

Current and upcoming challenges for data packaging of DECTRIS X-ray detectors

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Performance stats



Frame rate (cont.): 560 Hz
Image size: 16.77 Mpixel (w/o gaps)
Data rate in: 160 Gbps
Data rate out Filewriter (max): ~35 Gbps
Data rate out Stream (max) : ~75 Gbps

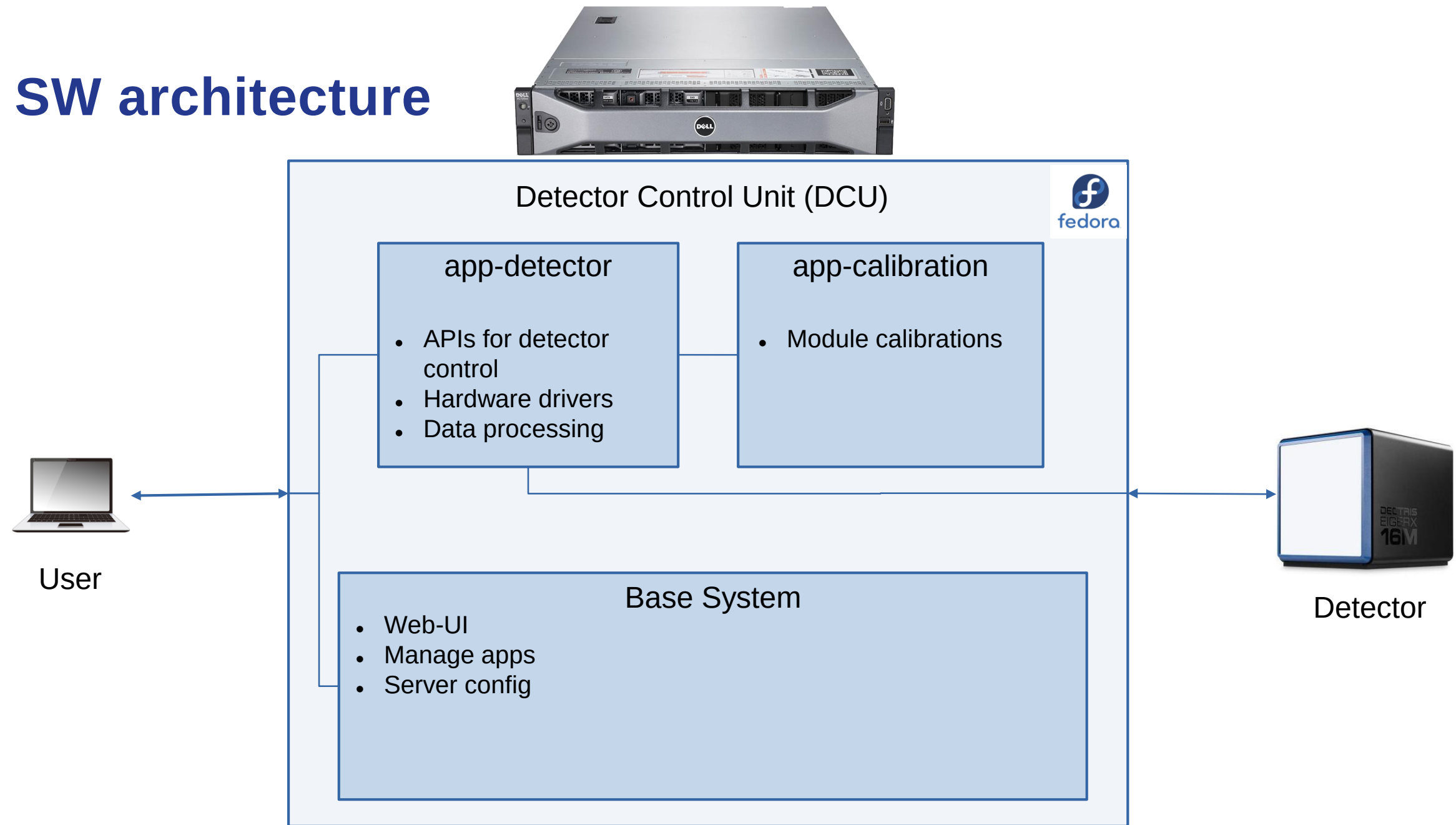
EIGER2 XE 16M

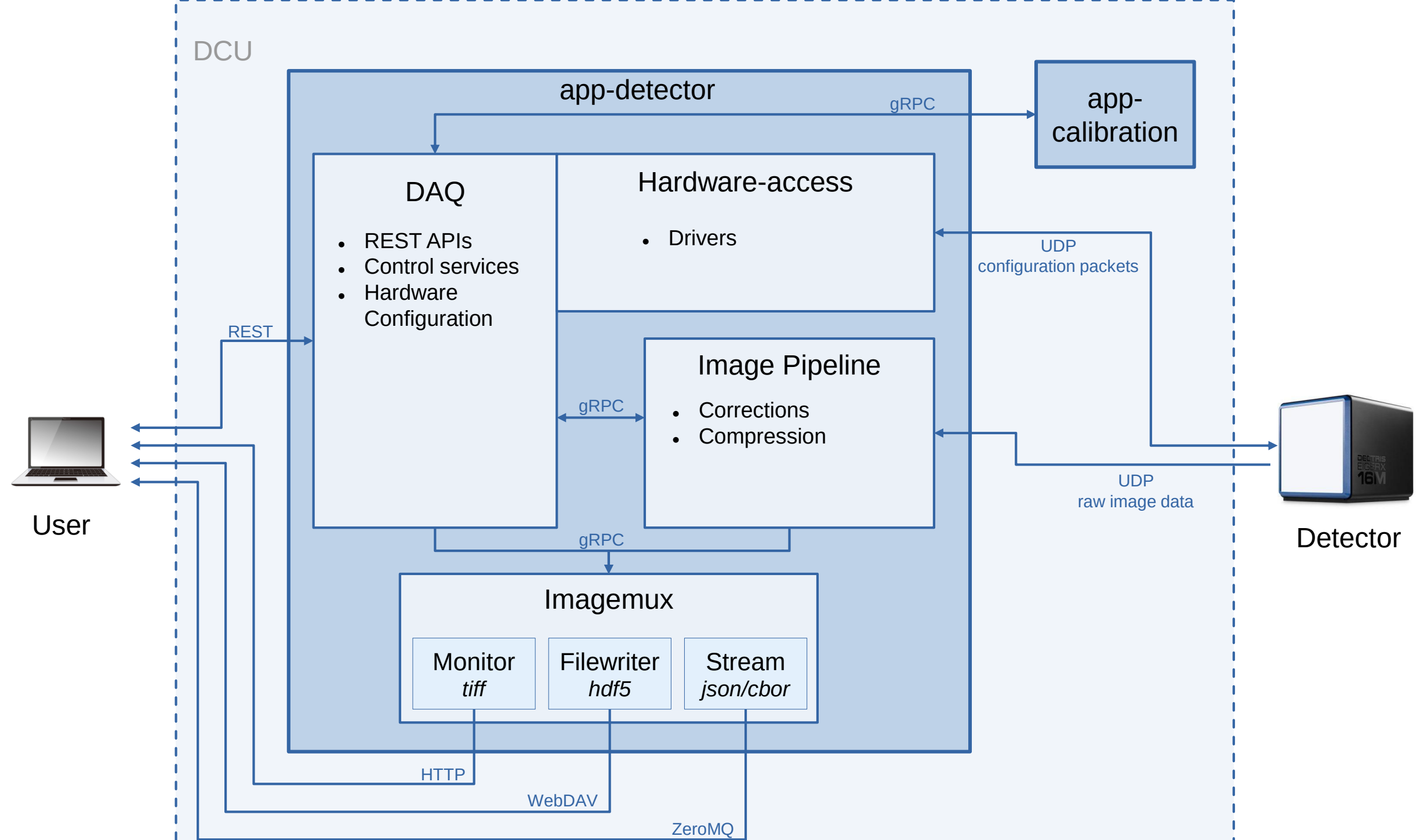


Frame rate (cont.): 120 kHz
Image size: 31 kpixel (w/o gaps)
Data rate in: 10 Gbps
Data rate out (max): 10 Gbps

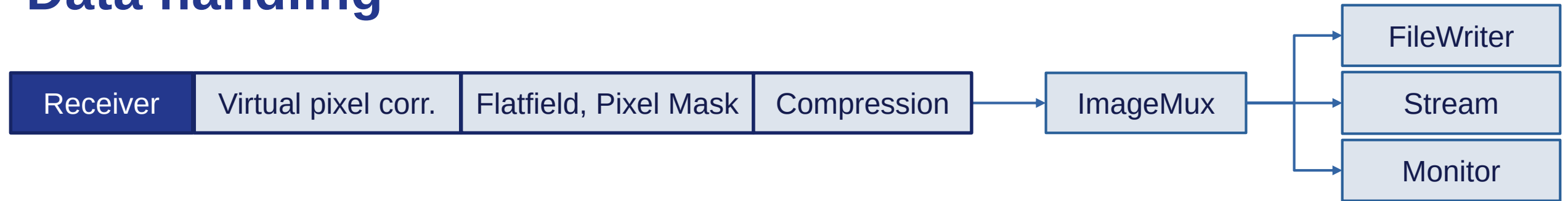
ARINA

SW architecture





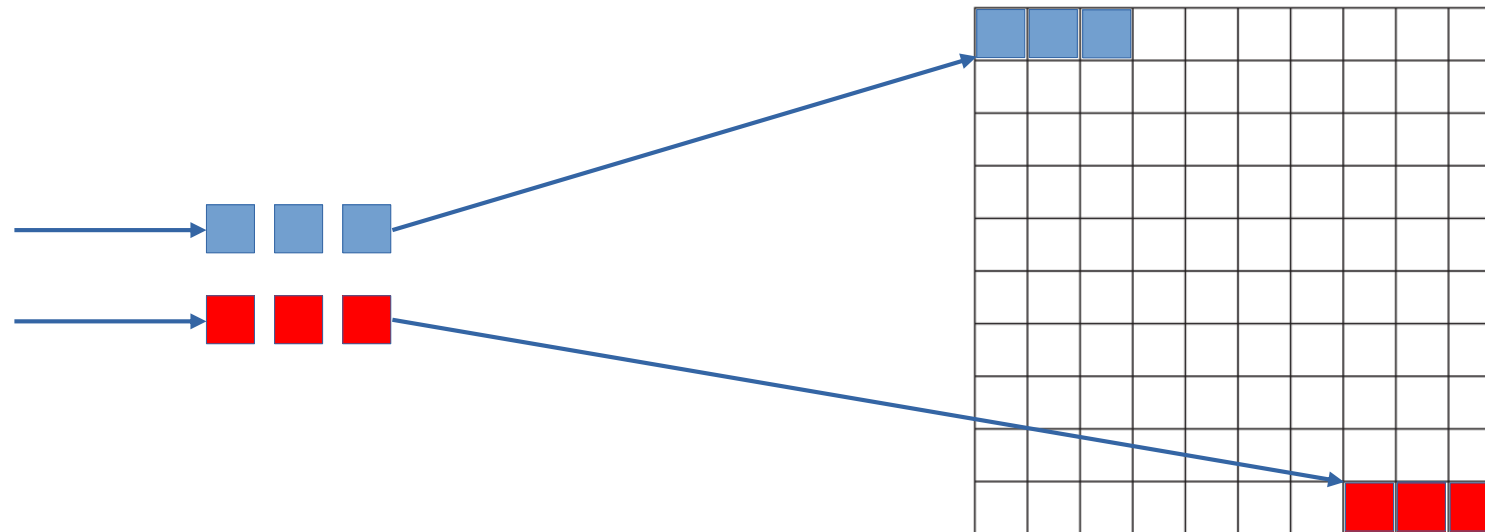
Data handling



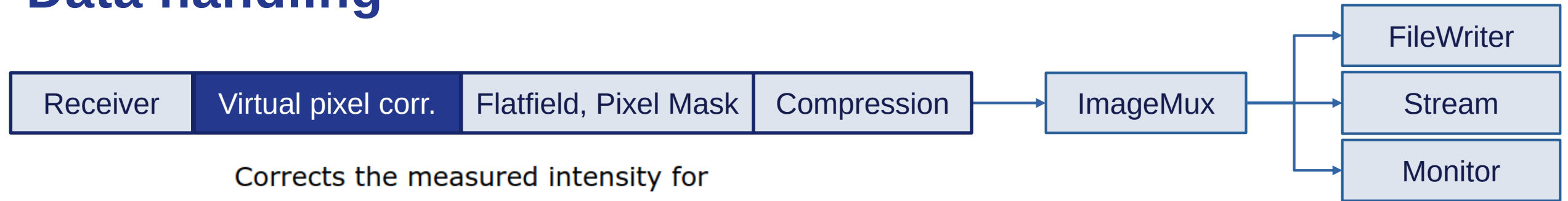
Modules
send UDP packets
with pixel intensities

Pixels values get:

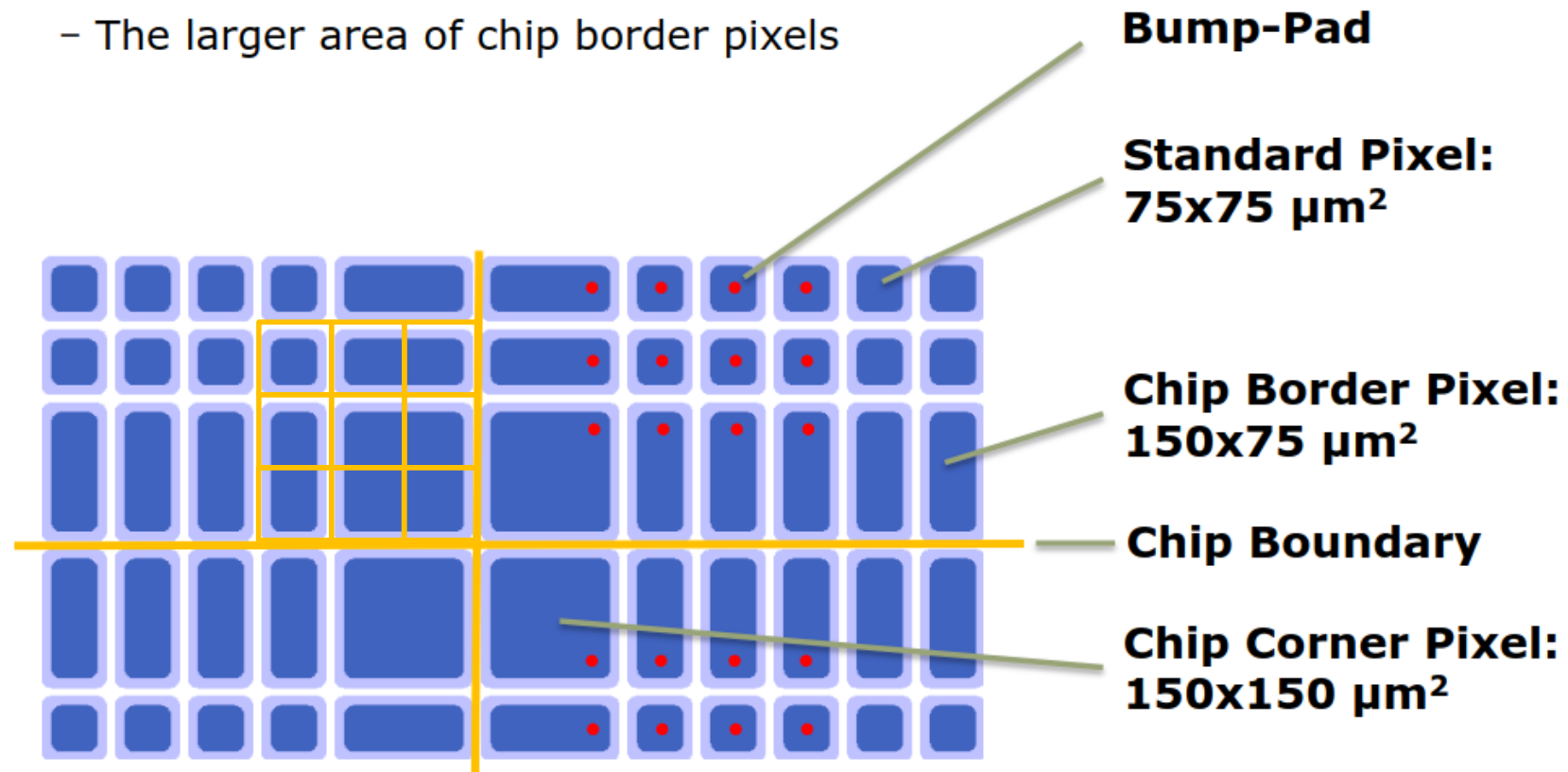
1. countrate corrected *[if correction enabled]*
2. placed at the final position in image
3. summed *[if auto_summation is enabled]*



Data handling



Corrects the measured intensity for
– The larger area of chip border pixels



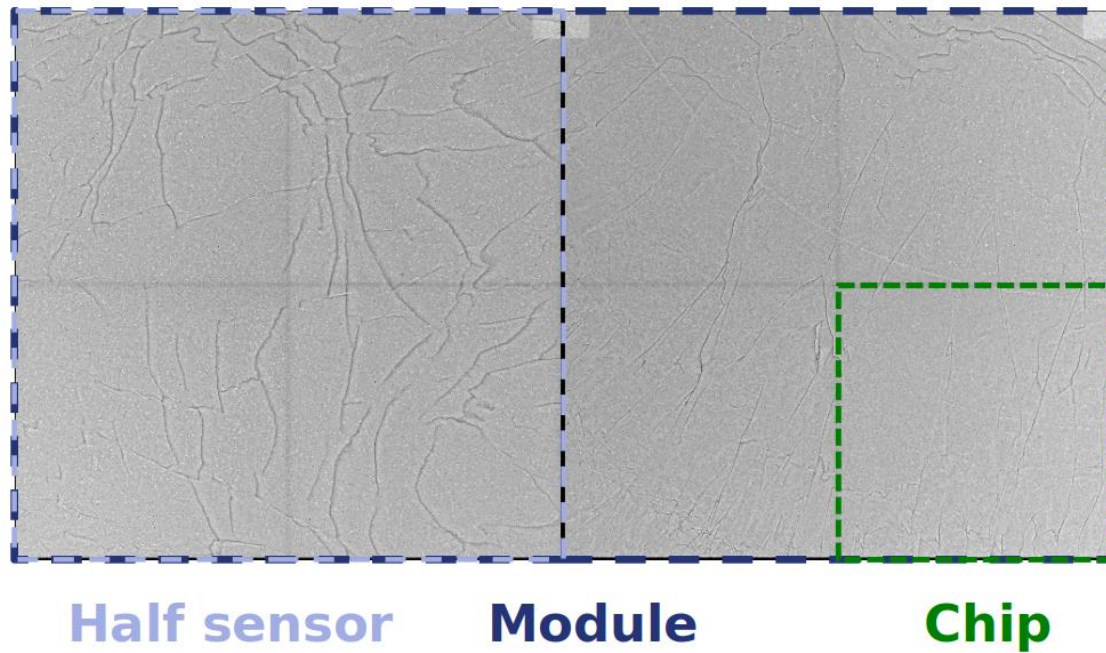
Sensor layout

Data handling

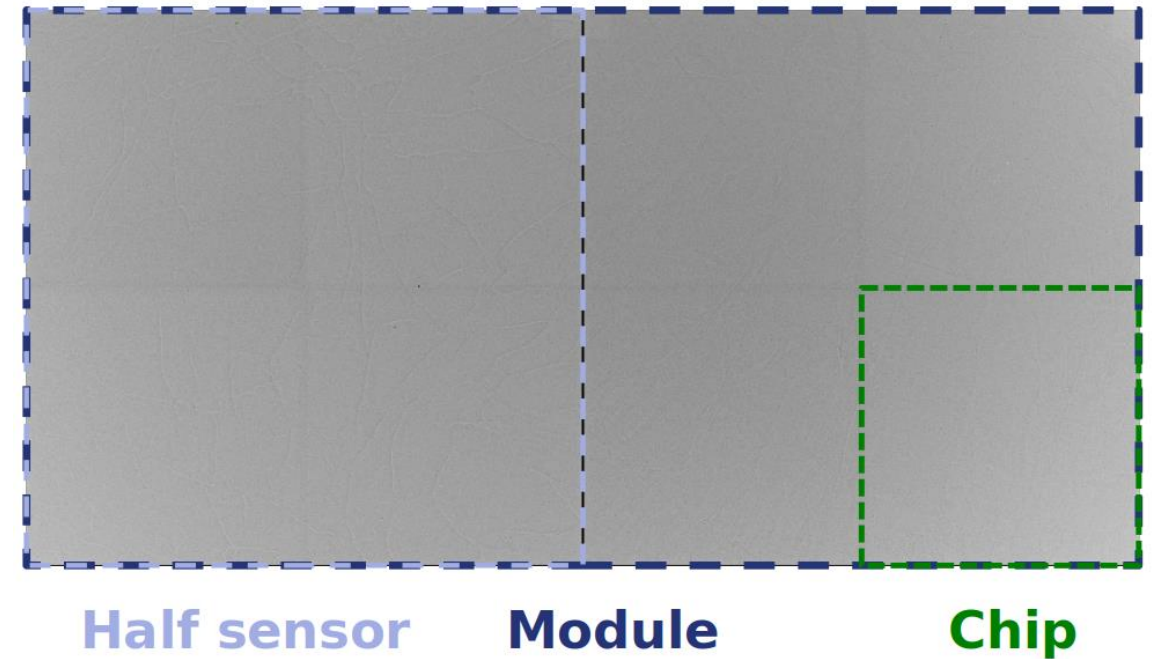


Single module image (example: CdTe)

Without flatfield



With flatfield

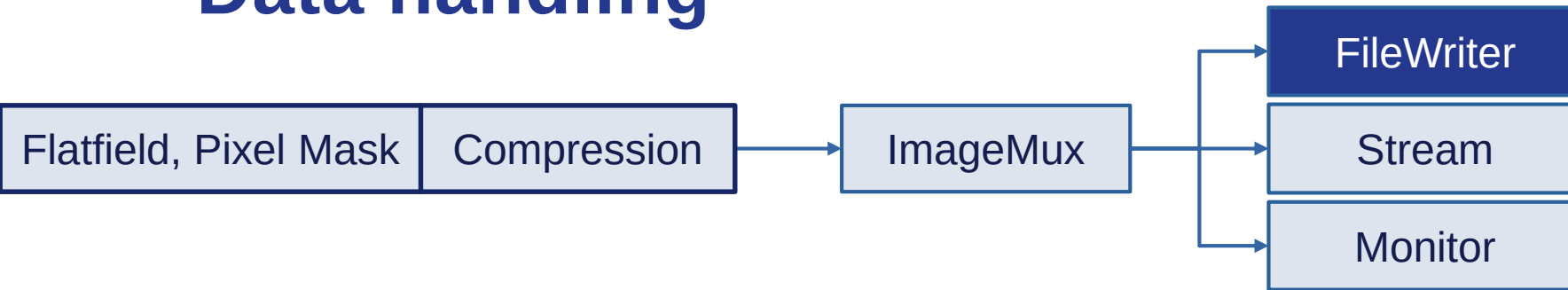


Data handling



- Finally the images are compressed with either “bitshuffle lz4” or “lz4”.
- Afterwards they are available in “imagemux” which provides customer facing interfaces:
 - Monitor
 - Filewriter
 - Stream

Data handling



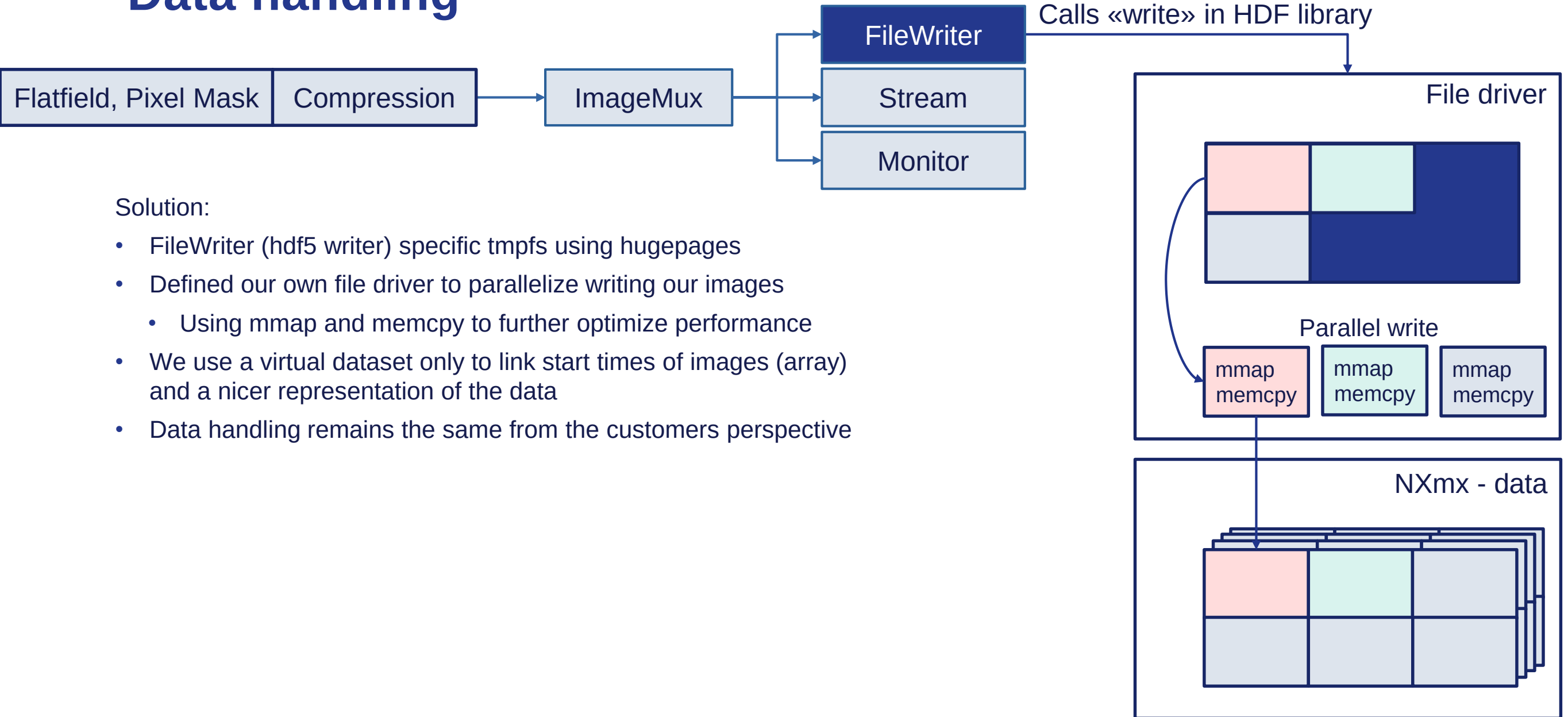
Start situation:

- Image pipeline max load ~ 75 Gbps compressed data
- Realistic compression average ~25% -> ~ 40 Gbps with current detectors
- Data always stays in RAM
- Standard HDF writer not fast enough

Issues:

- Virtual dataset not being used optimally due to downside in post-processing (more performance required)
- No possibility to parallelize writing into single data file

Data handling

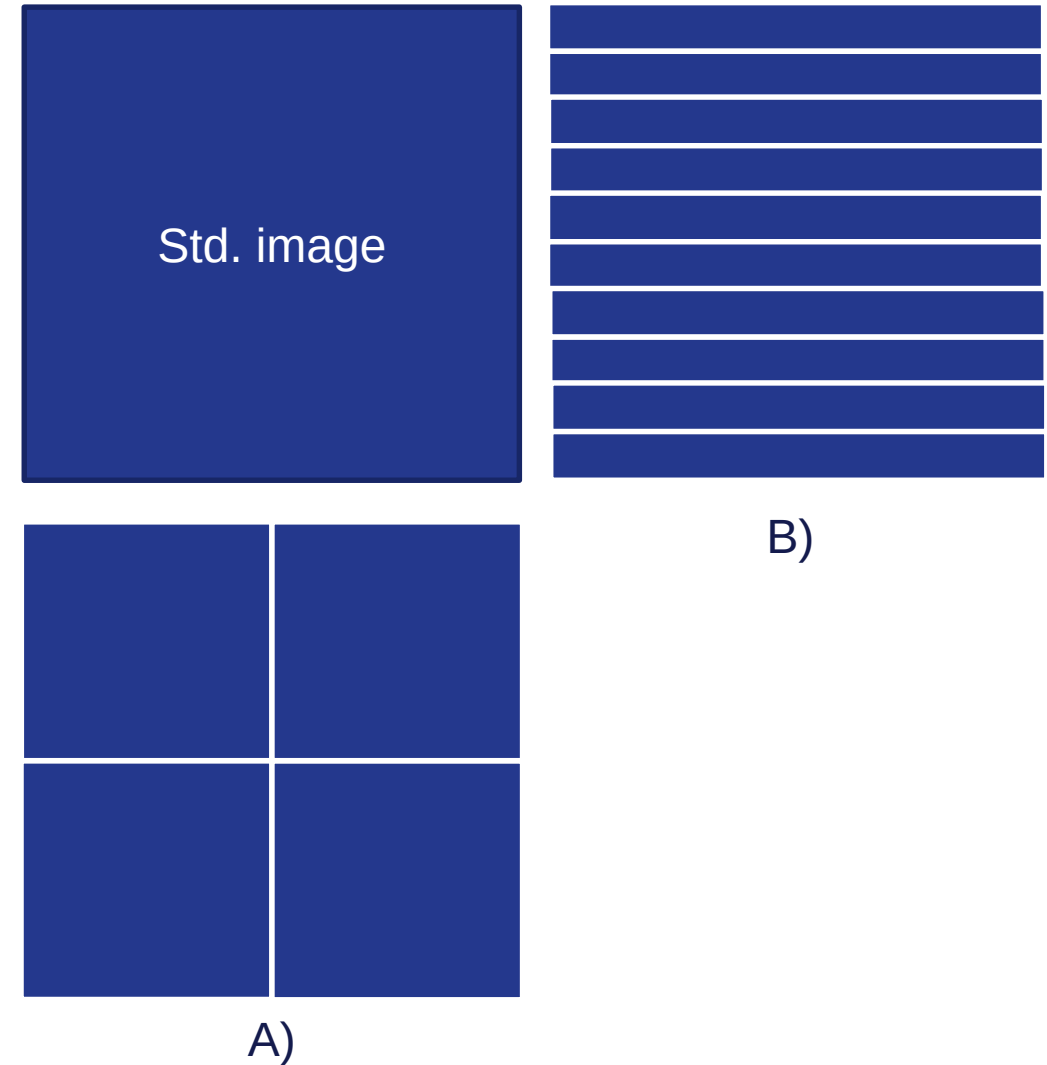


Solution:

- FileWriter (hdf5 writer) specific tmpfs using hugepages
- Defined our own file driver to parallelize writing our images
 - Using mmap and memcpy to further optimize performance
- We use a virtual dataset only to link start times of images (array) and a nicer representation of the data
- Data handling remains the same from the customers perspective

HDF – future challenges

- Virtual datasets don't automatically solve the parallel writing issue
 - A) Store data module / quadrant wise
 - B) Store data in a row representation
- Post-processing pipelines highly dependable on how the data is written
- Raw data rate increase factor >5
 - How do we write ~200 Gbps of compressed data using HDF?
- Maintenance of specific solution undesired



Evolution of Data Rates

PILATUS

2007: 0.14 Gbyte/s of Raw Data



Prototype detectors in development
(Jungfrau, Citius, ...)

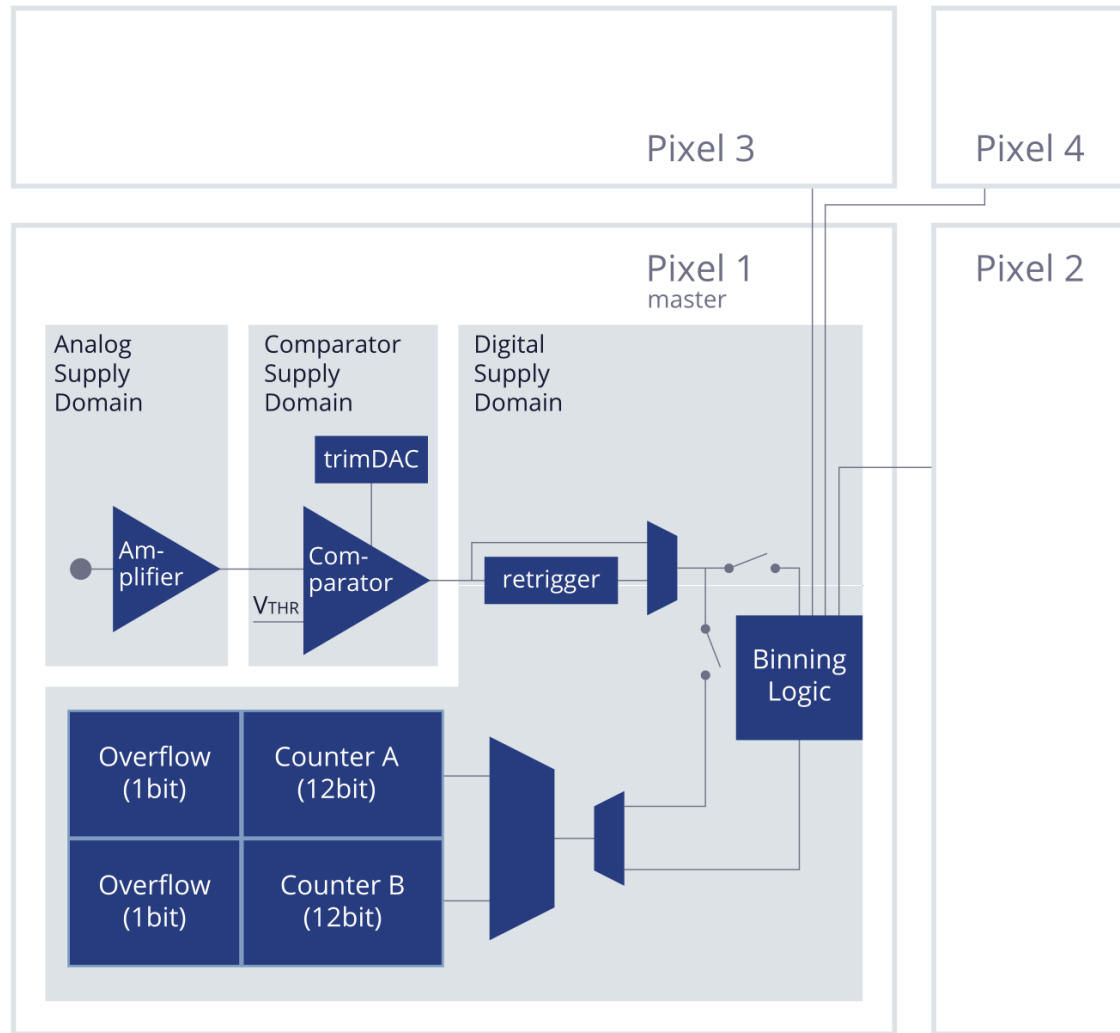
EIGER2/PILATUS4

2022: 18 Gbyte/s of Raw Data



Moore's Law for X-Ray detectors

Example: Fast ASIC development



Pixel size

100 μm $\times$ 100 μm

Pixel array

192 $\times$ 192 pixels

Readout modes

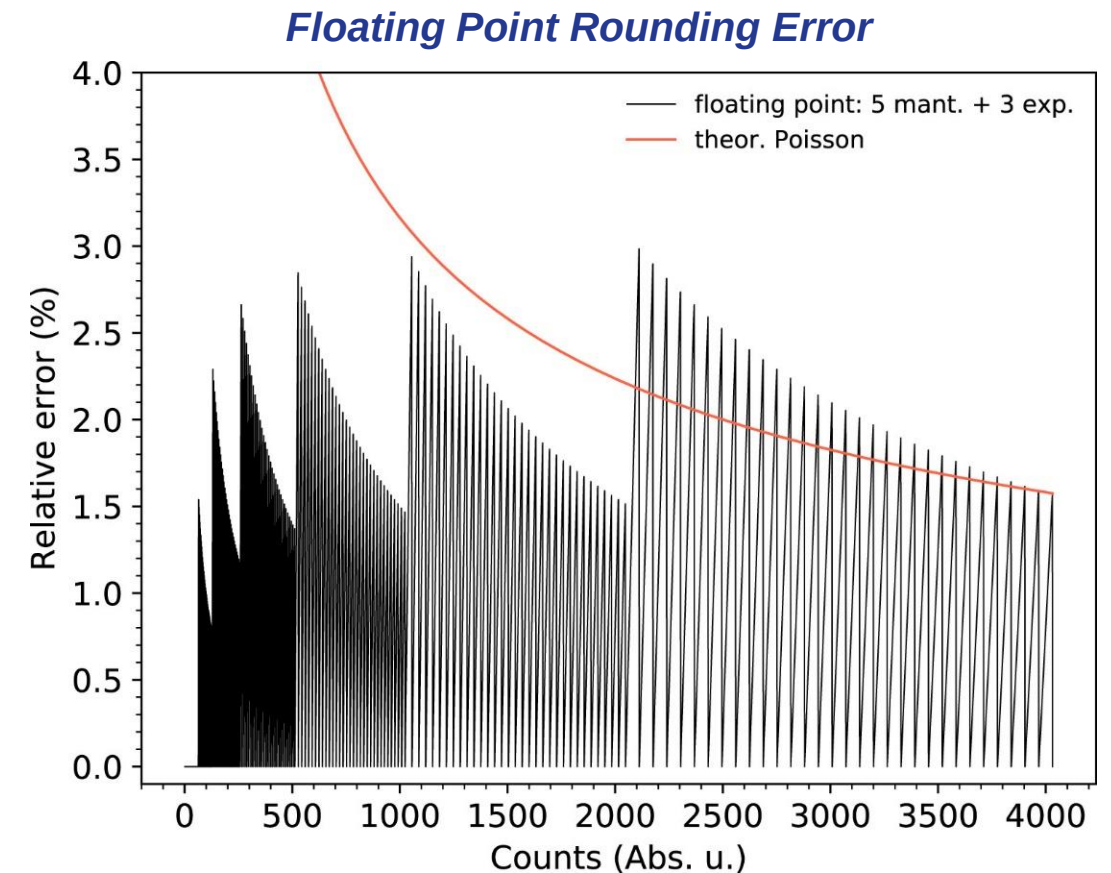
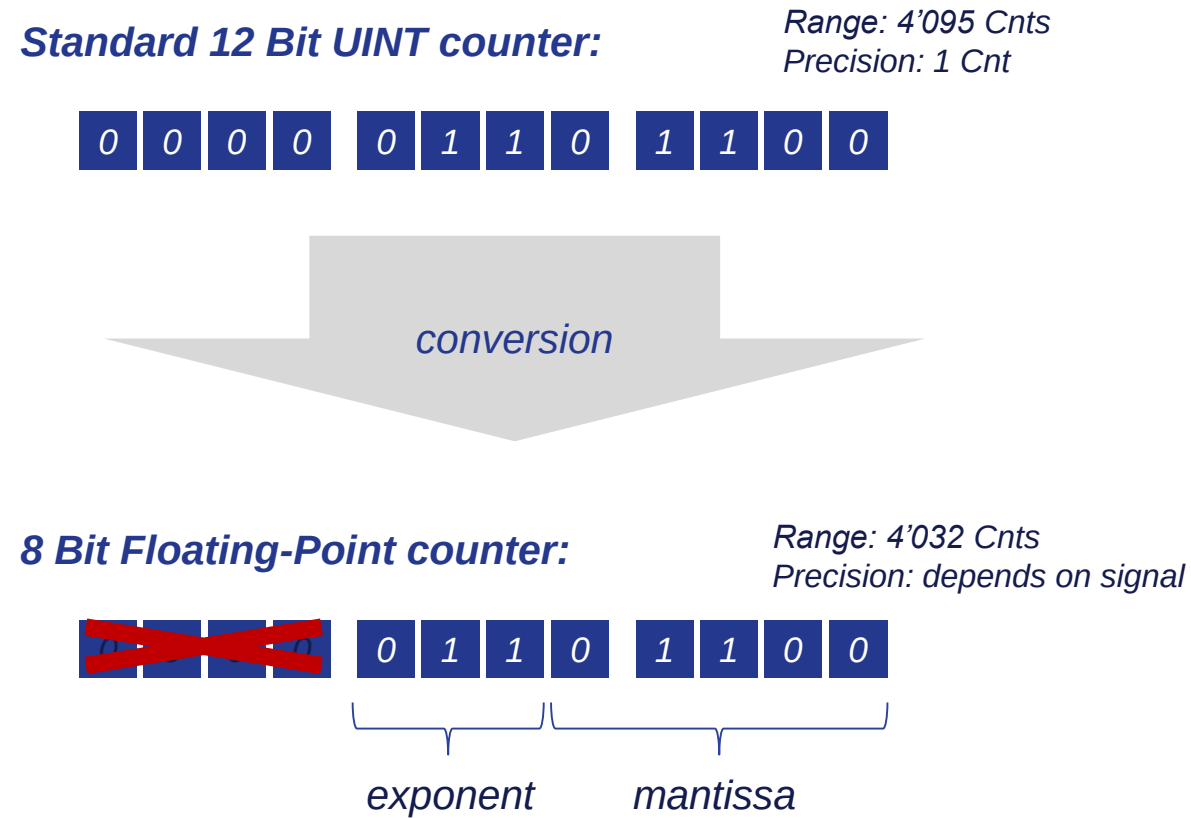
Full frame / 2 $\times$ 2 pixel digital binning

Counter encoding

12-bit integer / 8-bit floating-point

Instant Retrigger technology &
Room temperature operation

8-bit Floating-Point Compression



See P.Zambon, et.al. (2023), doi:10.1016/j.nima.2022.167888

FP Compression & Binning

Standard **33% bandwidth reduction**

1/4 of the data

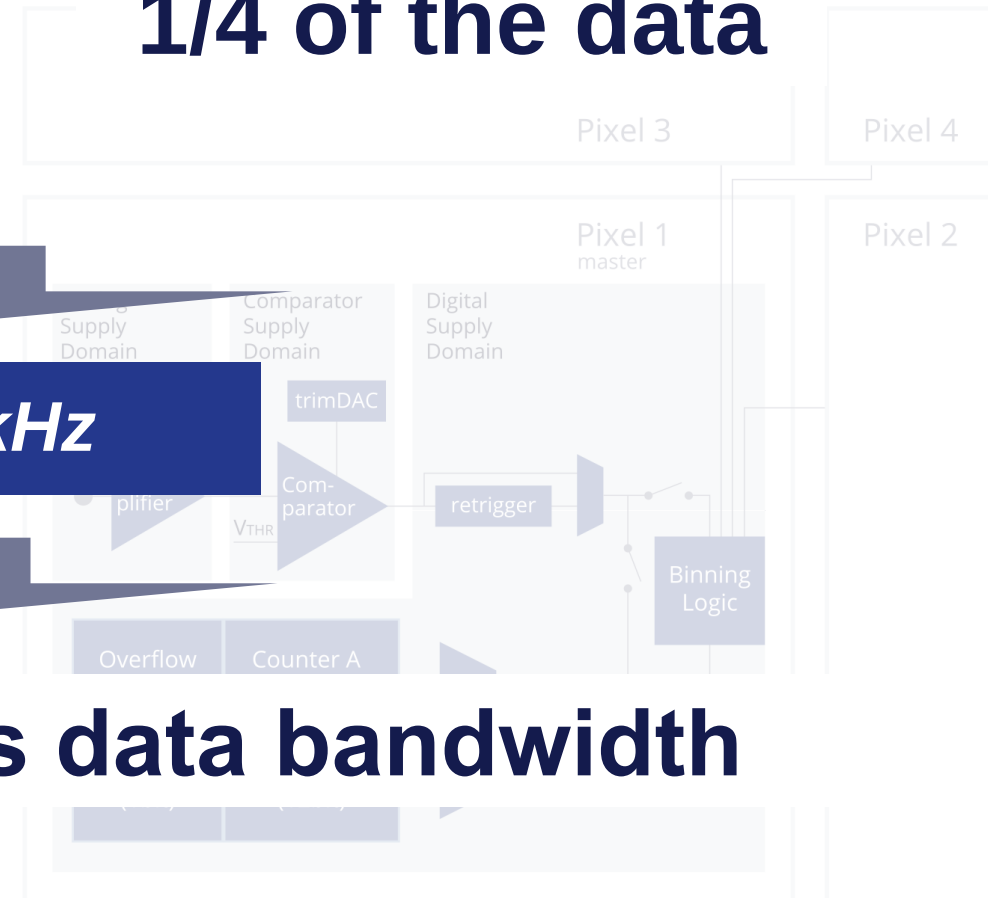
conversion

Framerate 120 kHz

8 Bit Floating-Point counter:

~~0 0~~ 0 1 1 0 1 1 0 0

less data in the pixel $\neq$ less data bandwidth



Recent: BitShuffle Compression

New, highly optimized BitShuffle implementation for modern processors by Kal Cuttler (DECTRIS)

- Implemented in C99
- Optimized with SIMD instructions including SSE2, AVX2, and AVX-512
- Does not allocate memory
- Support for all major compilers and operating systems

Typical **speedup** between **1.3x and 10x** depending on the CPU architecture, function, and arguments

see github.com/dectris/compression/

Test by John Wright, ESRF: **speedup up to >40%** for the entire "bslz4" decode operation

see https://github.com/jonwright/bslz4_to_sparse/issues/1

Edge Computing

Collaboration Project:

Started in April 2023

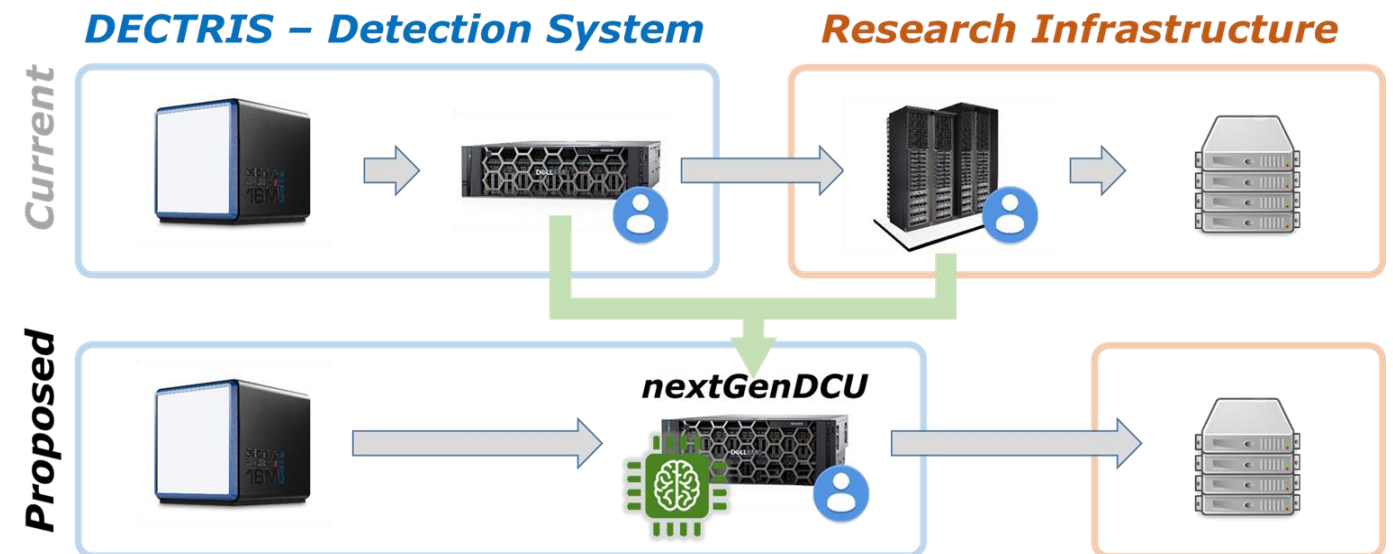
Radial integration, spot positions, indexing

Aim: no (millisecond) latency
for EIGER2 & PILATUS4



DECTRIS

Experiment requires live feedback



MX Image Scoring

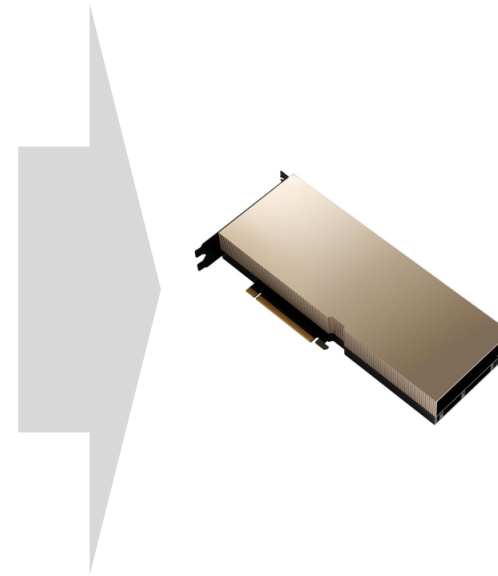
*Courtesy of Filip LEONARSKI
(PSI, SLS)*

on CPU



Spot finding
Peakfinder8: 25-50 ms/image

Indexing
Xgandalf (fast): 100 ms/image



on GPU/FPGA

Spot finding
COLSPOT on GPU: < 200 μ s

Indexing
Fast-feedback indexer on GPU: < 1 ms

Image scoring is faster than detector framerate

Future Challenges

- **Scientists always push the limit**
 - Data bandwidth will always be used
 - Data reduction upstream will lead to faster framerates
- **Bslz4 is great, but we need more**
 - Community will have to embrace lossy compression algorithms
- **Compression requires de-compression**
 - FAIR principles are key
 - de-compression overhead and integration are crucial for usability
- **Edge computing will become more**
 - Data should be transformed into actionable insight as soon as possible
 - «Process data where it is generated» -> enable data filtration
- **It's an «infrastructure» problem**
 - Detectors can easily do more
 - But storage, archiving, transfer, sharing, etc.. become paralyzed

Thank you for your attention!

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