Quantum Heuristic Algorithms for Hard Planning Problems from Aerospace Research

Knowledge for Tomorrow

Thorge Müller, Elisabeth Lobe, Tobias Stollenwerk

German Aerospace Center (DLR), Cologne

September 16, 2019 Helmholtz-Triumf-Workshop Hamburg



Content

- Quantum Computing at the German Aerospace Center
- Quantum Heuristic Algorithms for Flight Gate Assignment



• Our Mission:

How improve aerospace research with QC?

• Our Approach:





• Our Mission:

How improve aerospace research with QC?

• Our Approach:

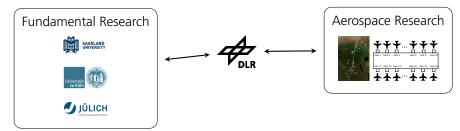




• Our Mission:

How improve aerospace research with QC?

• Our Approach:

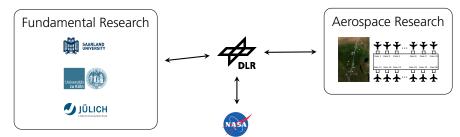




• Our Mission:

How improve aerospace research with QC?

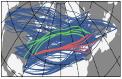
• Our Approach:



Quantum Artificial Intelligence Lab

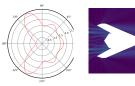


Quantum Computing at DLR - Topics

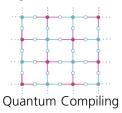


Applications for Q-Annealing (DLR/NASA)

<pre># test polynomial class class testPolynomial(unittest.TestCase): def setUo(self):</pre>
<pre># qubol: 5 x1 + 6 x2 + 3 x1 x3 + x4 + 3 x2 x4 + self.01 = polynomial.Polynomial(f(1,): 5, (2,):</pre>
qubo2 : 7 x5 + x2 x4 + 3 x3 x4 + x2
<pre>self.02 = polynomial.Polynomial({(2,): 1, (2, 4) # gubo3 : 7 x] + 2 x2 + 3 x3 + x4</pre>
<pre>self.Q3 = polynomial.Polynomial({(1,): 7, (2,):</pre>
<pre>self.04 = polynomial.Polynomial({(('x', 1),): 7,</pre>
<pre>self.filename_h5 = testdir + "/test_qubo.h5" self.filename_txt = testdir + "/test_qubo.txt"</pre>
<pre>def testEqual(self): 0 = polynomial.Polynomial({(1,): 7, (2,): 2, (3, self.assertFalse(0 self.01)</pre>
Software for QC



Applications for gate-based QC





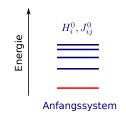
• How we reach the target state?



- How we reach the target state?
- solution: adiabatic development

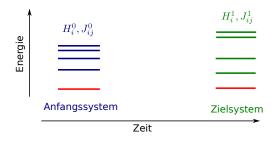


- How we reach the target state?
- solution: adiabatic development
 - 1. prepare the system in an known inital ground state



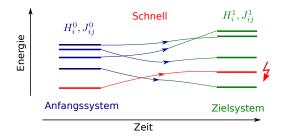


- How we reach the target state?
- solution: adiabatic development
 - 1. prepare the system in an known inital ground state



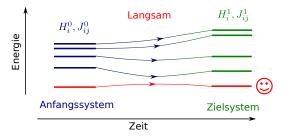


- How we reach the target state?
- solution: adiabatic development
 - 1. prepare the system in an known inital ground state



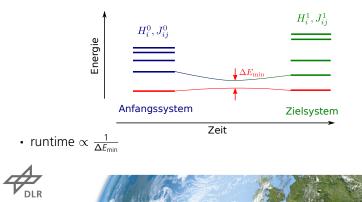


- How we reach the target state?
- solution: adiabatic development
 - 1. prepare the system in an known inital ground state
 - 2. change *slowly* towards the target sytsem





- How we reach the target state?
- solution: adiabatic development
 - 1. prepare the system in an known inital ground state
 - 2. change *slowly* towards the target sytsem



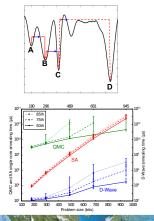
runtime of Quanum Annealers

there are hints of the supremacy of quantum annealers against classcial approaches

- problems with high and narrow barriers
- quantum tunneling through barriers

open questions:

- Is there a supremacy for real use cases?
- are there problems with a better scaling?





Flight Gate Assignment - Problem Size

A day at Frankfurt Airport

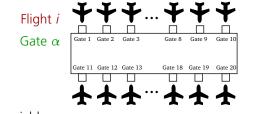
- about 1300 aircraft movements (arrival and departure)
- more than 90% are passenger flights
- more than 170000 passengers
- about 60% transfer passengers
- 278 gates







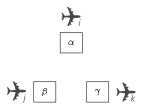
Flight Gate Assignment - Decision Variable



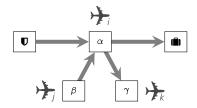
Decision variable

$$x_{i\alpha} = \begin{cases} 1, & \text{if flight } i \text{ is assigned to gate } \alpha \\ 0, & \text{otherwise} \end{cases}$$

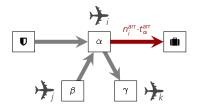






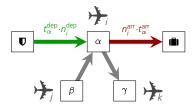






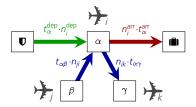
$$C = \sum_{i\alpha} n_i^{\rm arr} t_\alpha^{\rm arr} x_{i\alpha}$$





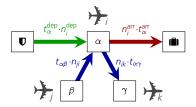
$$C = \sum_{i\alpha} n_i^{\text{arr}} t_{\alpha}^{\text{arr}} x_{i\alpha} + \sum_{i\alpha} n_i^{\text{dep}} t_{\alpha}^{\text{dep}} x_{i\alpha}$$





$$C = \sum_{i\alpha} n_i^{\text{arr}} t_{\alpha}^{\text{arr}} x_{i\alpha} + \sum_{i\alpha} n_i^{\text{dep}} t_{\alpha}^{\text{dep}} x_{i\alpha} + \sum_{ij\alpha\beta} n_{ij} t_{\alpha\beta} x_{i\alpha} x_{j\beta}$$





Minimizing the total transfer time with the cost function

$$C = \sum_{i\alpha} n_i^{\text{arr}} t_{\alpha}^{\text{arr}} x_{i\alpha} + \sum_{i\alpha} n_i^{\text{dep}} t_{\alpha}^{\text{dep}} x_{i\alpha} + \sum_{ij\alpha\beta} n_{ij} t_{\alpha\beta} x_{i\alpha} x_{j\beta}$$

 \rightarrow Quadratic Assignment problem



• One gate per flight: $\forall i : \sum_{\alpha} x_{i\alpha} = 1$:



• One gate per flight: $\forall i : \sum_{\alpha} x_{i\alpha} = 1$:

$$Q_{C} = \lambda_{C} \sum_{i} \left(\sum_{\alpha} x_{i\alpha} - 1 \right)^{2}$$



• One gate per flight: $\forall i : \sum_{\alpha} x_{i\alpha} = 1$:

$$Q_{C} = \lambda_{C} \sum_{i} \left(\sum_{\alpha} x_{i\alpha} - 1 \right)^{2}$$

• No arrival before departure at the same gate

$$x_{i\alpha} \cdot x_{j\alpha} = 0 \quad \forall (i,j) \in F, \ \forall \alpha$$



• One gate per flight: $\forall i : \sum_{\alpha} x_{i\alpha} = 1$:

$$Q_{C} = \lambda_{C} \sum_{i} \left(\sum_{\alpha} x_{i\alpha} - 1 \right)^{2}$$

• No arrival before departure at the same gate

$$x_{i\alpha} \cdot x_{j\alpha} = 0 \quad \forall (i,j) \in F, \ \forall \alpha$$

with F : set of forbidden flight pairs



• One gate per flight: $\forall i : \sum_{\alpha} x_{i\alpha} = 1$:

$$Q_{C} = \lambda_{C} \sum_{i} \left(\sum_{\alpha} x_{i\alpha} - 1 \right)^{2}$$

• No arrival before departure at the same gate

$$x_{i\alpha} \cdot x_{j\alpha} = 0 \quad \forall (i,j) \in F, \forall \alpha$$

with F : set of forbidden flight pairs

$$Q_T = \lambda_T \sum_{\alpha} \sum_{(i,j)\in F} x_{i\alpha} x_{j\alpha}$$

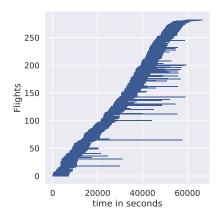


Flight Gate Assignment - Problem Instances

- Time data from agent based simulations (DLR-FW)
- Flight schedule from a mid-sized German airport
- Extract small but characteristic problem instances



M. Jung et. al.





Flight Gate Assignment - Annealing Results

- Time-to-solution with 99% probability (p: success probability) grows with problem size
- Main Result: Success probability suppressed by increased dynamical range C_{lsing} as a result of penalty terms





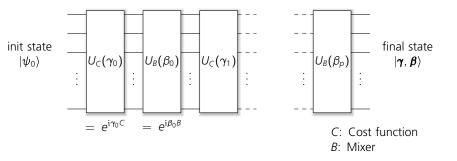
QA for Flight Gate Assignment - Summary and Outlook

- Flight gate assignment is amenable to QA
- Precision issues due to constraints
- Mitigate limited precision by bin-packing
- Open questions:
 - Are these problems hard for classical solvers?
 - How would larger problems perform?
 - Flight gate assignment with QAOA including constrained drivers
- Paper at arXiv:1811.09465



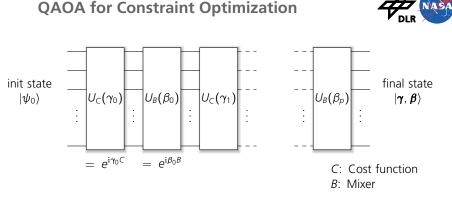






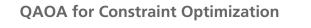


Hadfield et. al., arXiv:1709.03489

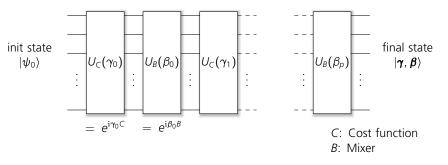


Get expectation value $\langle \boldsymbol{\gamma}, \boldsymbol{\beta} | C | \boldsymbol{\gamma}, \boldsymbol{\beta} \rangle$ through multiple measurements









Get expectation value $\langle \boldsymbol{\gamma}, \boldsymbol{\beta} | C | \boldsymbol{\gamma}, \boldsymbol{\beta} \rangle$ through multiple measurements



Hadfield et. al., arXiv:1709.03489



QAOA for Constraint Optimization



Find suitable mixer B

- That keeps valid states valid
- That explores the whole space

Example:

$$\sum_{i\alpha} x_{i\alpha} = 1$$

Use SWAP mixer:

$$\begin{array}{c}0\\0\\0\\1\\0\\0\end{array}\Rightarrow\begin{array}{c}0\\0\\0\\0\end{array}$$

Hadfield et. al., arXiv:1709.03489



QAOA Challenges for Real QC Hardware

Circuit synthesis for quantum algorithms

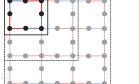


Circuit synthesis

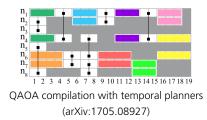


QAOA Challenges for Real QC Hardware

- Circuit synthesis for quantum algorithms
- Mapping quantum circuit to hardware with limited connectivity



Limited connectivity on QC chips





Circuit synthesis





www.DLR.de • Chart 17 > DLR > TM, EL and TS > Quantum Heuristic Algorithms for Hard Planning Problems from Aerospace Research

Thank You

