

WOM Tube - Photon Exit Angle Distribution

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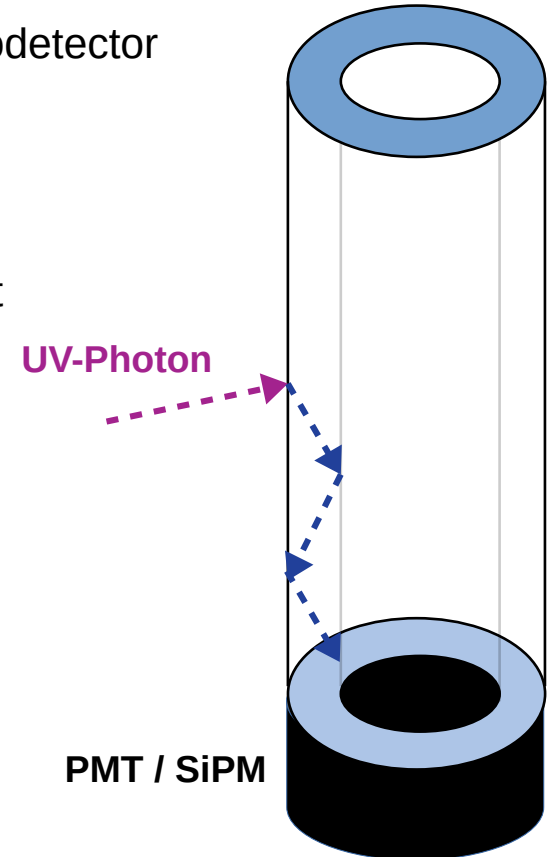
3rd High-D Consortium Meeting
February 9, 2023



Wavelength-Shifting Optical Modules

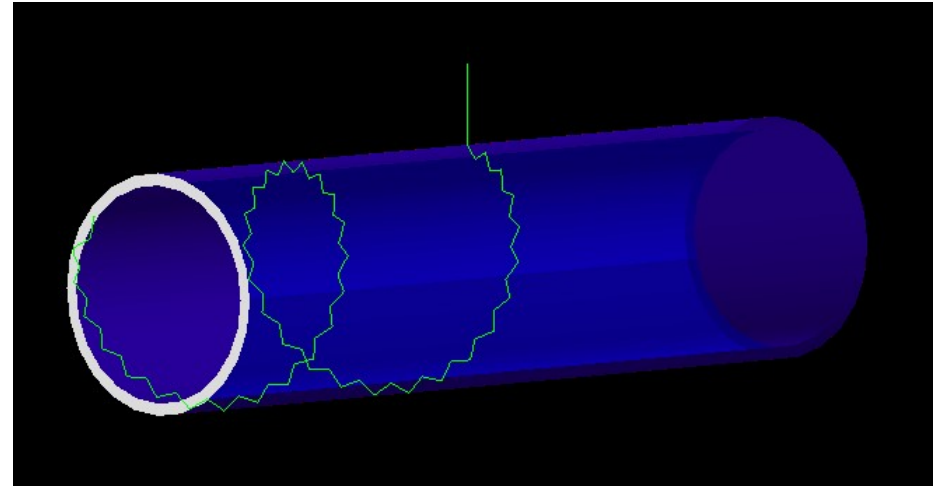
- **Wavelength-Shifting Optical Module (WOM)** = Large-Area Photodetector
- Cylindrical tube acts as **light collector**
- Outside of the tube coated with **wavelength-shifting paint**
 - Absorption of UV-photons, isotropic re-emission of visible light
- Internal **total reflection**, photons guided towards ends of tube
- Total capturing efficiency for secondary photons $\approx 73\%$ (ideally)
- **PMTs / SiPMs**: Detection of photons

→ Large effective area
→ Large acceptance angle



Photon exit angle measurements - Motivation

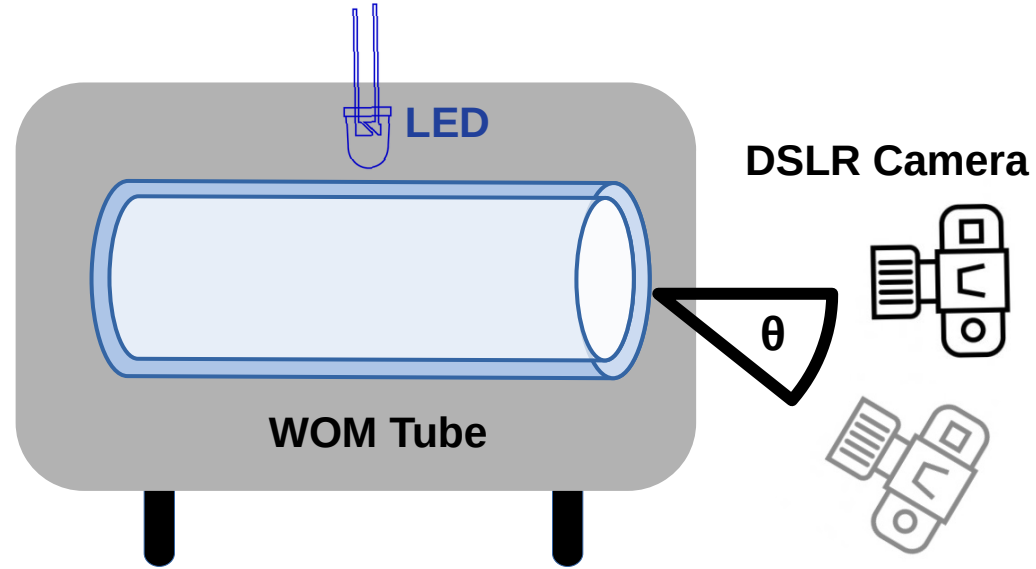
- **How much light can we effectively measure with SiPMs?**
 - Angular distribution of photons at exit window (SiPM angular acceptance)
- Optical properties of the WOM tube limit efficiency for detection of secondary photons
- Evaluate quality of WOM tube
 - Coating thickness
 - Surface quality
 - Efficiency of photon transport



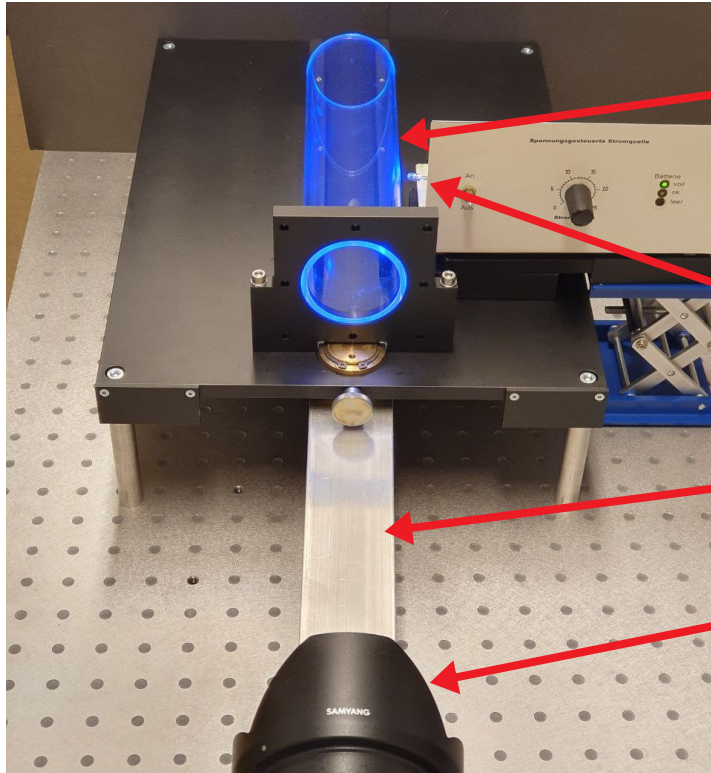
Photon path
(Geant4)

Photon exit angle measurements - Setup

- Idea: Use **DSLR camera** to capture photons of the WOM tube
- Change **exit angle** of captured photons by adjusting **camera angle θ**
- Light source: **UV LED**
 - $\lambda_{\text{peak}} = 375 \text{ nm}$
 - $\Delta\lambda = 9.0 \text{ nm}$
 - Opening angle $\approx 40^\circ$
 - Placed in the middle of the tube in close distance to surface ($\approx 2 \text{ cm}$)
- **Most photons hit the WOM surface approximately vertically**



Photon exit angle measurements - Setup

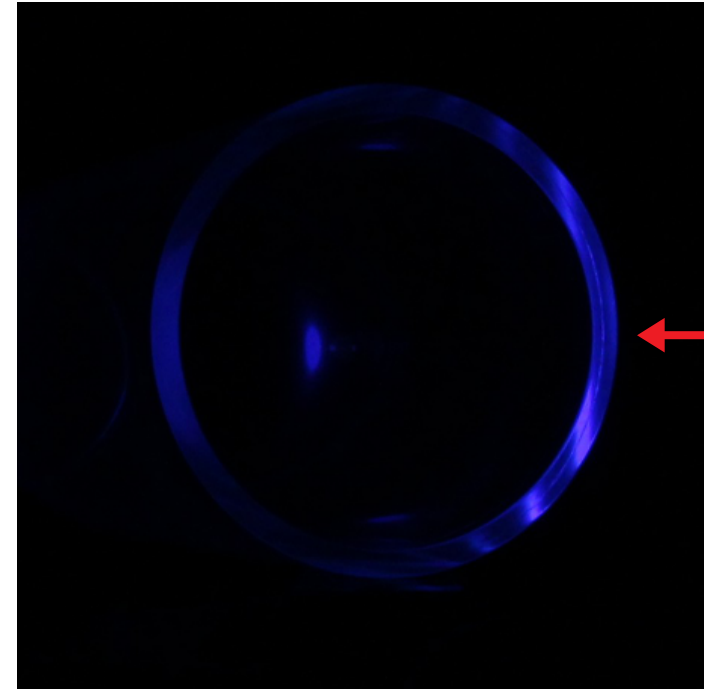


WOM tube

LED

Lever arm

Camera

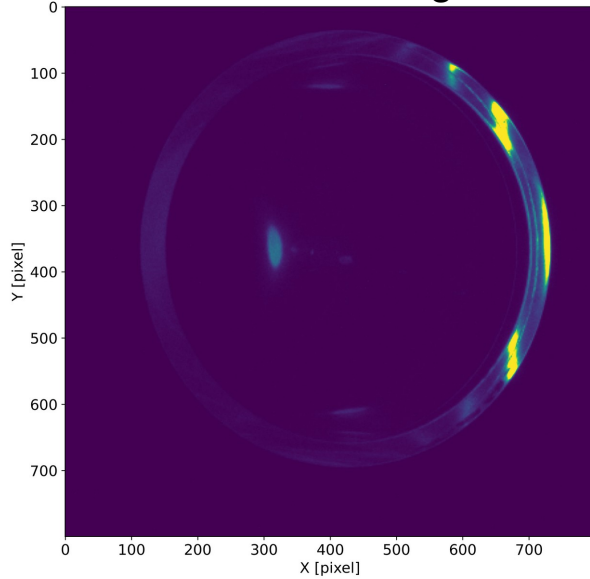


Light source
position

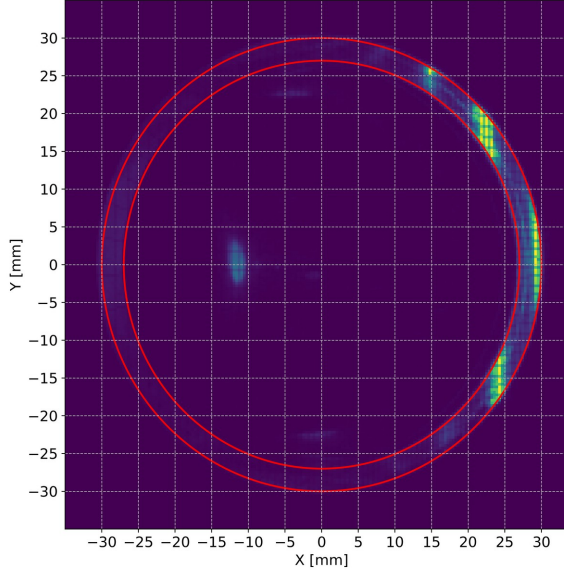
20°

Photo Processing

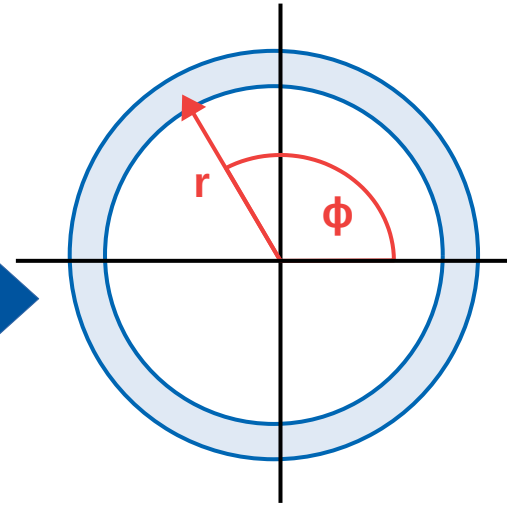
20° camera angle



Raw image



Reconstructed WOM surface

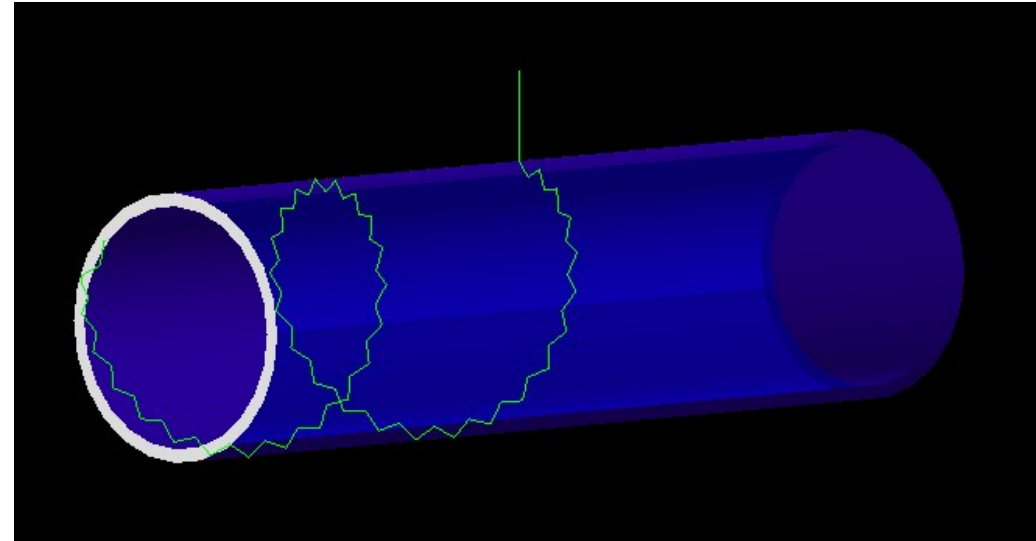


- Camera sensor: **blue**, red, and green pixels
- Algorithm identifies WOM surface on the photo
- Pixel coordinates of the camera sensor are transformed to reconstruct the geometry of the WOM surface (resolution $\sim 0.1\text{mm}$)

- Map each camera sensor pixel to position on WOM surface
- Allows for comparison of different camera angles

WOM Tube Simulation

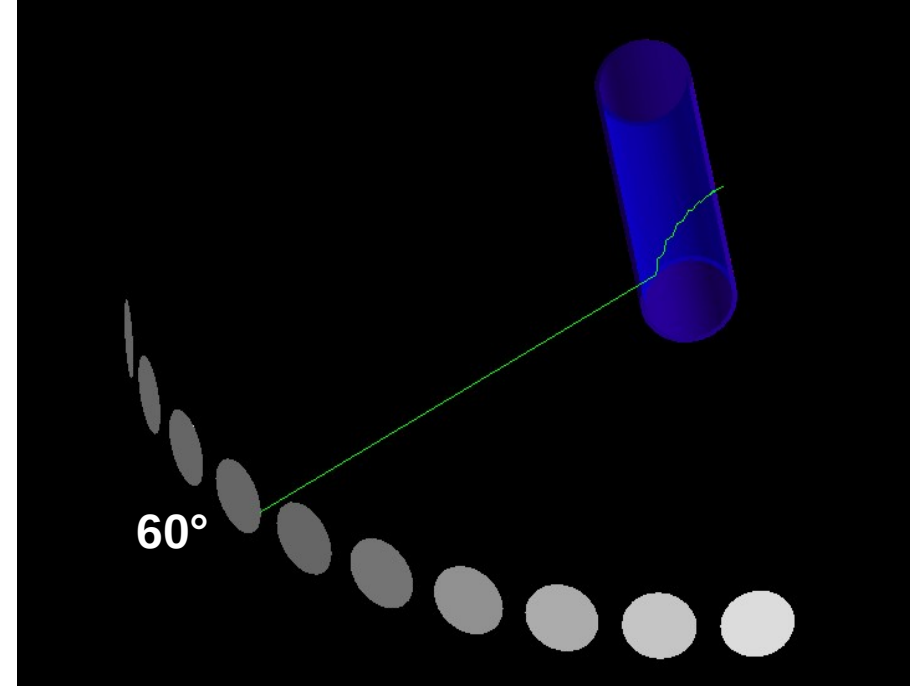
- Based on simulation toolkit Geant4
- Simulation of light source (LED):
Position, direction, wavelength distribution, opening angle
- Simulation of the WOM tube:
Wavelength-shifting properties of the paint, reflection and attenuation of photons



Photon path
(Geant4)

Simulated Images of WOM surface

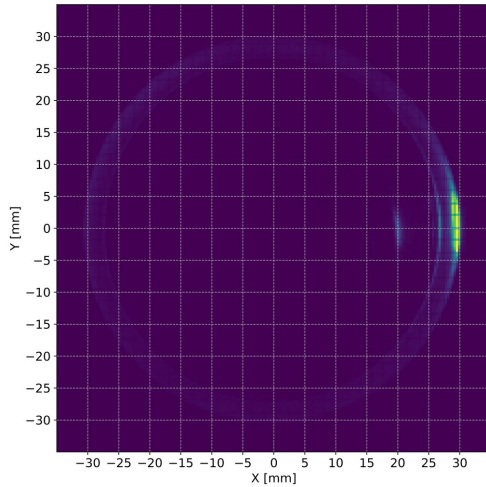
- Simulation of camera lens at different angles
- Lens diameter and distance to tube correspond to real measurement setup
- All photons leaving the tube and end up hitting a simulated camera lens at given angle contribute to the reconstructed image
- Reconstruction of image = reconstruct the position of the photon when exiting the WOM tube



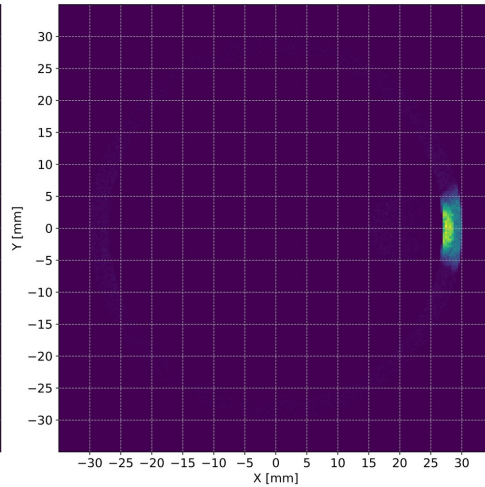
Different simulated camera lens angles
(Geant4)

Simulation vs Measurement

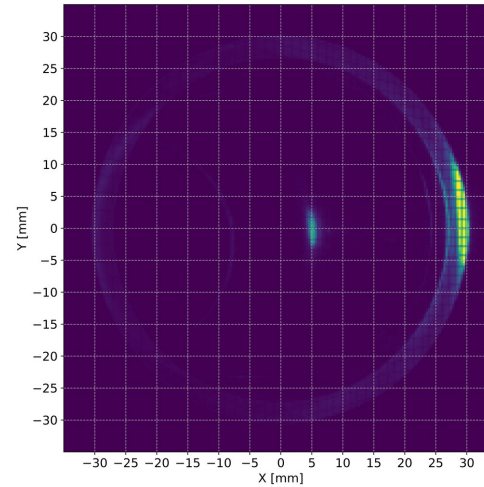
Real Photo, 0°



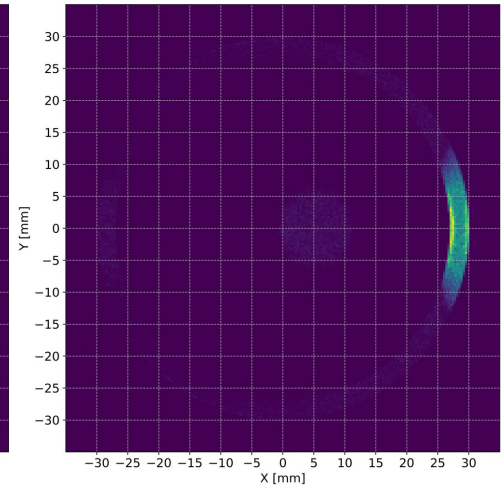
Simulation, 0°



Real Photo, 10°



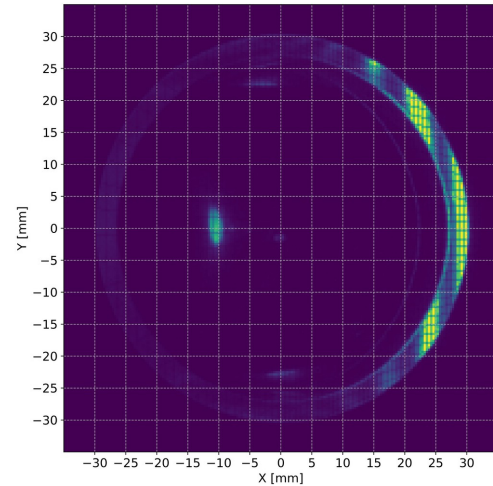
Simulation, 10°



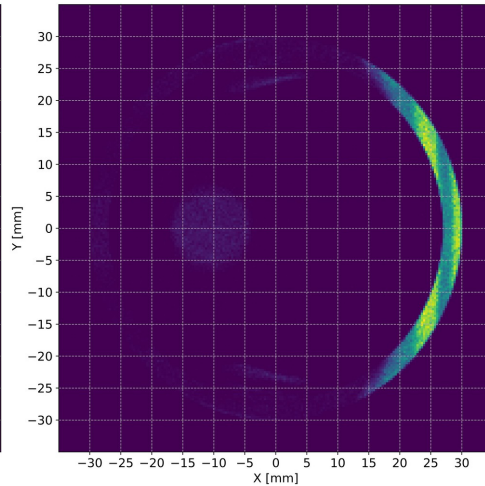
- WOM surface better visible in real photos (more homogeneously illuminated)
 - Simulated surface perfectly smooth, real surface has roughness/scratches/...
- **Structural similarities** clearly visible

Simulation vs Measurement

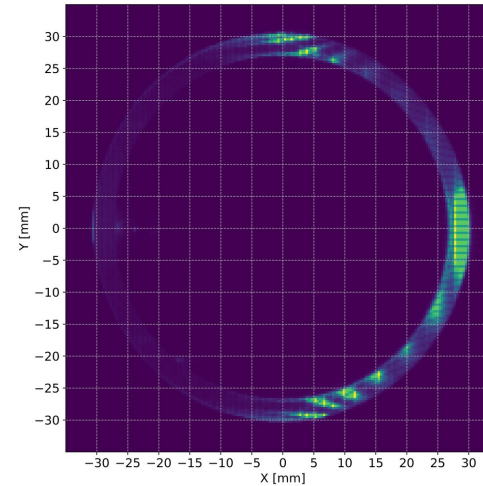
Real Photo, 20°



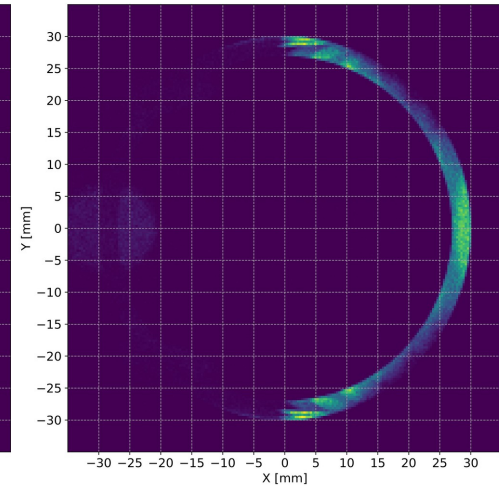
Simulation, 20°



Real Photo, 30°



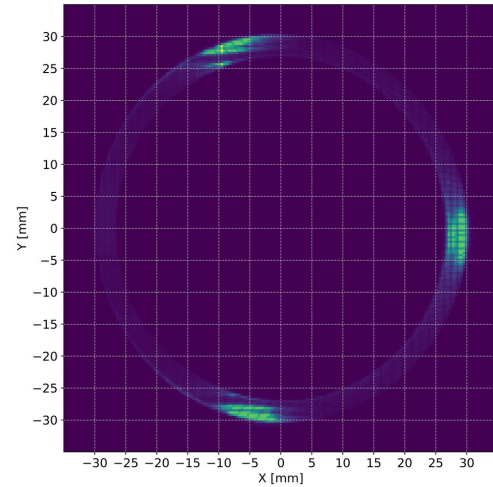
Simulation, 30°



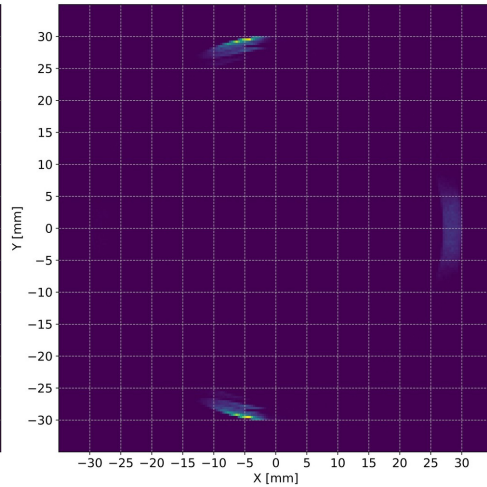
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Simulation vs Measurement

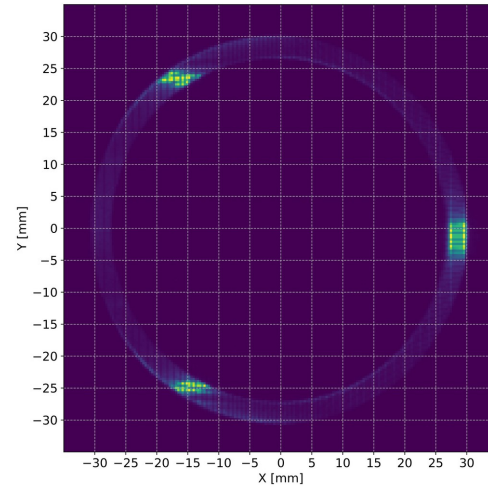
Real Photo, 40°



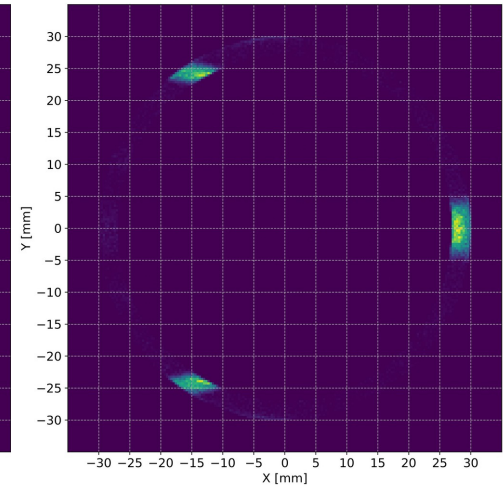
Simulation, 40°



Real Photo, 50°



Simulation, 50°

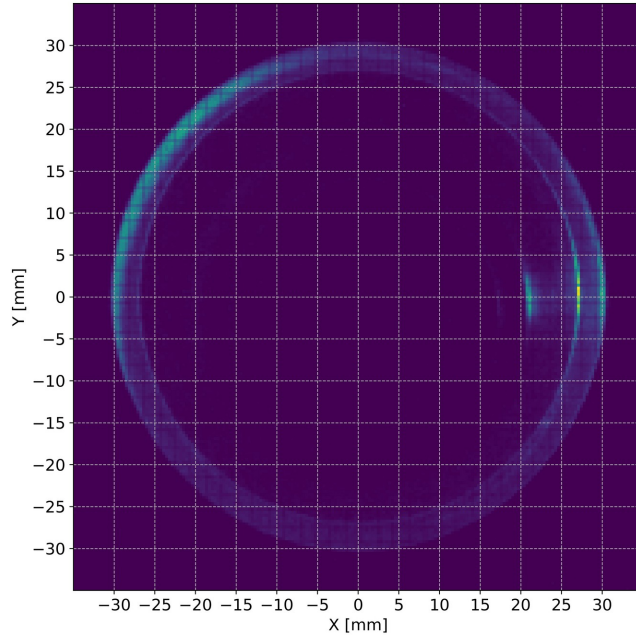


- WOM surface better visible in real photos (more homogeneously illuminated)
 - Simulated surface perfectly smooth, real surface has roughness/scratches/...
- **Structural similarities** clearly visible

→ What can we learn from the photos?

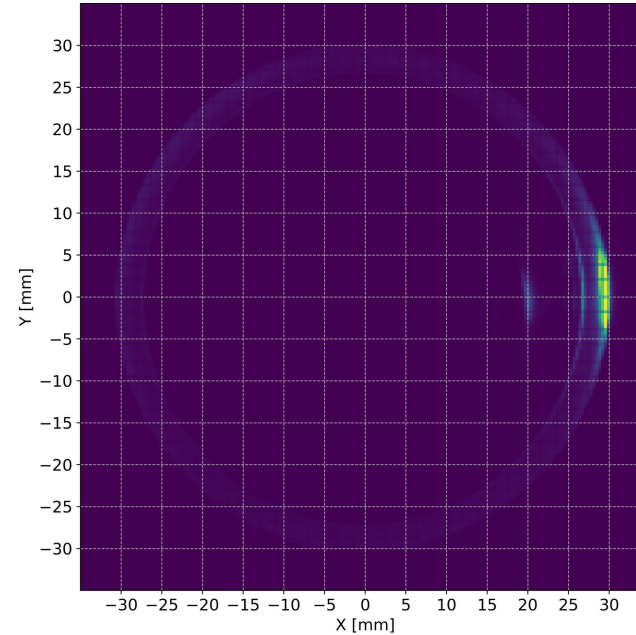
Tubes comparison

0° camera angle



- Single coating = single layer of paint
- ~ 5 micrometer thickness

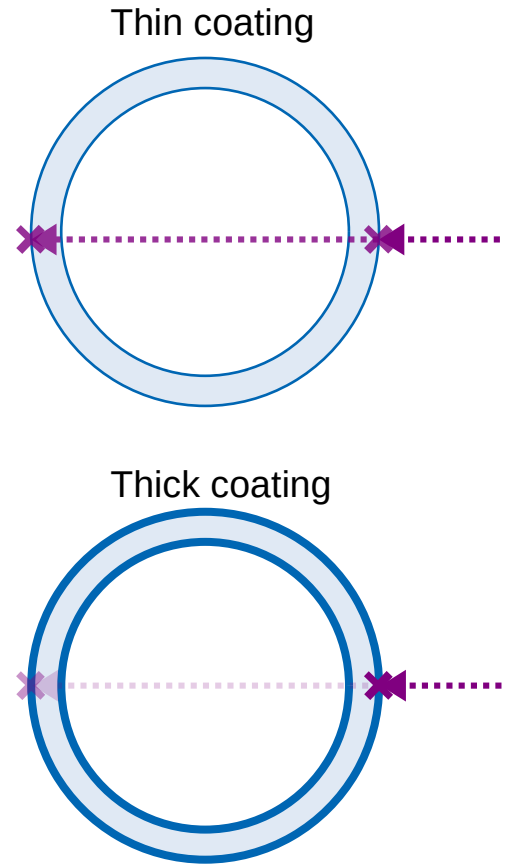
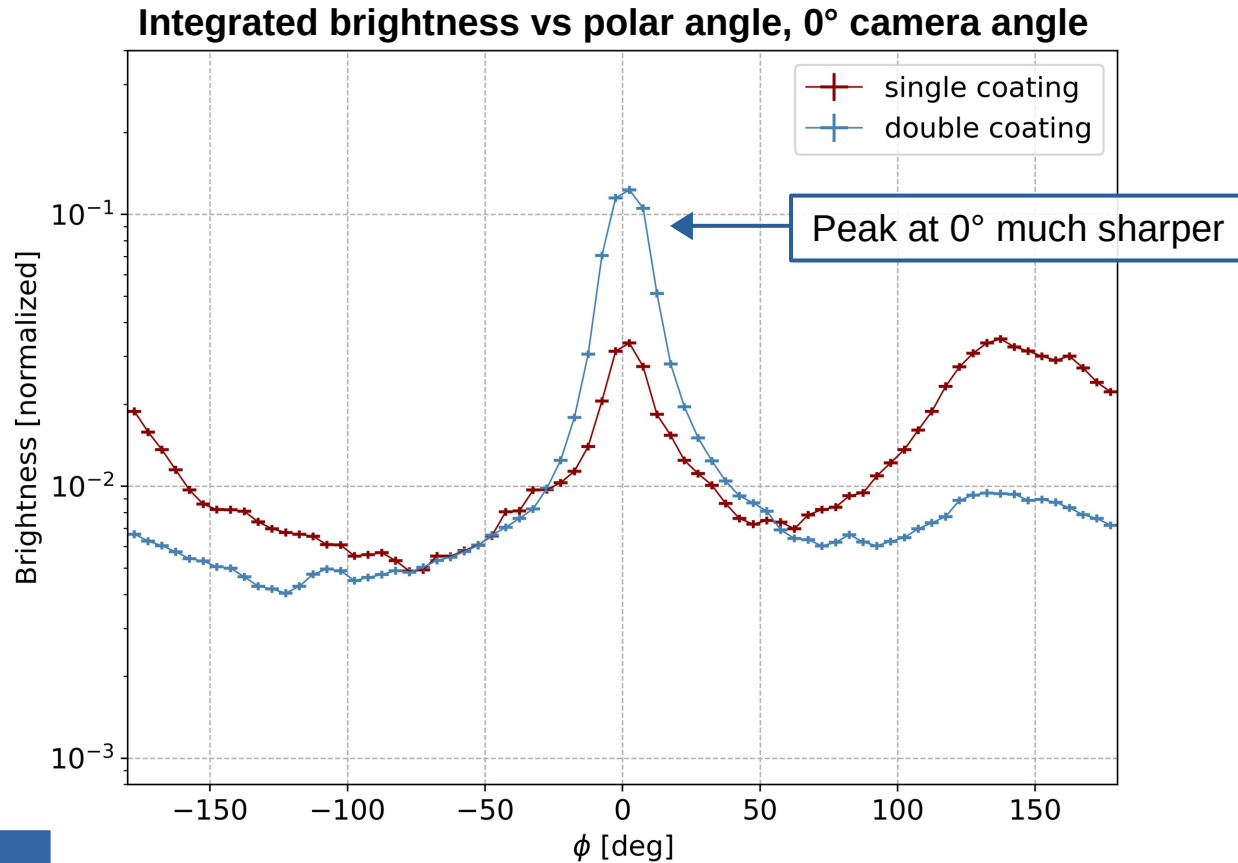
0° camera angle



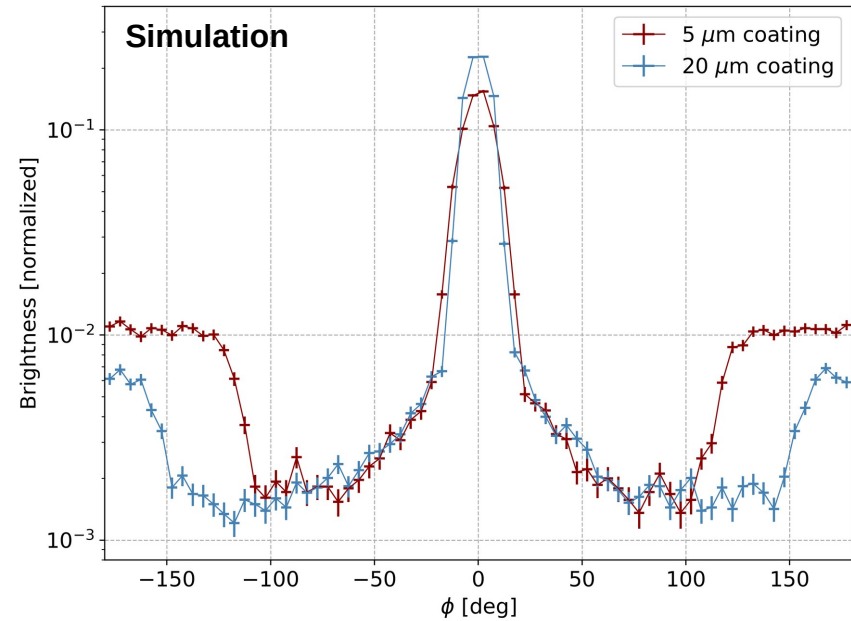
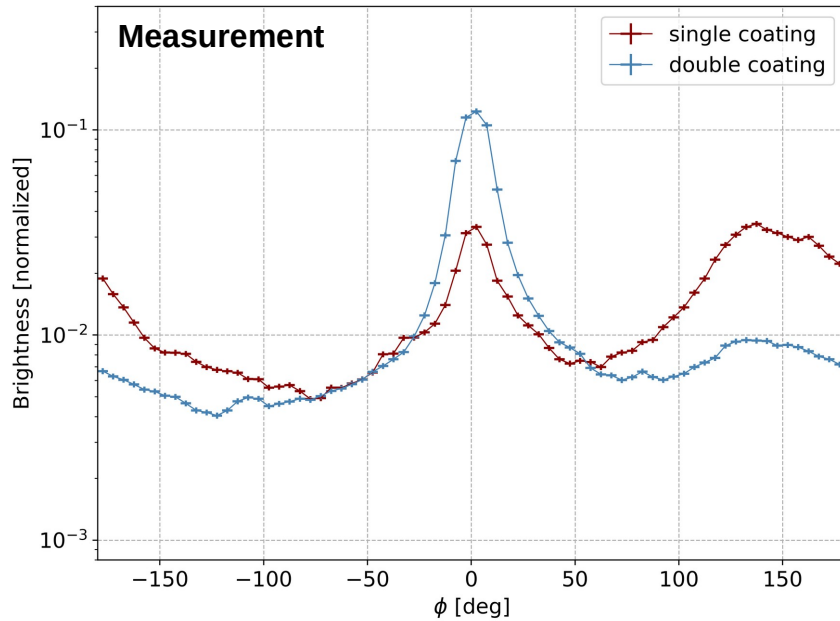
- Double coating = two layers of paint
- ~ 20 micrometer thickness

→ Why are the distributions so different?

Tubes comparison



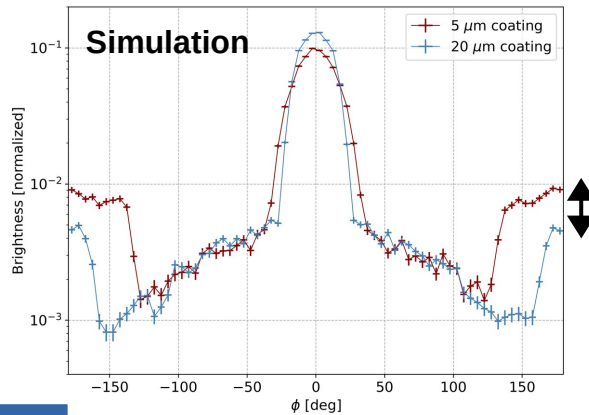
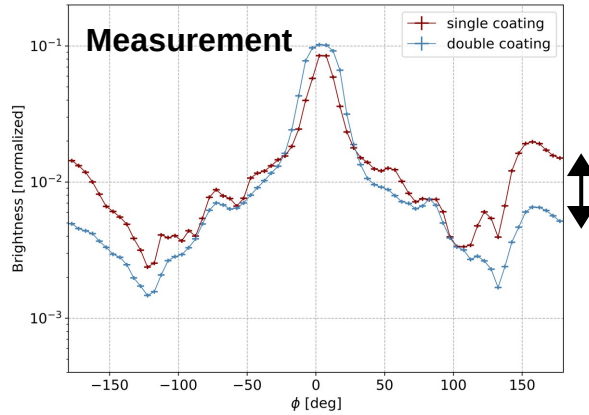
Tubes comparison



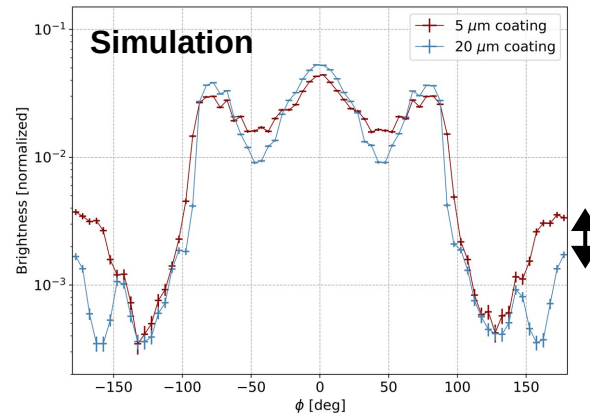
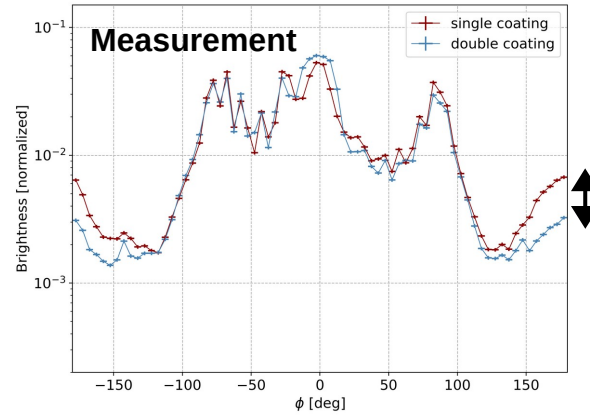
→ Simulation with significant differences, but seems to support the assumption

Tubes comparison

10° camera angle



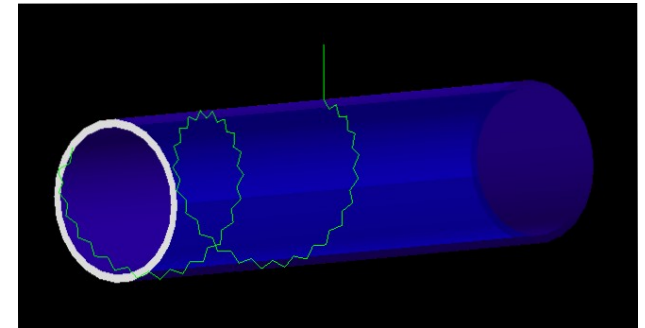
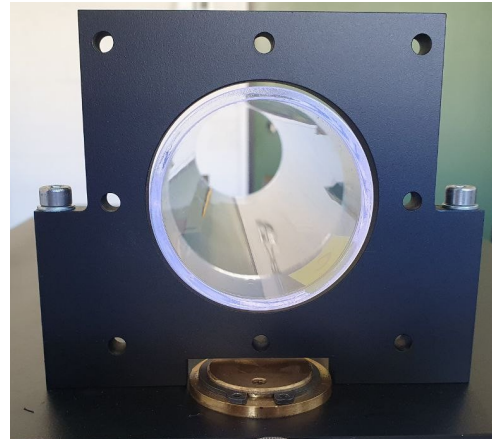
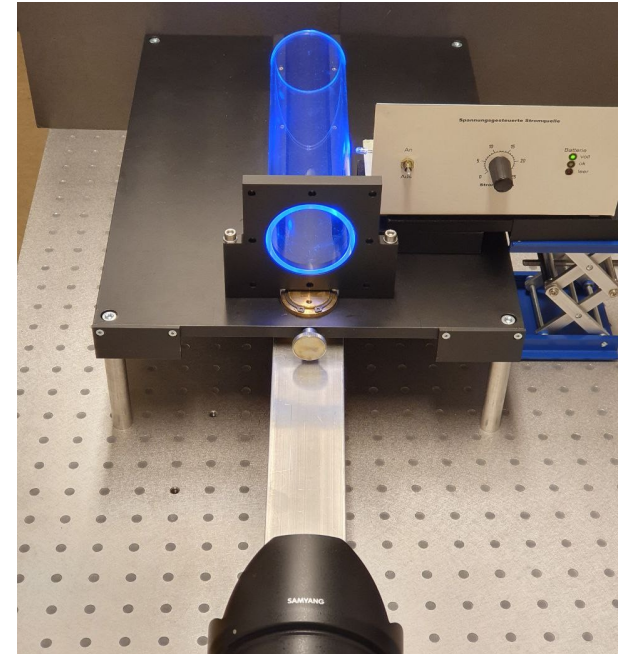
30° camera angle



- Simulation confirms:
Thicker layer of coating
results in more photons on
the other side of the tube
- Experimental setup
provides measurement of
coating thickness
- Quality control?

Summary

- WOM tube simulations show good agreement with the measurement: structures can be reproduced
- Measurement setup sensitive to thickness of WLS paint
→ Quality control
- Outlook: Automated setup with adjustable light source position
- Add grid of LEDs for calibration



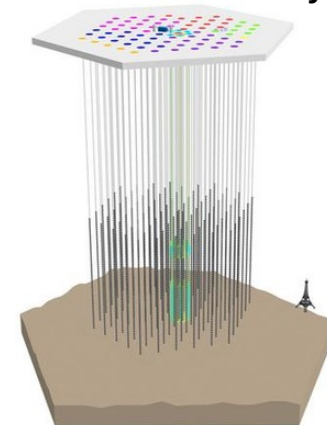
Backup

Wavelength-Shifting Optical Modules

- First proposed for large-scale water Cherenkov detectors in neutrino physics (e.g. IceCube) ¹
 - Instrumentation with large number of photosensitive devices (IceCube: PMTs)
 - Sensitivity limited by mass of instrumented volume, instrumentation density and photo collection area of each sensor
 - More photodetectors: significant cost factor
 - Larger photodetectors increase noise rate
- Solution: Increase sensitive area of each detector with light collector

¹ The Wavelength-shifting Optical Module (arXiv:2112.12258)

IceCube Observaory



physik.hu-berlin.de

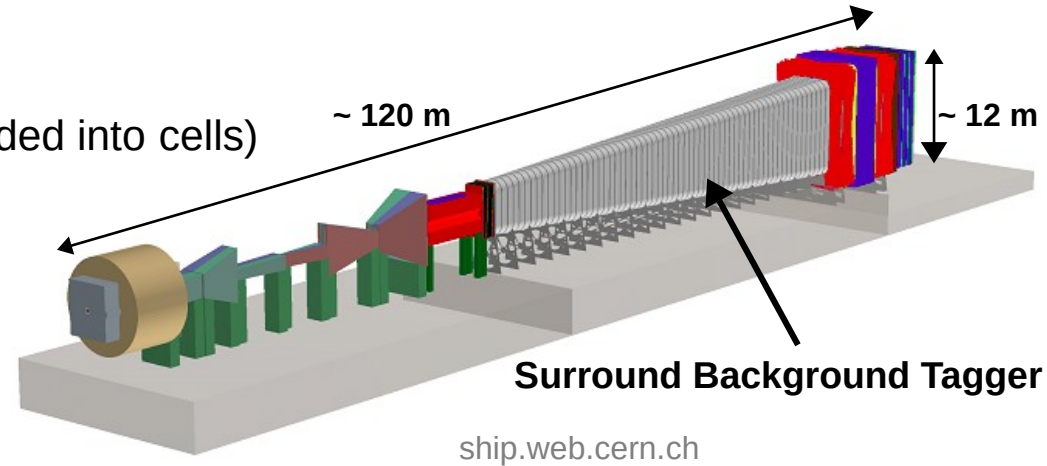
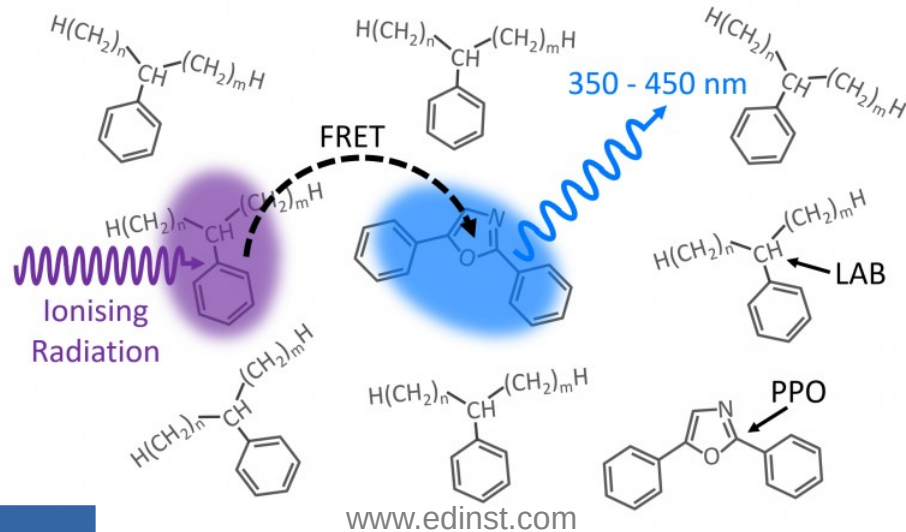
20" PMT, Super-Kamiokande



C. Warner, SPIE (2016)

WOMs in large-area liquid-scintillator detectors (SHiP-SBT)

- **SBT (Surround Background Tagger)**
 - Filled with $\sim 300 \text{ m}^3$ liquid scintillator (divided into cells)
 - Solvent: LAB (Linear alkylbenzene)
 - Fluor: PPO (2,5-diphenyloxazole), 2g/l



Challenges for detection of scintillation photons:

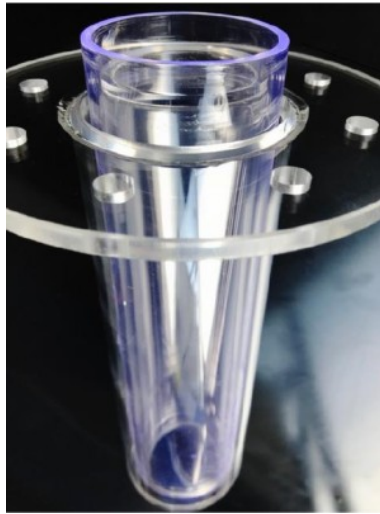
- Energy resolution and energy threshold limited by properties of photo sensors → **Highly efficient**
- Large volume → **Cost-effective**

WOMs in large-area liquid-scintillator detectors (SHiP-SBT)

- **PMMA tube:**
 - 23 cm length, 60 mm diameter, 3 mm thickness
 - Coated with wavelength-shifting (WLS) paint (Bis-MSB)

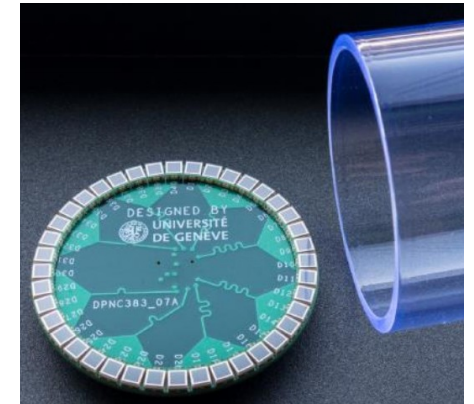
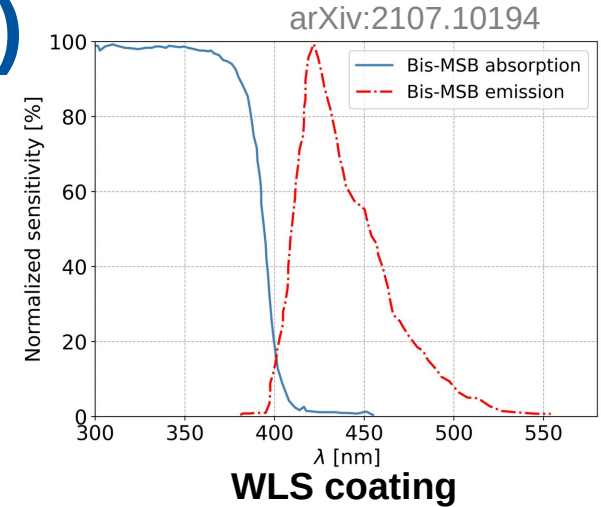


WOM tube



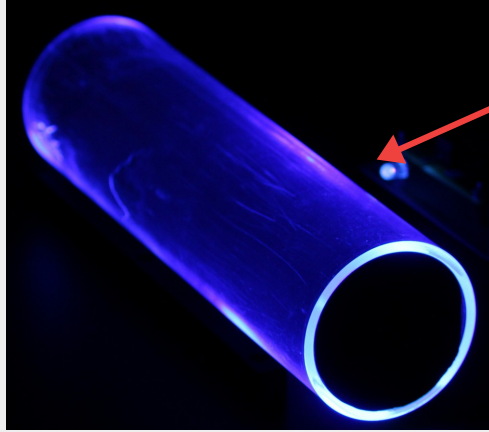
Vessel

- **PMMA vessel:**
 - Insulation from liquid scintillator
- **Photosensors:**
 - 40 SiPMs directly coupled to the exit surface of the tube
 - 3 mm $\times$ 3 mm sensitive area



40-SiPM PCB

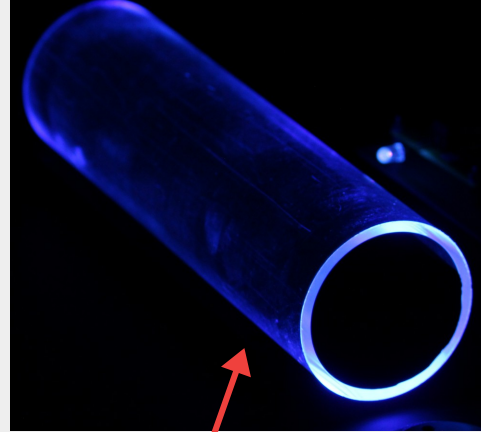
WOM Tubes and Surfaces



Double-sided
coating



Visible
scratches/
cracks

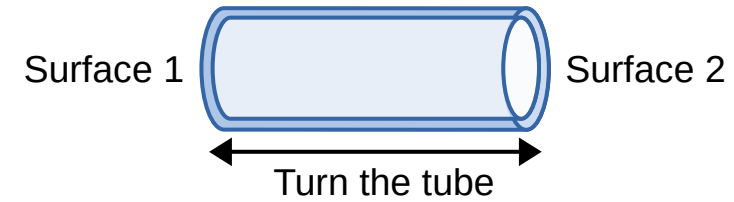
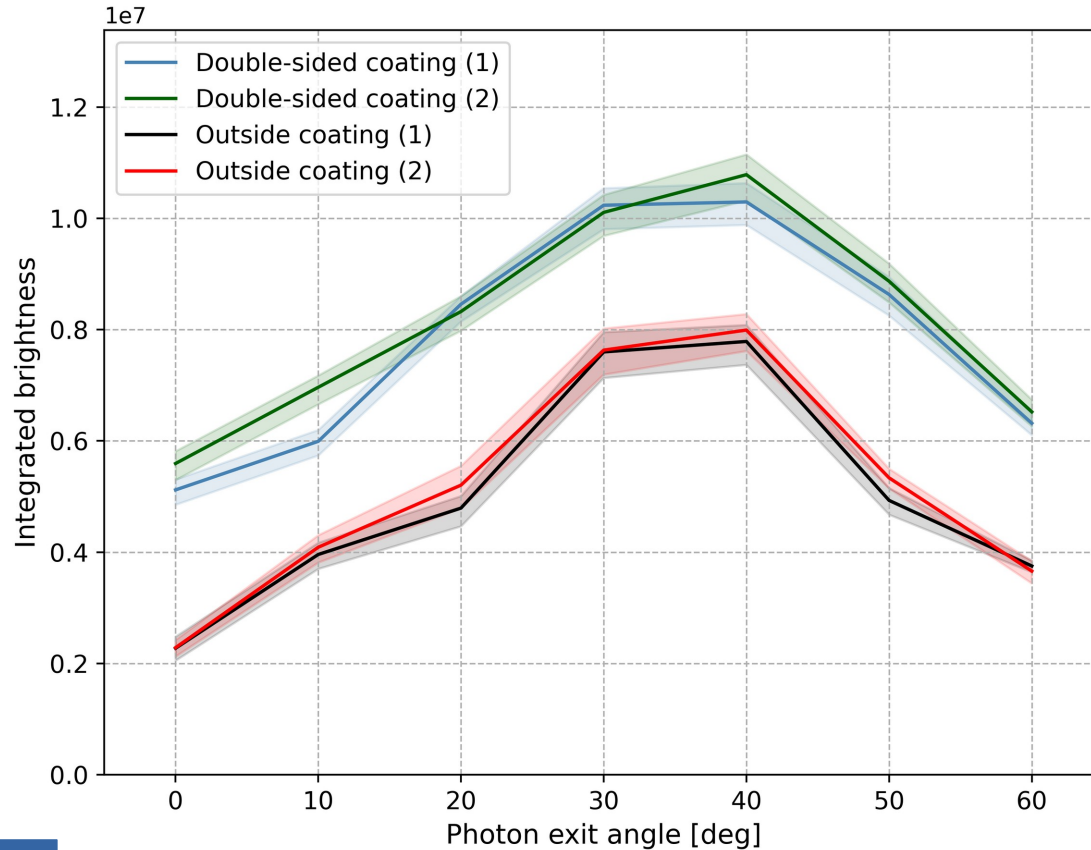


Outside
coating

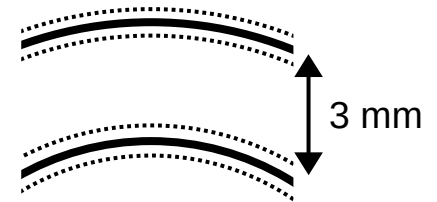
Residue from
coating process on
one of the surfaces
(both tubes)



Photon exit angle distribution



→ Error bands: Variation of radius by ± 0.1 mm



→ No significant differences between the two surfaces of each tube