

# Track Residuals wrt Vertex

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# Ideas

- ✦ Effects of misalignment are “averaged” over many tracks in a primary vertex and, therefore could be smaller than for a single primary track
- ✦ We repeat with CMS data/MC some of tests which were used at ZEUS
- ✦ How CMS misalignment becomes visible in the distance of a track wrt vertex was discussed by M.Musich at Tracker Alignment Meeting (19/01/10)

## Data samples

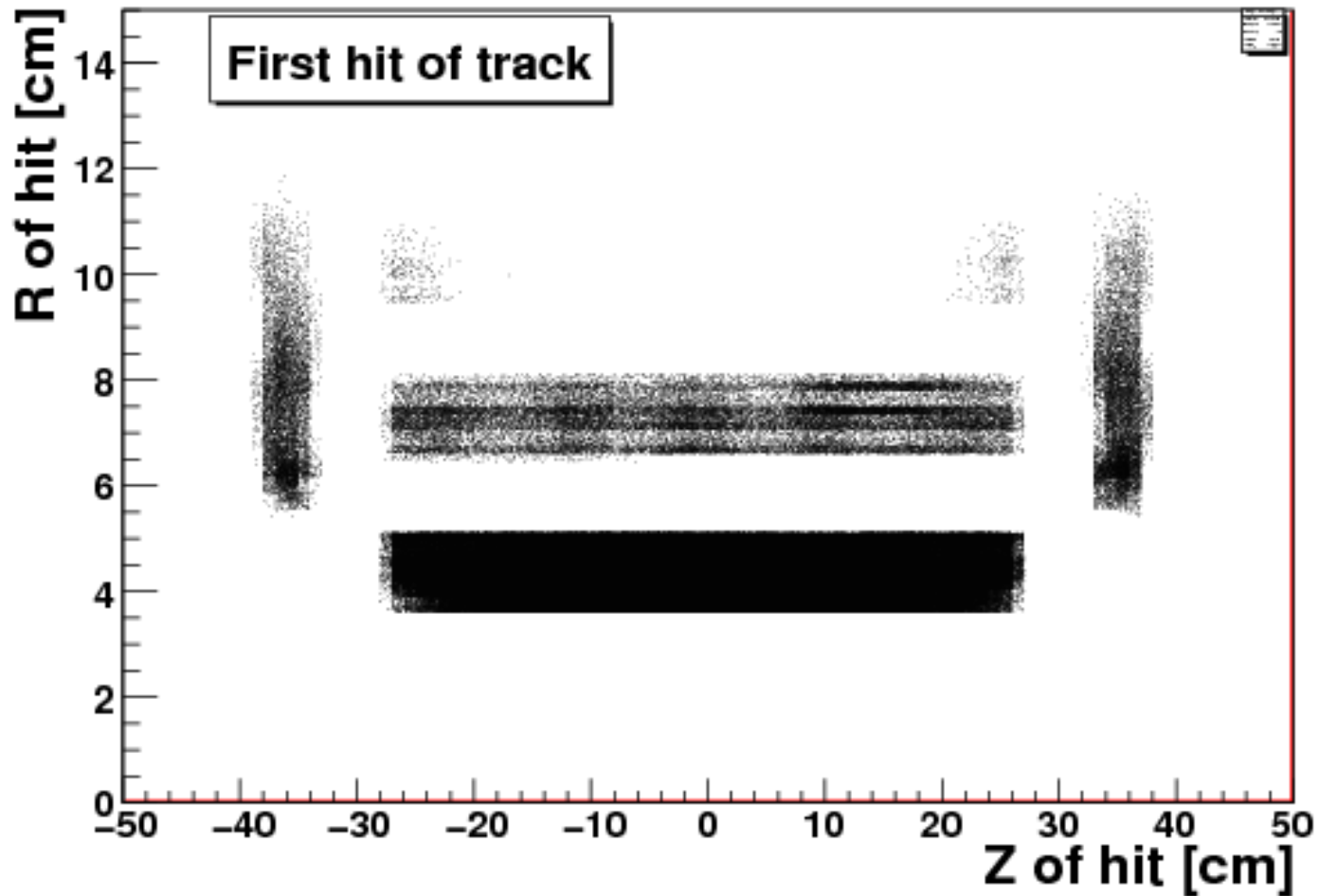
- ✓ We made a study for data:  
/Run2010A/Mu/RECO/Jun14thReReco\_v1/, runs 136088, 136100
- ✓ And MC: /CMSSW\_3\_8\_0\_pre8/RelVal.../GEN-SIM-RECO/MC\_38Y\_V6-v1/ for the mixture with MinBias, DIS, TTbar
- ✓ We used collections: offlinePrimaryVertices and generalTracks

## Selection criteria

- ✓ We select a primary vertex, loop over primary tracks and evaluate track's parameters wrt the vertex
- ✓ Select vertex if number of tracks  $> 10$
- ✓ For reference track:  $p > 1\text{GeV}$ ,  $\text{NDOF} > 4$
- ✓ Results are obtained without vertex refit

# Innermost hit of reference track

- 2-D histogram of R vs Z for first hit of selected tracks



## Parameters of vertex and track

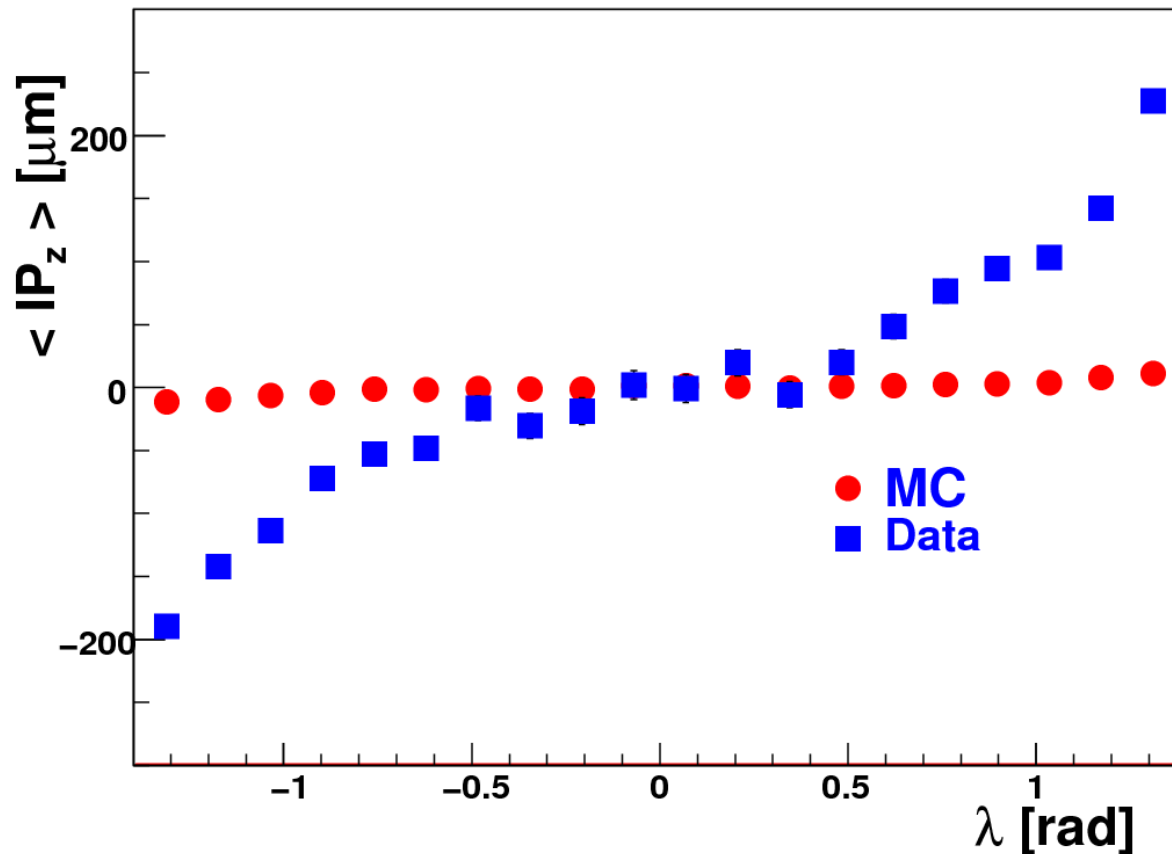
- Coordinate of the vertex  $V=(X_v, Y_v, Z_v)$
- For the reference track we calculate `trajectoryStateClosestToPoint(V)`
- Longitudinal Impact Parameter of the latter state we call  $IP_z$
- Innermost Measurement State of the reference track we propagate to the surface which is perpendicular to Z-axis and includes the point V
- Propagated track coordinates are  $(X_{tr}, Y_{tr}, Z_v)$

# What we study

- ✔ We study average values of track residuals wrt vertex:  
 $\langle IP_z \rangle$ ,  $\langle X_{tr} - X_v \rangle$ ,  $\langle Y_{tr} - Y_v \rangle$
- ✔ We use TProfile to show how the latter values depends on track angles  $\lambda$  ( $\pi/2 - \theta$ ) and  $\phi$
- ✔ I.e. no additional selections or fittings of distributions

## $\langle IP_z \rangle$ vs $\lambda$ for data and MC

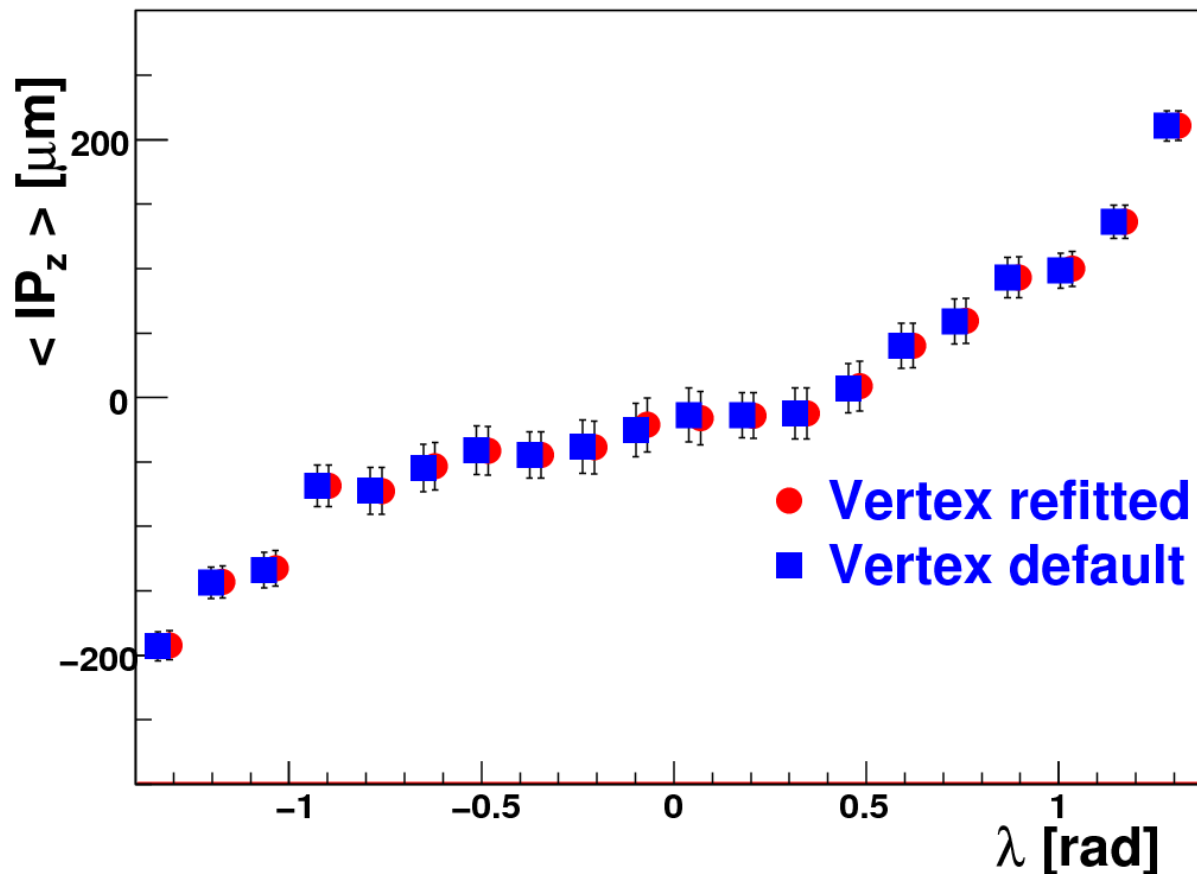
- Longitudinal impact parameter is biased for forward/backward tracks for data





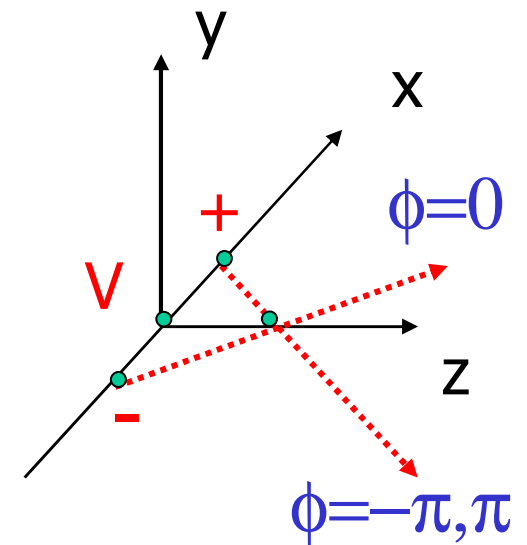
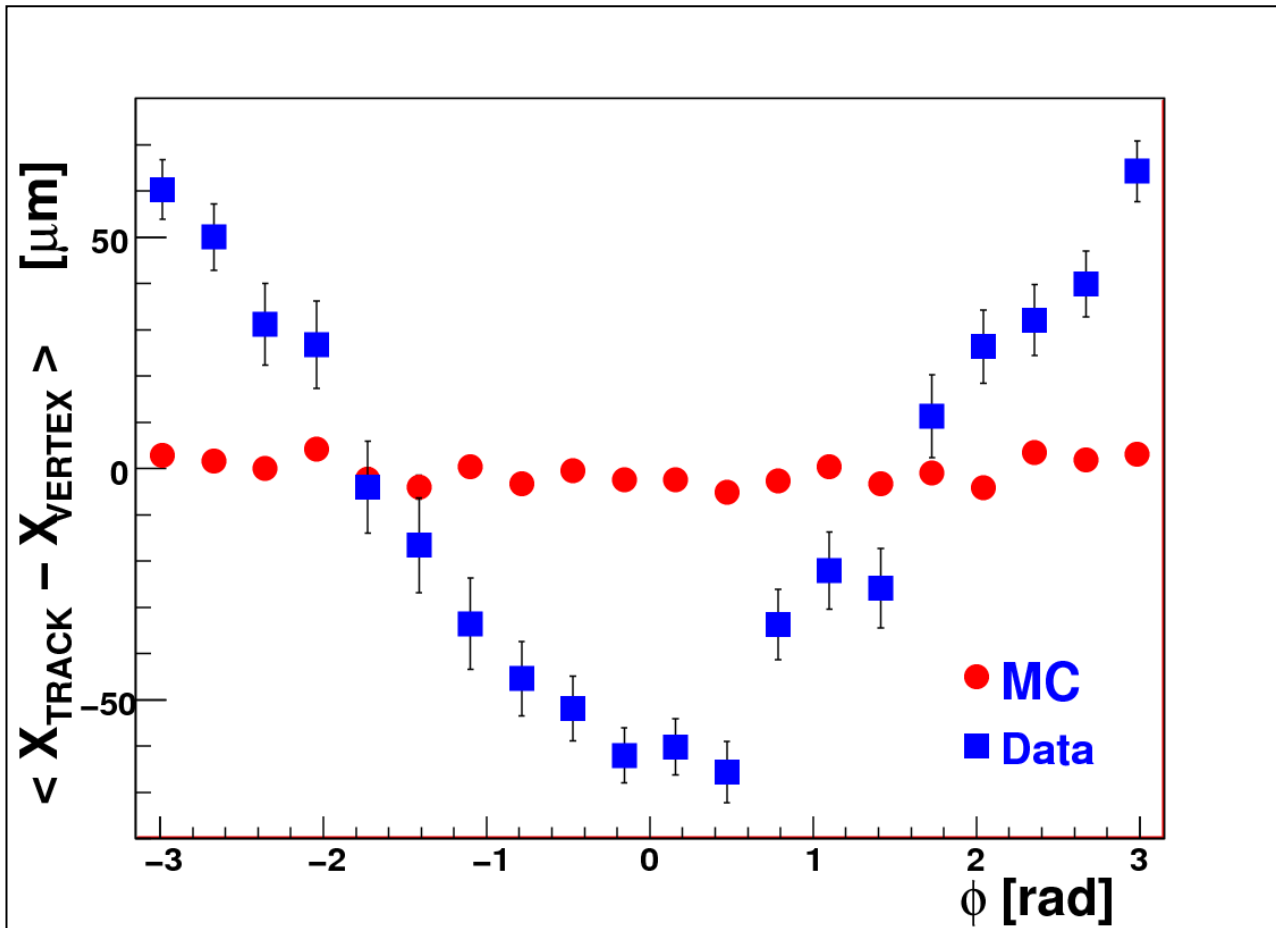
## $\langle IP_z \rangle$ vs $\lambda$ with vertex refit

- Unbiased refit of vertex (without reference track) shows almost no difference



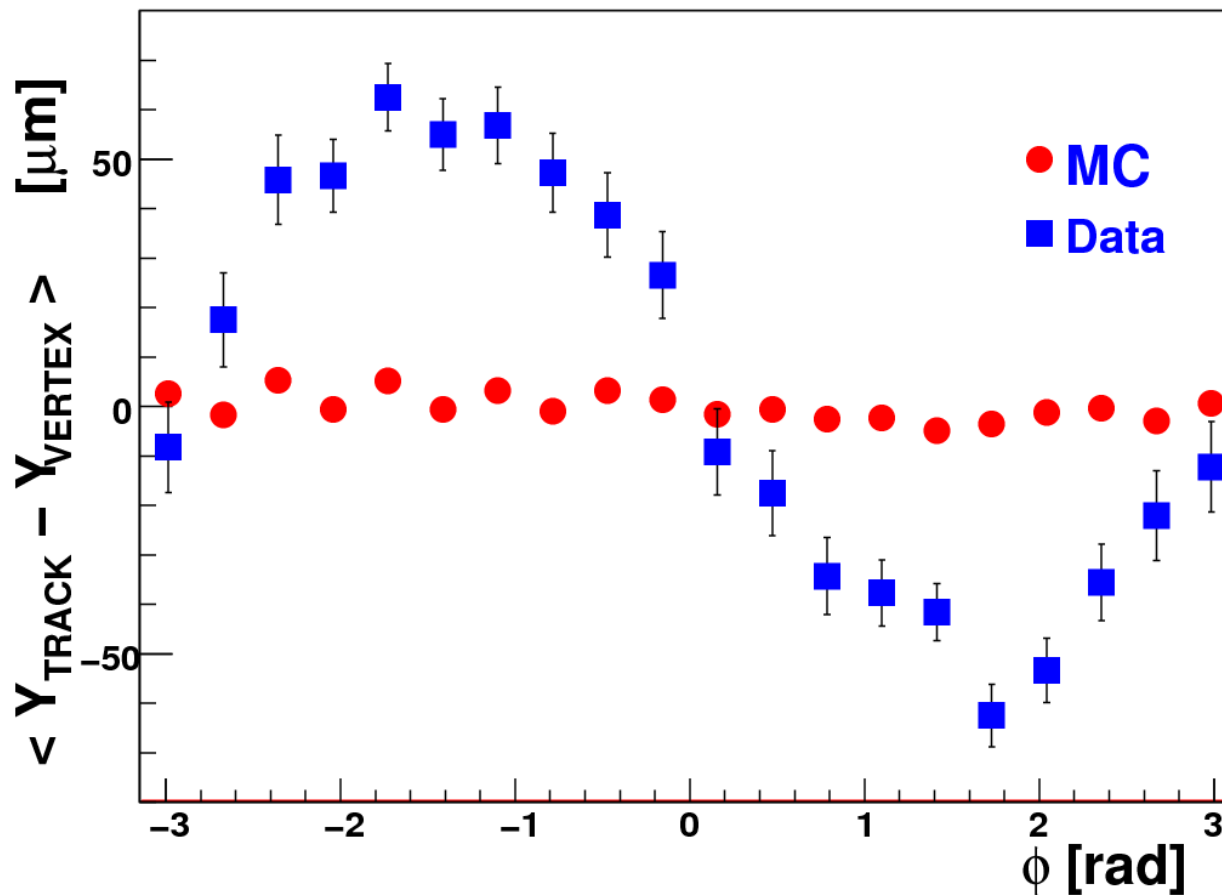
# $\langle X_{tr} - X_v \rangle$ vs $\phi$ for forward tracks

- $X_{tr}-X_v$  are biased for forward tracks ( $\lambda > 0.8$ ) for data



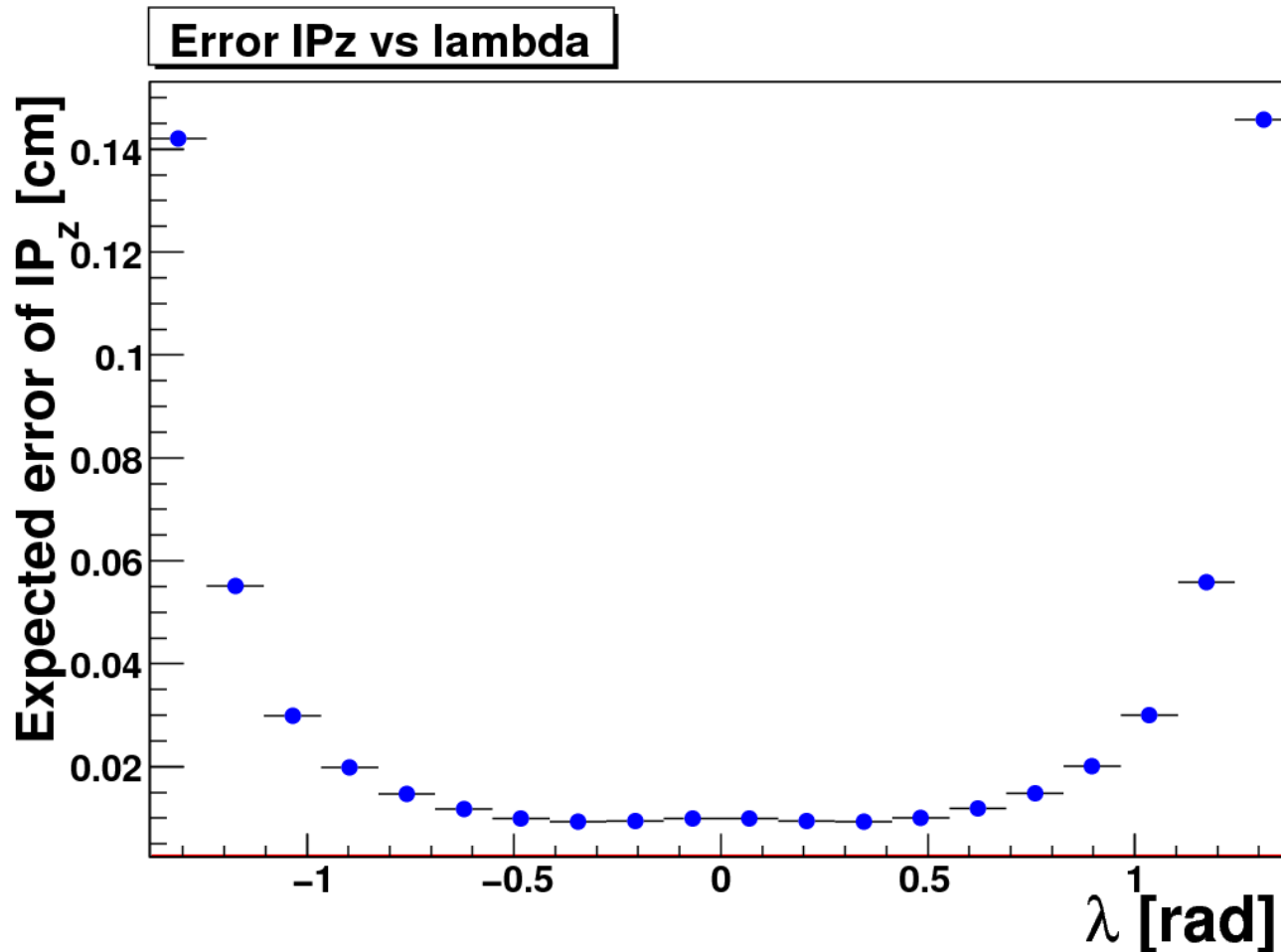
# $\langle Y_{tr} - Y_v \rangle$ vs $\phi$ for forward tracks

- Ytr-Yv are biased also for forward tracks ( $\lambda > 0.8$ ) for data



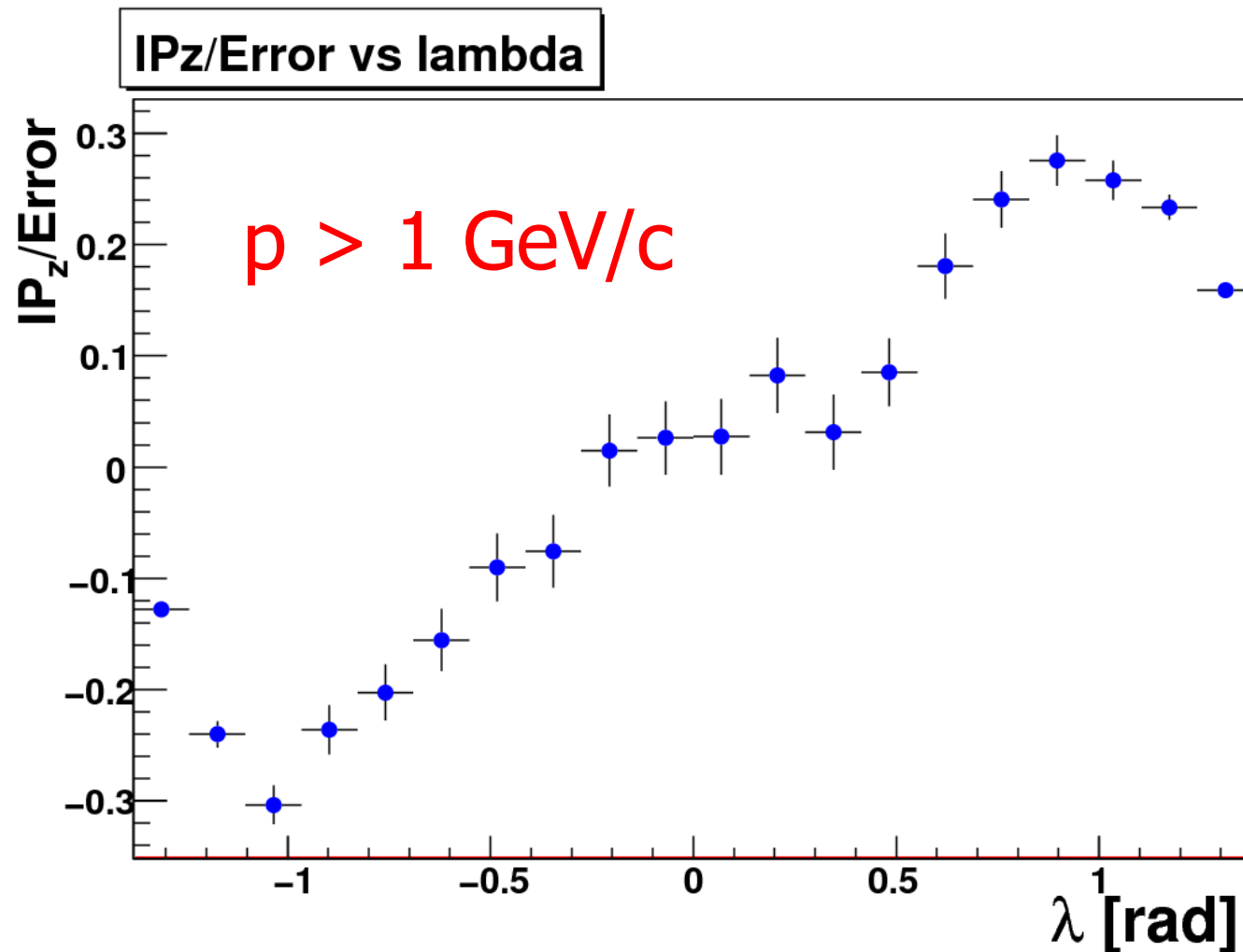
# Expected error of IPz vs $\lambda$ for data

- Expected error of the longitudinal impact parameter increases for forward/backward tracks



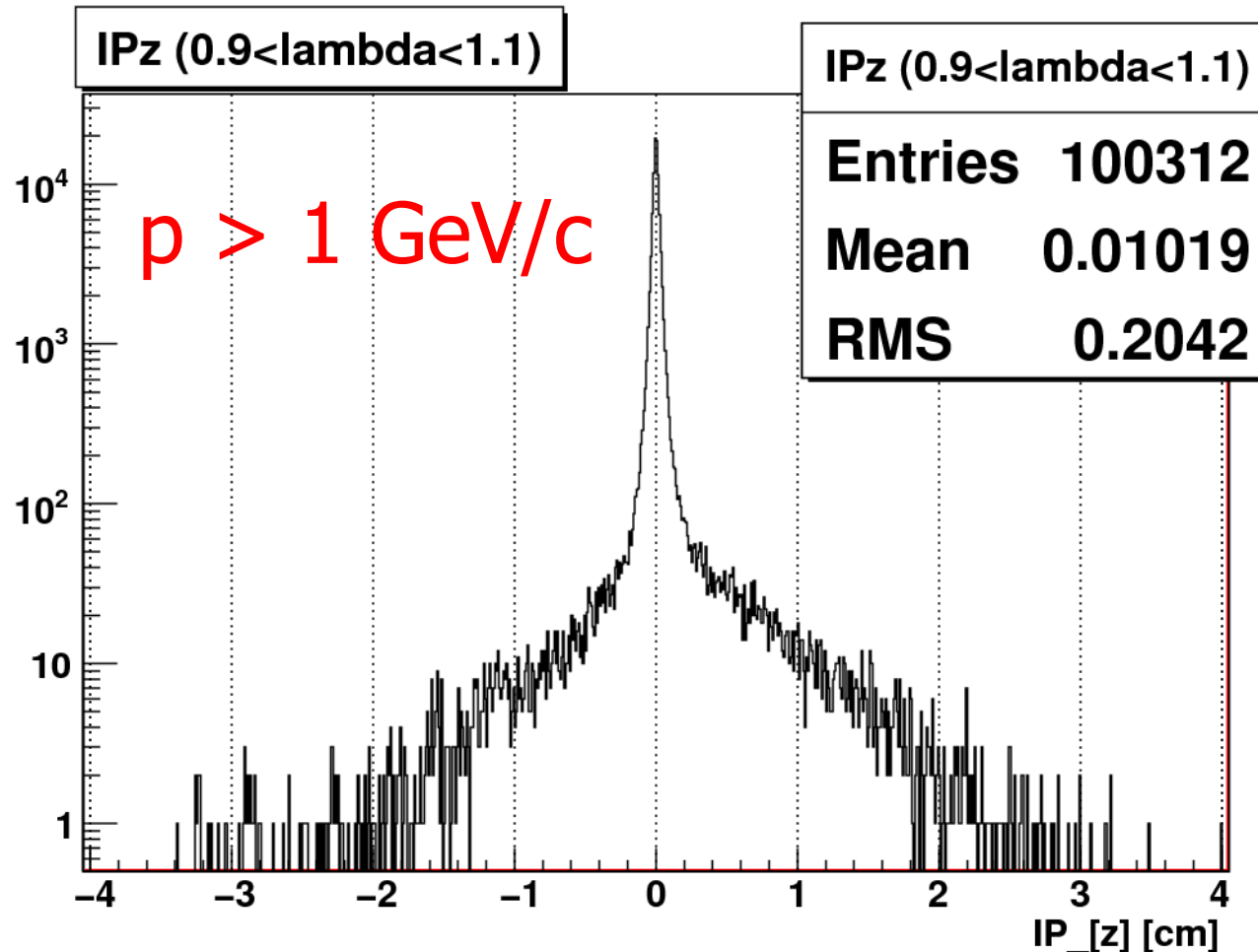
## $\langle \text{IP}_z/\text{error} \rangle$ vs $\lambda$ for data

- Maximal bias of  $\langle \text{IP}_z \rangle$  is about 0.3 of expected error



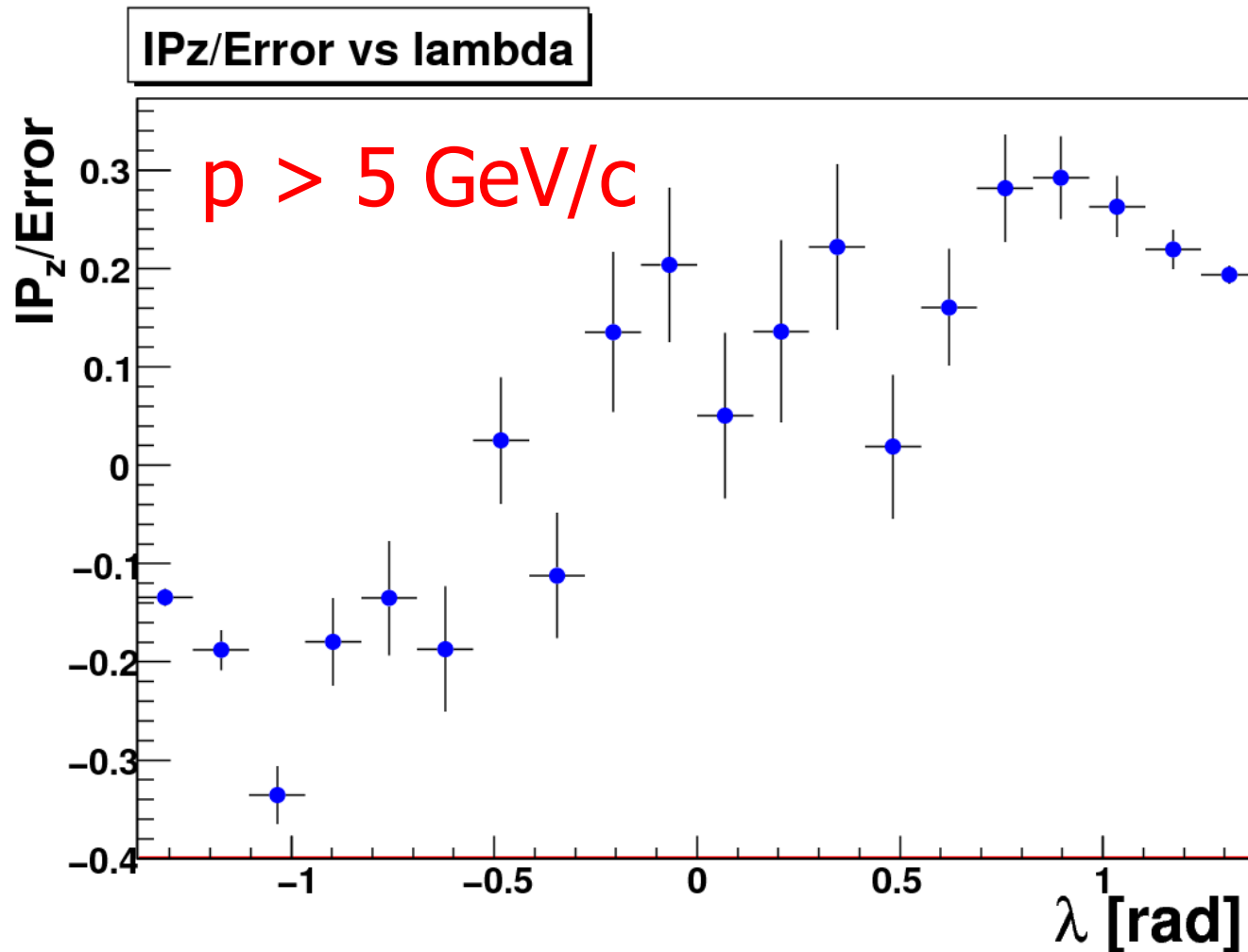
# IPz for forward tracks ( $0.9 < \lambda < 1.1$ ) for data

- Distribution includes tails



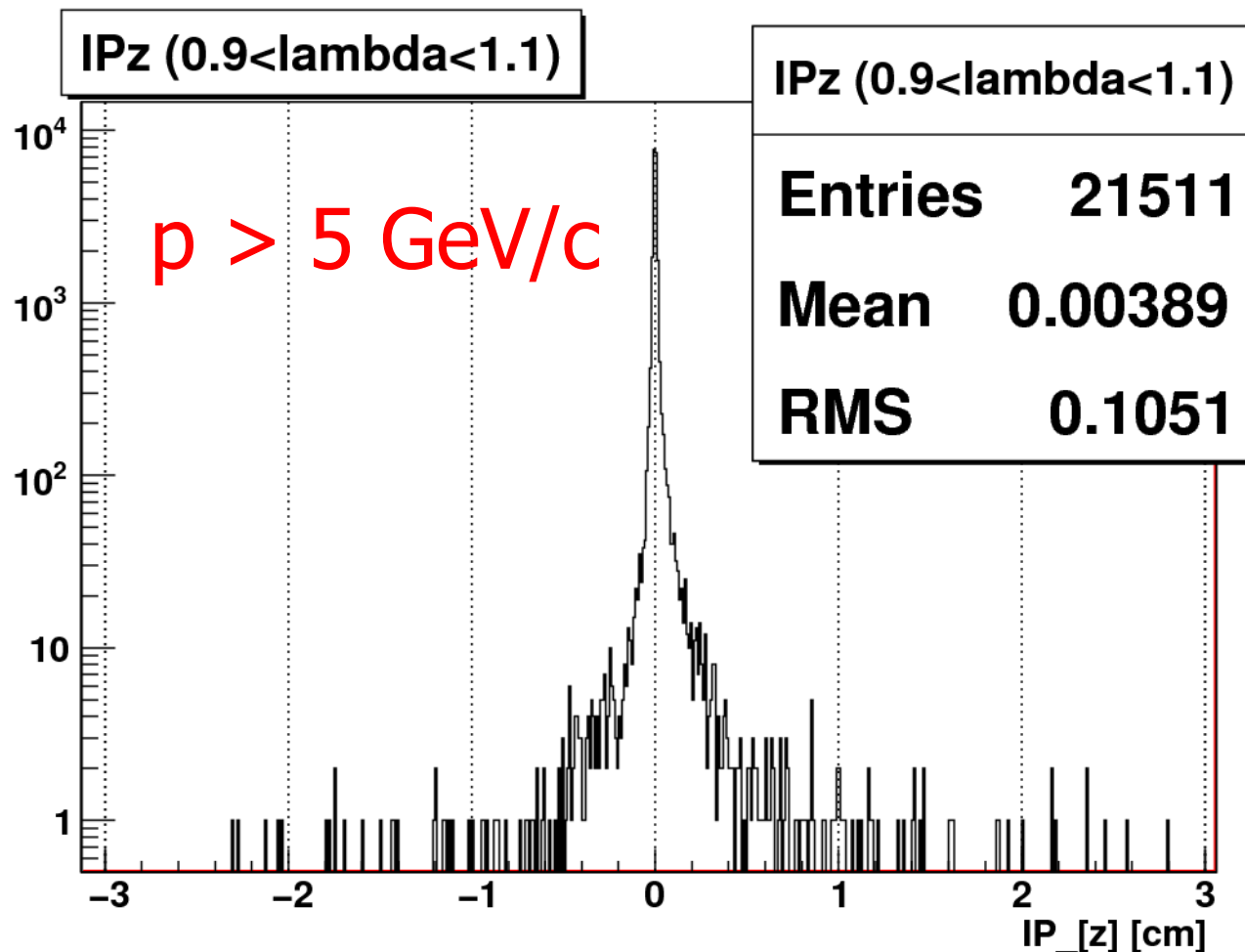
# $\langle \text{IP}_z/\text{error} \rangle$ vs $\lambda$ for data ( $p > 5\text{GeV}/c$ )

- Maximal bias of  $\langle \text{IP}_z \rangle$  is also about 0.3 of expected error



# IPz for forward tracks ( $0.9 < \lambda < 1.1$ ) $p > 5 \text{ GeV}/c$

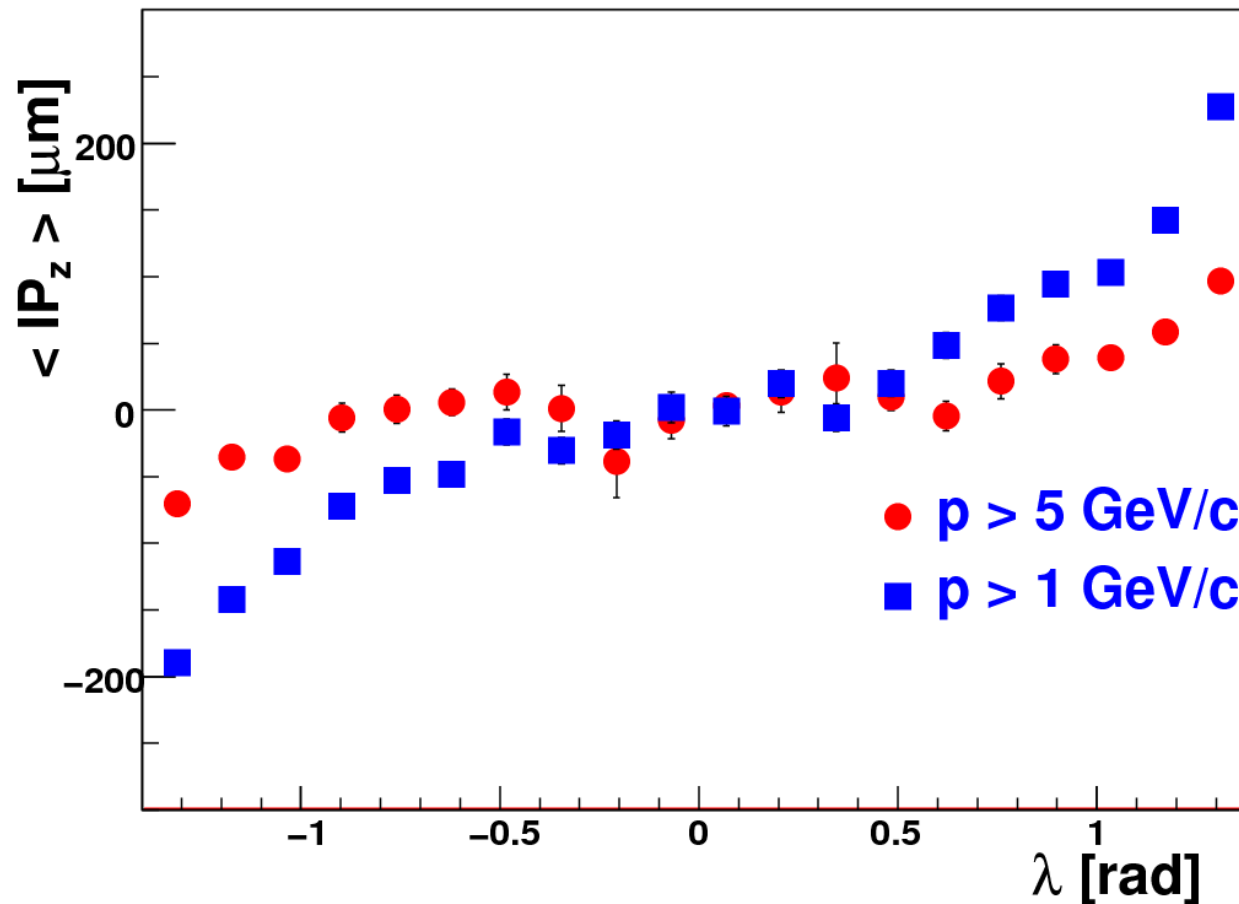
- Both bias and RMS are smaller for higher momentum





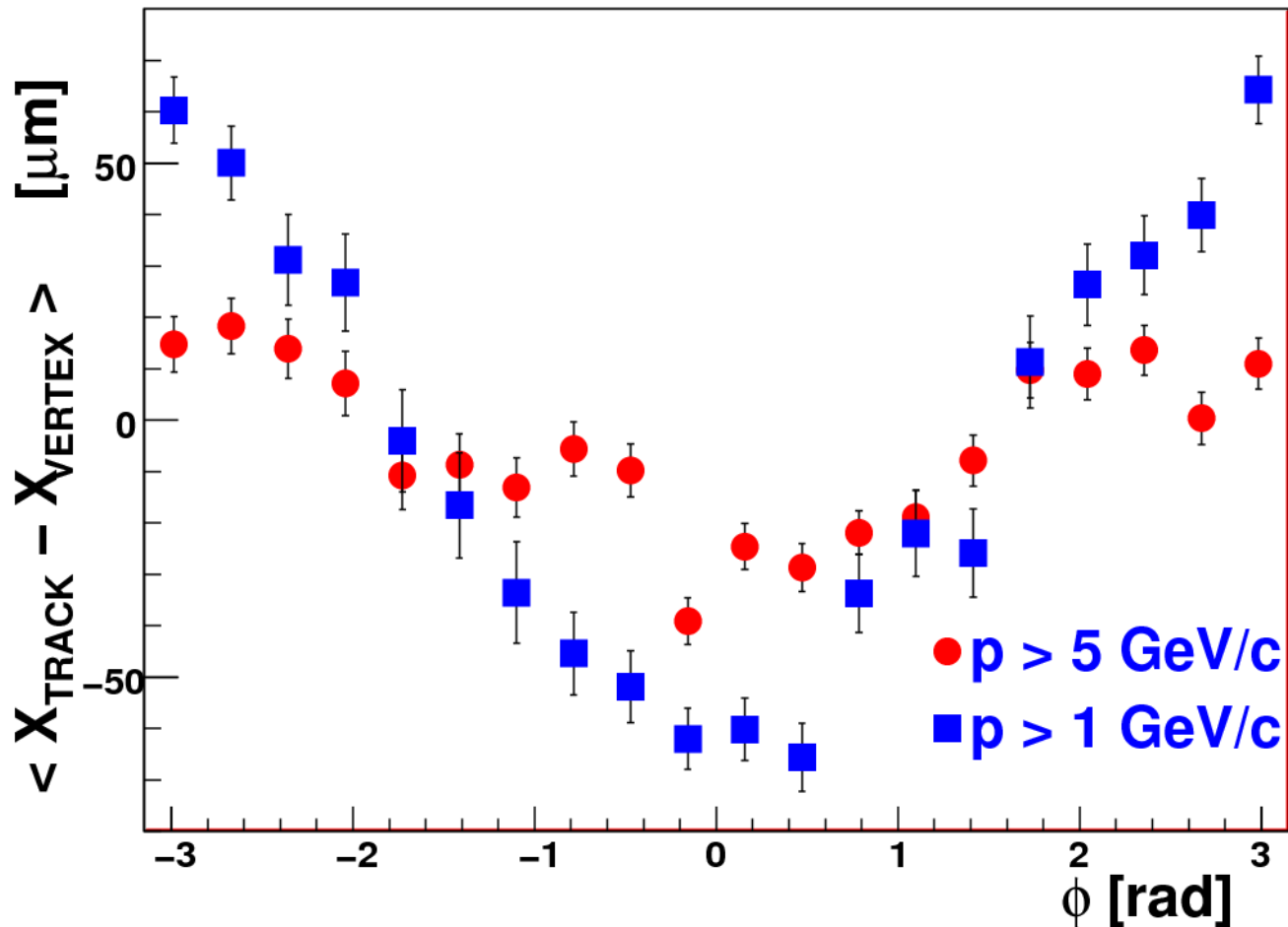
# $\langle IP_z \rangle$ vs $\lambda$ for data for $p > 1$ or $5$ GeV/c

- Bias is smaller for higher momentum cut



# $\langle X_{tr} - X_v \rangle$ vs $\phi$ for forward ( $\lambda > 0.8$ )

- Bias of  $X_{tr}-X_v$  is also smaller for higher momentum cut



# S U M M A R Y

- ✔ Tracks residuals wrt vertices show bias
- ✔ The latter bias could be an indicator of misalignment
- ✔ Residuals of IPz can be included in the objective function for Millepede
- ✔ The implementation of residuals  $X_{tr}-X_v$  and  $Y_{tr}-X_v$  is also possible for Millepede, but we have to compare it with the usage of track impact parameter wrt beam line (vertex errors and beam width)

# Backup Slides

▼ no slides more