

# ALPIDE staves in vacuum?

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# Possible issues

- ◉ **Outgassing:**

- ◉ all the stave components will outgas when we pull the vacuum the first time.
- ◉ outgassing will cause a shrinkage/deformation of the structure whose entities is typically contained and should not affect the structural behaviour, but could have some impact on the sensor position.
- ◉ Some additional precaution should be taken during assembly to minimise humidity absorption (bake-out of the carbon before gluing chip and HIC, keep the full stave in an humidity controlled environment)

- ◉ **Cooling water leaks:**

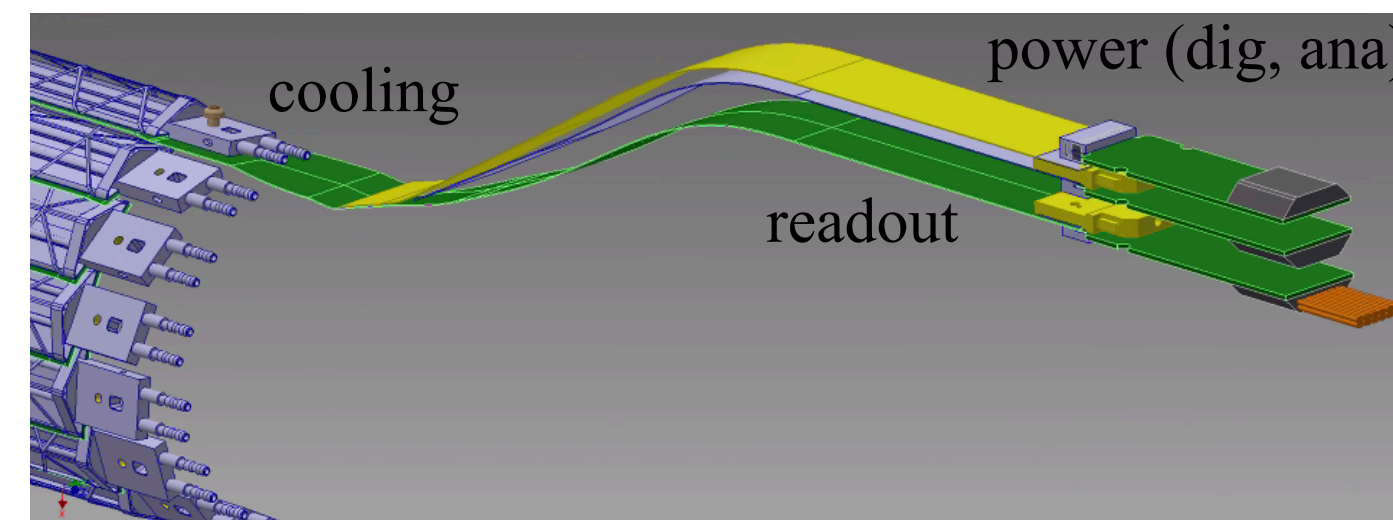
- ◉ we didn't discuss this in detail but we should plan to use a water leak-less system as in ALICE.
  - ◉ the pressure inside the cooling tube is lower than atmospheric such that if you have a failure you do not spill water outside but instead you'll suck air inside the tubes.
- ◉ in vacuum even if we'll have a lower-than-atmospheric pressure inside the tube, we'll still spill water in the system in case of a leak

- ◉ **Buckling:**

- ◉ in ALICE the pipes are subjected to a pressure from outside to inside, leading to possible buckling of the Kapton pipe wall.
- ◉ in case of operation in vacuum the pressure will be from inside to outside (no buckling, better)
- ◉ the tubes have been tested up to 50 bar

- ◉ **Feedthrough(s)**

- ◉ will need at least 4 customised feedthroughs from each side of the tracker
  - ◉ each stave has 1 readout + 2 power flex flat cables + cooling I/O
  - ◉ staves are bundled in pairs together (along one layer)



- ◉ **Movability:** only when chamber is open since we ditched the remotely-controlled hexapod idea

# Tracker's services

