

Correction Schemes for Superconducting Undulators

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Introduction

- Planar superconducting undulators commonly require global and local field correction
 - Global field can be present in undulators with iron yoke
 - Local corrections are usually required at the ends
- Local (periodic) errors can be well controlled by precise machining / fabrication of parts but some methods exist for local correction if specifications are difficult to meet
- Overall control of the mechanical structure (undulator gap) is also critical to obtaining low phase error
 LBNL 1.5 m Nb₃Sn Undulator from LCLS-II R&D Program



D. Arbelaez, et al., International Committee for Future Accelerators, Beam Dynamics Newsletter No. 78. 2019



Several examples are shown from LBNL Nb₃Sn SCU Design and testing for 19 mm period undulator with 8.0 mm gap

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Outline

- Basic end design considerations for planar SCUs
 - Saturation effects
 - Local vs. global effects
- End correction schemes
- Local (periodic) correction schemes
- Gap corrections
- Conclusions





Basic End Design Kicks (ideal)



of coil turns is given by the difference in neighboring pole potentials





End Design Including Local End Errors

- Kick and displacement errors at the ends due to non-ideal effects
- Even or Odd number of poles
 - Even zero net steering, non-zero net displacement
 - **o** Odd zero net displacement, non-zero net steering



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Undulator Pole/Core Saturation

- Saturation of the undulator core and poles leads to non-ideal effects
 - Pole saturation changes the local kick strength
 - Pole and core saturation leads to non-ideal global effects



- 2D calculations are shown to demonstrate the principles
- For accurate results 3D calculation must be used

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Global Field Effects



Global field effects are present due to saturation





Global Field Effects Can Scale Unfavorably With Undulator Length

- Magnetic field was calculated with two different length undulators (second one is twice as long) with odd symmetry
- The effect of the end coil corrector is shown

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- Slope of the distributed field scales approximately with 1/L
- Second field integral scales with slope $L^3 \approx L^2$





End Correction Schemes

of coil turns:

1/8, 1/2, 7/8, 1

- Less turns in the pockets at the ends of the undulator
- Corrector coils can be wound in the main coil pockets at the ends
- External dipole kick corrector is usually required since local and global errors may be coupled for co-wound correctors



Y. Ivanyushenkov et al., Phys. Rev. AB. 20, 100701 (2017)

LBNL Nb₃Sn Undulator Example







Example of End Design Approach for LBNL Nb₃Sn Undulator

2 Independent Correctors

• Correction of global field effects

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- 1 corrector (coil at each end wired in series) is used for correction of the global field effect
- $\circ~$ corrector produces both a local kick and a global field
- Correction of local end kick
 - 1 corrector at each end wired independently for entrance and exit kick correction
 - $\circ~$ This correction is decoupled from the main core and produces no global fields
 - Field clamps are included for this corrector in order to avoid interference with nearby magnetic components





Global Field Correction

- Coils are wound in first and last pocket of each core
- Produces a global correction + local kick

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Strength is chosen to cancel only global field error





Local End Kick Correction

- Magnetically decoupled from main undulator core
- Produces only local kicks
- Field clamps are used to minimize stray field
- Compact design (fits under splice joint in Nb₃Sn device)







Measurement Results for End Correctors for LBNL Nb₃Sn Undulator

- Co-wound corrector produces global field when powered
 - Field decreases towards the center of the undulator due to high reluctance path
 - Hysteresis is present and pre-cycle has to be performed to avoid strong second field integral errors
- Kick corrector produces local response and is well decoupled from the undulator

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End Corrector Field Integral





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Local Correction Schemes

- Induction shimming (demonstrated on short undulator) ۲
- Addition of iron pieces in core pockets ۰
- Small coil loops around poles
- **Current loops on vacuum chamber**

Wire Loops Around the Poles



S. Prestemon et al., IEEE TRANS. APPL. SUPERCOND., VOL. 15, NO. 2, JUNE 2005

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Induction Shimming Concept



Additional Iron Pieces Concept



S Chunjarean et al., Supercond. Sci. Technol. 24 (2011) 055013



e-beam

Switch-Based Tuning Concept

• One superconducting path - with heater

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- One resistive path (low resistance)
- When heater is on the superconducting path becomes resistive (high resistance)





Current path via lithography on YBCO Tapes

- Commercial tape from SuperPower Inc.
- Masks designed for photolithography process
- Chemical etching used to remove Copper, Silver, and YBCO layers where desired
- Solderable thin film heaters were developed for efficient and reliable fabrication

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• Laser cutting is used to separate joint section









Full Length Layout Concept

- Correctors are placed on both sides of the vacuum chamber
- Top and bottom correctors are used together
- Drive current on each side of the vacuum chamber
 - $\,\circ\,$ Allows for loops with positive and negative orientation
 - $\circ~$ Return current line is directly below the drive current







Full Length Layout Concept

• Various configurations allow for:

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- $\circ\,$ Increase and decrease in the phase error without introducing a net kick
- $\circ\,$ Positive and negative net kicks without net changes in the phase
- $\,\circ\,$ Individual correctors give both a kick and phase change



Corrector Fabrication

- Process to adhere correctors to the vacuum chamber was developed using vacuum bag process
- Correctors and glue take up 0.2 mm of excess thickness









Correction Method Demonstration

- Local (periodic) correction method using HTS loops was successfully demonstrated
- Independent correction of net phase and trajectory errors was demonstrated
- Correction strength was still sufficient to reduce phase error from 9.2° to 5.4°
 - $\circ \quad \mbox{Due to fabrication issues correctors were only placed on one side of the vacuum chamber (1/2 strength)}$
- Local increase in vacuum chamber temperature did not affect the undulator

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D. Arbelaez et al., Synchrotron Radiation News **31**(3), 9–13 (2018)



Phase Error Correction by Gap Adjustment

- Phase errors can be reduced by mechanical adjustment of the undulator gap
- Method was developed and successfully implemented at APS

$$\Delta P(z_p) = 360^\circ \frac{K^2}{\lambda_u \left(1 + K^2/2\right)} \frac{1}{B_0} \frac{dB}{dg} \int_{z_0}^{z_p} \delta g(z) dz$$

Simulated Effect of Gap Correction for LBNL Nb₃Sn Undulator



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Gap Adjustment Mechanism for APS Undulator



J. Bahrdt, E. Gluskin, Nuclear Inst. and Methods in Physics Research, A 907 (2018) 149–168



Conclusions

- Analysis shows the need for local and global correction
- End corrections can be performed using co-wound and independent kick correctors
- Local (periodic) correction scheme has been developed using HTS loop coils and heater switches
- Precise fabrication and assembly process is essential to obtaining low magnetic field errors





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