ATLAS $H \rightarrow \gamma \gamma$ Differential Cross Section Measurements

-- with a special focus on the background modelling --

Nils Gillwald November 23, 2021











Why Measure Differential Cross Sections?

- Selected differential measurements sensitive to many Higgs boson properties:
 - $p_T^{\gamma\gamma} \rightarrow \text{ggF}$ & perturbative QCD, Yukawa & BSM couplings
 - * $|y_{\gamma\gamma}|
 ightarrow {\tt ggF}$ & perturbative QCD, proton PDFs
 - $\Delta \phi_{jj} \rightarrow$ Higgs boson spin & CP properties
 - • •
- > Better measurements constrain unknown physics!
- > Measurements are almost model independent \rightarrow allow direct comparison to predictions





Analysis Overview

Fiducial and differential cross sections in the $H \to \gamma \gamma$ channel

- > $\gamma\gamma$ excellent channel to work with
 - High photon selection efficiency
 - Excellent $m_{\gamma\gamma}$ resolution \rightarrow robust background subtraction
 - Balances low BR of 0.23%!
- > Conf using full Run-2 dataset, 139.0 fb $^{-1}$ at $\sqrt{s} = 13$ TeV
- > Total cross section measured in inclusive fiducial region
- > Differential measurement of six variables:
 - = $p_T^{\gamma\gamma}$, $|y_{\gamma\gamma}|$, $N_{\rm jets}$, p_T^{j1} , m_{jj} , $\Delta\phi_{jj}$
- > Two interpretations:
 - b and c Yukawa couplings
 - SMEFT

Analysis Strategy

- > Measure differential cross section by simultaneously fitting the $m_{\gamma\gamma}$ distributions in all bins of a variable
 - $\rightarrow~{\rm Get}~{\rm signal}~\sigma\times Br$ and background yield for every bin
- Fit uses analytical S and B shape parametrizations
 - Need to choose a background function for each bin \rightarrow Background modelling
- > Systematic uncertainties shared between all bins of a variable
- Unfold detector effects for easier cross-experiment & theory comparison





Strategy

- Parametrize total background component with simple analytical function
 - But which functional form should be used?
- \rightarrow Build background template closely matching data
 - Used to determine the background functional form for the final S + B fit
 - Not used to determine the background function parameters



→ Need shapes & fractions of all background sources to build complete template

Strategy

- Parametrize total background component with simple analytical function
 - But which functional form should be used?
- → Build background template closely matching data
 - Used to determine the background functional form for the final S + B fit
 - Not used to determine the background function parameters
 - ightarrow Need shapes & fractions of all background sources to build complete template
 - > Smooth background templates using Gaussian Process Regression (GPR)
 - > Background model bias studies
 - Estimate potential impact of background model choice on signal yield: spurious signal (SS)
 - Background function selection



Template Building

- > Backgrounds are continuous non-resonant $\gamma\gamma$ (irreducible) and γj , jj (reducible)
- Build background template by adding different background distributions:
 - $\gamma\gamma$ shape from $\gamma\gamma$ MC simulation
 - γj shape from data control region
 - *jj* neglected (no impact on template shape)
- > Relative background fractions from data
 - Control regions defined by inverting the selection criteria for each γ separately
- > Inclusive fiducial composition typically $\gamma\gamma$ ~76%, γj ~21%, j j ~3%



Spurious Signal: Potential bias on $\sigma \times Br$ by background model choice

- > A good background model describes the data well, with only small bias on the extracted $\sigma \times Br$ value
 - Evaluate goodness-of-fit (χ^2) and SS of each considered function
 - Considered functions: Exp(polynomial O(1,2,3)), Bernstein polynomials O(3,4,5), Power Law



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 - Evaluate goodness-of-fit (χ^2) and SS of each considered function
 - Considered functions: Exp(polynomial $\mathcal{O}(1,2,3)$), Bernstein polynomials $\mathcal{O}(3,4,5)$, Power Law
- SS is evaluated by S + B fits to the background-only template: 17 fits scanning m_{γγ} ∈ [121, 129] GeV, max(S) chosen as SS
- > Choose function with lowest #d.o.f. passing SS and χ^2 criteria
- > Spurious signal used as systematic uncertainty in final data fit



Results Selected Highlights

- > Spectrum probed to high $p_T^{\gamma\gamma}$ values
- Provide differential variables for precise theory comparisons
- Provide total cross section measurement
- Overall good agreement with SM predictions



 $\sigma_{\rm fid}$ predicted

= 65.2 ± 4.5 (stat.) ± 5.6 (syst.) ± 0.3 (theo.) fb = 63.6 ± 3.3 fb

 $\sigma_{\rm SM}$

κ_b and κ_c Interpretations How to use differential measurements to

constrain physics beyond the SM



- > Consider overall rescaling of the b/c-quark Yukawa couplings y with a factor $\kappa_{b/c} \sim y_{b/c}^{\text{modified}}/y_{b/c}^{\text{SM}}$
- > Constraints on κ_b and κ_c from measured $p_T^{\gamma\gamma}$ distribution (profile likelihood)



EFT Interpretation

- SM EFT adding eight dimension-6 operators to SM Lagrangian
 - Basically (re-)combining SM operators to higher orders
- > Warsaw basis, new physics scale at $\Lambda=1~{\rm TeV}$
- > Limits obtained by likelihood fit to $p_T^{\gamma\gamma}$, $N_{\rm jets}$, m_{jj} , $\Delta\phi_{jj}$ and p_T^{j1}
- > Limits are set on the dim-6 operators







- Differential cross section measurements provide a precision view into Higgs boson properties, possible BSM physics, and physics modelling
- > $H \rightarrow \gamma \gamma$ is an excellent channel for such measurements
 - Good $m_{\gamma\gamma}$ resolution and selection efficiency
- > A reliable background model is essential for the $H \rightarrow \gamma \gamma$ analysis
- > Measurements show good agreement with SM predictions, with $\sim 11\%$ precision
- Looking forward to include more variables and to combine different channels!



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Backup





Established to the Gaugeane Completion





How to produce Higgs bosons at the LHC...

- > Four major production modes:
 - Gluon-gluon fusion (ggF), vector boson fusion (VBF), W/Z Strahlung, top-quark associated production



> ggF dominating, then VBF, VH(WH/ZH), ttH

Mode	Cross section [pb]
ggF	48.61
VBF	3.766
WH	1.358
ZH	0.880
ttH	0.507

Source: LHCHXSWG

...and how they decay

- > H dominantly decays into $b\bar{b}$
- > Next WW, gg, $\tau\tau$
- Decay into gg and γγ only possible via loops (massless particles!)
- > Decay into photons ($\gamma\gamma$) relatively suppressed, BR \sim 0.227%
- > $\gamma\gamma$ still excellent channel to work with
 - High photon selection efficiency
 - Excellent $m_{\gamma\gamma}$ resolution
 - \rightarrow robust background subtraction
 - Balances low BR!



Event Selection & Fiducial Region

- > Harmonize truth and reconstruction cuts as much as possible
 - Avoid acceptance effects: reduces model dependencies

Photon and Event Selection

- > Two energetic, isolated, central γ
- > $m_{\gamma\gamma} \in [105, 160]$ GeV most signal in [120, 130] GeV
- > Neural network selects $\gamma\gamma$ vertex: better four-momentum and $m_{\gamma\gamma}$ resolution, jet association

Jet Selection

- > Central R = 0.4 anti-k_t jets
- > Jet vertex tagger to suppress pileup
- > Overlap removal: prioritize e, γ over jets

Electron and Photon ID

- > Shapes of the showers in the electromagentic (EM) calorimeter used for e and γ ID
- > Shapes can be sorted into four categories:
 - Track properties (e), lateral development, longitudinal development, track-cluster spatial compatibility
- > e ID: discriminate e from e from hadronic jets, converted γ , and e from heavy-flavour hadrons
- > γ ID: discriminate γ from hadronic jet backgrounds (bkd), π^0 decays
- > e ID constructs a likelihood discriminant from these, using data $Z \rightarrow ee$ ($E_T > 15$ GeV) and $J/\Psi \rightarrow ee$ ($E_T < 15$ GeV) tag and probes
- > γ uses cut-based approach: MC $Z \rightarrow \ell \ell \gamma$ signal with data Z+jets bkd (10 < E_T < 25) GeV and inclusive-photon production MC with MC dijet bkd ($E_T > 25$ GeV)

Choice of Binnings

- Strategy: Start with fine binning, merge until optimisation criteria satisfied
- > Optimise variable binnings with respect to:
 - Expected significance $\geq 2\sigma$
 - Harmonization with categories in Higgs couplings analysis (STXS), $H \rightarrow 4\ell$ and CMS



Signal Extraction

Including Systematic Uncertainties in Likelihood Fits -- Profile Likelihood

- > Systematics are due to imperfect knowledge of auxiliary parameters
- > But we have some knowledge: $\theta = \theta_0 \pm \Delta \theta$
- > Modify likelihood function accordingly:

0

$$\mathcal{L}(\underline{n,\theta^{0}};\underline{\mu,\theta}) = \prod_{i \in \mathsf{bins}} \mathcal{P}(n_{i}|\mu,\theta) \times \prod_{j \in \mathsf{syst}} \mathcal{G}(\theta_{j}^{0}|\theta_{j},\Delta\theta_{j})$$
bservables Parameters

- P is the probability of the observables given a model i.e., the signal and background model enter here!
- > A priori knowledge interpreted as "auxiliary measurement"
 - Implemented as constraint / penalty term, i.e. probability density function
 - Often Gaussian, interpreting $\pm \Delta \theta$ as σ

Signal Model

Source: ATLAS-CONF-2019-029

 MC - Model

MC

— Model

135

 $m_{\gamma\gamma}$ [GeV]



- Signal modelled by a double sided Crystal Ball function (CB)
- Good description of the Hsignal peak

- Signal shape fixed from fit to $m_H = 125$ GeV MC
- mean + width of CB fixed, but can be effectively modified by constrained energy scale and resolution and Higgs mass nuisance parameters

ABCD Sideband Method & use for Background Templates

- > Invert γ isolation and ID in order to create signal and background enriched regions
- E.g., var1 = ID, var = iso
- > A is signal regions, B, C, D background enriched
- > IF var1 and var2 are uncorrelated, then

$$\frac{N_A}{N_B} = \frac{N_C}{N_D} \Leftrightarrow N_A = \frac{N_B N_C}{N_D}$$

var2 1 B A 0 D C 0 1 var1

Source: Particle Wiki

- ⇒ Get an estimate on signal region from backround regions!
- > Apply a similar method to $H \rightarrow \gamma \gamma$ background decomposition, treating each photon separately \rightarrow 2x2D sideband method

Spurious Signal: Potential bias by background model choice

Aim: Estimate potential bias to \boldsymbol{S} by background model choice

- Run S + B fits on background template for all considered models
 - 9 steps for $m_{\gamma\gamma} \in [123, 127]~{
 m GeV}$
- Max(S) chosen as this model's potential bias
- Accept model if:
 - $\ \ \ S < 20\%$ of expected background uncertainty, or
 - S < 10% of expected # signal events
 - If no model passes, use $S \pm x\Delta_S$: Δ_S statistical uncertainty of $S, x \in \{1, 2\}$ can be further relaxed
 - $p(\chi^2)$ for model on template sidebands > 1%
- > Choose lowest d.o.f. model passing criteria



- > Spurious signal scan, $p_T^{\gamma\gamma}$ bin 7
- Functions: Exp(polynomial O(1,2,3)), Bernstein polynomials O(3,4,5), Power Law

Background Model GPR Bias Study

If we smooth our background templates, do we spoil our spurious signal bias estimate?

> Strategy:

- Assume a true background shape and throw background template toys from it
- Compare the spurious signal results on raw and smoothed templates
- If unbiased, mean value of distributions should agree within uncertainties
- > Examples from $p_T^{\gamma\gamma}$, bin 45 60 GeV

Based on this study, smoothing is unbiased!



Unfolding in a nutshell

Removing Efficiency and Reconstruction Effects

The problem.

- Experiments measure detector-level quantities
- > Would need to run full reconstruction on MC theory prediction
 - Cannot be done outside of ATLAS!
 - Difficult to compare results to updated theoretical predictions
- Impossible to compare to analytical theory predictions

The solution.

- Convert experimental data to "truth quantities"!
- > More useful for theorists
- Easier comparison to MC generator output
- > Easier cross-experiment comparisons
- Don't depend on knowledge on how to run the detector simulation

Unfolding in a nutshell, II

Removing Efficiency and Reconstruction Effects

- > Different approaches to unfolding:
 - Bin-by-bin correction factor (top): c =truth / reco
 - Matrix approach (bottom): $\vec{n}_{\rm truth} = R^{-1} \times \vec{n}_{\rm reco}$
- Each method has different strengths and weaknesses
- Many more points, such as biases, regularization (fixing problems with matrix inversion), interpolations, model dependence due to use of simulation, ...
- > Our analysis uses the matrix approach
 - No regularization, directly in likelihood fit



Thanks to Carsten Burgard for the plots! They contain dummy data only.

$$\mathcal{L}\left(m_{\gamma\gamma};\nu^{\mathsf{sig}},\nu^{\mathsf{bkg}}
ight) = 0$$

$$\mathcal{L}\left(m_{\gamma\gamma};\nu^{\mathsf{sig}},\nu^{\mathsf{bkg}}
ight) =$$

 $\nu^{\text{sig}} \underbrace{\mathcal{S}\left(m_{\gamma\gamma}^{j}; \theta_{k}\right)}_{\text{signal model PDF}}$

$$\mathcal{L}\left(m_{\gamma\gamma};\nu^{\mathsf{sig}},\nu^{\mathsf{bkg}}
ight) =$$

 $\nu^{\text{sig}}\underbrace{\mathcal{S}\left(m_{\gamma\gamma}^{j};\theta_{k}\right)}_{\text{signal model PDF}} + \nu^{\text{bkg}}\underbrace{\mathcal{B}\left(m_{\gamma\gamma}^{j}\right)}_{\text{bkg model PDF}}$

$$\mathcal{L}\left(m_{\gamma\gamma};\nu^{\mathsf{sig}},\nu^{\mathsf{bkg}}
ight) =$$

$$\underbrace{\prod_{j=1}^{n} \left[\nu^{\text{sig}} \underbrace{\mathcal{S}\left(m_{\gamma\gamma}^{j}; \theta_{k}\right)}_{\text{signal model PDF} \text{ bkg model PDF}} + \nu^{\text{bkg}} \underbrace{\mathcal{B}\left(m_{\gamma\gamma}^{j}\right)}_{\text{bkg model PDF}} \right]}_{\text{product over all events in a } m_{\gamma\gamma} \text{ bin}}$$

$$\mathcal{L}\left(m_{\gamma\gamma};\nu^{\mathrm{sig}},\nu^{\mathrm{bkg}}\right) = \underbrace{\frac{e^{-\nu}}{n!}}_{j} \underbrace{\prod_{j}^{n} \left[\nu^{\mathrm{sig}} \underbrace{\mathcal{S}\left(m_{\gamma\gamma}^{j};\theta_{k}\right)}_{\mathrm{signal\ model\ PDF}\ bkg\ \mathrm{model\ PDF}} + \nu^{\mathrm{bkg}} \underbrace{\mathcal{B}\left(m_{\gamma\gamma}^{j}\right)}_{\mathrm{product\ over\ all\ events\ in\ a\ m_{\gamma\gamma}\ bin}}\right]}_{\mathrm{product\ over\ all\ events\ in\ a\ m_{\gamma\gamma}\ bin}}$$





$$\mathcal{L}\left(m_{\gamma\gamma};\nu^{\mathrm{sig}},\nu^{\mathrm{bkg}}\right) = \underbrace{\prod_{i}^{m} \frac{e^{-\nu}}{n!}}_{product \text{ over all events in a } m_{\gamma\gamma} \text{ bin}}_{product \text{ over all bins of a variable}} + \underbrace{\nu^{\mathrm{bkg}} \underbrace{\mathcal{B}\left(m_{\gamma\gamma}^{j}\right)}_{product \text{ over all bins of a variable}}} \times \underbrace{\prod_{k} C_{k}\left(\theta_{k};0,1\right)}_{product \text{ over all bins of a variable}} \times \underbrace{\prod_{k} C_{k}\left(\theta_{k};0,1\right)}_{product \text{ over all bins of a variable}} \times \underbrace{\prod_{k} C_{k}\left(\theta_{k};0,1\right)}_{product \text{ over all bins of a variable}} \times \underbrace{\prod_{k} C_{k}\left(\theta_{k};0,1\right)}_{product \text{ over all bins of a variable}} \times \underbrace{\prod_{k} C_{k}\left(\theta_{k};0,1\right)}_{product \text{ over all bins of a variable}} \times \underbrace{\prod_{k} C_{k}\left(\theta_{k};0,1\right)}_{product \text{ over all bins of a variable}} \times \underbrace{\prod_{k} C_{k}\left(\theta_{k};0,1\right)}_{product \text{ over all bins of a variable}} \times \underbrace{\prod_{k} C_{k}\left(\theta_{k};0,1\right)}_{product \text{ over all bins of a variable}} \times \underbrace{\prod_{k} C_{k}\left(\theta_{k};0,1\right)}_{product \text{ over all bins of a variable}} \times \underbrace{\prod_{k} C_{k}\left(\theta_{k};0,1\right)}_{product \text{ over all bins of a variable}} \times \underbrace{\prod_{k} C_{k}\left(\theta_{k};0,1\right)}_{product \text{ over all bins of a variable}} \times \underbrace{\prod_{k} C_{k}\left(\theta_{k};0,1\right)}_{product \text{ over all bins of a variable}} \times \underbrace{\prod_{k} C_{k}\left(\theta_{k};0,1\right)}_{product \text{ over all bins of a variable}} \times \underbrace{\prod_{k} C_{k}\left(\theta_{k};0,1\right)}_{product \text{ over all bins of a variable}} \times \underbrace{\prod_{k} C_{k}\left(\theta_{k};0,1\right)}_{product \text{ over all bins of a variable}} \times \underbrace{\prod_{k} C_{k}\left(\theta_{k};0,1\right)}_{product \text{ over all bins of a variable}} \times \underbrace{\prod_{k} C_{k}\left(\theta_{k};0,1\right)}_{product \text{ over all bins of a variable}} \times \underbrace{\prod_{k} C_{k}\left(\theta_{k};0,1\right)}_{product \text{ over all bins of a variable}} \times \underbrace{\prod_{k} C_{k}\left(\theta_{k};0,1\right)}_{product \text{ over all bins of a variable}} \times \underbrace{\prod_{k} C_{k}\left(\theta_{k};0,1\right)}_{product \text{ over all bins of a variable}} \times \underbrace{\prod_{k} C_{k}\left(\theta_{k};0,1\right)}_{product \text{ over all bins of a variable}} \times \underbrace{\prod_{k} C_{k}\left(\theta_{k};0,1\right)}_{product \text{ over all bins of a variable}} \times \underbrace{\prod_{k} C_{k}\left(\theta_{k};0,1\right)}_{product \text{ over all bins of a variable}} \times \underbrace{\prod_{k} C_{k}\left(\theta_{k};0,1\right)}_{product \text{ over all bins of a variable}} \times \underbrace{\prod_{k} C_{k}\left(\theta_{k};0,1\right)}_{product \text{ over all bins of a variable}} \times \underbrace{\prod$$

where
$$\nu_i^{\text{sig}} = \sum_l R_{il} \sigma_l B_{\gamma\gamma} \cdot \mathcal{L}_{\text{int}}$$

in this Analysis

$$\mathcal{L}\left(m_{\gamma\gamma};\nu^{\mathrm{sig}},\nu^{\mathrm{bkg}}\right) = \underbrace{\prod_{i}^{m} \frac{e^{-\nu}}{n!}}_{product \text{ over all events in a } m_{\gamma\gamma} \text{ bin}} \underbrace{\prod_{j}^{n} \left[\nu^{\mathrm{sig}} \underbrace{\mathcal{S}\left(m_{\gamma\gamma}^{j};\theta_{k}\right)}_{\text{signal model PDF bkg model PDF}} + \nu^{\mathrm{bkg}} \underbrace{\mathcal{B}\left(m_{\gamma\gamma}^{j}\right)}_{\text{nuisance parameter constraints}} \right]}_{\text{product over all bins of a variable}} \times \underbrace{\prod_{k} C_{k}\left(\theta_{k};0,1\right)}_{\text{nuisance parameter constraints}}$$

where
$$u_i^{\mathsf{sig}} = \sum_l R_{il} \sigma_l B_{\gamma\gamma} \cdot \mathcal{L}_{\mathsf{int}}$$

> R_{il} is the response matrix used for the unfolding, $n_i^{\text{detector}} = R_{il} n_i^{\text{particle}}$

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- > R_{il} is the response matrix used for the unfolding, $n_i^{\text{detector}} = R_{il} n_i^{\text{particle}}$
- > $\sigma_l B_{\gamma\gamma}$ is the cross section in bin *l* times the $H \to \gamma\gamma$ BR

The LHC

- > Operating since 2008
- > 27 km long, pp collisions at $\sqrt{s} = 13$ TeV (since 2015)
- > ATLAS peak luminosity: 2.14×10^{34} cm⁻²s⁻¹
- > 2808 bunches, $\sim 10^{11}$ protons each; temporal spacing 25 ns
- Main experiments: ATLAS/CMS (multi-purpose), LHCb (b physics / CP), ALICE (heavy ions / qg-plasma)



The ATLAS experiment

- > 44 × 25 m, 7000 t
- Divided into barrel and end-caps, nearly 4π solid angle coverage
- Onion structure: Tracking layers, EM and hadronic calorimeters, muon chambers
- Magnets between layers bend charged particles for easier reconstruction and measurements
- Trigger selects interesting events (~1/40,000 or 0.0025%)



Some thoughts on template statistics: GPR Smoothing









GPR Smoothing - Why it's needed

- > $H \rightarrow \gamma \gamma$ analysis has very small S/B ratio
- Rely on smooth background template to estimate spurious signal (SS)
 - Model choice and associated SS very sensitive to even small fluctuations in template
 - SS might just be large due to random fluctuation in the generated distribution!
 - Suboptimal function choice, overestimated systematic uncertainties
- Can't just generate more background events already generated 1.025 billion!

Note: Black points are MC template, not data!!



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 - Model choice and associated SS very sensitive to even small fluctuations in template
 - SS might just be large due to random fluctuation in the generated distribution!
 - ⇒ Suboptimal function choice, overestimated systematic uncertainties
- Can't just generate more background events already generated 1.025 billion!
- > Use Gaussian Process Regression (GPR): smooth out fluctuations for better background model choice

Note: Black points are MC template, not data!!



GPR Smoothing - What it is & how it works

- A Gaussian process (GP) is a set of random variables x_i where all subsets have a multivariate normal distribution
 - All linear combinations of subsets are Gaussian distributed
 - Correlations encoded in covariance matrix $\boldsymbol{\Sigma}$

$$\Sigma = \begin{pmatrix} \sigma_0 & c_{01} & c_{02} & \dots & c_{0n} \\ c_{10} & \sigma_1 & c_{12} & \dots & c_{1n} \\ \dots & \dots & \dots & \dots & \dots \\ c_{n0} & c_{n1} & c_{n2} & \dots & \sigma_n \end{pmatrix}$$

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Source: Rasmussen, Williams: Gaussian Processes for Machine Learning

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- A Gaussian process (GP) is a set of random variables x_i where all subsets have a multivariate normal distribution
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 - Correlations encoded in covariance matrix $\boldsymbol{\Sigma}$
- > Fit GP by fitting μ , Σ to n supporting points
 - Important to choose a good prior μ and Σ !
- For a histogram, supporting points would be the single bins
- > Can use fitted μ , Σ as smoothed version of a distribution!

$$\Sigma = \begin{pmatrix} \sigma_0 & c_{01} & c_{02} & \dots & c_{0n} \\ c_{10} & \sigma_1 & c_{12} & \dots & c_{1n} \\ \dots & \dots & \dots & \dots & \dots \\ c_{n0} & c_{n1} & c_{n2} & \dots & \sigma_n \end{pmatrix}$$



Source: Rasmussen, Williams: Gaussian Processes for Machine Learning

GPR: Choice of Prior - Kernels

- > Choice of mean function depends on the distribution to model:
 - Constant, Linear, Exponential, ...
- > Correlation matrix can be simplified by using a Kernel
 - Analytically describes level of correlation between two distinct points
- > Different kinds of Kernels possible:
 - Radial Basis Function (RBF) Kernel:
 - $k(x_i, x_j) = \exp\left(-\frac{1}{2}d(x_i/l, x_j/l)^2\right)$ with d Euclidian distance, l length scale
 - Gibbs Kernel (useful for smoothly falling distributions): Like RBF, but $l \rightarrow l(x)$
- > Smoothing gets more agressive with increasing length scale
- > Can also add a Kernel sensitive to the uncertainties of the supporting points
 - White Kernel: $constant \times Id(N)$
 - Linear Error Kernel: Id(N) matrix with linearly decreasing values as a function of x