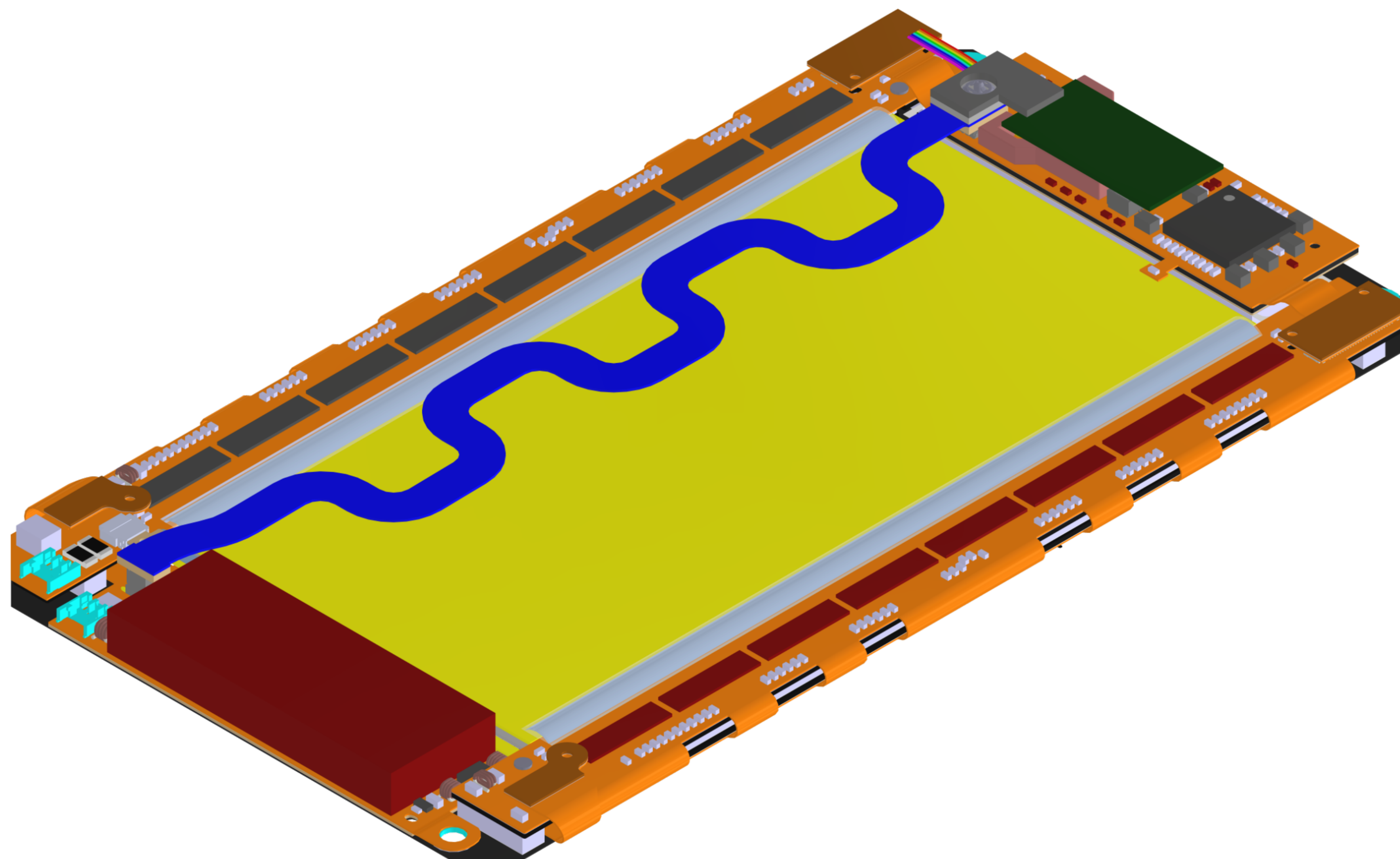
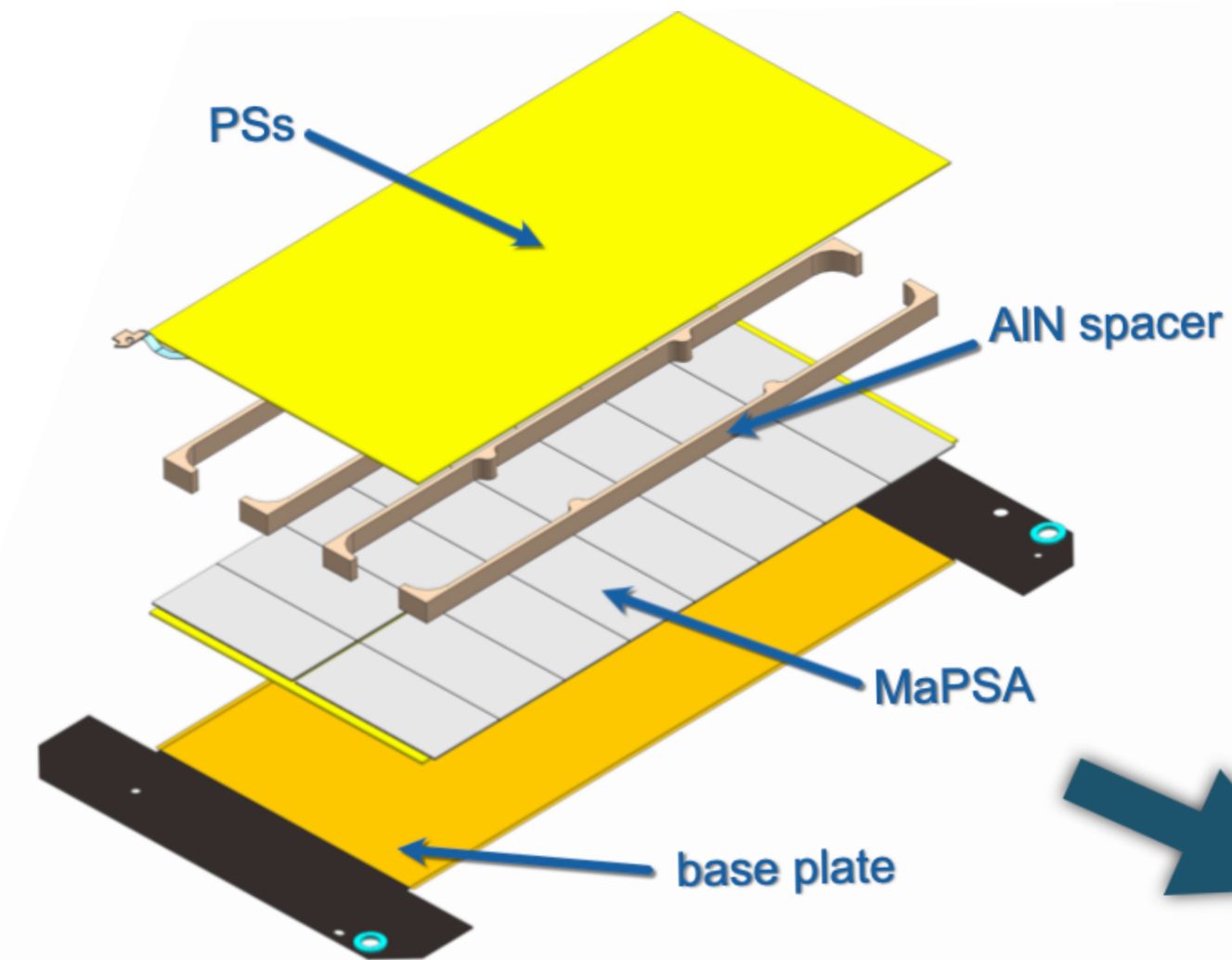
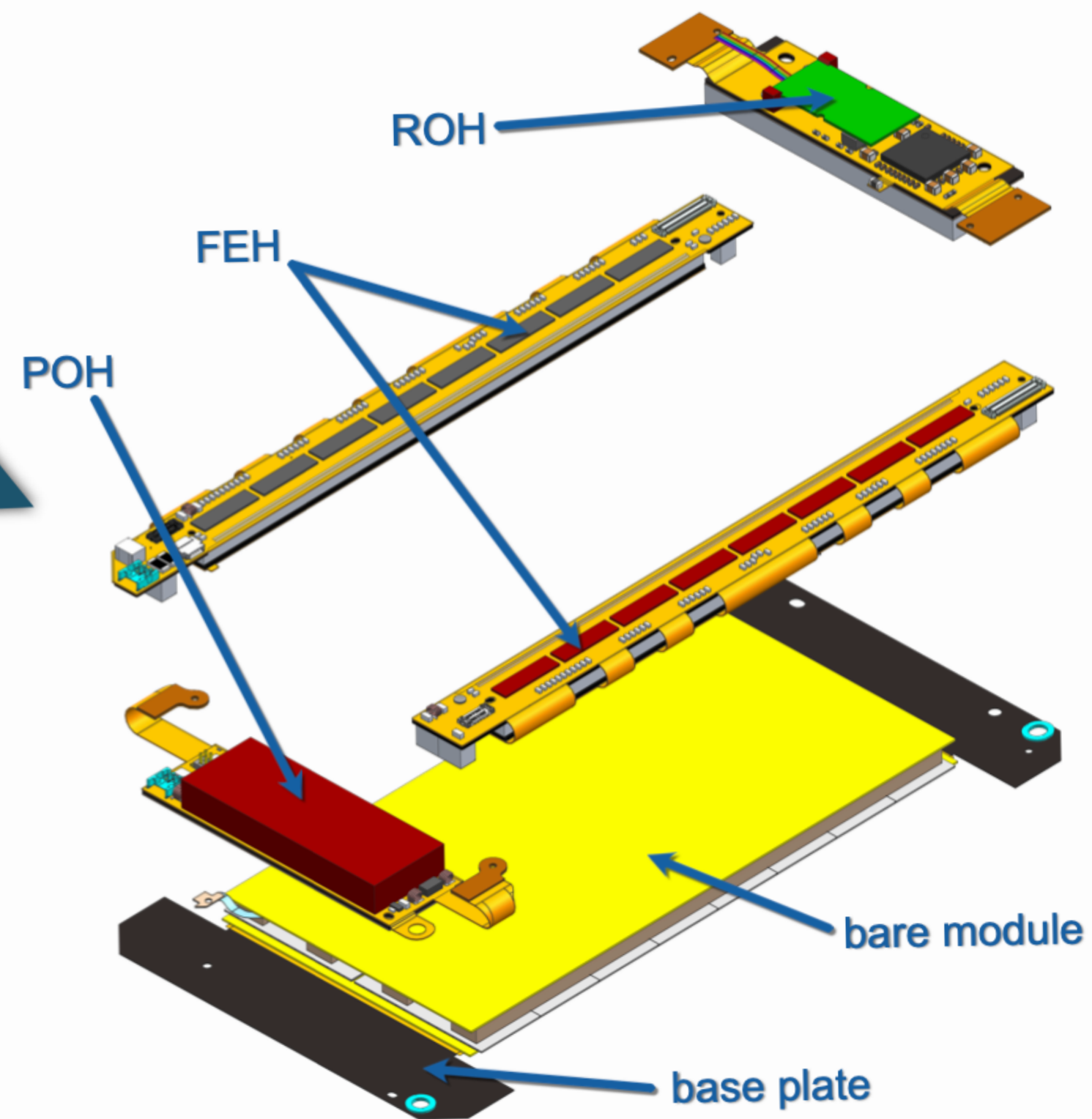


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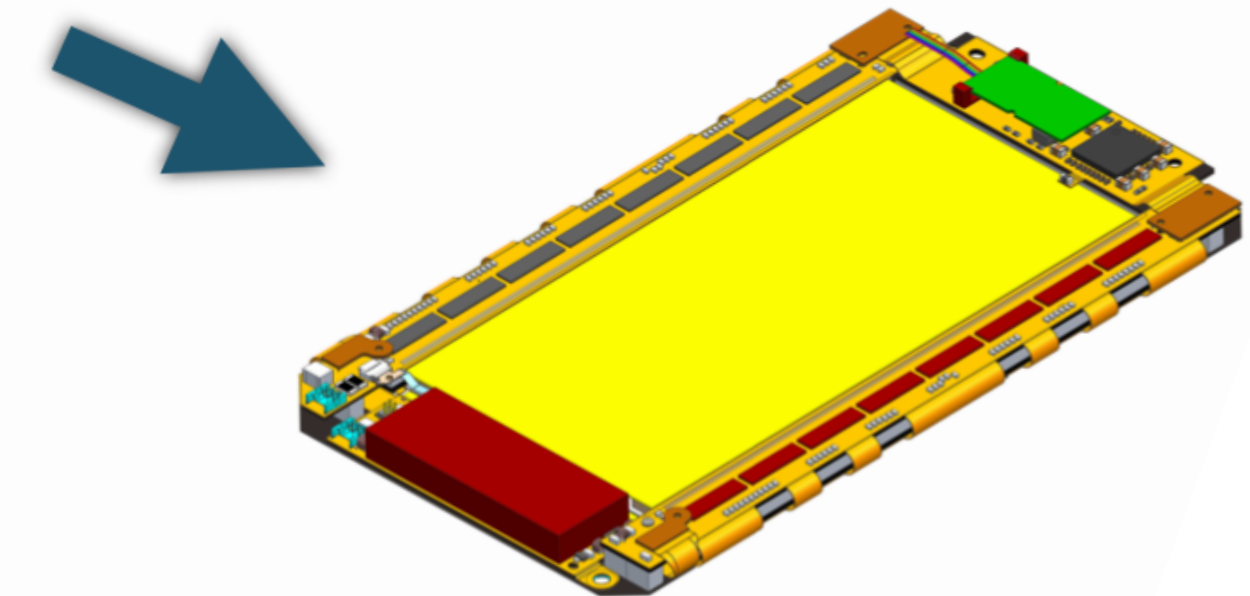




- Relative sensor to sensor alignment $\leq 800 \mu\text{rad}$
- Assembly is done on a robotic system



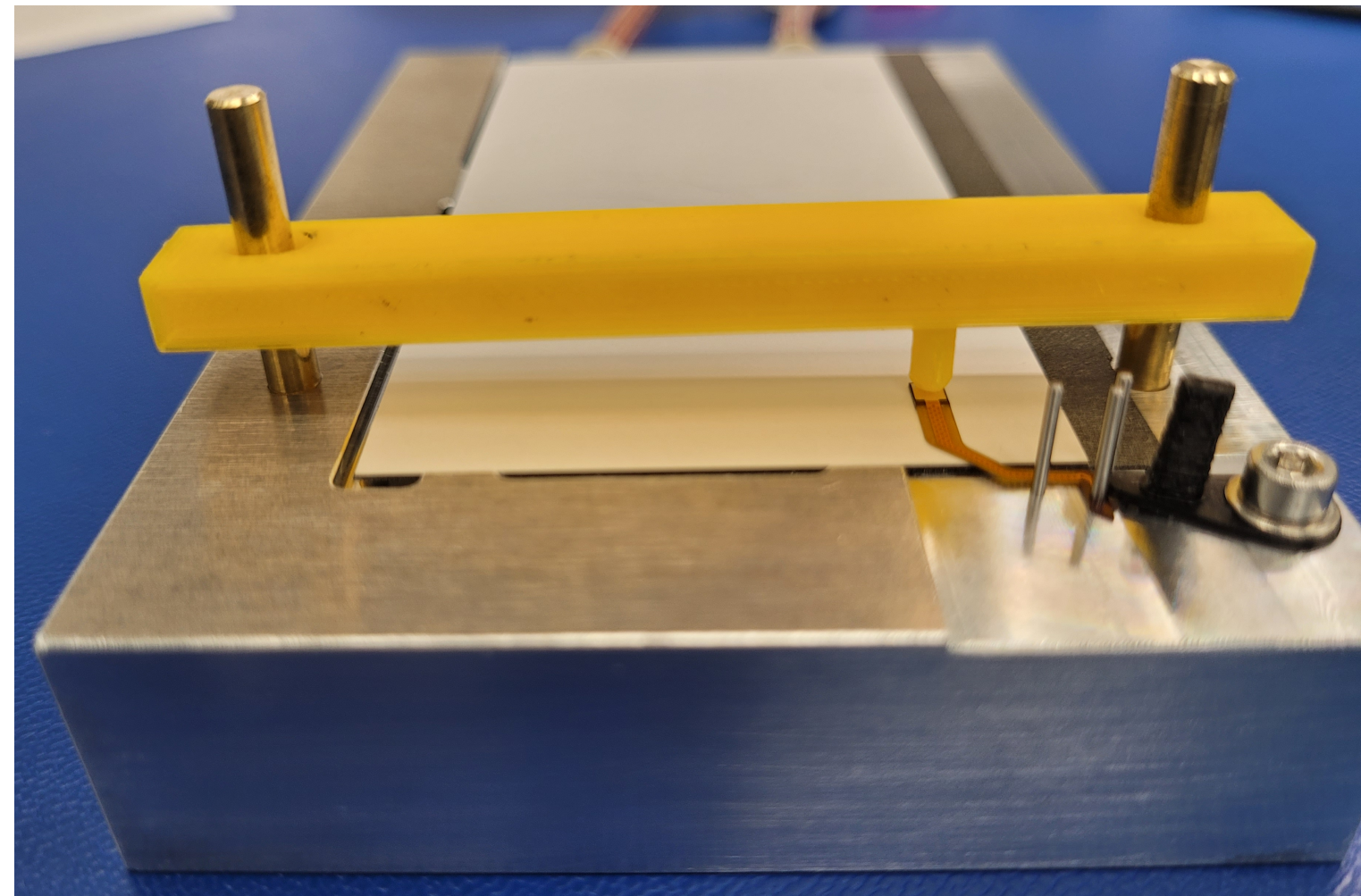
Hybrids are attached to bare module using jigs



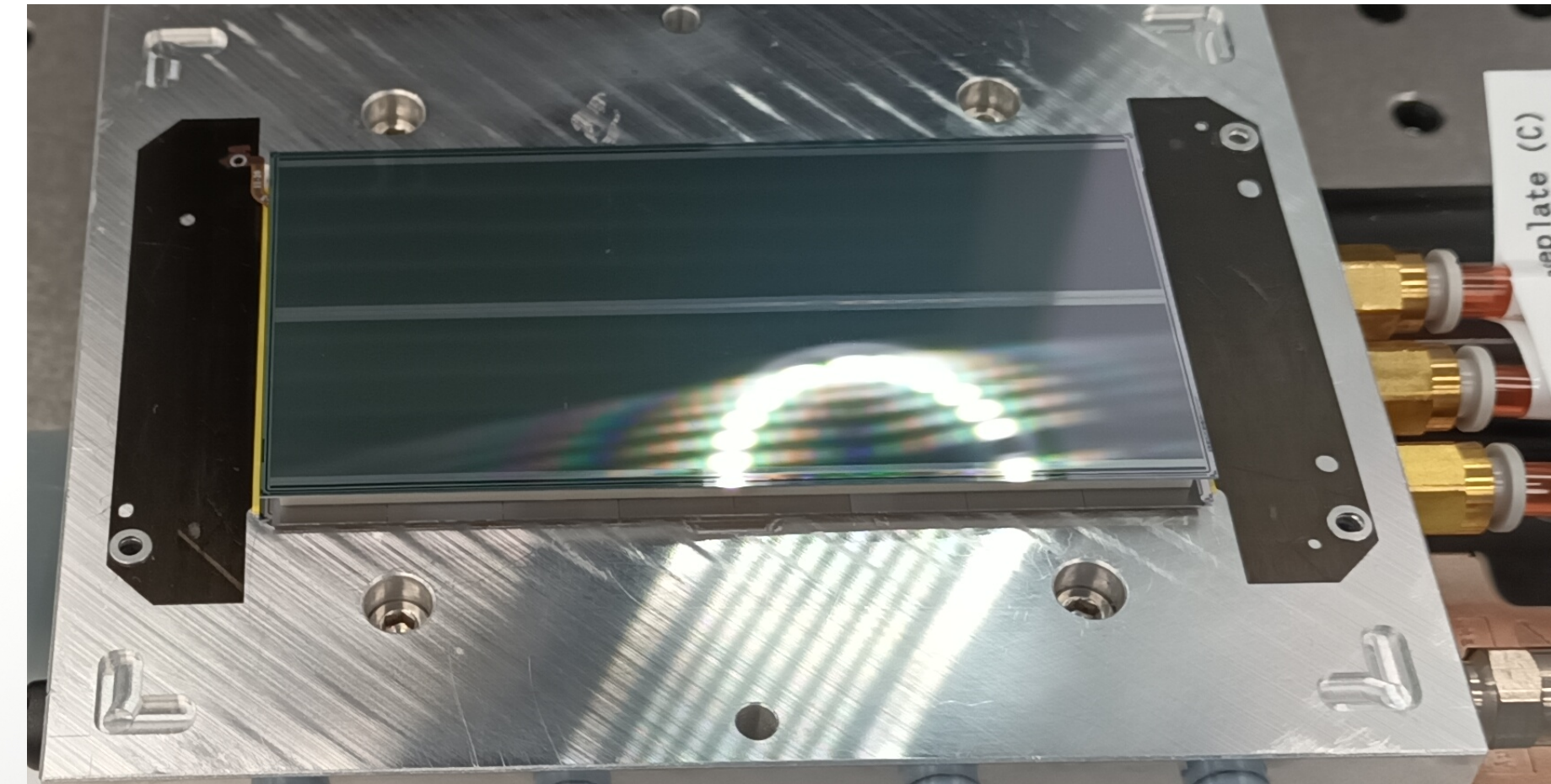
Steps towards full module



- **HV tail gluing**



- **electrical test of skeleton** (all hybrids)
- **automated assembly of bare module:** CF Baseplate + MaPSA + Spacers+ PSs sensor



- **metrology:**
 - $DX = 0.0006\text{mm}$
 - $DY = 0.0003\text{mm}$
 - $DZ = 3.9542\text{mm}$
 - Angle (Y midlines) = 401 micro rad (0.023 deg)
 - Angle (X midlines) = 401 micro rad (0.023 deg)

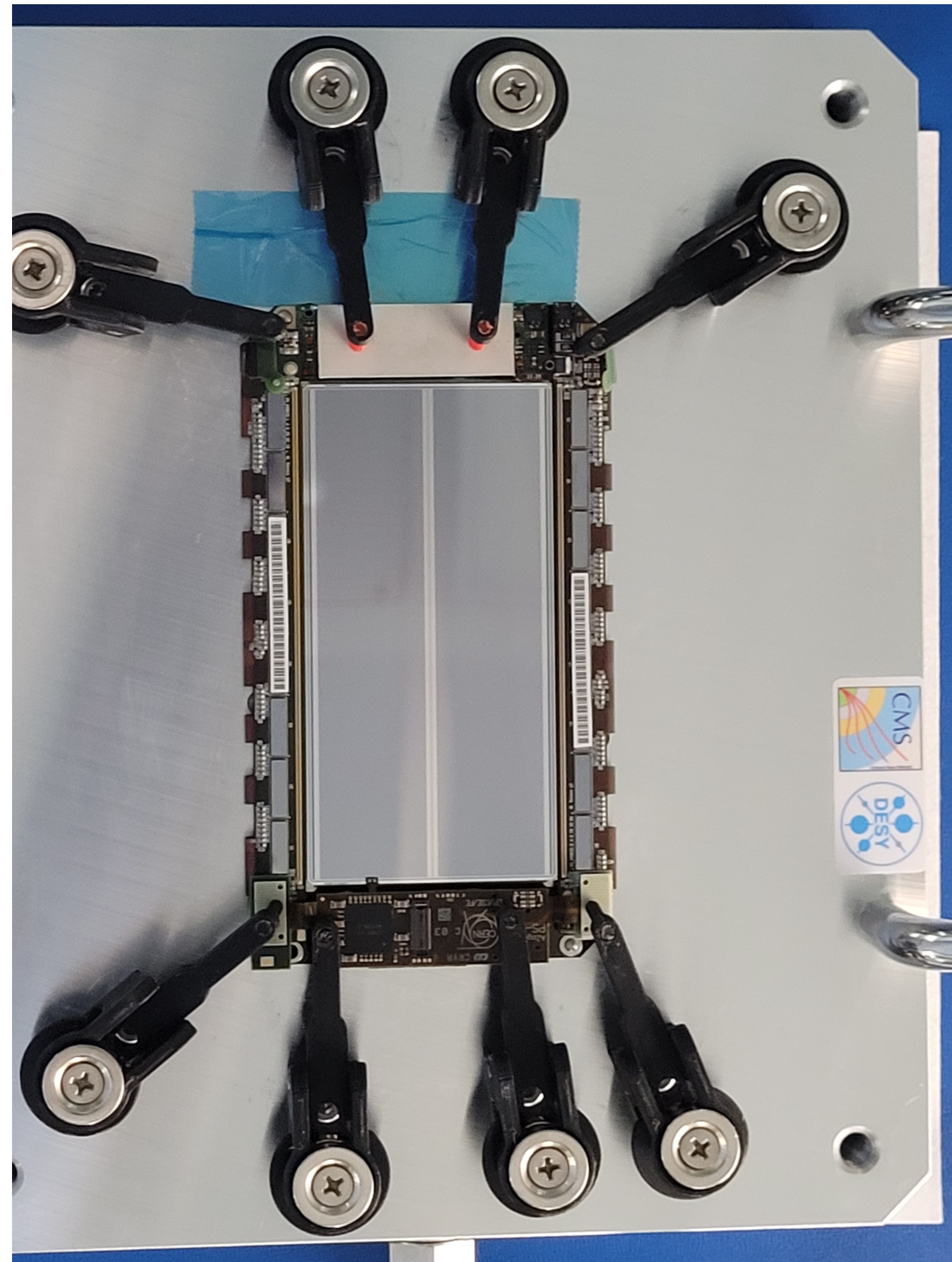
Flatness of the PSs was measured to be 0.0334mm

Steps towards full module



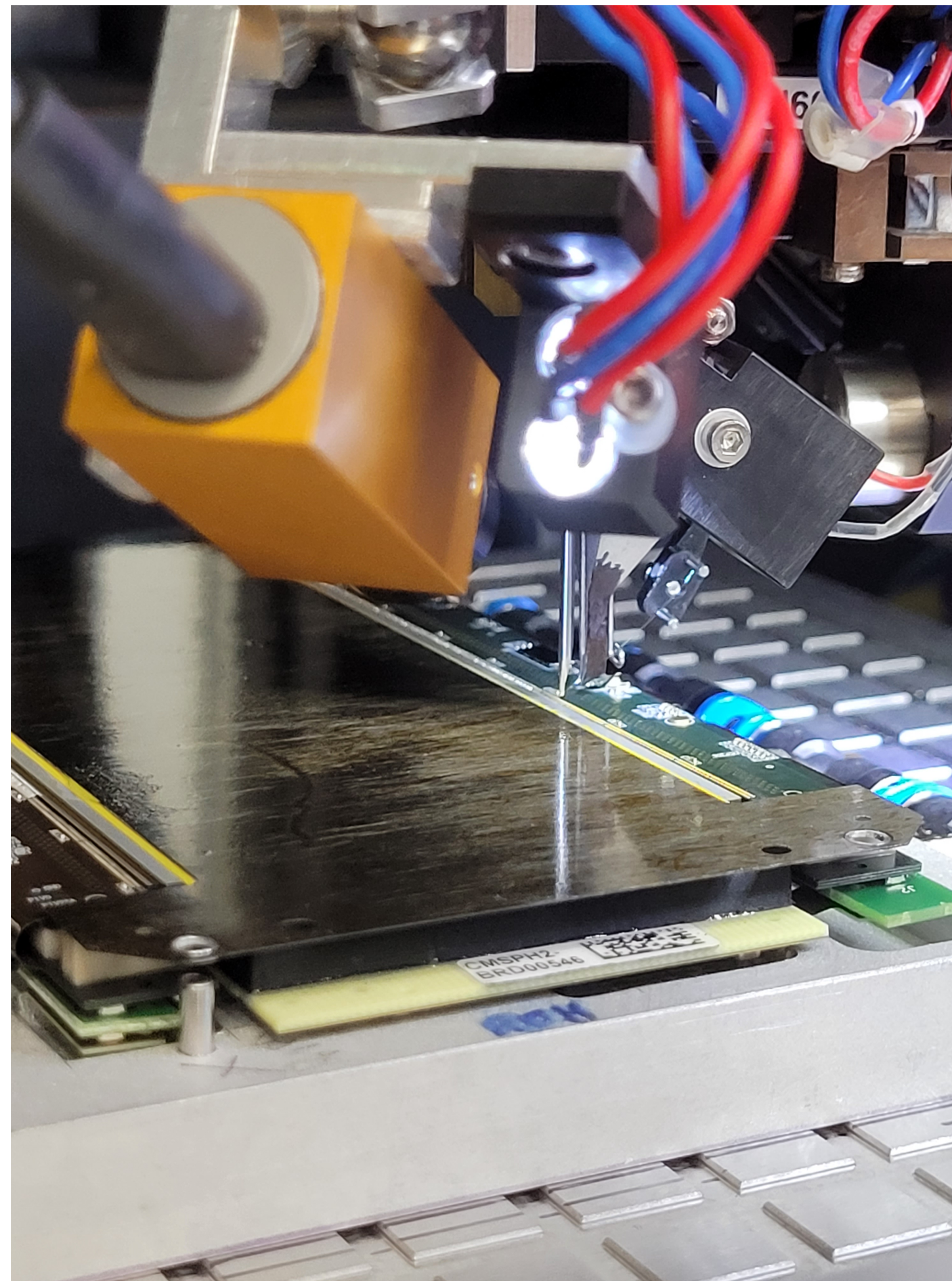
- **hybrids gluing:**

- manual assembly

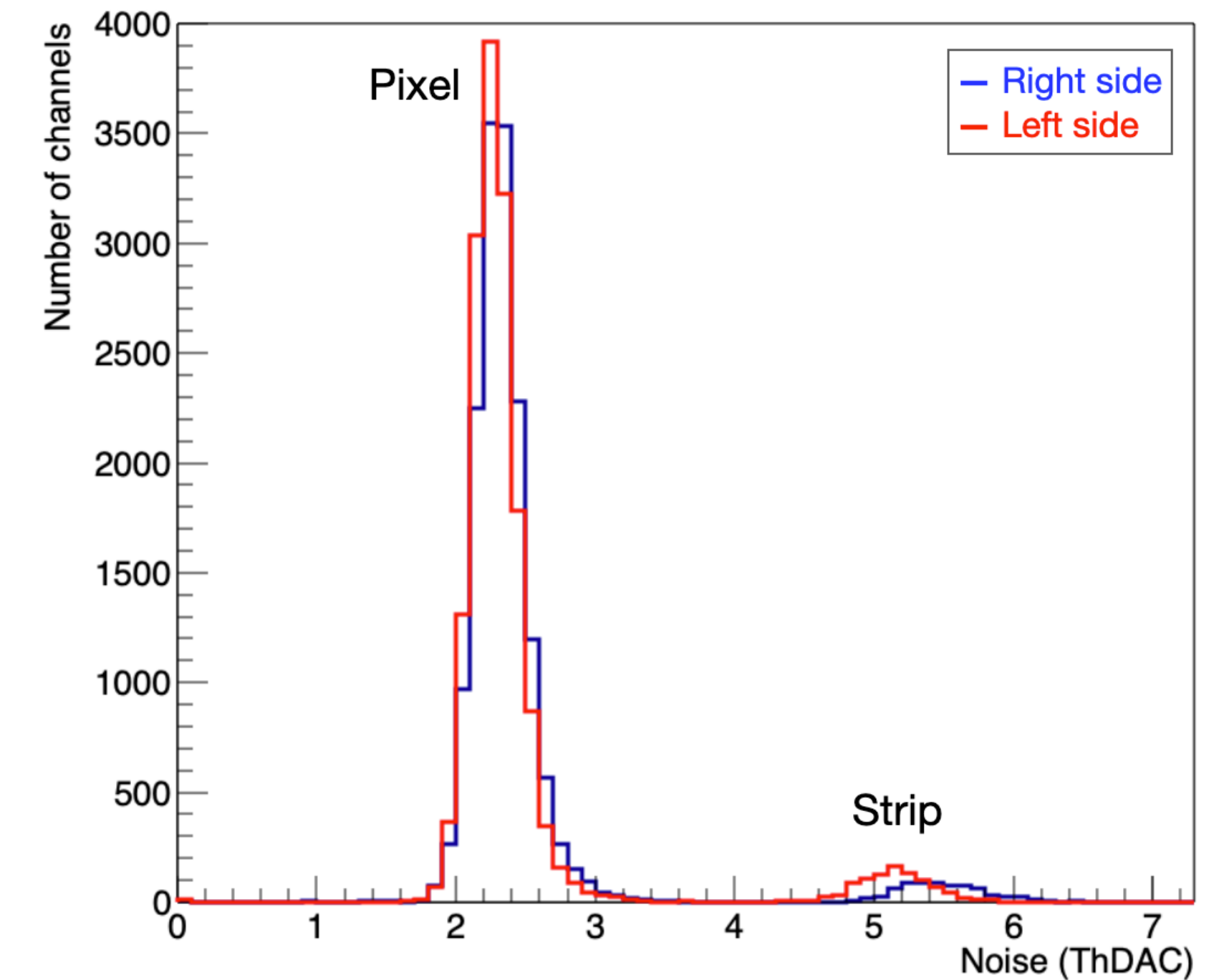


- **wire bonding**

- MaPSa side (photo) and PSs side



- **electrical test of full module**



- **next:**

- wire bond encapsulation
- preparation for test beam