# Unfolding A Statistics Group Project

Gero Flucke DESY



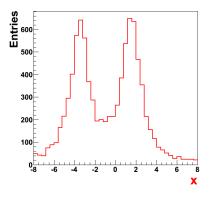


4th Annual Workshop of the Helmholtz Alliance "Physics at the Terascale" December 1-3, 2010 Dresden

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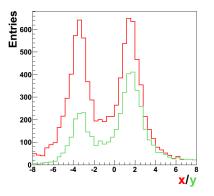
- Unfolding: an ill-posed problem
- An Unfolding Framework
- Summary

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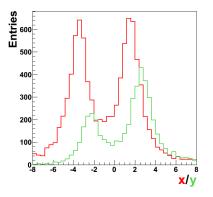
#### We measure a distribution:

- Nature produces f(x).
- Our detector has limited acceptance: f(x) ⇒ g(y).
- Probably we suffer from a bias.
- For sure resolution is limited.
- Background might be an issue.



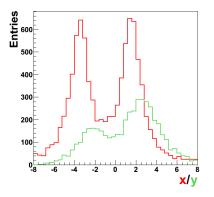
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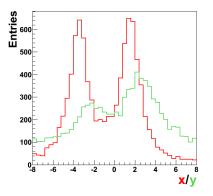
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# Measuring Process: More Formally

# $\int A(y,x) f(x) dx + b(y) = g(y)$

Our Detector	True Distribution	Measured Distribution
<ul> <li>Limited</li> </ul>	Invariant Mass.	Another one!
Acceptance	Transverse	Including
Inefficiencies	Momentum.	background
<ul> <li>Limited</li> </ul>	Something	<i>b</i> ( <i>y</i> )!
Resolution	multidimensional.	
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## Usual goal:

- Find out, whether a theory can describe f(x).
- But the measurement gives g(y)!
- Way out: We know our detector response A (hopefully pretty well).

## Data/Theory Comparison

 $\int A_{sim}(y, x) f_{theo}(x) dx + b(y) = g_{theo}(y)$ 

#### Simulate Measurement Process

- Feed theoretical *f<sub>theo</sub>(x)* through detector simulation *A<sub>sim</sub>*.
- Add background b(y) (simulation / from data).
- Compare g<sub>theo</sub>(y) to measured g(y).

- Probably the best one can do!
- But how to compare to
  - future theories?
  - another experiment?
- $\Rightarrow \text{ Need to} \\ \text{reconstruct } f(x) \text{ from } g(y), \\ \bullet \text{ using } A_{sim}, b(y). \end{aligned}$

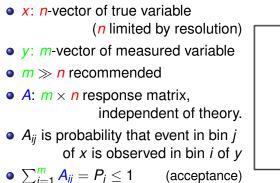
 $\Rightarrow$  Unfolding!

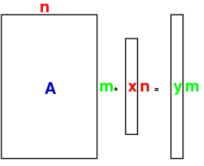
Here and in the following: Follow V. Blobel's notations.

# $\int A_{sim}(y, x) f(x) dx + b(y) = g(y)$

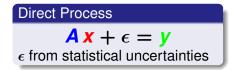
Discretize to use linear algebra (for simplicity: skip background b):

A x = y





## Unfolding is an Inverse Problem



The III-posed Inverse Problem

- Reconstruct input x from a measured output y.
- A washes out fine structures in x, cannot be reconstructed from y.
- ⇒ Small perturbation of the data can cause an arbitrary large perturbation of the solution.

#### **Inverse Process**

Find A<sup>#</sup> to get estimator x̂

$$\hat{\mathbf{X}} = \mathbf{A}^{\sharp}\mathbf{y}$$

•  $A^{\sharp}$ :  $n \times m$  matrix, ("generalised inverse").

# Least Squares Solution

 $\mathbf{A}\mathbf{x} + \epsilon = \mathbf{y}$ 

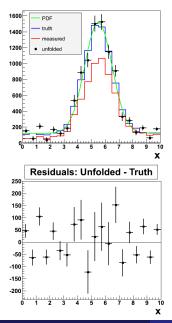
• Minimise  $(Ax - y)^T V_y^{-1} (Ax - y)$  (LS principle)  $\Rightarrow A^{\sharp} = (A^T V_y^{-1} A)^{-1} A^T V_y^{-1}$  $\Rightarrow V_x = A^{\sharp} V_y A^{\sharp T}$  (standard error propagation)

(Small  $y_i \Rightarrow$  use Maximum Likelihood with Poisson statistics.)

#### Result

- Unbiased estimator  $\hat{x} = A^{\sharp}y$ .
- Smallest variance V<sub>x</sub> of all unbiased estimators.
- But you will see
  - large fluctuations
  - and large correlations!
- $\Rightarrow$  next slide.

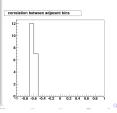
## Matrix Inversion



#### **Even Simpler Case**

$$\mathbf{n} = \mathbf{m} \Rightarrow \mathbf{A}^{\sharp} = \mathbf{A}^{-1}$$

- True distribution (Gauss).
- Measured distribution:
  - some acceptance loss,
  - Gaussian resolution:  $\sigma_x = 0.5$  (= bin width).
- Unfolding result.
- Residuals show large fluctuations.
- Accompanied by large negative correlations of adjacent bins:



Gero Flucke (DESY)

Unfolding

### Using Diagonalisation

• Diagonalise *n*-matrix  $(AV_y^{-1}A^T) = U \wedge U^T$ .

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$$UU^T = U^T U = I$$
.

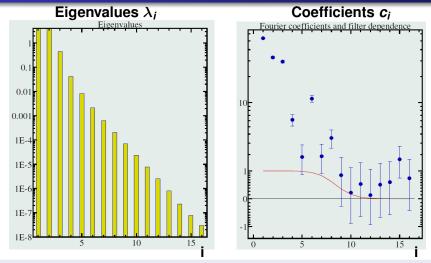
- A is diagonal matrix of Eigenvalues  $\lambda_1 \ge \lambda_2 \ge \cdots \ge \lambda_n \ge 0$ .
- Now one can write

$$\hat{x} = \sum_{i=1}^{n} \frac{1}{\sqrt{\lambda_i}} c_i u_i, \qquad V_x = \sum_{i=1}^{n} \frac{1}{\lambda_i} u_i u_i^{T}$$

• *u<sub>i</sub>* normalised Eigenvectors,

•  $c_i$  coefficients with uniform variance:  $V_c = I$ .

## Eigenvalues Spectrum and Coefficients $c_i$



- Eigenvalues decrease by orders of magnitude.
- Coefficients  $c_i$  of small  $\lambda_i$  are insignificant (since:  $V_c = I$ ).

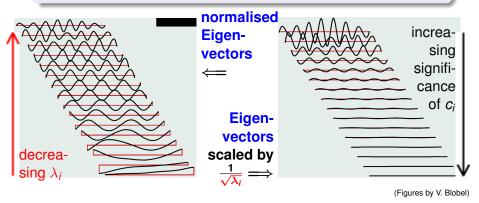
(Figures by V. Blobel)

Image: A matrix

## Investigate Solution

$$\hat{x} = \sum_{i=1}^{n} \frac{1}{\sqrt{\lambda_i}} c_i u_i \qquad \qquad V_x = \sum_{i=1}^{n} \frac{1}{\lambda_i} u_i u_i^T$$

- $V_c = I$ : Insignificant coefficients (noise, follow N(0, 1))
  - can make large contribution to  $\hat{x}$
  - if Eigenvalues are small!



# How to deal with Insignificant High Frequency Eigenvectors?

## Simple Approach

• Cut-off, i.e. ignore insignificant coefficients  $c_i$  with  $k < i \le n$ 

• 
$$\hat{x} = \sum_{i=1}^{k} \frac{1}{\sqrt{\lambda_i}} c_i u_i$$
  $V_x = \sum_{i=1}^{k} \frac{1}{\lambda_i} u_i u_i^T$ 

- Without any bias.
- Problems:
  - $V_x$  singular (rank k < size n), i.e.  $V_x^{-1}$  does not exist.
  - Exact *k* not unambiguous: Prefer smooth cut-off.

## Art of Unfolding: Regularisation

- Add penalty term to the minimised expression to make a smooth cut-off.
- Stay (almost) bias free.

# Regularisation

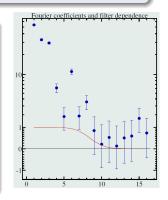
#### New Expression to minimise

• Minimise 
$$(Ax - y)^T V_y^{-1} (Ax - y) + \tau (Lx)^T Lx$$

- L: Matrix, depending on regularisation approach.
- $\tau$ : Regularisation parameter.

• With 
$$L = I$$
 (identity):  
 $\Rightarrow \hat{x} = \sum_{i=1}^{k} \frac{\phi_i}{\sqrt{\lambda_i}} c_i u_i,$   
 $\phi_i = \frac{\lambda_i}{\lambda_i + \tau} = 1 \dots 0.$ 

- ⇒ Damping of (insignificant) contributions of small Eigenvalues.
  - But rank deficit of covariance V<sub>x</sub> remains:
    - Fitting cumbersome without  $V_x^{-1}$ !
    - Collapse bins?



• Minimise 
$$(Ax - y)^T V_y^{-1} (Ax - y) + \tau (Lx)^T Lx$$

## Choice of Regularisation Scheme

- L = I: Norm of solution.
  - Easily usable for multi-dimensional distributions.
- L based on second derivatives expression.
  - Seems natural for physics: Assumption of smooth result.
  - Extension for more dimensions not straight forward.
- Entropy method adds a sum like  $\tau \times \sum_i x_i \log x_i$ .
  - Easily usable for multi-dimensional distributions.

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### Choice of Regularisation Parameter

- Depending on curvature vs.  $\chi^2$  ("L-curve").
- Choose point of smallest global correlations.

• Match  $\sum \phi_i = \sum \frac{\lambda_i}{\lambda_i + \tau}$  to number of significant coefficients  $c_i$ .

#### Message to take away

Main inherent problems of unfolding:

- Smearing detector A(y,x) washes out fine structure of truth f(x) in measurement g(y).
- Straight forward unfolding introduces high frequency terms from fluctuations in g(y) (and large correlations).
- (Smooth) cut-off needed: regularisation.
- Often leads to covariance  $V_x$  being singular.

# The Analysis Centre and Unfolding

## Alliance Workshop in May 2010

• At DESY:

https://indico.desy.de/conferenceDisplay.py?confld=3009.

- Presentation of experts.
- $\Rightarrow$  Revealed controversy among experts.
  - Presentation of experience with available implementations.

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# Some Algorithms

## RUN

- by Volker Blobel (Uni Hamburg)
- regularised unfolding (L based on second derivatives)
- data internally represented by cubic B-splines instead of bins
- > 20 years old: FORTRAN

## TRUEE

- C++ version of RUN
- by Natalie Milke (Uni Dortmund)
- extension for time dependence foreseen

## GURU

- by Höcker and Kartvelishvili
- singular value decomposition (SVD similar to diagonalisation) with regularisation

Gero Flucke (DESY)

# Some more Algorithms

## TUnfold

- by S. Schmitt (DESY)
- least squares fit with free choice of regularisation scheme
- already shipped with ROOT (correct version since ROOT 5.27/04)

### Iterative "Bayesian"

- by G. D'Agostini (University and INFN Roma1)
- Bayesian "knowledge update", starting with MC input
- various implementations (and also development)

### **Bin-by-Bin Corrections**

- implemented in various analyses:  $\hat{x}_i = N_i^{data} \left(\frac{N_i^{gen}}{N_i^{rec}}\right)_{MC}$
- not recommended: correct only for MC = truth

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## RooUnfold

- by Tim Adye (RAL) et al.
- Framework containing
  - iterative "Bayesian" algorithm,
  - singular value decomposition (SVD),
  - bin-by-bin method (for comparison not recommended).
- Since summer extended by
  - interface to TUnfold,
  - unregularised matrix inversion (for comparison).

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#### Unfolding Framework

Getting people together,

within and beyond Alliance.

#### to develop a Framework for Unfolding Algorithms:

- common code accessibility,
- unified data handling,
- test framework,
- o documentation.
- Will not work as a black box:
  - Cannot relieve the user from the need to understand mechanisms, input,....

# Unfolding Framework

- Decided to base work on RooUnfold
  - add response object A(y, x) with unbinned information (T. Adye),
  - integrate TRUEE (G.F., N. Milke),
  - work on improved version of "Iterative Bayesian" method (K. Bierwagen [Göttingen], J. Therhaag [Bonn]),
  - probably add simple Likelihood fit for comparison,
  - standalone, configurable main program (P. Cipriano [DESY]),
  - more test features.
- Discussing a systematic test of algorithms
  - "blind test" proposal (N. Gagunashvili [Iceland]),
  - exactly known detector response A(y, x)
  - comparing residuals, covariance,  $\chi^2, \ldots$ 
    - (best "figure(s) of merit" yet unclear)
  - still in starting phase.

### Interested to learn more?

- More details on Alliance Wiki: https://www.wiki.terascale.de/index.php/Unfolding\_Framework\_Project
- Alliance Workshop in May 2010 at DESY (proceedings to come): https://indico.desy.de/conferenceDisplay.py?confld=3009
- To follow the activities, sign-up the mailing list https://lists.desy.de/sympa/review/hep-unfolding
- Last day of PHYSTAT 2011 (17.-20.1.2011 at CERN) dedicated to unfolding: http://indico.cern.ch/conferenceDisplay.py?confId=107747

#### You want to contribute?

- Contact me: gero.flucke@desy.de
- Sign up mailing list https://lists.desy.de/sympa/review/hep-unfolding-dev
- Monthly EVO meetings.

- Unfolding needed to compare
  - experiments with each other
  - and with (future) theories.
- Ill-posed problem due to smearing effect of response matrix A:
  - high frequency terms need to be regularised.
- Experts debate about correctness of each others method.
- Analysis Centre is working on a Framework for unfolding algorithms, including tests of algorithms.
  - Your experience (and expertise) welcome.
  - Will pay back in future!

#### For the Future:

Stay tuned!