



From RigidBody to *CurvedBody* ?

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Overview

- ★ Idea
- ★ Method
- ★ Measurement
- ★ Summary
- ★ Outlook

Idea

- ★ Si strip sensor surface $w(u,v)$
 - Check for curvature with MillePede
 - Deviation Δw from flatness will affect position measurement $\Delta u = \Delta w \tan(\text{track angle})$
 - Important for cosmics (large track angles)

Method

- ★ Current alignment: like Taylor expansion
 - ▶ In use: $\Delta w(u) = a_0 + a_1 u$ (offset a_0 , slope a_1)
 - ▶ Add next term $a_2 u^2/2$? (curvature a_2)
 - ▶ Problem: a_0 and a_2 are correlated $\rightarrow a_0$ changes
- ★ Better: use system of orthogonal functions
 - ▶ Legendre polynomials: $L_n(x)$, $x = -1 \dots +1$
 - ▶ $\Delta w(u_r) = c_0 L_0(u_r) + c_1 L_1(u_r) + c_2 L_2'(u_r)$, $u_r = 2u/L_u$,
 $L_0(x) = 1$, $L_1(x) = x$, $L_2'(x) = x^2 - 1/3$
(<offset> c_0 , step (center to edge) c_1 , sagitta c_2)
 - ▶ Variance from L_2' : $\sigma_w^2 = 4/45 c_2^2 \approx (0.3 c_2)^2$

Measurement

- ★ Cosmics, 200k tracks, pixel fixed
- ★ Patched into Mille
 - ▶ 3 new alignment parameters (per module)
 $\Delta w \rightarrow \Delta w + S_u L_2'(u_r) + S_{uv} L_1(u_r)L_1(v_r) + S_v L_2'(v_r)$
 - ▶ with u_r, v_r in local **sensor** or **module** frame
 - ▶ TOB, outer TEC have 2 sensors per module
- ★ Approximations
 - ▶ Sensors are **rectangles**
 - ▶ Modules consist of 1 or 2 **identical** sensors

Ideal MC sensor sagittas [μm]

	TIB	TID	TOB	TEC ring 1-4	TEC ring 5-7
$\langle S_u \rangle$	0 ± 1	0 ± 1	0 ± 1	0 ± 1	-1 ± 1
$\langle S_{uv} \rangle$	0 ± 1	1 ± 1	0 ± 1	0 ± 1	-2 ± 1
$\langle S_v \rangle$	0 ± 1	0 ± 1	0 ± 1	0 ± 1	2 ± 1

$\chi^2/\text{ndf} = 1.04$

‘Default hit error’

CRAFT09 sagittas [μm]

Sensor

Module

	TIB	TID	TOB	TEC ring 1-4	TEC ring 5-7
$\langle S_u \rangle$	-28 ± 1	-40 ± 1	-30 ± 1	-34 ± 1	-29 ± 2
$\langle S_{uv} \rangle$	-4 ± 1	-8 ± 2	-5 ± 1	14 ± 1	4 ± 1
$\langle S_v \rangle$	-9 ± 1	-6 ± 2	-9 ± 1	-51 ± 1	-13 ± 1
$\langle S_u \rangle$	-28 ± 1	-40 ± 1	-30 ± 1	-33 ± 1	-24 ± 2
$\langle S_{uv} \rangle$	-4 ± 1	-8 ± 2	-8 ± 1	13 ± 1	16 ± 2
$\langle S_v \rangle$	-10 ± 1	-6 ± 2	-68 ± 1	-50 ± 1	-6 ± 2

$\chi^2/\text{ndf} = 0.99$

$\chi^2/\text{ndf} = 0.88$

Summary

★ Ideal MC

- ▶ Consistent with perfectly flat sensors

★ CRAFT09

- ▶ Sagitta in u

- ♦ All modules, about $30\ \mu\text{m}$

- ▶ Sagitta in v

- ♦ TOB, inner TEC modules, about $60\ \mu\text{m}$

- ▶ Systematic error in w of $10\text{-}20\ \mu\text{m}$

- ♦ Important contribution to measurement error for cosmics

Outlook

- ★ What to do about module curvature?
 - Check with other sources
 - Ignore as before
 - Use for CPE error angular dependence
 - Implement in tracking
- ★ Complete implementation of CurvedBody as alternative alignable?