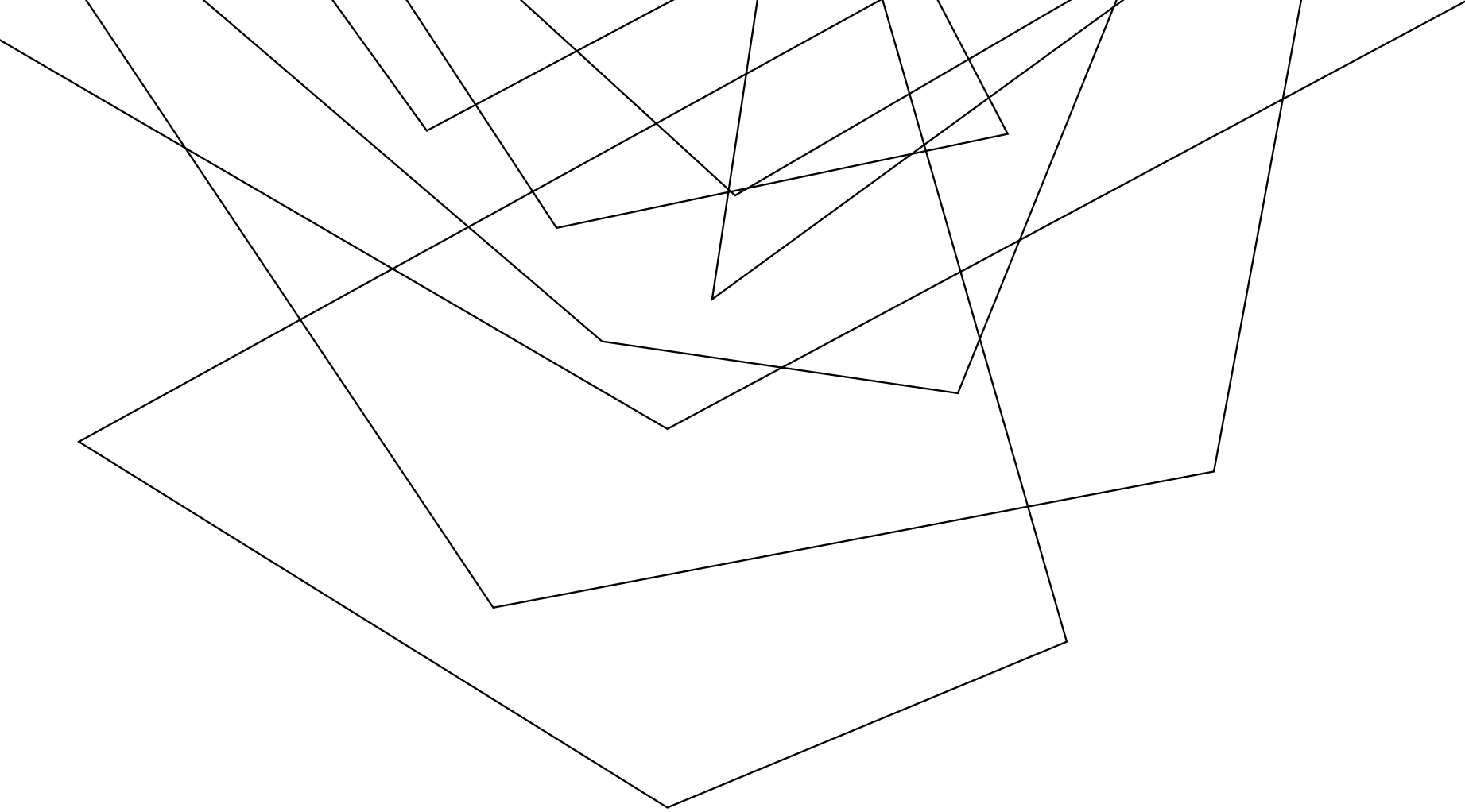


Abstract geometric lines forming various polygons and shapes, primarily in the upper left quadrant of the slide.

AUTOENCODER

Thorben Finke (RWTH Aachen University)

Train-the-Trainer Workshop, Dortmund 19.06.2023

OUTLINE

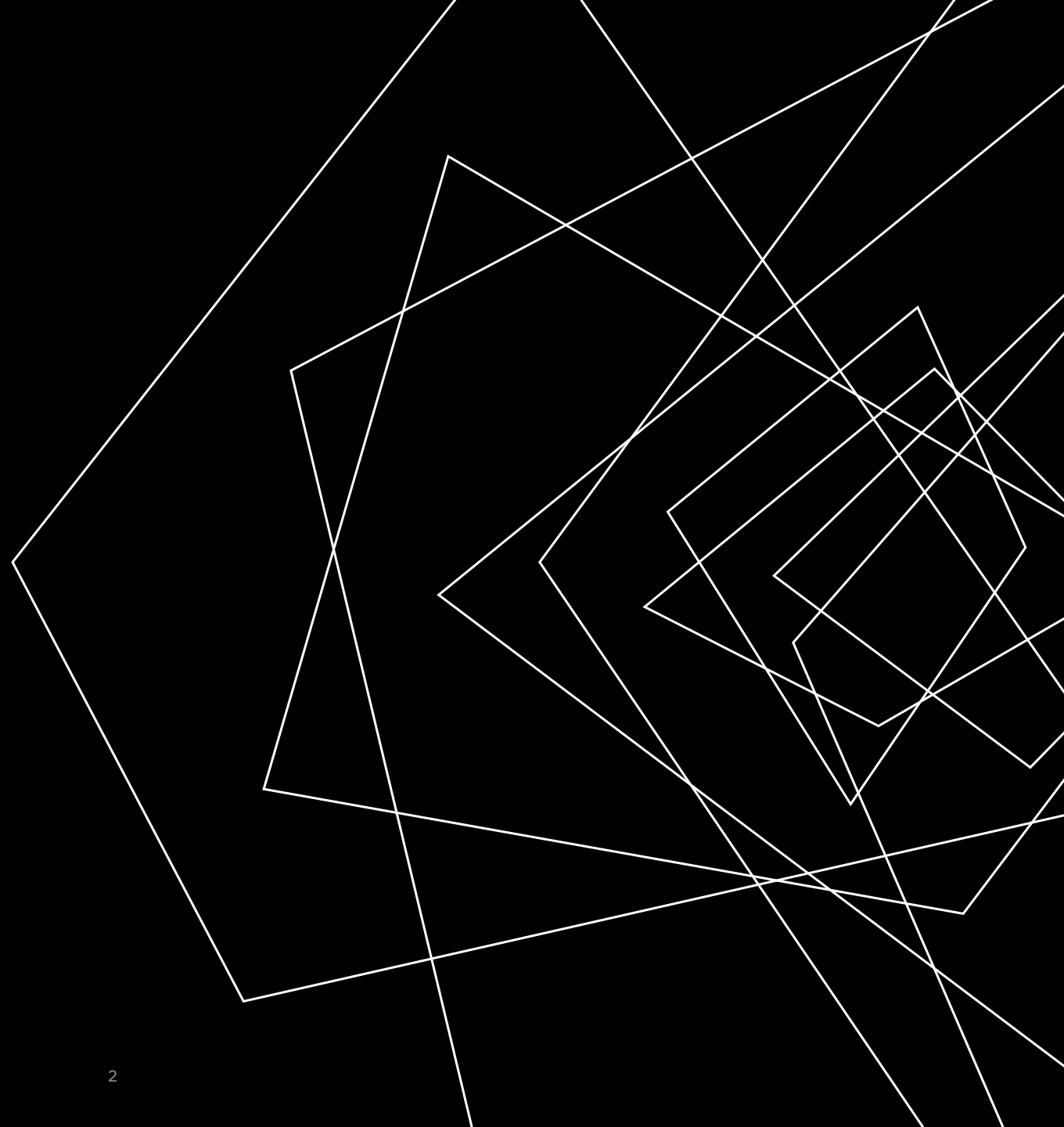
Introduction

Basic setup

Autoencoder variants

Detecting anomalies

Summary



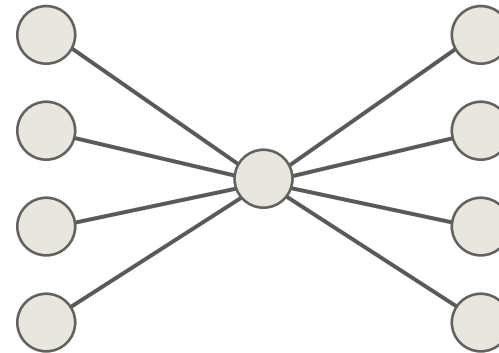
INTRODUCTION

- Autoencoder perform data compression and expansion
- Best linear encoding $\mathbf{E} \in \mathbb{R}^{c \times d}$ and decoding $\mathbf{D} \in \mathbb{R}^{d \times c}$ into orthonormal basis:

Principle Component Analysis (PCA)

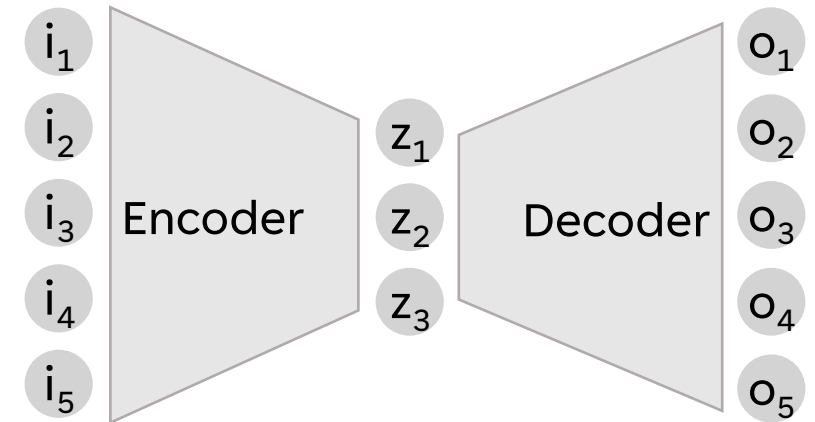
$$\vec{x}' = \mathbf{D}\mathbf{E}\vec{x} \text{ minimize } \|\vec{x} - \vec{x}'\|^2$$

- Results in $\mathbf{E} = \mathbf{D}^T$ eigenvectors of the covariance matrix of the data
- Visualization for $d = 4, c = 1$



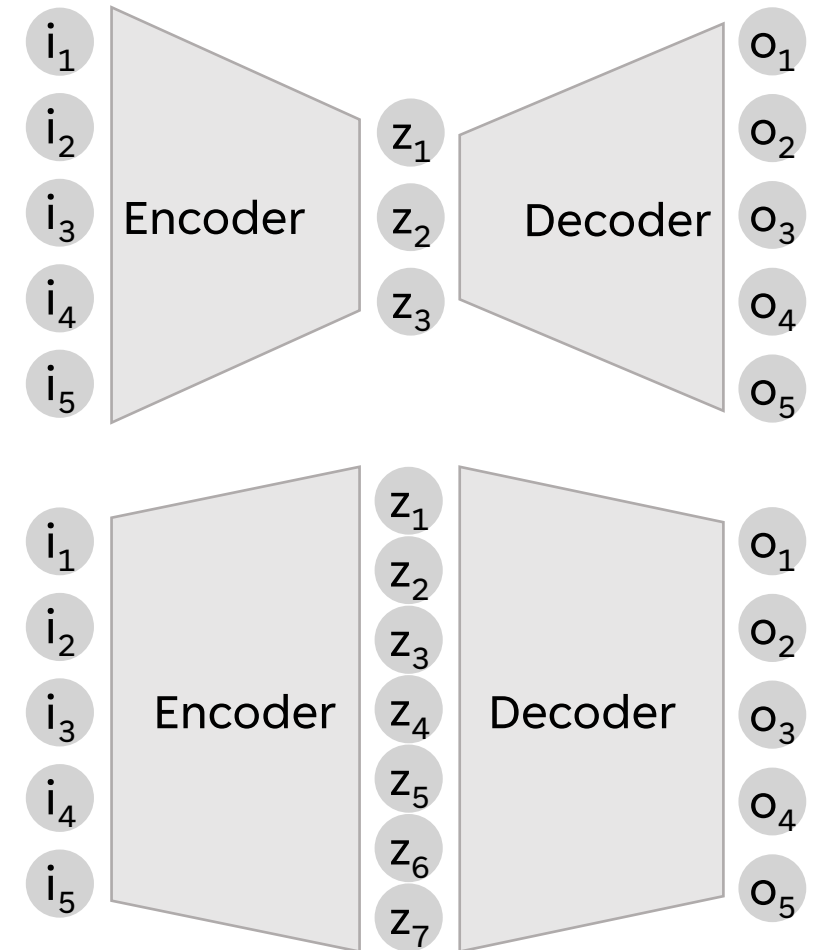
BASIC SETUP

- Autoencoder consist of two parts: Encoder and decoder
- Encoder projects input $\mathbf{i}$ to some latent representation $\mathbf{z}$
- Decoder projects back to the input dimension
- Train to minimize difference between input and output
- Unsupervised method, since no labels required



BASIC SETUP

- Undercomplete AE: Reduced latent dimension
- Overcomplete AE: Sparsity constraint
- Applications:
 - Feature extraction
 - Denoising
 - Data generation
 - Anomaly detection

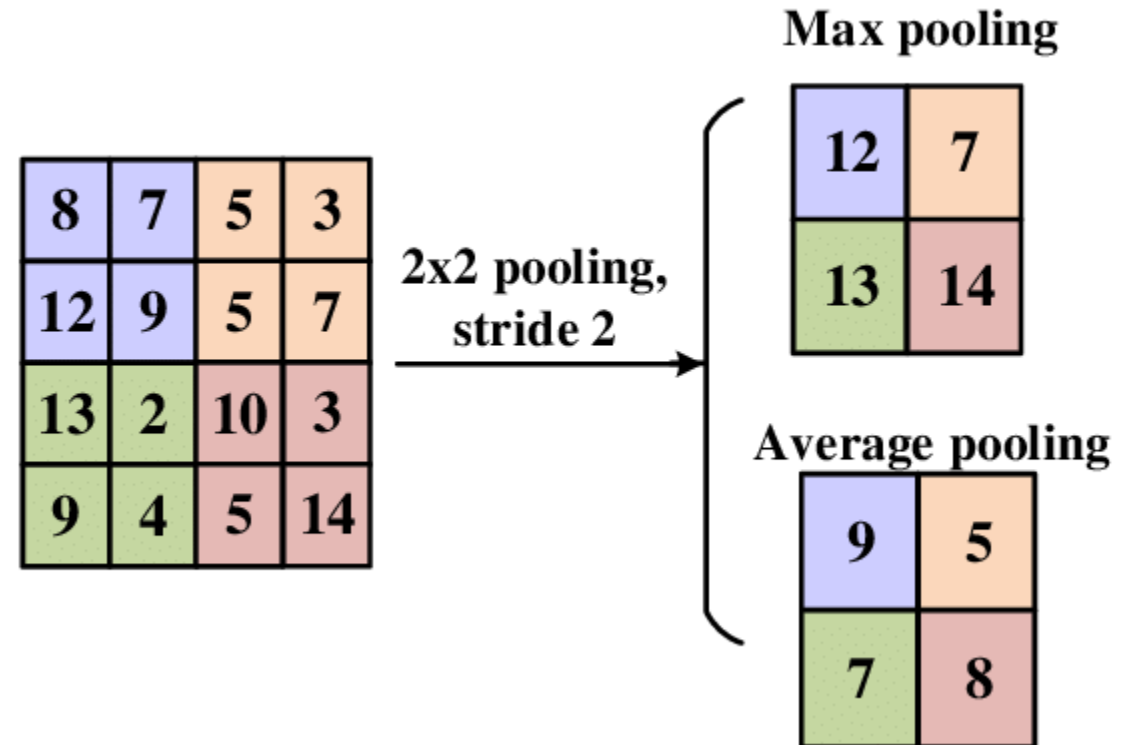


VARIOUS INPUTS

- Features
 - Fully connected architectures
- Sequences
 - Recurrent architectures
- Images
 - Convolutional architectures
- Graphs
 - Graph convolutional architectures

CONVOLUTIONAL AUTOENCODER

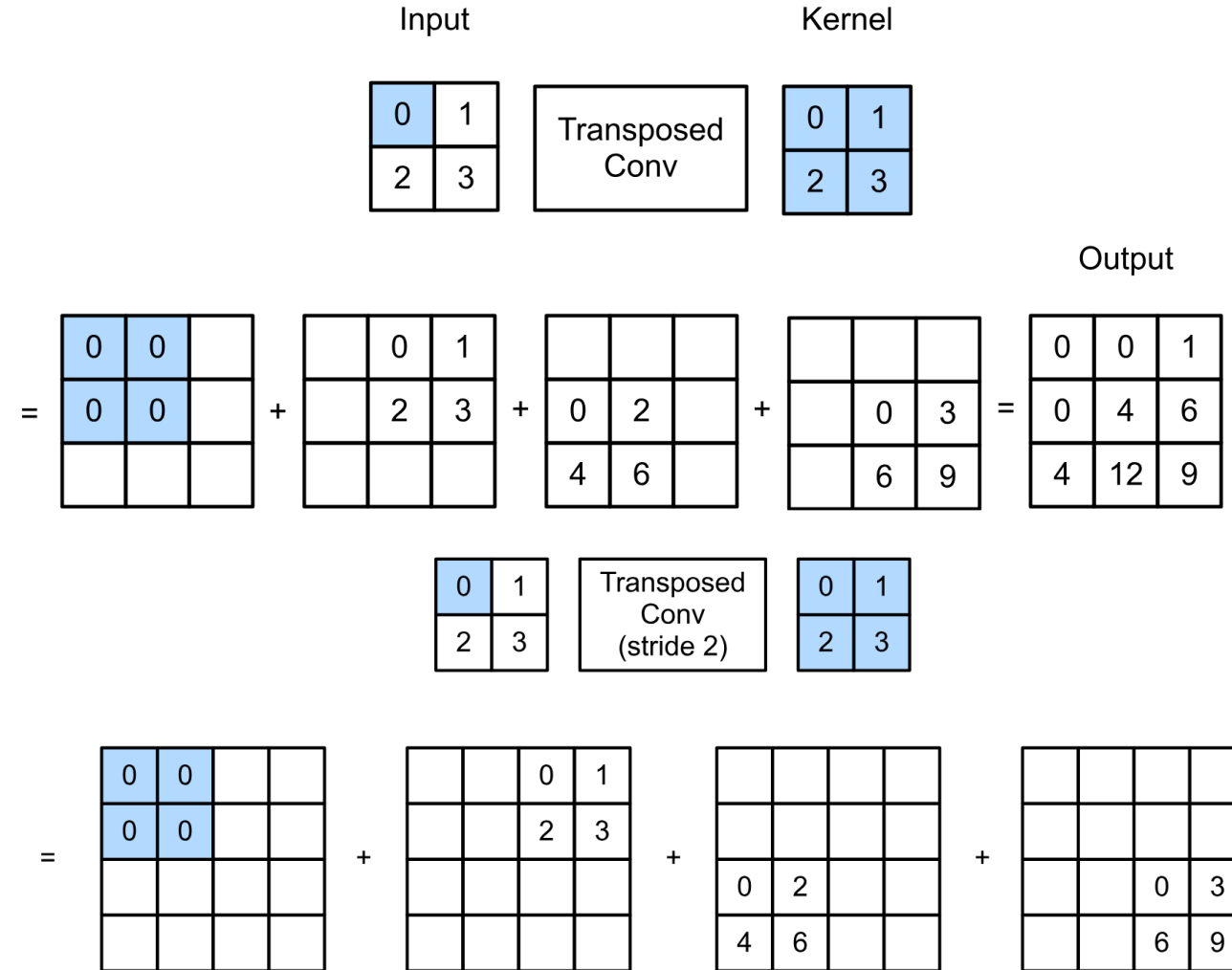
- **Dimensional reduction**
 - Pooling operations
 - Convolutions with stride > 1
- Dimensional inflation
 - Upsampling
 - Transposed convolutions



[Source](#)

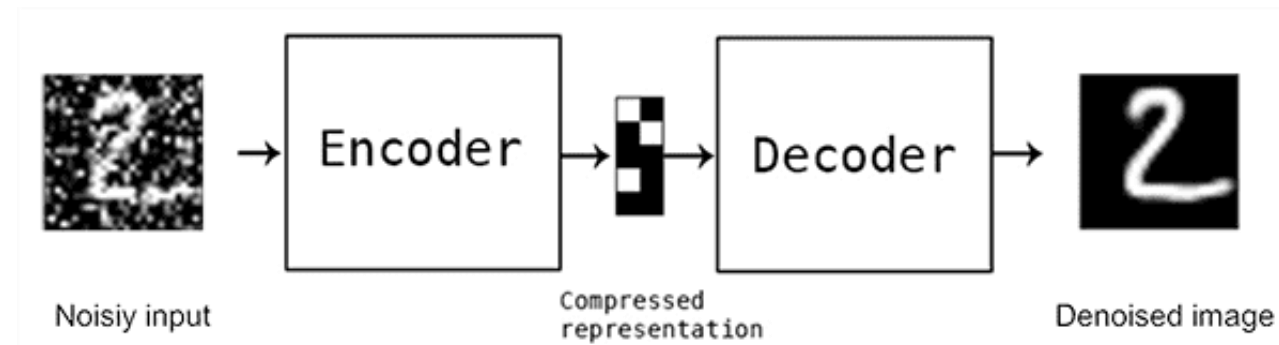
CONVOLUTIONAL AUTOENCODER

- Dimensional reduction
 - Pooling operations
 - Convolutions with stride > 1
- **Dimensional inflation**
 - Upsampling
 - Transposed convolutions



DENOISING AUTOENCODERS

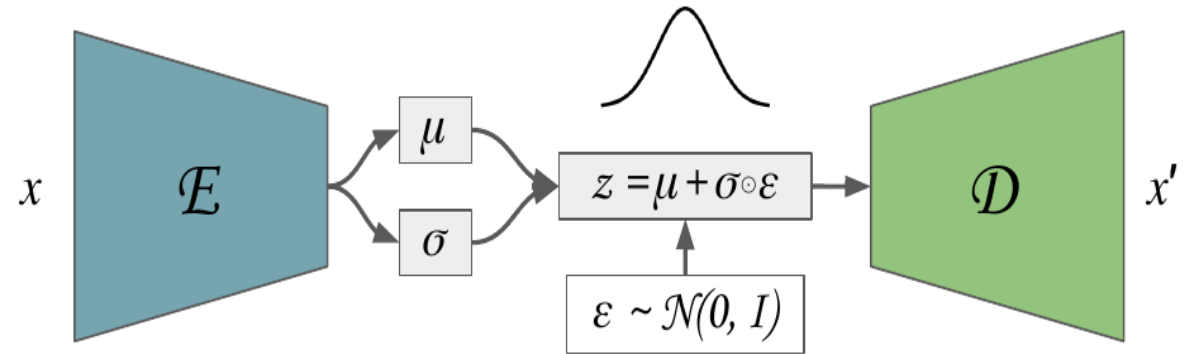
- Add noise to the inputs
- Train to reconstruct input without noise
- Originally intended to learn more robust representations
- Reduced risk of overfitting
- Physics applications
 - Gravitational waves [1711.09919](#)
 - Foreground removal in cosmology [1902.09278](#)
 - Radio astronomy [2110.08618](#)
 - Air shower signal recovery [1901.04079](#)



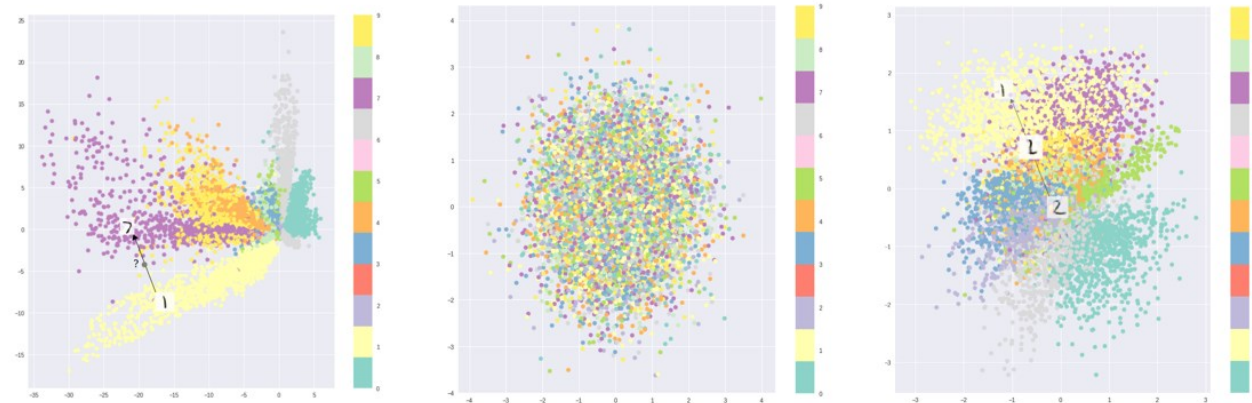
[Source](#)

VARIATIONAL AUTOENCODER

- Replace deterministic latent space by trainable distribution
- Reparameterization trick to update the distribution parameters
- Additional term in the loss imposing a given distribution
 - $\mathcal{L} = \beta D_{KL}(p, q) + \|x - x'\|^2$
- Results in smooth and more interpretable latent space



[2211.01421](#)



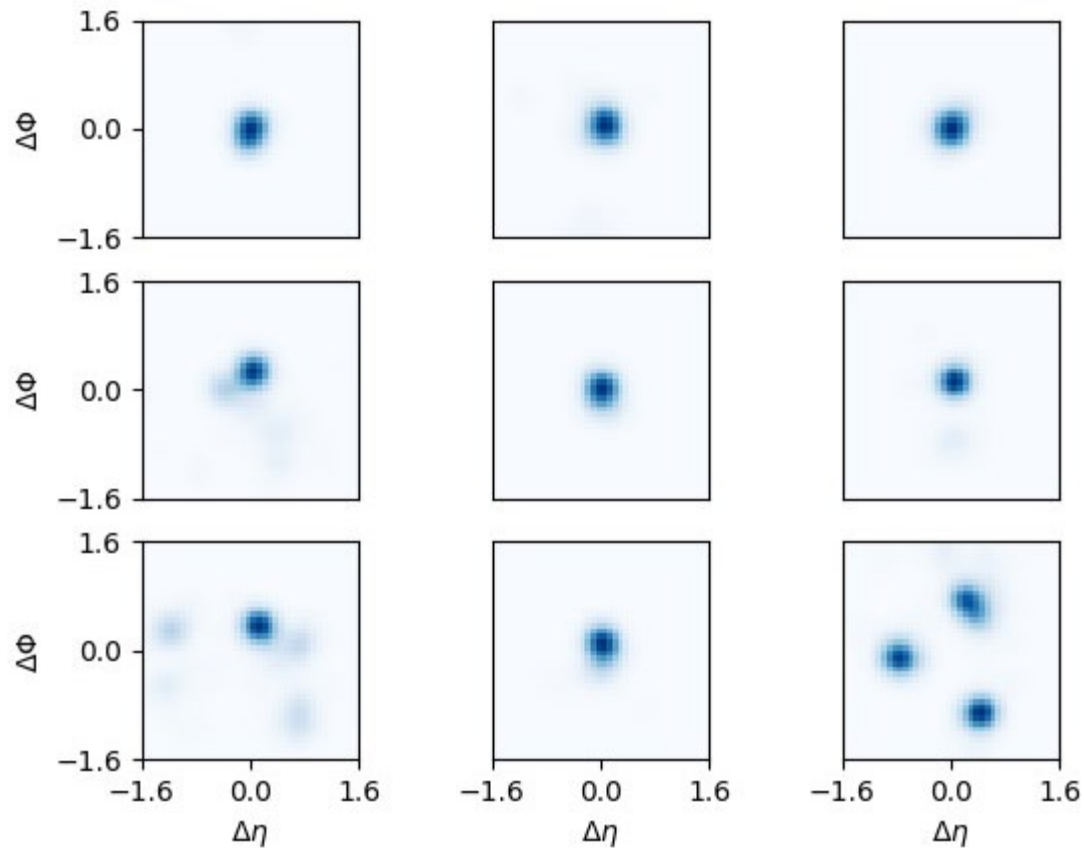
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ANOMALY DETECTION USING AUTOENCODERS

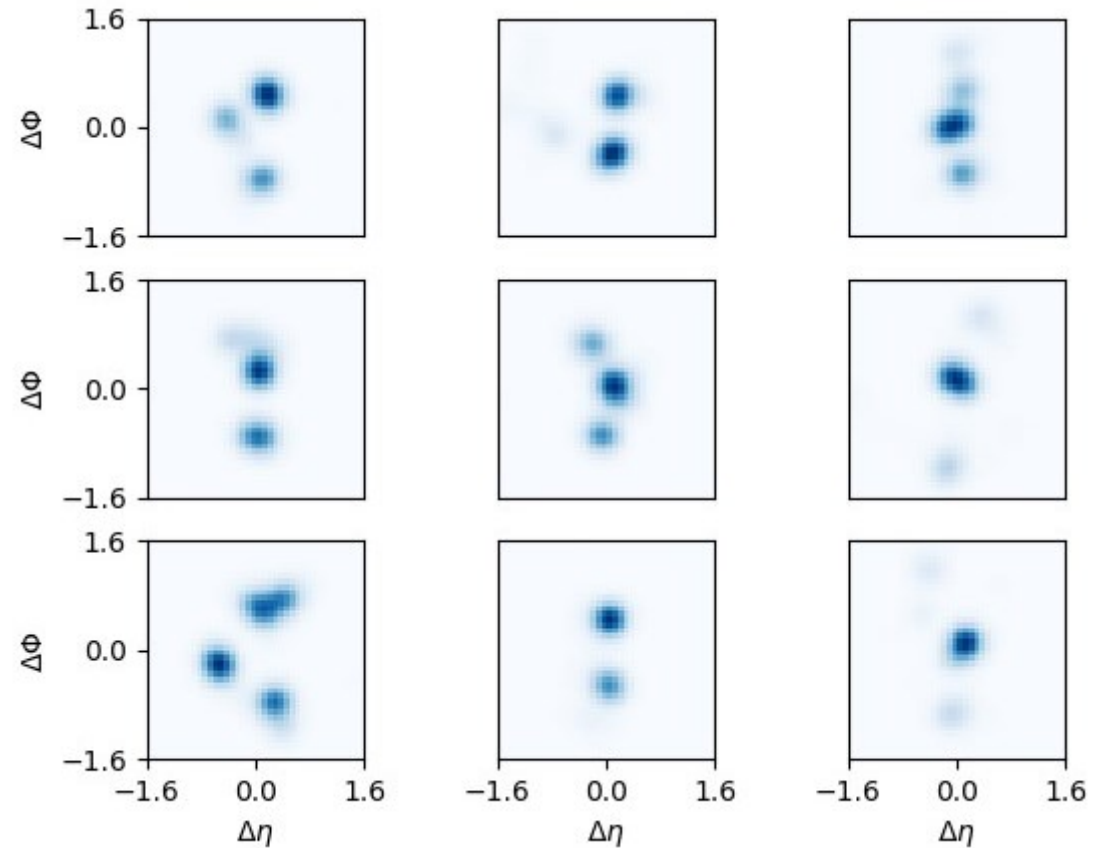
- Learn what's normal to find anomalies
- During training learn meaningful representation of normal data
- Idea: reconstruction of anomalous data is worse than for normal data
 - Use the reconstruction loss as anomaly score during inference
- Example: anomalous jet tagging on the top tagging benchmark dataset
[10.5281/zenodo.2603256](https://doi.org/10.5281/zenodo.2603256)

ANOMALY DETECTION USING AUTOENCODERS – JET IMAGE EXAMPLE

Light QCD jets

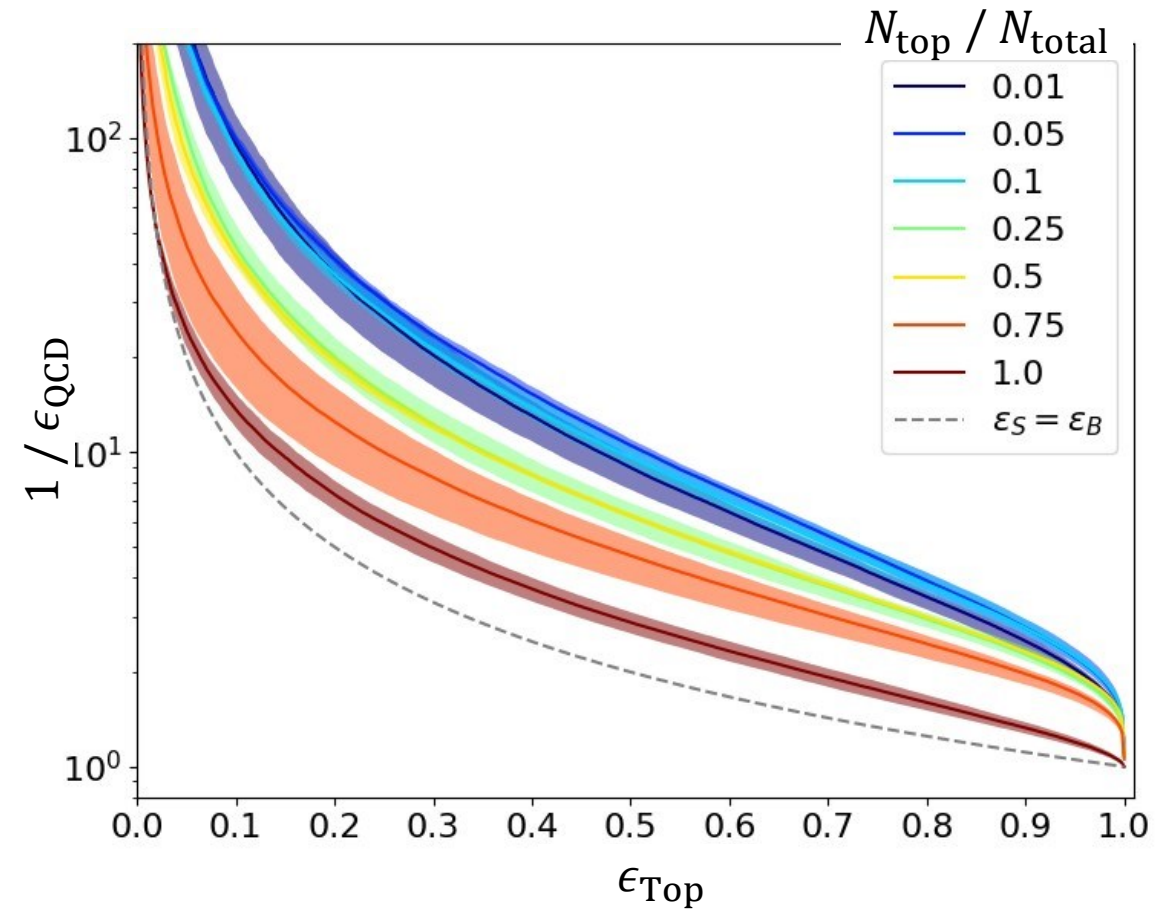


Top jets



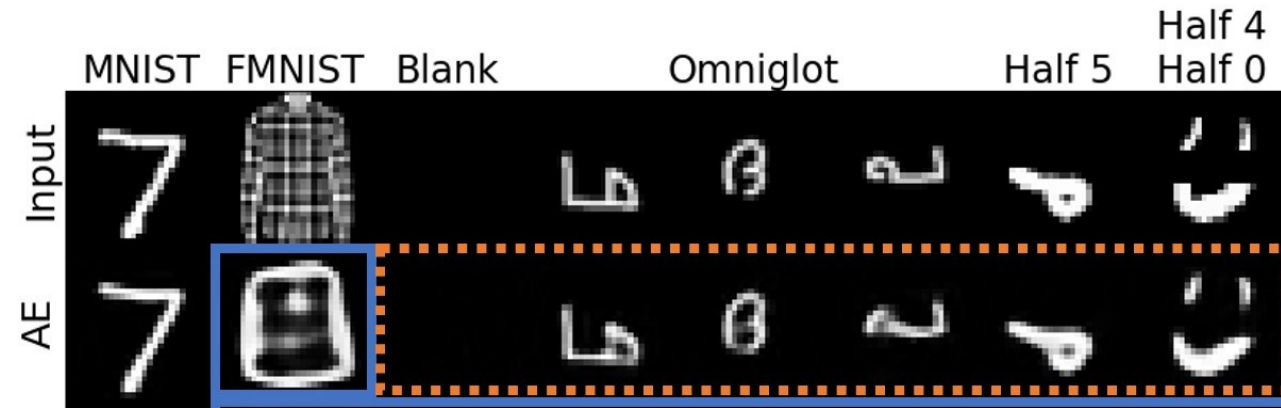
ANOMALY DETECTION USING AUTOENCODERS – JET EXAMPLE

- Need to check signal contamination during training
- Expectation: at ~ 0.5 this should become random
- Outcome: even for training on top only, top jets are reconstructed worse



ANOMALY DETECTION USING AUTOENCODERS

- Train an autoencoder on MNIST data
- Check the reconstruction of outliers
 - Generalization beyond the original data manifold
- Solution: Autoencoding under normalization constraints [2105.05735](#)



[2105.05735](#)

NORMALIZED AUTOENCODER

- Energy based model

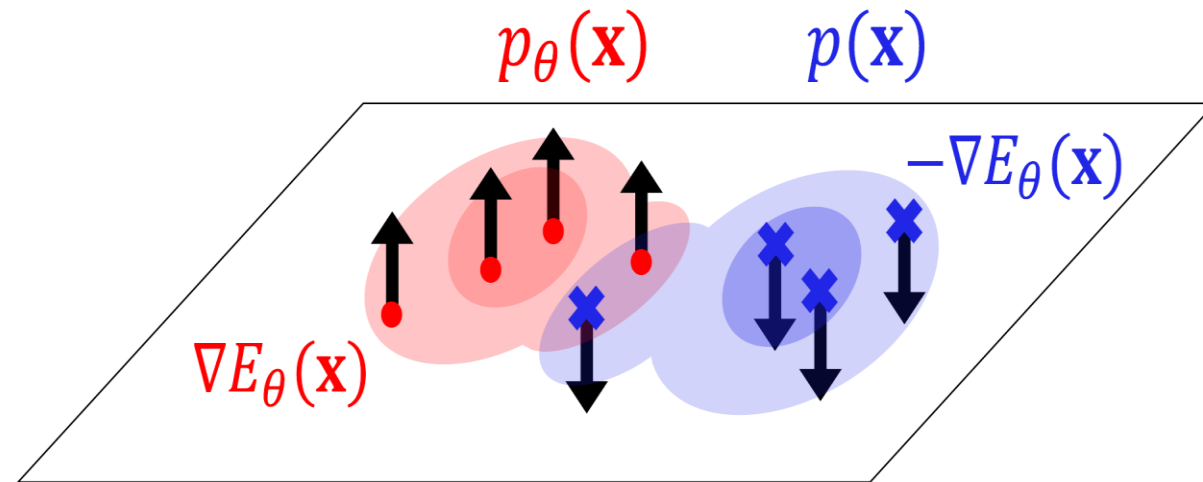
$$p_{\theta}(x) = \frac{1}{\Omega_{\theta}} \exp\left(-\frac{E_{\theta}(x)}{T}\right)$$

- Normalization constraint

$$\Omega_{\theta} = \int \exp\left(-\frac{E_{\theta}(x)}{T}\right) dx$$

- Maximize $p_{\theta}(x)$:

$$\mathcal{L} = \underbrace{\mathbb{E}_{x \sim p(x)} \left[\frac{E_{\theta}(x)}{T} \right]}_{\text{positive energy}} - \underbrace{\mathbb{E}_{x \sim p_{\theta}(x)} \left[\frac{E_{\theta}(x)}{T} \right]}_{\text{negative energy}}$$



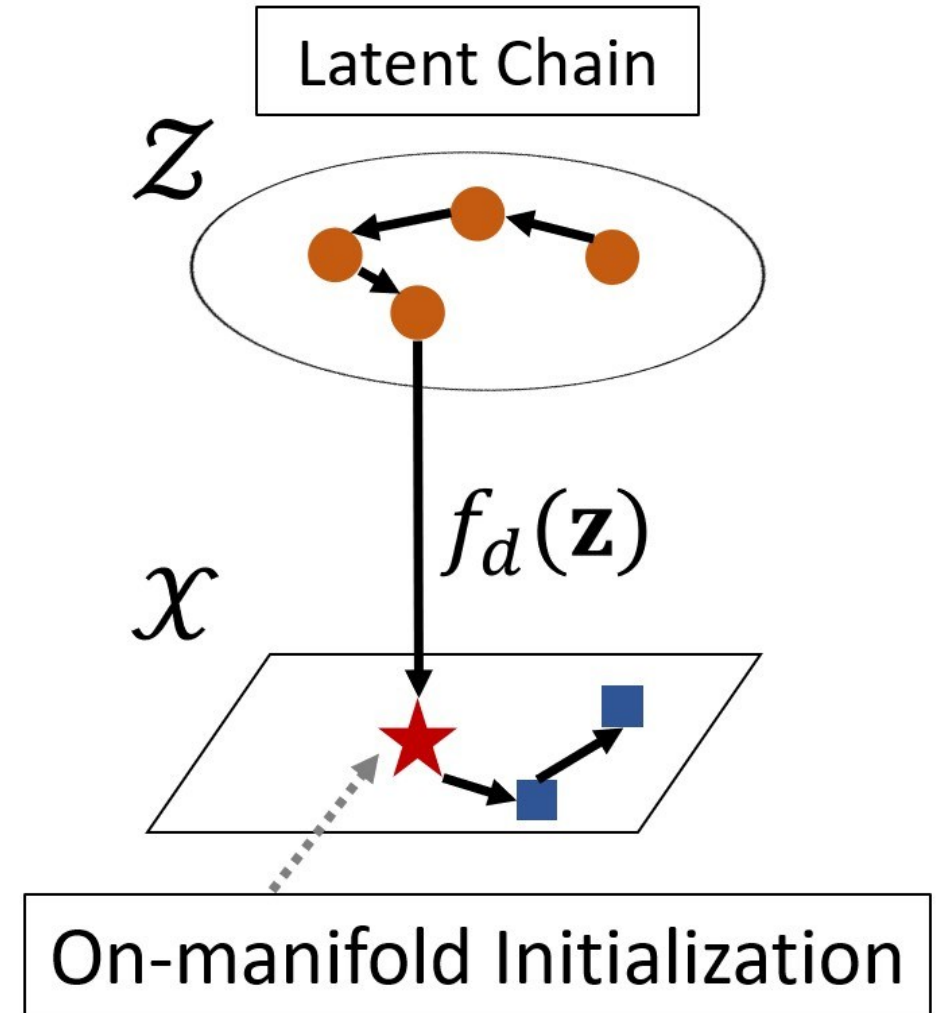
NORMALIZED AUTOENCODER SAMPLING FROM THE MODEL

- Energy defined as reconstruction error
- Negative samples obtained using Langevin Monte Carlo

$$x_{t+1} = x_t + \lambda_x \nabla_x \log(p_\theta(x_t)) + \sigma_x \epsilon_t$$

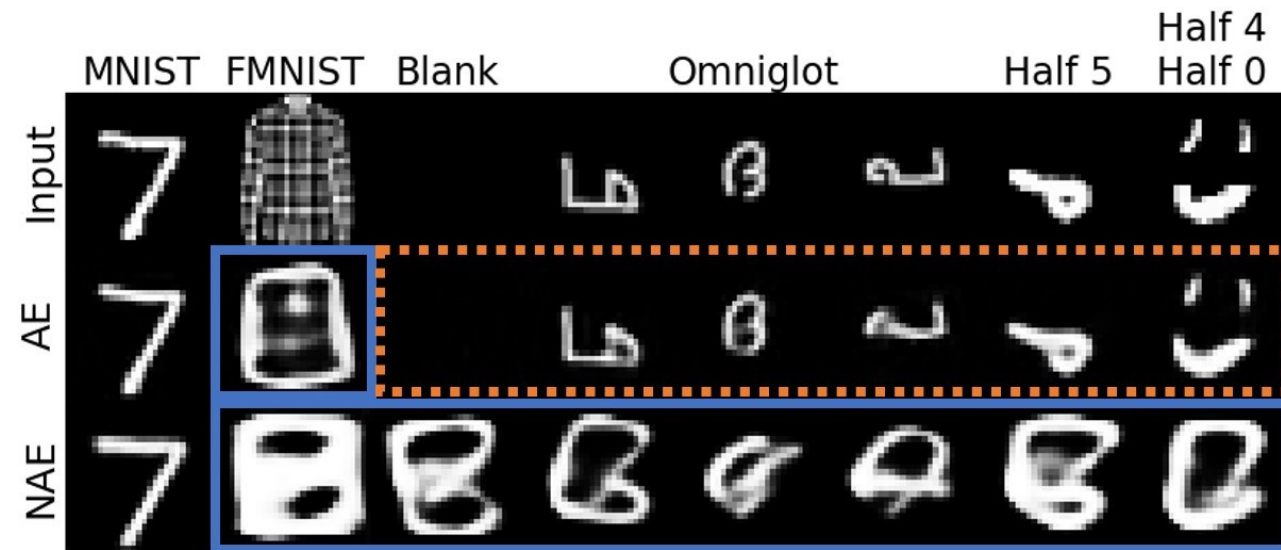
- Use on-manifold initialization (OMI) using the decoder of the autoencoder
 - Introduces second MCMC in the latent space

$$q_\theta(z) = \frac{1}{\Psi_\theta} \exp\left(-\frac{H_\theta}{T_z}\right), H_\theta = E_\theta(D(z))$$



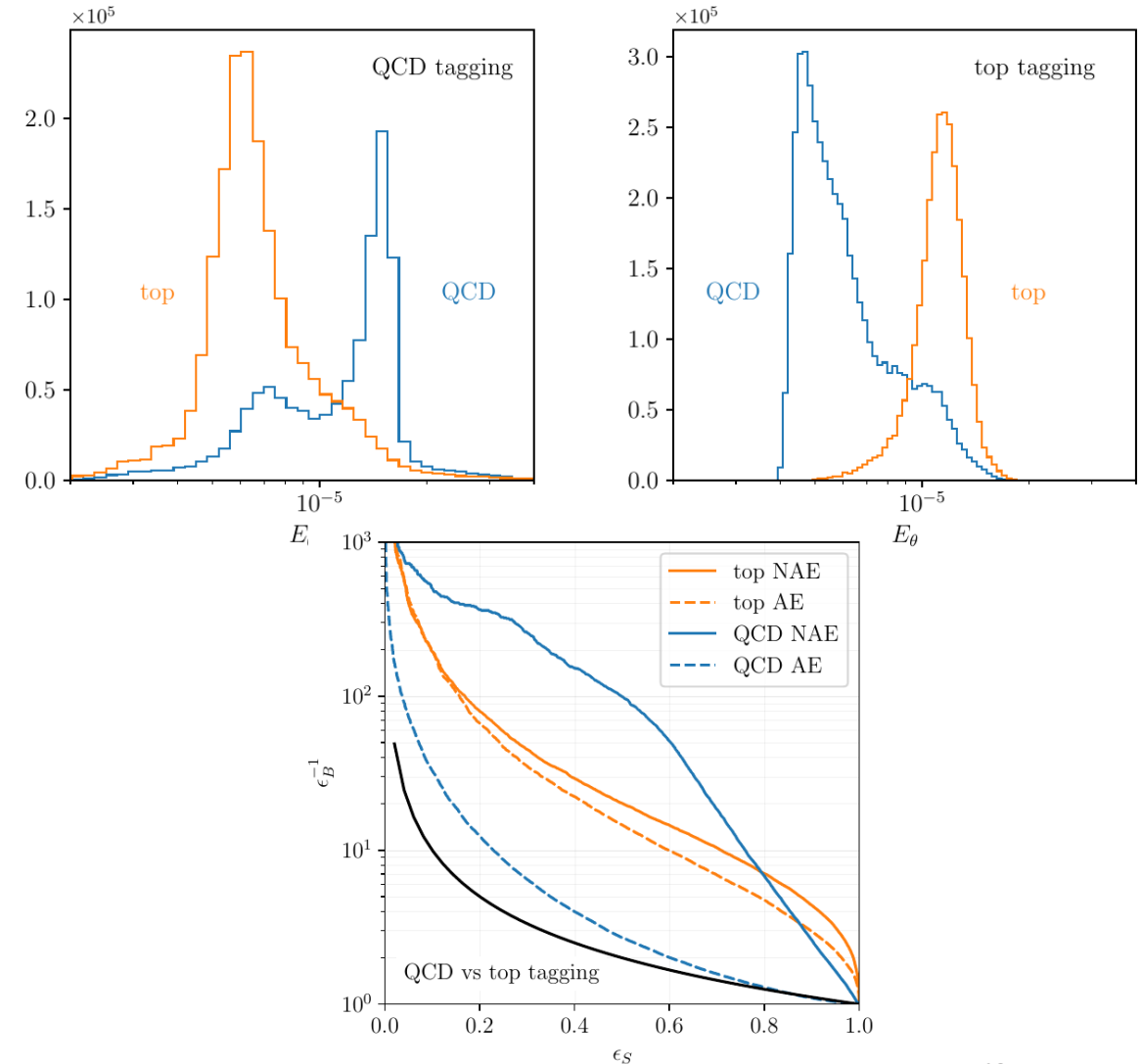
NORMALIZED AUTOENCODER RESULTS

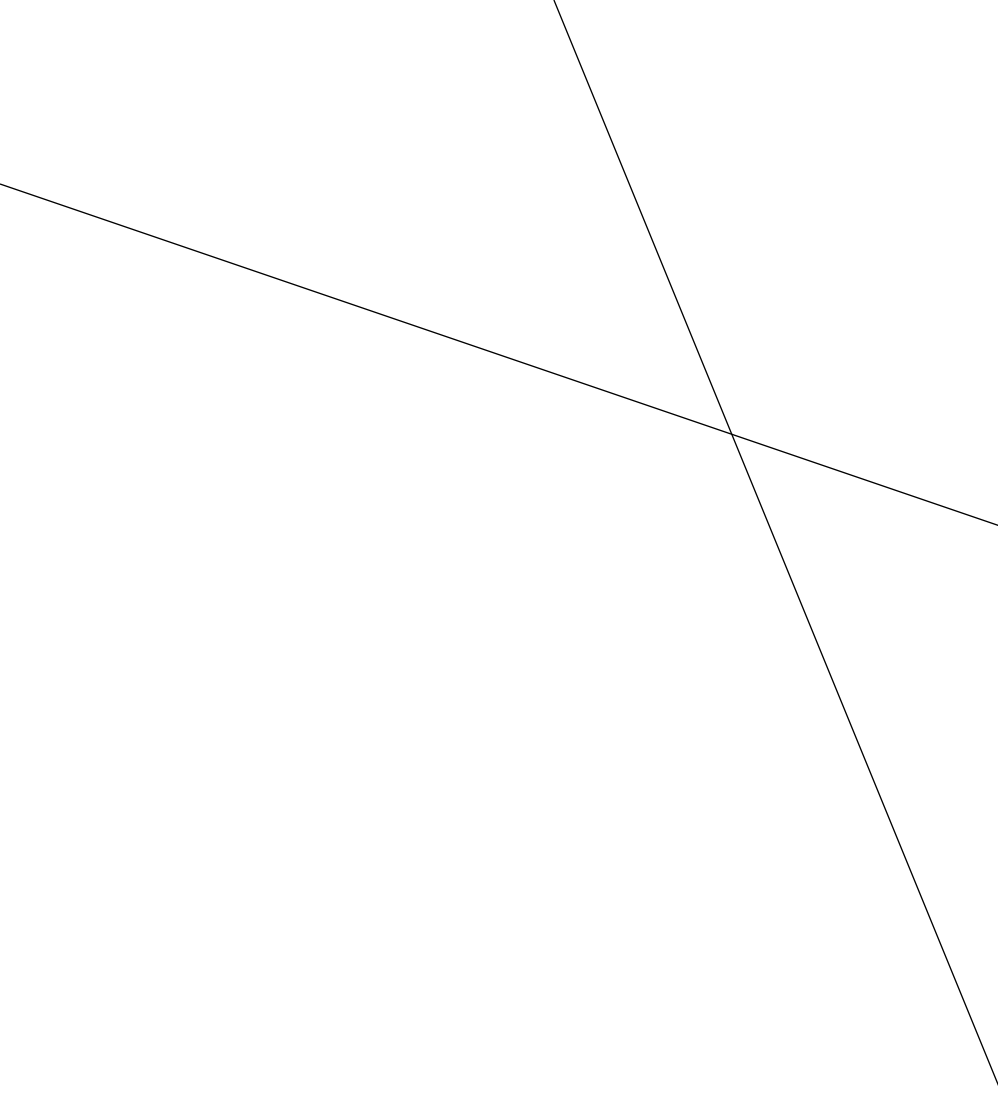
- Results on the MNIST Example from earlier:



NORMALIZED AUTOENCODER IN HEP

- Autoencoder for anomaly detection in HEP show similar issues
- Example QCD and top jets
- Normalized autoencoder shows promising results [2206.14255](#)



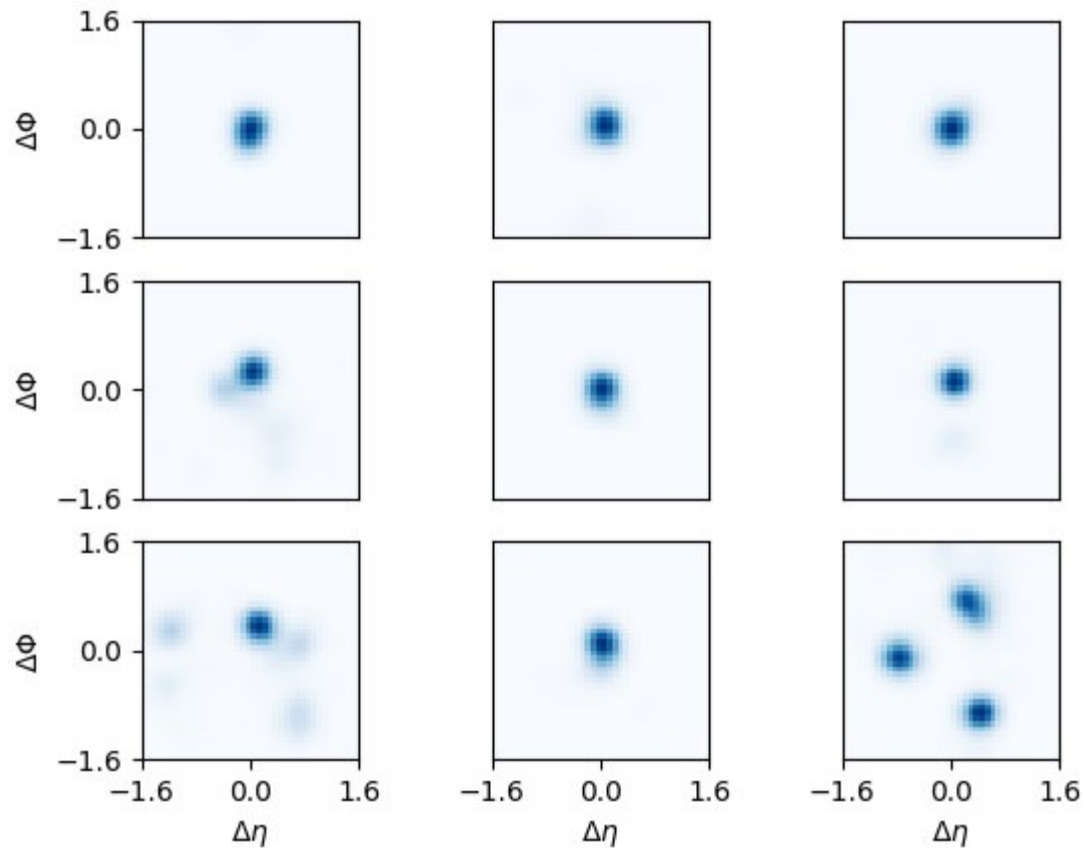


SUMMARY

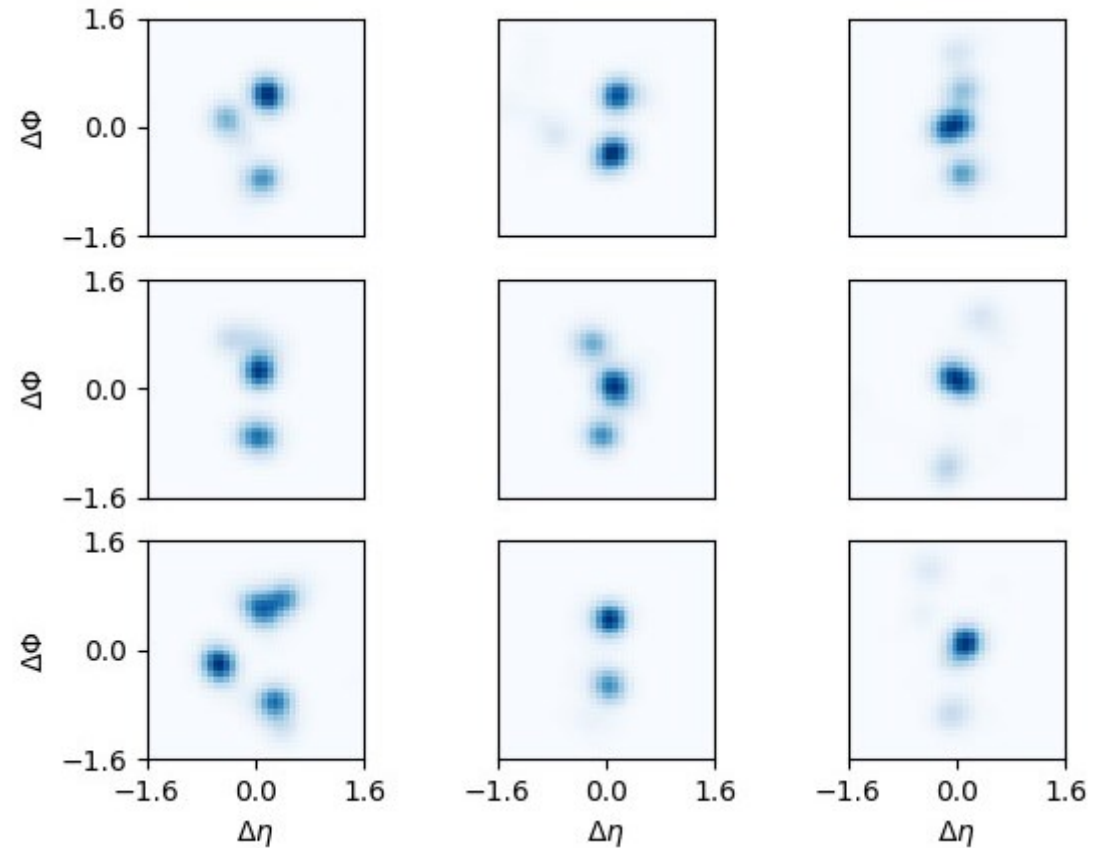
- Autoencoder provide an unsupervised learning algorithm
- Various applications: feature extraction, denoising, data generation, anomaly detection
- Anomaly detection with autoencoders is a difficult task because of generalization capabilities of regular autoencoder

ANOMALY DETECTION USING AUTOENCODERS – JET EXAMPLE

Light QCD jets

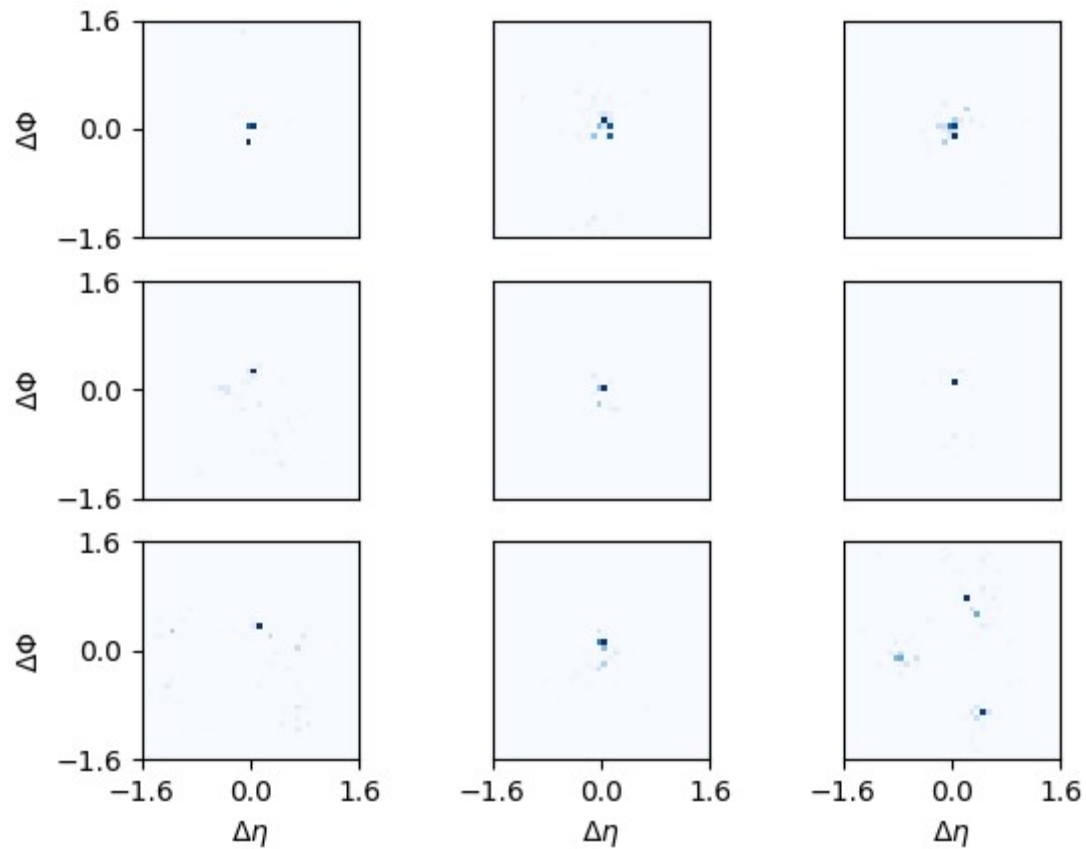


Top jets



ANOMALY DETECTION USING AUTOENCODERS – JET EXAMPLE

Light QCD jets



Top jets

