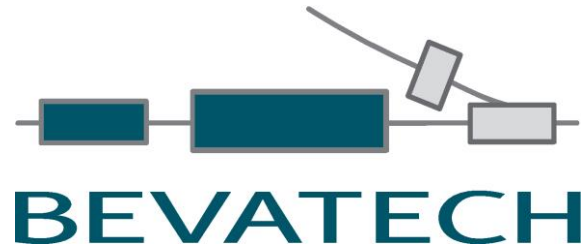
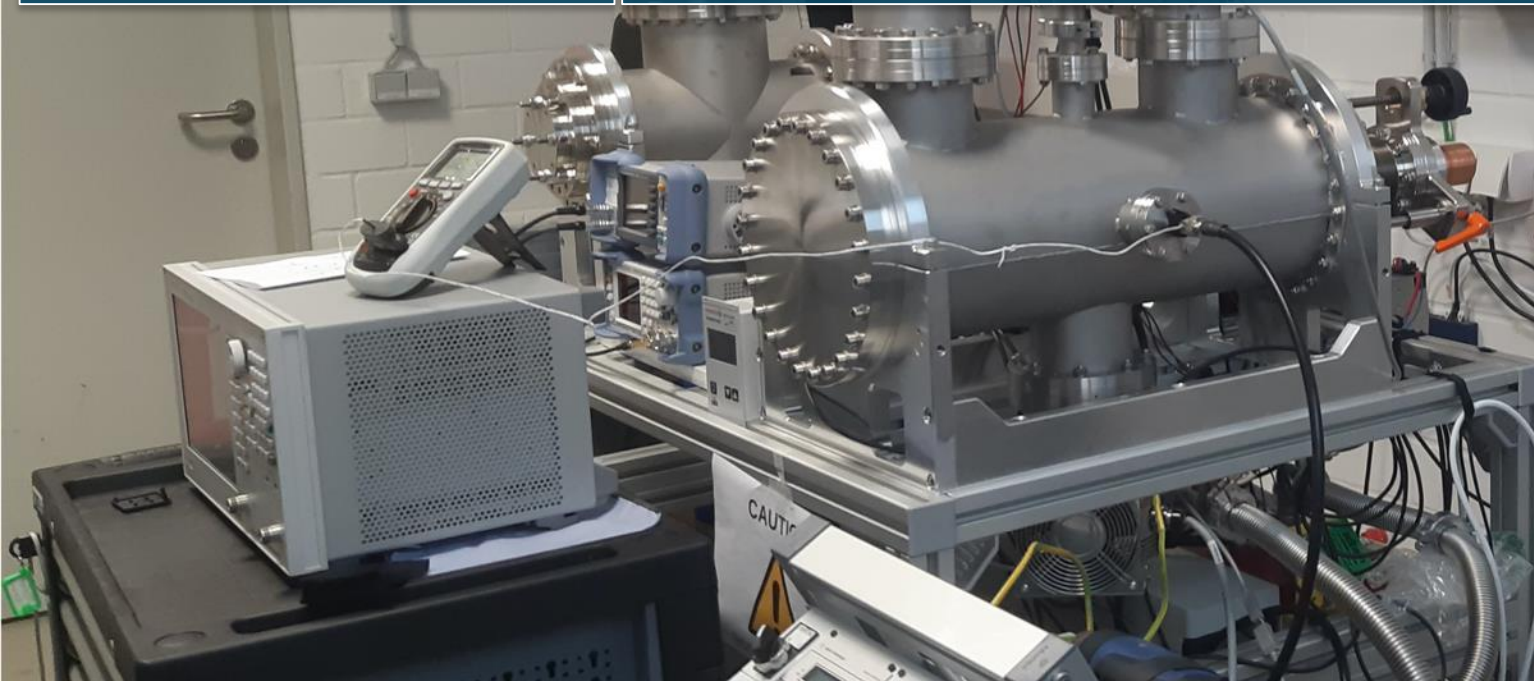


A MTCA based LLRF for the LILAC injector of the NICA project

1. December 2020

Christian Trageser, BEVATECH GmbH



A MTCA based LLRF for the LILAC injector of the NICA project

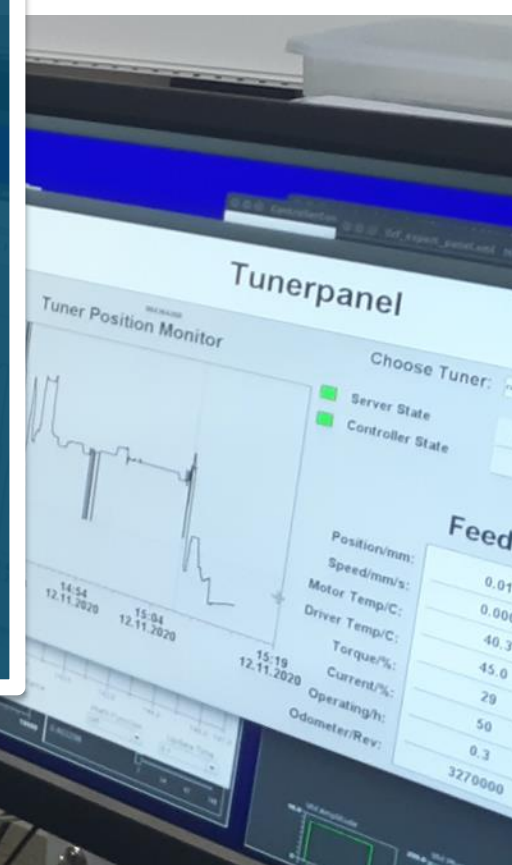
1. December 2020

Christian Trageser, BEVATECH GmbH

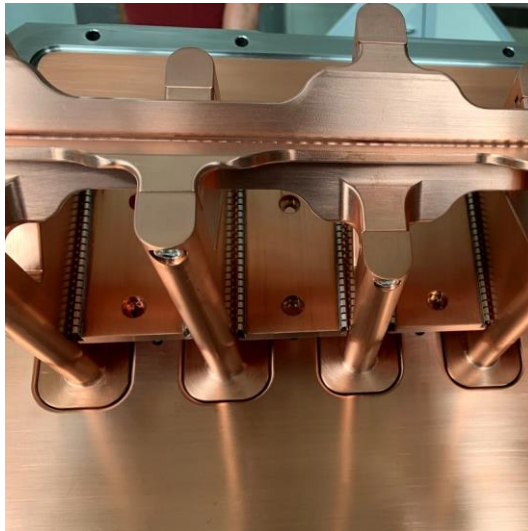


Outline

1. LLRF for LILAC Injector
2. MTCA based LLRF
3. Tuner Controls for LLRF
4. Test Bench
5. Summary



ACCELERATORS & VACUUM



- Complete LINAC Systems
- RF Cavities
- Beam Diagnostic
- Vacuum Technology
- Tumor Therapy

ENGINEERING & CONSULTING



- Beam Lines
- Vacuum
- Design Studies
- RF Research
- Outsourcing
- Project Management

ELECTRONICS & IT



- Micro TCA
- Automation
- Instrumentation & Controls
- Project Management

1. LLRF for LILAC Injector

Nuclotron-based Ion Collider Facility @ JINR

- Accelerator and Experimental Complex

Main Goal:

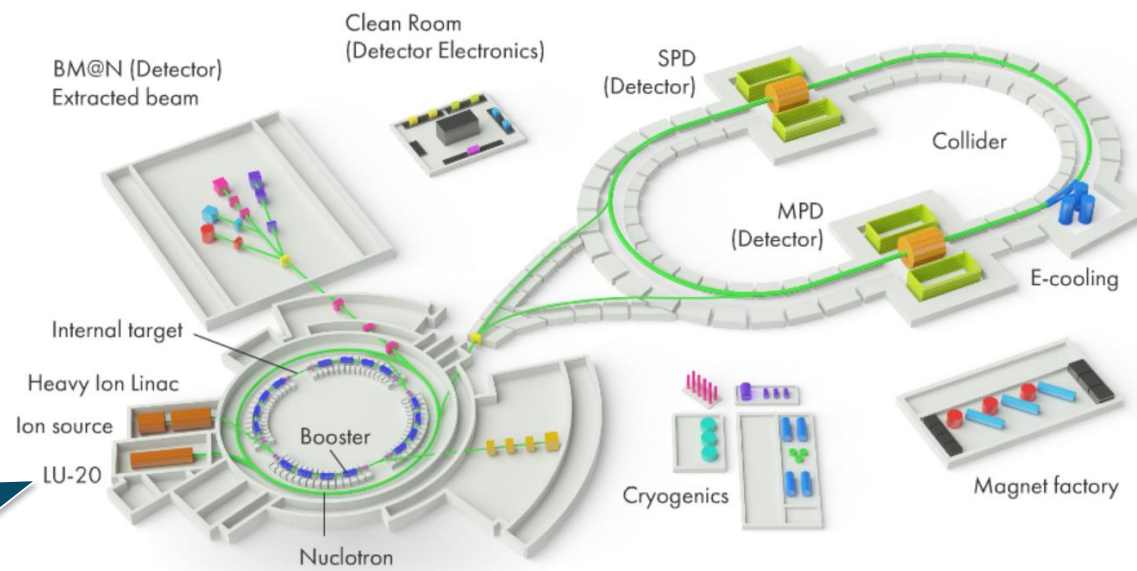
- Provide ion beams for hot and dense strongly interacting baryonic matter and spin physics



Facility parts:

- Light Ion LinAC (LILac)
- **Heavy Ion LinAC (HILac)**
- NUCLOTRON SC Synchrotron
- BOOSTER SC Synchrotron
- Colider Ring
- Experiments

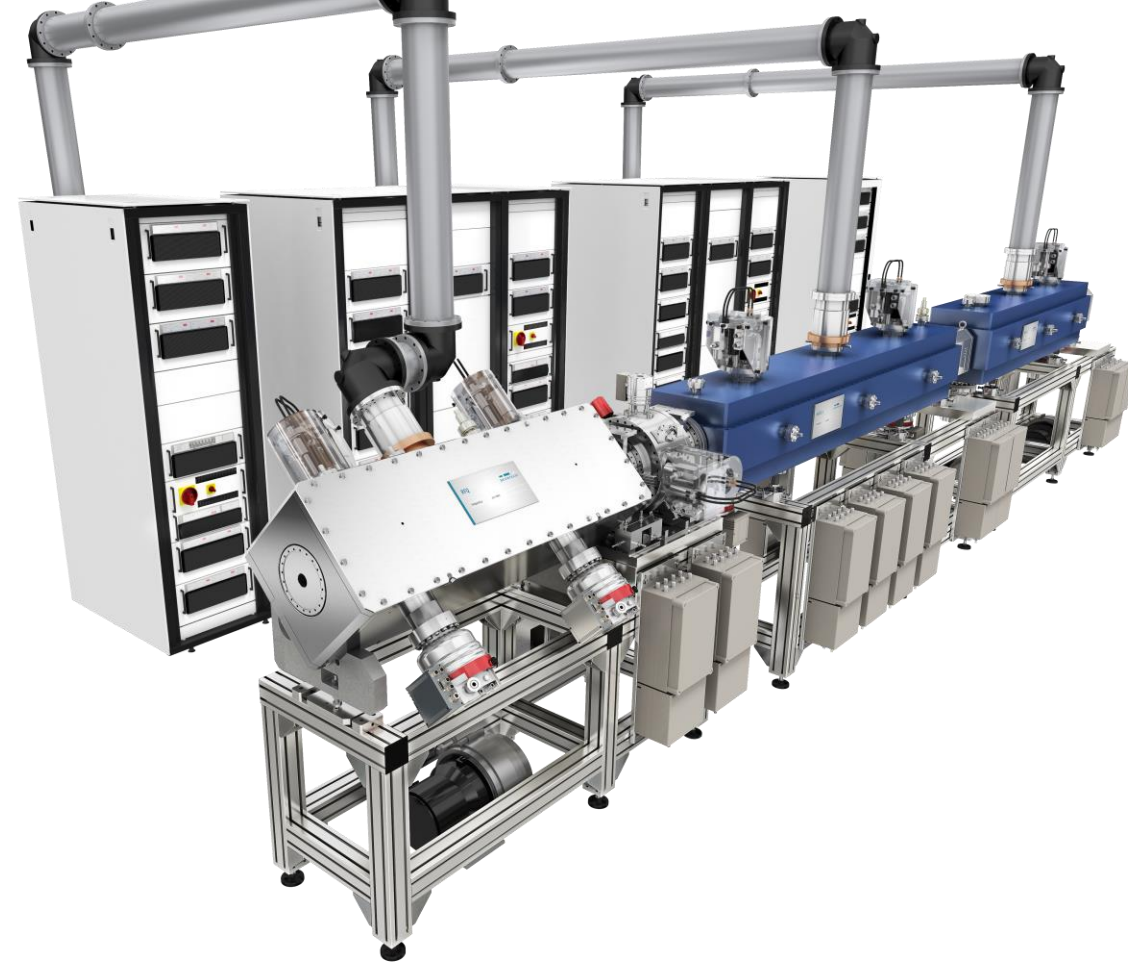
NICA Complex



LILac will
replace LU-20

Image from <https://nica.jinr.ru/complex.php>

Parameter	Protons	C ⁴⁺
Min/max A/q:	1	3
Injection Energy/keV:	30	60
Exit Energy/MeV:	7	21
Beam Current/mA	5	15
Frequency/MHz:	162.5	
Repetition Rate/Hz	5	
Current Pulse Length/us	30	
RF Pulse Length/us	200	
Puls Power/MW	1.8	
Transmission	> 80 %	
Full Length LINAC/m	< 12.5	



LILac - Light Ion LinAC

LEBT

RFQ

REBUNCHER

IH1

IH2

IH3

DEBUNCHER

NUCLOTRON

6 cavities

What is a Low Level RF (LLRF)?

LLRF

**Low
Level
Radio
Frequency**

What?

Stabilizes amplitude,
frequency, phase

Why?

Improves beam loss,
energy spread, beam
phase

Requirements for LILAC LLRF
Amplitude stability < 0.2 %
Phase stability < 0.1 °

User

Set-points

Beam



Beam



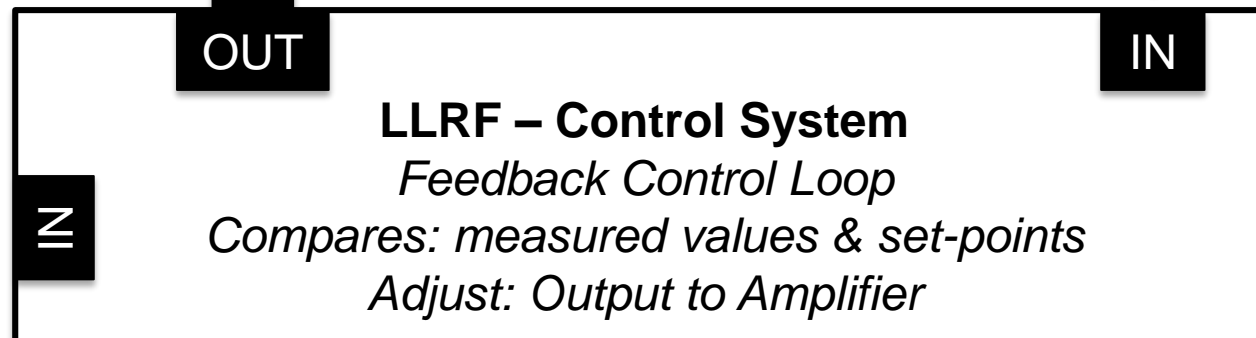
S
i
g
n
a
l

OUT

Measures values

P
r
o
p
e
r
t
y

IN



What is a Low Level RF (LLRF)?

LLRF

Low
Level
Radio
Frequency

What?

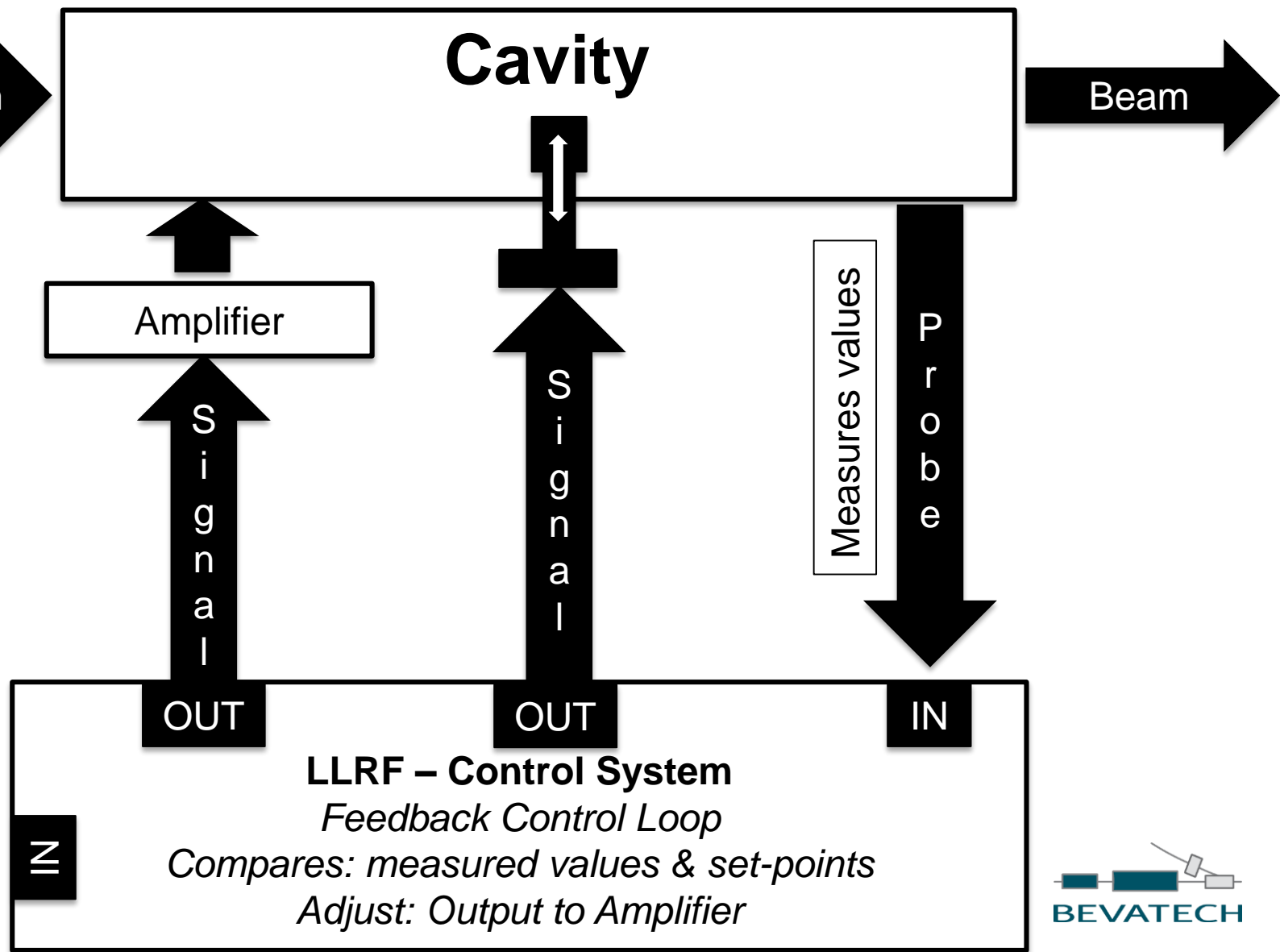
Stabilizes amplitude, frequency, phase

Why?

Improves beam loss, energy spread, beam phase

User

Set-points



Requirements for LILAC LLRF
Amplitude stability < 0.2 %
Phase stability < 0.1 °





Cooperation

2017

Discussion to derive XFEL LLRF for Hadron Linacs

2018

Suggested TDR to JINR

2019

Developing and Testing LLRF

2020

Awaiting Commissioning with first cavity



2. MTCA Based LLRF

MTCA Crate

Vector Signal Generator

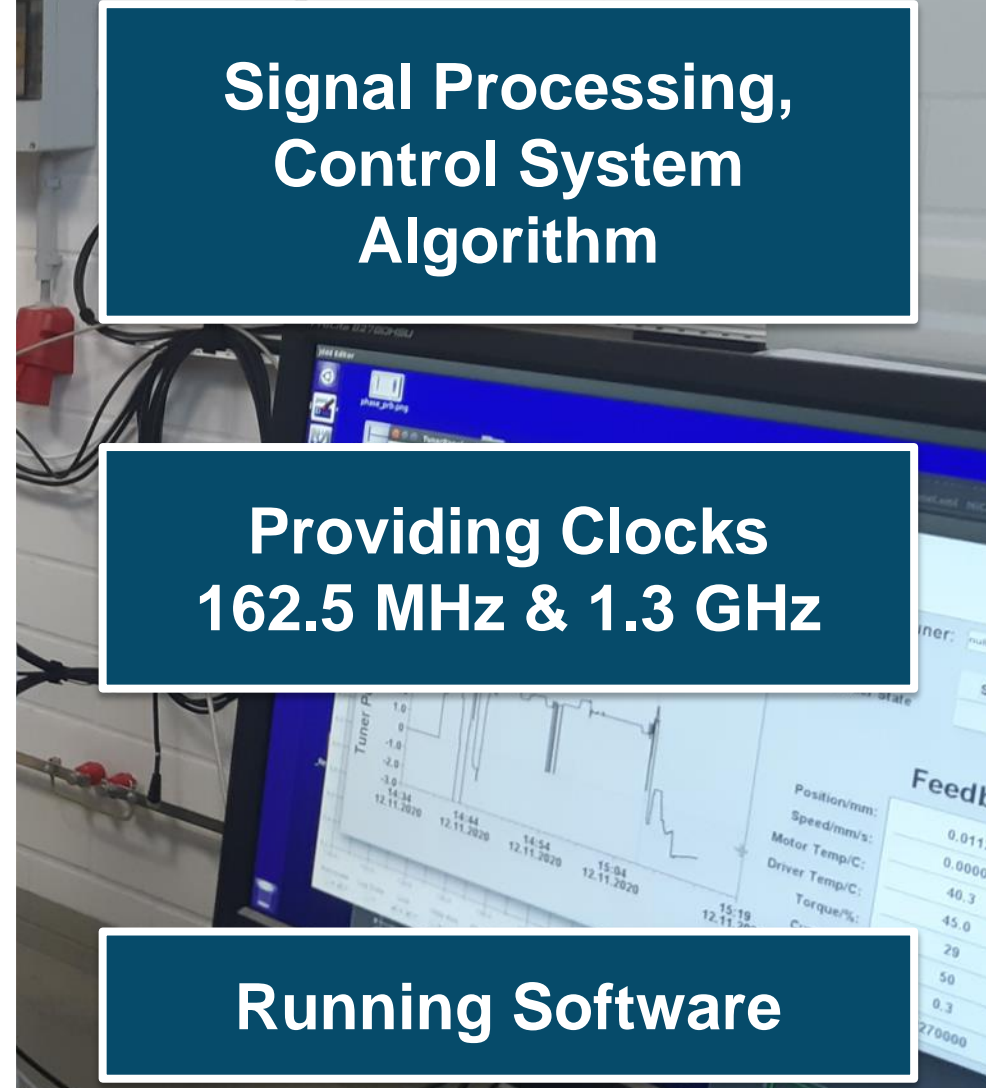
External CPU

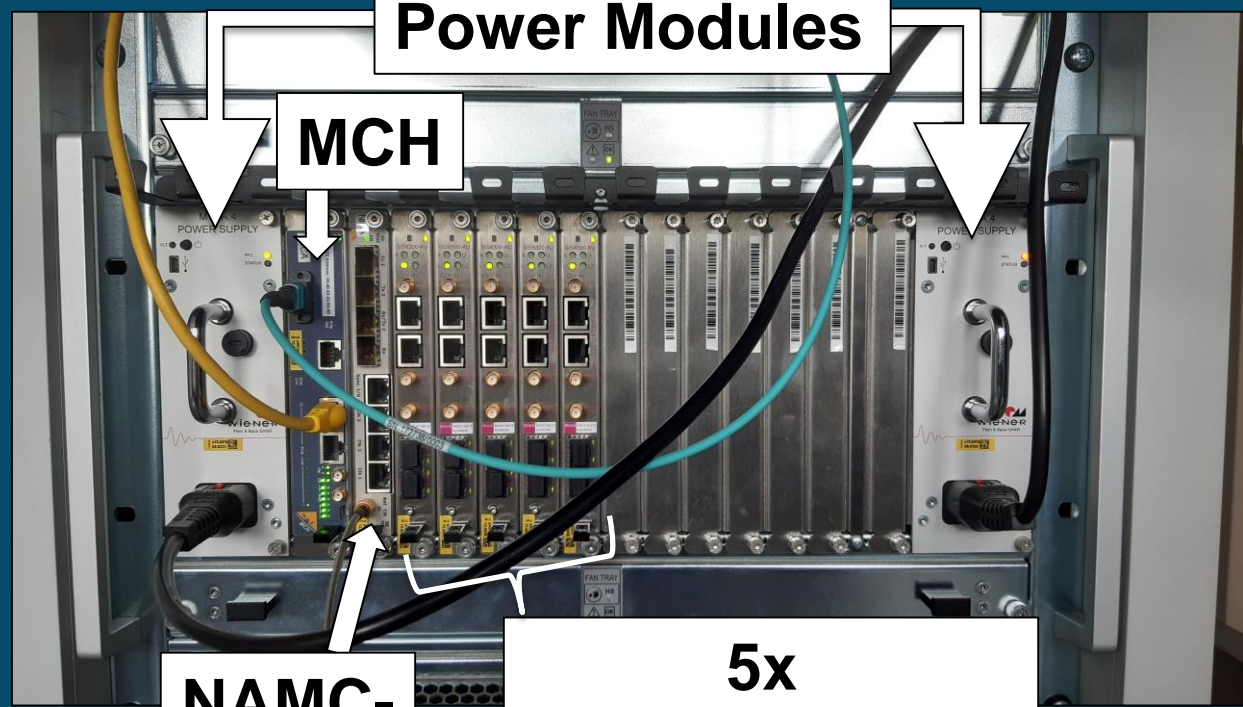
Signal Processing,
Control System
Algorithm

Providing Clocks
162.5 MHz & 1.3 GHz

Running Software

LLRF Parts





Power Modules

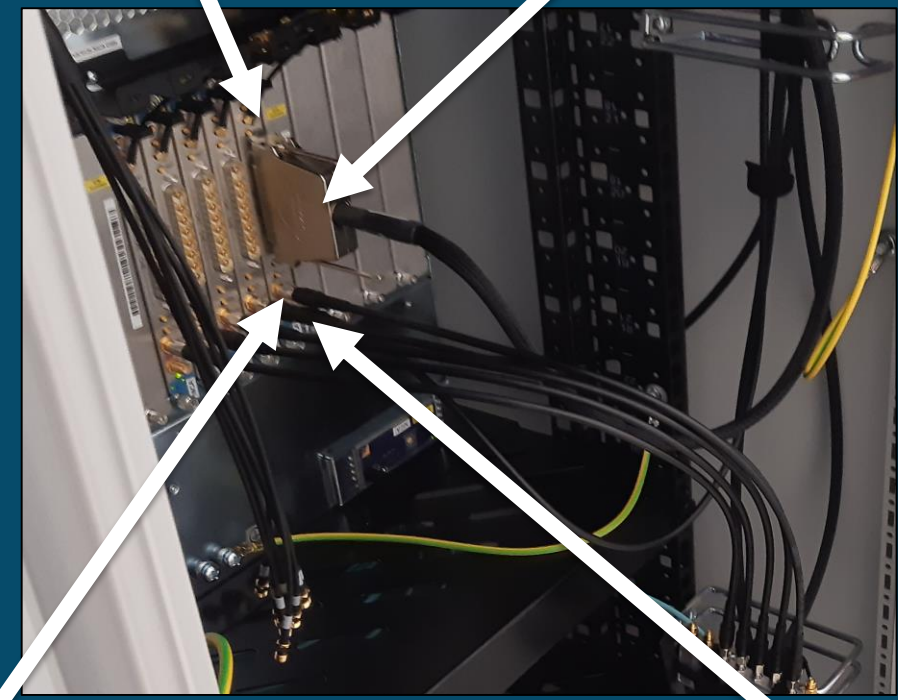
MCH

NAMC-Timer

**5x
Digitizer Boards**

Interlock Connector

**FBM Connector
(8 Inputs)**



**Reference Clock (SMA)
1.3 GHz from MO**

**Vector Modulator
Output**

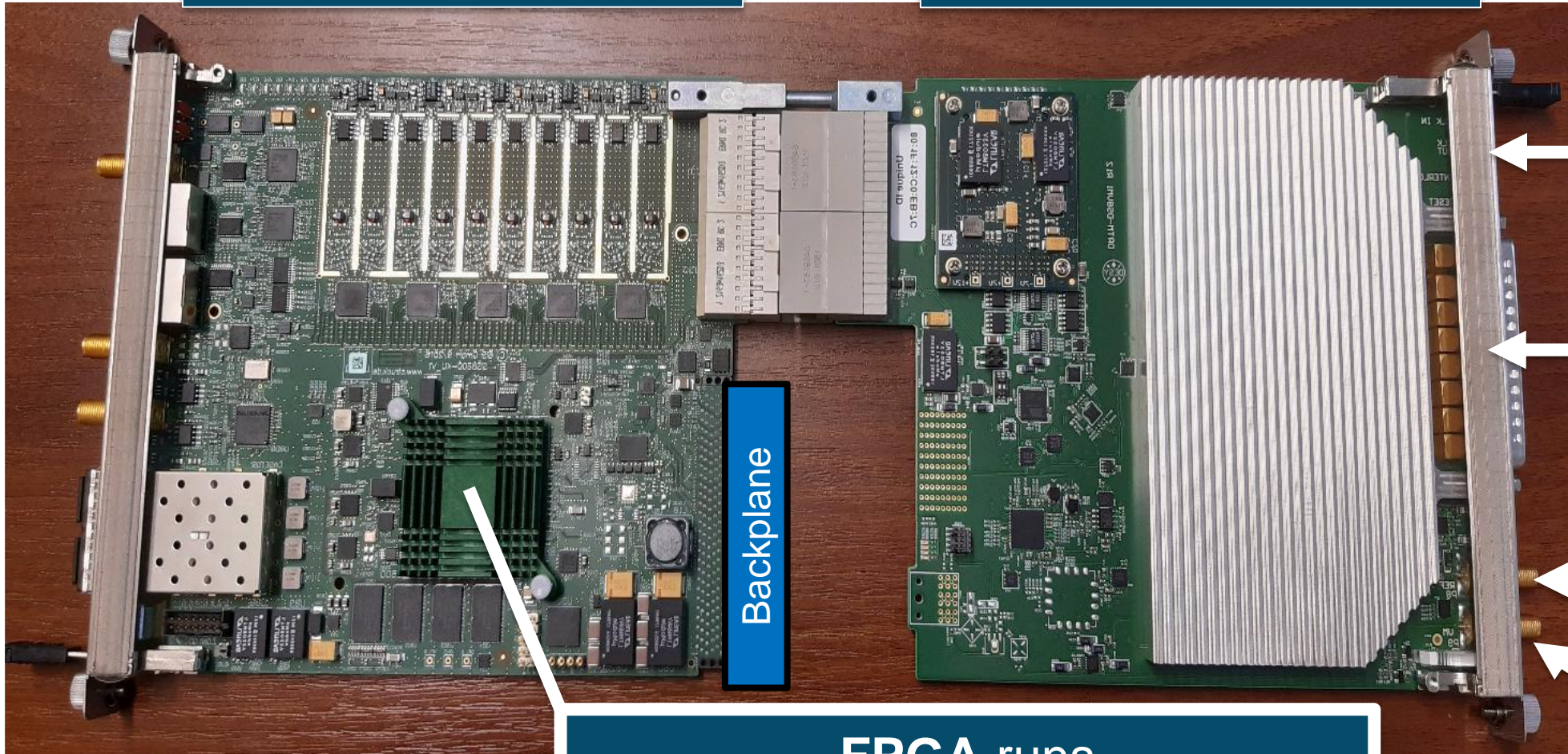
MTCA – Crate (front)

MTCA – Crate (rear)

Front
AMC: SIS8300KU

Rear
RTM: DS8VM1

AMC/RTM for each cavity



Backplane

Interlock

Probe,
Forwarded,
Reflected
Signals

Ref. Clock
(162.5 MHz)

Vector
Modulator
(Output)

FPGA runs
control algorithm for
Amplitude/Phase Control System

struck innovative
systeme



BEVATECH

DOOCS.

The Distributed Object-Oriented Control System Framework

JAVA
DOOCS
DATA
DISPLAY



**Firmware
(on FPGA)**

Control Algorithm



**DOOCS Server
(on external CPU)**

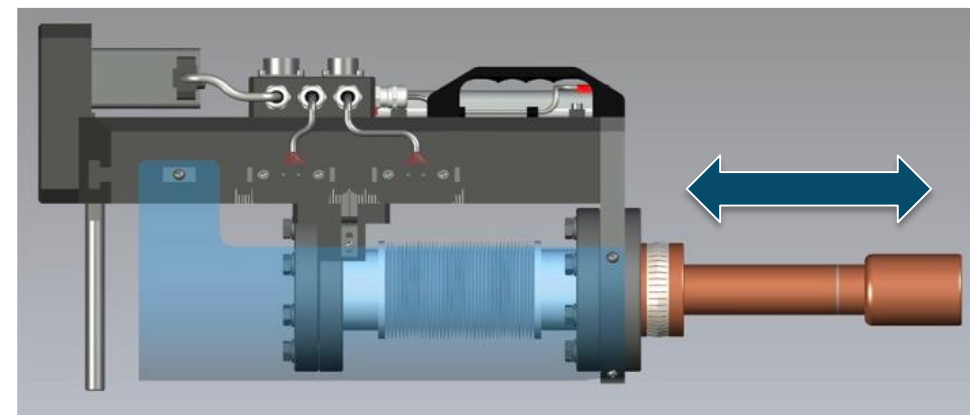
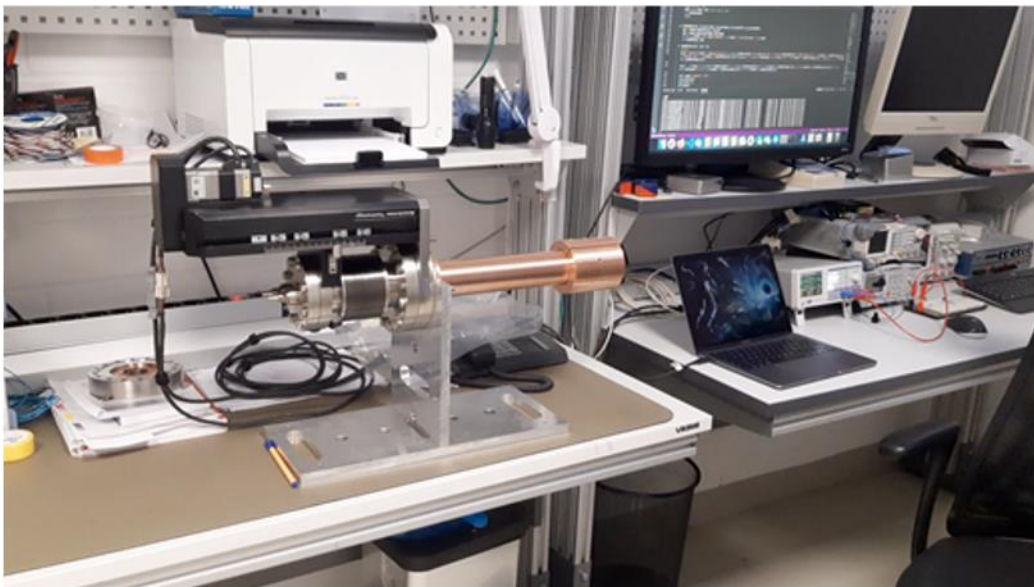
*Configuring, Controlling,
Monitoring, Connecting
Digitizer Boards*



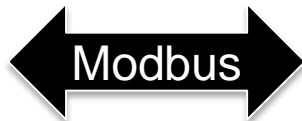
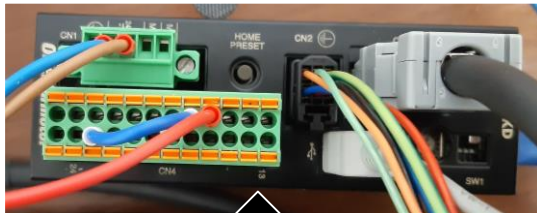
**GUI
(remote)**

Interaction User

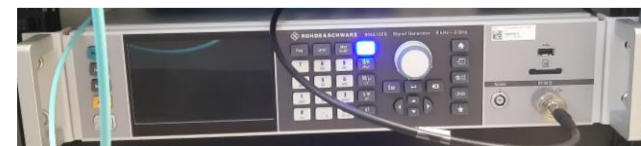
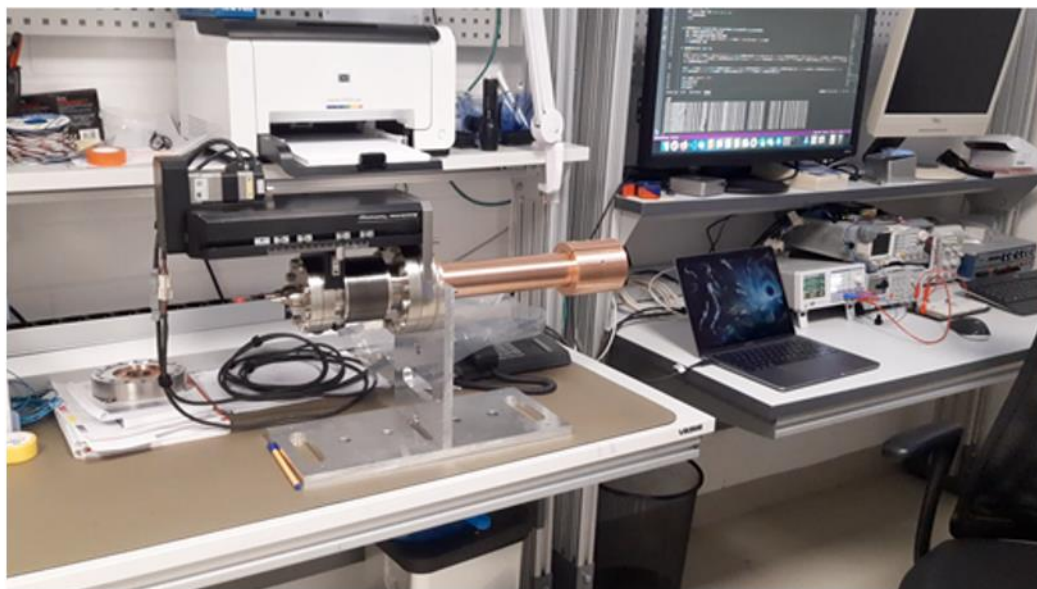
3. Tuner Controls



Orientalmotor



LLRF



microTCA

TECHNOLOGY LAB

A HELMHOLTZ INNOVATION LAB

Write in ChimeraTK

Compile/link to

EPICS

OPC UA

DOOCS

TANGO

not yet available

Switch between

LLRF so far DOOCS

NICA uses TANGO

Control system and
Hardware
Interface with
Mapped and
Extensible
Register-based device
Abstraction

-
Tool
Kit



Open Source

<https://github.com/ChimeraTK>

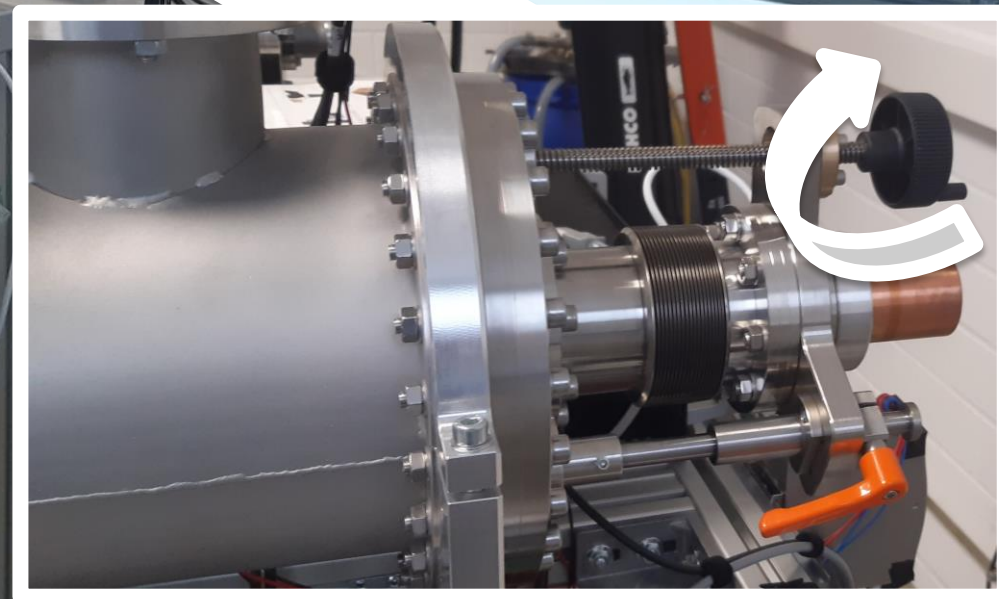


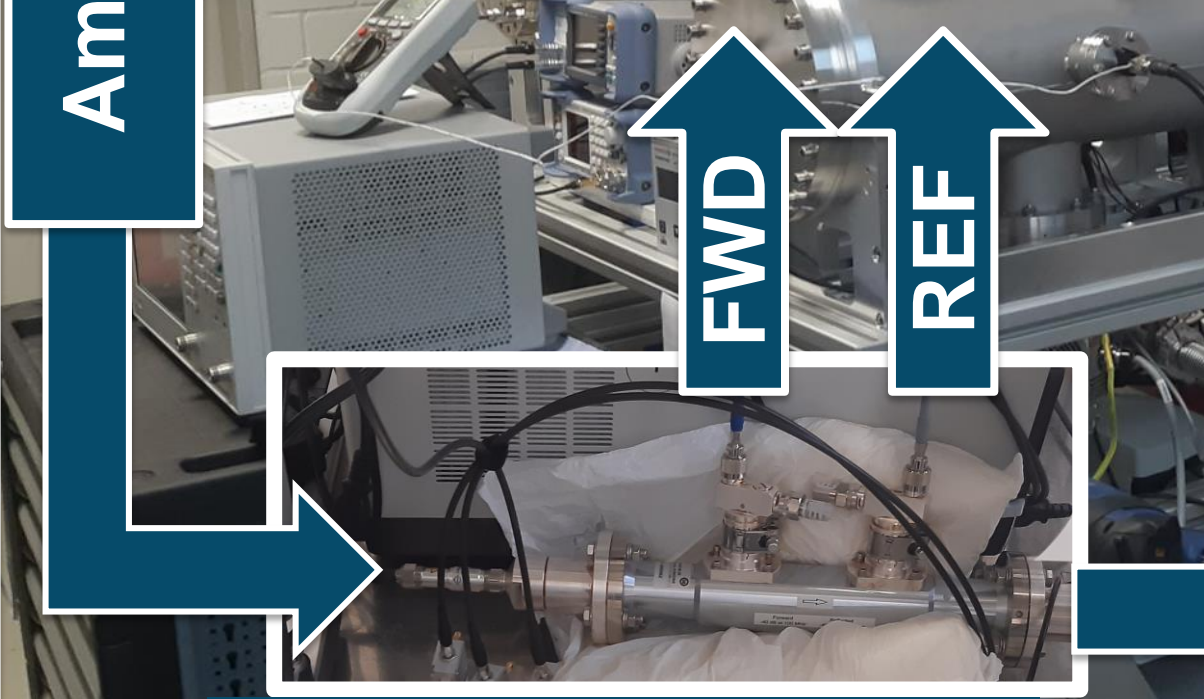
4. Test Bench

Test Bench - Cavity

Cavity for testing

Adjustable Resonance Frequency
150 - 190 MHz





Directional Coupler

Amplifier

PROBE

FWD

REF

Tunerpanel

Tuner Position Monitor

Choose Tuner:

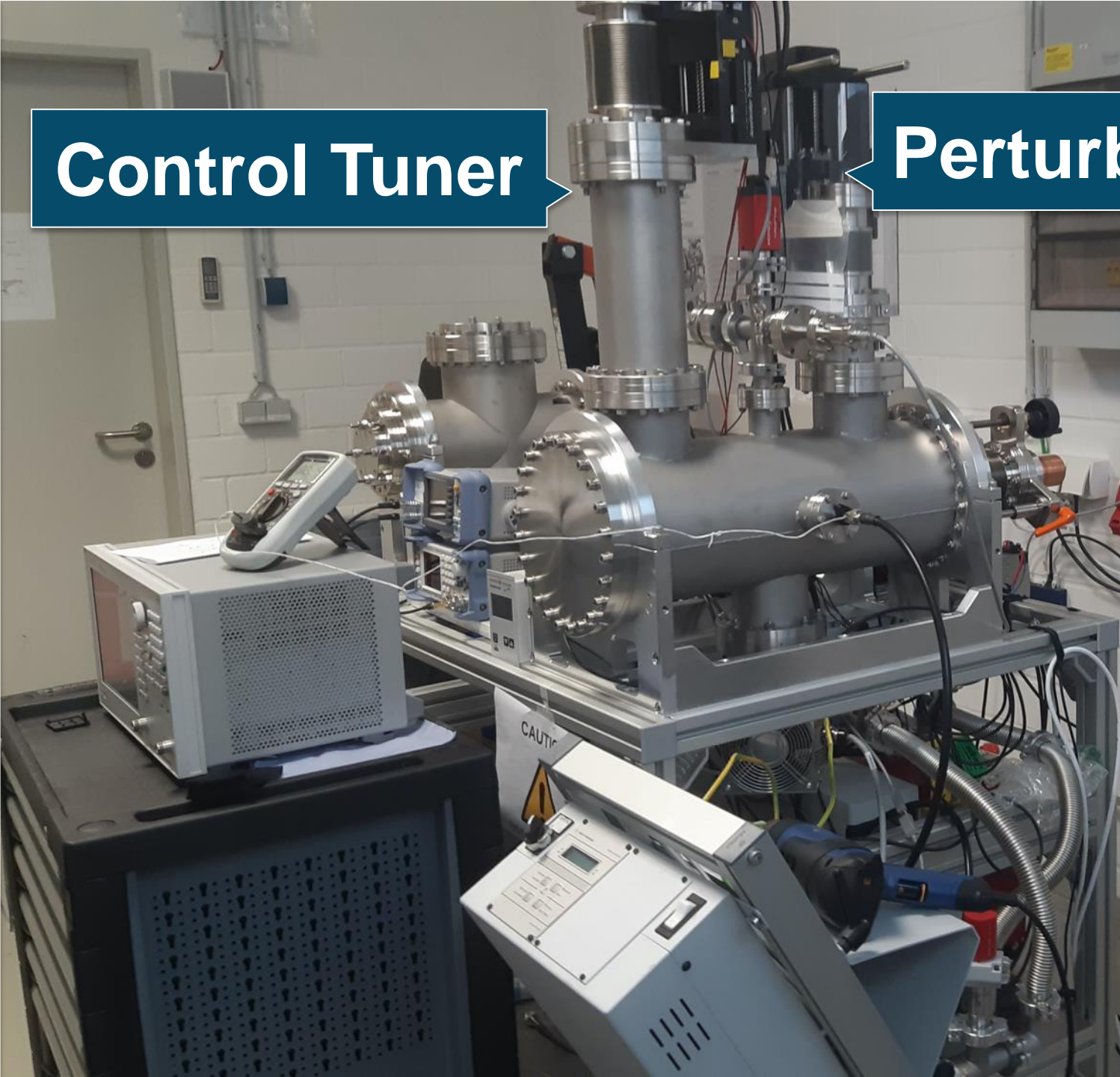
Server State
Controller State

Feed

Position/mm:	0.011
Speed/mm/s:	0.0000
Motor Temp/C:	40.3
Driver Temp/C:	45.0
Torque%:	29
Current%:	50
Operating/h:	0.3
Odometer/Rev:	3270000

Control Tuner

Perturbation Tuner





Tunerpanel

Choose Tuner:

Tuner Position Monitor

Server State
 Controller State

Feedback	Setpoint
Position/mm:	1.5957
Speed/mm/s:	0.0000
Motor Temp/C:	29.6
Driver Temp/C:	44.0
Torque/%:	12
Current/%:	50
Operating/h:	6.6
Odometer/Rev:	3123000

UNAVAILABLE WHILE CONTROLLER IS ACTIVE



Controller Configuration

Choose Tuner:

	Feedback	Setpoint
Response Phase Coeff:	0.024000	0.024000
Response Threshold:	0.000100	0.000100
Puls Divider:	15	15
Min Valid Tuner Pos/mm:	-20.0000	-20.0000
Max Valid Tuner Pos/mm:	20.0000	20.0000
Tuner Speed/ mm/s:	4.00000	4.00000
Tuner Pos Gain	-0.0440	0.0440
Tuner Pos Offset	0.0000	0.0000



LLRF Data Processor

Choose Tuner:

FORWARD Phase

REFLECTED Phase

PROBE Phase

Mixer:

+

Sum:

Process of Flattop/%:

AVG/deg:

Slope/deg/us:

Lab GUI



5. Summary

- **System under testing @ BEVATECH**
- **Tuner Control System is under development**
- **Testing with cavities is ongoing**
- **MTCA based LLRF highly customizable and flexible**
- **ChimeraTK allows for early use of the system and later easy adaption to NICA control system environment**
- **JDDD allows to create simple GUIs quickly**
- **Excellent Cooperation with MTCA Techlab**