

# Highlights & news from KIT

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Luca Scomparin<sup>3</sup>, Chenran Xu<sup>2</sup>, Anke-Susanne Müller<sup>1,2</sup>

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**ACCLAIM Meeting 03/02/2023**

## New members



Stephan Robert Kötter  
Postdoc

- Orbit correction
- Photoinjector laser manipulation with ML

## Publications

- "Bayesian Optimization of the Beam Injection Process into a Storage Ring", **C. Xu** et al., e-Print: [2211.09504](#) [physics.acc-ph] (submitted to PRAB)
- "Surrogate Modelling of the FLUTE Low-Energy Section", **C. Xu** et al., [IPAC'22 TUPOPT070](#)
- "Optimization Studies of Simulated THz Radiation at FLUTE", **C. Xu** et al., [IPAC'22 WEPOMS023](#)
- "KINGFISHER: a framework for fast machine learning inference for autonomous accelerator systems", **L. Scomparin** et al., [IBIC'22 MOP42](#)

## Outreach & collaboration

Machine Learning workshop of the MTARD ST3 annual meeting: <https://github.com/ansantam/2022-MT-ARD-ST3-ML-workshop>



Keynote: reinforcement learning in the research field of accelerators, Conceptual Advances in Deep Learning for Research on Universe and Matter, A. Santamaría García, September 2022, <https://indico.scc.kit.edu/event/2853/contributions/11041/>

Machine learning for tuning, prediction, and control at the KIT electron accelerators, 3rd ICFA Beam Dynamics Mini-Workshop on Machine Learning Applications for Particle Accelerators, A. Santamaría García, November 2022, <https://indico.bnl.gov/event/16158/contributions/69582/>

# 1st collaboration workshop on Reinforcement Learning for Autonomous Accelerators (RL4AA'23)

20-21 February 2023

Institute of Beam Physics and Technology (KIT)

Europe/Berlin timezone

Overview

Timetable

Contribution List

My Conference

  └ My Contributions

Registration

Participant List

Venue

Contact

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Reinforcement learning (RL) is a powerful learning paradigm of machine learning (ML). It is particularly suited to tackle control problems in large environments, can learn from experience without the need of a model of the dynamics, and can deal with delayed consequences.

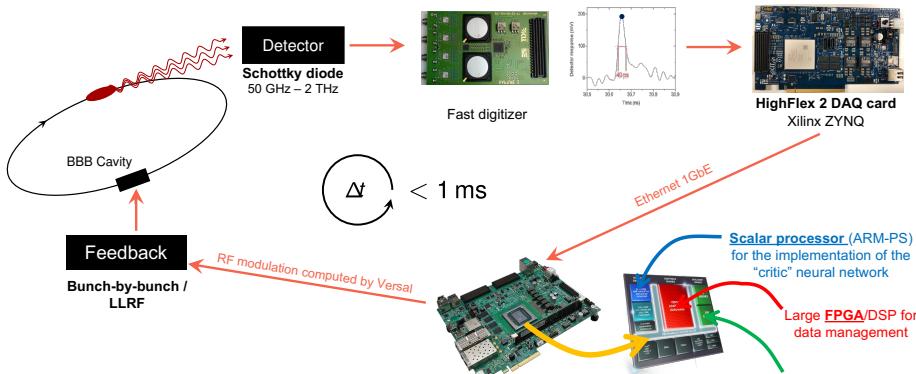
Capturing your control problem as a meaningful Markov Decision Process (MDP) is not trivial. Additional challenges arise in the training in terms of stability and evaluation. Other practical aspects include reproducibility, efficiency, implementation, deployment in hardware, or choosing the most suitable algorithm for your problem.

RL applications in particle accelerators are very promising, but have been deployed in real machines only a handful of times. This workshop aims at lowering the barrier in applying RL and making it a more widely used tool.

We will take time for valuable discussions on the topic of RL applied to particle accelerators and to improve our common knowledge. We will also exchange ideas about promising future avenues and help consolidate a community to advance in this area of research in accelerator controls.

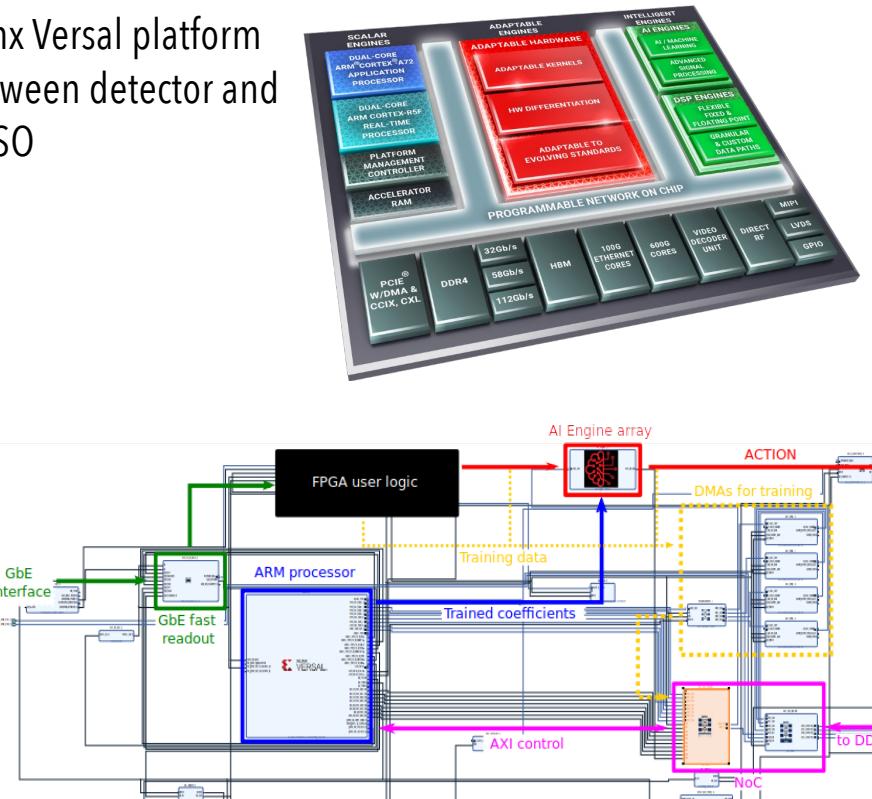
<https://indico.scc.kit.edu/event/3280/>

- Ongoing development of RL feedback system based on Xilinx Versal platform
- Target of low loop latency (tens of  $\mu\text{s}$ ) and long distance between detector and action necessary, plus integration with KAPTURE and KALYPSO



Courtesy of M. Caselle & L. Scomparin

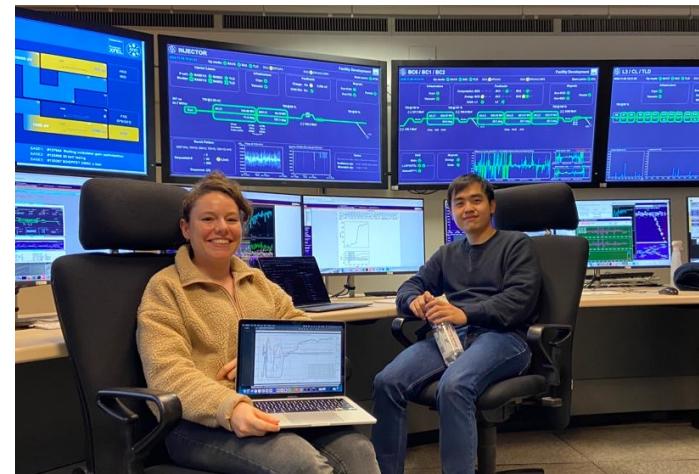
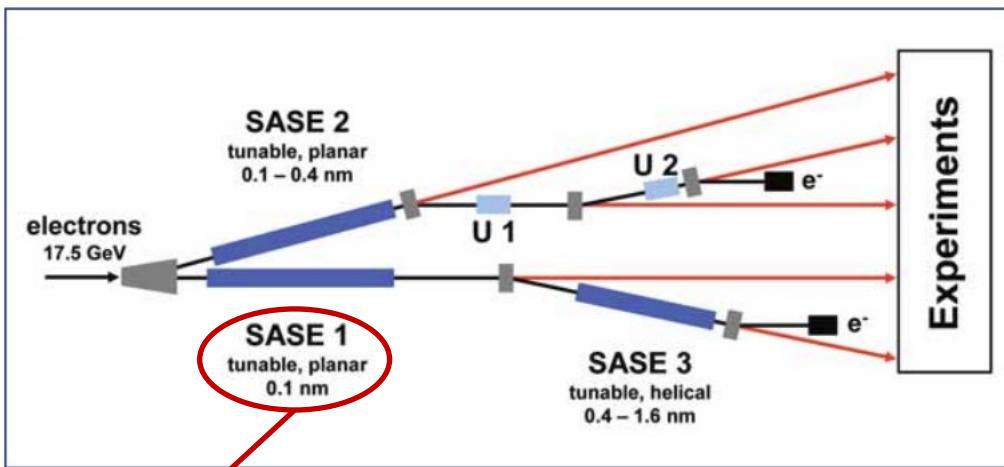
Andrea Santamaría García



LAS/IBPT

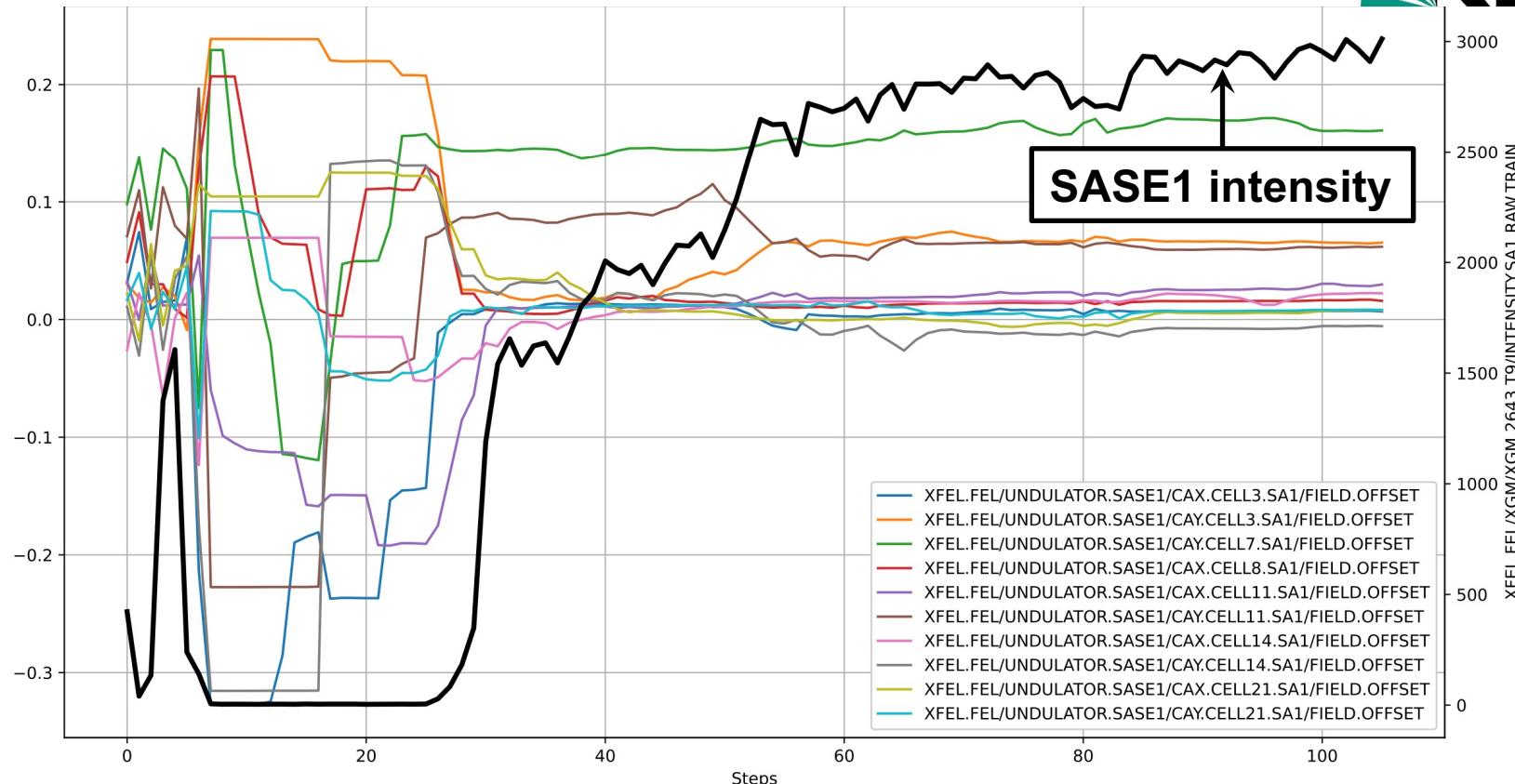
# Trying Bayesian optimization at the European XFEL

Cheran Xu, Sergey Tomin, Andrea Santamaría García



- **Goal:** increase the photon intensity at SASE1 by tuning air coils
- **Air coils:** provide small beam trajectory corrections (max. steering power +/- 0.6 T.mm)
- **SASE1:** 35 undulators of 5m length and 1m separation. Two air coils (H,V) upstream and downstream of each undulator

# Bayesian optimization of SASE signal with 10 air coils



# THZ PULSE OPTIMIZATION AT FLUTE

## Surrogate model

input

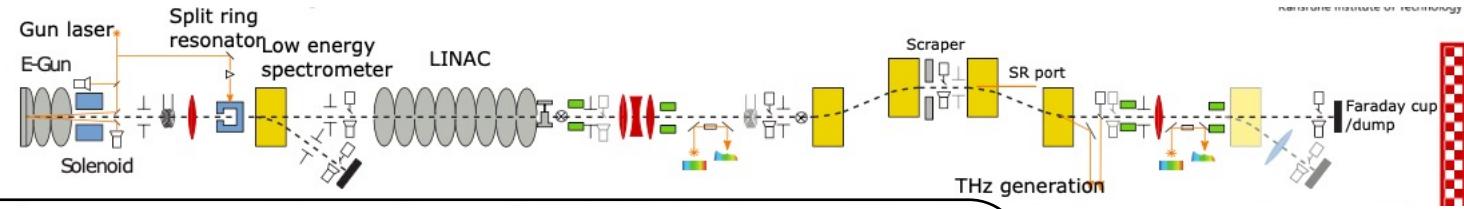
1. RF gun phase
2. RF gun amplitude
3. Solenoid current
4. Bunch charge

[C. Xu et al. TUOPT070, IPAC22](#)

output

1. Mean energy
2. Energy spread
3. RMS bunch length
4. Beam size
5. Emittance
6. % remaining part.

Can inform/guide the optimization with smart initial guesses



## Parallel Bayesian optimization

input

1. RF gun phase
2. RF gun amplitude
3. Solenoid current
4. Linac phase
5. Linac amplitude
6. Chicane bending radius

objective

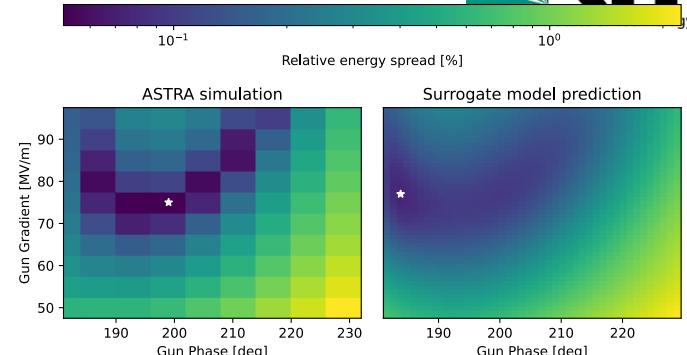
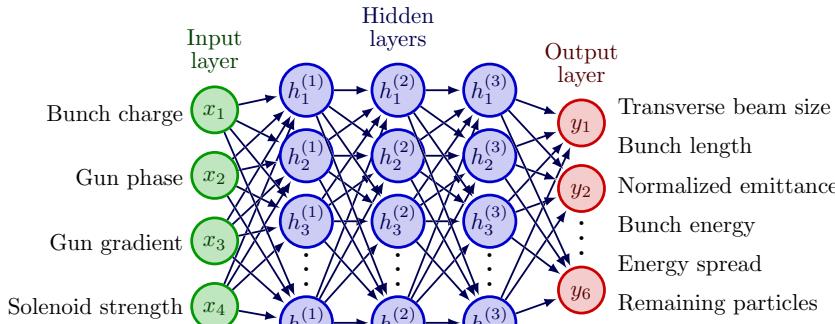
- Min. RMS bunch length after chicane
- Max. peak E-field of CSR pulse

observation

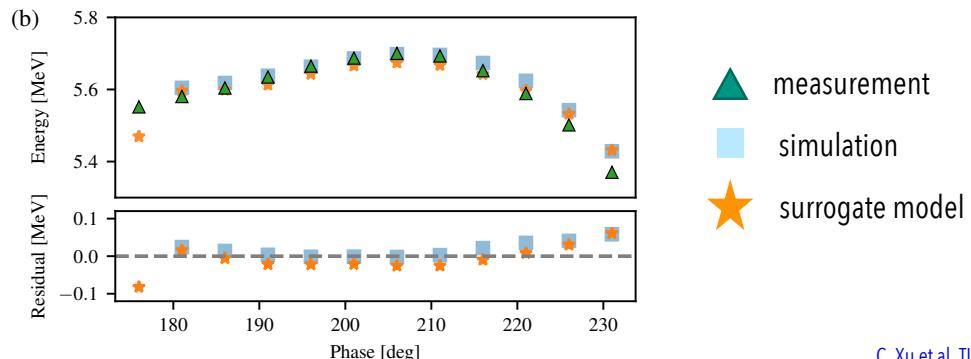
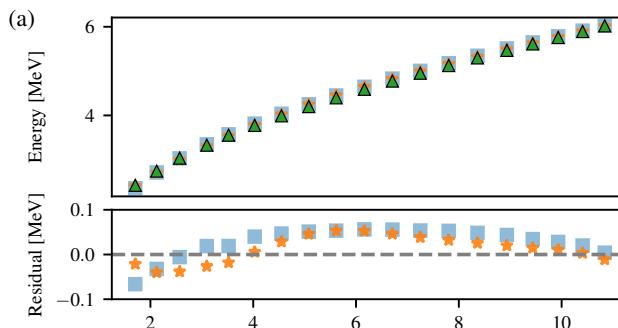
- Long. phase space
- Spectral intensity
- Form factor
- Bunch current profile
- THz pulse E-field

[C. Xu et al. WEPOMS023, IPAC22](#)

# SURROGATE MODEL AS VIRTUAL DIAGNOSTIC

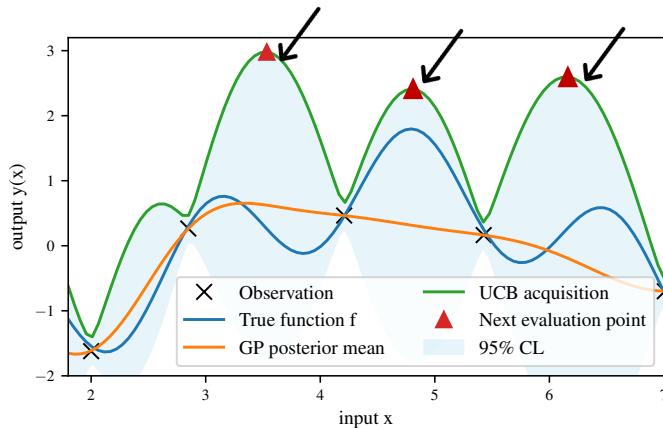


Good agreement with measurements:

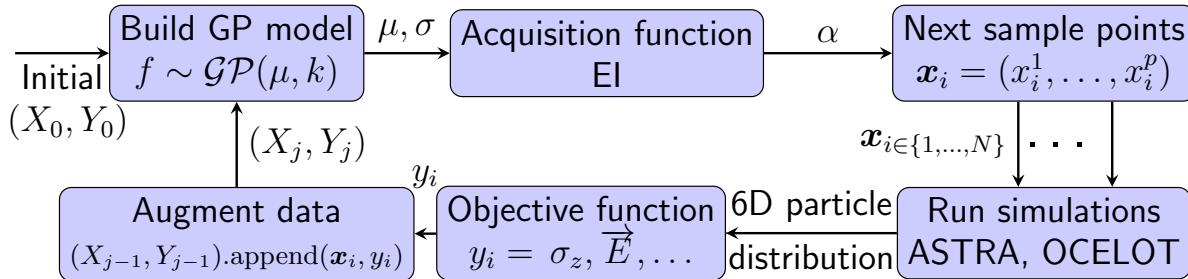
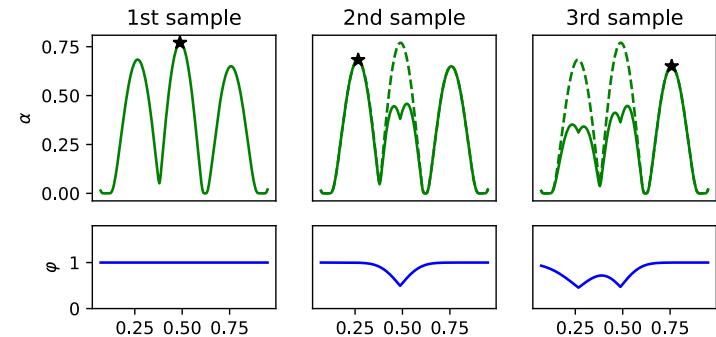
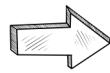


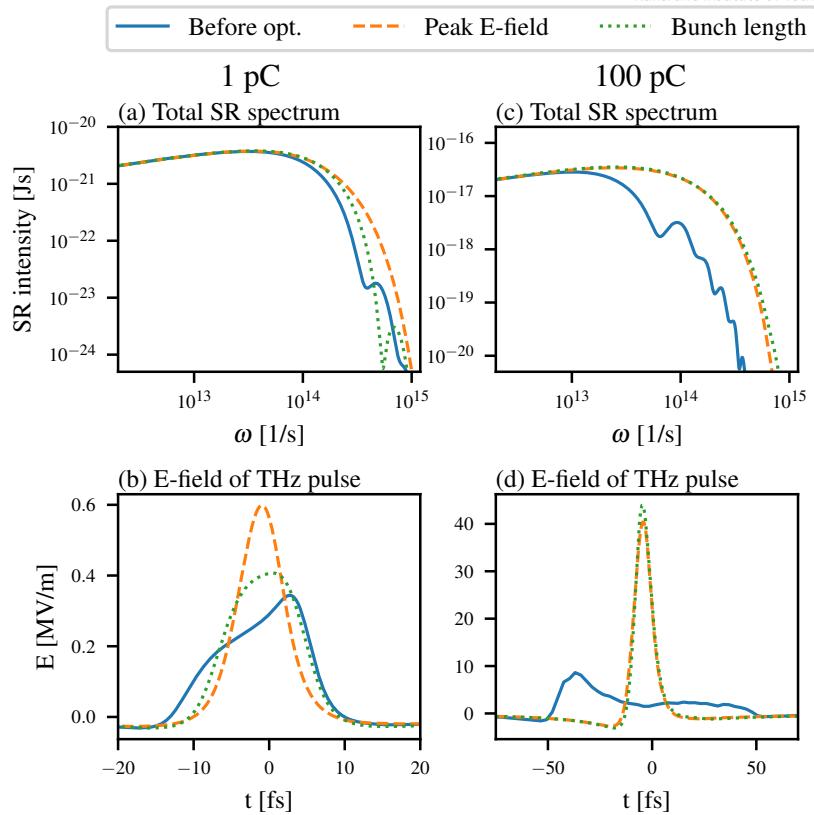
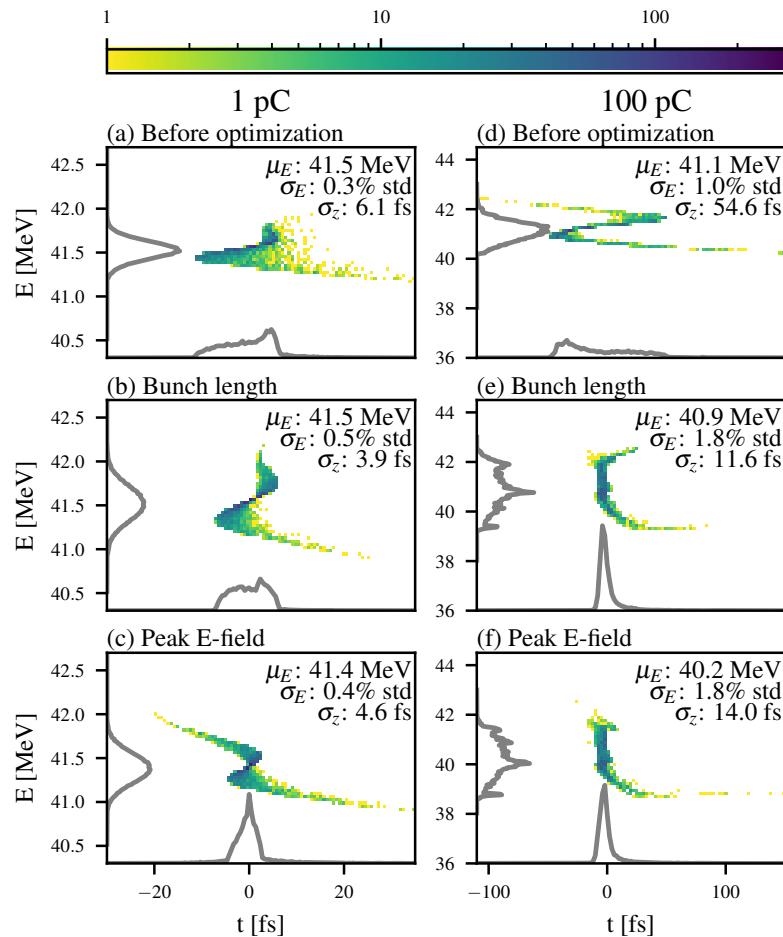
C. Xu et al. TUOPT070, IPAC22

# PARALLEL BAYESIAN OPTIMIZATION



A batch of points is selected to be processed in parallel





# Thank you for your attention!