Development of a new B-Mapping System for SRF Cavity Vertical Tests.

J. C. Wolff^{1,2}*, A. Goessel¹, W. C. A. Hillert², C. Mueller¹, D. Reschke¹, L. Steder¹ and D. Tischhauser¹ ¹DESY, Hamburg, Germany. ²University of Hamburg – Institute for Experimental Physics, Hamburg, Germany.

ABSTRACT

Magnetic flux trapped in the Niobium bulk material of superconducting radio frequency (SRF) cavities degrades their quality factor and the accelerating gradient. The sensitivity of the surface resistance to trapped magnetic flux is mainly determined by the pre-treatment, the cavity geometry and the Niobium grain size and orientation. To potentially improve the flux expulsion characteristics and hence the efficiency of future accelerator facilities further studies of the

trapping behavior are essential. For this purpose a so-called "B-Mapping System" to monitor the magnetic flux along the outer cavity surface of SRF 1.3 GHz TESLA-Type single-cell cavities is currently under development at DESY. Contrary to former approaches, this system digitizes the sensor signals already inside of the cryostat to extensively reduce the number of required cable feedthroughs.

B-MAPPING-SYSTEM: SIGNAL PROCESSING

SENSOR-BOARD

EVALUATION-BOARD











DESY-sensor-board based on B-Mapping approach at Helmholtz-Zentrum Berlin (HZB) using single axis AMR-sensors of type SENSITEC AFF755B. Sensors are arranged in groups of three to enable spatial magnetic flux measurements.



SYSTEM OPERATED BY **EXTERNAL COMPUTER**

DESIGNED TO COVER FULL SENSOR-

Effective Number Of Bits (ENOB): 18

SIGNAL RESOLUTION:

(f_s: 50 Hz; Gain: 1)

- **3** AMR-sensors per sensor-group (Group)
- 9 sensor-groups per sensor-board
- **48** sensor-boards \leftrightarrow **48** evaluation-boards
- Σ 1296 sensors or 432 sensor-groups

SENSOR SIGNALS DIGITIZED INSIDE OF CRYOSTAT:

- extensively reduced number of feedthroughs
- shorter analog signal lines
- reduced thermal noise

SYSTEM OVERVIEW:

 \rightarrow enhanced signal-to-noise ratio (SNR)





CONCLUSION

A new approach of a "B-Mapping System" digitizing the differential sensor signals already

SYSTEM CALIBRATION

RESIDUAL BACKGROUND FIELD:

X-AMR-Sensor - Group 1

systom	operated with a toggling	
Κνειρπ		

SENSOR CALIBRATION:

sensor included test coils used





for calibration:

 \rightarrow linear fit to a coil current rise of **0 – 200 mA** (stepw.: **5 mA**)

high component spread possible according to datasheet:

value evaluated by HZB: (0.249 ± 0.12) µT/mA used for [DOI: 10.1063/1.5030509]

inside of the cryostat was developed and successfully tested DESY. The system at improves the vertical test environment and enables spatial measurements of the magnetic flux along the outer surface of 1.3 GHz TESLA-Type cavities even without an applied stray field. To improve the accuracy of the AMRsensor calibration the series connection of the test coils will be separated into independent lines for each axis. Thereby the stray impact from other test coils can be reduced.

* Jonas.Wolff@desy.de

This work was supported by the Helmholtz Association within the topic Accelerator Research and Development (ARD) of the Matter and Technologies (MT) Program.







