Tomasz Włostowski CERN BE-CEM | SY-RF

Use of MTCA.4 and White Rabbit in the CERN SPS Low Level RF system





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Background

- In 2015 decision was taken to renovate the Low Level Radio Frequency controls in the Super Proton Synchrotron¹ at CERN
- The new system relies on distribution of the reference clock and RF signals over <u>White Rabbit</u>. In order to be able deliver beams of requested quality, the RF required:
- < 13 ps end-to-end precision (1 deg phase @ 200 MHz, reproducible every power cycle)
- -130 dBc/Hz PN at 1 kHz (223 MHz)

The "old" analog LLRF system



WR-based LLRF



We had to deliver WR gear that can do that: WRS-LJD, LPDC, eRTM, WR2RF

¹The second-largest accelerator at CERN (8 km circumference) and a direct injector to the LHC.

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The LLRF System Overview



- Cavity Controller handles a single RF cavity (we have 6 in the SPS)
- Beam Controller calculates the RF frequency (called "RF-Train") and distributes it using WR Streamers
- The CC and BC reside in two MTCA.4 crates, with the LLRF backplane

 The <u>eRTM</u> provides the Local Oscillator and ADC/DAC clocks for the CC/BC

- The <u>WR2RF</u> receives the RF-Train and can generate the actual cavity RF signals and RF-synchronous trigger pulses.
- WRS-LJD and LPDC allow for improved precision and PN

The eRTM14/15

MTCA.4 eRTM, slots 14-15 of RFBP:

- "Sandwich" of two boards: digital with the FPGA and analog with the oscillators and clock distribution
- Kintex-7 7K70T FPGA
- Controlled by a heavily customized WR PTP Core
- Two DDS analog clocks LO and REF:
 - From 10 to 300 MHz, sine wave
 - Passive clock distribution with adjustable power (0-14 dBm)
 - 11 outputs for each (backplane + FP), on/off control + power monitoring
 - Network-wide phase alignment (WR trigger)
- Two digital clocks CLKA and CLKB:
 - 62.5, 125, 250 or 500 MHz
 - 10 outputs for each (backplane + FP), on/off control
- PPS and 10 MHz in/out
- Two WR uplink ports foreseen for network redundancy
- Software control over USB (we tried IPMI and failed...)
- Stand-alone (no MTCA crate) operation possible





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The eRTM 14/15 Clock Recovery and Distribution

- LO output must have PN better than -130 dBc/Hz at 1 kHz offset @ 223 MHz
- This is above WR PLL bandwidth and PN figure offered by FPGA PHYs
- Must provide enough PN headroom for the DDS
- Solution: AXIOM45ULN 100 MHz OCXO
- DDS and digital clocks require ~100 fs rms jitter and a master clock of 1 GHz
- Solution: multiply using PLL + discrete oscillator combo (CVCSO-914-1000)
- 2nd PLL bandwidth = ~10 kHz
- PN at offsets below 10 Hz not critical (not "seen" by the beam)
- LO/REF outputs used for driving RF mixers (low-distortion sinewave), using an analog network of RF amplifiers and passive splitters



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10MHz

-174 dBc/Hz

The eRTM14/15 PN measurements



- DDS LO/REF PN of -130.5 dBc/Hz at 1 KHz (223.5 MHz), jitter 51 fs (100 Hz 10 MHz)
- CLKA PN of -126 dBc/Hz at 1 KHz (500 MHz), jitter 32 fs (100 Hz 10 MHz)
- Measured for front panel outputs of the eRTM14/15

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At these PN levels, even mechanical vibrations caused by cooling fans matter!

The eRTM14/15 Varia

Management capabilities:

- IPMI/MMC implemented on STM32F3 MCUs using LNLS's OpenMMC (our experience is very positive)
- Monitoring of onboard voltages, 10+ temperature sensors and **OCXO** health
- USB control provides access to all board features (frequencies, amplitudes, WR link control) and provides same monitoring capabilities as IPMI
- Grafana panels for interactive monitoring/alarms

Future plans:

- CERN PS 200 MHz deployment
- Extend frequency range (applications: SPS 800 MHz system, LHC Crab Cavities, LHC LLRF 400 MHz). Upgrade DDS and clock distribution electronics
- Streamline calibration of the board (currently hand-done)

L0 ftw: 39374bc6 (223.500MHz)							REF ftw: 39374bc6 (223.500MHz)					
LO level adjust: 0.2578 (66/256)							REF level adjust: 0.2578 (66/256					
LO pll_out_power: 3.930 dBm							REF pll_out_power: 14.970 dBm					
LO sync_state: rdy							REF sync_state: rdy					
_004:	pow:	11.49	90 dBm	st:	monito	r İ	REF	F04:	pow:	11.670	dBm	st:monito
L005:	pow:	11.85	50 dBm	st:	monito	r İ	REF	F05:	pow:	11.560	dBm	st:monito
_006:	pow:	11.89	90 dBm	st:	monito	r İ	REF	-06:	pow:	12.050	dBm	st:monito
L007:	pow:	11.78	30 dBm	st:	monito	r İ	REF	-07:	pow:	12.100	dBm	st:monito
_008:	pow:	11.67	70 dBm	st:	monito	r	REF	:80	pow:	12.090	dBm	st:monito
_009:	pow:	11.85	50 dBm	st:	monito	r	REF	-09:	pow:	11.950	dBm	st:monito
_010:	pow:	11.86	50 dBm	st:	monito	r	REF	10:	pow:	11.860	dBm	st:monito
_011:	pow:	11.72	20 dBm	st:	monito	r	REF	11:	pow:	11.980	dBm	st:monito
_012:	pow:	11.70	90 dBm	st:	monito	r	REF	12:	pow:	11.870	dBm	st:monito
CLKAB:												
CLKA04:	on	rdy	500.0	MHz	(CLKB	4:	on	rdy	125.0	MHz	
CLKA05:	on	rdy	500.0	MHz	(CLKB	15 :	on	rdy	125.0	MHz	
CLKA06:	on	rdy	500.0	MHz	(CLKB	6:	on	rdy	125.0	MHz	
CLKA07:	on	rdy	500.0	MHz	(CLKB	17:	on	rdy	125.0	MHz	
CLKA08:	on	rdy	500.0	MHz	(CLKB	8:	on	rdy	125.0	MHz	
CLKA09:	on	rdy	500.0	MHz	(CLKB	9:	on	rdy	500.0	MHz	
CLKA10:	on	rdy	500.0	MHz	(CLKB1	.0:	on	rdy	125.0	MHz	
CLKA11:	on	rdy	500.0	MHz	(CLKB1	.1:	on	rdy	125.0	MHz	
CLKA12:	on	rdy	500.0	MHz	(CLKB1	.2:	on	rdy	125.0	MHz	
CLKA13:	on	rdy	500.0	MHz	(CLKB1	.3:	on	rdy	125.0	MHz	
CLKA14:	on	rdy	500.0	MHz		CLKB1	.4:	on	rdy	125.0	MHz	
CLKA15:	on	rdy	500.0	MHz		CLKB1	.5:	on	rdy	125.0	MHz	





WR RF Distribution

Based on the RFNCO core provided by the LLRF team

- A bit more complex than the "DDS (Beam Control) over WR" idea presented in the past...
- Inputs momentary RF parameters (machine-specific) broadcast by the Beam Controller using the WR Streamers
- The NCO core computes the momentary RF phase and outputs sin/cos for the DAC
- External DAC and mixer produce the ultimate RF output
- Performance very similar to eRTM (-132 dBc/Hz @ 1kHz/200 MHz RF out)



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Drawings courtesy J. Gill, A. Spierer and G. Hagmann

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Improving WR Precision

Goal: The RF system needs the phase reproducibility (power-cycle) better than 13 ps (1 degree at 200 MHz)

- "Standard" WR offers ~100 ps
- Most of this comes from the FPGA transceiver
- Two main sources of uncertainty:
 - Xilinx's TX/RX Phase Align logic
 - PMA bit clock -> PCS word clock dividers, where each 'tap' introduces slightly different phase offset
- Solution: LPDC (Low Phase Drift Capable) ports:
 - Disable Phase Alignment
 - Tom's Casino¹ approach keep resetting the TX/RX path measuring the phase of the clocks until it hits a predefined value (bypasses divider uncertainty)
- Currently available for GTXE1 (Virtex-6) and GTXE2 (Kintex 7 and Zynq-7000)
- Supported devices: WRS v6.0, eRTM, WR2RF-VME, SPEC7





¹For more details/bibliography, see ICALEPCS 2021 THBR02 paper. Name by Peter Jansweijer/NIKHEF ©

Use of MTCA.4 and White Rabbit in the CERN SPS Low Level RF system

Our experience with MTCA.4

The SPS LLRF was also the first application of MTCA.4¹ in the CERN Accelerator Sector – and as such came with some issues:

- Clock distribution and eRTM control issues
- Thermal design of the crate and fan units
- Rear Power Module firmware issues with powering and communicating with the LLRF RTMs
- No standard data link between the CPU and eRTM slots 14-15
- Bugs in MCH firmware, such as non-functional configuration parameters
- CPU BIOS configuration (PCI Express) is very complex. Wrong settings can 'brick' the CPU module
- Difficult debugging of IPMI/MMC communication

After 4 months of intense collaboration with the vendors – issues fixed

¹ Platform: Schroff/Nvent 11850-026 crate + LLRF backplane + NAT MCH/CPU/PMs

Our experience with MTCA.4 eRTM/DS8VM1 clock divider sync

- DS8VM1 board has only CLKA RFBP input
- Board is clocked by 500 MHz from the RFBP, but needs divided-down clocks (250/125/62.5 MHz) aligned to WR
- We had do develop a Fine Pulse Generator core on the SIS83K FPGA to generate the SYNC pulses for the clock dividers
- Per-slot calibration necessary (RFBP CLKAB lines are not length matched)
- Would have been much easier to use CLKB as the slow sync clock
- Easy to fix in hardware, but we could not do this ourselves
- Written collaboration agreement (NDA-like) required to obtain even the snippets of schematics from DESY
- Project delayed by several months



Our experience with MTCA.4

eRTM thermal issues

- eRTM14-15 slot cooling is very poor in the 9U nVent crate
- 84 W (7 A * 12 V) of total fan power, 36 W dissipated for slots 14-15, boards heating up to 100 deg Celsius!
- Suboptimal allocation of fan power (front fans 3x more powerful than the rear). Top fan tray not doing anything.
- Air inlet in front of the crate: front fans "steal" air for the rear part of the crate
- MCH not allowing to control front/back fans independently (bug in firmware)
- Similar overheating observed for the RPMs
- Firmware fixes and putting more powerful fans in the back provided a bit of improvement, but the fans are still at maximum speed and are extremely loud

5 \$ fix for eRTM/RPM cooling

eRTM14/15 slot

No top fan tray needed (no impact on temperatures)



Cut a hole in the back of the crate

Installed a plexiglass air barrier separating front/back airflows

Conclusions

- Numerous new features for the White Rabbit ecosystem, enabling new areas of applications
- Vastly improved PN and phase reproducibility
- MTCA.4: suitable platform (after some bugfixing), but requires a lot of effort to set up correctly
- Fully digital LLRF system entirely relying on WR for synchronization and RF distribution, including driving the RF cavities in a large operational machine
- All components available for everyone as Open Source Software/Hardware on ohwr.org.

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Backup slides

The WR2RF

VME64x card for interfacing the WR LLRF with the "analog" world

- Provides compatibility with VME systems
- Replaces expensive coaxial cabling with a single WR fiber
- WR Clock and DDS identical as in the eRTM board
- 2 independent RF outputs
- 250 MSPS 16-bit I/Q DAC followed by an upconverter
- Numerically Controlled Oscillator capable of reproducing the SPS cavities RF signal
- 2 low jitter Trigger Units per each RF output, generating pulse patterns synchronous with the RF (bunch clock, orbit clock or arbitrary pulses)
- A number of standard timing I/Os (PPS, 10 MHz, slow triggers)
- User API in C

Applications: driving systems that require beamsynchronous analog timing (instrumentation, kickers, synchronization with the Proton Synchrotron)

