

OOAD Examples

- 1 Jet Finder
- 2 Track Fitting
- 3 Shared Libraries
- 4 Sequence Diagram

1 Jet Finder

- Recombination jet finder in e^+e^-
 - Define *resolution parameter* y_{ij} (a.k.a. distance)
 - Define *combination procedure*
- The recombination algorithm:
 - calculate all y_{ij}
 - combine particles with smallest y_{ij} into a pseudo-particle, remove original (pseudo-) particles
 - stop if all $y_{ij} > y_{\text{cut}}$ or no (pseudo-) particles left

1 Jet Finder

<i>Algorithm</i>	<i>Resolution</i>	<i>Combination</i>
<i>E</i>	$(\mathbf{p}_i + \mathbf{p}_j)^2 / s$	$\mathbf{p}_i + \mathbf{p}_j$
<i>JADE0</i>	$2\mathbf{E}_i\mathbf{E}_j(1 - \cos\Theta_{ij})/s$	$\mathbf{p}_i + \mathbf{p}_j$
<i>JADEP0</i>	$(\mathbf{p}_i + \mathbf{p}_j)^2 / s$	$\mathbf{E}_k = \mathbf{E}_i + \mathbf{E}_j; \vec{\mathbf{p}}_k = E_k \frac{\vec{\mathbf{p}}_i + \vec{\mathbf{p}}_j}{ \vec{\mathbf{p}}_i + \vec{\mathbf{p}}_j }$
<i>JADEP</i>	$(\mathbf{p}_i + \mathbf{p}_j)^2 / s$	$\vec{\mathbf{p}}_k = \vec{\mathbf{p}}_i + \vec{\mathbf{p}}_j; \mathbf{E}_k = \vec{\mathbf{p}}_k $
<i>Durham</i>	$2 \min(\mathbf{E}_i^2, \mathbf{E}_j^2)(1 - \cos\Theta_{ij})/s$	$\mathbf{p}_i + \mathbf{p}_j$
<i>Geneva</i>	$\frac{8\mathbf{E}_i\mathbf{E}_j(1 - \cos\Theta_{ij})}{9(\mathbf{E}_i + \mathbf{E}_j)^2}$	$\mathbf{p}_i + \mathbf{p}_j$
<i>LUCLUS</i>	$\frac{2 \vec{\mathbf{p}}_i \vec{\mathbf{p}}_j \sin(\Theta_{ij}/2)}{(\vec{\mathbf{p}}_i + \vec{\mathbf{p}}_j)}$	$\mathbf{p}_i + \mathbf{p}_j$

1 Jet Finder

- Design classes for a jet finder package
- Input is `vector<FourVector*>`
- User can query
 - Number of jets for given y_{at}
 - Value of y_{at} when # of jets changes $N-1 \rightarrow N$
 - Association of input 4-vectors with jets
 - Jet 4-vectors for given y_{at}

2 Track Fitting

- A typical HEP detector
 - tracking subdetectors with 2D or 3D readout
 - a uniform magnetic field (with small defects)
- Hit finding solved for each subdetector
 - have `vector<SVTHit>`, `vector<DCHHit>` etc.
- Want several track fit algorithms, e.g.
 - Simple 5-parameter helix fit
 - a Kalman filter
 - but don't worry now about algorithm details

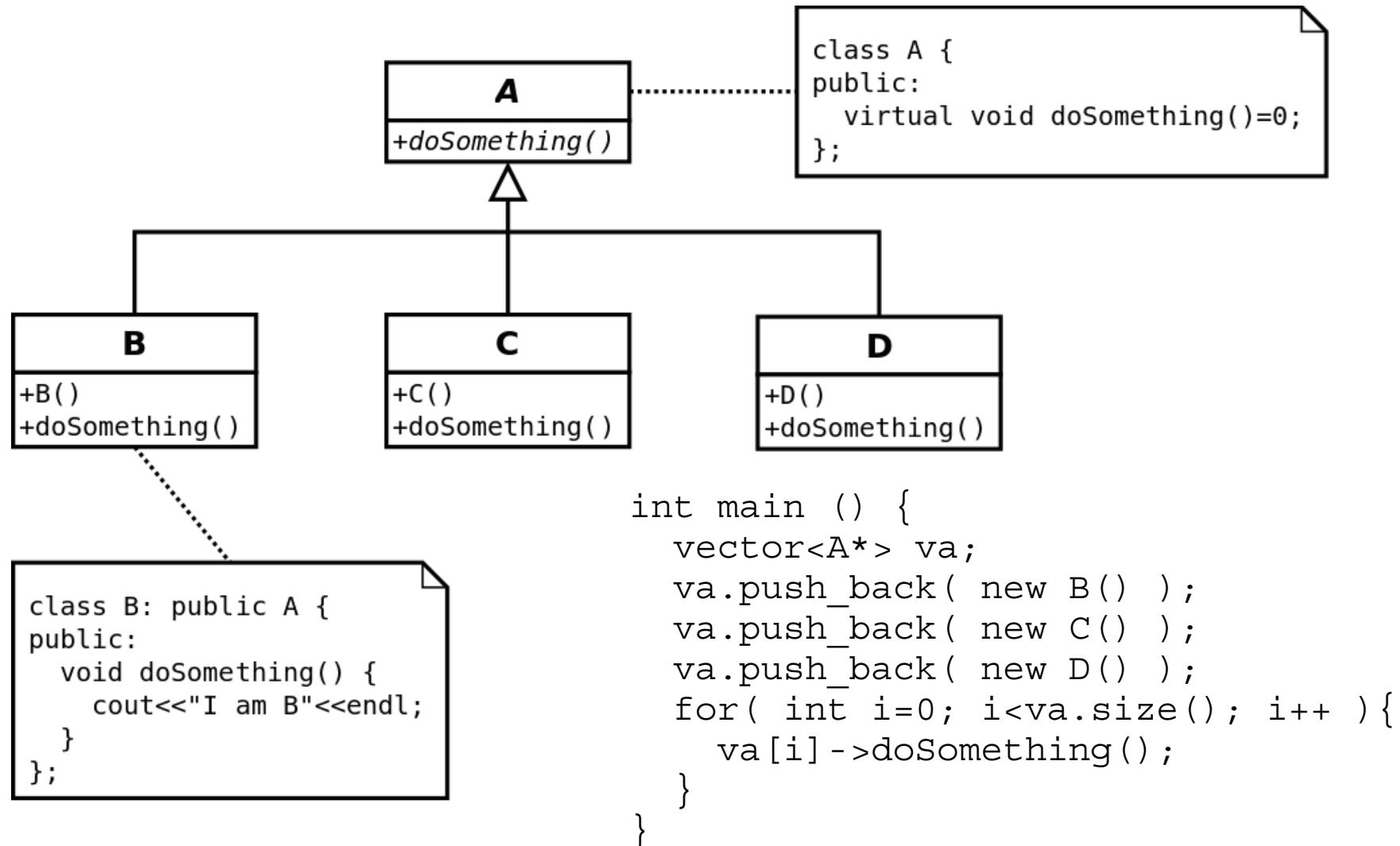
2 Track Fitting

- Design classes for track fitting code
- Start from hits of individual subdetectors
 - avoid direct coupling of concrete hit classes to track fitting classes
- Output is an object with methods for
 - momentum vector along trajectory
 - error matrix
 - start and end point
 - fit quality
 - hit association

3 Creating objects from DLLs

- An application (e.g. Athena) loads DLLs
- How can we create objects from the DLL?
 - direct creation not possible → want interchangeable DLLs
- DLL loaded via dlopen at run-time
 - need a mechanism to create objects once a DLL is loaded

4 Sequence Diagram



Draw the sequence diagram showing the actions in main