
Nominal gap	6.8 mm
K-value	3.49
Support diameter / length	30 cm / 3.4 m
Vacuum chamber	11 mm x 5 mm
Period length	30 mm
Poles / a module	226 poles (= 113 periods)
Total weight w/o vac. chamber	1000 kg





LCLS-I undulator field: horizontal gradient modeling

Based on measured profiles

 \mathbf{Y}

Besides longitudinal profile By(z)0.005 transverse gradient By(x) has been measured $a_n = \frac{2}{L} \int_{-\frac{L}{2}}^{\frac{2}{2}} B_y(x=0, y=0, z) \cos\left(\frac{2\pi nz}{N_U \lambda_U}\right) dz$ Measured horizontal gradient FT. -0.005 $b_n = \frac{2}{L} \int_{-\frac{L}{2}}^{\frac{L}{2}} B_y(x = 0, y = 0, z) \sin\left(\frac{2\pi nz}{N_{UAU}}\right) dz$ 3.49K - x🗕 🔶 - linear fit $[a_n^2 + b_n^2]^{1/2}$ -1.5 -0.5 0.5 1.5 3.483.47 3.463.45n/(N_=120) 3.44-10-55 10 0 *x* (mm) $\chi(x, y, z) = -\frac{\cosh[k_x(x_0 + x)]}{\cosh[k_x x_0]} \cdot \sum_{k=1}^{N_h \cdot N_U} \{a_n \cos(k_{zn} z) + b_n \sin(k_{zn} z)\} \cdot \frac{\sinh(k_{yn} y)}{k_{yn}}$ $\frac{B_y(x, y, z)}{B_0} \propto \frac{\cosh[k_x(x_0 + x)]}{\cosh[k_x x_0]}$ 3D Field map $\vec{B} = -\frac{\partial \chi}{\partial \vec{r}}$, including horizontal gradient $k_x \cdot \tanh[k_x x_0] = \frac{d}{dx} \left(\frac{K(x)}{K_0} \right)$ $B_{x}(x, y, z) = \frac{\sinh[k_{x}(x_{0}+x)]}{\cosh[k_{x}x_{0}]} \cdot \sum_{n=1}^{N_{h} \cdot N_{U}} \{a_{n} \cos(k_{zn}z) + b_{n} \sin(k_{zn}z)\} \cdot \frac{k_{x}}{k_{yn}} \cdot \sinh(k_{yn}y)$ $x_0 \approx 1.33m$ $k_r \approx 0.916 \, m^{-1}$ $B_{y}(x, y, z) = \frac{\cosh[k_{x}(x_{0}+x)]}{\cosh[k_{x}x_{0}]} \cdot \sum_{n=1}^{N_{h} \cdot N_{U}} \{a_{n}\cos(k_{zn}z) + b_{n}\sin(k_{zn}z)\} \cdot \cosh(k_{yn}y)$ $k_x^2 + k_{yn}^2 = k_{zn}^2 = \left(\frac{2\pi n}{N_{11}\lambda_{11}}\right)^2$ $B_z(x, y, z) = \frac{\cosh[k_x(x_0+x)]}{\cosh[k_x x_0]} \cdot \sum_{n=1}^{N_h \cdot N_U} \{-a_n \sin(k_{zn}z) + b_n \cos(k_{zn}z)\} \cdot \frac{k_{zn}}{k_{yn}} \cdot \sinh(k_{yn}y)$

DESY. M. Krasilnikov et al., | LCLS-I undulator horizontal gradient modeling for THz@PITZ, ARD ST3 workshop, 24.09.2020

On-axis By and Bx measured along the 3.4 m undulator

Design and modeling of correction coils

Horizontal undulator gradient impact onto beam transport and THz SASE FEL

 Transverse gradient will lead to an off-axis (~25 mm) trajectory in the horizontal plane; steering coils are considered to correct it





