

# *Improved (iterative) Bayesian unfolding*

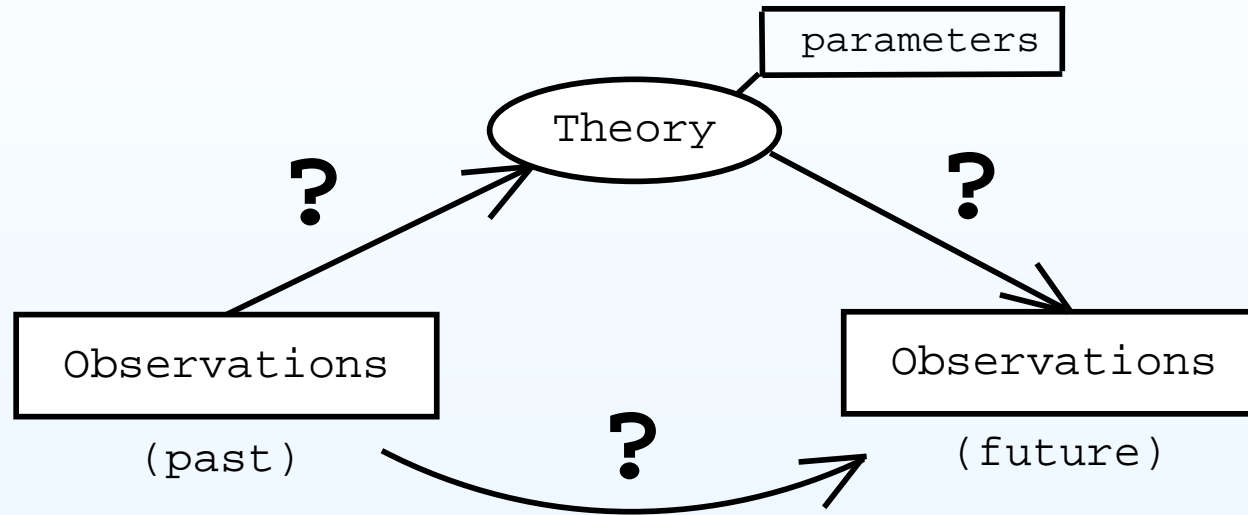
Giulio D'Agostini

University and INFN Section of "Roma1"

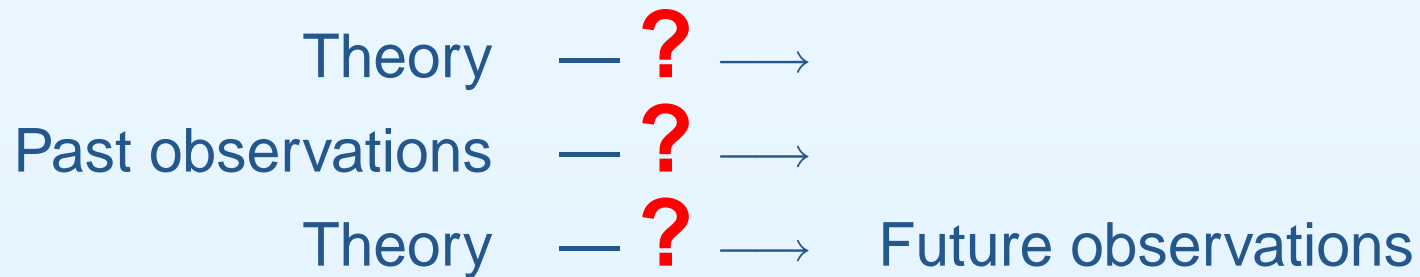
# Outline

- Learning from data the probabilistic way
  - Causes  $\longleftrightarrow$  Effects
    - “The essential problem of the experimental method” (Poincaré).*
  - Graphical representation of probabilistic links
  - Learning about causes from their effects
- Parametric inference Vs unfolding
- From principles to real life... [the iteration ‘dirty trick’]
- The old code and its weak point
- Improvements:
  - use (conjugate) pdf’s insteads of just ‘estimates’
  - uncertainty evaluated by general rules of probability (instead of ‘error propagation’ formulae)
    - $\Rightarrow$  integrals over the weighted possibilities  $\rightarrow$  MC
- Some examples on toy models

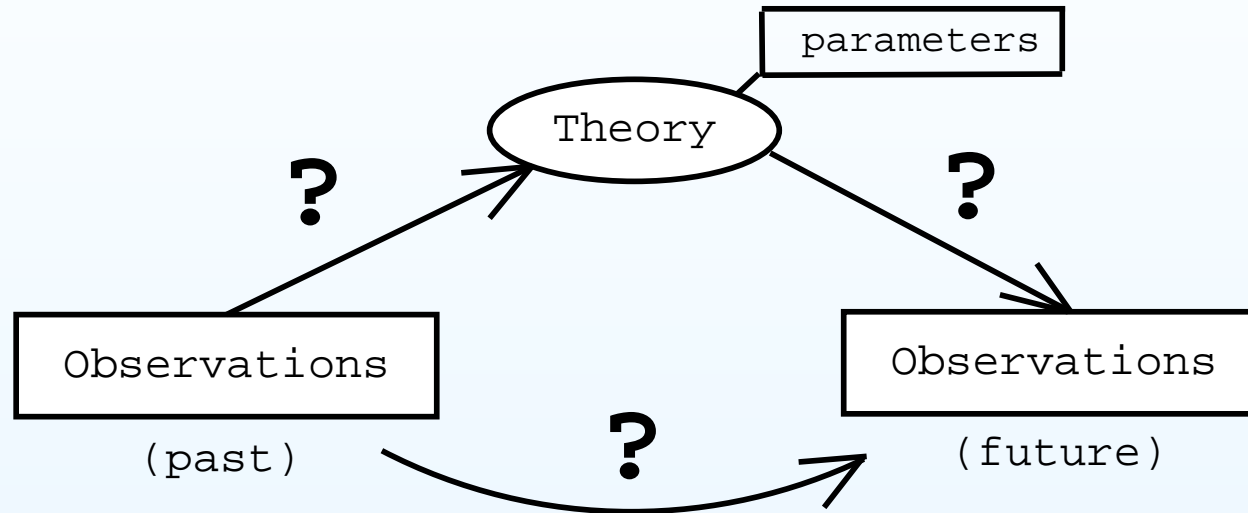
# Learning from experience and source of uncertainty



Uncertainty:



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## Uncertainty:

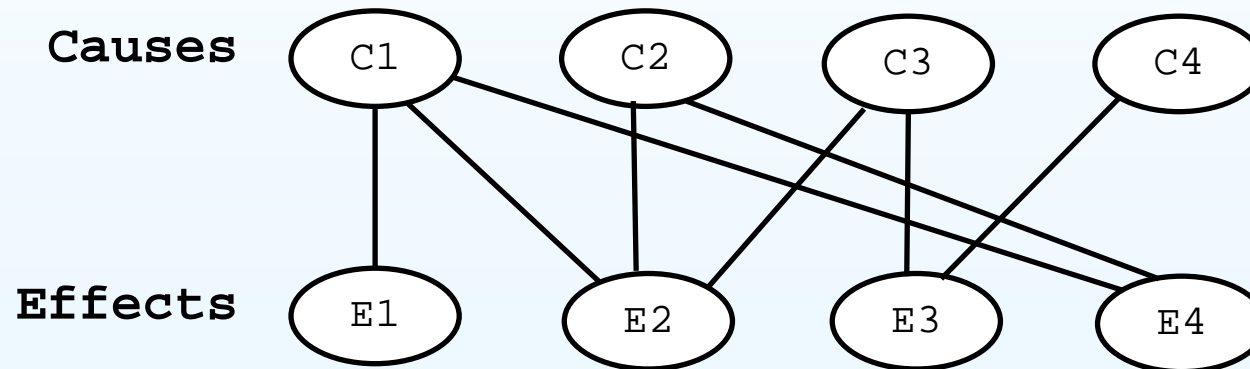
Theory — ? —> Future observations  
Past observations — ? —> Theory  
Theory — ? —> Future observations

⇒ **Uncertainty about causal connections**

**CAUSE ⇔ EFFECT**

## Causes → effects

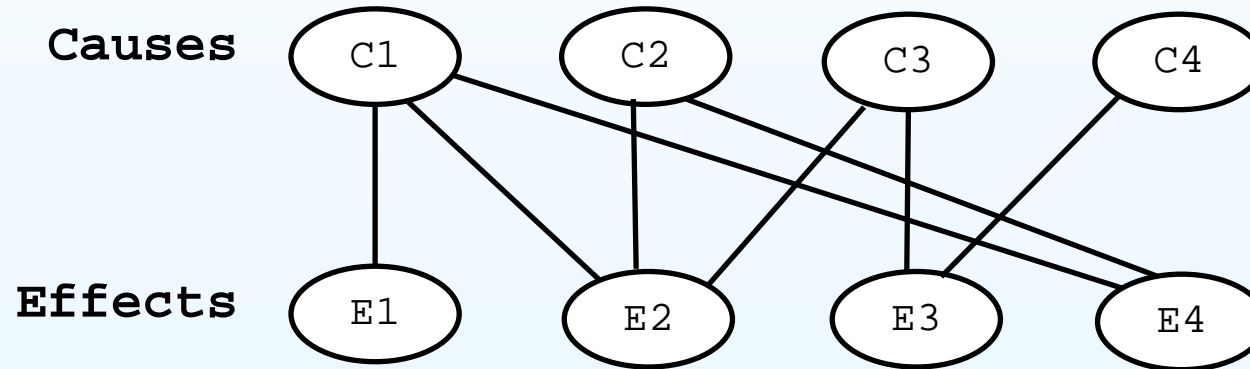
The same *apparent* cause might produce several, different effects



Given an observed effect, we are not sure about the exact cause that has produced it.

## Causes → effects

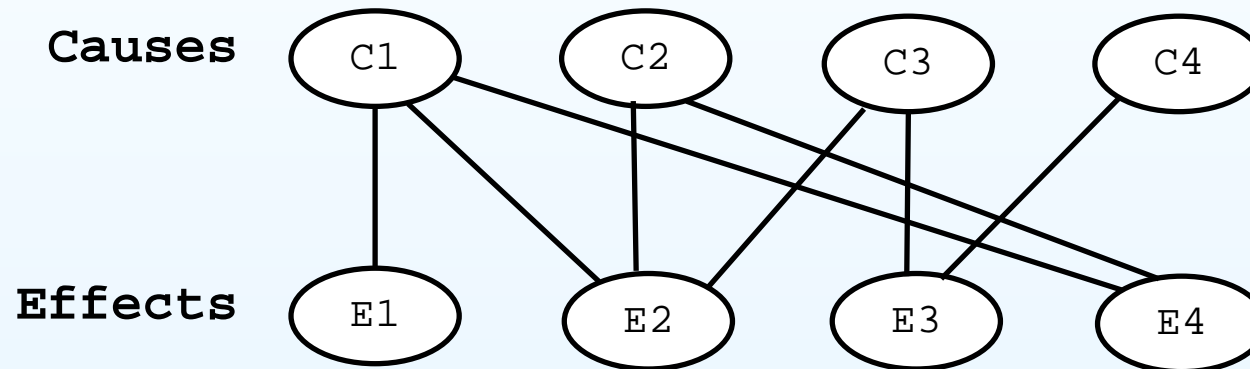
The same *apparent* cause might produce several, different **effects**



Given an **observed effect**, we are not sure about the **exact cause** that has produced it.

## Causes → effects

The same *apparent* cause might produce several, different effects



Given an observed effect, we are not sure about the exact cause that has produced it.

$$E_2 \Rightarrow \{C_1, C_2, C_3\}?$$

## The essential problem of the experimental method

---

“Now, these problems are classified as *probability of causes*, and are most interesting of all their scientific applications. I play at *écarté* with a gentleman whom I know to be perfectly honest. What is the chance that he turns up the king? It is  $1/8$ . This is a problem of the *probability of effects*.



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I play with a gentleman whom I do not know. He has dealt ten times, and he has turned the king up six times. What is the chance that he is a sharper? This is a problem in the probability of causes. It may be said that **it is the essential problem of the experimental method.**”

(H. Poincaré – *Science and Hypothesis*)

## Uncertainty and probability

We, as physicists, consider absolutely natural and meaningful statements of the following kind

- $P(-10 < \epsilon'/\epsilon \times 10^4 < 50) \gg P(\epsilon'/\epsilon \times 10^4 > 100)$
- $P(170 \leq m_{top}/\text{GeV} \leq 180) \approx 70\%$
- $P(M_H < 200 \text{ GeV}) > P(M_H > 200 \text{ GeV})$

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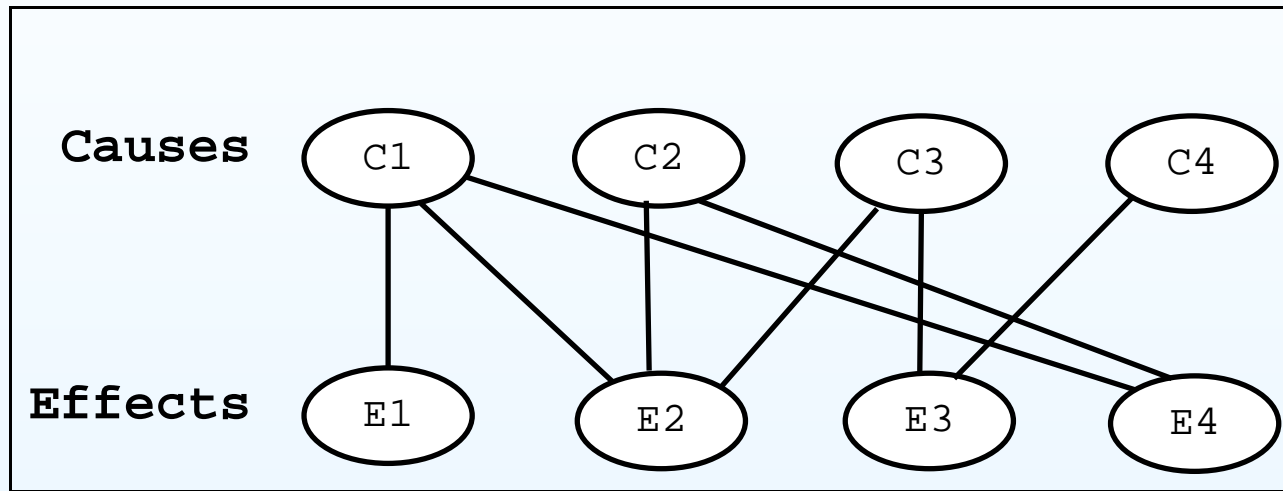
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I **stick to common sense** (and physicists common sense) and assume that probabilities of causes, probabilities of hypotheses, probabilities of the numerical values of physics quantities, etc. are **sensible concepts that match the mind categories of human beings**

(see D. Hume, C. Darwin + modern researches)

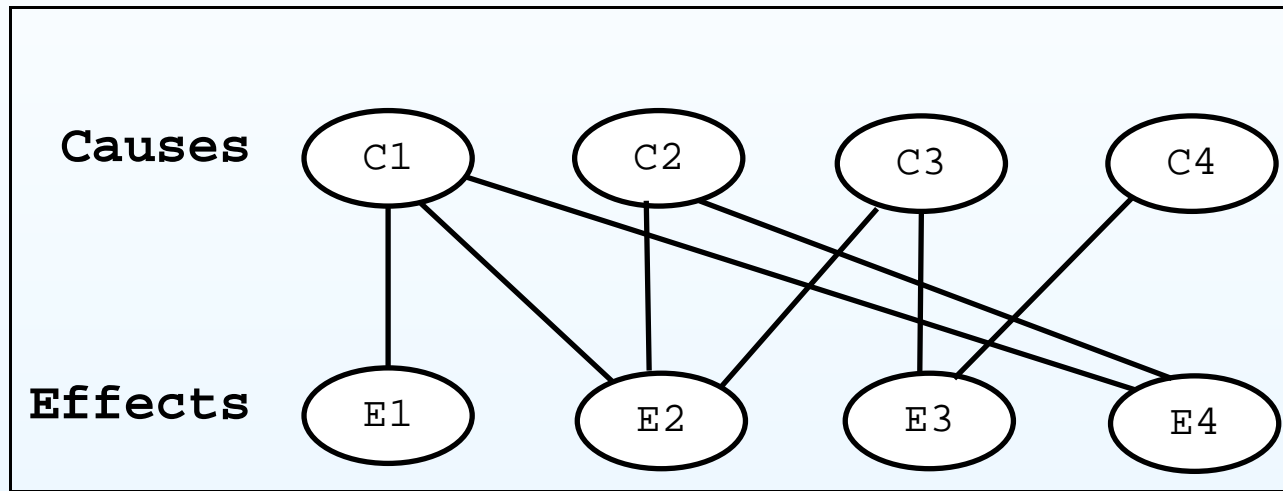
# From causes to effects and back

Our original problem:



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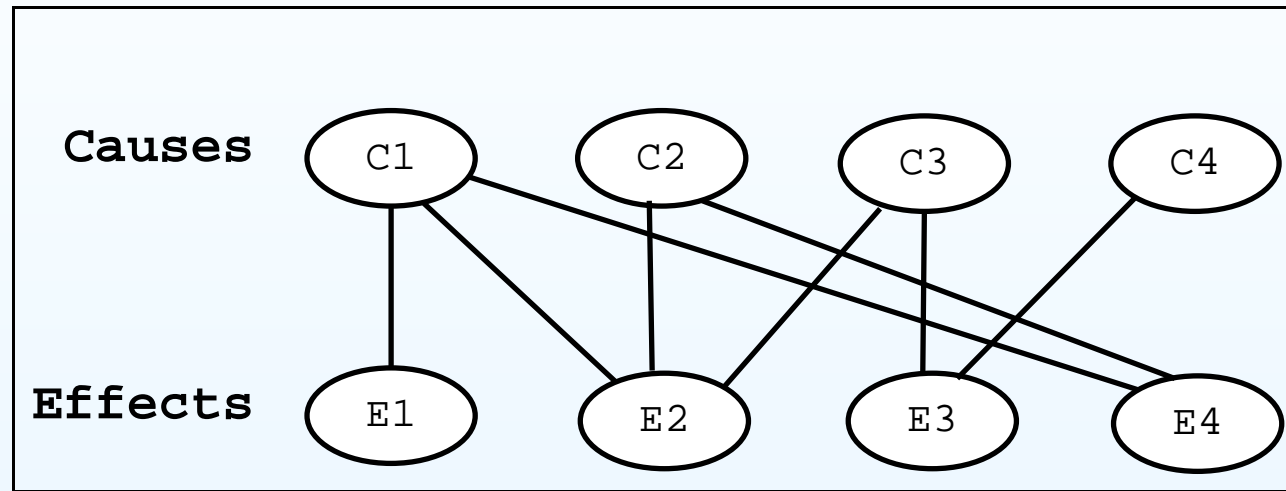


Our conditional view of probabilistic causation

$$P(E_i | C_j)$$

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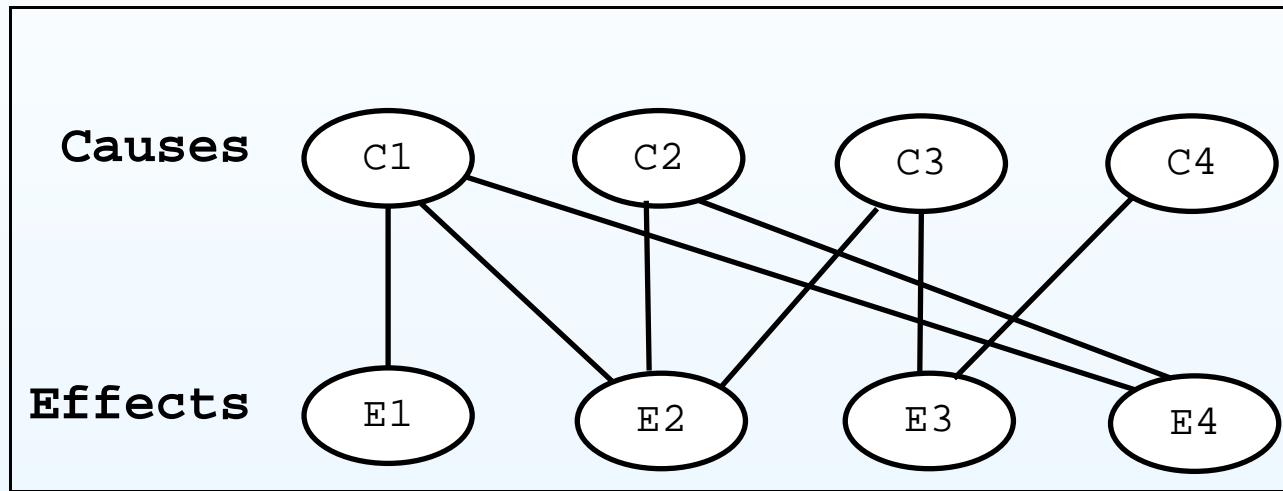
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Our conditional view of probabilistic inference

$$P(C_j | E_i)$$

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Our conditional view of probabilistic causation

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The fourth basic rule of probability:

$$P(C_j, E_i) = P(E_i | C_j) P(C_j) = P(C_j | E_i) P(E_i)$$



## Symmetric conditioning

Let us take **basic rule 4**, written in terms of hypotheses  $H_j$  and effects  $E_i$ , and rewrite it this way:

$$\frac{P(H_j | E_i)}{P(H_j)} = \frac{P(E_i | H_j)}{P(E_i)}$$

*“The condition on  $E_i$  changes in percentage the probability of  $H_j$  as the probability of  $E_i$  is changed in percentage by the condition  $H_j$ .”*

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Got ‘after’

Calculated ‘before’

(where ‘before’ and ‘after’ refer to the knowledge that  $E_i$  is true.)

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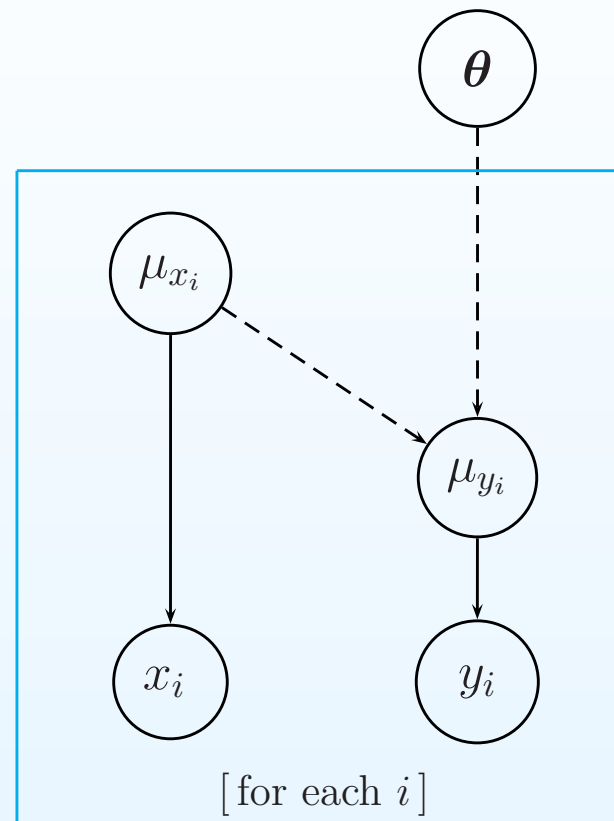
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⇒ Bayes theorem

## A different way to view fit issues



- Deterministic link  $\mu_x$ 's to  $\mu_y$ 's
  - Probabilistic links  $\mu_x \rightarrow x, \mu_y \rightarrow y$
- $\Rightarrow$  aim of fit:  $\{x, y\} \rightarrow \theta \Rightarrow f(\theta | \{x, y\})$

## Parametric inference Vs unfolding

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$$f(\boldsymbol{\theta} | \{\boldsymbol{x}, \boldsymbol{y}\}):$$

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$f(\theta | \{x, y\})$ :

probabilistic parametric inference

⇒ it relies on the kind of functions parametrized by  $\theta$

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BUT sometimes we wish to interpret the data as little as possible

⇒ just public ‘something equivalent’ to an experimental distribution, with the bin contents fluctuating according to an underlying multinomial distribution, but having possibly got rid of physical and instrumental distortions, as well as of background.

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⇒ **Unfolding** (deconvolution)

## Why unfolding?

The idea is to provide something similar to an experimental spectrum, with a minimal interpretation by the experimentalist, a part from correcting from distortions due to physics and detector effects (including background).

(The alternative would be to give a parametrized description of the true spectrum – a fit)

## Smearing matrix $\rightarrow$ unfolding matrix

Invert smearing matrix?

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Invert smearing matrix?

In general is a **bad idea**:

not a rotational problem

but an inferential problem!

## Smearing matrix $\rightarrow$ unfolding matrix

---

Imagine  $S = \begin{pmatrix} 0.8 & 0.2 \\ 0.2 & 0.8 \end{pmatrix}$ :  $\rightarrow U = S^{-1} = \begin{pmatrix} 1.33 & -0.33 \\ -0.33 & 1.33 \end{pmatrix}$

Let the true be  $s_t = \begin{pmatrix} 10 \\ 0 \end{pmatrix}$ :  $\rightarrow s_m = S \cdot s_t = \begin{pmatrix} 8 \\ 2 \end{pmatrix}$ ;

If we measure  $s_m = \begin{pmatrix} 8 \\ 2 \end{pmatrix} \rightarrow S^{-1} \cdot s_m = \begin{pmatrix} 10 \\ 0 \end{pmatrix}$  ✓

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**BUT**

if we had measured  $\begin{pmatrix} 9 \\ 1 \end{pmatrix} \rightarrow S^{-1} \cdot s_m = \begin{pmatrix} 11.7 \\ -1.7 \end{pmatrix}$

if we had measured  $\begin{pmatrix} 10 \\ 0 \end{pmatrix} \rightarrow S^{-1} \cdot s_m = \begin{pmatrix} 13.3 \\ -3.3 \end{pmatrix}$

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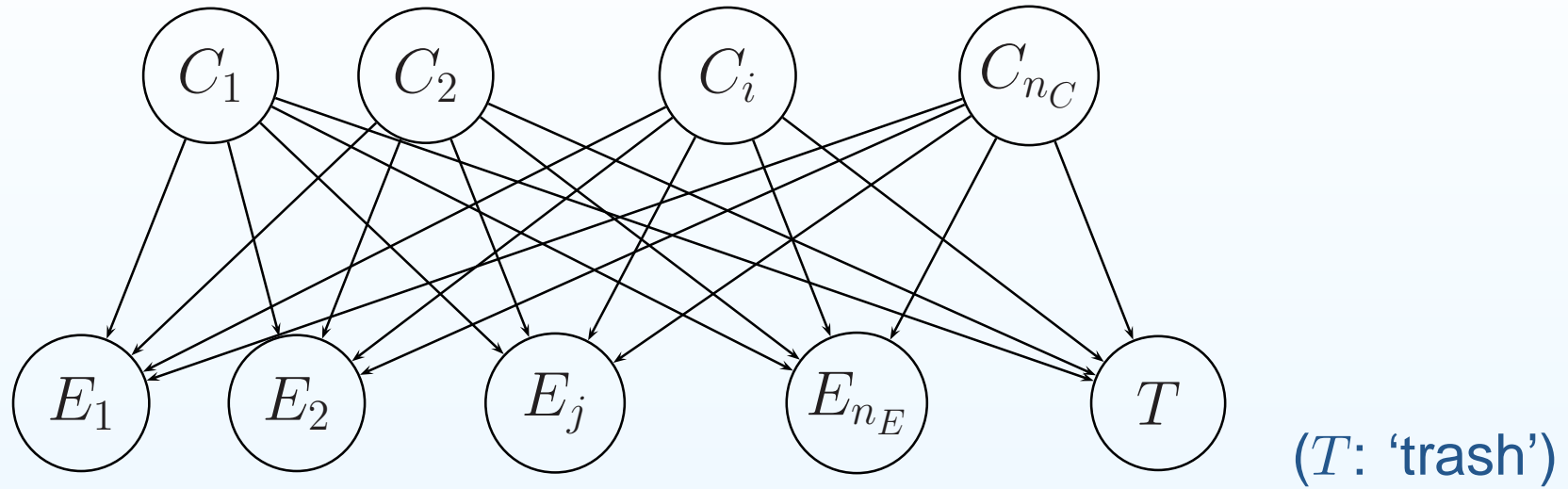
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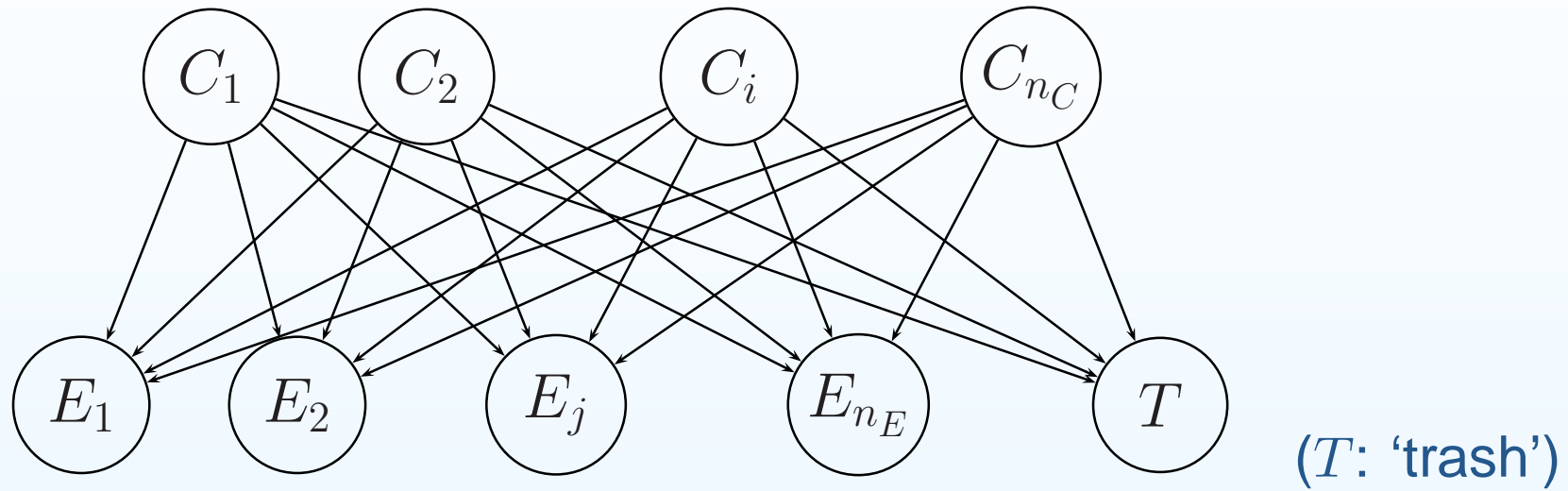
Indeed, matrix inversion is recognized to producing ‘crazy spectra’ and even negative values (unless such large numbers in bins such fluctuations around expectations are negligible)



## Discretized unfolding



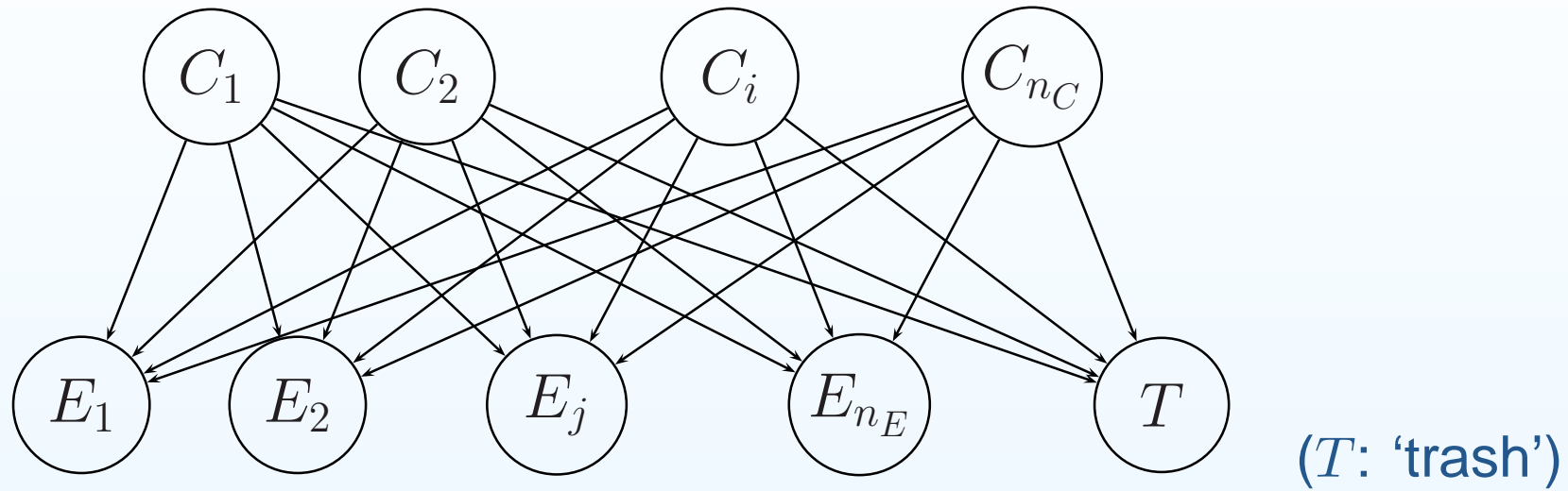
## Discretized unfolding



$x_C$ : true spectrum (nr of events in cause bins)

$x_E$ : observed spectrum (nr of events in effect bins)

## Discretized unfolding



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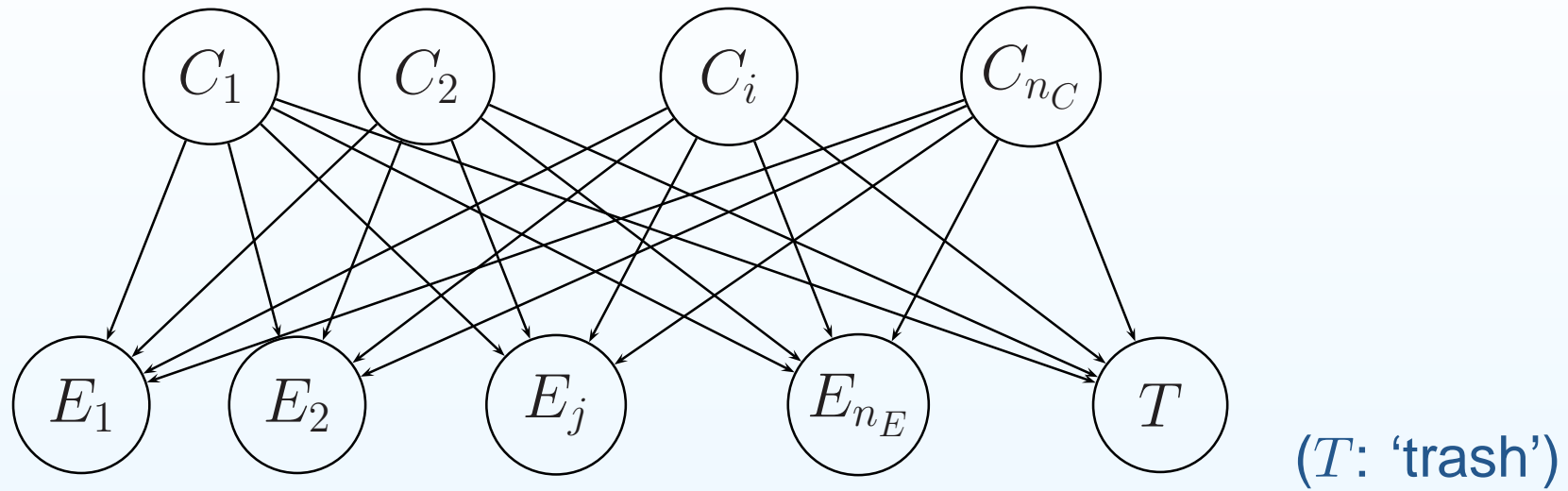
$\mathbf{x}_E$ : observed spectrum (nr of events in effect bins)

**Our aim:**

- **not** to find *the* true spectrum
- but, **more modestly**, rank in beliefs all possible spectra that might have caused the observed one:

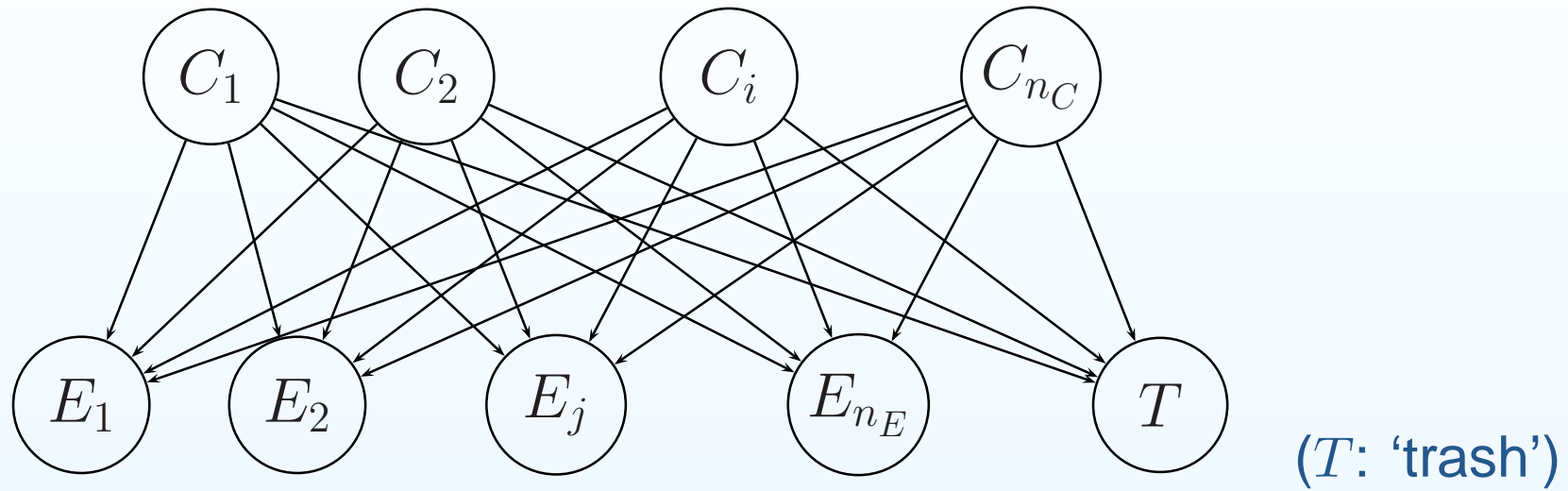
$$\Rightarrow P(\mathbf{x}_C | \mathbf{x}_E, I)$$

## Discretized unfolding



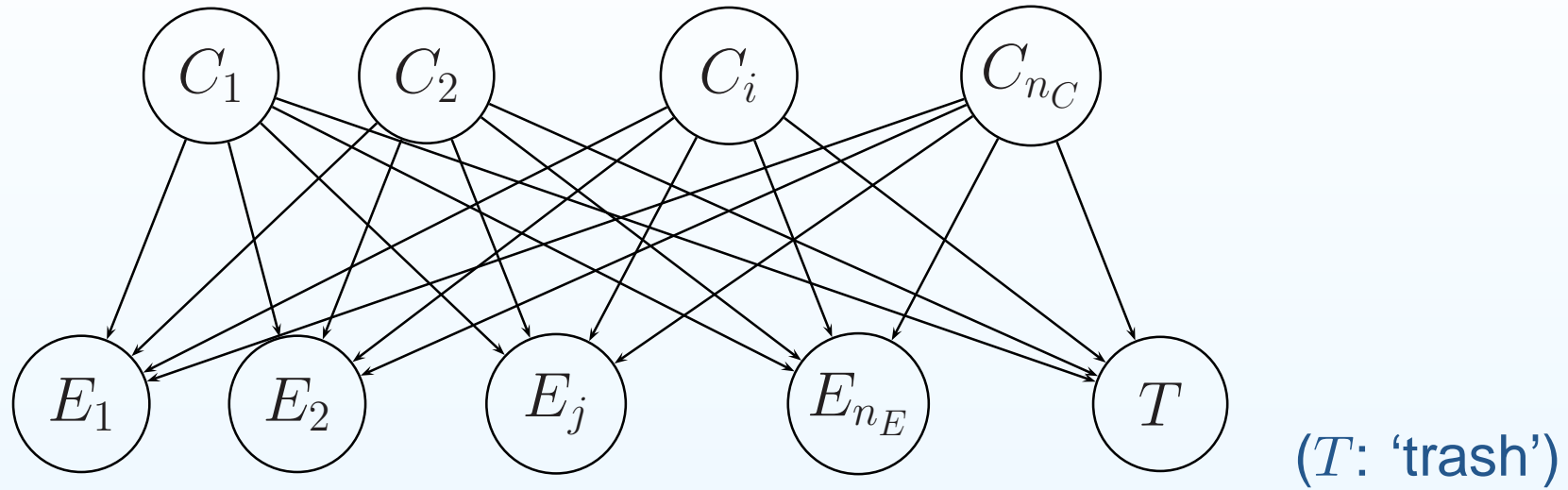
- $P(\mathbf{x}_C | \mathbf{x}_E, I)$  depends on the knowledge of *smearing matrix*  $\Lambda$ , with  $\lambda_{ji} \equiv P(E_j | C_i, I)$ .

## Discretized unfolding



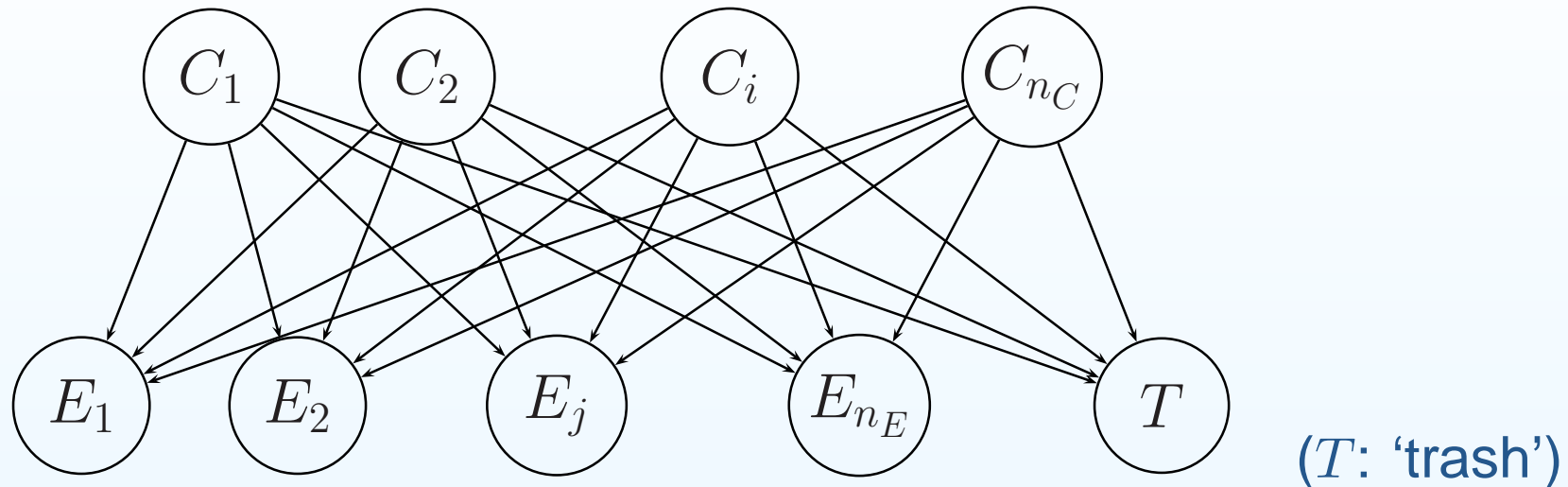
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 $\Rightarrow f(\Lambda | I)$

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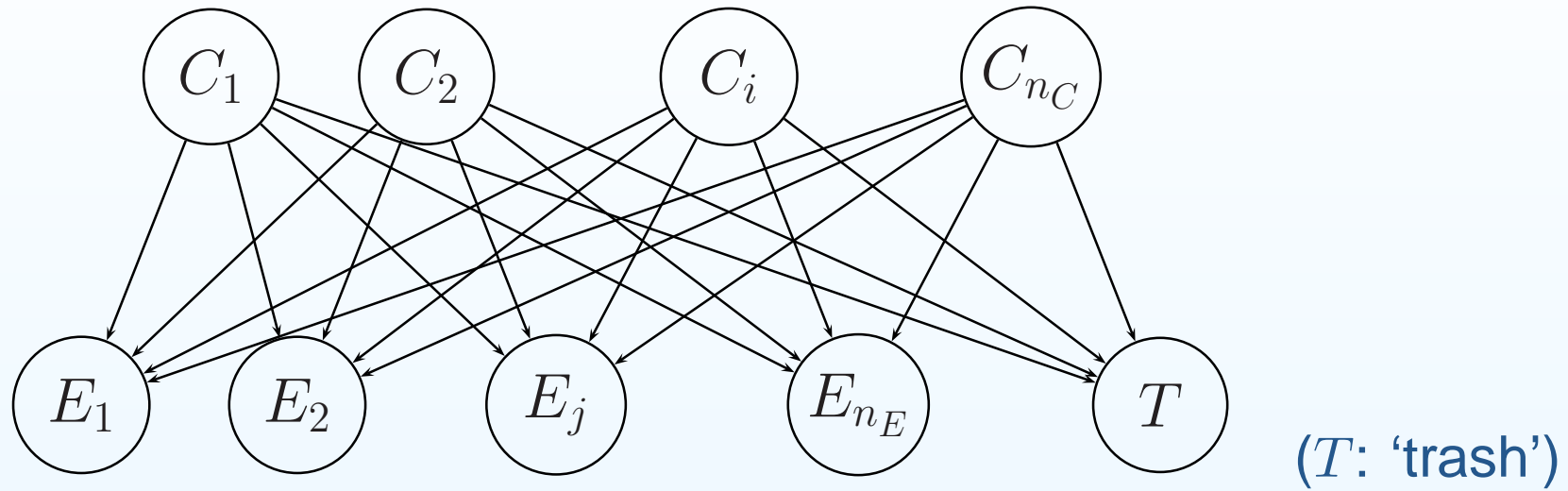
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- for each possible  $\Lambda$  we have a pdf of spectra:  
 $\rightarrow P(\mathbf{x}_C | \mathbf{x}_E, \Lambda, I)$

## Discretized unfolding



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- for each possible  $\Lambda$  we have a pdf of spectra:  
 $\rightarrow P(\mathbf{x}_C | \mathbf{x}_E, \Lambda, I)$   
 $\Rightarrow P(\mathbf{x}_C | \mathbf{x}_E, I) = \int P(\mathbf{x}_C | \mathbf{x}_E, \Lambda, I) f(\Lambda | I) d\Lambda$  [by MC!]

## Discretized unfolding

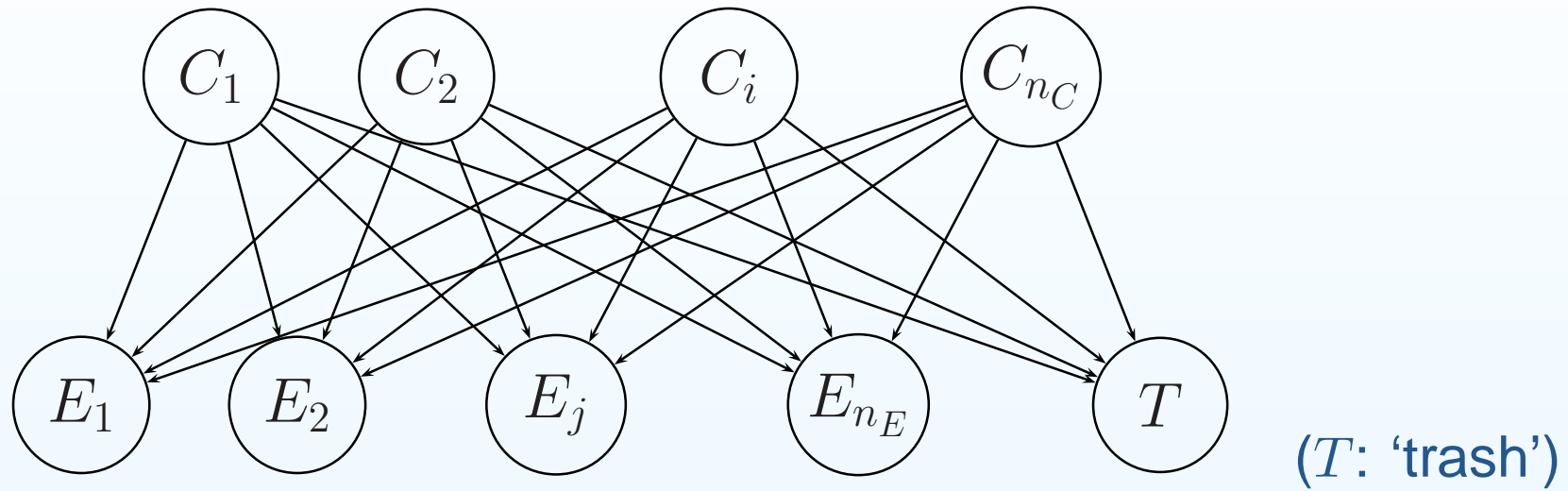


- Bayes theorem:

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## Discretized unfolding



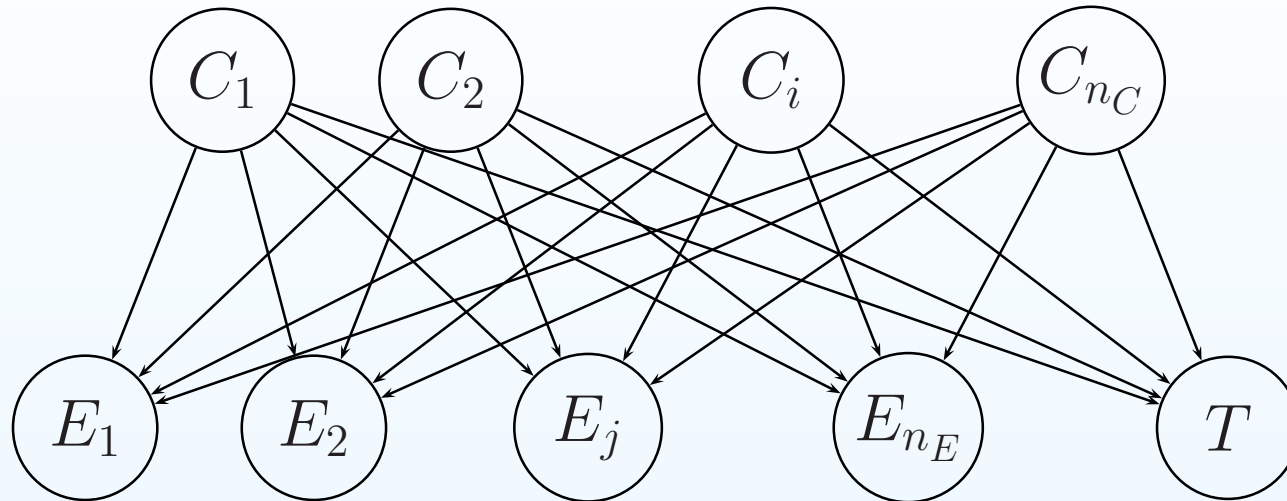
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- Indifference **w.r.t. all possible spectra**

$$P(\mathbf{x}_C | \mathbf{x}_E, \Lambda, I) \propto P(\mathbf{x}_E | \mathbf{x}_C, \Lambda, I)$$

$$\underline{P(\mathbf{x}_E \mid x_{C_i}, \Lambda, I)}$$



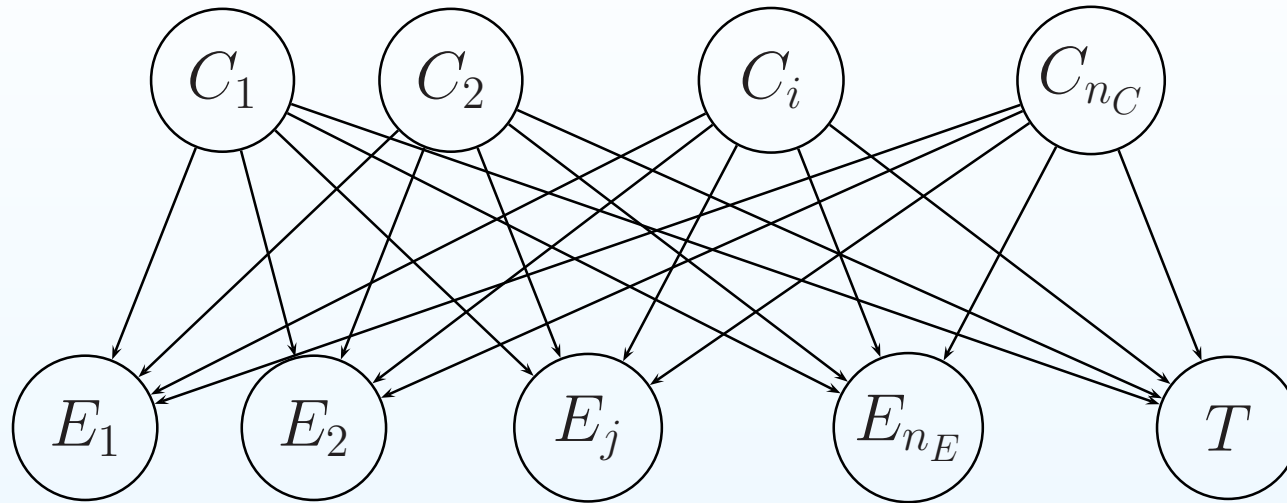
Given a certain number of events in a cause-bin  $x(C_i)$ , the number of events in the effect-bins, included the ‘trash’ one, is described by a multinomial distribution:

$$\mathbf{x}_E \mid x(C_i) \sim \text{Mult}[x(C_i), \boldsymbol{\lambda}_i],$$

with

$$\begin{aligned} \boldsymbol{\lambda}_i &= \{\lambda_{1,i}, \lambda_{2,i}, \dots, \lambda_{n_E+1,i}\} \\ &= \{P(E_1 \mid C_i, I), P(E_2 \mid C_i, I), \dots, P(E_{n_E+1,i} \mid C_i, I)\} \end{aligned}$$

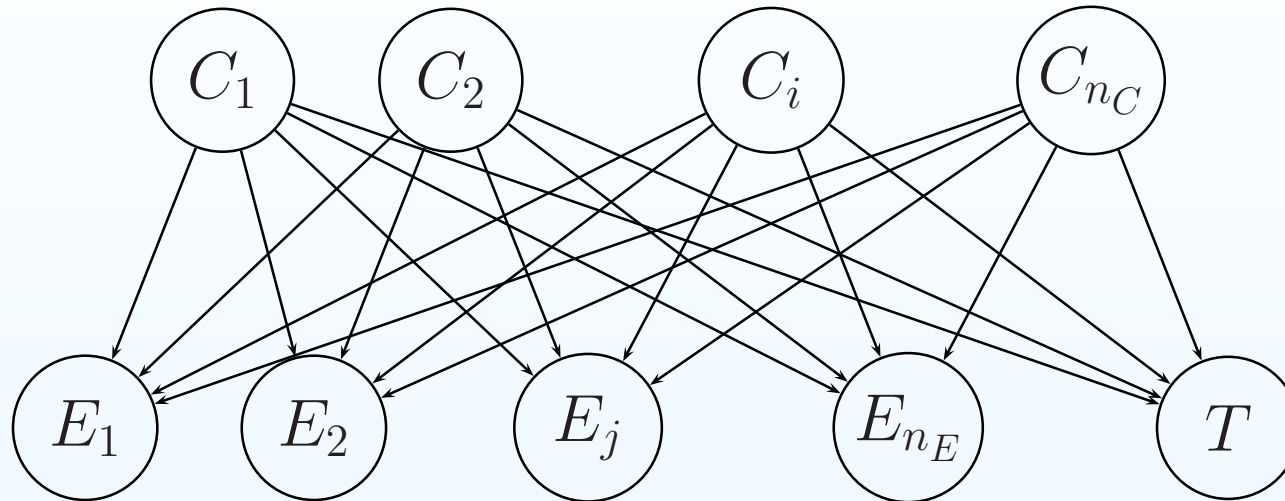
$$P(\mathbf{x}_E \mid \mathbf{x}_C, \Lambda, I)$$



$\mathbf{x}_{E|x(C_i)}$  multinomial random vector,

$\Rightarrow \mathbf{x}_{E|x(C)}$  **sum of several multinomials.**

$$P(\mathbf{x}_E \mid \mathbf{x}_C, \Lambda, I)$$



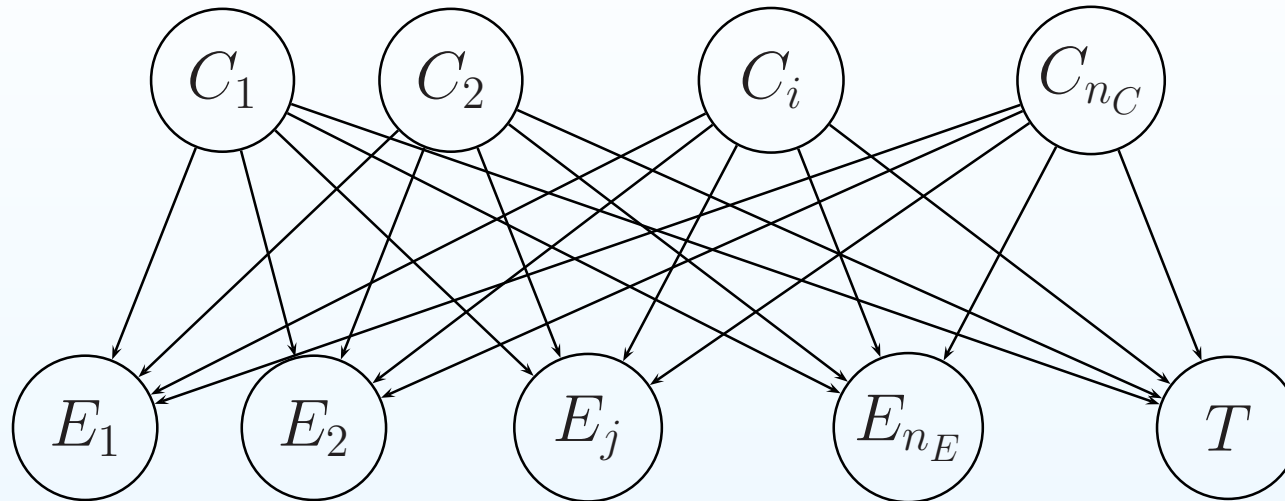
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**BUT**

**no 'easy' expression for  $P(\mathbf{x}_E \mid \mathbf{x}_C, \Lambda, I)$**

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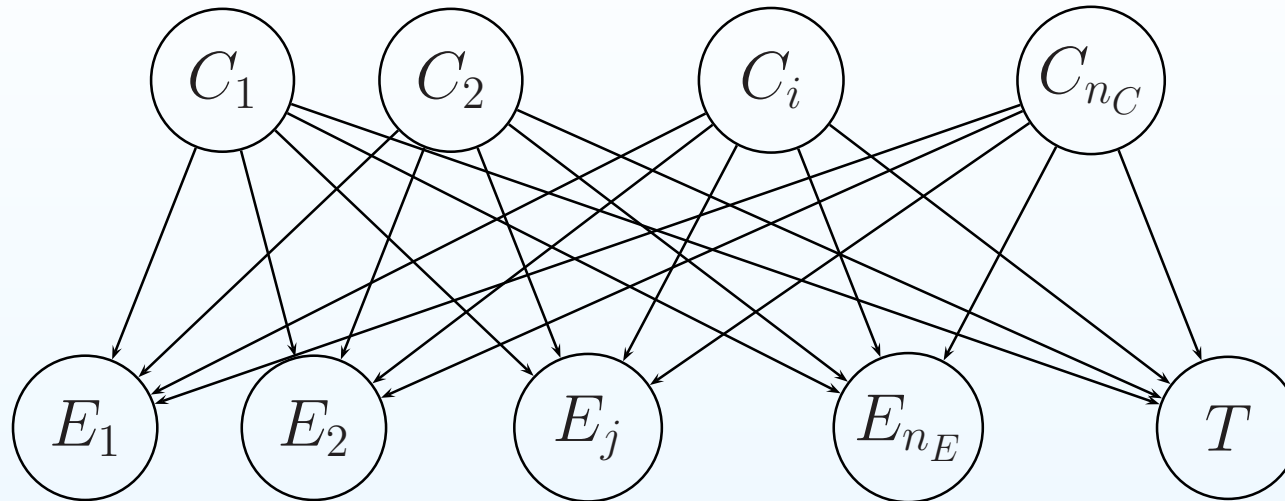
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**$\Rightarrow$  STUCK!**

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**no 'easy' expression for  $P(\mathbf{x}_E \mid \mathbf{x}_C, \Lambda, I)$**

$\Rightarrow$  **STUCK!**

$\Rightarrow$  Change strategy

## The rescue trick

Instead of using the original probability inversion  
(applied directly) to spectra

$$P(\mathbf{x}_C | \mathbf{x}_E, \Lambda, I) \propto P(\mathbf{x}_E | \mathbf{x}_C, \Lambda, I) \cdot P(\mathbf{x}_C | I),$$

we restart from

$$P(C_i | E_j, I) \propto P(E_j | C_i, I) \cdot P(C_i | I).$$

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## Old algorithm

---

1. [\*]  $\lambda_{ij}$  estimated by MC simulation as

$$\lambda_{ji} \approx x(E_j)^{MC} / x(C_i)^{MC} ;$$

## Old algorithm

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$$\lambda_{ji} \approx x(E_j)^{MC} / x(C_i)^{MC} ;$$

2.  $P(C_i | E_j, I)$  from Bayes theorem;  $[\theta_{ij} \equiv P(C_i | E_j, I)]$

$$P(C_i | E_j, I) = \frac{P(E_j | C_i, I) \cdot P(C_i | I)}{\sum_i P(E_j | C_i, I) \cdot P(C_i | I)},$$

or

$$\theta_{ij} = \frac{\lambda_{ji} \cdot P(C_i | I)}{\sum_i \lambda_{ji} \cdot P(C_i | I)},$$

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4. [\*] Uncertainty by ‘standard error propagation’

## Improvements

1.  $\lambda_i$ : having each element  $\lambda_{ji}$  the meaning of “ $p_j$ ” of a **Multinomial** distribution, their distribution can easily (and conveniently and realistically) modelled by a **Dirichlet**:

$$\lambda_i \sim \text{Dir}[\alpha_{prior} + \mathbf{x}_E^{MC} |_{x(C_i)^{MC}}],$$

(The Dirichlet is the **prior conjugate** of the Multinomial)

## Improvements

1.  $\lambda_i$ :

$$\lambda_i \sim \text{Dir}[\alpha_{\text{prior}} + \mathbf{x}_E^{MC} |_{x(C_i)^{MC}}],$$

2. uncertainty on  $\lambda_i$ :

taken into account by sampling  $\Rightarrow$  equivalent to integration

$$\Rightarrow P(\mathbf{x}_C | \mathbf{x}_E, I) = \int P(\mathbf{x}_C | \mathbf{x}_E, \Lambda, I) f(\Lambda | I) d\Lambda$$



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4.  $x(E_j) \rightarrow \mu_j$ : what needs to be shared is not the observed number  $x(E_j)$ , but rather the estimated true value  $\mu_j$ :  
remember  $x(E_j) \sim \text{Poisson}[\mu_j]$

$$\mu_j \sim \text{Gamma}[c_j + x(E_j), r_j + 1],$$

(Gamma is prior conjugate of Poisson)

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**BUT**  $\mu_i$  is real, while the the **number of event parameter** of a multinomial must be integer  $\Rightarrow$  solved with interpolation

5. uncertainty on  $\mu_i$ : taken into account by sampling

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- Empirical approach (with help of simulation):
  - ‘True spectrum’ recovered in a couple of steps
  - Then the solution starts to **diverge** towards a **wildy oscillating spectrum** (any unavoidable fluctuation is believed more and more...)
    - ⇒ find empirically an optimum



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- intermediate smoothing ⇒ **we believe physics is 'smooth'**
- ... but 'irregularities' of the data are not washed out  
(⇒ unfolding Vs parametric inference)

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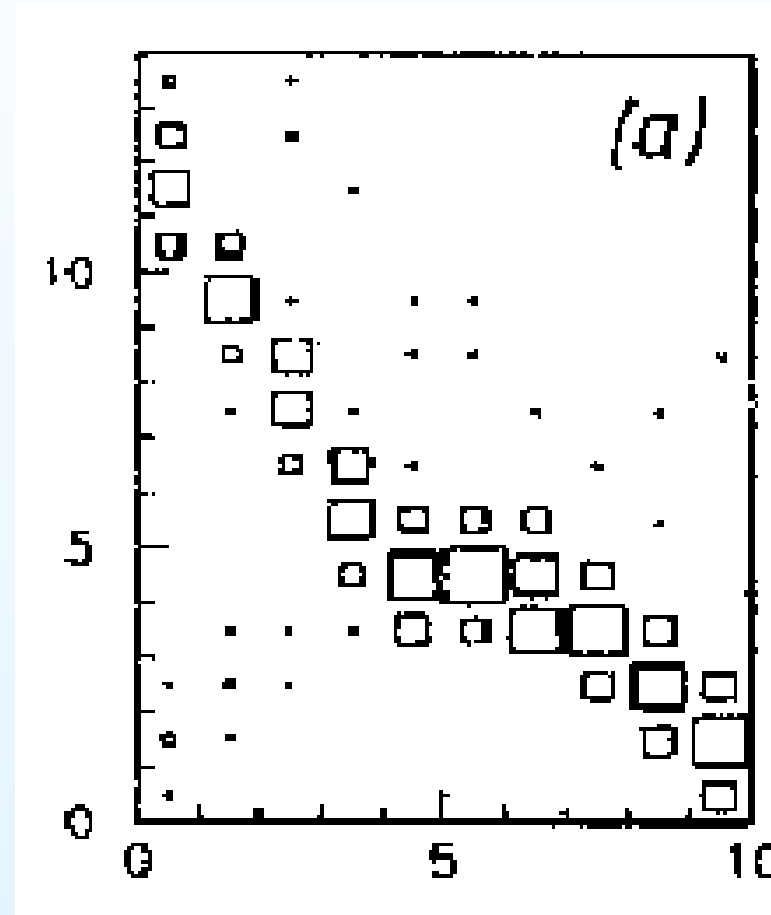
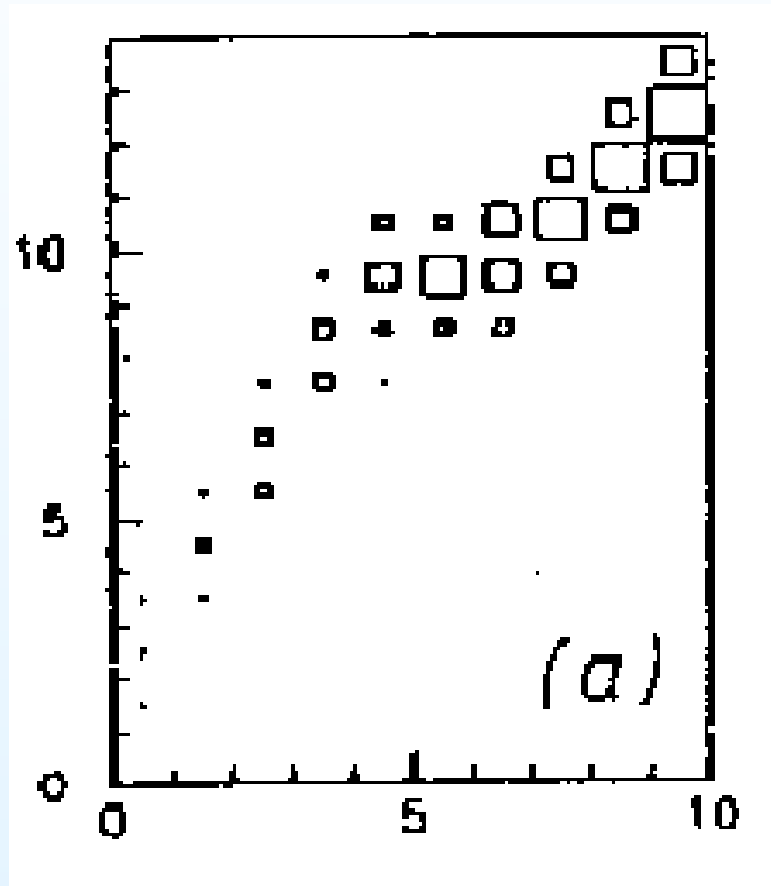
⇒ Good compromise and good results

⇒ Very 'Bayesian'

⇒ No oscillations for  $n_{steps} \rightarrow \infty$

## Examples

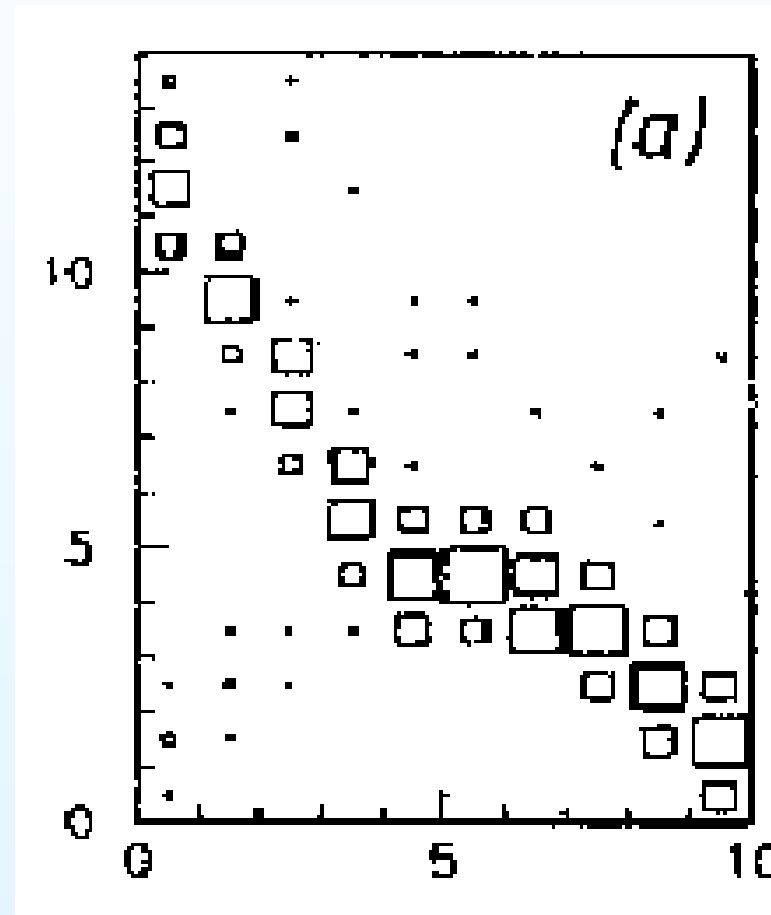
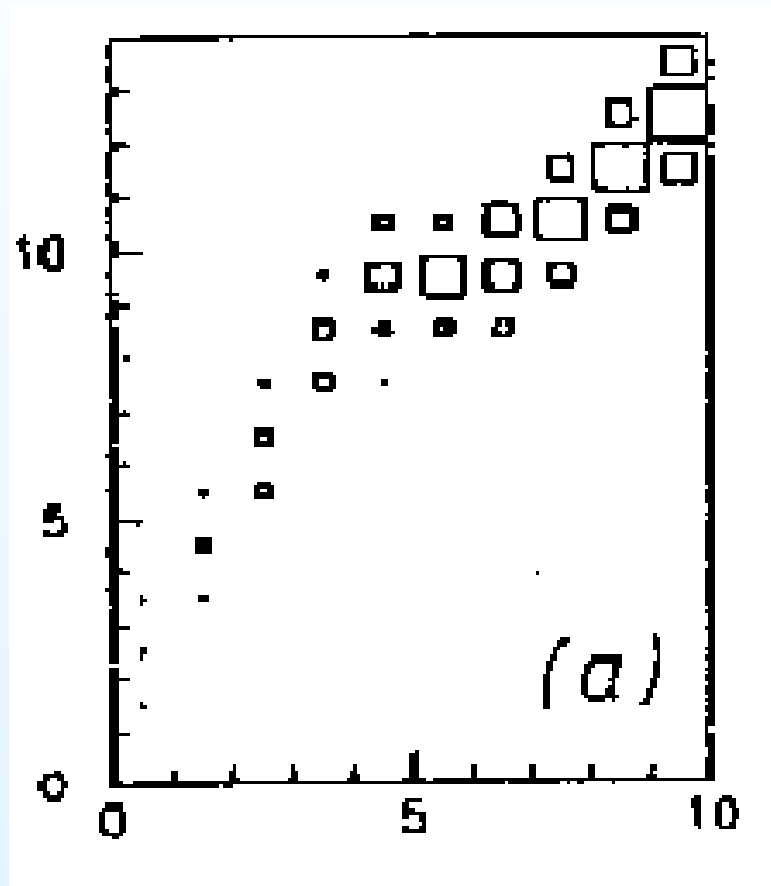
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⇒ watch DEMO

## Conclusions

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→ Some notes follow ⇒

## Notes added

1. “iterative” put within parentheses in title  
(motivated by Zech’ classification of methods)
  - (a) the spirit of the method is Bayesian
  - (b) the iteration issue is secondary

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2. An interesting book:  
(thanks to Blobel)
  - J. Kaipio and E. Somersalo  
Statistical and Computational Inverse Problems  
Springer, 2004

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2. An interesting book:
3. Uncertainty due the possible choice among several smearing models,  $\Lambda_1$ ,  $\Lambda_2$ , etc.  
(triggered by Marisa Sandhoff’s talk)
  - the  $\theta_i$  sampling can be done at random from either matrix,  
with weights depending on our beliefs in the different unfolding models  
(obviously not yet implemented in the R code, and I am not sure I will do it, but it can be implemented in C/C++ versions)

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GdA, NIM A362 (1995) 487

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⇒ just a honest statement: what is wrong with it?

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**Buon divertimento!**