

# Design actual status

Two stations on the same kinematic mount platform. Cheap X stages

X axis PI L-408.501200

<https://www.physikinstrumente.com/en/products/linear-stages/stages-with-stepper-dc-brushless-dc-bldc-motors/l-408-compact-linear-stage-100000035/>

Y axis PI Q-545

<https://www.physikinstrumente.com/en/products/linear-stages/miniature-linear-stages/q-545-q-motion-precision-linear-stage-103170/>

“specular” layout to maximize accessibility to detectors for mounting / dismounting / maintenance (once cage removed)

Faraday cage made of bent s.steel (or aluminum) sheets

Air sealing of cage to base plate by means of gasket

E.g. 3D printed gasket

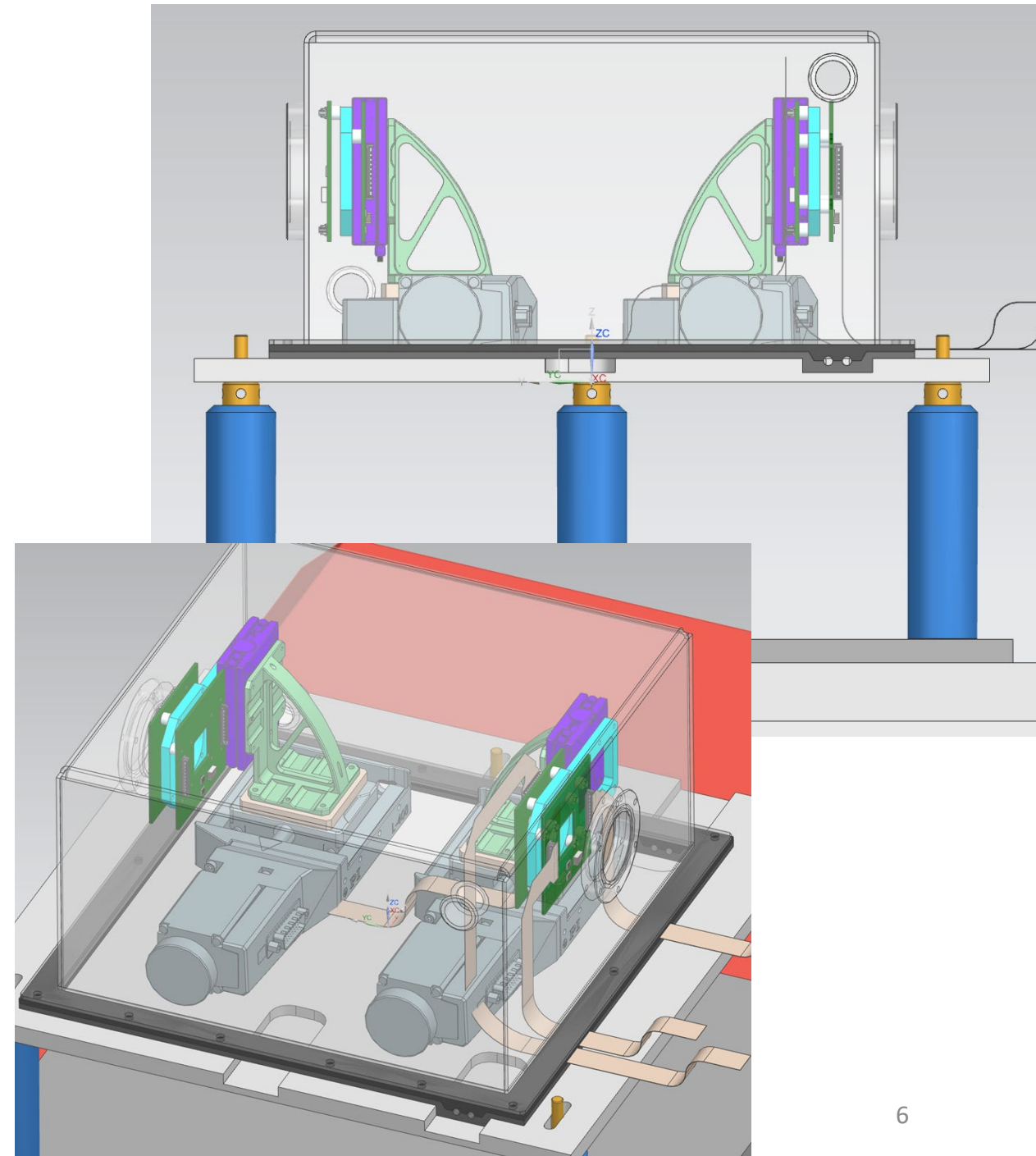
Flat cables compressed between gaskets

(flat cables bent/folded at  $45^\circ$  to get  $90^\circ$  deg angle and adequate degree of freedom for movements .. )

Slots in the base plate to pass cables (sealed with gasket)

Circular flanges for beam Kapton windows

Dry air or N<sub>2</sub> in/out vent ports at opposite corners



## .. possible missing inputs/requirements

Full platform remotely adjustable?

- -Which direction(s) and angle(s) ?

Needing to move detectors outside beam?

- E.g. longer stroke, now 25 mm
- full platform may displace, two position mechanism

Any requirement on:

- distance between detectors couples?
- distance of cage / windows from detectors?
- Inlet windows requirements?
- “exit window” needed?
- Signals cables routing
  - (grouped vs spaced, shielded, which direction)
- Separation/distance/shielding
  - between stages cables and detector cables?
- Anything else....?

