Data-Driven Diagnosis at EuXFEL

Antonin Sulc Hamburg, April 27, 2022

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> What's European XFEL.













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- Diagnosis and predictive maintenance tasks on accelerator controls. >











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- **Example:** Quench detection with a purely data-driven model.









Overview

- What's European XFEL. >
- Diagnosis and predictive maintenance tasks on accelerator controls. >
- **Example:** Quench detection with a purely data-driven model. >
- **Example:** Anomaly detection on beam position monitors.







The European XFEL:

> Consists of a superconducting cavities that boosts electrons.



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- > Consists of a superconducting cavities that boosts electrons.
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- > These X-ray flashes are then distributed to three beamlines (SASE).



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- > Many components are operating in extreme conditions (radiation, heat...).
- > At any moment, any component can fail.
- > When a component fails, it can lead to undesired **downtime**.











Examples

(1) LLRF Cavities

- > Monitoring signals from cavities.
- Detecting quenches and other faults.

(2) Orbit Monitoring

- > Analyzing electron orbits in SASEs.
- Various types of problems are indicated by variations on orbits.





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Cavities

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[Wikipedia]





Cavities

- The superconducting LLRF cavities accelerate electron bunches.
- The electrons are accelerated by alternating electric fields.
- Trajectory is manipulated via a magnetic field.
- Superconductivity is important to maintain the efficiency.
- Very low temperatures (near absolute zero) are needed for superconductivity.

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(1) Monitoring Superconducting LLRF Cavities



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> Quench (right) means a loss of superconductivity in a cavity, which has a significant effect on the quality factor.





(1) Data-Driven Monitoring of Superconducting LLRF Cavities



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- Semi-supervised anomaly loss [Ruff(2019)]

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$$L\left(\boldsymbol{\theta}\right) = \|f_{\boldsymbol{\theta}}(\mathbf{x}) - \mathbf{C}\|_{2}^{y} + \|f_{\boldsymbol{\theta}}(\mathbf{x}) - \mathbf{C}\|_{2} \text{ where } y \in \{-1, 1\}.$$





Semi-Supervised Anomaly Loss

Semi-supervised anomaly loss [Ruff(2019)]

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 $L(\theta) = \|f_{\theta}(\mathbf{x}) - \mathbf{c}\|_{2}^{y} + \|f_{\theta}(\mathbf{x}) - \mathbf{c}\|_{2}$ where $y \in \{-1, 1\}$.





(1) Results - Quenches





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(1) Feature Space - TSNE of $f_{\theta}(\mathbf{x})$



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(2) Orbit Monitoring

Assumption

There is a systematic pattern shown in orbits given by the physical construction of EuXFEL.



Orbit Monitoring - FODO Lattice







(2) Orbit Monitoring



(2) Orbit Monitoring









(2) Data-Driven Orbit Monitoring

Model-Based Orbit Monitoring



- > Credits to **R. Kammering**.
- > Fit a sine and measure residual.
- > Pros It is fast and intuitive.

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> **Cons** No intra-bunching instabilities.



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Model-Free Orbit Monitoring



- > Series of BPM read-outs.
- > Train a model with the anomaly loss.
- Pros Takes into consideration intra-bunching instabilities.







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- > Each input are stacked horizontal and vertical positions from all beamlines.
- > We do not have any faulty labels.
- > Unsupervised anomaly loss

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$$L(\theta) = \|f(\mathbf{x}; \theta) - \mathbf{C}\|_2$$

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(2) Feature Space - TNSE of $f(\mathbf{x}; \theta)$



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This is the joint work of A. Eichler and Raimund Kammering!

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