

Confidence Interval Estimation

Part II

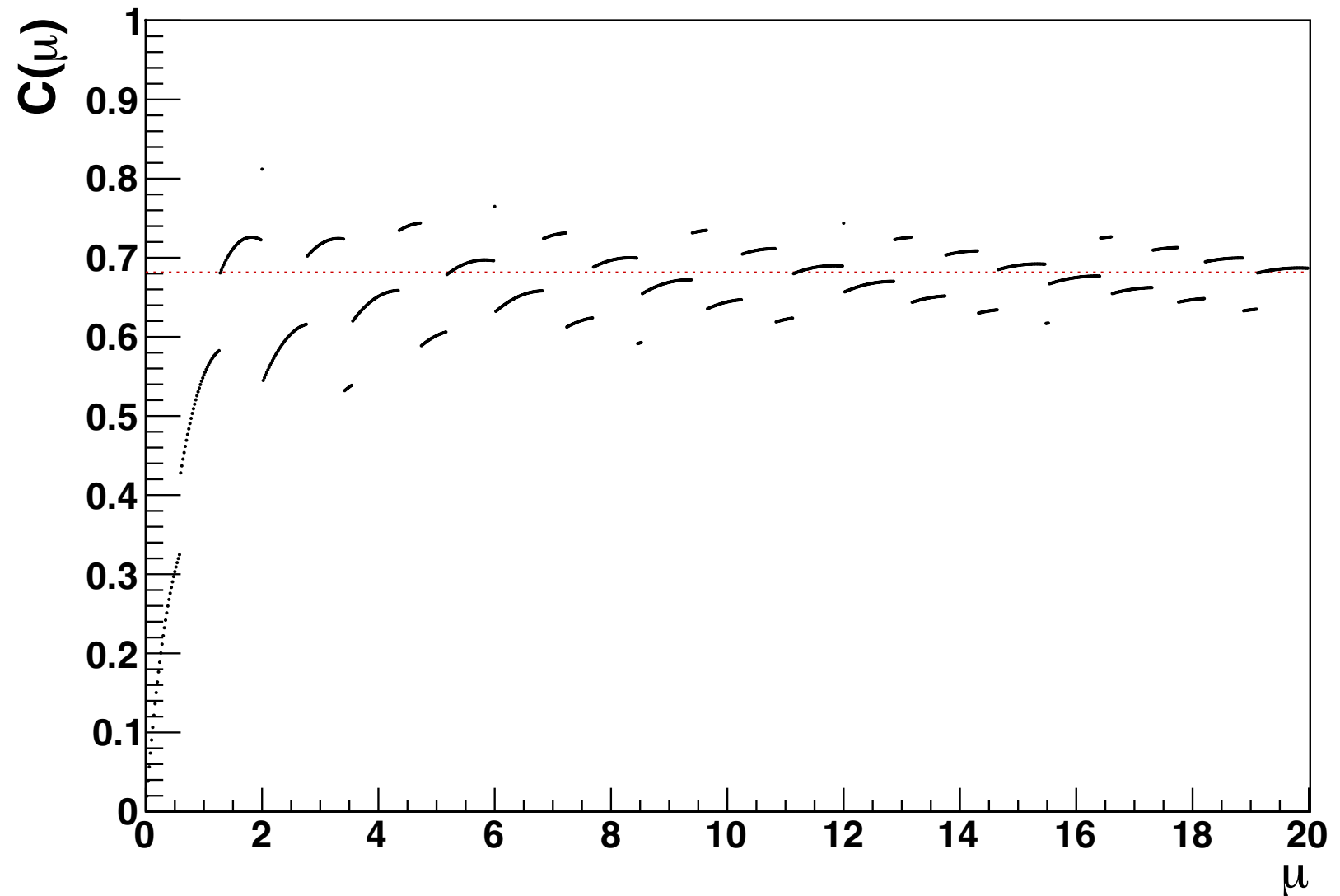
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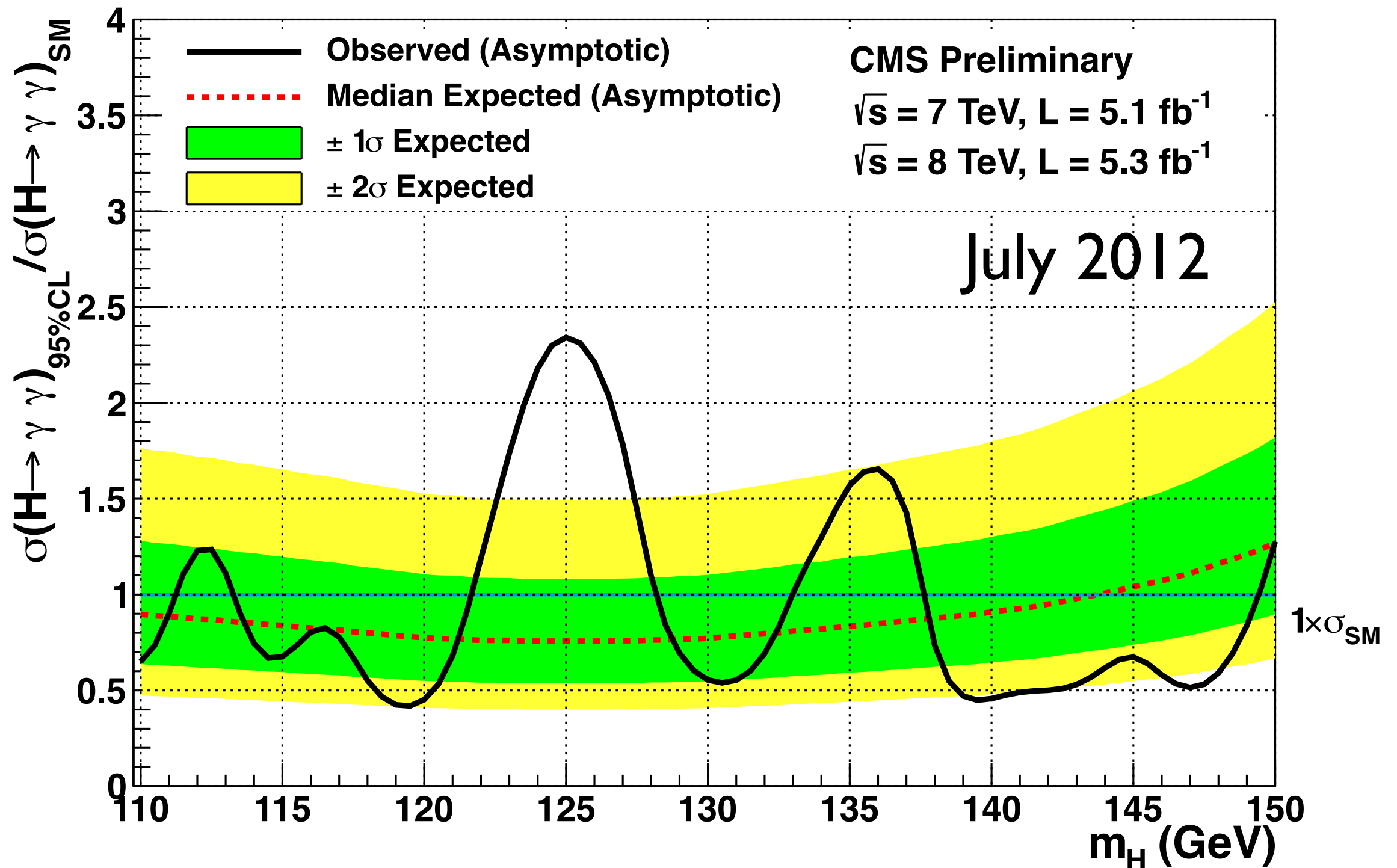
Poisson Distribution: Choice of $\sigma = \sqrt{n}$

- Best estimate of μ :
Observation n
- Calculate the
uncertainty as \sqrt{n} :
$$n - \sqrt{n} < \mu < n + \sqrt{n}$$
- Serious undercoverage



- minimum coverage is close to 0%

Confidence Intervals and Limits



Note: Upper limits are just one-sided confidence intervals at X% CL

Limits

- Difficulty of setting confidence intervals at physical boundaries (with constraints), for example:

cross section > 0

$\theta = x - y$ (for example $m^2 = E^2 - p^2$)

- Assume that we know $\hat{\theta} > 0$, the upper limit is:

$$\theta_{\text{up}} = \hat{\theta} + \sigma_{\hat{\theta}} \Phi^{-1}(1 - \beta) \quad \text{so for 95\% CL } \Phi^{-1}(0.95) = 1.65$$

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- Now consider the case where we measured $\hat{\theta} = -2$
and the resolution of our experiment is $\sigma_{\hat{\theta}} = 1$

We get:

$$\theta_{\text{up}} = -0.35 \text{ at 95\% CL and we did not learn anything!}$$

Note that from a frequentist' point of view, this is totally fine. If we performed the experiment a large number of times, we would end up with a meaningful physical bound. This does not change the fact, that we did not learn anything from our experiment at hand.

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fix the negative limit on x by adjusting x_{up} until it becomes positive:

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Results in a solution much better than the experimental resolution! BAD!

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3. Bayes Theorem

Can encode our prior knowledge in the prior $\pi(\theta)$!

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)} \quad \text{with} \quad P(B) = \sum_i P(B|A_i)P(A_i)$$

3. Bayes Theorem

$$p(\theta|\mathbf{d}) = \frac{L(\mathbf{d}|\theta)\pi(\theta)}{\int L(\mathbf{d}|\theta')\pi(\theta')d\theta'}$$

d... observed data

L... likelihood to observe the data

π... prior knowledge

p(θ|d)... estimator for θ (ML)

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Can now calculate an upper limit for given probability α :

$$\alpha = \int_{-\infty}^{\theta_{\text{up}}} p(\theta|\mathbf{d}) \quad \text{and} \quad \beta = \int_{\theta_{\text{down}}}^{\infty} p(\theta|\mathbf{d})$$

and encode the prior knowledge:
$$\pi(\theta) = \begin{cases} 1 & \theta \geq 0 \\ 0 & \theta < 0 \end{cases}$$

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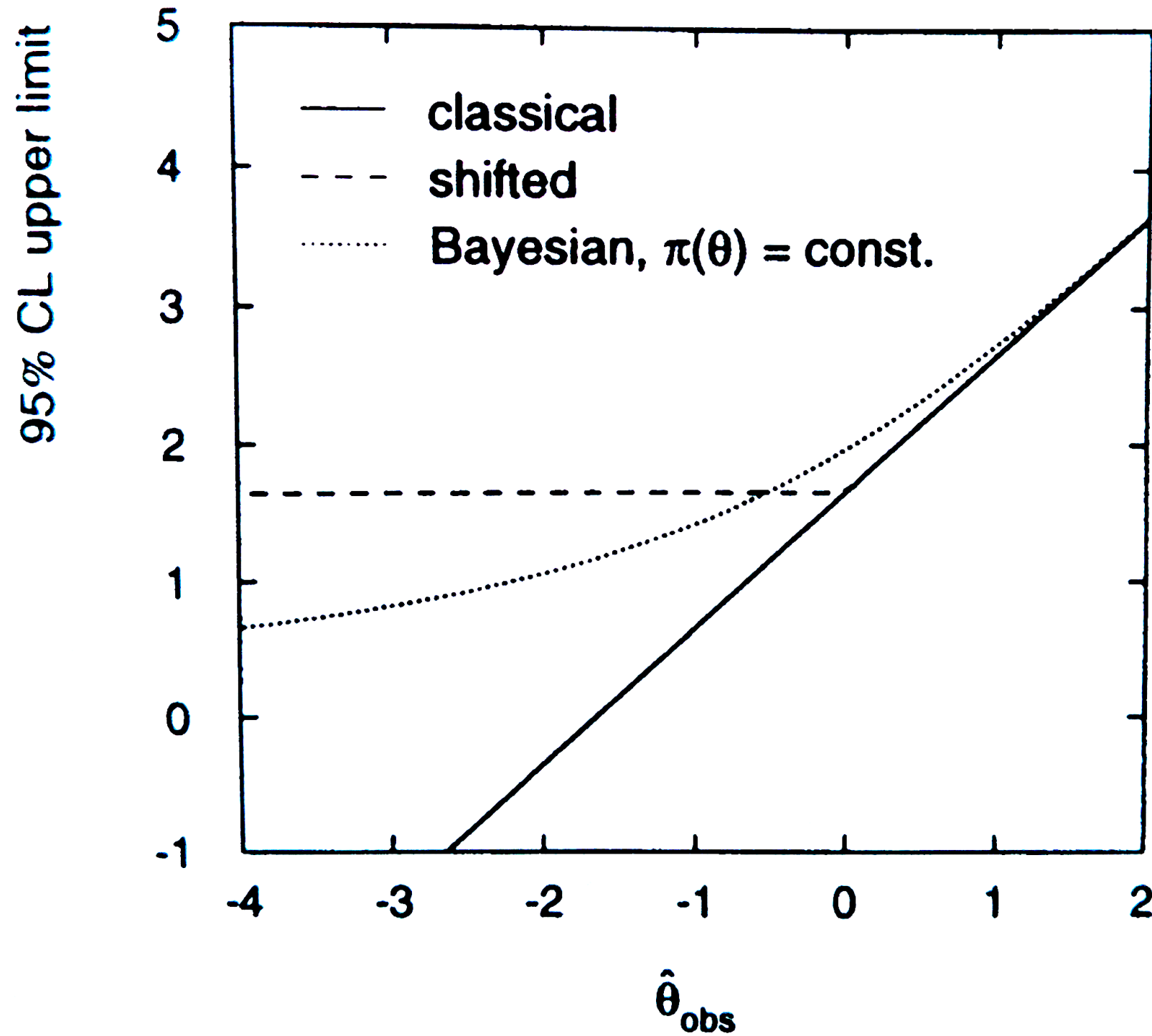
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We get:

$$1 - \beta = \frac{1}{N} \int_{-\infty}^{\theta_{\text{up}}} L(\mathbf{d}|\theta')\pi(\theta')d\theta' \quad \text{with} \quad N = \int_{-\infty}^{\infty} L(\mathbf{d}|\theta')\pi(\theta')d\theta'$$

solve numerically for θ_{up}

Possible Solutions



picture credit: G. Cowan

Poisson with Background

Realistic case: $n = n_s + n_b$

- ▶ Both, n_s and n_b are Poisson variables with means ν_s, ν_b
- ▶ Prob. function $f(n; \nu_s, \nu_b) = \frac{(\nu_s + \nu_b)^n}{n!} e^{-(\nu_s + \nu_b)}$

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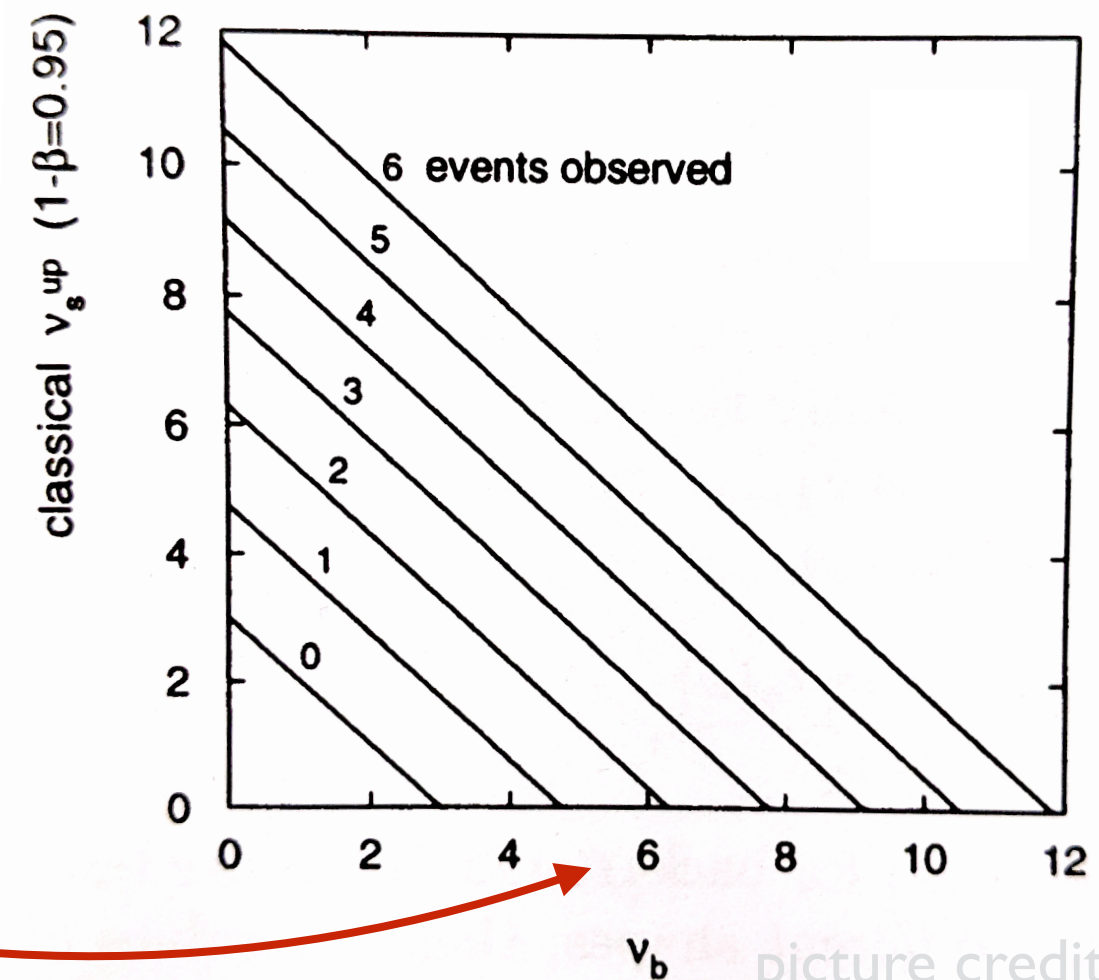
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- Upper limits:

$$\nu_s^{\text{up}} = \nu_s^{\text{up}}(\nu_b = 0) - \nu_b$$

No positive upper limit possible for small n and large ν_b



picture credit: G. Cowan

Poisson with Background

Possible solution: Bayesian method

- ▶ Write the likelihood function as a function of ν_s :

$$L(n_{\text{obs}}|\nu_s) = \frac{(\nu_s + \nu_b)^{n_{\text{obs}}}}{n_{\text{obs}}!} e^{-(\nu_s + \nu_b)}$$

- ▶ The posterior becomes

$$p(\nu_s|n_{\text{obs}}) = \frac{L(n_{\text{obs}}|\nu_s)\pi(\nu_s)}{\int L(n_{\text{obs}}|\nu'_s)\pi(\nu'_s)d\nu'_s}$$

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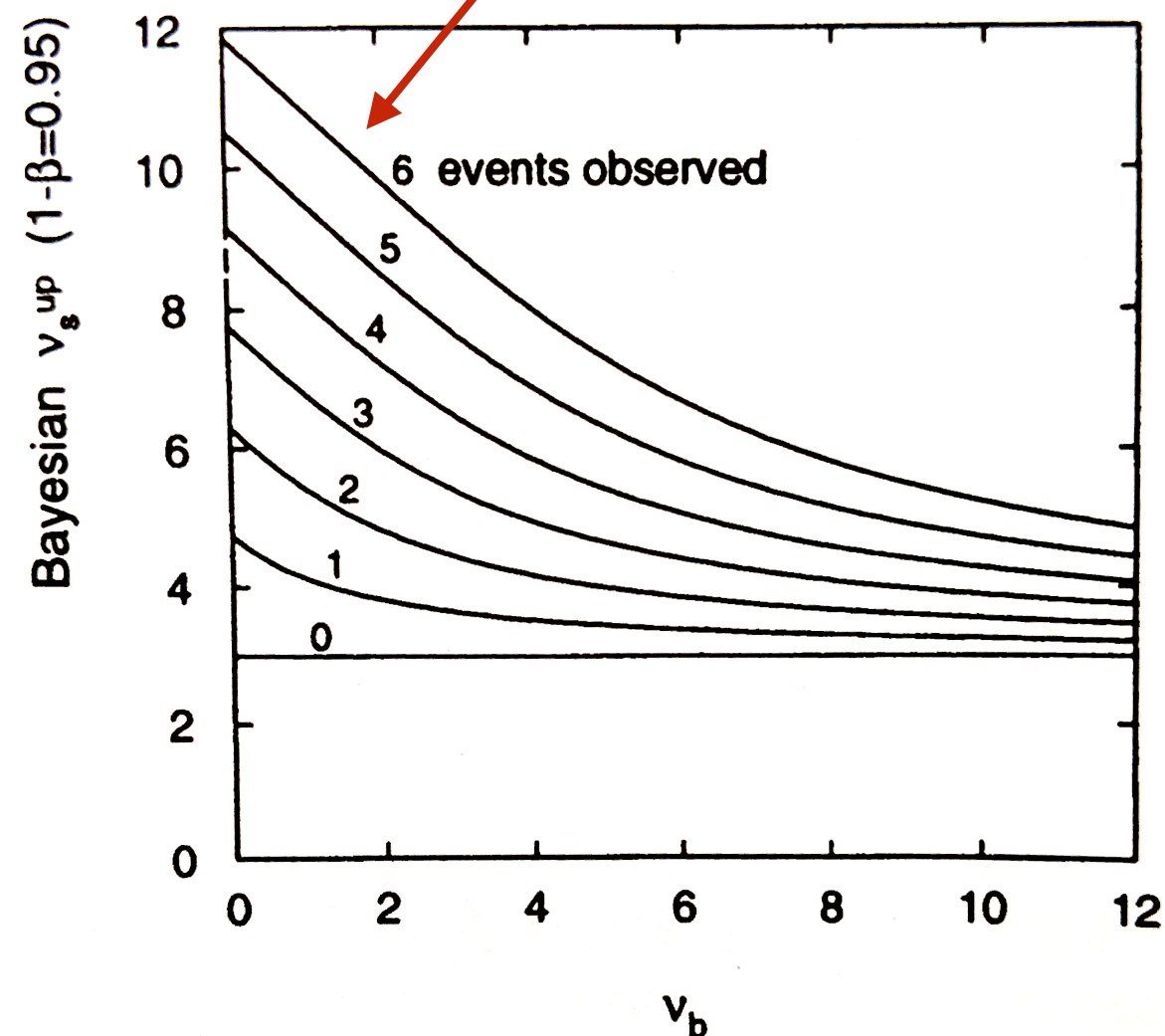
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- Integrate to get an upper limit at a given CL $1-\beta$:

$$\beta = \frac{e^{-(\nu_s^{\text{up}} + \nu_b)} \sum_{n=0}^{n_{\text{obs}}} \frac{1}{n!} (\nu_s^{\text{up}} + \nu_b)^n}{e^{-\nu_b} \sum_{n=0}^{n_{\text{obs}}} \frac{1}{n!} \nu_b^n}$$

(solve numerically for ν_s^{up})

Agreement with previous case (small ν_b)



CLs Method

- Incorporate knowledge about what is signal and background
- Define “test statistic” Q (function of observables and parameters) which “ranks” experiments from the least to most “signal-like”
- Likelihood ratios for **signal** and **background** hypotheses are used as the test statistic:

$$Q = \frac{\mathcal{L}(N_{data}, N_S + N_B)}{\mathcal{L}(N_{data}, N_B)}$$

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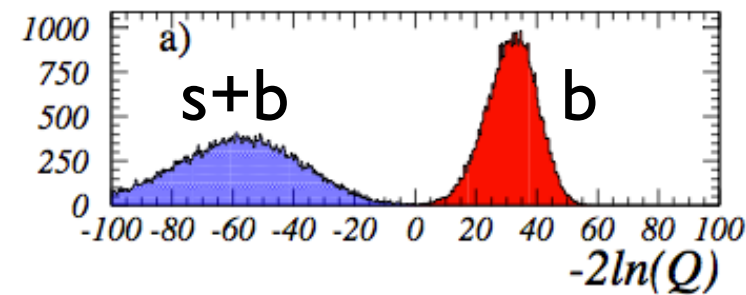
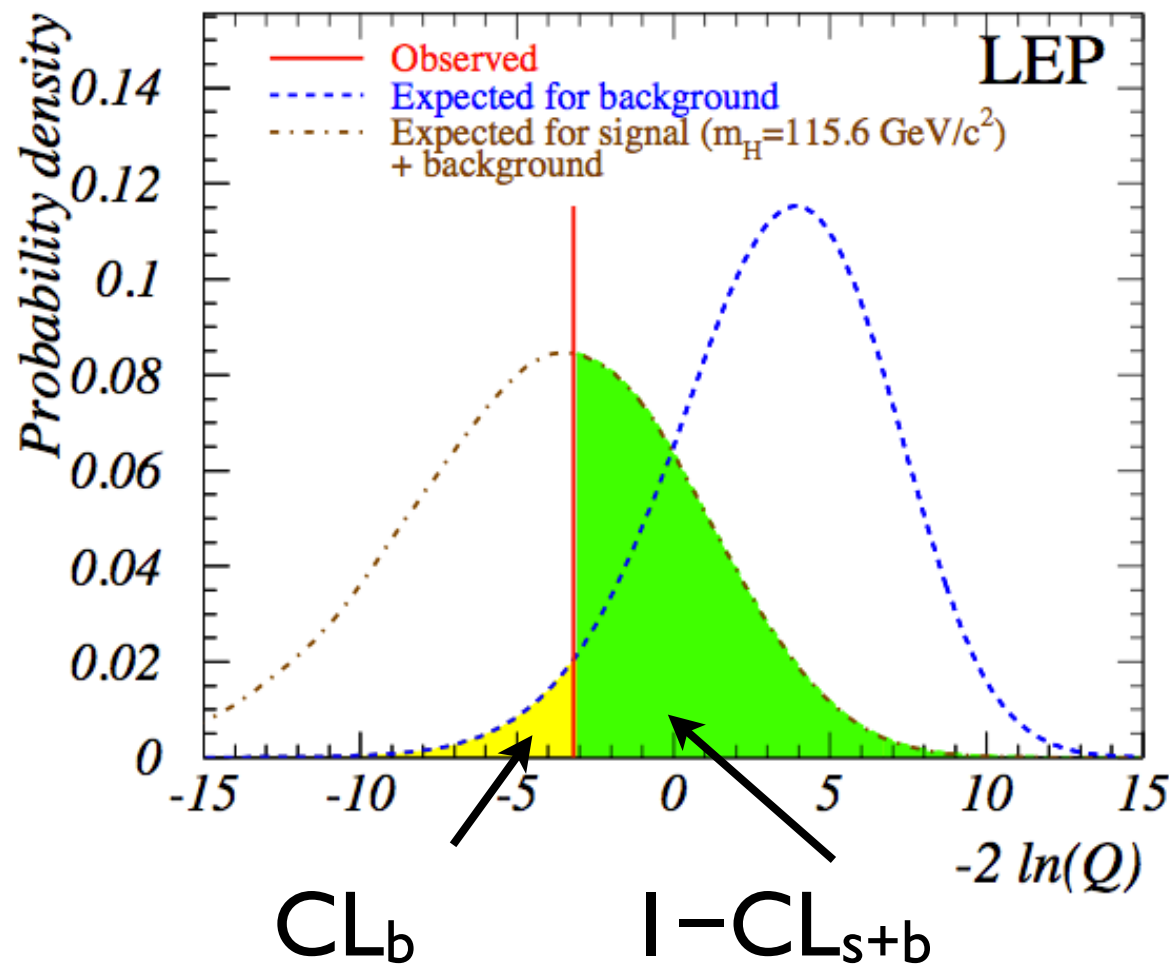
- Confidence in **signal+background** hypothesis $CL_{s+b} = P_{s+b}(Q \leq Q_{obs})$ where

$$P_{s+b}(Q \leq Q_{obs}) = \int_{-\infty}^{Q_{obs}} \frac{dP_{s+b}}{dQ} dQ$$

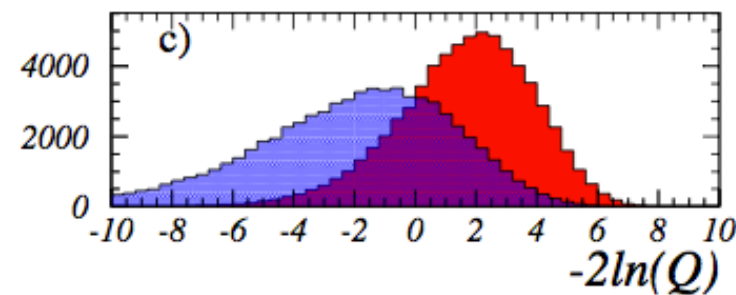
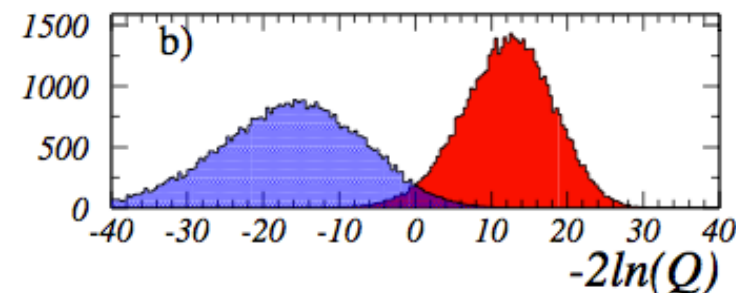
- and dP_{s+b}/dQ is the p.d.f. of Q for the S+B hypothesis
- Confidence in **background**-only hypothesis: $CL_b = P_b(Q \leq Q_{obs})$

- and analogues: $P_b(Q \leq Q_{obs}) = \int_{-\infty}^{Q_{obs}} \frac{dP_b}{dQ} dQ$

CLs Method



good sensitivity

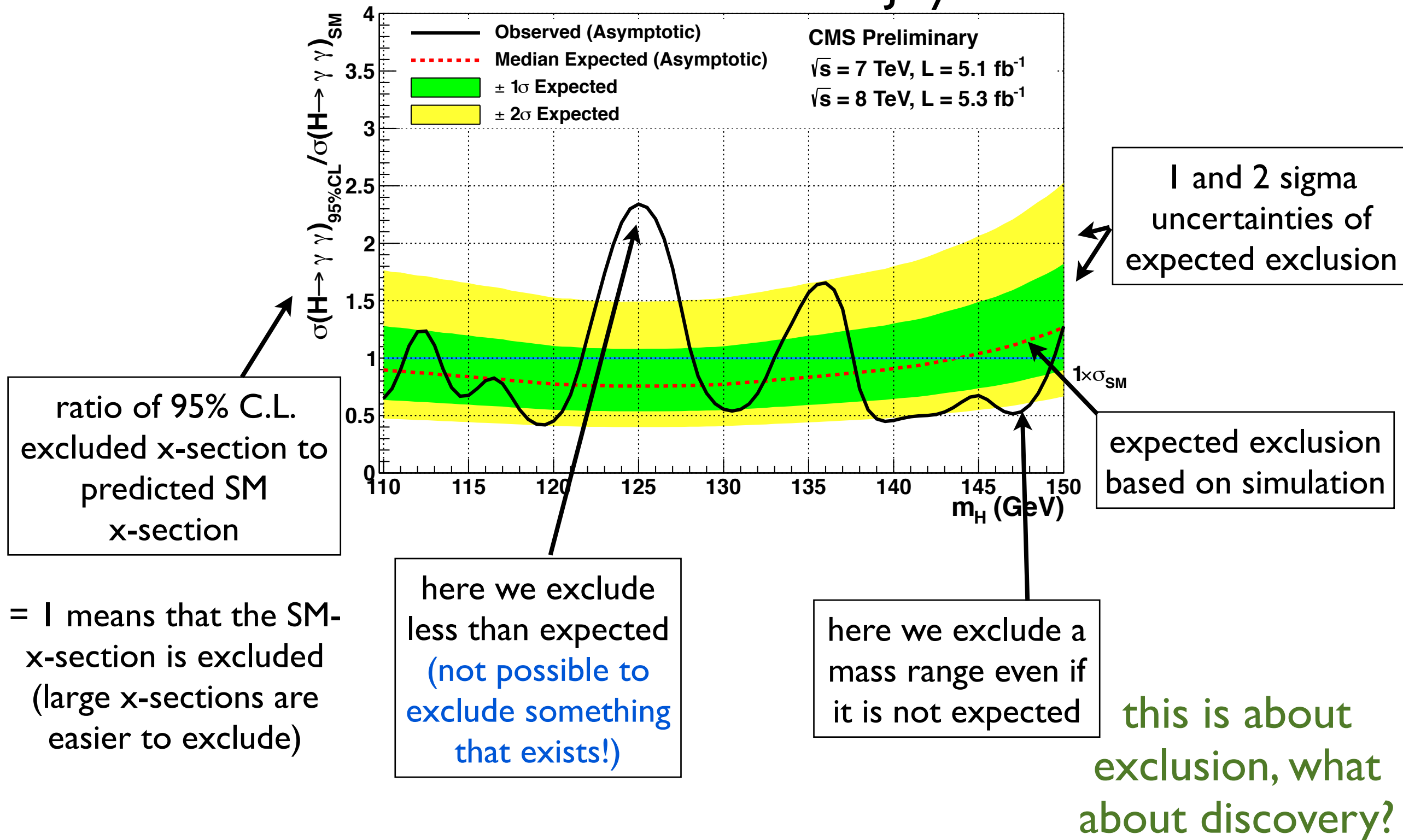


bad sensitivity

- The problem of unphysical results in case of small signals in the presence of background is avoided by normalising the S+B hypothesis to the B-only hypothesis: $CL_s = \frac{CL_{s+b}}{CL_b}$
- Tries to approximate the confidence in the S-hypothesis in the absence of background

Excluding (or Discovering) the Higgs Boson

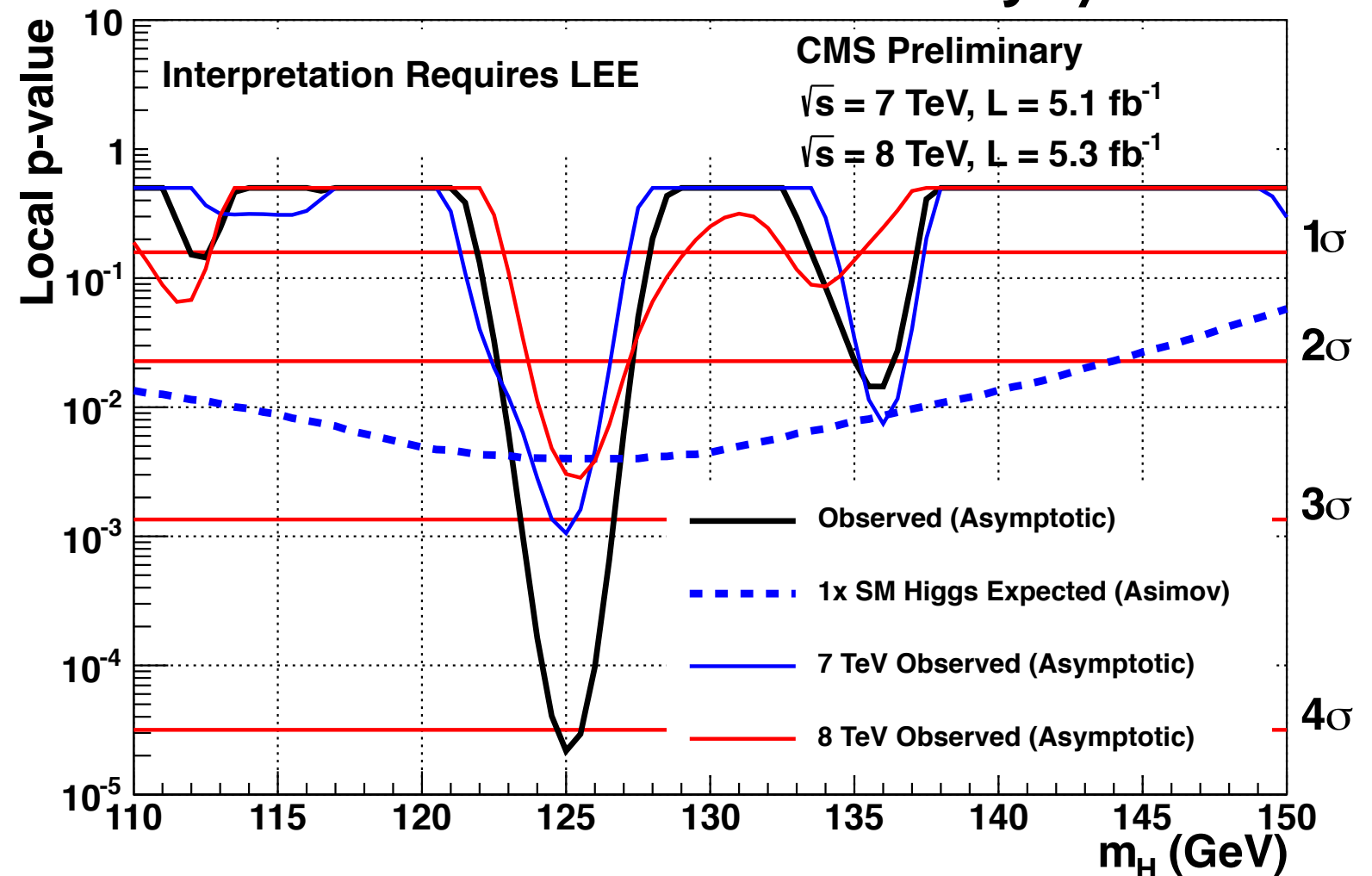
July 2012



Discovering the Higgs Boson

July 2012

- Repeat many toy experiments and calculate the **probability that the observed excess is a statistical fluctuation**
- As a function of the mass
- 3 sigma excesses (called evidence) **often disappeared**, even though the probability of statistical fluctuation was small....



- 5 sigma excesses are called “discovery”