### Integration by parts

#### Andrey Grozin

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# Steps to solve a problem

 Diagrams generation, classification into topologies, routing momenta

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- Tensor and Dirac algebra in numerators, reduction to scalar Feynman integrals
- Reduction of scalar Feynman integrals to master integrals
- ▶ Calculation of master integrals

# Steps to solve a problem

- Diagrams generation, classification into topologies, routing momenta
- ► Tensor and Dirac algebra in numerators, reduction to scalar Feynman integrals
- Reduction of scalar Feynman integrals to master integrals
- ▶ Calculation of master integrals

Expansion in small ratios of momenta and masses (the method of regions)

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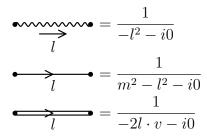
### Feynman graphs and Feynman integrals

Loop momenta  $k_1, \ldots, k_L$ External momenta  $p_1, \ldots, p_E$  $q_i = k_1, \ldots, k_L, p_1, \ldots, p_E$ Line momenta  $l_1, \ldots, l_I$  — linear combinations of  $q_i$ 

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### Feynman graphs and Feynman integrals

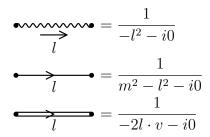
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#### Feynman graphs and Feynman integrals

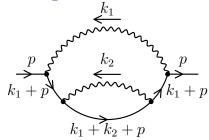
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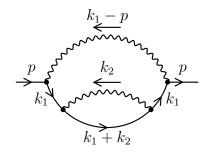


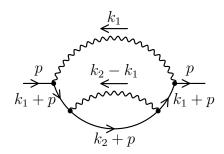
Denominators  $D_i$  are linear in  $s_{ij} = k_i \cdot q_j$ 

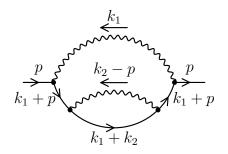
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### Routing momenta



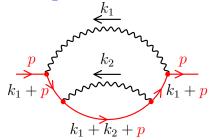


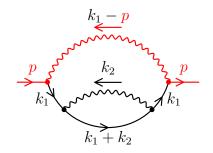


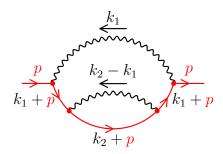


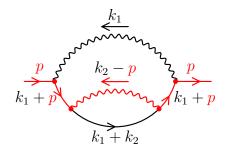
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# Routing momenta

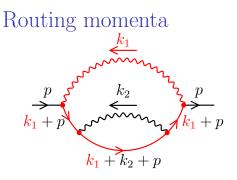


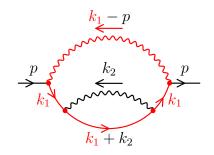


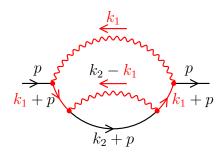


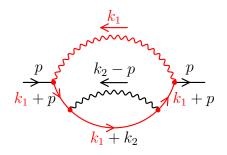


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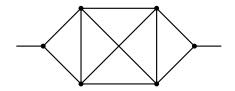






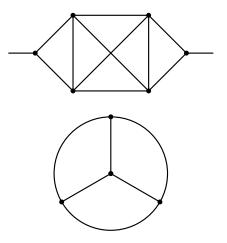
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# Symmetries





# Symmetries



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### Irreducible numerators

There are

$$N = \frac{L(L+1)}{2} + LE$$

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scalar products  $s_{ij} = k_i \cdot q_j$ 

#### Irreducible numerators

There are

$$N = \frac{L(L+1)}{2} + LE$$

scalar products  $s_{ij} = k_i \cdot q_j$ (E + 1)-legged L-loop diagrams: the maximum number of denominators

$$M = 3L + E - 2 \qquad N - M = \frac{(L - 1)(L + 2E - 4)}{2}$$

Vacuum diagrams

$$M = 3(L-1) \qquad N - M = \frac{(L-2)(L-3)}{2}$$

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Irreducible numerators  $D_{M+1}, \ldots, D_N$ 

### Scalar Feynman integral

$$I(n_1, \dots, n_N) = \int d^d k_1 \cdots d^d k_L f(k_1, \dots, k_L)$$
$$f(k_1, \dots, k_L) = \frac{1}{D_1^{n_1} \cdots D_N^{n_N}}$$

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 $D_i$  are linear functions of  $s_{ij} = k_i \cdot q_j$ Point in *L*-dimensional integer space For irreducible numerators,  $n_i \leq 0$ 

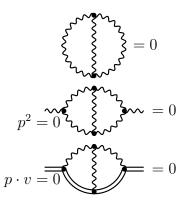
### Dimensionality: 0 scales

 $[\mathrm{mass}]^{Ld-n}$ 



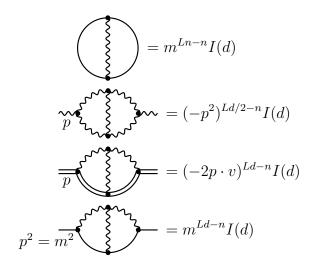
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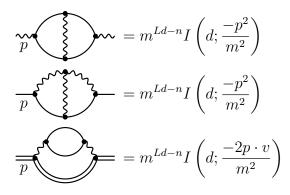
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Dimensionality: 1 scale



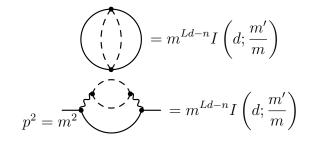
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#### Dimensionality: 2 scales



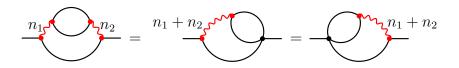
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Dimensionality: 2 scales

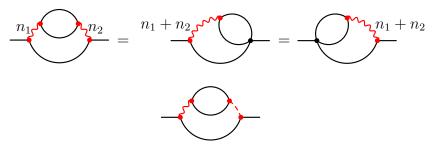


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### Self-energy insertions

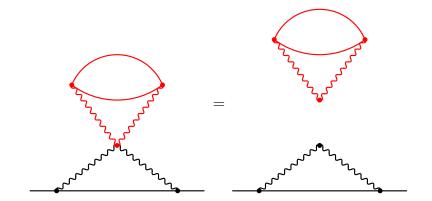


## Self-energy insertions

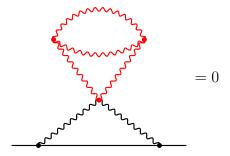


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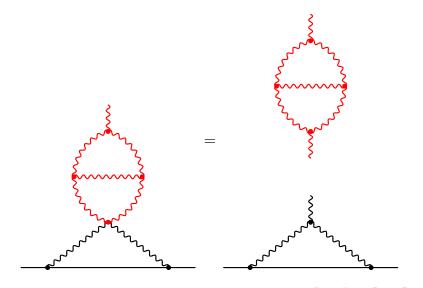
Linearly-dependent denominators



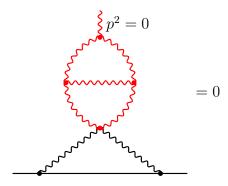
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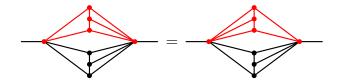
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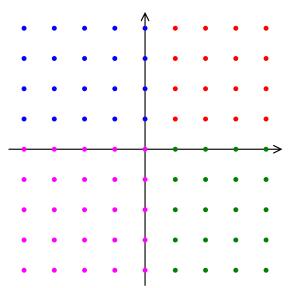


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Sectors



Partial ordering

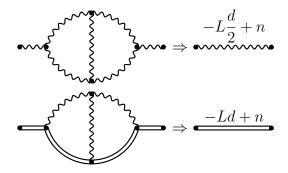
#### Sectors

▶ For irreducible numerators, sectors  $n_i > 0$  don't exist

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- ► Trivial sectors: I = 0 (at least, the sector with all n<sub>i</sub> ≤ 0 is trivial)
- Sectors just above trivial ones: often an explicit formula via Γ functions
- ▶ Some sectors are related by symmetries

#### Non-integer indices



d cannot be compared with integers  $\Rightarrow$  No sectors along this index

# Integration momenta substitutions Lie group

$$k_i \to M_{ij}q_j = A_{ij}k_j + B_{ij}p_j$$
$$M = \begin{pmatrix} A_{11} & \cdots & A_{1L} & B_{11} & \cdots & B_{1E} \\ \vdots & \ddots & \vdots & B_{11} & \cdots & B_{1E} \\ A_{L1} & \cdots & A_{LL} & B_{L1} & \cdots & B_{LE} \end{pmatrix}$$
$$\det \mathbf{A} \neq 0$$

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$$\det A \neq 0$$

Infinitesimal transformations  $k_i \rightarrow k_i + \alpha q_j$ 

$$f \to f + \alpha q_j \cdot \partial_i f$$

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If j = i $d^d k_i \to (1 + \alpha)^d d^d k_i = (1 + \alpha d) d^d k_i$ 

# Lie algebra

$$\int d^d k_1 \cdots d^d k_L O_{ij} f = 0$$
$$O_{ij} = \partial_i \cdot q_j \qquad \partial_i = \frac{\partial}{\partial k_i}$$

R. Lee (2008)

$$[O_{ij}, O_{i'j'}] = \delta_{ij'}O_{i'j} - \delta_{i'j}O_{ij'}$$

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$$[O_{ij}, O_{i'j'}] = \delta_{ij'}O_{i'j} - \delta_{i'j}O_{ij'}$$

$$O_{ij} = d\delta_{ij} + q_j \cdot \sum_n \frac{\partial D_n}{\partial k_i} \frac{\partial}{\partial D_n}$$

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# Operator notation

$$(\mathbf{n}_i F)(n_1, \dots, n_i, \dots, n_N) = n_i F(n_1, \dots, n_i, \dots, n_N)$$
  

$$(\mathbf{i}^+ F)(n_1, \dots, n_i, \dots, n_N) = F(n_1, \dots, n_i + 1, \dots, n_N)$$
  

$$(\mathbf{i}^- F)(n_1, \dots, n_i, \dots, n_N) = F(n_1, \dots, n_i - 1, \dots, n_N)$$
  

$$\mathbf{i}^+ \mathbf{i}^- = \mathbf{i}^- \mathbf{i}^+ = 1 \qquad [\mathbf{i}^\pm, \mathbf{n}_j] = \pm \delta_{ij} \mathbf{i}^\pm$$

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$$\hat{\mathbf{i}}^+ = \mathbf{n}_i \mathbf{i}^+$$
  
 $[\hat{\mathbf{i}}^+, \mathbf{j}^-] = \delta_{ij}$ 

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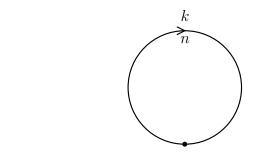
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$$\hat{\mathbf{i}}^+ = \mathbf{n}_i \mathbf{i}^+$$
  
 $[\hat{\mathbf{i}}^+, \mathbf{j}^-] = \delta_{ij}$ 

$$\int d^d k_1 \cdots d^d k_L O_{ij} f = 0 = P_{ij}(\hat{\mathbf{i}}^+, \mathbf{i}^-) I(n_1, \dots, n_N)$$
$$[P_{ij}, P_{i'j'}] = \delta_{ij'} P_{i'j} - \delta_{i'j} P_{ij'}$$

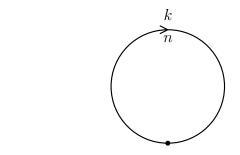
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$$\frac{1}{i\pi^{d/2}} \int \frac{d^d k}{D^n} = m^{d-2n} V(n) \qquad D = m^2 - k^2 - i0$$

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by dimensionality



$$\frac{1}{i\pi^{d/2}} \int \frac{d^d k}{D^n} = m^{d-2n} V(n) \qquad D = m^2 - k^2 - i0$$

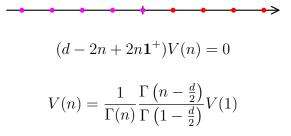
by dimensionality

$$V(n) = \frac{1}{i\pi^{d/2}} \int \frac{d^d k}{D^n} \qquad D = 1 - k^2 - i0$$

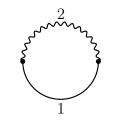


$$(d-2n+2n\mathbf{1}^+)V(n)=0$$

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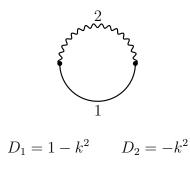


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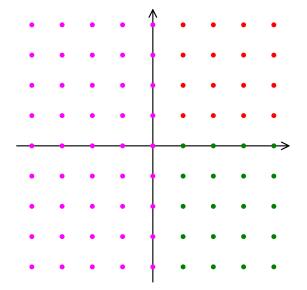
$$D_1 = 1 - k^2$$
  $D_2 = -k^2$ 

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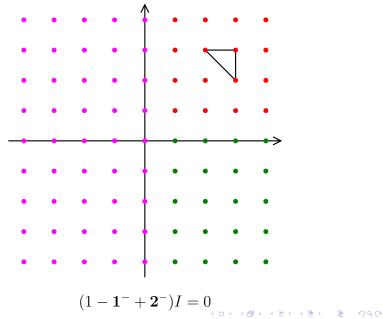


 $D_1 - D_2 = 1$ 

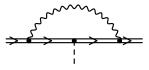
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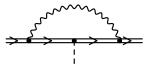
Linear dependent HQET denominators



$$D_1 = -2(k+p_1) \cdot v = -2(k \cdot v + \omega_1)$$
$$D_2 = -2(k+p_2) \cdot v = -2(k \cdot v + \omega_2)$$
$$D_1 - D_2 + 2(\omega_1 - \omega_2) = 0$$
$$\mathbf{1}^- - \mathbf{2}^- + 2(\omega_1 - \omega_2) = 0$$

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Linear dependent HQET denominators

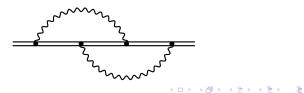


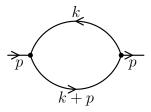
$$D_1 = -2(k + p_1) \cdot v = -2(k \cdot v + \omega_1)$$
  

$$D_2 = -2(k + p_2) \cdot v = -2(k \cdot v + \omega_2)$$
  

$$D_1 - D_2 + 2(\omega_1 - \omega_2) = 0$$
  

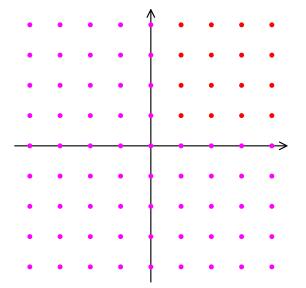
$$\mathbf{1}^- - \mathbf{2}^- + 2(\omega_1 - \omega_2) = 0$$



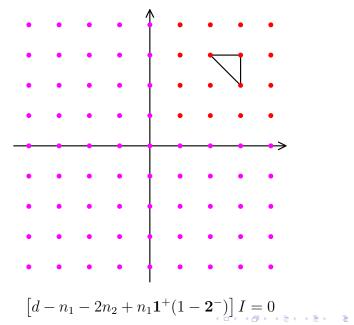


$$p^{2} = -1 \text{ (restore by dimensionality)}$$
$$D_{1} = -(k+p)^{2} \qquad D_{2} = -k^{2}$$
$$p^{2} = -1 \qquad k^{2} = -D_{2} \qquad 2p \cdot k = 1 - D_{1} + D_{2}$$
$$\partial \cdot k = d - 2k \cdot (k+p) \frac{\partial}{\partial D_{1}} - 2k \cdot k \frac{\partial}{\partial D_{2}}$$

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#### Some codes

- ▶ Mincer (Form) 3-loop massless self-energies
- Recursor (Reduce) 2-loop massive on-shell self-energies, 3-loop massive vacuum diagrams
- ▶ SHELL2 (Form) 2-loop massive on-shell self-energies
- ▶ Matad (Form) 3-loop massive vacuum diagrams
- ▶ Slicer (Reduce) 3-loop massless self-energies
- ▶ Grinder (Reduce) 3-loop HQET self-energies
- ▶ SHELL3 (Form) 3-loop massive on-shell self-energies

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# Homogeneity relations

$$\left(\sum_{i} p_{i} \cdot \frac{\partial}{\partial p_{i}} + \sum_{i} m_{i} \frac{\partial}{\partial m_{i}}\right) I = \left(Ld - 2\sum_{i} n_{i}\right) I$$

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$$\left(\sum_{i} p_{i} \cdot \frac{\partial}{\partial p_{i}} + \sum_{i} m_{i} \frac{\partial}{\partial m_{i}} - Ld + 2\sum_{i} n_{i}\right) f$$
$$= \left(\sum_{i} q_{i} \cdot \frac{\partial}{\partial q_{i}} + \sum_{i} m_{i} \frac{\partial}{\partial m_{i}} - \sum_{i} k_{i} \cdot \frac{\partial}{\partial k_{i}} - Ld + 2\sum_{i} n_{i}\right) f$$
$$= \left(-\sum_{i} k_{i} \cdot \frac{\partial}{\partial k_{i}} - Ld\right) f = -\left(\sum_{i} \frac{\partial}{\partial k_{i}} \cdot k_{i}\right) f$$

Lorentz-invariance relations  $E \ge 2 \ (i \ne j)$ 

$$p_i^{\mu} p_j^{\nu} \left( \sum_n p_n^{[\mu} \frac{\partial}{\partial p_n^{\nu]}} \right) I = 0$$

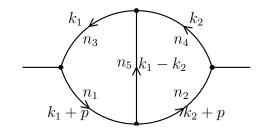
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$$p_i^{\mu} p_j^{\nu} \left( \sum_n p_n^{[\mu} \frac{\partial}{\partial p_n^{\nu]}} \right) I = 0$$

They are linear combinations of IBP relations

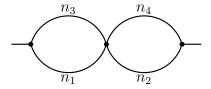
$$p_{i}^{\mu}p_{j}^{\nu}\left(\sum_{n}p_{n}^{[\mu}\frac{\partial}{\partial p_{n}^{\nu]}}\right)f = p_{i}^{\mu}p_{j}^{\nu}\left(\sum_{n}q_{n}^{[\mu}\frac{\partial}{\partial q_{n}^{\nu]}} - \sum_{n}k_{n}^{[\mu}\frac{\partial}{\partial k_{n}^{\nu]}}\right)f$$
$$= -p_{i}^{\mu}p_{j}^{\nu}\left(\sum_{n}k_{n}^{[\mu}\frac{\partial}{\partial k_{n}^{\nu]}}\right)f$$
$$= \sum_{n}\left(p_{j}\cdot k_{n}p_{i}\cdot\frac{\partial}{\partial k_{n}} - p_{i}\cdot k_{n}p_{j}\cdot\frac{\partial}{\partial k_{n}}\right)f$$
$$= \sum_{n}\frac{\partial}{\partial k_{n}}\cdot\left(p_{i}p_{j}\cdot k_{n} - p_{j}p_{i}\cdot k_{n}\right)f$$

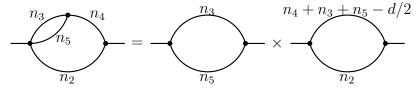


$$D_1 = -(k_1 + p)^2 \qquad D_2 = -(k_2 + p)^2$$
  
$$D_3 = -k_1^2 \qquad D_4 = -k_2^2 \qquad D_5 = -(k_1 - k_2)^2$$

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### Trivial cases



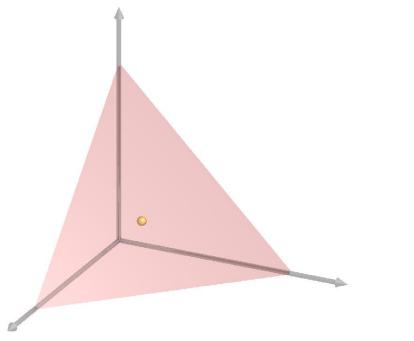


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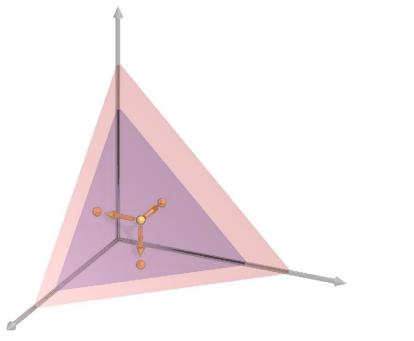
$$\partial_2 \cdot (k_2 - k_1) = d - n_2 - n_4 - 2n_5 - (D_1 - D_5) \frac{\partial}{\partial D_2} - (D_3 - D_5) \frac{\partial}{\partial D_4}$$

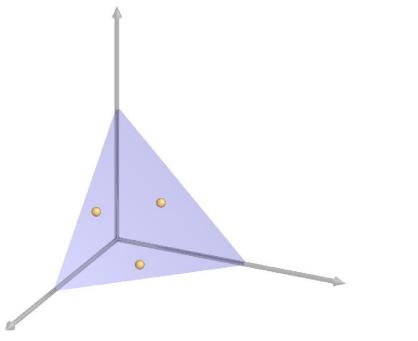
 $[d - n_2 - n_4 - 2n_5 + n_2 \mathbf{2}^+ (\mathbf{1}^- - \mathbf{5}^-) + n_4 \mathbf{4}^+ (\mathbf{3}^- - \mathbf{5}^-)]G = 0$ 

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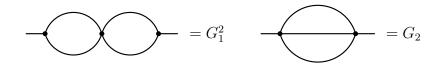


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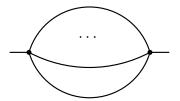




# Master integrals



$$G_n = \frac{g_n}{\left(n+1-n\frac{d}{2}\right)_n \left((n+1)\frac{d}{2}-2n-1\right)_n}$$
$$g_n = \frac{\Gamma(1+n\varepsilon)\Gamma^{n+1}(1-\varepsilon)}{\Gamma(1-(n+1)\varepsilon)}$$



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# Homogeneity relation

 $\partial_1 \cdot k_1$ 

 $[d - n_2 - n_5 - 2n_4 + n_2 \mathbf{2}^+ (1 - \mathbf{4}^-) + n_5 \mathbf{5}^+ (\mathbf{3}^- - \mathbf{4}^-)]G = 0$ 

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 $\partial_1 \cdot k_1$  mirrir-symmetric

# Homogeneity relation

$$\partial_1 \cdot k_1$$

$$[d - n_2 - n_5 - 2n_4 + n_2 \mathbf{2}^+ (1 - \mathbf{4}^-) + n_5 \mathbf{5}^+ (\mathbf{3}^- - \mathbf{4}^-)]G = 0$$

 $\partial_1 \cdot k_1$  mirrir-symmetric

 $p\cdot (\partial/\partial p)G$ 

$$[2(d-n_3-n_4-n_5)-n_1-n_2+n_1\mathbf{1}^+(1-\mathbf{3}^-)+n_2\mathbf{2}^+(1-\mathbf{4}^-)]G=0$$

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#### Larin relation

Insert  $(k_1 + p)^{\mu}$ . The vector integral  $\sim p^{\mu}$ :

$$k_1 + p \to \frac{(k_1 + p) \cdot p}{p^2} p = \left(1 + \frac{D_1 - D_3}{-p^2}\right) \frac{p}{2}$$

 $\partial/\partial p^{\mu}$ 

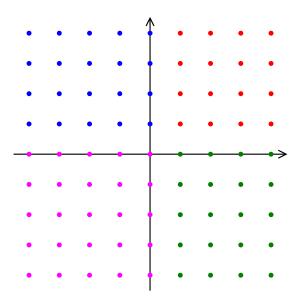
$$\left(\frac{3}{2}d - \sum n_i\right)\left(1 + \frac{D_1 - D_3}{-p^2}\right)$$

Explicit differentiation

$$d + \frac{n_1}{D_1} 2(k_1 + p)^2 + \frac{n_2}{D_2} 2(k_2 + p) \cdot (k_1 + p)$$

$$\begin{bmatrix} \frac{1}{2}d + n_1 - n_3 - n_4 - n_5 + \left(\frac{3}{2}d - \sum n_i\right)(\mathbf{1}^- - \mathbf{3}^-) \\ + n_2 \mathbf{2}^+ (\mathbf{1}^- - \mathbf{5}^-) \end{bmatrix} G = 0$$

Ordering



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#### Statement of the problem

Suppose we have *n* variables  $x_1, \ldots, x_n$ . They are not independent, but satisfy some polynomial equations  $p_1 = 0$ ,  $\ldots, p_m = 0$  ( $p_j$  are polynomials of  $x_i$ ). Let's consider a polynomial *q*. Is it equal to 0 due to the constraints on our variables? If there is another polynomial  $q_2$ , there is the question of their equality.

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These questions would become very easy if we had an algorithm reducing polynomials of dependent variables to a canonical form. Two equal polynomials reduce to the same canonical form; a polynomial equal to 0 reduces to the canonical form 0.

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These questions would become very easy if we had an algorithm reducing polynomials of dependent variables to a canonical form. Two equal polynomials reduce to the same canonical form; a polynomial equal to 0 reduces to the canonical form 0.

We can try to use the equations  $p_j = 0$  for simplifying the polynomial q, i.e. for replacing its more complicated terms by combinations of simpler ones. But to do so we first have to accept some convention which terms are more complicated and which are more simple.

We need a total order of monomials (i.e. products of powers of the variables  $x_1^{n_1} \cdots x_n^{n_n}$ ). An order is total if for any monomials s and t either s < t, or s > t, or s = t is true. An order is admissible if two properties are satisfied:

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- $1 \leq s$  for any monomial s,
- if s < t then su < tu for any monomial u.

# Monomial orders

Lexicographic order

. . .

We are comparing two monomials:  $s = x_1^{n_1} x_2^{n_2} \cdots x_n^{n_n}$  and  $t = x_1^{m_1} x_2^{m_2} \cdots x_n^{m_n}$ •  $n_1 > m_1 \Rightarrow s > t$ •  $n_1 < m_1 \Rightarrow s < t$ •  $n_1 = m_1$ •  $n_2 > m_2 \Rightarrow s > t$ •  $n_2 < m_2 \Rightarrow s < t$ •  $n_2 = m_2$ 

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▶ 
$$n_2 = m_2$$

. . .

#### By total degree than lexicographic

First we compare the total degree  $n = n_1 + n_2 + \cdots + n_n$  of the monomial s and the total degree

 $m = m_1 + m_2 + \cdots + m_n$  of the monomial t.

- $\blacktriangleright n > m \Rightarrow s > t$
- $\blacktriangleright \ n < m \Rightarrow s < t$

# Reduction of polynomials

Let's fix some admissible monomial order. We'll write polynomials in descending order: the leading term first, followed by the rest ones. We'll normalize all polynomials  $p_j$  in such a way that the coefficient of the leading term is 1. Now they can be used as substitutions which replace the leading term by minus sum of the remaining ones.

Lexicographic order with x > y

$$p_1 = x^2 + y^2 - 1$$
  $p_2 = xy - \frac{1}{4}$ 

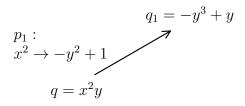
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$$q = x^2 y$$

Lexicographic order with x > y

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  $p_2 = xy - \frac{1}{4}$ 

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Lexicographic order with x > y

$$p_{1} = x^{2} + y^{2} - 1 \qquad p_{2} = xy - \frac{1}{4}$$

$$q_{1} = -y^{3} + y$$

$$p_{1}:$$

$$x^{2} \rightarrow -y^{2} + 1$$

$$q = x^{2}y$$

$$p_{2}:$$

$$xy \rightarrow \frac{1}{4}$$

$$q_{2} = \frac{1}{4}x$$

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Every time when more than one substitution can be applied to a term of a polynomial q, a fork appears; maybe, its branches join later, but maybe, they don't. A set of polynomials  $p_1, \ldots, p_n$  is called a *Gröbner basis* (for a given monomial order) if reduction of any polynomial q with respect to this set is unique. (This definition is not constructive.)

The constraints  $p_1 = 0$  and  $p_2 = 0$  allow us to simplify the monomials  $x^2$  and xy. Do these constraints contain an extra information usable for simplification but not obvious? Yes, they do!

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$$p_{1} = x^{2} + y^{2} - 1 = 0 \qquad \qquad \times y \qquad \qquad x^{2}y + y^{3} - y = 0$$
$$p_{2} = xy - \frac{1}{4} = 0 \qquad \qquad \times x \qquad \qquad x^{2}y - \frac{1}{4}x = 0$$

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$$\frac{1}{4}x + y^{3} - y = 0$$

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$$p_{2} = xy - \frac{1}{4} = 0 \qquad \qquad \times x \qquad \qquad x^{2}y - \frac{1}{4}x = 0$$

$$\frac{1}{4}x + y^{3} - y = 0$$

S-polynomial  $S(p_1, p_2)$ 

$$p_3 = x + 4y^3 - 4y$$

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Lexicographic order with x > y

$$p_{1} = x^{2} + y^{2} - 1 \qquad p_{2} = xy - \frac{1}{4}$$

$$q_{1} = -y^{3} + y$$

$$p_{1}:$$

$$x^{2} \rightarrow -y^{2} + 1$$

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$$p_{2}:$$

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$$q = x^{2}y$$

$$p_{3}:$$

$$x \rightarrow -4y^{3} + 4y$$

$$q_{2} = \frac{1}{4}x$$

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 $p_1$ ,  $p_2$ ,  $p_3$  form a Gröbner basis (though we have not proven this). We can reduce them with respect to each other (omitting vanishing polynomials). The reduced Gröbner basis is

$$p_1 = y^4 - y^2 + \frac{1}{16}$$
$$p_2 = x + 4y^3 - 4y$$

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It has triangular structure.

# Buchberger algorithm

Given a set of polynomials  $P = \{p_j\}$ 

- ► S = set of all pairs (i, j) of integer numbers from 1 to n with i < j</p>
- while S is not empty
- Choose and remove some pair (i, j) from S
- $\blacktriangleright \qquad \text{Calculate } S \text{-polynomial } S(p_i, p_j)$
- $\blacktriangleright \qquad \text{Reduce it with respect to } P$
- if the result is not 0, add this polynomial to P and the corresponding pairs to S

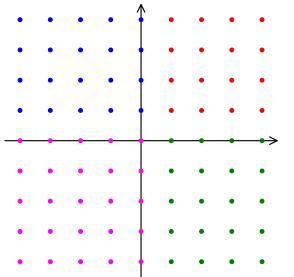
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- if the result is not 0, add this polynomial to *P* and the corresponding pairs to *S*

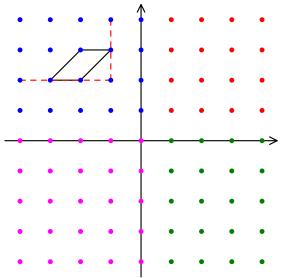
The set of pairs S alternatingly shrinks and grows. But it can be proved that this process terminates after a finite number of steps, and produces a Gröbner basis P.

### Sectors and corners



 $I(n_1, n_2) = (\mathbf{1}^{-})^{-n_1} (\mathbf{2}^{+})^{n_2 - 1} I(0, 1)$ 

Normal form of IBP relations in a sector



$$\sum_{j_1,j_2} C_{j_1j_2}(n_i) \left(\mathbf{1}^{-}\right)^{j_1} \left(\mathbf{2}^{+}\right)^{j_1} \sim 0$$

#### S-bases

#### Find a Gröbner-like basis, reduce $(\mathbf{1}^{-})^{-n_1} (\mathbf{2}^{+})^{n_2-1}$ and apply to I(0,1)

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Gröbner bases for PDE

Each line has a separate mass  $m_i$ 

$$\frac{\partial}{\partial m_i^2} \Rightarrow -\mathbf{n}_i \mathbf{i}^+$$

#### IBP

$$\sum C_{j_1\dots j_N}(m_1^2,\dots,m_N^2) \left(\frac{\partial}{\partial m_1^2}\right)^{j_1} \cdots \left(\frac{\partial}{\partial m_N^2}\right)^{j_N} \sim 0$$

2-loop self-energy diagrams with all different masses

# Approaches

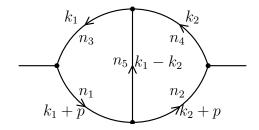
#### • Generic $n_i$

 Construct an algorithm and implement by hand: Mincer, ...

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- More automated approaches
  - Gröbner-based approaches
  - Lie-algebra based approaches
  - Baikov's methods
- Specific numeric n<sub>i</sub>: Laporta algorithm
   (Air, FIRE, reduze...)

# 2-loop self-energy diagram





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# 3-loop vacuum diagram

