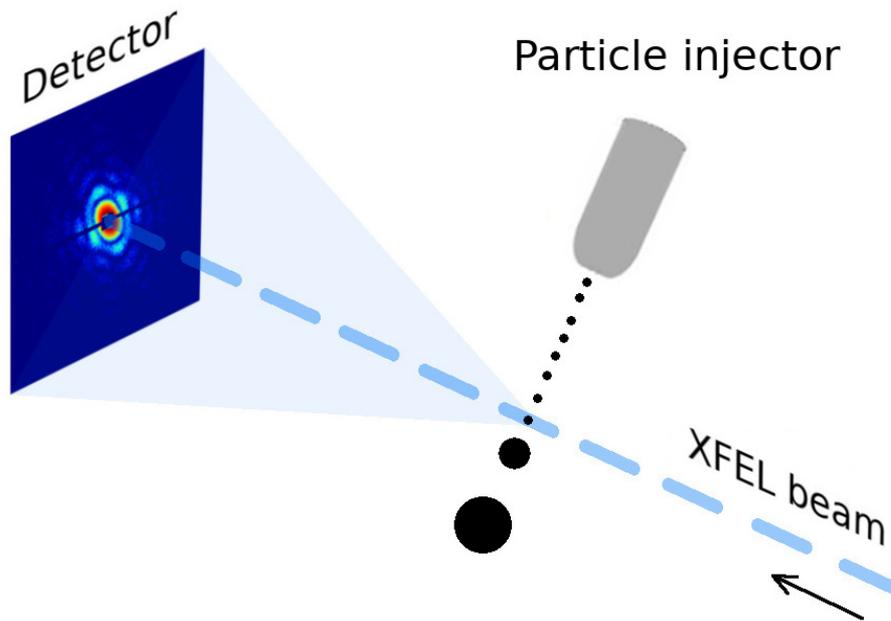


# Classification of diffraction patterns in Single Particle Imaging (SPI) experiments performed at X-ray free-electron lasers using a Convolutional Neural Network (CNN)

Alexandr Ignatenko

Hamburg, 04.12.2020

# SPI experiment



LCLS 2018

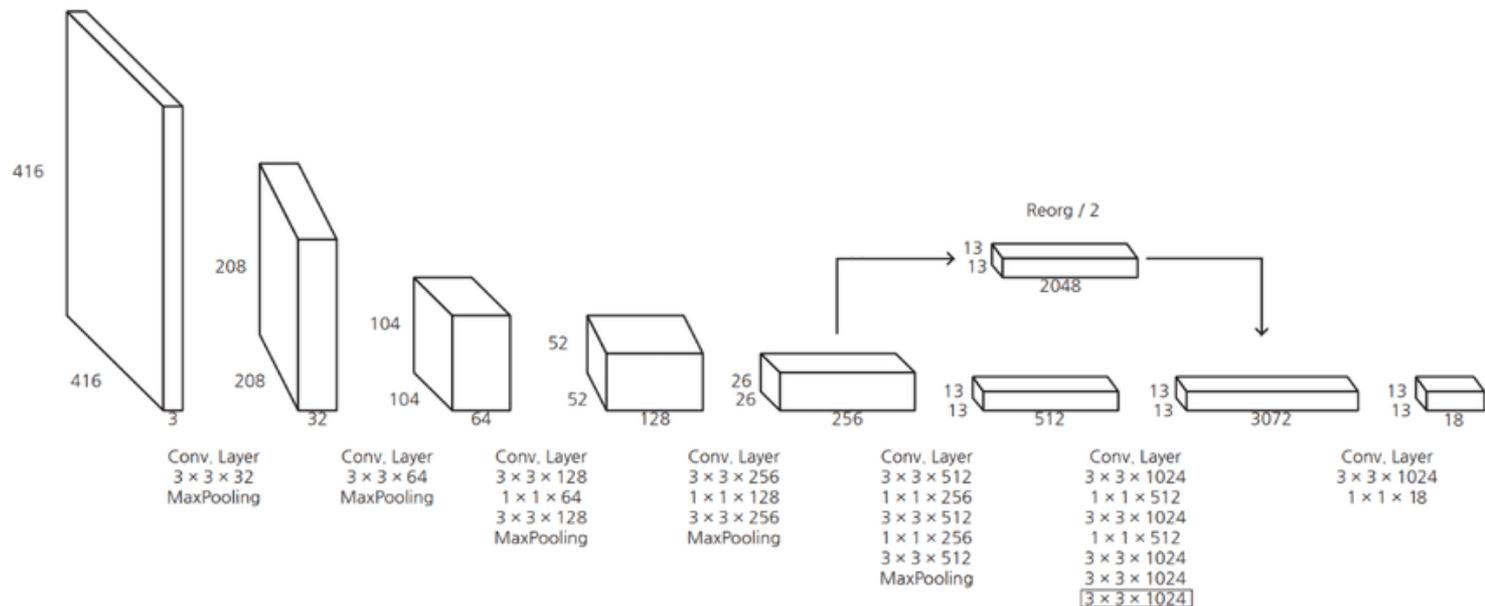
- AMO beamline at LCLS
- Sample – bacteriophage PR772, expected size 60-75 nm
- $E = 1.7 \text{ keV}$  ( $\lambda = 7.29 \text{ \AA}$ )
- Detector distance = 130 mm
- Detector – pnCCD, one plane (512x1024) was operational

Data processing pipeline:

Pre-processing → Classification → Orientation determination & background subtraction → Phase retrieval and structure reconstruction

Classification: hit finding, size filtering, single-hit classification

# YOLOv2



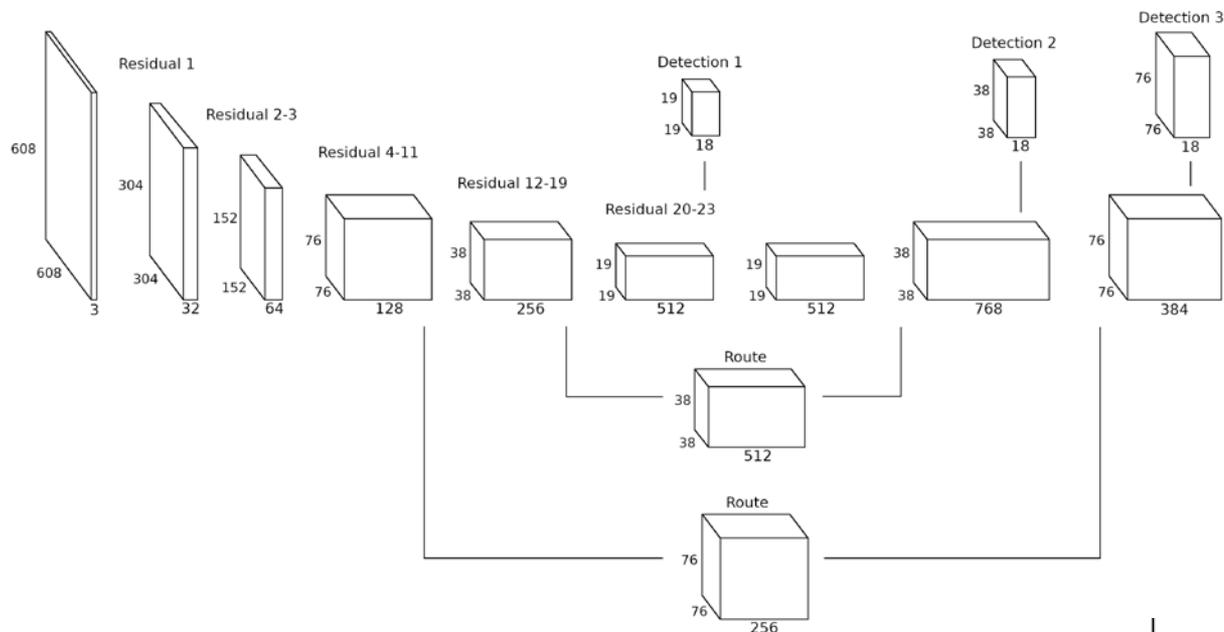
S. Seong et al., Determination of Vehicle Trajectory through Optimization of Vehicle Bounding Boxes using a Convolutional Neural Network. *Sensors* **2019**, 19, 4263

Darknet-19 feature extractor trained on ImageNet  
+ 1 convolutional layer: 20 convolutional layers

Loss function with classification and localization terms

Stochastic gradient descent (SGD) used for minimization  
Batch size: 64

# YOLOv3

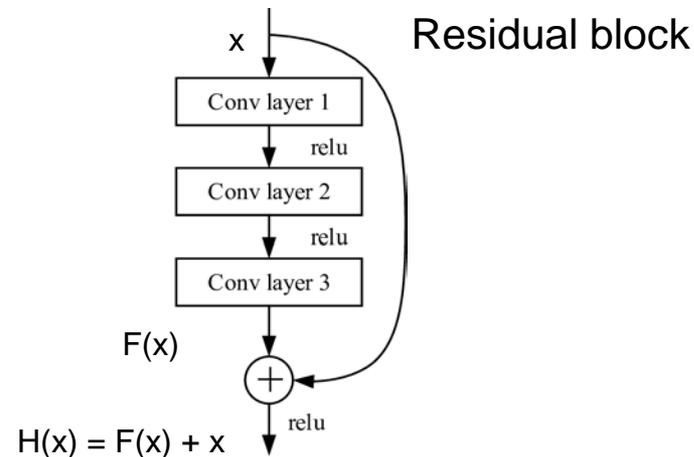


Darknet-53 feature extractor trained on ImageNet  
53 convolutional layer in feature extraction

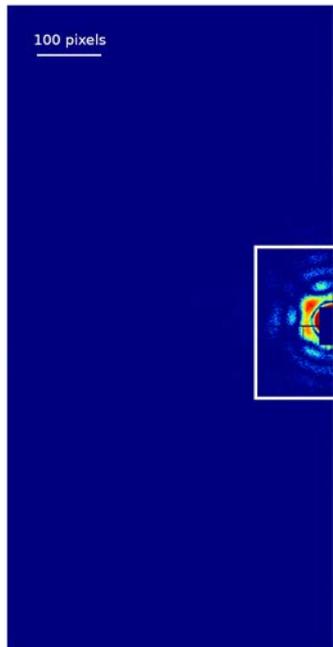
Residual architecture

Loss function with classification and localization terms

Stochastic gradient descent (SGD) used for minimization  
Batch size: 24



# Data preparation



HDF5 file

Pattern  
512x1024

ROI  
123x240

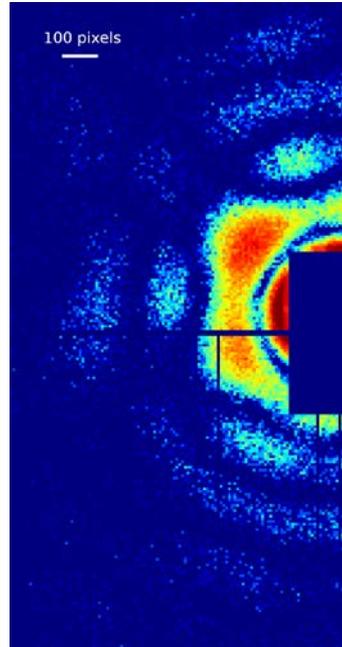


Image file

954x1855

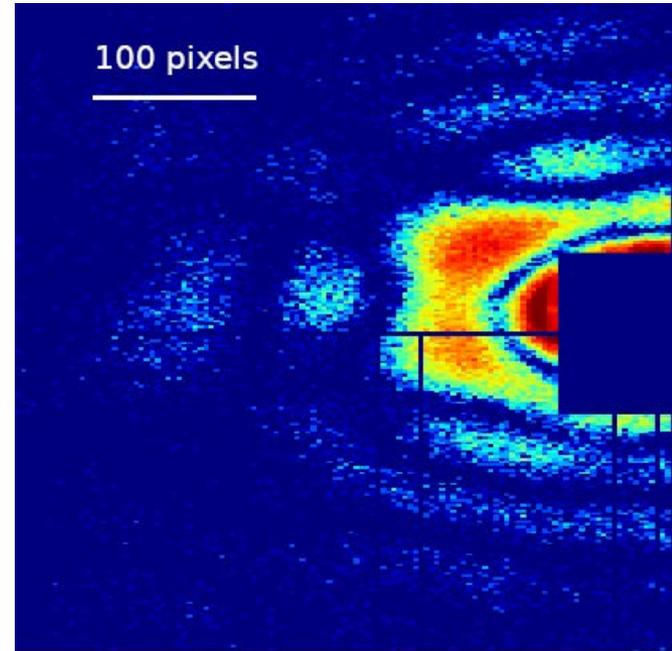


Image file

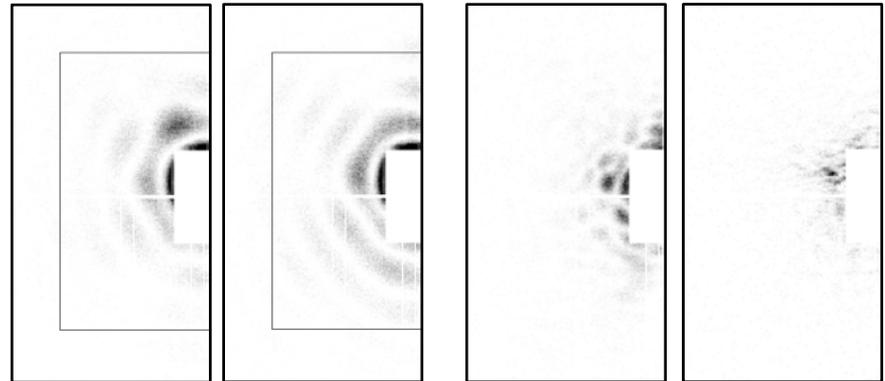
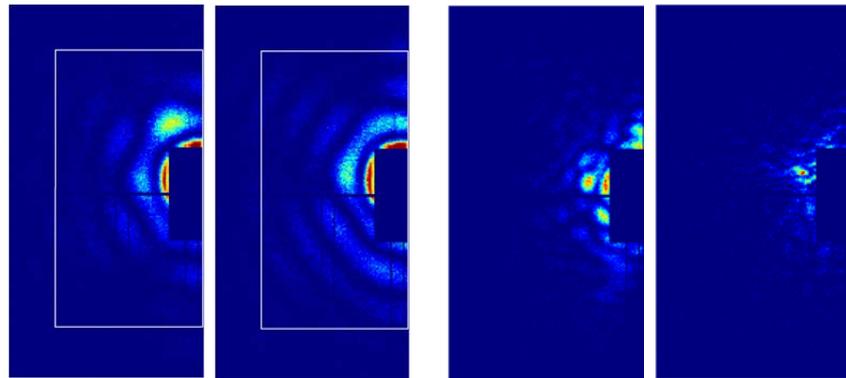
416x416  
(YOLOv2)

608x608  
(YOLOv3)

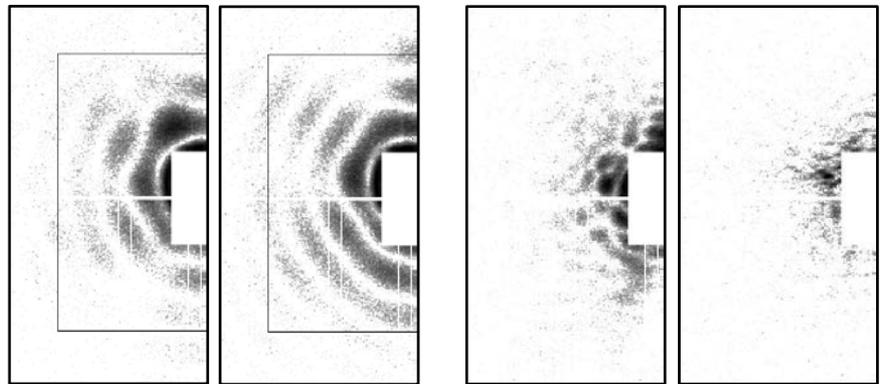
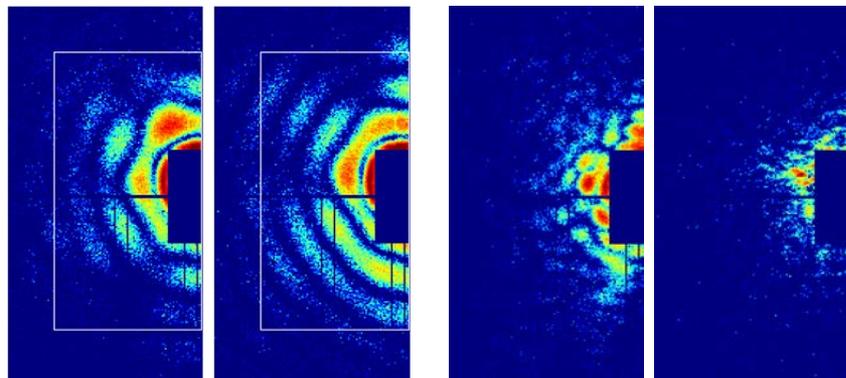
# Data representation

Color (3 RGB layers, “jet” color scheme)

Grayscale (3 identical layers)



Linear scale



Logarithmic scale

Positive

Negative

Positive

Negative

$$I(q) \sim q^{-3} \div q^{-4}$$

# Training, validation and test sets

## Training set

165 positive examples (single hits)

390 negative examples

## Validation set

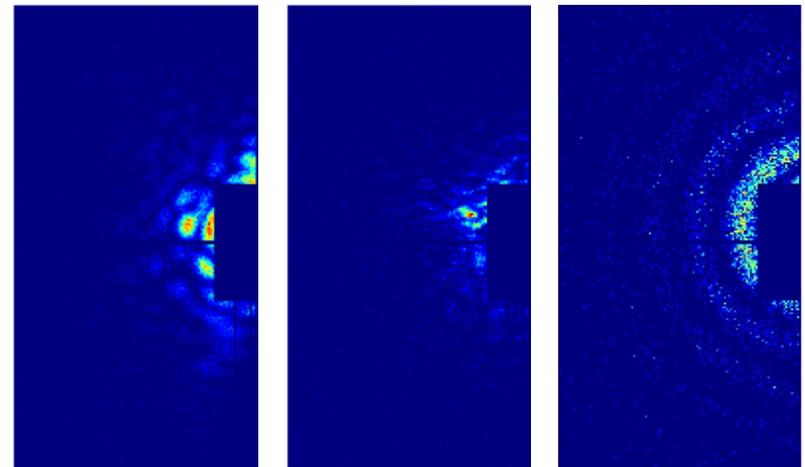
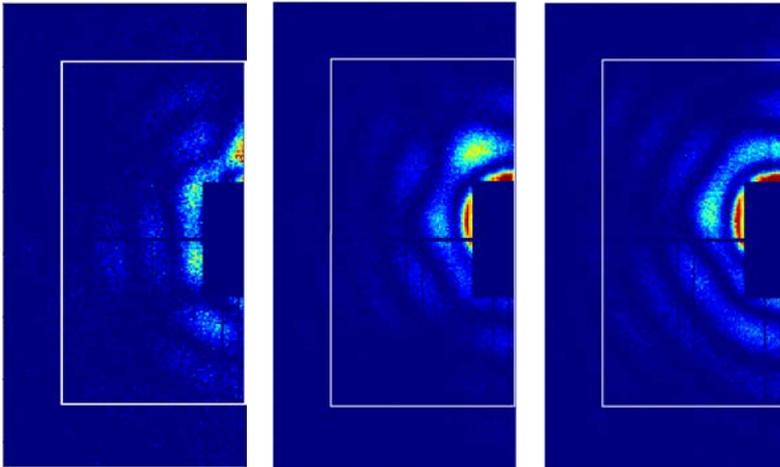
53 positive examples (single hits)

283 negative examples

## Test set (55-84 nm)

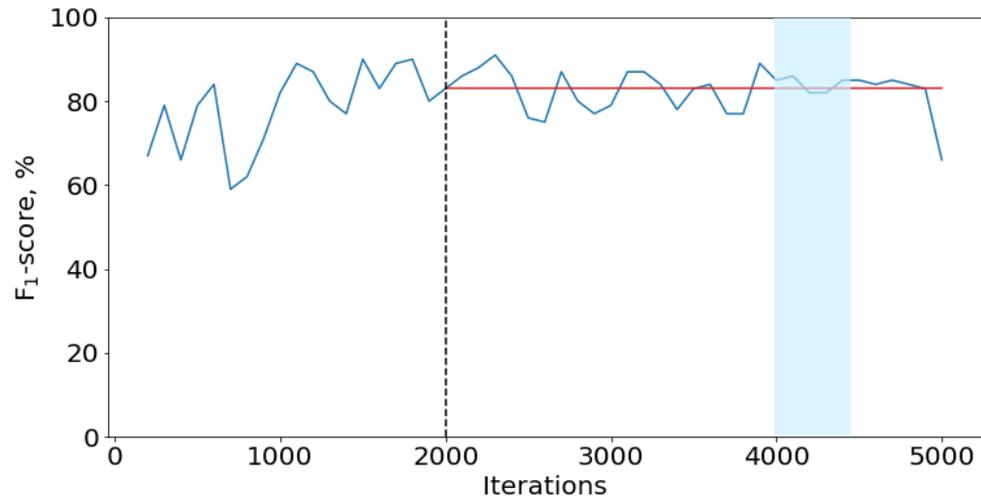
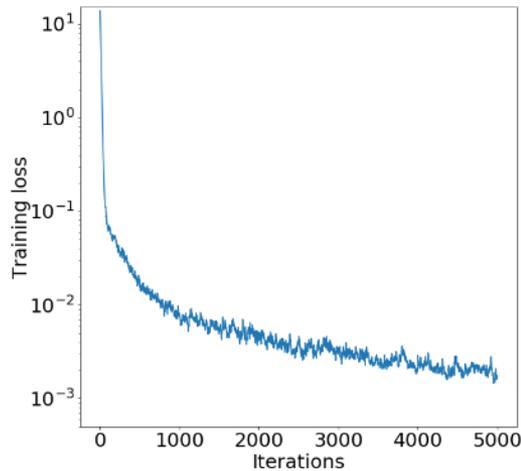
995 positive examples (single hits)

16 937 negative examples



# Training, validation and test

Observe training loss every iteration and save model every 100 iterations



Validation procedure to find an optimal training stage (not to optimize the hyper-parameters, *i.e.* size and number of filters, learning rate, batch size etc)

Calculate F<sub>1</sub>-score on validation data set (every 100 iterations) to control overfitting

Intersection selection (4000, 4100, 4200, 4300 and 4400 iterations) for test

# Results

## Intersection selection

<b>Model</b>	<b>Number of selected single hits</b>	<b>Intersection with manual selection</b>	<b>IoU for manual selection, %</b>	<b>Accuracy, %</b>	<b>Precision, %</b>	<b>Recall, %</b>
<b>YOLOv2, color, linear</b>	1185	597	38	95	50	60
<b>YOLOv2, color, log</b>	1368	614	35	94	45	62
<b>YOLOv2, grayscale, linear</b>	1756	622	29	92	35	63
<b>YOLOv2, grayscale, log</b>	904	487	34	95	54	50
<b>YOLOv3, color, linear</b>	1041	505	33	94	49	51
<b>YOLOv3, grayscale, linear</b>	2316	465	16	87	20	47

# Results

## Comparison with a reference method

Model	Number of selected single hits	Intersection with manual selection	IoU for manual selection, %	Accuracy, %	Precision, %	Recall, %
YOLOv2, color, linear	1185	597	38	95	50	60
EM based	1085	574	34	94	53	48

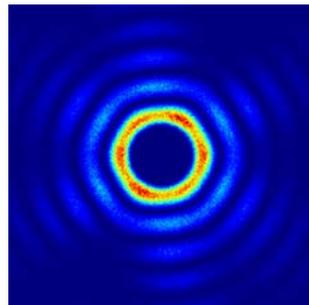
Ground truth: manual selection

A. Ignatenko et al. (2020) "Classification of diffraction patterns in single particle imaging experiments performed at X-ray free-electron lasers using a convolutional neural network", *Machine Learning: Science and Technology* (submitted). Preprint available <http://arxiv.org/abs/2008.07288>

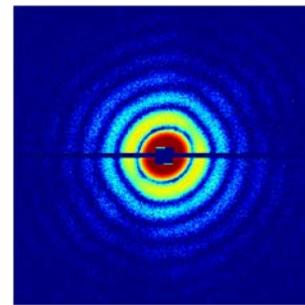
# Outlook

- Build a custom CNN and train with diffraction patterns to the full depth
- Optimize hyper-parameters (use larger filters, reduce number of filters, increase batch size)
- Try state-of-the-art architectures
- Try methods of self-supervised and semi-supervised learning
- Attempt to generalize for many objects

Train with large amount of data: simulated+experimental data for many objects, extensive data augmentation



Simulated pattern (central part masked out)



Experimental pattern

# Thank you for your attention!

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