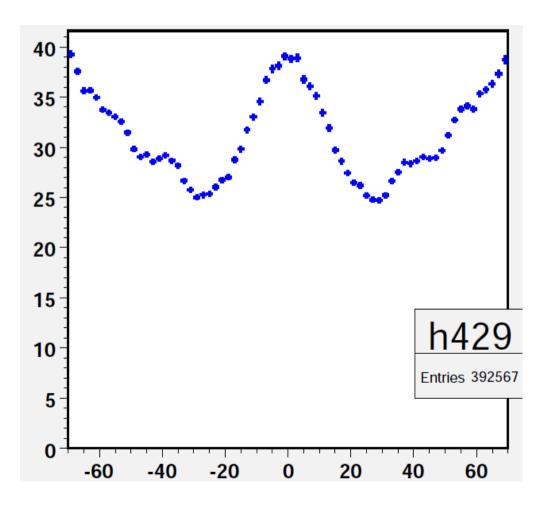
### **Pixel resolution studies**

Daniel Pitzl, DESY CMS Tracker Upgrade 23.2.2011



- Triplet method
- Hit resolutions
- some dependencies

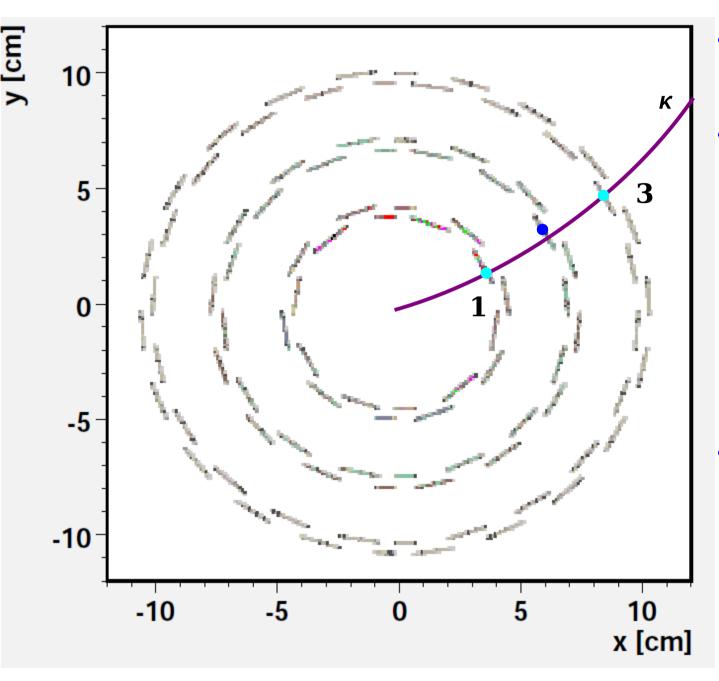
## Questions

- What is the intrinsic position resolution of the barrel pixel detector?
  - In  $r\phi$  and in z, data and MC.
  - Test of alignment, hit reconstruction, and track reconstruction.
- Future monitoring:
  - rφ resolution is expected to degrade with radiation damage (mobility degradation, Lorentz angle reduction, and trapping all reduce the charge sharing between pixels in a cluster).

# Tools

- Overlap regions (2 hits in one layer):
  - used extensively during CMS commissioning,
  - less sensitive to misalignment.
  - Iow statistics, only explores sensor edge, not used here.
- Triplets (hits in 3 layers).

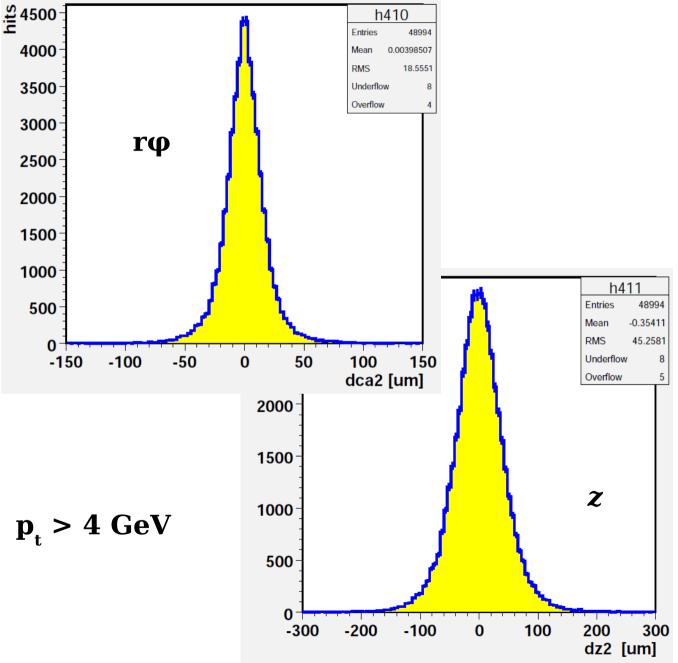
# **Pixel triplets**



- Select tracks with hits in 3 pixel layers.
- Redefine track:
  - curvature from full tracker,
  - position and angles from hits 1 and 3.
  - analytic code from J. Gassner 1996.
- Interpolate to middle layer:
  - residual between track and hit.

D. Pitzl (DESY): Pixel resolution

# **Triplet residuals**

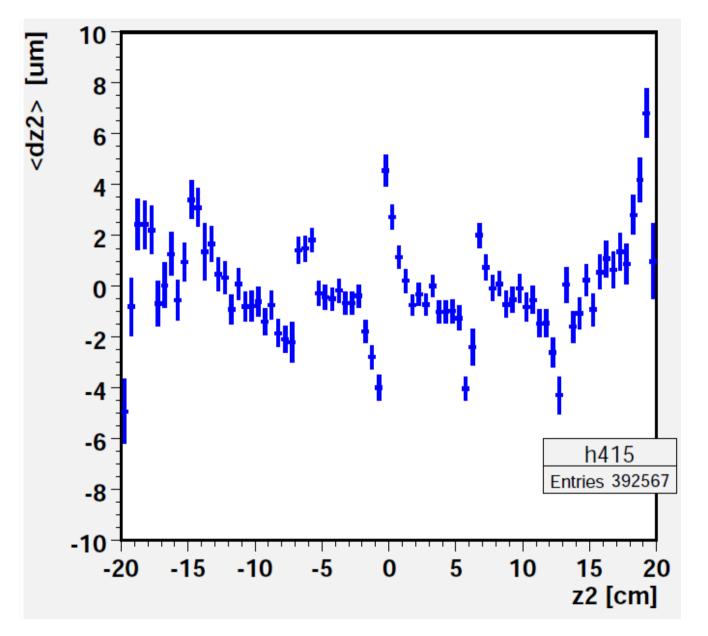


- RECO data taken Oct 2010, Dec22 reRepro, minBias and Zmumu.
- Using generalTracks.
- Using TransientRecHits:
  - alignment applied.
  - Mean residual is zero:
    - Method works,
    - alignment is good.
- Hits on tracks:

•

 no outliers, no background.

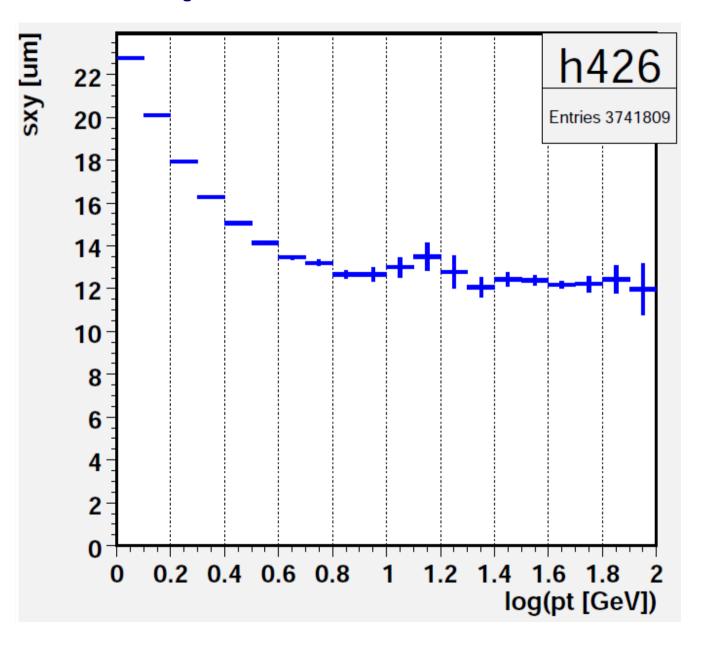
### z dependence of mean z residual



- ±4 µm trend repeats every 6.4 cm:
  - bowed modules?
  - fodder for the alignment group...

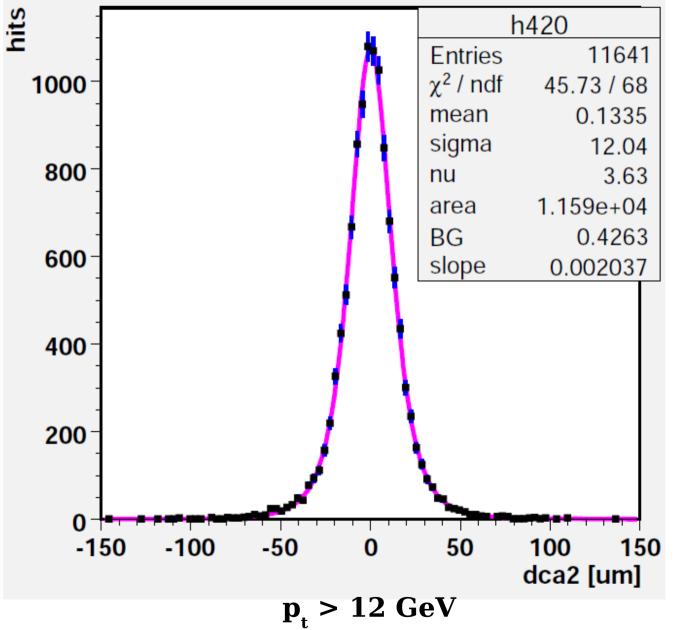
D. Pitzl (DESY): Pixel resolution

# $\mathbf{p}_{t}$ dependence of $\mathbf{r}\boldsymbol{\phi}$ resolution



- Width of the residual distribution is affected by multiple scattering in layers 1 and 2:
  - Need p<sub>t</sub> > 4 GeV to observe intrinsic pixel resolution.

# triplet r $\phi$ residuals at high $p_{t}$



 Width of the residual distribution at high p<sub>+</sub>:

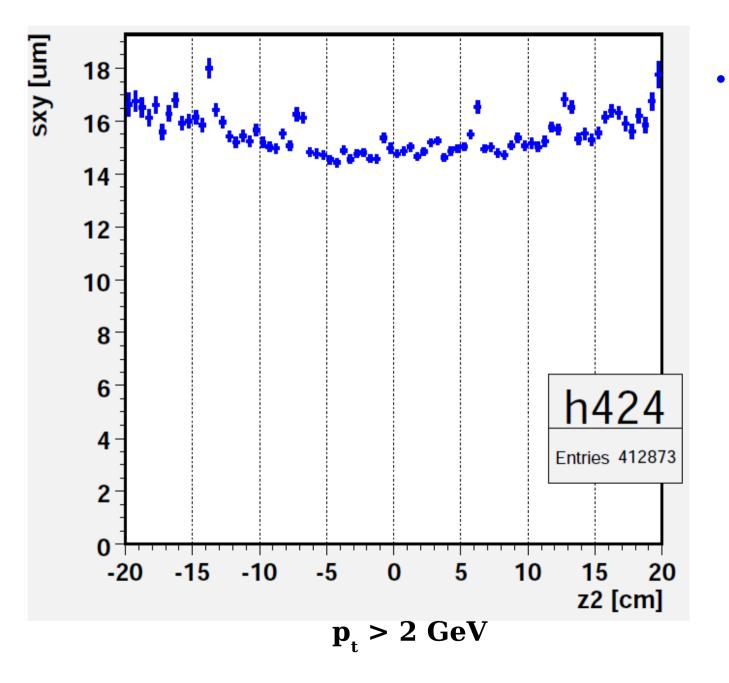
$$\sigma_r^2 = \sigma_2^2 + (\sigma_1/2)^2 + (\sigma_3/2)^2$$

• All  $\sigma$  equal:

$$\sigma_r = \sqrt{3/2} \sigma_i$$

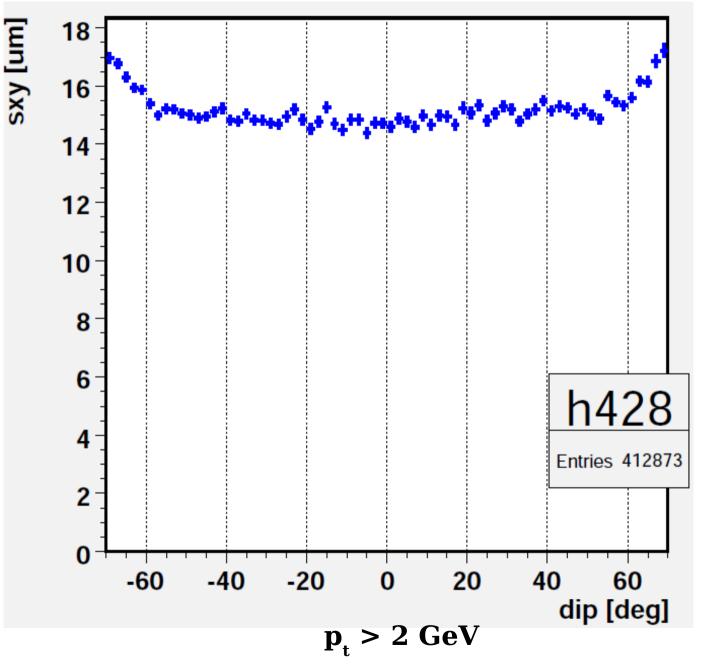
- Result:
  - σ<sub>i</sub> = 10 μm,
  - ▶ with 100 µm pitch.
  - in 3.8 T.

#### z dependence of r $\phi$ resolution



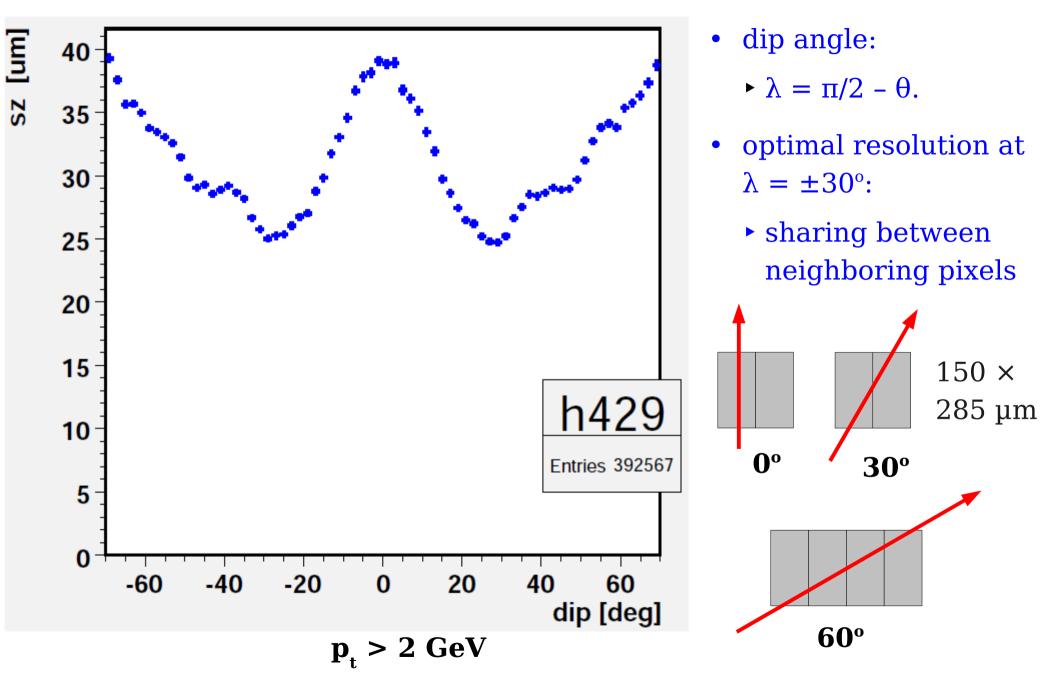
rφ resolution deteriorates at *z*gaps between modules.

## dip angle dependence of $r\phi$ resolution



- dip angle:
  - $\lambda = \pi/2 \theta$ .
- rφ resolution deteriorates at large dip angles:
  - poor curvature measurement in the tracker?

## dip angle dependence of z resolution



## **Summary**

- Tracks with 3 pixel hits:
  - one degree of freedom in *z*, e.g. the middle hit.
  - use of an external curvature measurement gives one degree of freedom in rφ as well: triplet method.
  - (remove any bias: repeat track fit without 2<sup>nd</sup> pixel layer...).
- Mean residuals are zero within a few microns:
  - Alignment is good
  - small systematic trend along z with module structure.
- Pixel r $\phi$  resolution is 10  $\mu$ m, measured at high  $p_t$ .
- Pixel *z* resolution:
  - varies with angle of incidence (or rapidity).
  - reaches 25 μm, with 150 μm pitch.
- Next:
  - ► look at MC.